

Transfer Learning

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UW DATA 598

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Swayamdipta



Transfer Learning in Natural Language Processing

June 2, 2019
NAACL-HLT 2019



Sebastian
Ruder



Matthew
Peters



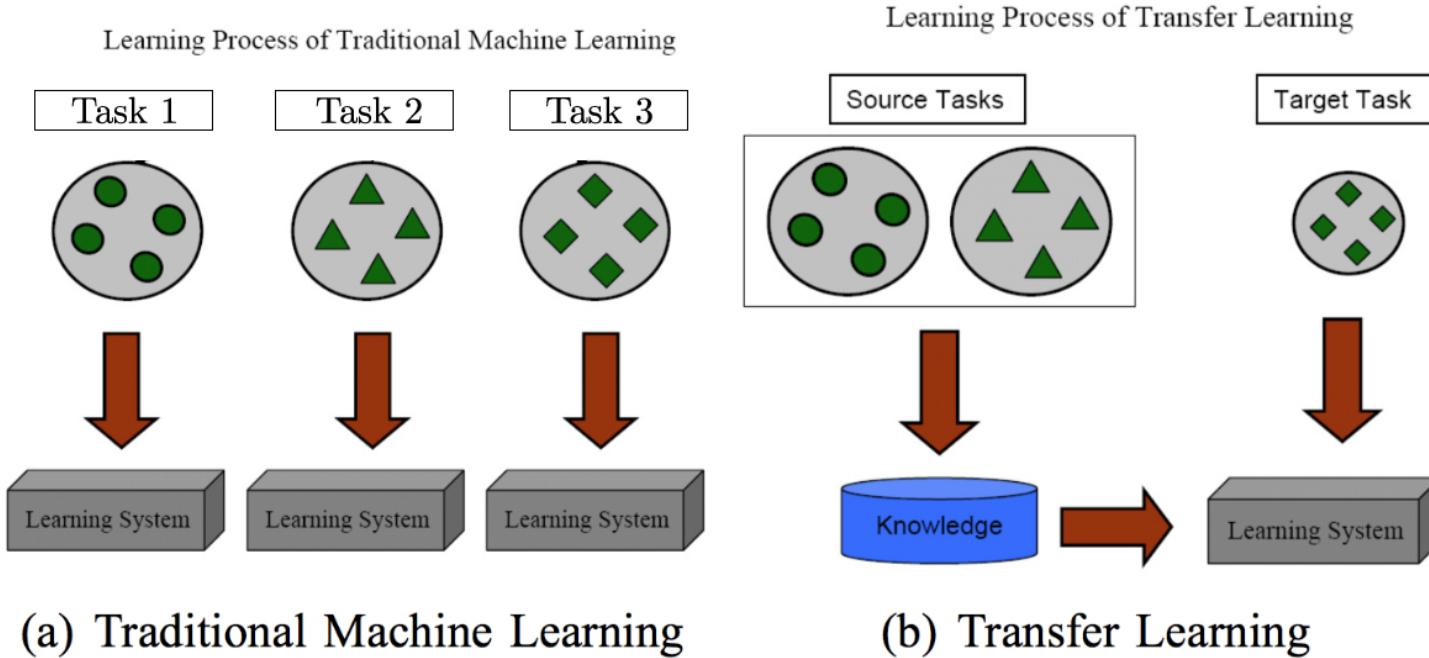
Swabha
Swayamdipta



Thomas
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What is transfer learning?



Preliminaries

- ❑ Focus: Natural Language Processing
- ❑ Goal: provide broad overview of methods in transfer learning
 - ❑ focusing on the most empirically successful methods *in NLP (as of 2019)*
- ❑ Demo:
 - ❑ Transfer learning from language model to a text classification task in NLP

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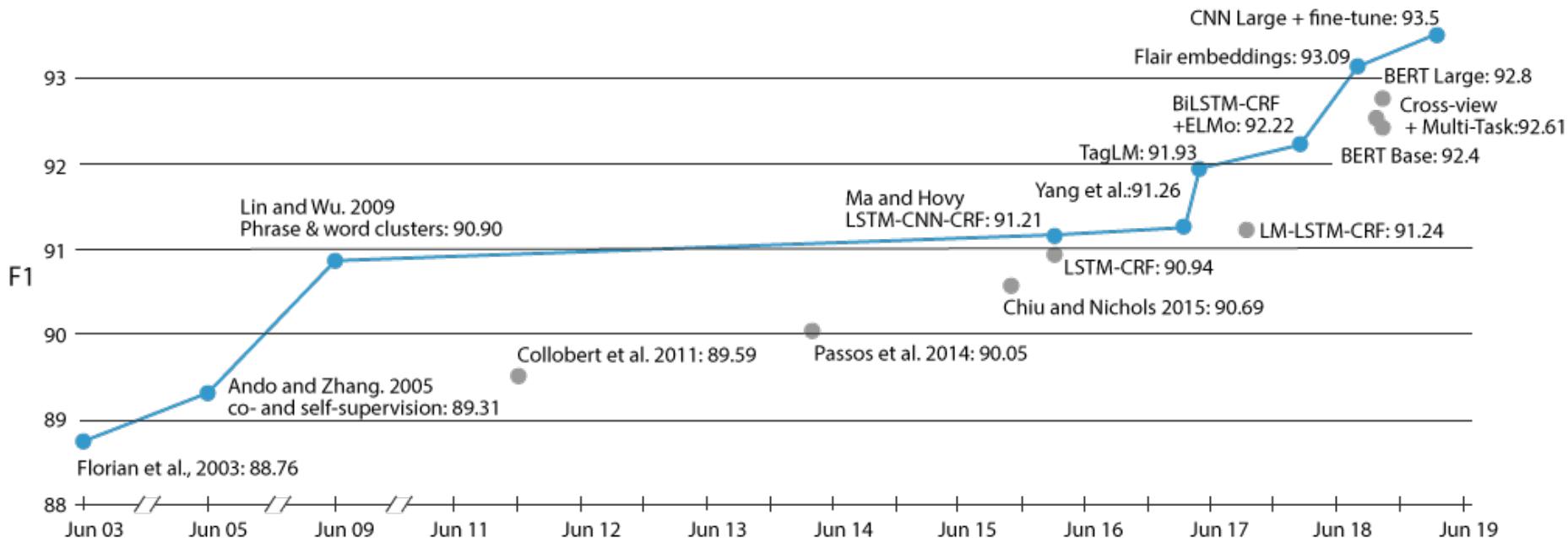
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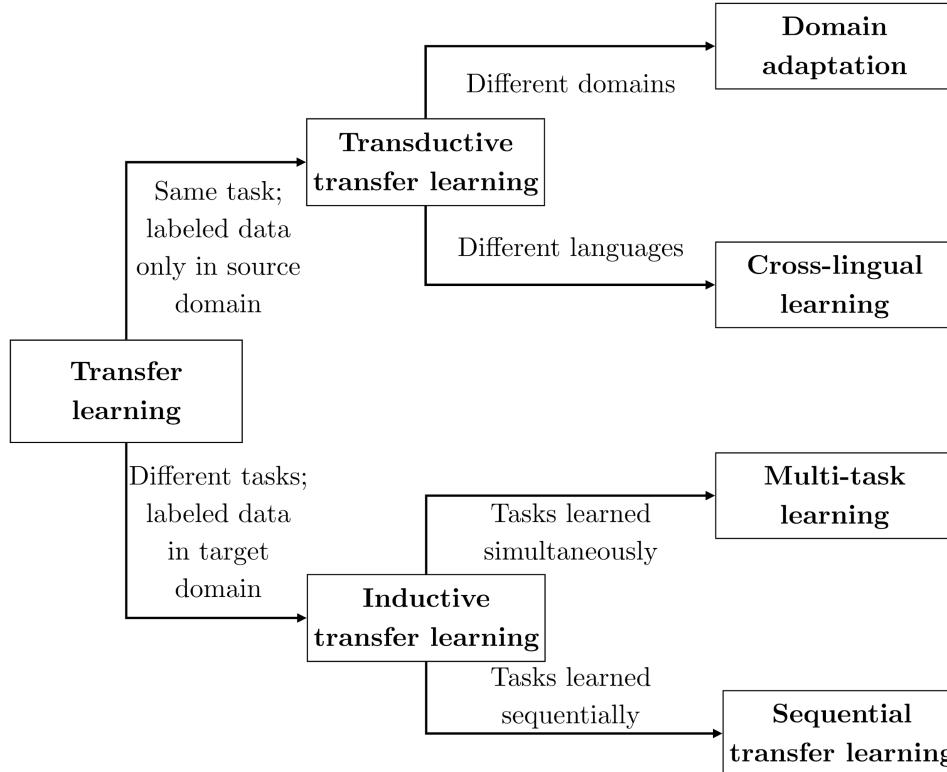
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- ❑ Empirically, transfer learning has resulted in state-of-the-art performance
 - ❑ for many supervised NLP tasks (e.g. classification, information extraction, Q&A, etc).

Why transfer learning (in NLP)? Empirically...

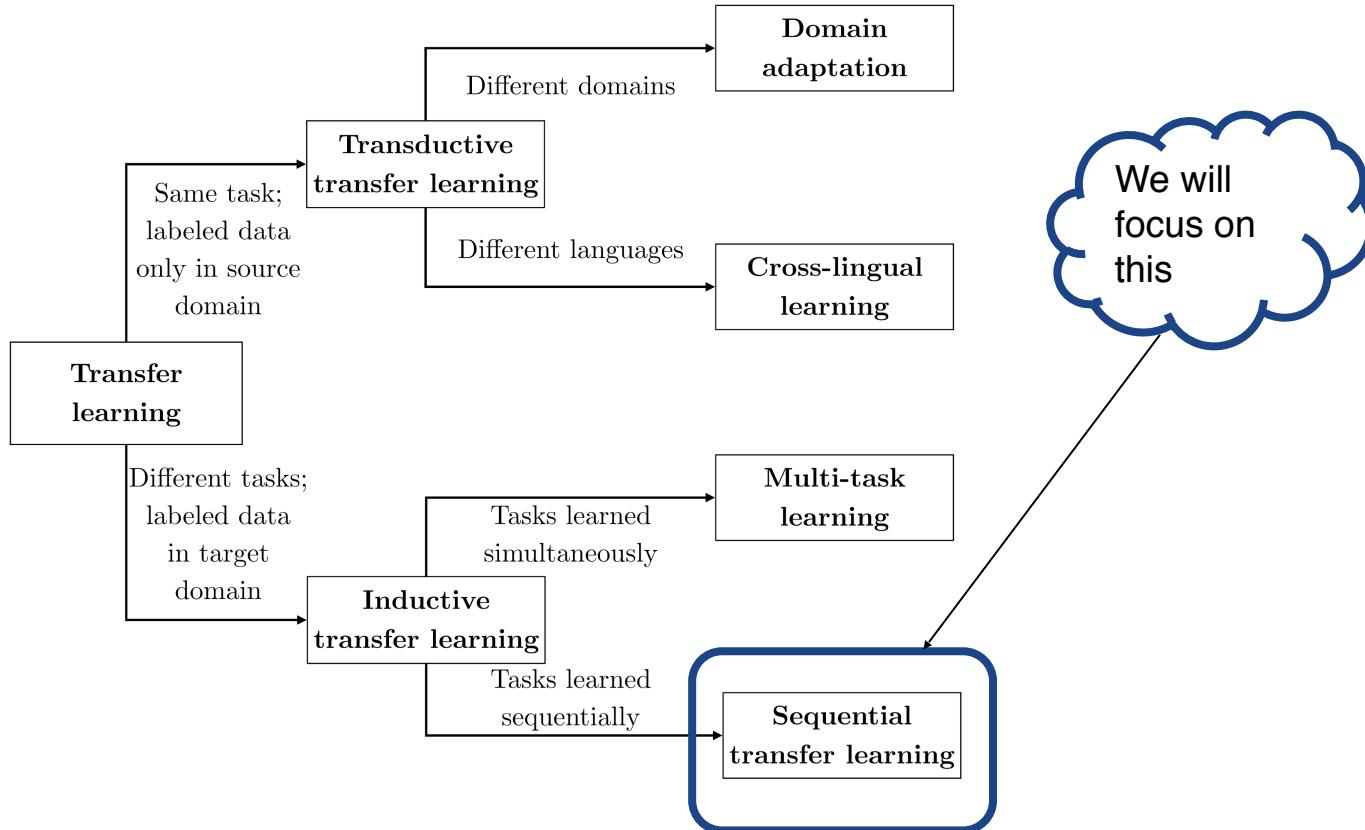
Performance on Named Entity Recognition (NER) on CoNLL-2003 (English) over time



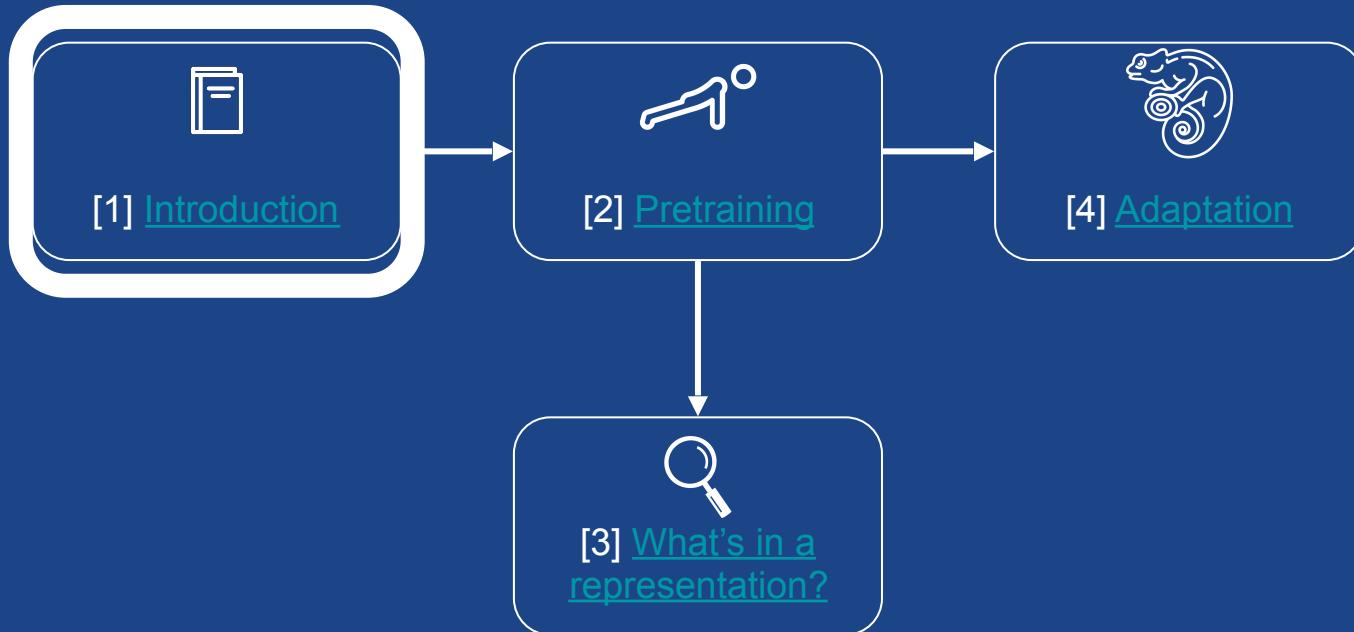
Types of transfer learning in NLP



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Agenda

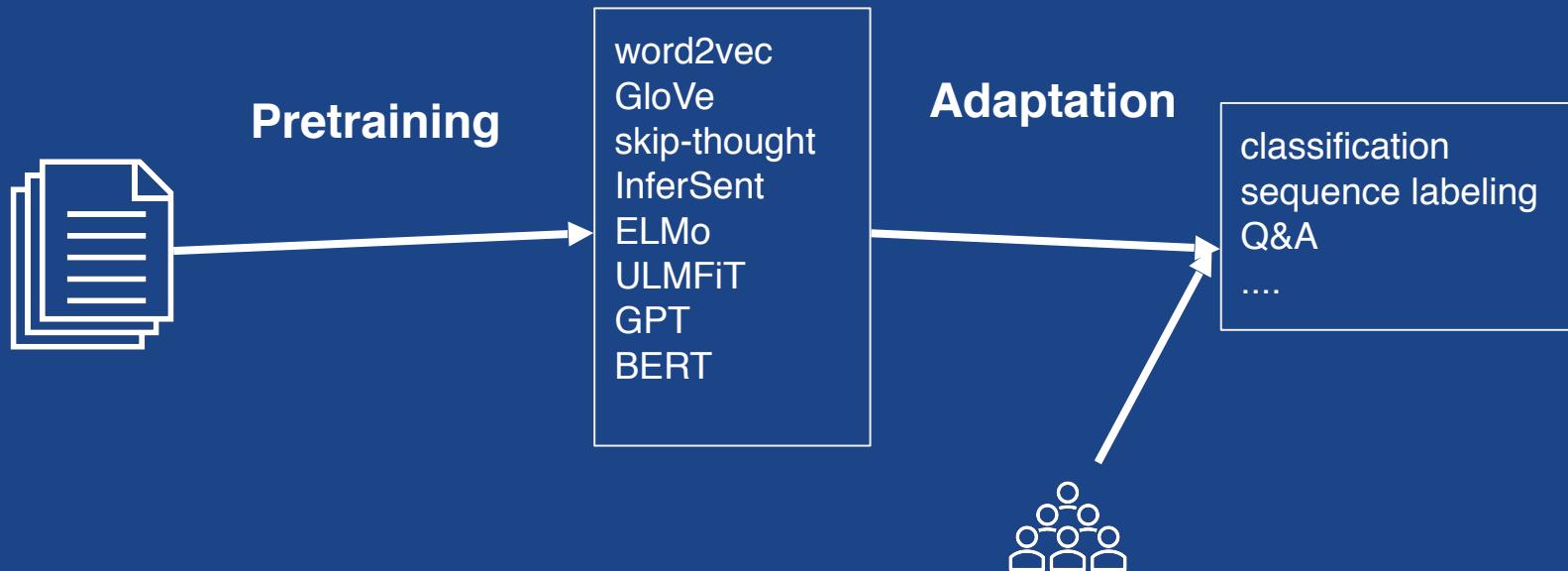


1. Introduction



Sequential transfer learning

Learn on one task / dataset, then transfer to another task / dataset



Pretraining tasks and datasets

- Unlabeled data and self-supervision
- Supervised pretraining

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 - NLI for sentence representations
 - Task-specific—transfer from one Q&A dataset to another

Concrete example—word vectors

Word embedding methods (e.g. word2vec) learn one vector per word:

cat = [0.1, -0.2, 0.4, ...]

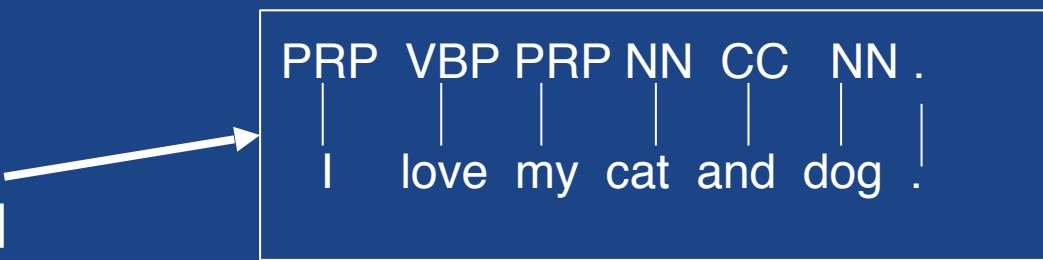
dog = [0.2, -0.1, 0.7, ...]

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PRP VBP PRP NN CC NN .
| | | | | | .
I love my cat and dog .

I love my cat and dog . }-> “positive”

Major Themes

Major themes: From words to words-in-context

Word vectors

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- ❑ Doesn't require human annotation
- ❑ Many languages have enough text to learn high capacity model
- ❑ Versatile—can learn both sentence and word representations with a variety of objective functions

Major themes: pretraining vs target task

Choice of pretraining and target tasks are coupled

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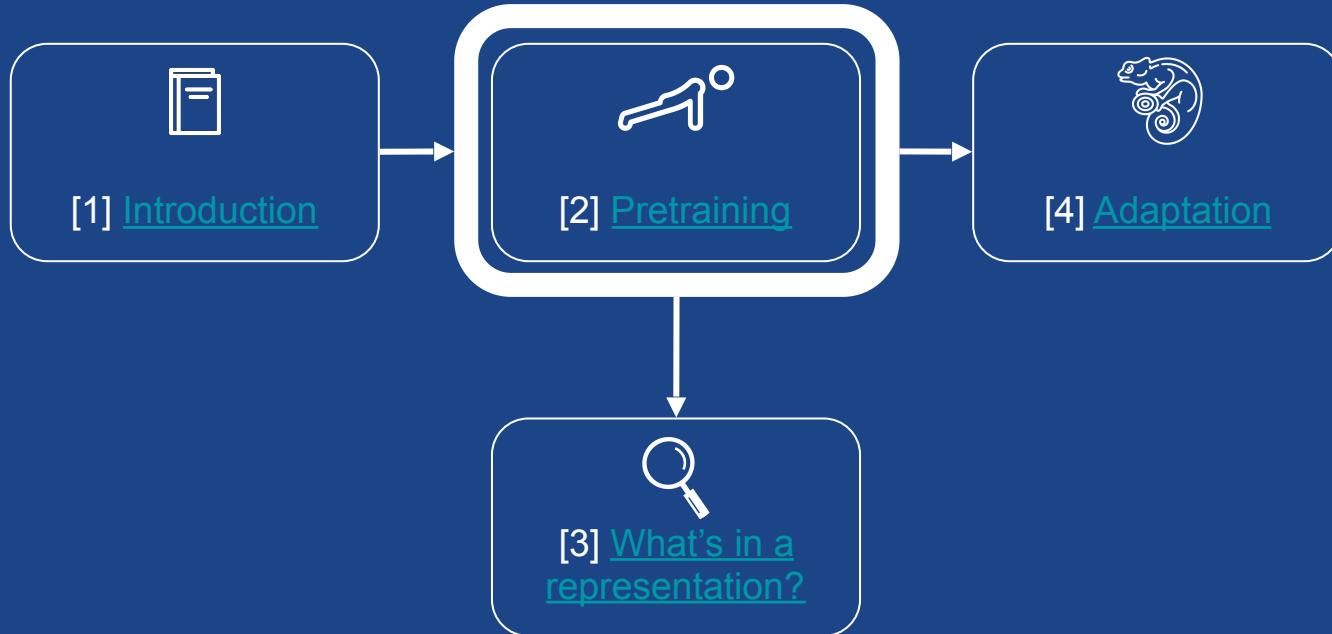
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In general:

- ❑ Similar pretraining and target tasks → best results

Agenda



2. Pretraining

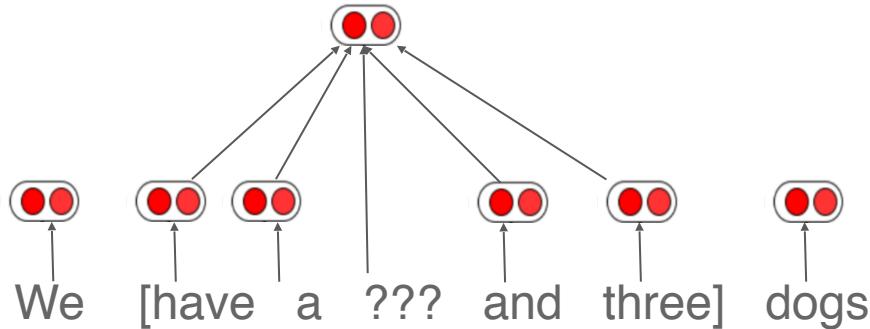


Overview

- ❑ Language model pretraining
- ❑ Word vectors (types)
- ❑ Contextual word vectors (tokens)
- ❑ Self-supervised and Supervised pretraining

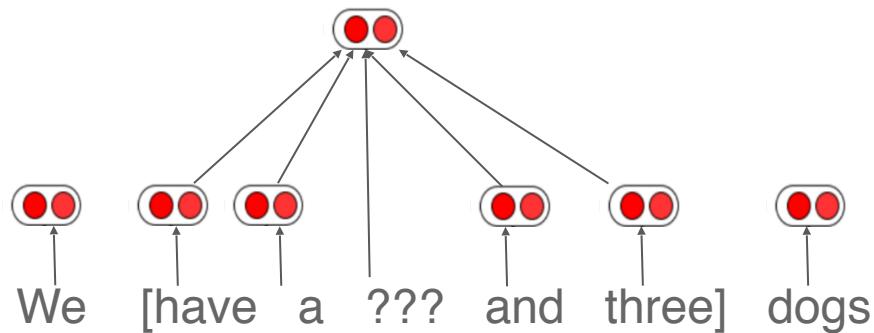
LM pretraining

word2vec, [Mikolov et al \(2013\)](#)

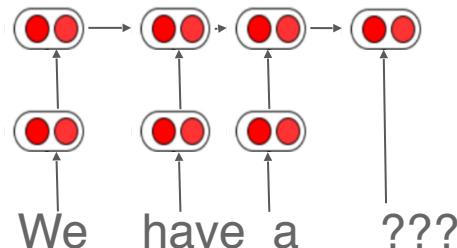


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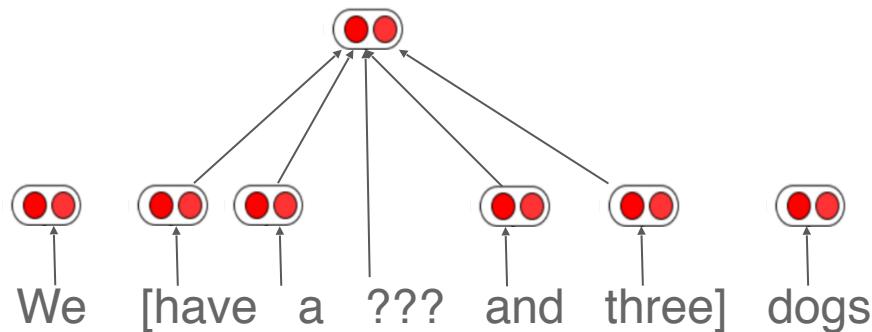


ELMo, [Peters et al. 2018](#), ULMFiT ([Howard & Ruder 2018](#)), GPT ([Radford et al. 2018](#))

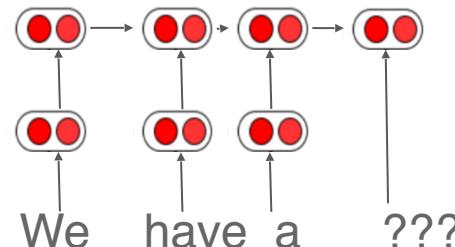


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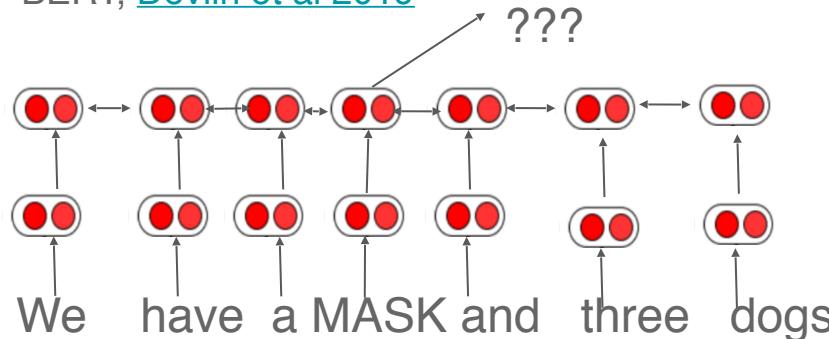
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BERT, [Devlin et al 2019](#)



Word vectors

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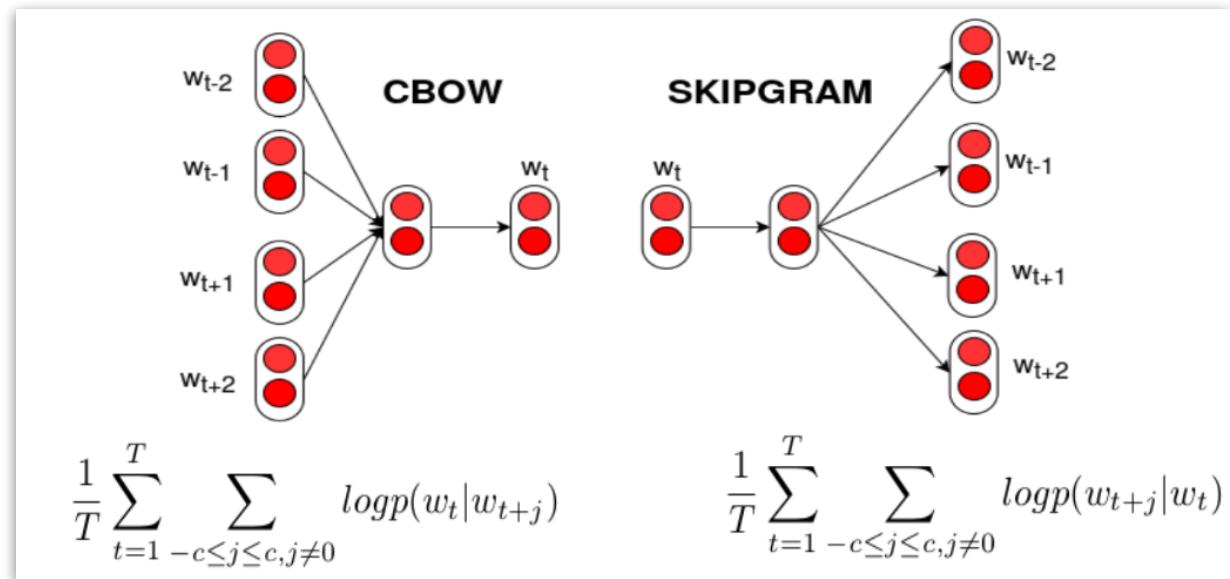
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- Embeddings are themselves parameters—can be learned
- Sharing representations across tasks
- Lower dimensional space
 - Better for computation—difficult to handle sparse vectors.

word2vec

Efficient algorithm + large scale training → high quality word vectors

([Mikolov et al., 2013](#))



See also:

- ❑ [Pennington et al. \(2014\)](#): GloVe
- ❑ [Bojanowski et al. \(2017\)](#): fastText

Contextual word vectors

Contextual word vectors - Motivation

Word vectors compress all contexts into a *single vector*

Nearest neighbor GloVe vectors to “play”

VERB

playing
played

NOUN

game
games
players
football

ADJ

multiplayer

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multiplayer

??

play
(theatrical)
Play

Contextual word vectors - Key Idea

- ♦ Instead of learning one vector per word type, learn a vector that depends on context

$f(\text{play} \mid \text{The kids play a game in the park.})$

\neq

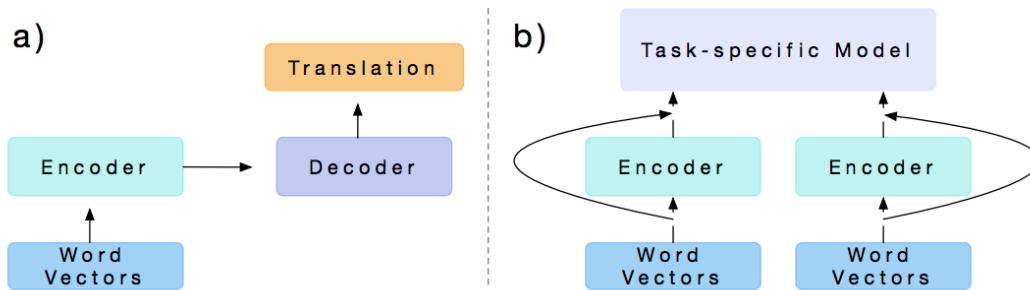
$f(\text{play} \mid \text{The Broadway play premiered yesterday.})$

- ♦ Many approaches based on language models.

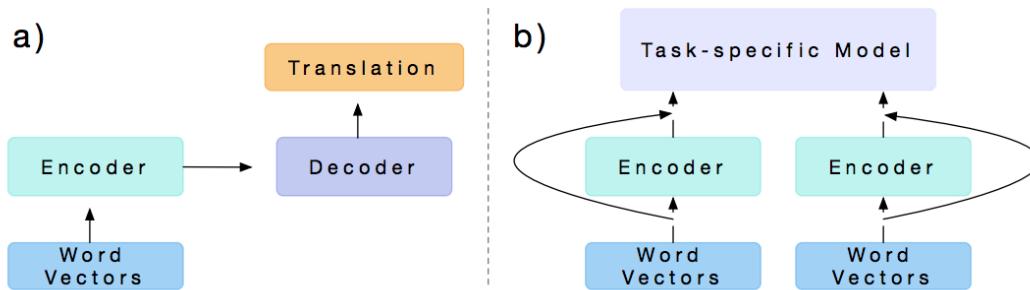
- ♦ We'll only look at a few.

Pretraining Tasks

Supervised Pretraining: CoVe

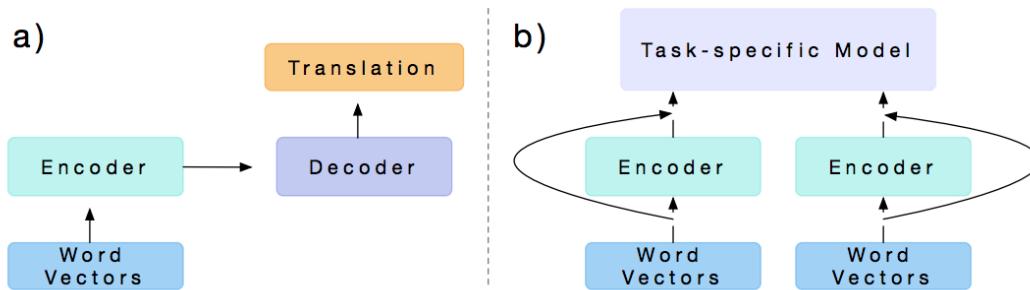


Supervised Pretraining: CoVe



Pretrain bidirectional
encoder with MT
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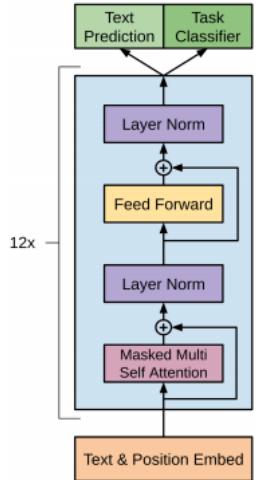


Pretrain bidirectional encoder with MT supervision, extract LSTM states

Adding CoVe with GloVe gives improvements for classification, NLI, Q&A

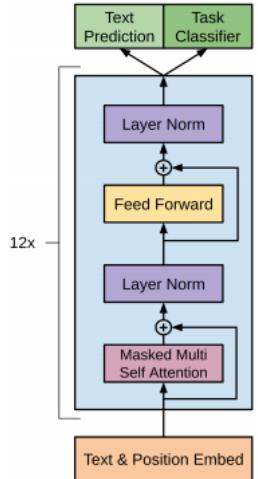
Dataset	Random	GloVe	GloVe+					
			Char	CoVe-S	CoVe-M	CoVe-L	Char+CoVe-L	
SST-2	84.2	88.4	90.1	89.0	90.9	91.1	91.2	
SST-5	48.6	53.5	52.2	54.0	54.7	54.5	55.2	
IMDb	88.4	91.1	91.3	90.6	91.6	91.7	92.1	
TREC-6	88.9	94.9	94.7	94.7	95.1	95.8	95.8	
TREC-50	81.9	89.2	89.8	89.6	89.6	90.5	91.2	
SNLI	82.3	87.7	87.7	87.3	87.5	87.9	88.1	
SQuAD	65.4	76.0	78.1	76.5	77.1	79.5	79.9	

Self-supervised Pretraining: GPT



(Radford et al., 2018)

Self-supervised Pretraining: GPT



Pretrain large 12-layer **left-to-right** Transformer Language Model.

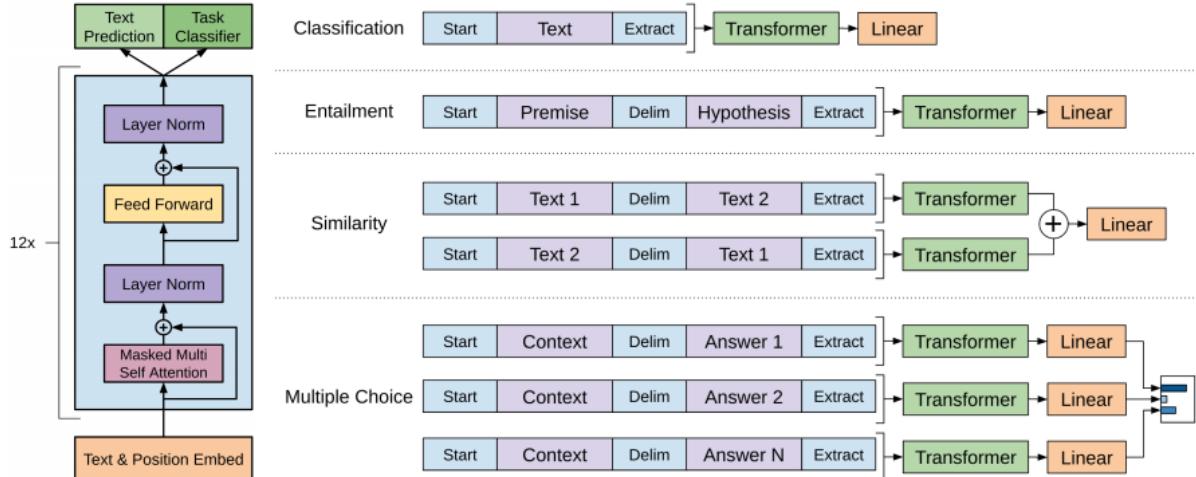
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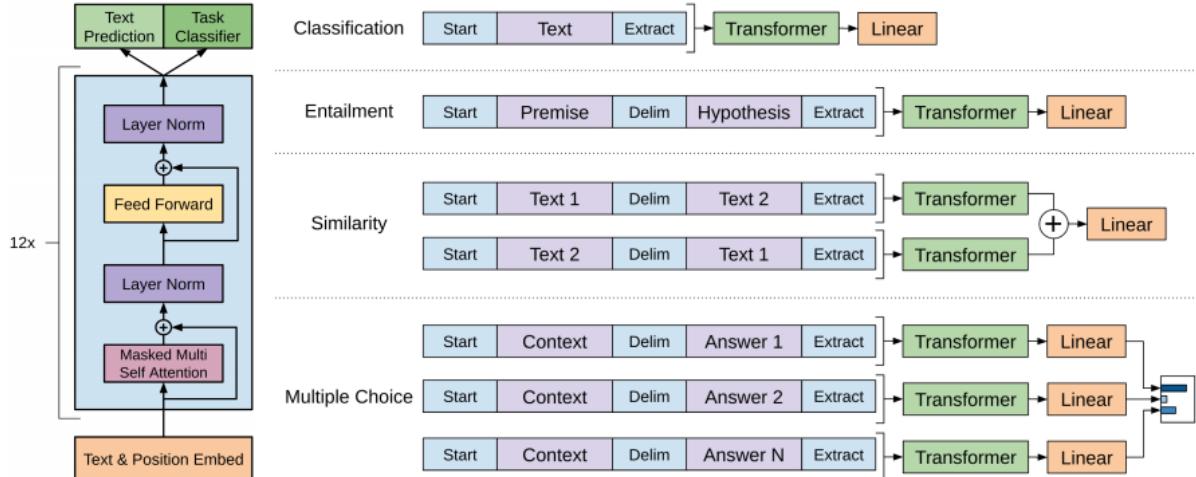
[More on Transformers in coming slides]

Finetuning for sentence classification, sentence pair classification and multiple choice question-answer classification gave state-of-the-art results for 9 tasks.

Method	MNLI-m	MNLI-mm	SNLI	SciTail	QNLI	RTE
ESIM + ELMo [44] (5x)	-	-	<u>89.3</u>	-	-	-
CAFE [58] (5x)	80.2	79.0	<u>89.3</u>	-	-	-
Stochastic Answer Network [35] (3x)	<u>80.6</u>	<u>80.1</u>	-	-	-	-
CAFE [58]	78.7	77.9	88.5	<u>83.3</u>		
GenSen [64]	71.4	71.3	-	-	<u>82.3</u>	59.2
Multi-task BiLSTM + Attn [64]	72.2	72.1	-	-	<u>82.1</u>	61.7
Finetuned Transformer LM (ours)	82.1	81.4	89.9	88.3	88.1	56.0

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More variants of GPT: 2 and 3!

(Radford et al., 2018)

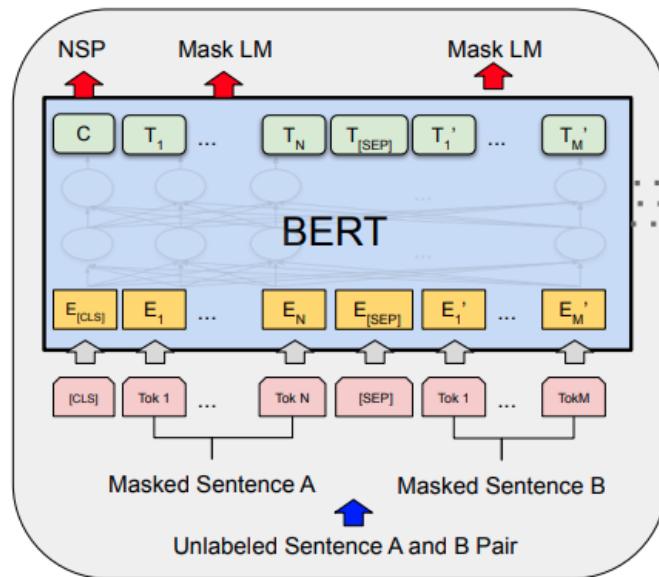
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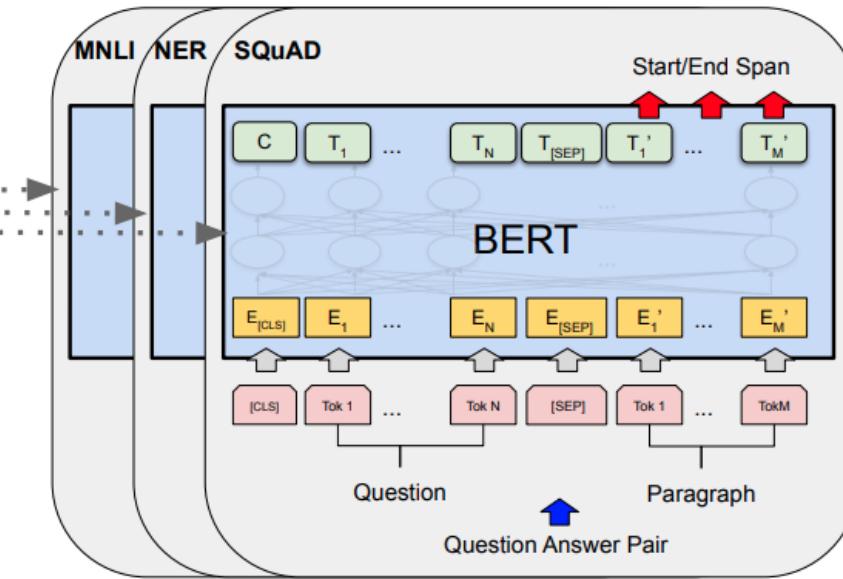
BERT pretrains both sentence and contextual word representations, using **masked LM** and **next sentence prediction**. BERT-large has 340M parameters, 24 layers!

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Pre-training



Fine-Tuning

[\(Devlin et al. 2019\)](#)

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- ❑ Empirically works better than translation: “Language Modeling Teaches You More Syntax than Translation Does” ([Zhang et al. 2018](#))

Hands-on #1: Pretraining a Transformer Language Model



Hands-on: Overview



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❑ Goals:

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- ❑ Expose all the details in a simple, concise and self-contained code-base
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Plan

- Build a GPT-2 / BERT model
- Pretrain it on a rather large corpus with $\sim 100M$ words
- Adapt it for a target task (question categorization) to get SOTA performances

Hands-on pre-training



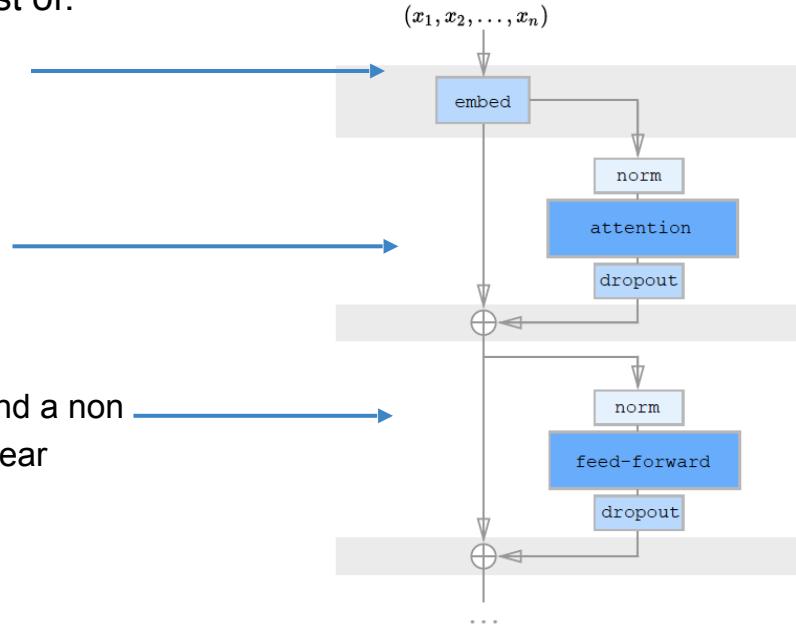
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- summing words and position embeddings
- applying a succession of transformer blocks with:
 - layer normalisation
 - a self-attention module
 - dropout and a residual connection
- another layer normalisation
- a feed-forward module with one hidden layer and a non-linearity: Linear \Rightarrow Non-Linear Activation \Rightarrow Linear
- dropout and a residual connection

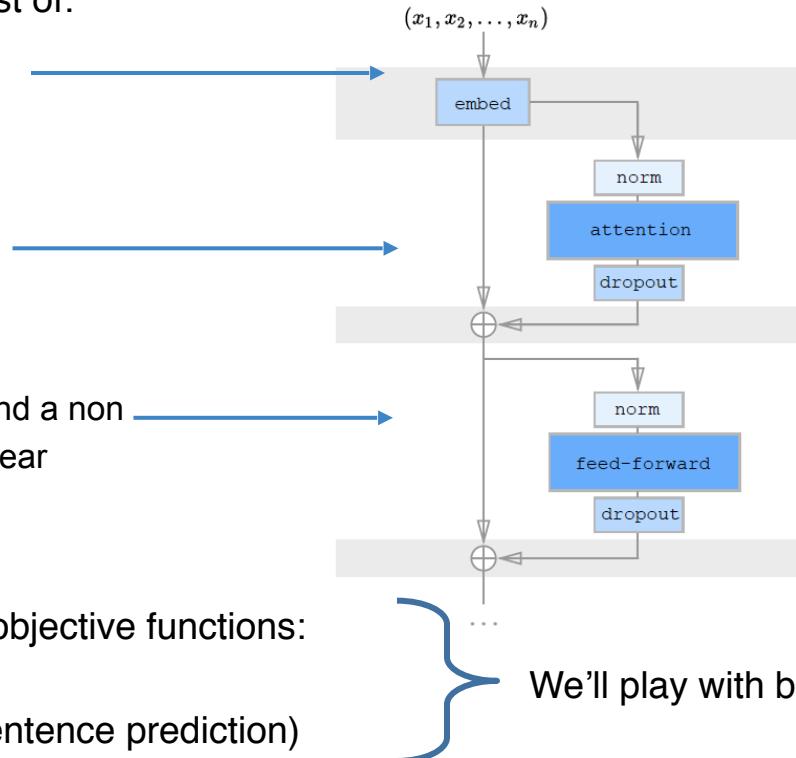




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- summing words and position embeddings
- applying a succession of transformer blocks with:
 - layer normalisation
 - a self-attention module
 - dropout and a residual connection
- another layer normalisation
- a feed-forward module with one hidden layer and a non-linearity: Linear \Rightarrow Non-Linear Activation \Rightarrow Linear
- dropout and a residual connection



Main differences between GPT/GPT-2/BERT are the objective functions:

- causal language modeling for GPT
- masked language modeling for BERT (+ next sentence prediction)

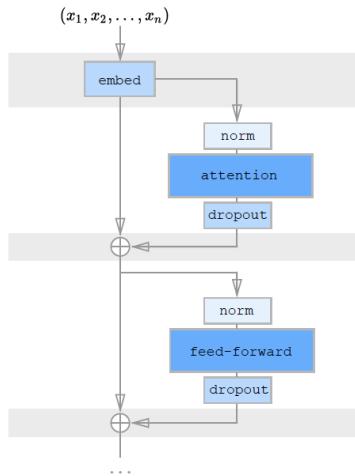
We'll play with both

[Illustration from \(Child et al., 2019\)](#)



Hands-on pre-training

Let's code the backbone of our model!



```
import torch
import torch.nn as nn

class Transformer(nn.Module):
    def __init__(self, embed_dim, hidden_dim, num_embeddings, num_max_positions, num_heads, num_layers, dropout, causal):
        super().__init__()
        self.causal = causal
        self.tokens_embeddings = nn.Embedding(num_embeddings, embed_dim)
        self.position_embeddings = nn.Embedding(num_max_positions, embed_dim)
        self.dropout = nn.Dropout(dropout)

        self.attentions, self.feed_forwards = nn.ModuleList(), nn.ModuleList()
        self.layer_norms_1, self.layer_norms_2 = nn.ModuleList(), nn.ModuleList()
        for _ in range(num_layers):
            self.attentions.append(nn.MultiheadAttention(embed_dim, num_heads, dropout=dropout))
            self.feed_forwards.append(nn.Sequential(nn.Linear(embed_dim, hidden_dim),
                                                    nn.ReLU(),
                                                    nn.Linear(hidden_dim, embed_dim)))
            self.layer_norms_1.append(nn.LayerNorm(embed_dim, eps=1e-12))
            self.layer_norms_2.append(nn.LayerNorm(embed_dim, eps=1e-12))

    def forward(self, x, padding_mask=None):
        positions = torch.arange(len(x), device=x.device).unsqueeze(-1)
        h = self.tokens_embeddings(x)
        h = h + self.position_embeddings(positions).expand_as(h)
        h = self.dropout(h)

        attn_mask = None
        if self.causal:
            attn_mask = torch.full((len(x), len(x)), -float('Inf'), device=h.device, dtype=h.dtype)
            attn_mask = torch.triu(attn_mask, diagonal=1)

        for layer_norm_1, attention, layer_norm_2, feed_forward in zip(self.layer_norms_1, self.attentions,
                                                                       self.layer_norms_2, self.feed_forwards):

            h = layer_norm_1(h)
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            x = self.dropout(x)
            h = x + h

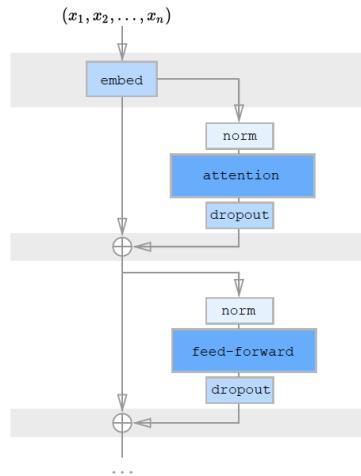
            h = layer_norm_2(h)
            x = feed_forward(h)
            x = self.dropout(x)
            h = x + h

        return h
```



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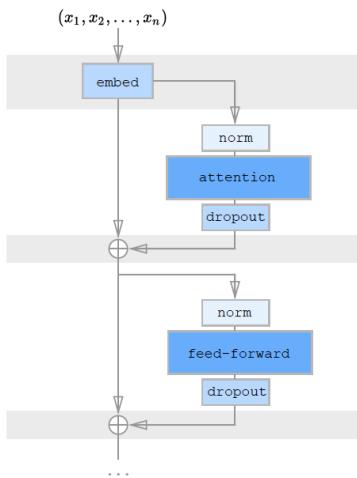
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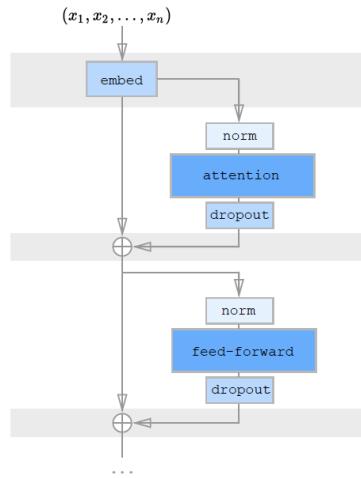
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            h = layer_norm_2(h)
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```



Hands-on pre-training

Two attention masks?

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import torch
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class Transformer(nn.Module):
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                                                    nn.ReLU(),
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            h = x + h

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```



Hands-on pre-training

Two attention masks?

- padding_mask masks the padding tokens. It is specific to each sample in the batch:

I	love	Mom	'	s	cooking
I	love	you	too	!	
No	way				
This	is	the	shit		
Yes					

```
import torch
import torch.nn as nn

class Transformer(nn.Module):
    def __init__(self, embed_dim, hidden_dim, num_embeddings, num_max_positions, num_heads, num_layers, dropout, causal):
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            h = x + h

        return h
```



Hands-on pre-training

Two attention masks?

- padding_mask masks the padding tokens. It is specific to each sample in the batch:

I	love	Mom	'	s	cooking
I	love	you	too	!	
No	way				
This	is	the	shit		
Yes					

- attn_mask is the same for all samples in the batch. It masks the previous tokens for causal transformers:

I	love	Mom	'	s	cooking
love					
Mom					
,					
s					
cooking					

```

import torch
import torch.nn as nn

class Transformer(nn.Module):
    def __init__(self, embed_dim, hidden_dim, num_embeddings, num_max_positions, num_heads, num_layers, dropout, causal):
        super().__init__()
        self.causal = causal
        self.tokens_embeddings = nn.Embedding(num_embeddings, embed_dim)
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        return h

```



Hands-on pre-training

To pretrain our model, we need to add a few elements: a head, a loss and initialize weights.

```
class TransformerWithLMHead(nn.Module):
    def __init__(self, config):
        """ Transformer with a language modeling head on top (tied weights) """
        super().__init__()
        self.config = config
        self.transformer = Transformer(config.embed_dim, config.hidden_dim, config.num_embeddings,
                                      config.num_max_positions, config.num_heads, config.num_layers,
                                      config.dropout, causal=not config.mlm)

        self.lm_head = nn.Linear(config.embed_dim, config.num_embeddings, bias=False)
        self.apply(self.init_weights)
        self.tie_weights()

    def tie_weights(self):
        self.lm_head.weight = self.transformer.tokens_embeddings.weight

    def init_weights(self, module):
        """ initialize weights - nn.MultiheadAttention is already initialized by PyTorch (xavier) """
        if isinstance(module, (nn.Linear, nn.Embedding, nn.LayerNorm)):
            module.weight.data.normal_(mean=0.0, std=self.config.initializer_range)
        if isinstance(module, (nn.Linear, nn.LayerNorm)) and module.bias is not None:
            module.bias.data.zero_()

    def forward(self, x, labels=None, padding_mask=None):
        """ x has shape [seq length, batch], padding_mask has shape [batch, seq length] """
        hidden_states = self.transformer(x, padding_mask)
        logits = self.lm_head(hidden_states)

        if labels is not None:
            shift_logits = logits[:-1] if self.transformer.causal else logits
            shift_labels = labels[1:] if self.transformer.causal else labels
            loss_fct = nn.CrossEntropyLoss(ignore_index=-1)
            loss = loss_fct(shift_logits.view(-1, shift_logits.size(-1)), shift_labels.view(-1))
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Hands-on pre-training

To pretrain our model, we need to add a few elements: a head, a loss and initialize weights.

We add these elements with a pretraining model encapsulating our model.

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1. A pretraining head on top of our core model: we choose a language modeling head with tied weights

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2. Initialize the weights

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        logits = self.lm_head(hidden_states)

        if labels is not None:
            shift_logits = logits[:-1] if self.transformer.causal else logits
            shift_labels = labels[1:] if self.transformer.causal else labels
            loss_fct = nn.CrossEntropyLoss(ignore_index=-1)
            loss = loss_fct(shift_logits.view(-1, shift_logits.size(-1)), shift_labels.view(-1))
            return logits, loss

        return logits
```



Hands-on pre-training

To pretrain our model, we need to add a few elements: a head, a loss and initialize weights.

We add these elements with a pretraining model encapsulating our model.

1. A pretraining head on top of our core model: we choose a language modeling head with tied weights

2. Initialize the weights

3. Define a loss function: we choose a cross-entropy loss on current (or next) token predictions

```
class TransformerWithLMHead(nn.Module):
    def __init__(self, config):
        """ Transformer with a language modeling head on top (tied weights) """
        super().__init__()
        self.config = config
        self.transformer = Transformer(config.embed_dim, config.hidden_dim, config.num_embeddings,
                                      config.num_max_positions, config.num_heads, config.num_layers,
                                      config.dropout, causal=not config.mlm)

        self.lm_head = nn.Linear(config.embed_dim, config.num_embeddings, bias=False)
        self.apply(self.init_weights)
        self.tie_weights()

    def tie_weights(self):
        self.lm_head.weight = self.transformer.tokens_embeddings.weight

    def init_weights(self, module):
        """ initialize weights - nn.MultiheadAttention is already initialized by PyTorch (xavier) """
        if isinstance(module, (nn.Linear, nn.Embedding, nn.LayerNorm)):
            module.weight.data.normal_(mean=0.0, std=self.config.initializer_range)
        if isinstance(module, (nn.Linear, nn.LayerNorm)) and module.bias is not None:
            module.bias.data.zero_()

    def forward(self, x, labels=None, padding_mask=None):
        """ x has shape [seq length, batch], padding_mask has shape [batch, seq length] """
        hidden_states = self.transformer(x, padding_mask)
        logits = self.lm_head(hidden_states)

        if labels is not None:
            shift_logits = logits[:-1] if self.transformer.causal else logits
            shift_labels = labels[1:] if self.transformer.causal else labels
            loss_fct = nn.CrossEntropyLoss(ignore_index=-1)
            loss = loss_fct(shift_logits.view(-1, shift_logits.size(-1)), shift_labels.view(-1))
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        return logits
```



Hands-on pre-training

Now let's take care of our data and configuration

```
▶ from pytorch_pretrained_bert import BertTokenizer, cached_path  
tokenizer = BertTokenizer.from_pretrained('bert-base-cased', do_lower_case=False)
```

```
▶ from collections import namedtuple  
  
Config = namedtuple('Config',  
    field_names="embed_dim, hidden_dim, num_max_positions, num_embeddings      , num_heads, num_layers,"  
    "dropout, initializer_range, batch_size, lr, max_norm, n_epochs, n_warmup,"  
    "mlm, gradient_accumulation_steps, device, log_dir, dataset_cache")  
args = Config( 410      , 2100      , 256      , len(tokenizer.vocab), 10      , 16      ,  
    0.1      , 0.02      , 16      , 2.5e-4, 1.0 , 50      , 1000      ,  
    False, 4, "cuda" if torch.cuda.is_available() else "cpu", "./"      , "./dataset_cache.bin")
```

```
▶ dataset_file = cached_path("https://s3.amazonaws.com/datasets.huggingface.co/wikitext-103/"  
    "wikitext-103-train-tokenized-bert.bin")  
datasets = torch.load(dataset_file)  
  
# Convert our encoded dataset to torch.tensors and reshape in blocks of the transformer's input length  
for split_name in ['train', 'valid']:  
    tensor = torch.tensor(datasets[split_name], dtype=torch.long)  
    num_sequences = (tensor.size(0) // args.num_max_positions) * args.num_max_positions  
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```

```
▶ model = TransformerWithLMHead(args).to(args.device)  
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Hands-on pre-training

We'll use a pre-defined open vocabulary tokenizer: BERT's model cased tokenizer.

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Hyper-parameters taken from [Dai et al., 2018](#) (Transformer-XL) ⇔ ~50M parameters causal model.

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Use a large dataset for pre-training:
WikiText-103 with 103M tokens ([Merity et al., 2017](#)).

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dataset_file = cached_path("https://s3.amazonaws.com/datasets.huggingface.co/wikitext-103/"  
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    datasets[split_name] = tensor.narrow(0, 0, num_sequences).view(-1, args.num_max_positions)
```

Instantiate our model and optimizer

```
model = TransformerWithLMHead(args).to(args.device)  
optimizer = torch.optim.Adam(model.parameters(), lr=args.lr)
```

Hands-on pre-training



And we're done: let's train!

```
import os
from torch.utils.data import DataLoader
from ignite.engine import Engine, Events
from ignite.metrics import RunningAverage
from ignite.handlers import ModelCheckpoint
from ignite.contrib.handlers import CosineAnnealingScheduler, create_lr_scheduler_with_warmup, ProgressBar

dataloader = DataLoader(datasets['train'], batch_size=args.batch_size, shuffle=True)

# Define training function
def update(engine, batch):
    model.train()
    batch = batch.transpose(0, 1).contiguous().to(args.device) # to shape [seq length, batch]
    logits, loss = model(batch, labels=batch)
    loss = loss / args.gradient_accumulation_steps
    loss.backward()
    torch.nn.utils.clip_grad_norm_(model.parameters(), args.max_norm)
    if engine.state.iteration % args.gradient_accumulation_steps == 0:
        optimizer.step()
        optimizer.zero_grad()
    return loss.item()
trainer = Engine(update)

# Add progressbar with loss
RunningAverage(output_transform=lambda x: x).attach(trainer, "loss")
ProgressBar(persist=True).attach(trainer, metric_names=['loss'])

# Learning rate schedule: linearly warm-up to lr and then decrease the learning rate to zero with cosine
cos_scheduler = CosineAnnealingScheduler(optimizer, 'lr', args.lr, 0.0, len(dataloader) * args.n_epochs)
scheduler = create_lr_scheduler_with_warmup(cos_scheduler, 0.0, args.lr, args.n_warmup)
trainer.add_event_handler(Events.ITERATION_STARTED, scheduler)

# Save checkpoints and training config
checkpoint_handler = ModelCheckpoint(args.log_dir, 'checkpoint', save_interval=1, n_saved=5)
trainer.add_event_handler(Events.EPOCH_COMPLETED, checkpoint_handler, {'mymodel': model})
torch.save(args, os.path.join(args.log_dir, 'training_args.bin'))
```



```
trainer.run(train_dataloader, max_epochs=args.n_epochs)
```

...

Epoch [1/50]

[365/28874] 1%| , loss=2.30e+00 [03:43<4:52:22]



Hands-on pre-training

And we're done: let's train!

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trainer.run(train_dataloader, max_epochs=args.n_epochs)
```



trainer.run(train_dataloader, max_epochs=args.n_epochs)

41



... Epoch [1/50]

[365/28874] 1%|| , loss=2.30e+00 [03:43<4:52:22]

Hands-on pre-training



And we're done: let's train!

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torch.save(args, os.path.join(args.log_dir, 'training_args.bin'))
```



```
trainer.run(train_dataloader, max_epochs=args.n_epochs)
```

Go!

→

... Epoch [1/50]

[365/28874] 1% | loss=2.30e+00 [03:43<4:52:22]

Hands-on pre-training — Concluding remarks

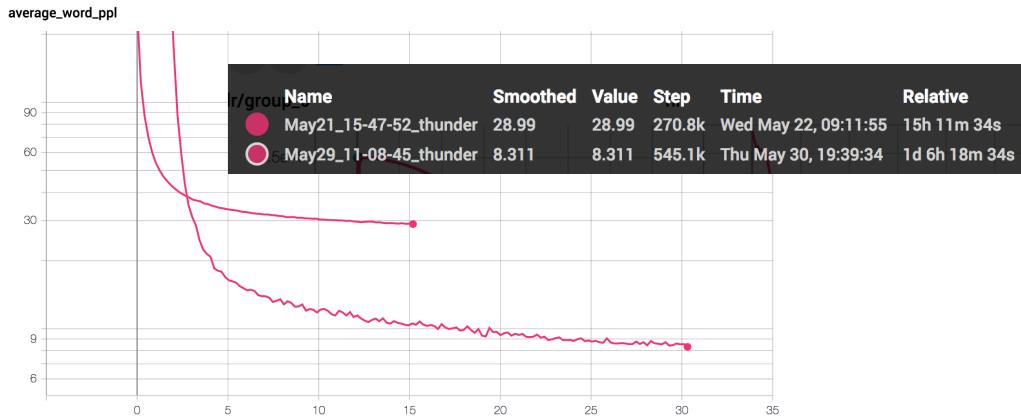


- ❑ On pretraining
 - ❑ **Intensive**: in our case 5h–20h on 8 V100 GPUs (few days w. 1 V100) to reach a good perplexity
⇒ share your pretrained models
 - ❑ **Robust to the choice of hyper-parameters** (apart from needing a warm-up for transformers)
 - ❑ Language modeling is a hard task, your model should **not have enough capacity to overfit** if your dataset is large enough ⇒ you can just start the training and let it run.
 - ❑ **Masked-language modeling**: typically 2-4 times slower to train than causal LM
We only mask 15% of the tokens ⇒ smaller signal

Hands-on pre-training – Concluding remarks



- ❑ First model:
 - ❑ exactly the one we built together ⇒ a 50M parameters causal Transformer
 - ❑ Trained 15h on 8 V100
 - ❑ Reached a **word-level perplexity of 29** on wikitext-103 validation set (quite competitive)
- ❑ Second model:
 - ❑ Same model but trained with a **masked-language modeling** objective (see the repo)
 - ❑ Trained 30h on 8 V100
 - ❑ Reached a “masked-word” perplexity of 8.3 on wikitext-103 validation set

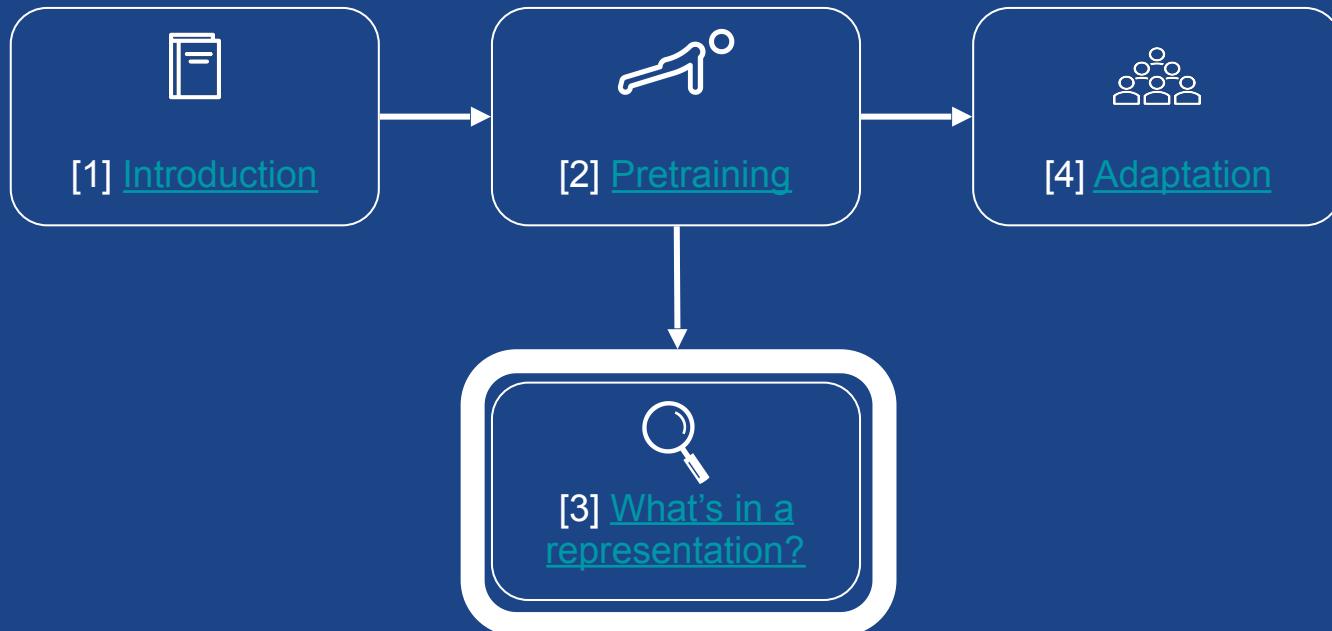


Model	#Params	Validation PPL	Test PPL
Grave et al. (2016b) – LSTM	-	-	48.7
Bai et al. (2018) – TCN	-	-	45.2
Dauphin et al. (2016) – GCNN-8	-	-	44.9
Grave et al. (2016b) – LSTM + Neural cache	-	-	40.8
Dauphin et al. (2016) – GCNN-14	-	-	37.2
Merity et al. (2018) – 4-layer QRNN	151M	32.0	33.0
Rae et al. (2018) – LSTM + Hebbian + Cache	-	29.7	29.9
Ours – Transformer-XL Standard	151M	23.1	24.0
Baevski & Auli (2018) – adaptive input [◦]	247M	19.8	20.5
Ours – Transformer-XL Large	257M	17.7	18.3

Wikitext-103 Validation/Test PPL

[Dai et al., 2018](#)

Agenda



3. What is in a Representation?



Why care about what is in a representation?



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- ❑ Alternative to Extrinsic evaluation with downstream tasks
 - ❑ Complex, diverse with task-specific quirks



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- ❑ Alternative to Extrinsic evaluation with downstream tasks
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- ❑ Measures language-awareness of representations
 - ❑ To generalize to other tasks, new inputs
 - ❑ As intermediates for possible improvements to pretraining

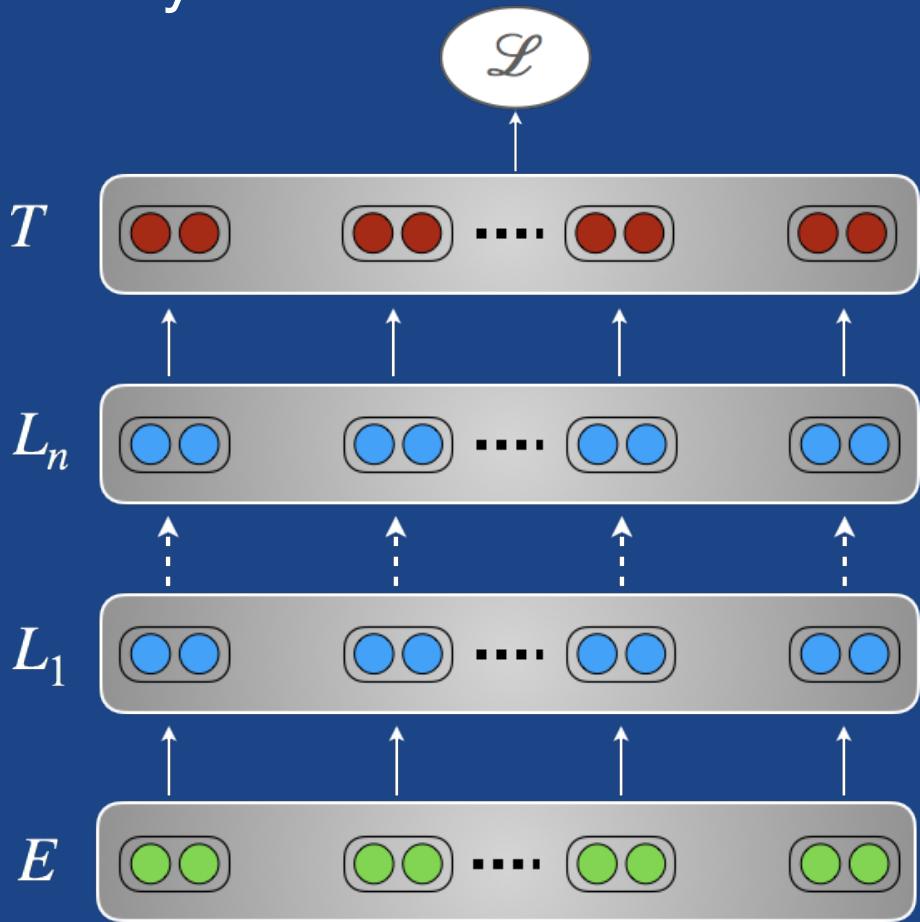


Why care about what is in a representation?

- ❑ Alternative to Extrinsic evaluation with downstream tasks
 - ❑ Complex, diverse with task-specific quirks
- ❑ Measures language-awareness of representations
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 - ❑ As intermediates for possible improvements to pretraining
- ❑ Interpretability!
 - ❑ Are we getting our results because of the right reasons?
 - ❑ Uncovering biases...



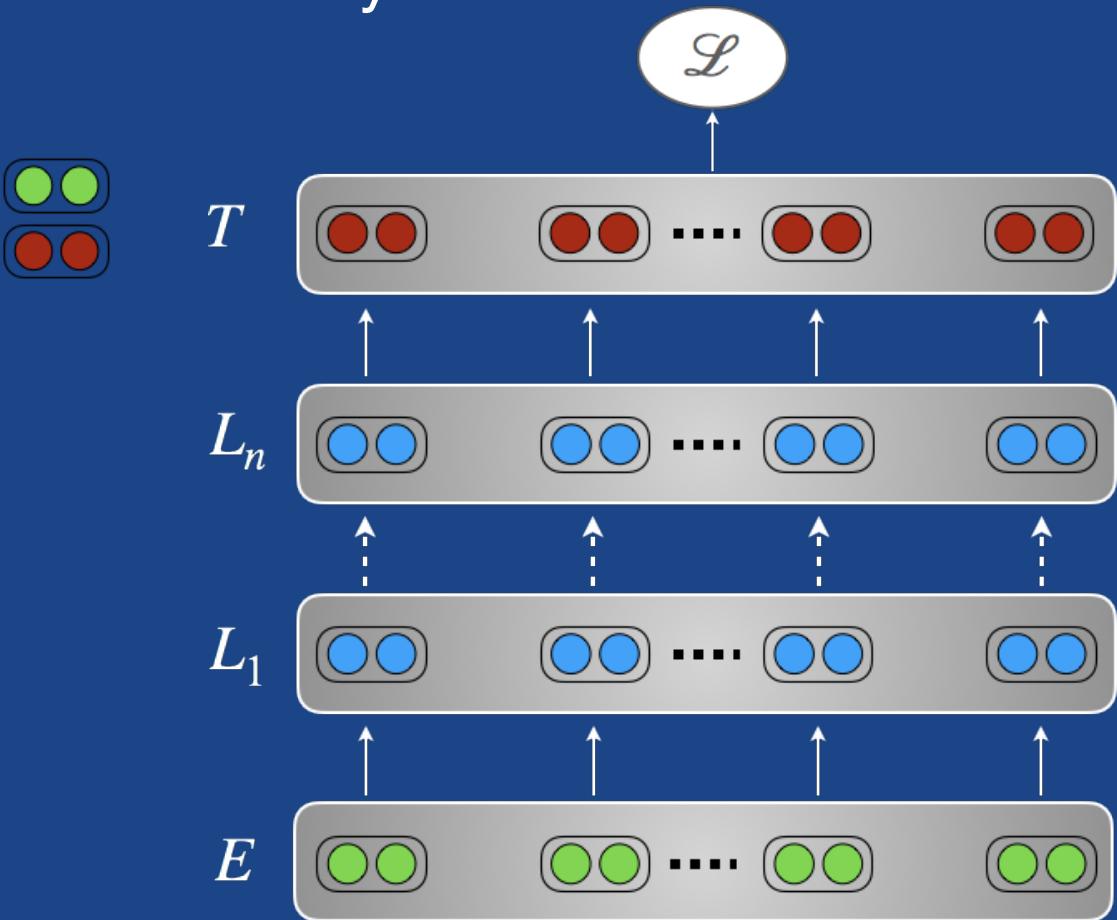
What to analyze?



What to analyze?

❑ Embeddings

- ❑ Word
- ❑ Contextualized

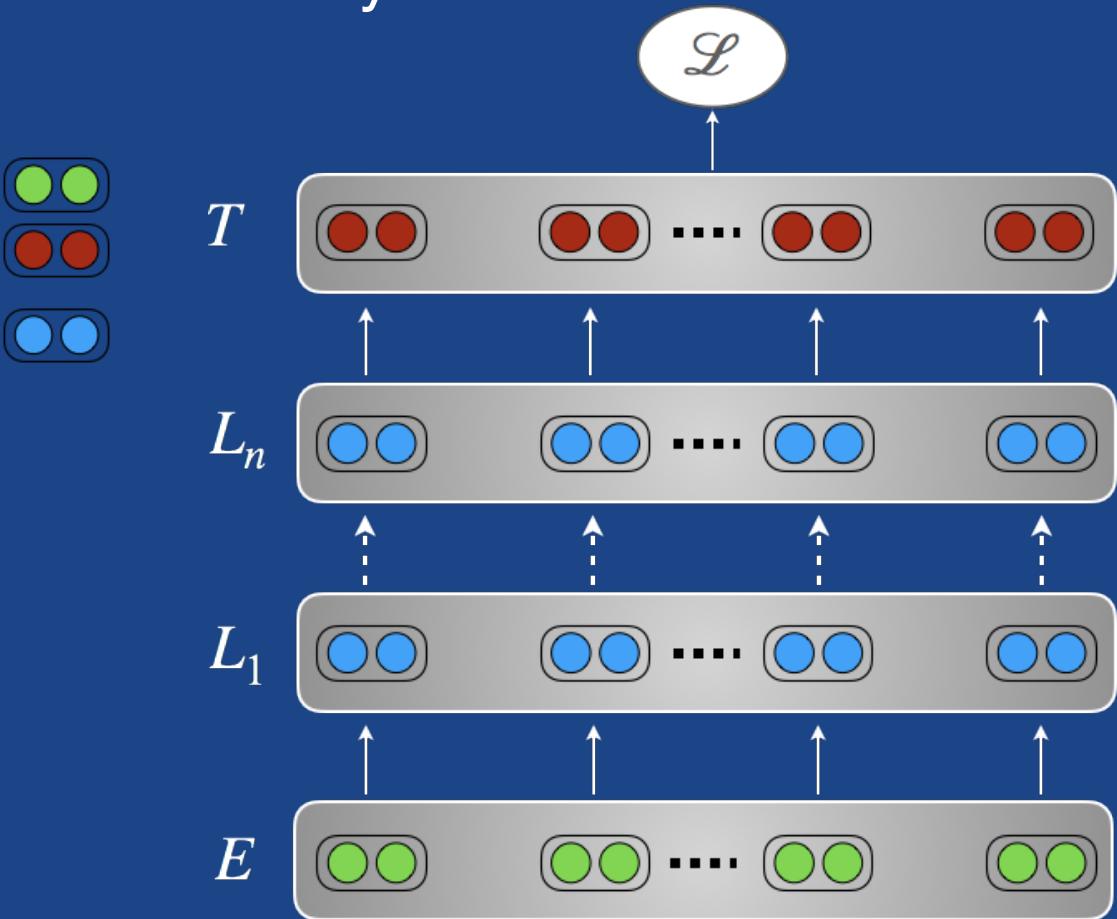


What to analyze?

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What to analyze?

- ❑ Embeddings

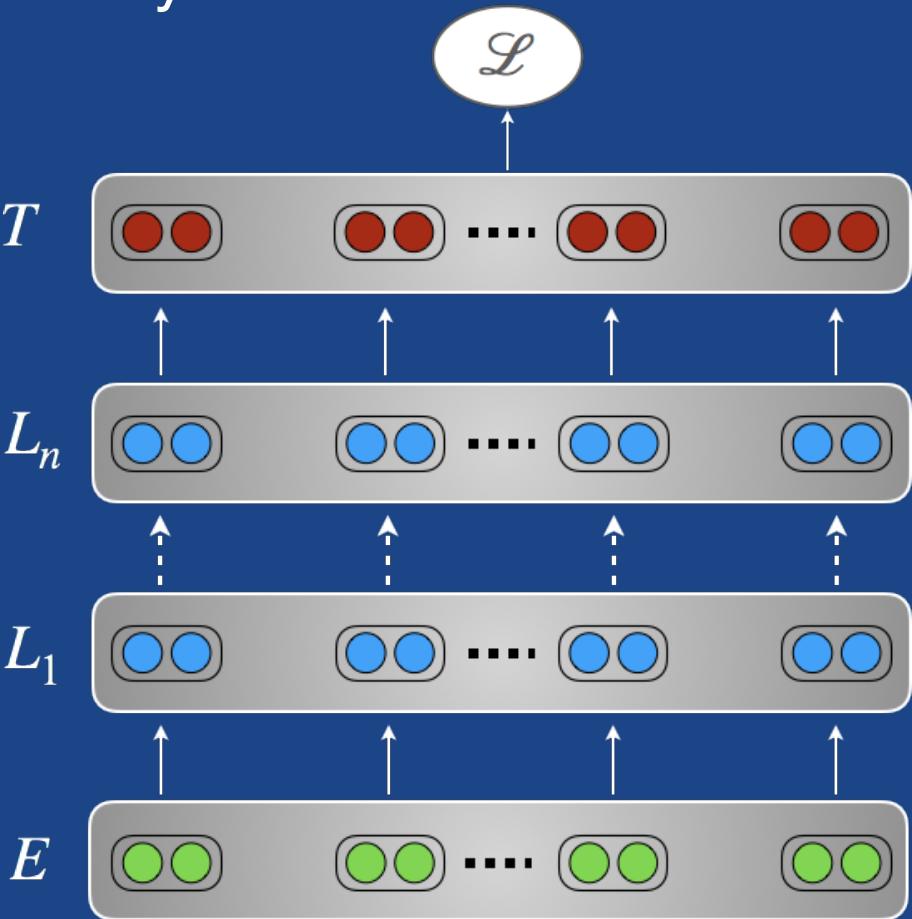
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- ❑ Network Activations

- ❑ Alterations:

- ❑ Architecture
 - ❑ (RNN / Transformer)



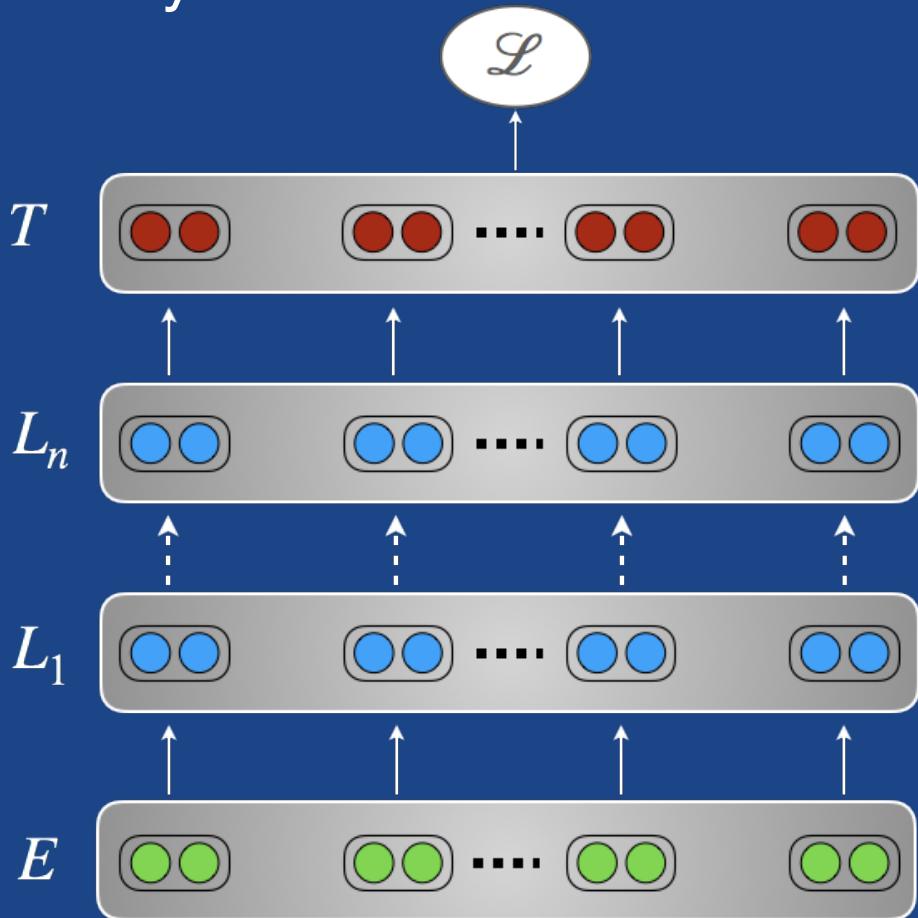
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Alterations:

- Architecture
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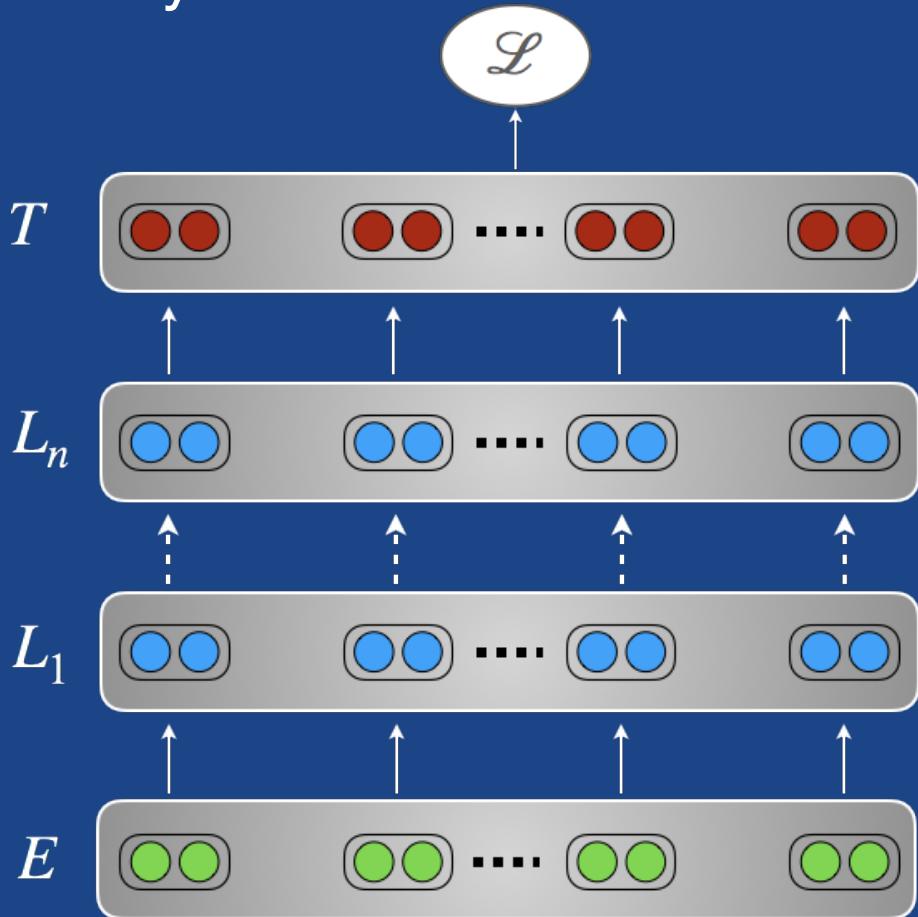


Network Activations



Alterations:

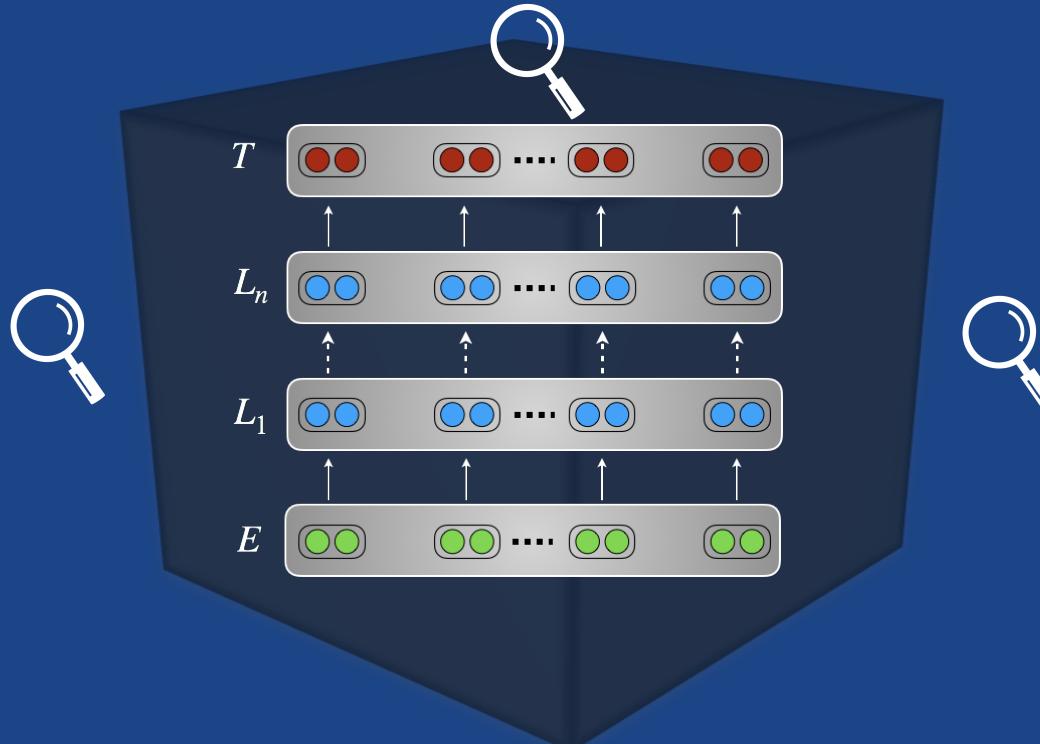
- Architecture
 - (RNN / Transformer)
- Layers
- Pretraining Objectives



Analysis Method 1: Visualization



Hold the embeddings / network activations static or **frozen**



Visualizing Embedding Geometries

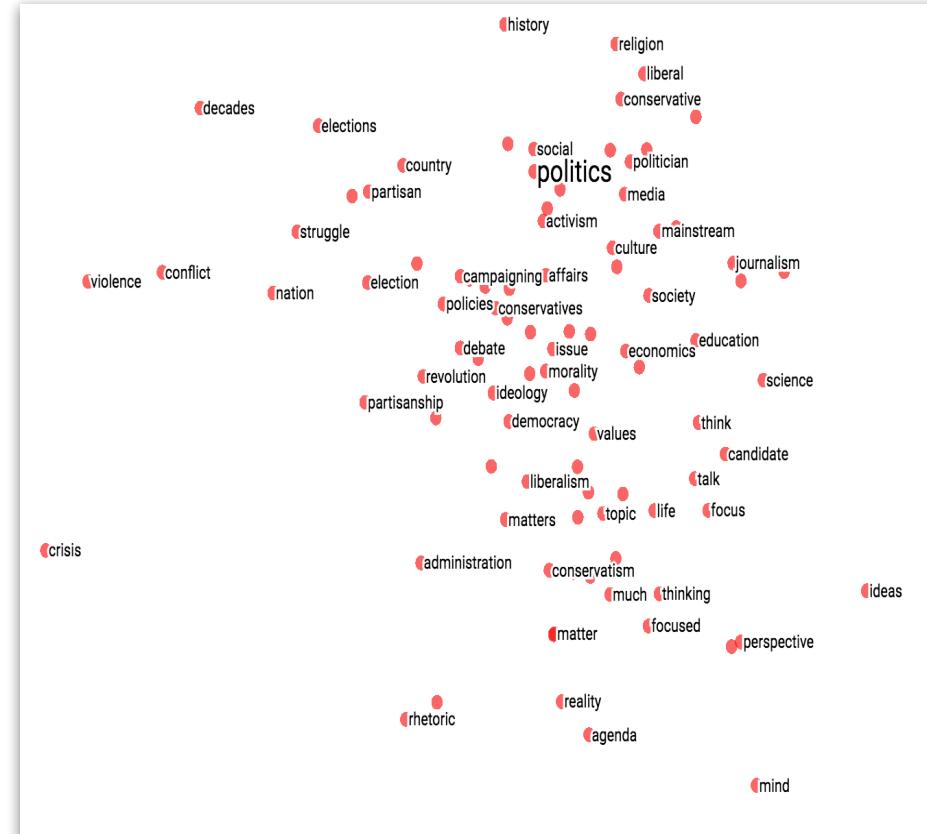


- ❑ Plotting embeddings **faithfully** into a lower dimensional (2D/3D) space
 - ❑ t-SNE [van der Maaten & Hinton, 2008](#)
 - ❑ PCA projections

Visualizing Embedding Geometries



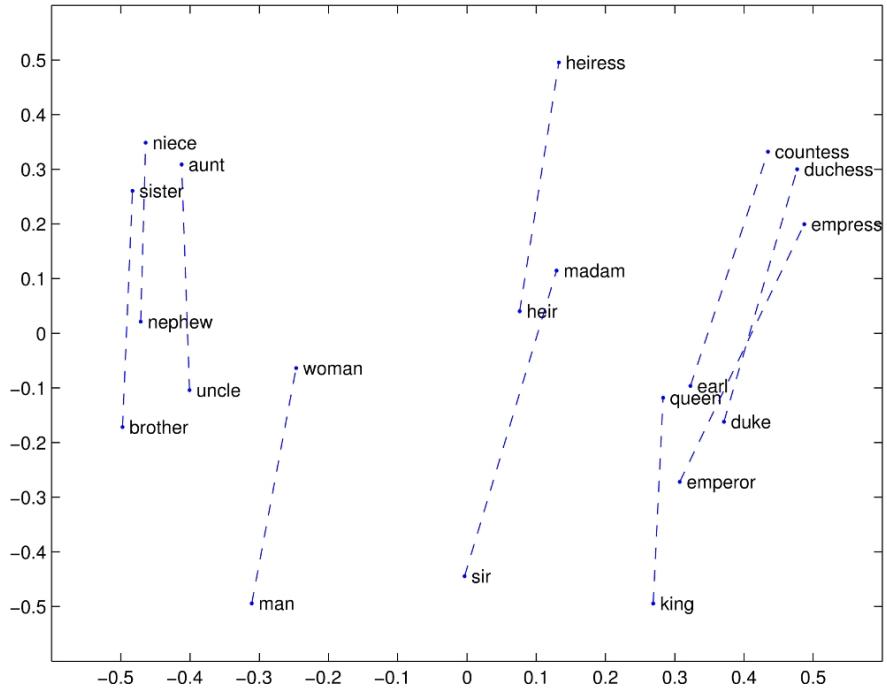
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Visualizing Embedding Geometries



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 - ❑ t-SNE [van der Maaten & Hinton, 2008](#)
 - ❑ PCA projections
- ❑ Visualizing word analogies [Mikolov et al. 2013](#)
 - ❑ Spatial relations
 - ❑ $W_{\text{king}} - W_{\text{man}} + W_{\text{woman}} \sim W_{\text{queen}}$

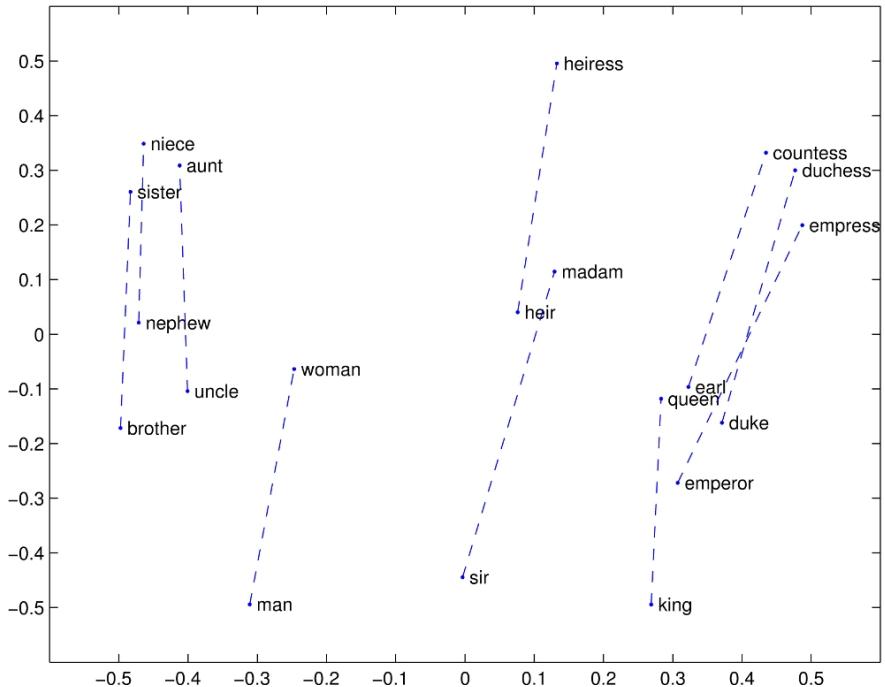


[Pennington et al., 2014](#)

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- ❑ High-level view of lexical semantics
 - ❑ Only a limited number of examples
 - ❑ Connection to other tasks is unclear
[Goldberg, 2017](#)



[Pennington et al., 2014](#)

Visualizing Neuron Activations



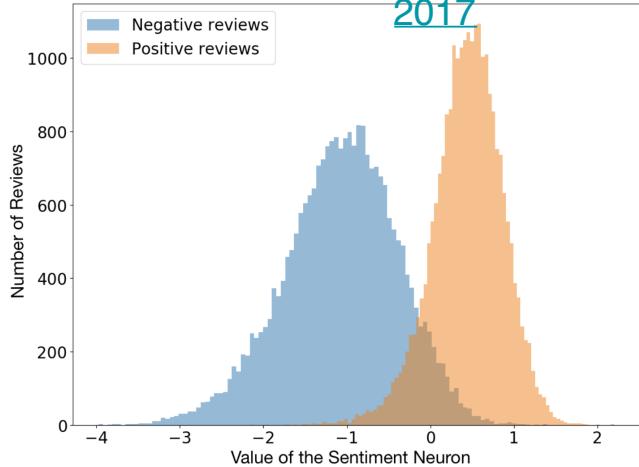
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Visualizing Neuron Activations



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[Radford et al.,
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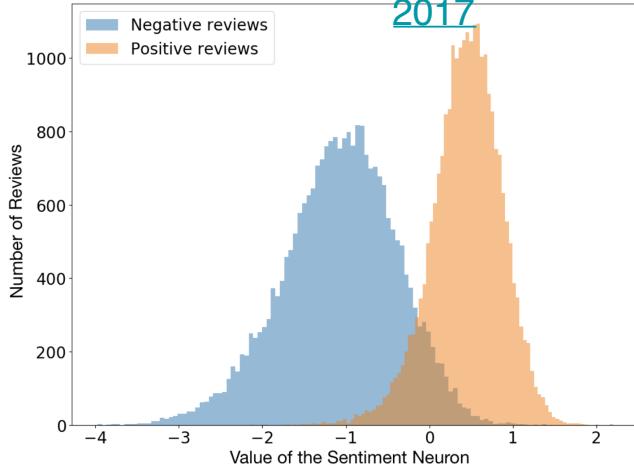


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Cell that is sensitive to the depth of an expression:

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            if (mask[i] & classes[class][i])
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    return 1;
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[Karpathy et al., 2016](#)

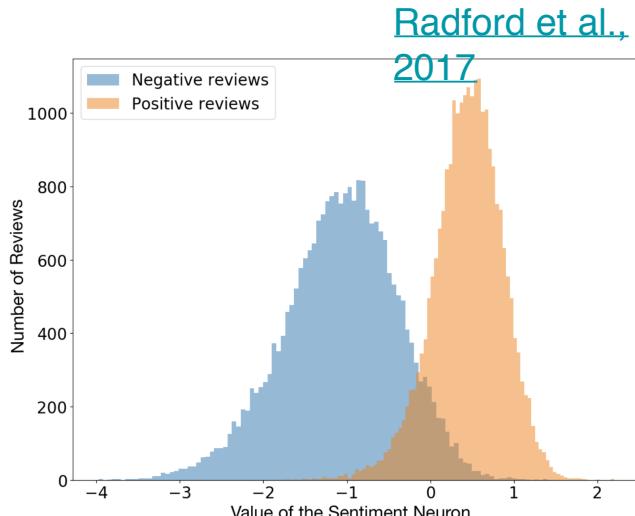
Visualizing Neuron Activations



- ❑ Neuron activation values correlate with features / labels
- ❑ Indicates learning of recognizable features
 - ❑ How to select which neuron? Hard to scale!
 - ❑ Interpretable != Important ([Morcos et al., 2018](#))

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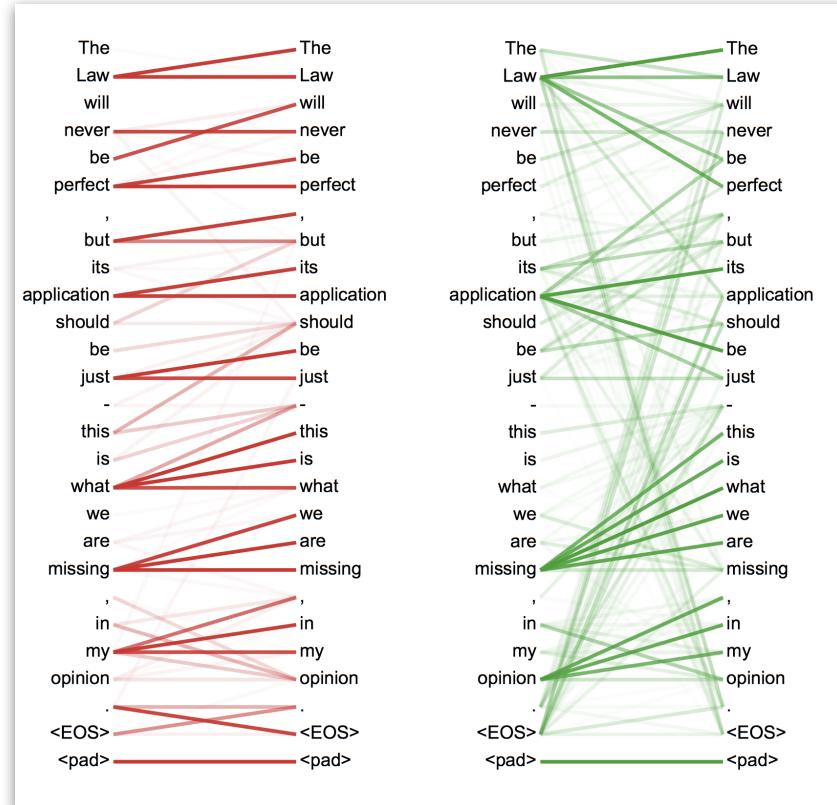


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Visualizing Attention Weights



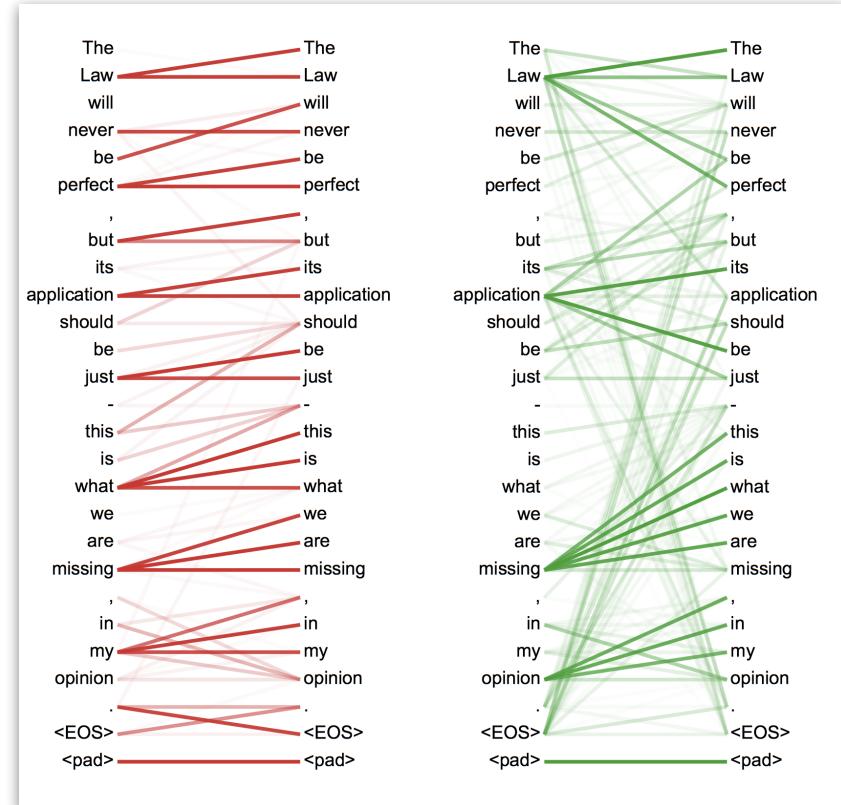
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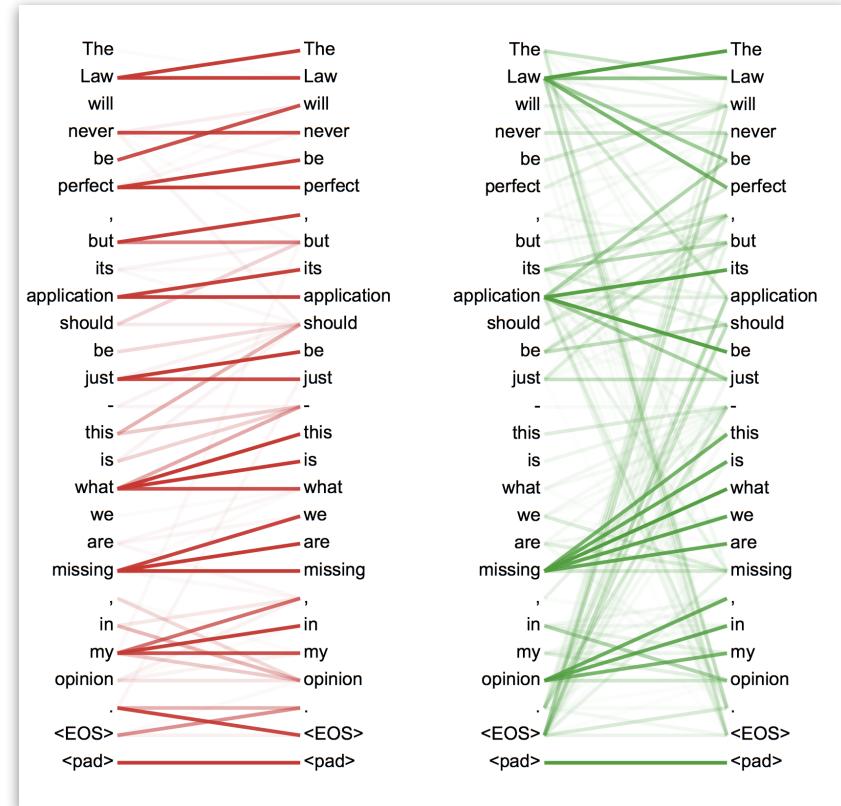
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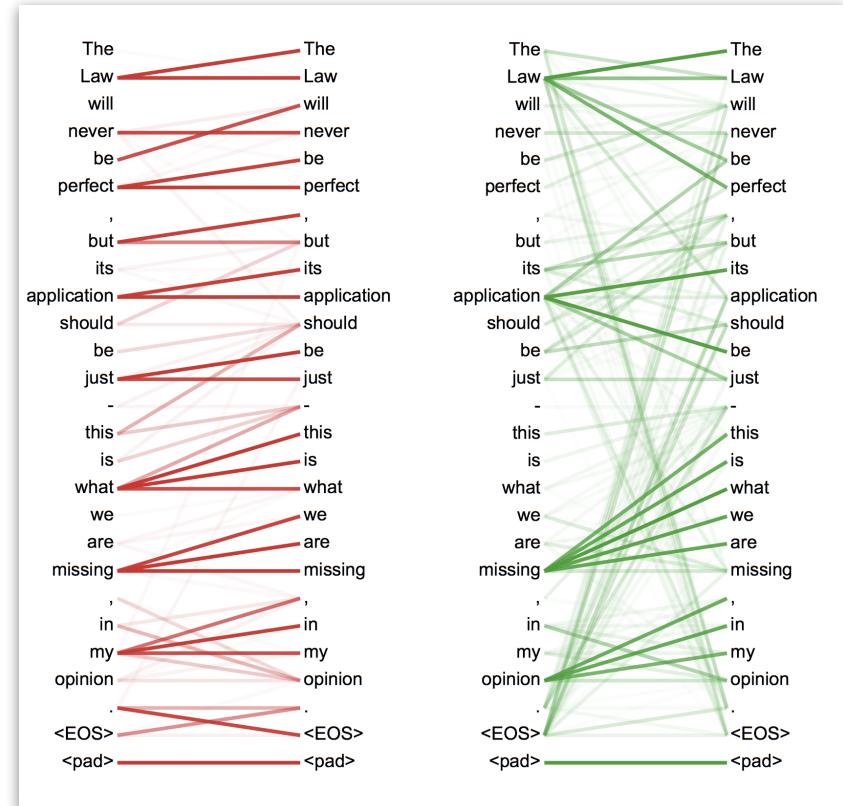
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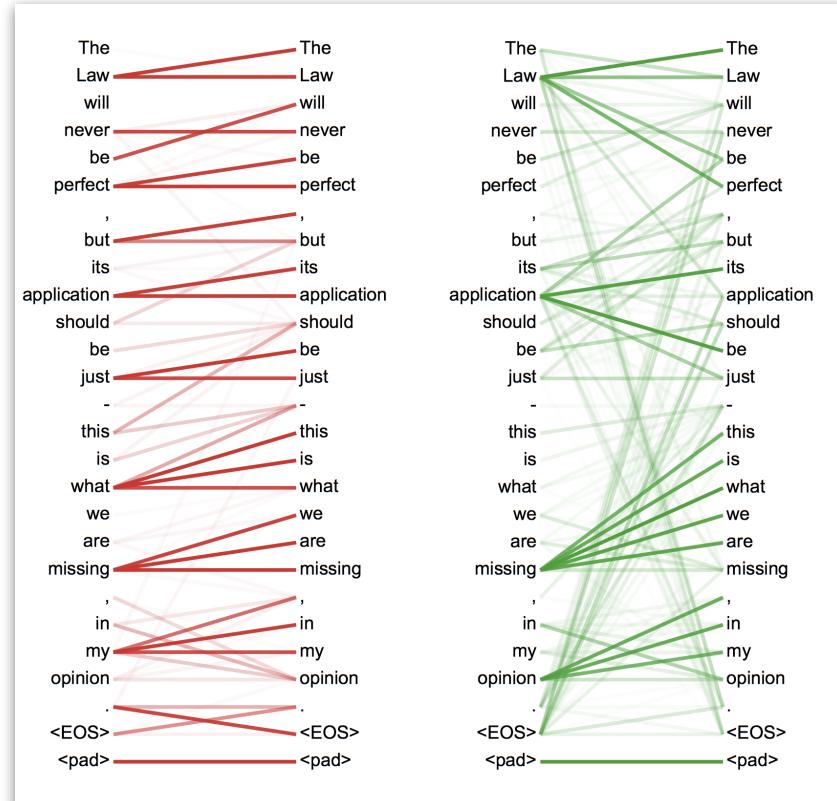
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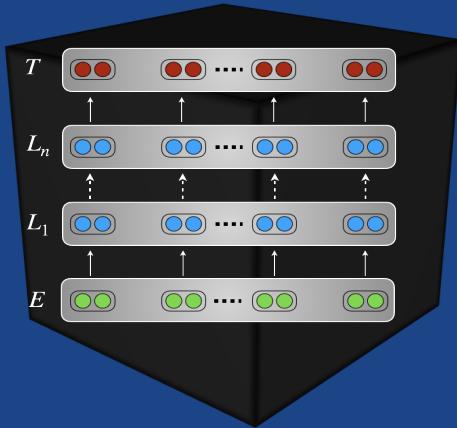
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 - ❑ Having sophisticated attention mechanisms can be a good thing!
 - ❑ Layer-specific (layer 5 / layer 6 in fig.)
- ❑ Interpretation can be tricky
 - ❑ Few examples only - cherry picking?
 - ❑ Robust **corpus-wide** trends? Next!

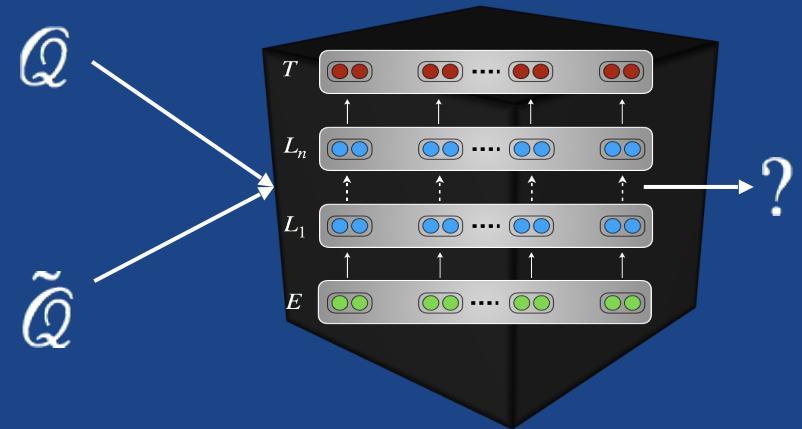


Analysis Method 2: Behavioral Probes



[Linzen et al., 2016](#); [Gulordava et al. 2018](#); [Marvin et al., 2018](#)

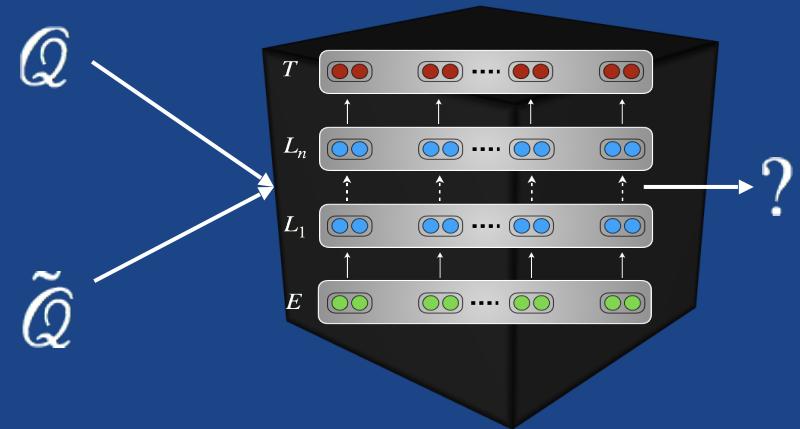
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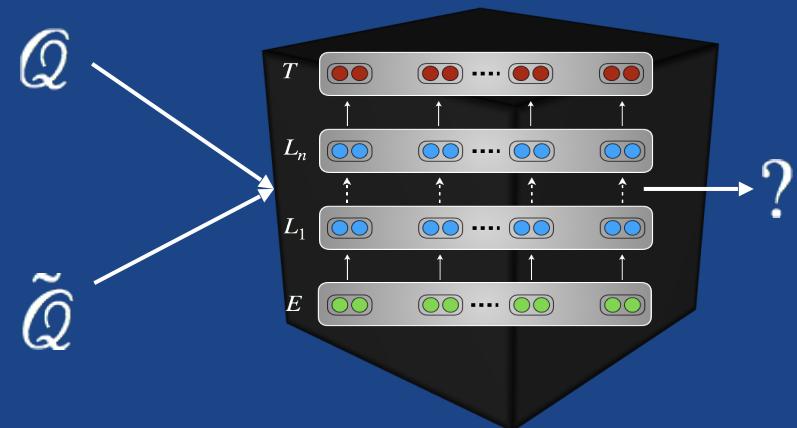
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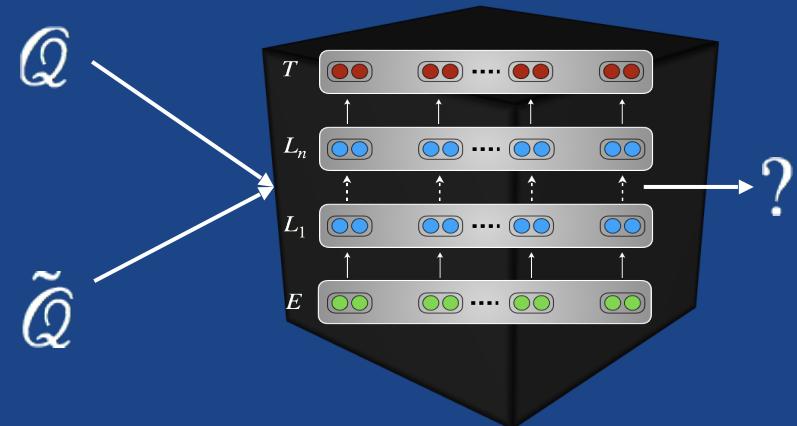


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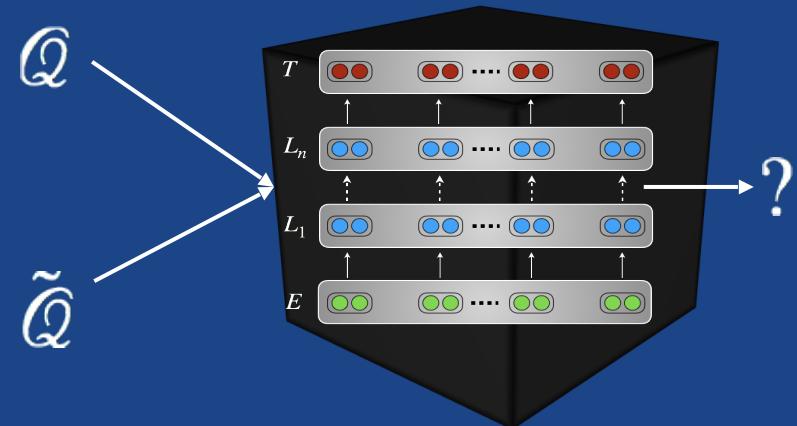


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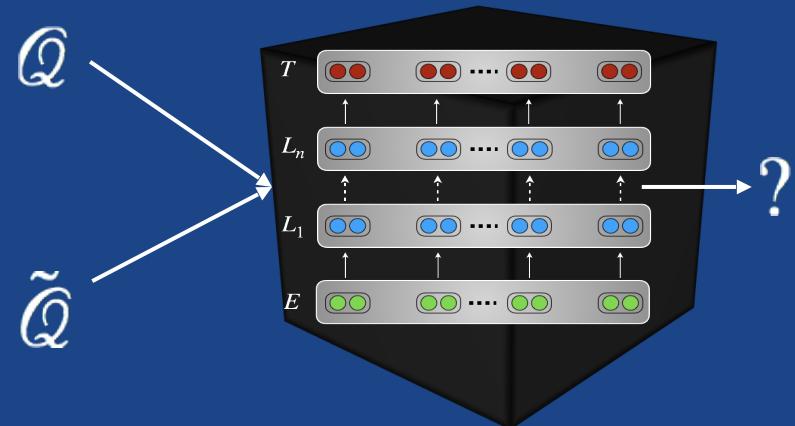


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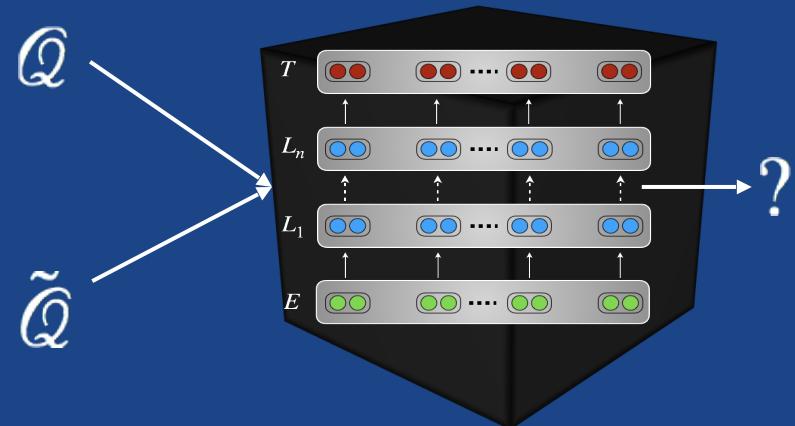


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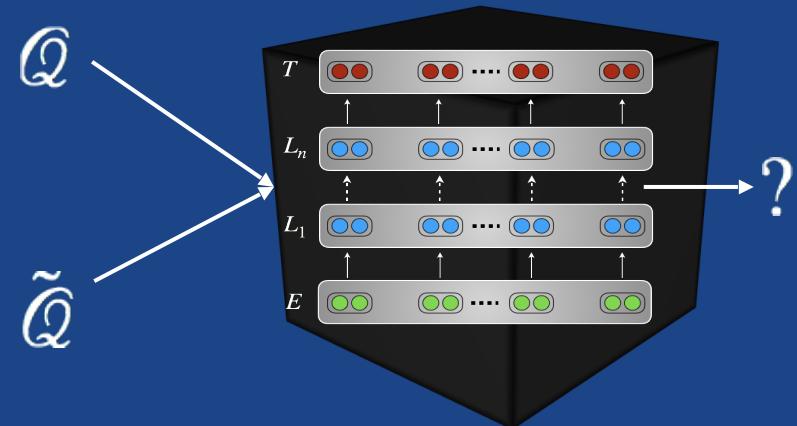


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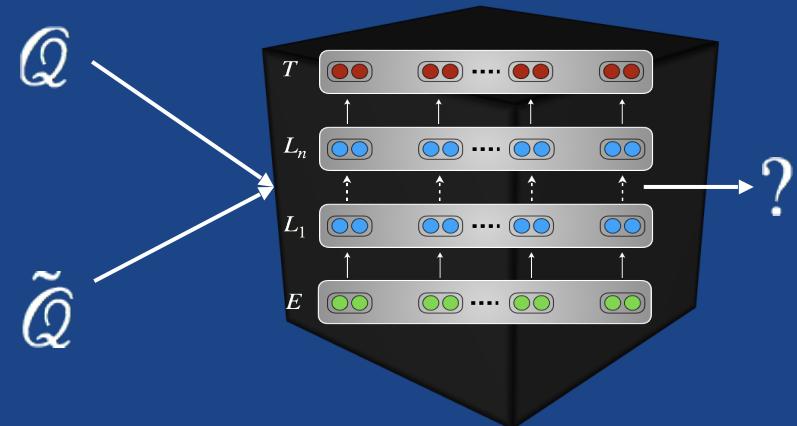


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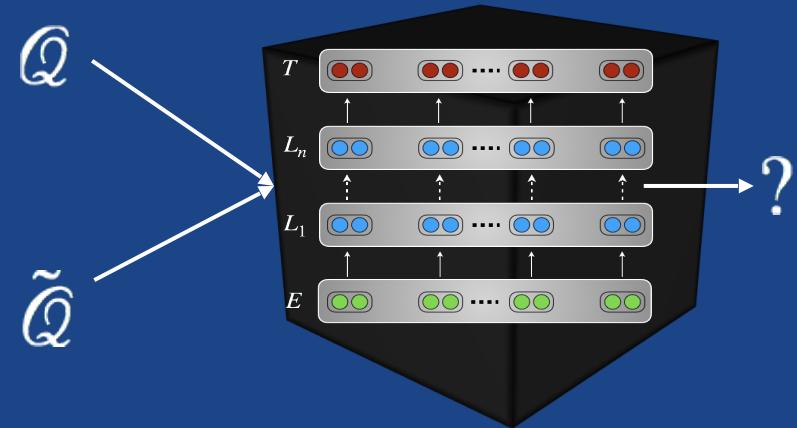


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 - Nonce sentences might be too different from original...



[Kuncoro et al. 2018](#)

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Analysis Method 3: Classifier Probes

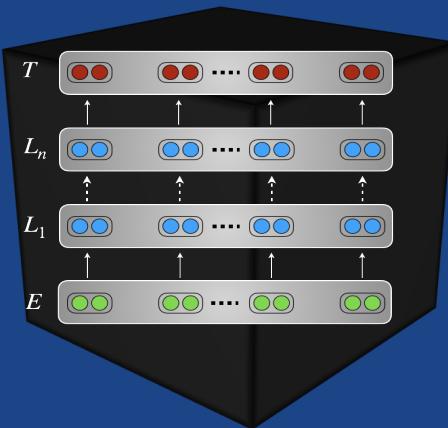


Hold the embeddings / network

activations static and

train a **simple supervised**

model on top



Analysis Method 3: Classifier Probes



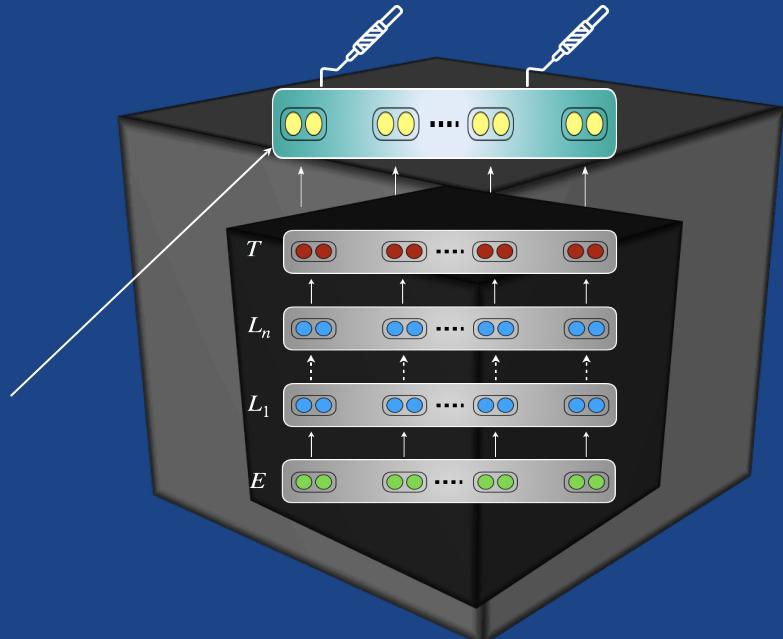
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Probe classification task
(Linear / MLP)



Probing Surface-level Features

[Zhang et al. 2018](#); [Liu et al., 2018](#); [Conneau et al., 2018](#)

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- ❑ Given a sentence, predict properties such as
 - ❑ Length
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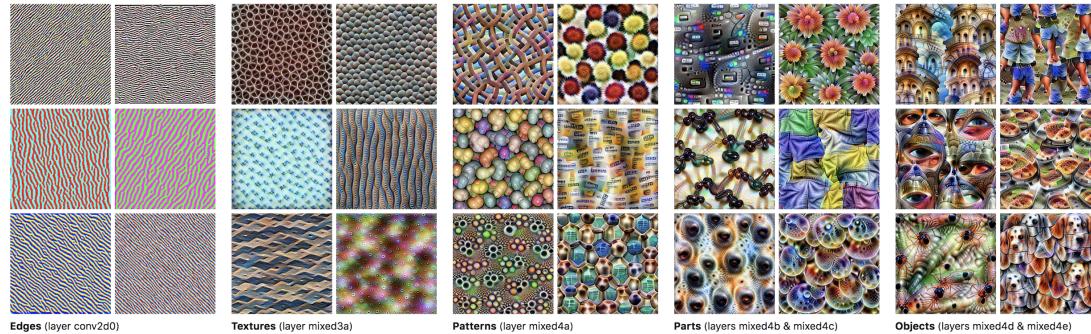
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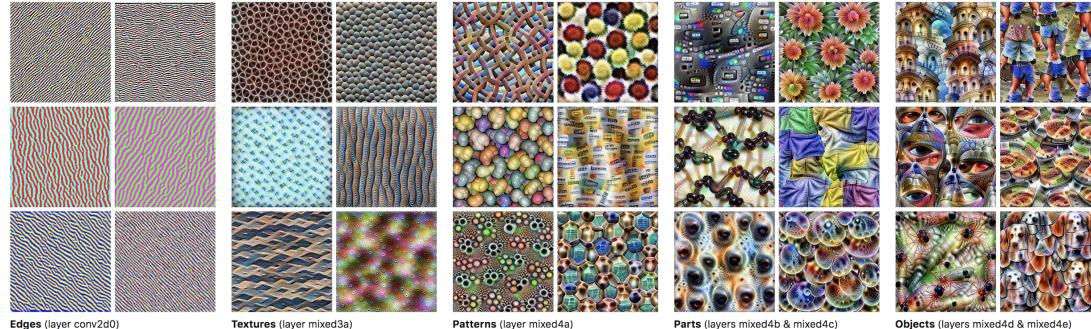
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Probing: Layers of the network



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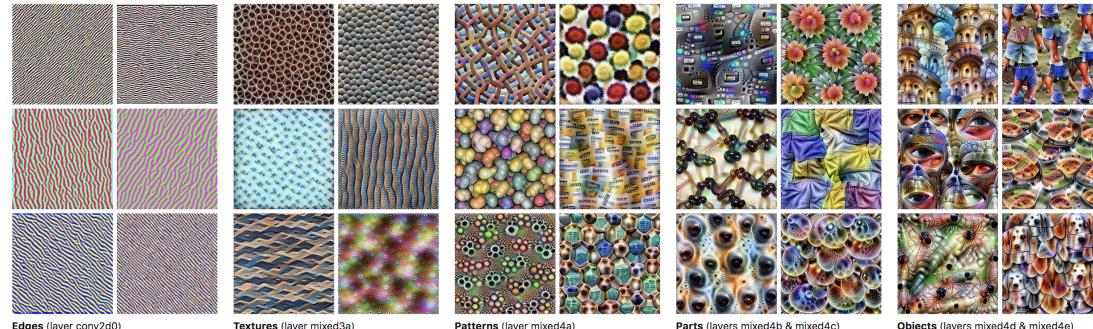
❑ RNN layers: General linguistic properties

- ❑ Lowest layers: **morphology**
- ❑ Middle layers: **syntax**
- ❑ Highest layers: Task-specific **semantics**

❑ Transformer layers:

- ❑ Different trends for different tasks; **middle-heavy**
- ❑ Also see [Tenney et. al., 2019](#)

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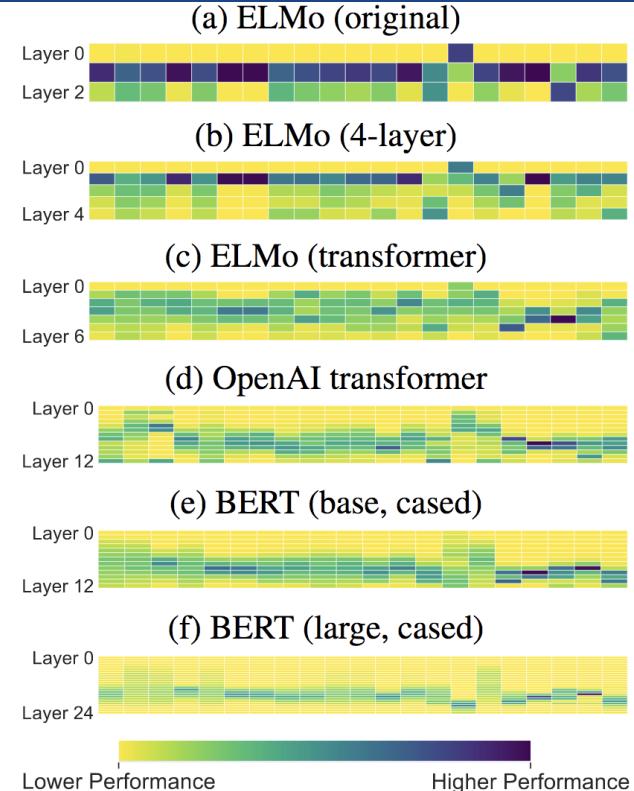


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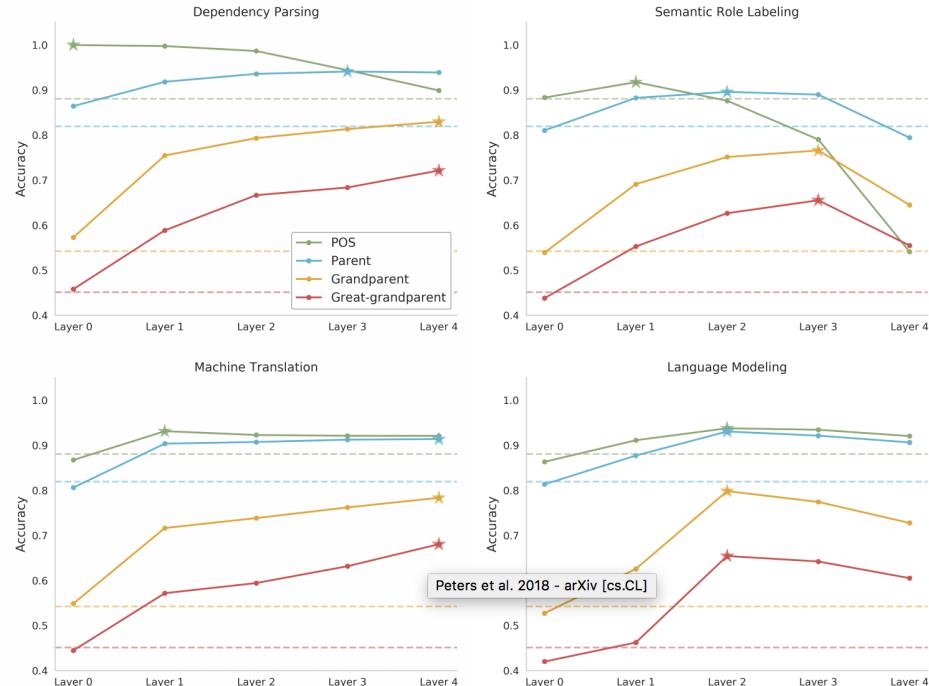
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[Fig. from Liu et al. \(NAACL 2019\)](#)

Probing: Pretraining Objectives

- ❑ Language modeling **outperforms** other unsupervised and supervised objectives.
 - ❑ Machine Translation
 - ❑ Dependency Parsing
 - ❑ Skip-thought
- ❑ **Low-resource** settings (size of training data) might result in opposite trends.



[Zhang et al., 2018](#); [Blevins et al., 2018](#); [Liu et al., 2019](#);

What have we learnt so far?



- ❑ Representations are **predictive** of certain linguistic phenomena:
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- ❑ Network architectures determine what is in a representation
 - ❑ Syntax and BERT Transformer ([Tenney et al., 2019](#); [Goldberg, 2019](#))
 - ❑ Different layer-wise trends across architectures

Open questions about probes



- ❑ What information should a good probe look for?
 - ❑ Probing a probe!

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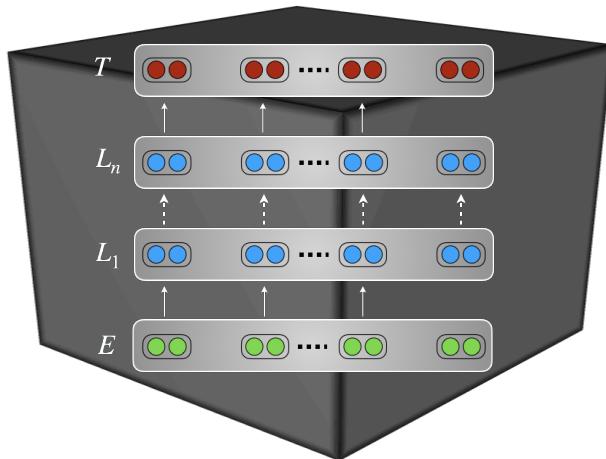


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- ❑ Should we be using **probes as evaluation metrics**?
 - ❑ might defeat the purpose...

Analysis Method 4: Model Alterations



- ❑ Progressively erase or mask network components
 - ❑ Word embedding dimensions
 - ❑ Hidden units
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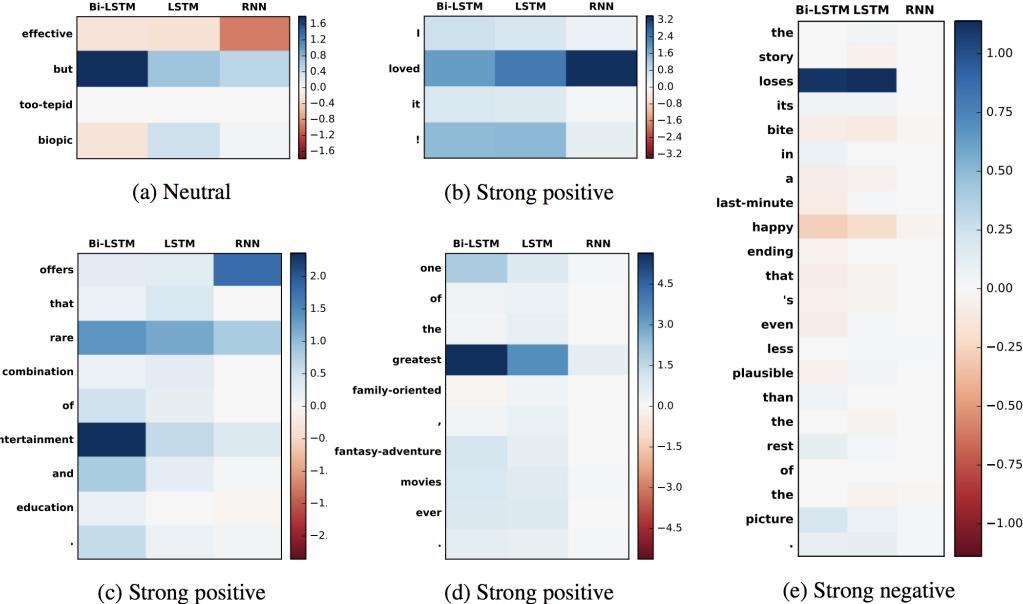
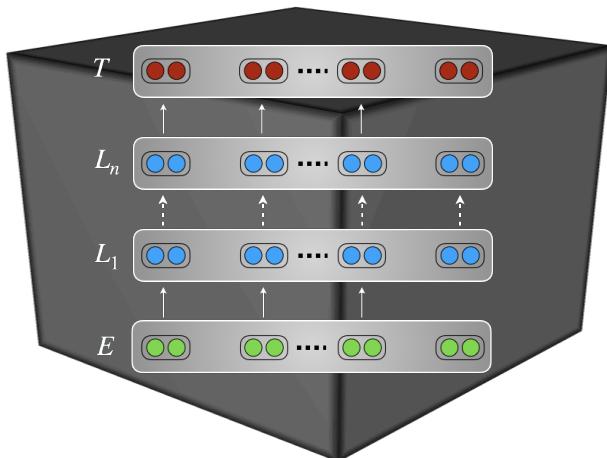
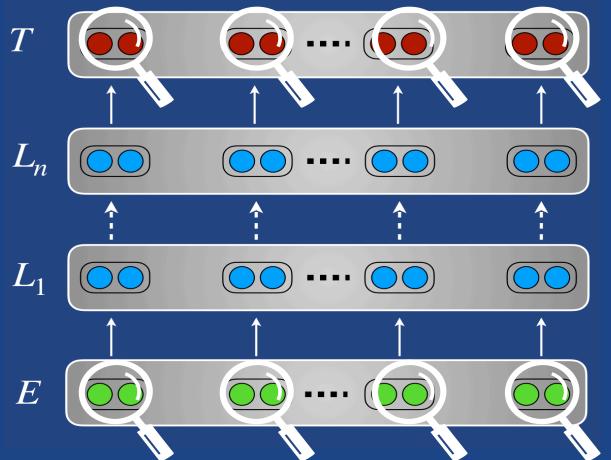


Figure 5: Heatmap of word importance (computed using Eq. 1) in sentiment analysis.

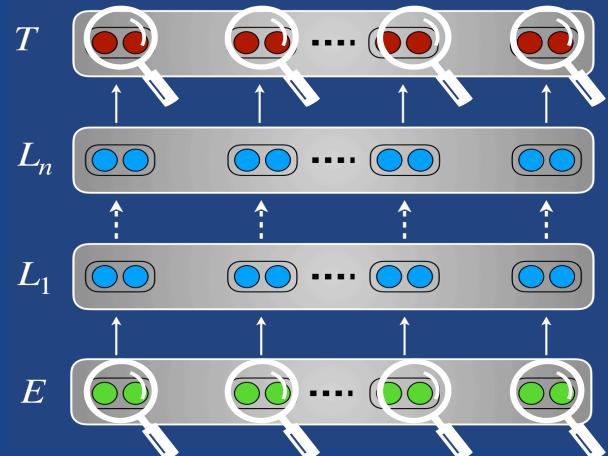
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So, what is in a representation?



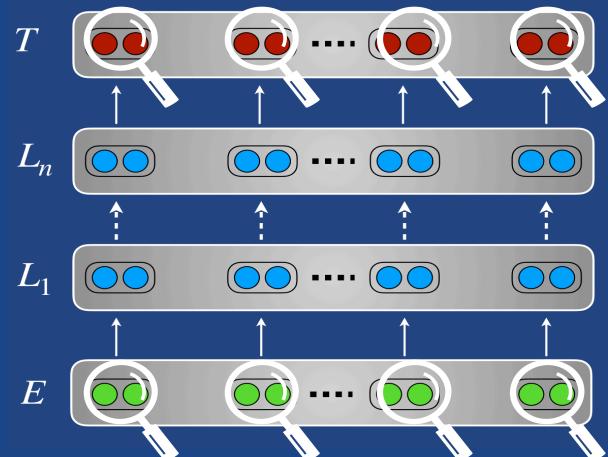
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- ❑ Visualization:
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- ❑ Probes:
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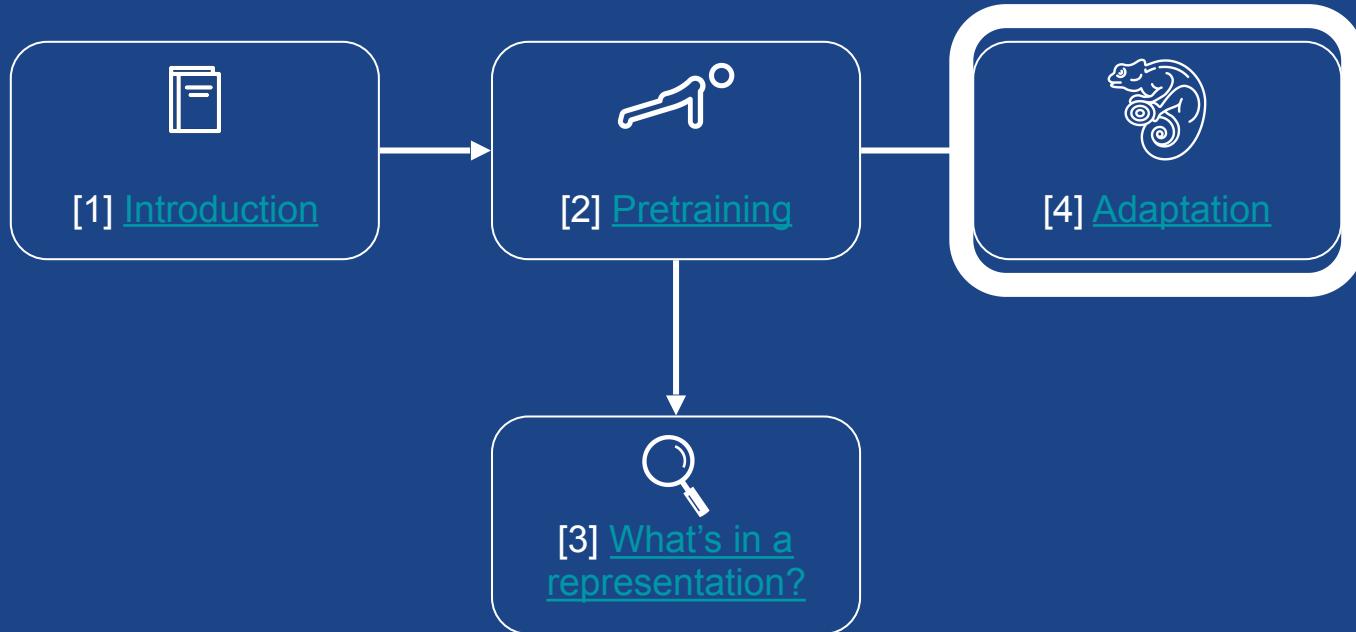


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- ❑ Analysis methods as tools to aid model development!



Agenda

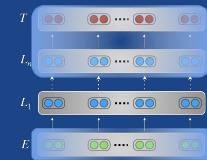
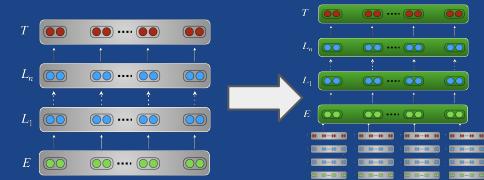


4. Adaptation



4 – How to adapt the pretrained model

Several orthogonal directions we can make decisions on:

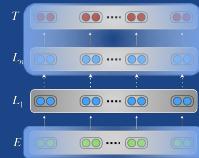
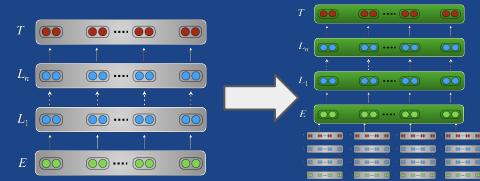


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1. Architectural modifications?

How much to change the pretrained model architecture for adaptation

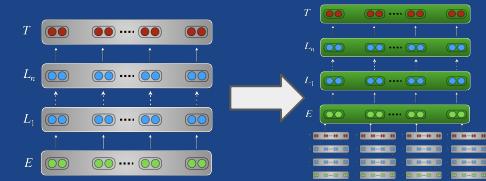


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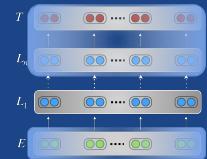
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2. Optimization schemes?

Which weights to train during adaptation and following what schedule



4.1 – Architecture

Two general options:

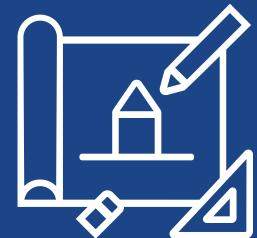
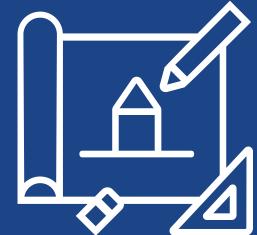


Image credit:
Darmawansyah

4.1 – Architecture

Two general options:



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4.1 – Architecture

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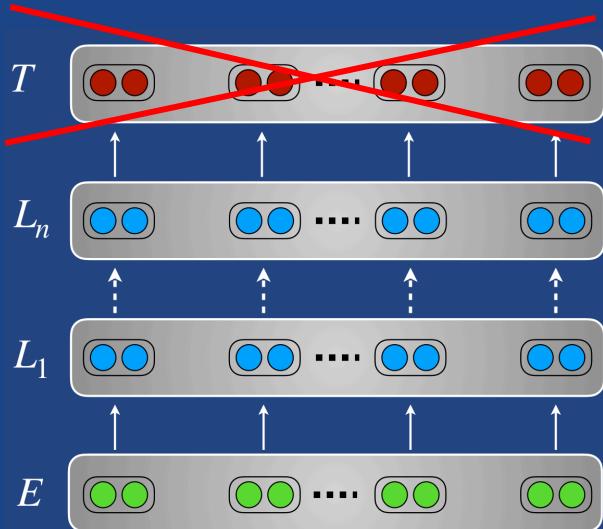
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- B. **Modify pretrained model internal architecture:**

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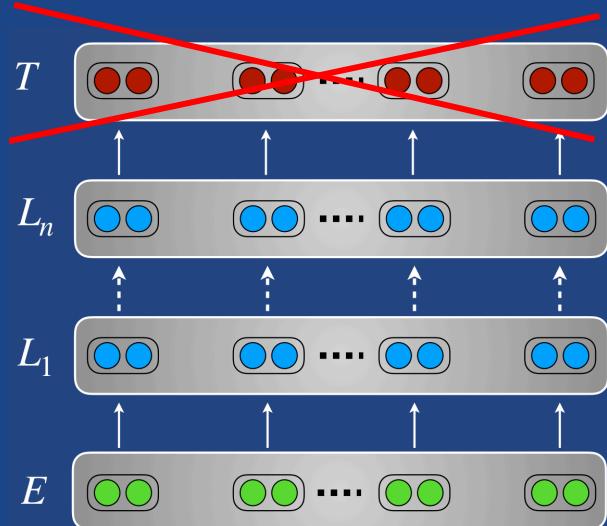
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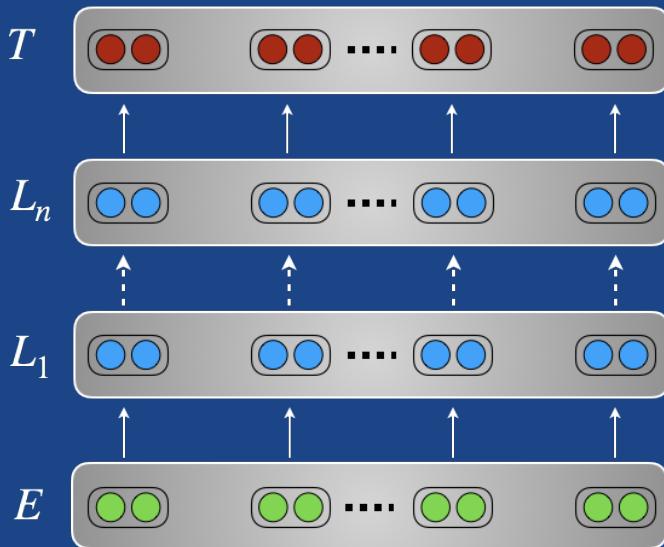
General workflow:

1. Remove pretraining task head if not useful for target task
 - a. Example: remove softmax classifier from pretrained LM
 - b. Not always needed: some adaptation schemes reuse the pretraining objective/task, e.g. for **multi-task learning**



4.1.A – Architecture: Keep model unchanged

General workflow:

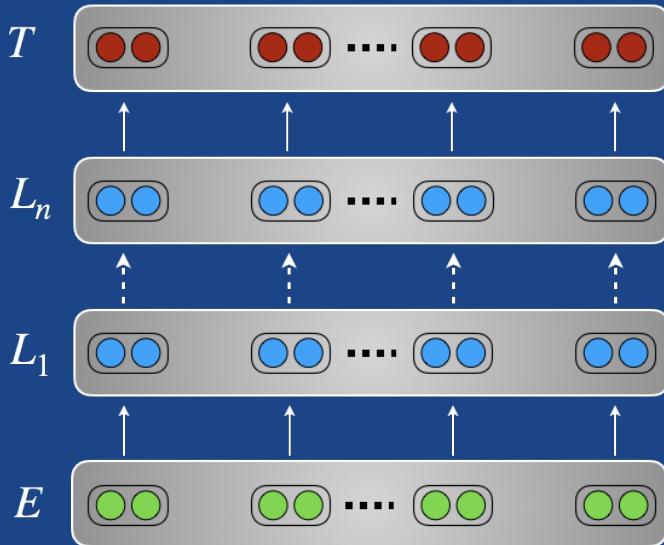


Also known as finetuning*

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General workflow:

2. Add target task-specific layers on top/bottom of pretrained model
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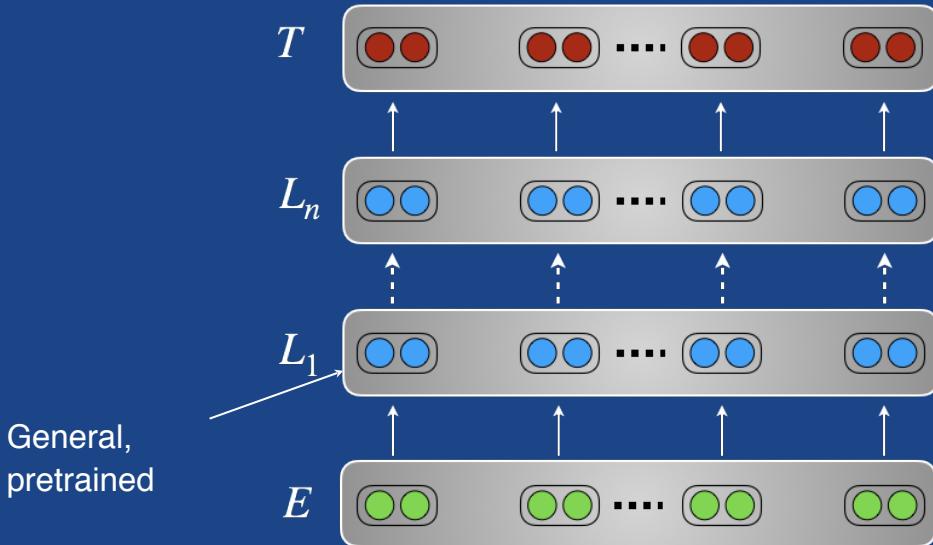


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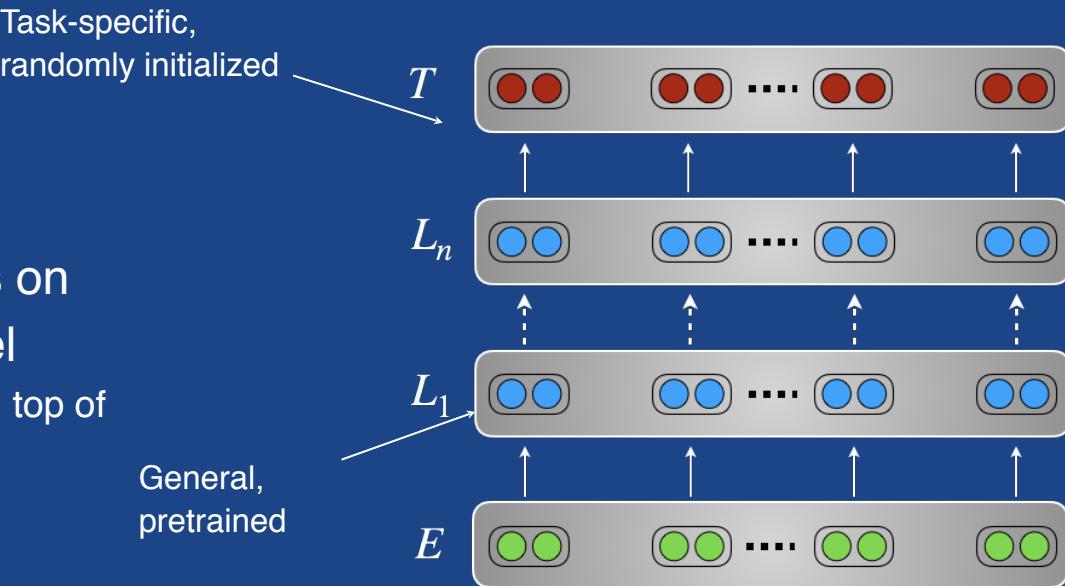


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Also known as finetuning*

Hands-on #2: Adapting our pretrained model



Hands-on: Model adaptation



Let's see how a simple fine-tuning scheme can be implemented with our pretrained model:

❑ Plan

- ❑ Start from our Transformer language model
- ❑ Adapt the model to a target task:
 - ❑ *keep the model **core unchanged**, load the pretrained weights*
 - ❑ *add a linear layer **on top**, newly initialized*
 - ❑ *use additional embeddings **at the bottom**, newly initialized*

Hands-on: Model adaptation



Adaptation task

- ❑ We select a text classification task as the downstream task
- ❑ TREC-6: The Text REtrieval Conference (TREC) Question Classification ([Li et al., COLING 2002](#))
- ❑ TREC consists of open-domain, fact-based questions divided into broad semantic categories contains 5500 labeled training questions & 500 testing questions with 6 labels:
NUMERIC, LOCATION, HUMAN, DESCRIPTION, ENTITY, ABBREVIATION

Hands-on: Model adaptation



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Ex:

- ★ How did serfdom develop in and then leave Russia ? → *DESCRIPTION*
- ★ What films featured the character Popeye Doyle ? → *ENTITY*

Hands-on: Model adaptation



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Ex:

- ★ How did serfdom develop in and then leave Russia ? → *DESCRIPTION*
- ★ What films featured the character Popeye Doyle ? → *ENTITY*

	Model	Test
TREC-6	CoVe (McCann et al., 2017)	4.2
	TBCNN (Mou et al., 2015)	4.0
	LSTM-CNN (Zhou et al., 2016)	3.9
	ULMFiT (ours)	3.6

Transfer learning models shine on this type of low-resource task

([Howard and Ruder, ACL 2018](#))

Hands-on: Model adaptation



First adaptation scheme

Hands-on: Model adaptation



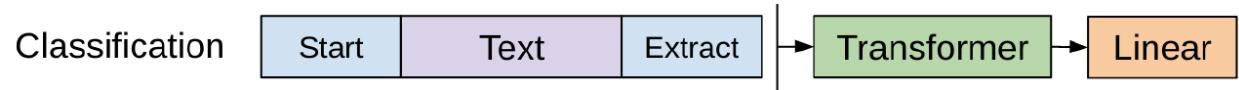
First adaptation scheme



Hands-on: Model adaptation



First adaptation scheme

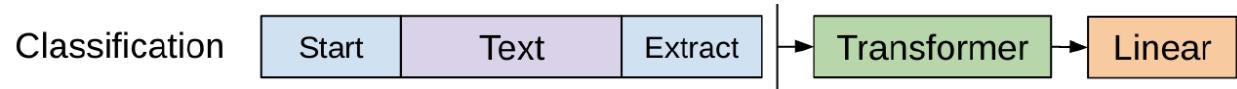


- ❑ Modifications:
 - ❑ Keep model internals unchanged
 - ❑ Add a linear layer on top
 - ❑ Add an additional embedding (classification token) at the bottom

Hands-on: Model adaptation



First adaptation scheme



- ❑ Modifications:
 - ❑ Keep model internals unchanged
 - ❑ Add a linear layer on top
 - ❑ Add an additional embedding (classification token) at the bottom
- ❑ Computation flow:
 - ❑ Model input: the tokenized question with a classification token at the end
 - ❑ Extract the last hidden-state associated to the classification token
 - ❑ Pass the hidden-state in a linear layer and softmax to obtain class probabilities

Hands-on: Model adaptation



```
▶ AdaptationConfig = namedtuple('AdaptationConfig',
    field_names="num_classes, dropout, initializer_range, batch_size, lr, max_norm, n_epochs,"
                "n_warmup, valid_set_prop, gradient_accumulation_steps, device,"
                "log_dir, dataset_cache")
adapt_args = AdaptationConfig(
    6           , 0.1      , 0.02        , 16          , 6.5e-5, 1.0   , 3,
    10          , 0.1      , 1, "cuda" if torch.cuda.is_available() else "cpu",
    "./"        , "./dataset_cache.bin")
```



```
▶ import random
from torch.utils.data import TensorDataset, random_split

dataset_file = cached_path("https://s3.amazonaws.com/datasets.huggingface.co/trec/"
                           "trec-tokenized-bert.bin")
datasets = torch.load(dataset_file)

for split_name in ['train', 'test']:

    # Trim the samples to the transformer's input length minus 1 & add a classification token
    datasets[split_name] = [x[:args.num_max_positions-1] + [tokenizer.vocab['[CLS]']]
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    # Pad the dataset to max length
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    tensor = torch.tensor(datasets[split_name], dtype=torch.long)
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# Create a validation dataset from a fraction of the training dataset
valid_size = int(adapt_args.valid_set_prop * len(datasets['train']))
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valid_dataset, train_dataset = random_split(datasets['train'], [valid_size, train_size])

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Hands-on: Model adaptation



Fine-tuning hyper-parameters:

- 6 classes in TREC-6
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Hands-on: Model adaptation



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Hands-on: Model adaptation



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⋮

Let's load and prepare our dataset:

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I	love	Mom	'	s	cooking	[CLS]
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No	way	[CLS]				
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Hands-on: Model adaptation



Fine-tuning hyper-parameters:

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adapt_args = AdaptationConfig(
    num_classes=6, dropout=0.1, initializer_range=0.02, batch_size=16, lr=6.5e-5, max_norm=1.0, n_epochs=3,
    n_warmup=10, valid_set_prop=0.1, gradient_accumulation_steps=1, device="cuda" if torch.cuda.is_available() else "cpu",
    log_dir='./', dataset_cache='dataset_cache.bin')
```

Let's load and prepare our dataset:

- trim to the transformer input size & add a classification token at the end of each sample,
- pad to the left,
- convert to tensors.

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test_loader = DataLoader(datasets['test'], batch_size=adapt_args.batch_size, shuffle=False)
```

Hands-on: Model adaptation



Adapt our model architecture

```
class TransformerWithClfHead(nn.Module):
    def __init__(self, config, fine_tuning_config):
        super().__init__()
        self.config = fine_tuning_config
        self.transformer = Transformer(config.embed_dim, config.hidden_dim, config.num_embeddings,
                                      config.num_max_positions, config.num_heads, config.num_layers,
                                      fine_tuning_config.dropout, causal=not config.mlm)

        self.classification_head = nn.Linear(config.embed_dim, fine_tuning_config.num_classes)

        self.apply(self.init_weights)

    def init_weights(self, module):
        if isinstance(module, (nn.Linear, nn.Embedding, nn.LayerNorm)):
            module.weight.data.normal_(mean=0.0, std=self.config.initializer_range)
        if isinstance(module, (nn.Linear, nn.LayerNorm)) and module.bias is not None:
            module.bias.data.zero_()

    def forward(self, x, clf_tokens_mask, clf_labels=None, padding_mask=None):
        hidden_states = self.transformer(x, padding_mask)

        clf_tokens_states = (hidden_states * clf_tokens_mask.unsqueeze(-1).float()).sum(dim=0)
        clf_logits = self.classification_head(clf_tokens_states)

        if clf_labels is not None:
            loss_fct = nn.CrossEntropyLoss(ignore_index=-1)
            loss = loss_fct(clf_logits.view(-1, clf_logits.size(-1)), clf_labels.view(-1))
            return clf_logits, loss
        return clf_logits
```

```
# If you have pretrained a model in the first section, you can use its weights
# state_dict = model.state_dict()

# Otherwise, just load pretrained model weights (and reload the training config as well)
state_dict = torch.load(cached_path("https://s3.amazonaws.com/models.huggingface.co/"
                                    "naacl-2019-tutorial/model_checkpoint.pth"), map_location='cpu')
args = torch.load(cached_path("https://s3.amazonaws.com/models.huggingface.co/"
                              "naacl-2019-tutorial/model_training_args.bin"))

adaptation_model = TransformerWithClfHead(config=args, fine_tuning_config=adapt_args).to(adapt_args.device)

incompatible_keys = adaptation_model.load_state_dict(state_dict, strict=False)
print(f"Parameters discarded from the pretrained model: {incompatible_keys.unexpected_keys}")
print(f"Parameters added in the adaptation model: {incompatible_keys.missing_keys}")
```

```
Parameters discarded from the pretrained model: ['lm_head.weight']
```

```
Parameters added in the adaptation model: ['classification_head.weight', 'classification_head.bias']
```

Hands-on: Model adaptation



Adapt our model architecture

Keep our pretrained model unchanged as the backbone.

```
class TransformerWithClfHead(nn.Module):
    def __init__(self, config, fine_tuning_config):
        super().__init__()
        self.config = fine_tuning_config
        self.transformer = Transformer(config.embed_dim, config.hidden_dim, config.num_embeddings,
                                      config.num_max_positions, config.num_heads, config.num_layers,
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        self.classification_head = nn.Linear(config.embed_dim, fine_tuning_config.num_classes)

        self.apply(self.init_weights)

    def init_weights(self, module):
        if isinstance(module, (nn.Linear, nn.Embedding, nn.LayerNorm)):
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        clf_tokens_states = (hidden_states * clf_tokens_mask.unsqueeze(-1).float()).sum(dim=0)
        clf_logits = self.classification_head(clf_tokens_states)

        if clf_labels is not None:
            loss_fct = nn.CrossEntropyLoss(ignore_index=-1)
            loss = loss_fct(clf_logits.view(-1, clf_logits.size(-1)), clf_labels.view(-1))
            return clf_logits, loss
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# Otherwise, just load pretrained model weights (and reload the training config as well)
state_dict = torch.load(cached_path("https://s3.amazonaws.com/models.huggingface.co/"
                                    "naacl-2019-tutorial/model_checkpoint.pth"), map_location='cpu')
args = torch.load(cached_path("https://s3.amazonaws.com/models.huggingface.co/"
                            "naacl-2019-tutorial/model_training_args.bin"))

adaptation_model = TransformerWithClfHead(config=args, fine_tuning_config=adapt_args).to(adapt_args.device)

incompatible_keys = adaptation_model.load_state_dict(state_dict, strict=False)
print(f"Parameters discarded from the pretrained model: {incompatible_keys.unexpected_keys}")
print(f"Parameters added in the adaptation model: {incompatible_keys.missing_keys}")
```

Parameters discarded from the pretrained model: ['lm_head.weight']

Parameters added in the adaptation model: ['classification_head.weight', 'classification_head.bias']

Hands-on: Model adaptation



Adapt our model architecture

Keep our pretrained model unchanged as the backbone.

Replace the pre-training head (language modeling) with the classification head:

A linear layer, which takes as input the hidden-state of the [CLF] token (using a mask)

```
class TransformerWithClfHead(nn.Module):
    def __init__(self, config, fine_tuning_config):
        super().__init__()
        self.config = fine_tuning_config
        self.transformer = Transformer(config.embed_dim, config.hidden_dim, config.num_embeddings,
                                      config.num_max_positions, config.num_heads, config.num_layers,
                                      fine_tuning_config.dropout, causal=not config.mlm)

        self.classification_head = nn.Linear(config.embed_dim, fine_tuning_config.num_classes)

    def apply(self.init_weights):
        self.apply(self.init_weights)

    def init_weights(self, module):
        if isinstance(module, (nn.Linear, nn.Embedding, nn.LayerNorm)):
            module.weight.data.normal_(mean=0.0, std=self.config.initializer_range)
        if isinstance(module, (nn.Linear, nn.LayerNorm)) and module.bias is not None:
            module.bias.data.zero_()

    def forward(self, x, clf_tokens_mask, clf_labels=None, padding_mask=None):
        hidden_states = self.transformer(x, padding_mask)

        clf_tokens_states = (hidden_states * clf_tokens_mask.unsqueeze(-1).float()).sum(dim=0)
        clf_logits = self.classification_head(clf_tokens_states)

        if clf_labels is not None:
            loss_fct = nn.CrossEntropyLoss(ignore_index=-1)
            loss = loss_fct(clf_logits.view(-1, clf_logits.size(-1)), clf_labels.view(-1))
            return clf_logits, loss
        return clf_logits
```

```
# If you have pretrained a model in the first section, you can use its weights
# state_dict = model.state_dict()

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state_dict = torch.load(cached_path("https://s3.amazonaws.com/models.huggingface.co/"
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Parameters discarded from the pretrained model: ['lm_head.weight']
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Hands-on: Model adaptation



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        self.config = fine_tuning_config
        self.transformer = Transformer(config.embed_dim, config.hidden_dim, config.num_embeddings,
                                      config.num_max_positions, config.num_heads, config.num_layers,
                                      fine_tuning_config.dropout, causal=not config.mlm)

        self.classification_head = nn.Linear(config.embed_dim, fine_tuning_config.num_classes)

    def apply(self.init_weights):
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    def init_weights(self, module):
        if isinstance(module, (nn.Linear, nn.Embedding, nn.LayerNorm)):
            module.weight.data.normal_(mean=0.0, std=self.config.initializer_range)
        if isinstance(module, (nn.Linear, nn.LayerNorm)) and module.bias is not None:
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    def forward(self, x, clf_tokens_mask, clf_labels=None, padding_mask=None):
        hidden_states = self.transformer(x, padding_mask)

        clf_tokens_states = (hidden_states * clf_tokens_mask.unsqueeze(-1).float()).sum(dim=0)
        clf_logits = self.classification_head(clf_tokens_states)

        if clf_labels is not None:
            loss_fct = nn.CrossEntropyLoss(ignore_index=-1)
            loss = loss_fct(clf_logits.view(-1, clf_logits.size(-1)), clf_labels.view(-1))
            return clf_logits, loss
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```

* Initialize all the weights of the model.

```
# If you have pretrained a model in the first section, you can use its weights
# state_dict = model.state_dict()

# Otherwise, just load pretrained model weights (and reload the training config as well)
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Parameters discarded from the pretrained model: ['lm_head.weight']
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Hands-on: Model adaptation

Adapt our model architecture

Keep our pretrained model unchanged as the backbone.

Replace the pre-training head (language modeling) with the classification head:

A linear layer, which takes as input the hidden-state of the [CLF] token (using a mask)

* Initialize all the weights of the model.

* Reload common weights from the pretrained model.

```
class TransformerWithClfHead(nn.Module):
    def __init__(self, config, fine_tuning_config):
        super().__init__()
        self.config = fine_tuning_config
        self.transformer = Transformer(config.embed_dim, config.hidden_dim, config.num_embeddings,
                                      config.num_max_positions, config.num_heads, config.num_layers,
                                      fine_tuning_config.dropout, causal=not config.mlm)

        self.classification_head = nn.Linear(config.embed_dim, fine_tuning_config.num_classes)

    def apply(self.init_weights):
        self.apply(self.init_weights)

    def init_weights(self, module):
        if isinstance(module, (nn.Linear, nn.Embedding, nn.LayerNorm)):
            module.weight.data.normal_(mean=0.0, std=self.config.initializer_range)
        if isinstance(module, (nn.Linear, nn.LayerNorm)) and module.bias is not None:
            module.bias.data.zero_()

    def forward(self, x, clf_tokens_mask, clf_labels=None, padding_mask=None):
        hidden_states = self.transformer(x, padding_mask)

        clf_tokens_states = (hidden_states * clf_tokens_mask.unsqueeze(-1).float()).sum(dim=0)
        clf_logits = self.classification_head(clf_tokens_states)

        if clf_labels is not None:
            loss_fct = nn.CrossEntropyLoss(ignore_index=-1)
            loss = loss_fct(clf_logits.view(-1, clf_logits.size(-1)), clf_labels.view(-1))
            return clf_logits, loss
        return clf_logits
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```
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Parameters discarded from the pretrained model: ['lm_head.weight']
Parameters added in the adaptation model: ['classification_head.weight', 'classification_head.bias']
```

Hands-on: Model adaptation



Our fine-tuning code:

```
optimizer = torch.optim.Adam(adaptation_model.parameters(), lr=adapt_args.lr)

# Training function and trainer
def update(engine, batch):
    adaptation_model.train()
    batch, labels = (t.to(adapt_args.device) for t in batch)
    inputs = batch.transpose(0, 1).contiguous() # to shape [seq length, batch]
    _, loss = adaptation_model(inputs, clf_tokens_mask=(inputs == tokenizer.vocab['[CLS]']), clf_labels=labels,
                                padding_mask=(batch == tokenizer.vocab['[PAD]']))
    loss = loss / adapt_args.gradient_accumulation_steps
    loss.backward()
    torch.nn.utils.clip_grad_norm_(adaptation_model.parameters(), adapt_args.max_norm)
    if engine.state.iteration % adapt_args.gradient_accumulation_steps == 0:
        optimizer.step()
        optimizer.zero_grad()
    return loss.item()
trainer = Engine(update)

# Evaluation function and evaluator (evaluator output is the input of the metrics)
def inference(engine, batch):
    adaptation_model.eval()
    with torch.no_grad():
        batch, labels = (t.to(adapt_args.device) for t in batch)
        inputs = batch.transpose(0, 1).contiguous() # to shape [seq length, batch]
        clf_logits = adaptation_model(inputs, clf_tokens_mask=(inputs == tokenizer.vocab['[CLS]']),
                                       padding_mask=(batch == tokenizer.vocab['[PAD]']))
    return clf_logits, labels
evaluator = Engine(inference)

# Attach metric to evaluator & evaluation to trainer: evaluate on valid set after each epoch
Accuracy().attach(evaluator, "accuracy")
@trainer.on(Events.EPOCH_COMPLETED)
def log_validation_results(engine):
    evaluator.run(valid_loader)
    print(f"Validation Epoch: {engine.state.epoch} Error rate: {100*(1 - evaluator.state.metrics['accuracy'])}")

# Learning rate schedule: linearly warm-up to lr and then to zero
scheduler = PiecewiseLinear(optimizer, 'lr', [(0, 0.0), (adapt_args.n_warmup, adapt_args.lr),
                                                (len(train_loader)*adapt_args.n_epochs, 0.0)])
trainer.add_event_handler(Events.ITERATION_STARTED, scheduler)

# Add progressbar with loss
RunningAverage(output_transform=lambda x: x).attach(trainer, "loss")
ProgressBar(persist=True).attach(trainer, metric_names=['loss'])

# Save checkpoints and finetuning config
checkpoint_handler = ModelCheckpoint(adapt_args.log_dir, 'finetuning_checkpoint', save_interval=1, require_empty=False)
trainer.add_event_handler(Events.EPOCH_COMPLETED, checkpoint_handler, {'mymodel': adaptation_model})
torch.save(args, os.path.join(adapt_args.log_dir, 'fine_tuning_args.bin'))
```

Hands-on: Model adaptation



Our fine-tuning code:

A simple training update function:

* *prepare inputs: transpose and build padding & classification token masks*

* *we have options to clip and accumulate gradients*

```
optimizer = torch.optim.Adam(adaptation_model.parameters(), lr=adapt_args.lr)

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    loss.backward()
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torch.save(args, os.path.join(adapt_args.log_dir, 'fine_tuning_args.bin'))
```

Hands-on: Model adaptation



Our fine-tuning code:

A simple training update function:

* *prepare inputs: transpose and build padding & classification token masks*

* *we have options to clip and accumulate gradients*

We will evaluate on our validation and test sets:

* *validation: after each epoch*

* *test: at the end*

```
optimizer = torch.optim.Adam(adaptation_model.parameters(), lr=adapt_args.lr)

# Training function and trainer
def update(engine, batch):
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    batch, labels = (t.to(adapt_args.device) for t in batch)
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    torch.nn.utils.clip_grad_norm_(adaptation_model.parameters(), adapt_args.max_norm)
    if engine.state.iteration % adapt_args.gradient_accumulation_steps == 0:
        optimizer.step()
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trainer.add_event_handler(Events.EPOCH_COMPLETED, checkpoint_handler, {'mymodel': adaptation_model})
torch.save(args, os.path.join(adapt_args.log_dir, 'fine_tuning_args.bin'))
```

Hands-on: Model adaptation – Results



We can now fine-tune our model on TREC:

Hands-on: Model adaptation – Results



We can now fine-tune our model on TREC:

```
[50] trainer.run(train_loader, max_epochs=adapt_args.n_epochs)
```

```
Epoch [1/3] [307/307] 100% ██████████, loss=3.85e-01 [01:10<00:00]
Validation Epoch: 1 Error rate: 9.174311926605505
Epoch [2/3] [307/307] 100% ██████████, loss=1.73e-01 [01:10<00:00]
Validation Epoch: 2 Error rate: 5.871559633027523
Epoch [3/3] [307/307] 100% ██████████, loss=9.63e-02 [01:10<00:00]
Validation Epoch: 3 Error rate: 5.688073394495408
<ignite.engine.engine.State at 0x7ff4c8b385f8>
```

```
evaluator.run(test_loader)
print(f"Test Results - Error rate: {100*(1.00 - evaluator.state.metrics['accuracy']):.3f}")
```

```
Test Results - Error rate: 3.600
```

Hands-on: Model adaptation – Results



We can now fine-tune our model on TREC:

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evaluator.run(test_loader)
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```

```
Test Results - Error rate: 3.600
```

Model	Test
CoVe (McCann et al., 2017)	4.2
TBCNN (Mou et al., 2015)	4.0
LSTM-CNN (Zhou et al., 2016)	3.9
ULMFiT (ours)	3.6

We are at the state-of-the-art
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Hands-on: Model adaptation – Results



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```

⋮

```
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Remarks:

- ❑ The error rate goes down quickly! After one epoch we already have >90% accuracy.
⇒ Fine-tuning is highly **data efficient** in Transfer Learning
- ❑ We took our pre-training & fine-tuning hyper-parameters straight from the literature on related models.
⇒ Fine-tuning is often **robust** to the exact choice of hyper-parameters

Hands-on: Model adaptation – Results



Let's conclude this hands-on with a few additional words on robustness & variance.

Hands-on: Model adaptation – Results



Let's conclude this hands-on with a few additional words on robustness & variance.

- Large pretrained models (e.g. BERT large) are prone to degenerate performance when fine-tuned on tasks with small training sets.

Hands-on: Model adaptation – Results



Let's conclude this hands-on with a few additional words on robustness & variance.

- ❑ Large pretrained models (e.g. BERT large) are prone to degenerate performance when fine-tuned on tasks with small training sets.
- ❑ Observed behavior is often “on-off”: it either works very well or doesn’t work at all.

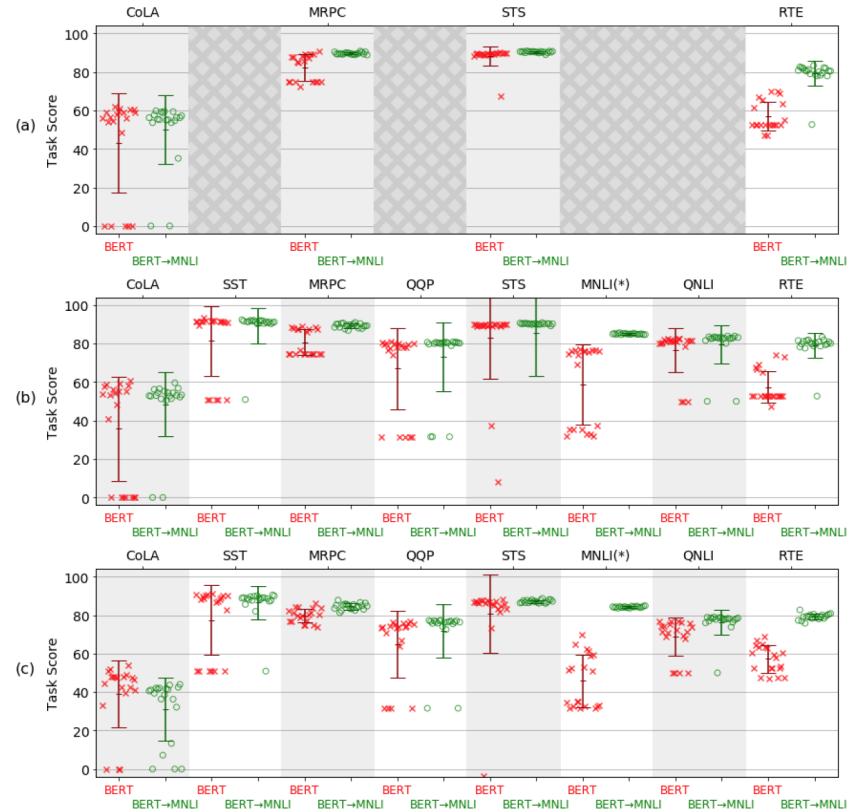


Figure 1: Distribution of task scores across 20 random restarts for BERT, and BERT with intermediary fine-tuning on MNLI. Each cross represents a single run. Error lines show mean \pm std. (a) Fine-tuned on all data, for tasks with <10k training examples. (b) Fine-tuned on no more than 5k examples for each task. (c) Fine-tuned on no more than 1k examples for each task. (*) indicates that the intermediate task is the same as the target task.

Hands-on: Model adaptation – Results



Let's conclude this hands-on with a few additional words on robustness & variance.

- ❑ Large pretrained models (e.g. BERT large) are prone to degenerate performance when fine-tuned on tasks with small training sets.
- ❑ Observed behavior is often “on-off”: it either works very well or doesn’t work at all.
- ❑ Understanding the conditions and causes of this behavior (models, adaptation schemes) is an open research question.

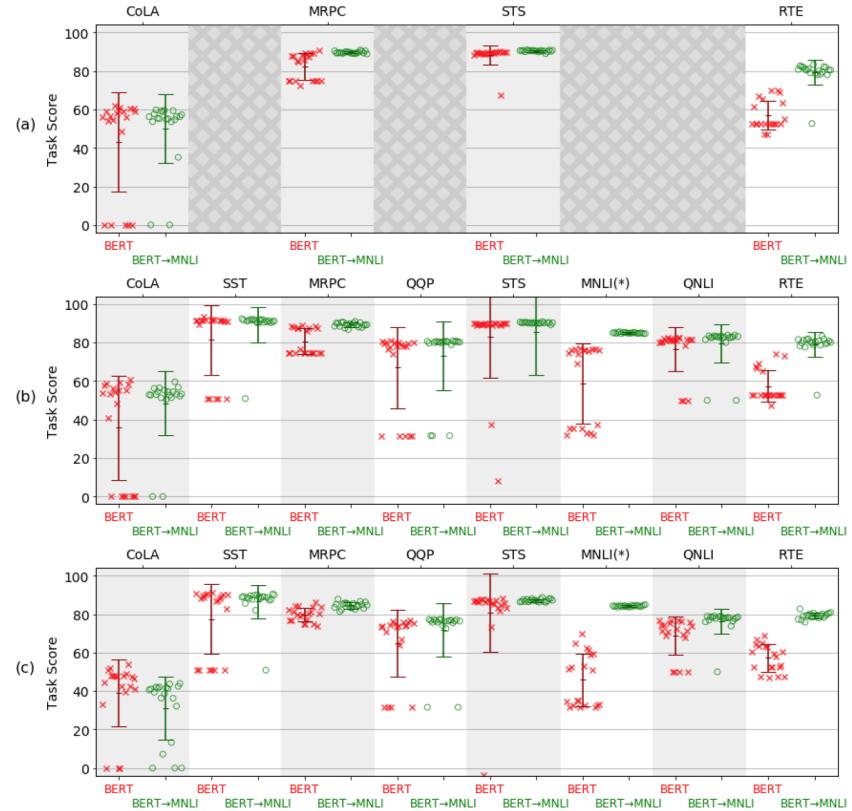
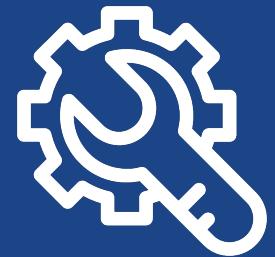
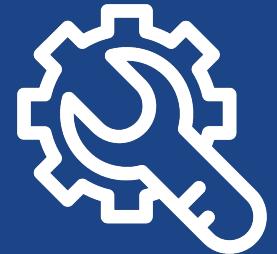


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4.2 – Optimization



4.2 – Optimization



Several directions when it comes to the optimization itself:

4.2 – Optimization



Several directions when it comes to the optimization itself:

- A. Choose **which weights** we should update
Feature extraction, fine-tuning, adapters



4.2 – Optimization



Several directions when it comes to the optimization itself:

- A. Choose **which weights** we should update
Feature extraction, fine-tuning, adapters



- B. Consider **practical trade-offs**
Space and time complexity, performance



4.2.A – Optimization: Which weights?

The main question: **To tune or not to tune (the pretrained weights)?**



4.2.A – Optimization: Which weights?

The main question: **To tune or not to tune (the pretrained weights)?**

- A. **Do not change** pretrained weights
Feature extraction, adapters



4.2.A – Optimization: Which weights?

The main question: **To tune or not to tune (the pretrained weights)?**

- A. **Do not change** pretrained weights
Feature extraction, adapters



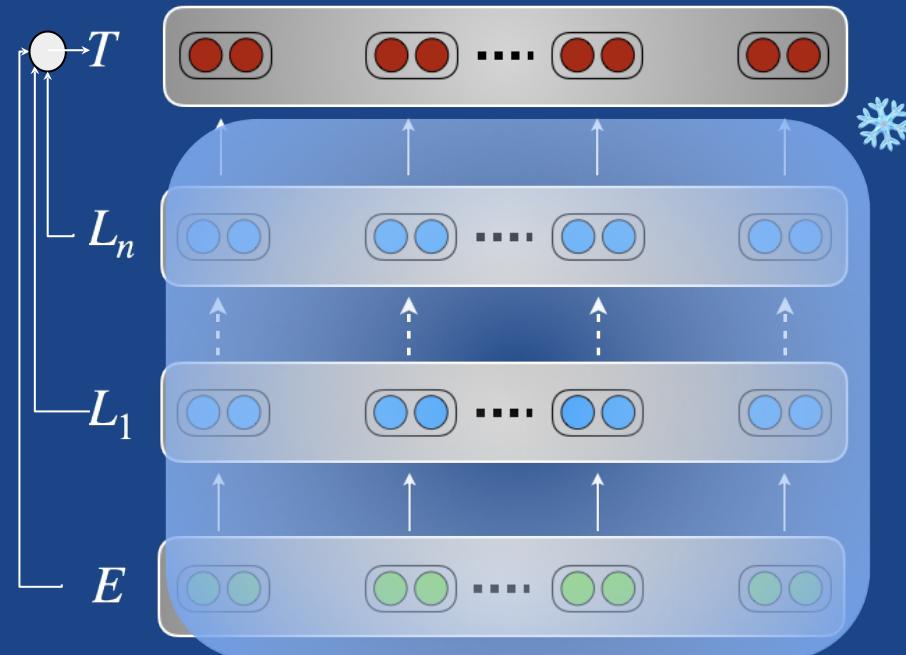
- B. **Change** pretrained weights
Fine-tuning

4.2.A – Optimization: Which weights?

Don't touch the pretrained weights!

Feature extraction:

- Weights are **frozen**
- A **linear classifier** is trained on top of the pretrained representations
- Don't just use features of the top layer!**
- Learn a **linear combination** of layers
([Peters et al., NAACL 2018](#), [Ruder et al., AAAI 2019](#))

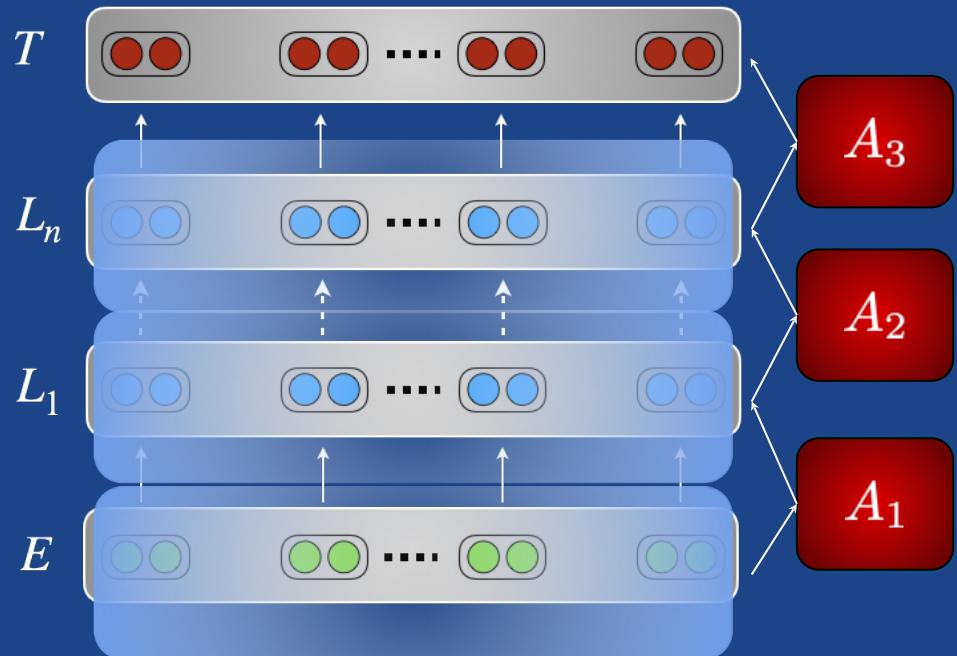


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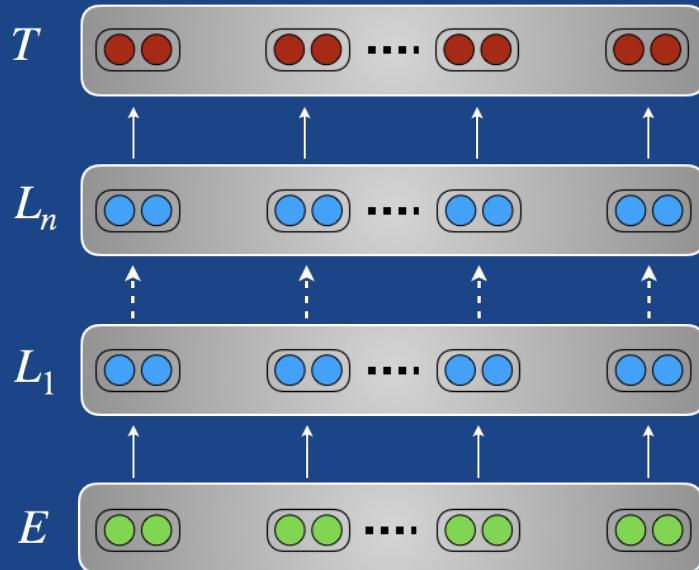
Adapters

- ❑ Task-specific modules that are added **in between** existing layers
- ❑ Only adapters are trained



4.2.A – Optimization: Which weights?

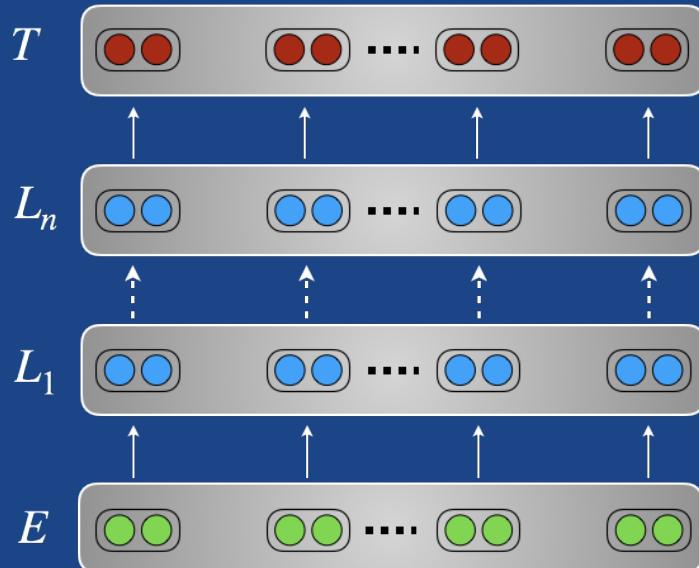
Yes, change the pretrained weights!



4.2.A – Optimization: Which weights?

Yes, change the pretrained weights!

Fine-tuning:

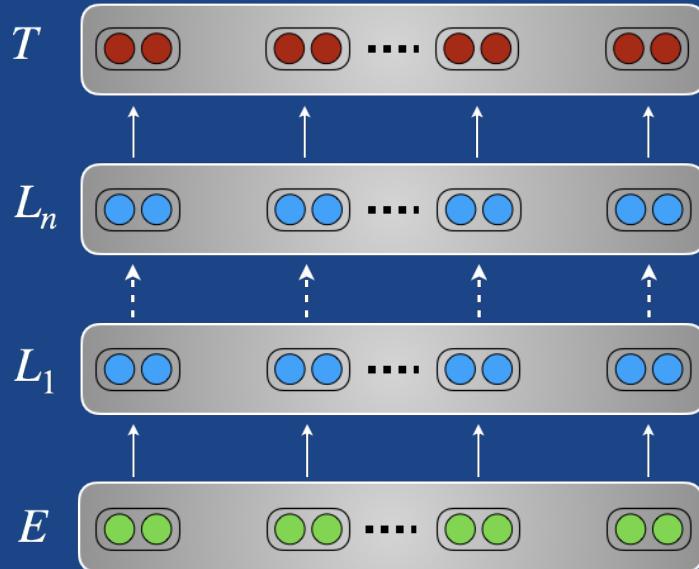


4.2.A – Optimization: Which weights?

Yes, change the pretrained weights!

Fine-tuning:

- Pretrained weights are used as **initialization** for parameters of the downstream model

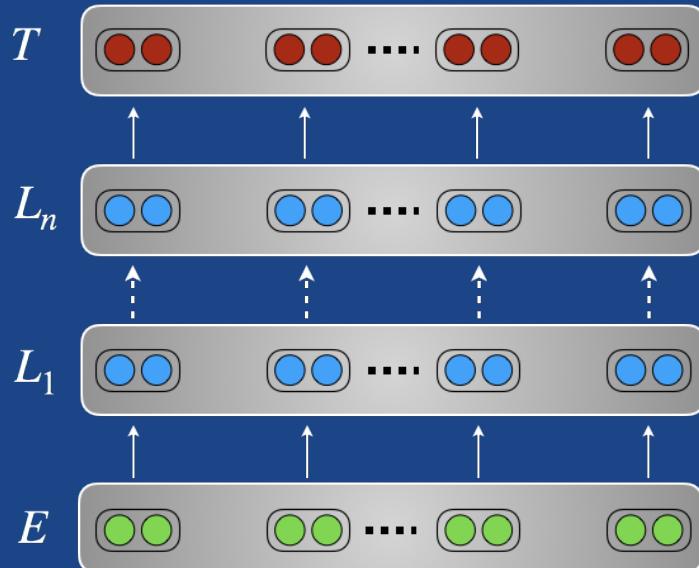


4.2.A – Optimization: Which weights?

Yes, change the pretrained weights!

Fine-tuning:

- Pretrained weights are used as **initialization** for parameters of the downstream model
- The **whole pretrained architecture** is trained during the adaptation phase



4.2.B – Optimization: Trade-offs



Several trade-offs when choosing which weights to update:

4.2.B – Optimization: Trade-offs

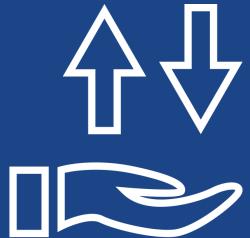


Several trade-offs when choosing which weights to update:

A. Space complexity

Task-specific modifications, additional parameters, parameter reuse

4.2.B – Optimization: Trade-offs



Several trade-offs when choosing which weights to update:

A. Space complexity

Task-specific modifications, additional parameters, parameter reuse

B. Time complexity

Training time

4.2.B – Optimization: Trade-offs



Several trade-offs when choosing which weights to update:

A. Space complexity

Task-specific modifications, additional parameters, parameter reuse

B. Time complexity

Training time

C. Performance

4.2.B – Optimization trade-offs: Space

Task-specific modifications



4.2.B – Optimization trade-offs: Space

Task-specific modifications



Additional parameters

4.2.B – Optimization trade-offs: Space

Task-specific modifications



4.2.B – Optimization trade-offs: Time



4.2.B – Optimization trade-offs: Performance

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- ❑ Rule of thumb: If task source and target tasks are **dissimilar***, use feature extraction ([Peters et al., 2019](#))

*dissimilar: certain capabilities (e.g. modelling inter-sentence relations) are beneficial for target task, but pretrained model lacks them

4.2.B – Optimization trade-offs: Performance

- ❑ Rule of thumb: If task source and target tasks are **dissimilar***, use feature extraction ([Peters et al., 2019](#))
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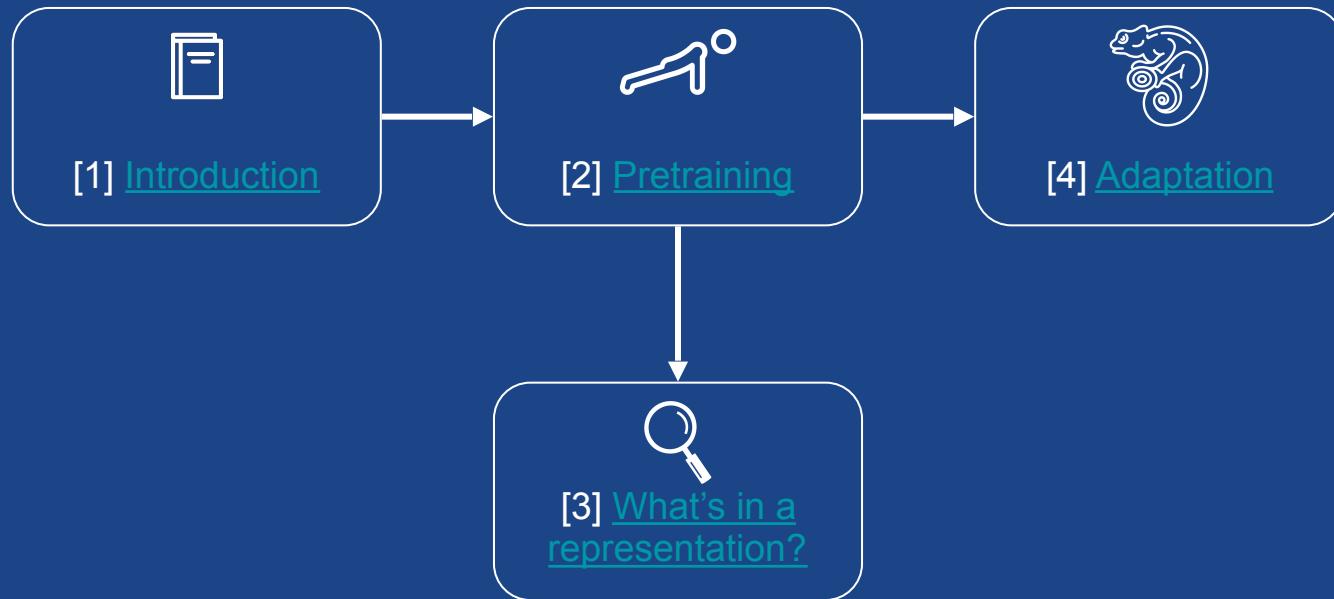
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- ❑ Fine-tuning BERT on textual similarity tasks works significantly better
- ❑ Adapters achieve performance competitive with fine-tuning
- ❑ Anecdotally, Transformers are easier to fine-tune (less sensitive to hyperparameters) than recurrent neural nets (e.g. LSTMs)

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In summary



Pretraining tasks

Pretraining tasks

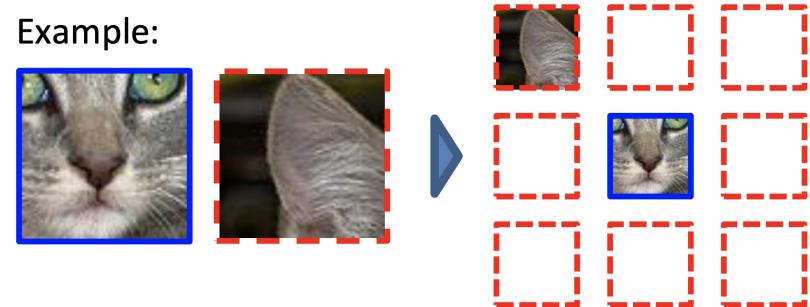
More diverse self-supervised objectives

Pretraining tasks

More diverse self-supervised objectives

- ❑ computer vision

Example:



Sampling a patch and a neighbour and predicting their spatial configuration
[\(Doersch et al., ICCV 2015\)](#)



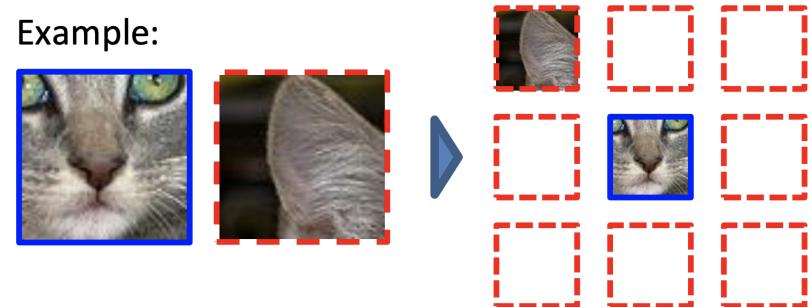
Image colorization ([Zhang et al., ECCV 2016](#))

Pretraining tasks

More diverse self-supervised objectives

- ❑ computer vision
- ❑ Self-supervision in language mostly based on word co-occurrence ([Ando and Zhang, 2005](#)) Instead, supervision on different levels of meaning

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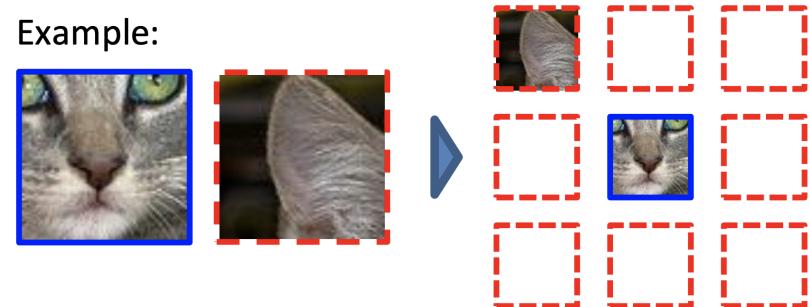
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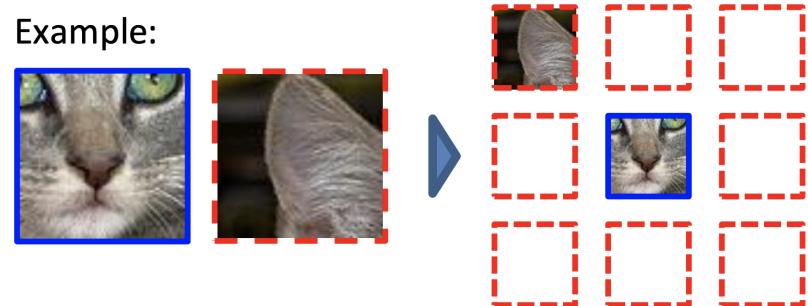
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Pretraining tasks

More diverse self-supervised objectives

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- ❑ Self-supervision in language mostly based on word co-occurrence ([Ando and Zhang, 2005](#)) Instead, supervision on different levels of meaning
 - ❑ Discourse, document, sentence, etc.
 - ❑ Using other signals, e.g. meta-data

Example:



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Pretraining tasks

Pretraining tasks

Need for grounded representations

Pretraining tasks

Need for grounded representations

- ❑ Limits of distributional hypothesis—difficult to learn certain types of information from raw text
 - ❑ Human reporting bias: not stating the obvious ([Gordon and Van Durme, AKBC 2013](#))
 - ❑ Common sense isn't written down
 - ❑ No grounding to other modalities

Pretraining tasks

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 - ❑ Human reporting bias: not stating the obvious ([Gordon and Van Durme, AKBC 2013](#))
 - ❑ Common sense isn't written down
 - ❑ No grounding to other modalities
- ❑ Possible solutions:
 - ❑ Incorporate other structured knowledge (e.g. knowledge bases like ERNIE, [Zhang et al 2019](#))
 - ❑ Multimodal learning (e.g. with visual representations like VideoBERT, [Sun et al. 2019](#))
 - ❑ Interactive/human-in-the-loop approaches (e.g. dialog, [Hancock et al. 2018](#))

Continual learning

- ❑ Current transfer learning **performs adaptation once**.
- ❑ Ultimately, we'd like to have models that continue to **retain and accumulate knowledge** across many tasks ([Yogatama et al., 2019](#)).
- ❑ No distinction between pretraining and adaptation; just **one stream of tasks**.
- ❑ Main challenge towards this: **Catastrophic forgetting**.

Thank you! Questions?

Email: swabhas@allenai.org

<https://swabhs.com>



Other Resources:

[Colab](#)

[Full tutorial Video](#)

[Tutorial](#)

[Slides](#)