

Automatic frame-semantic role labeling

Swabha Swayamdipta

Carnegie Mellon University / University of Washington

Outline

1. Task of frame-SRL

2. Primary Subtasks

a. Target Identification

b. Frame Identification

c. Frame-Element Identification

3. Advanced Modeling

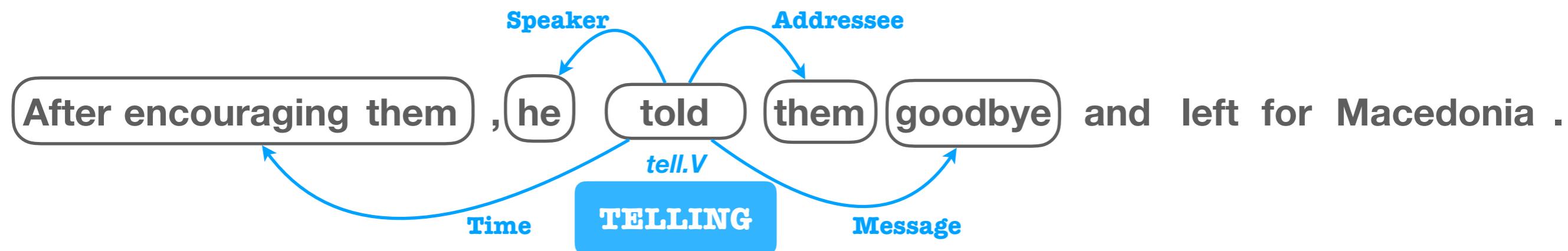
4. Looking forward: Multilingual Extensions

Frame-Semantic Role Labeling (frame-SRL)

After encouraging them , he told them goodbye and left for Macedonia .

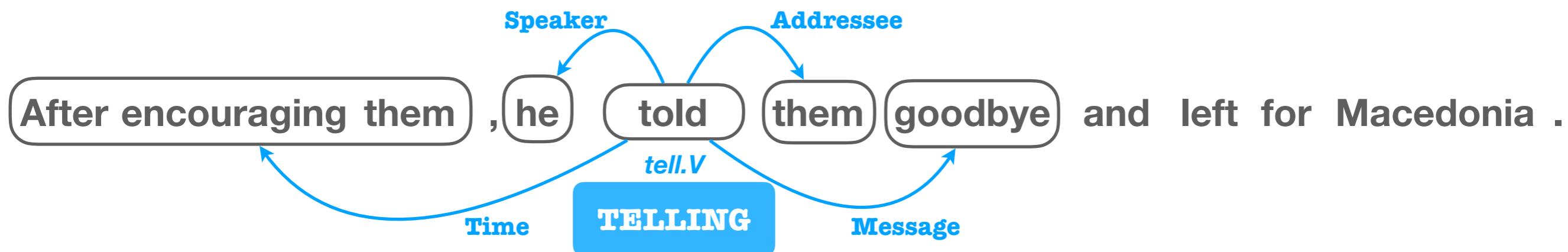
Frame-Semantic Role Labeling (frame-SRL)

Sentence → Graph



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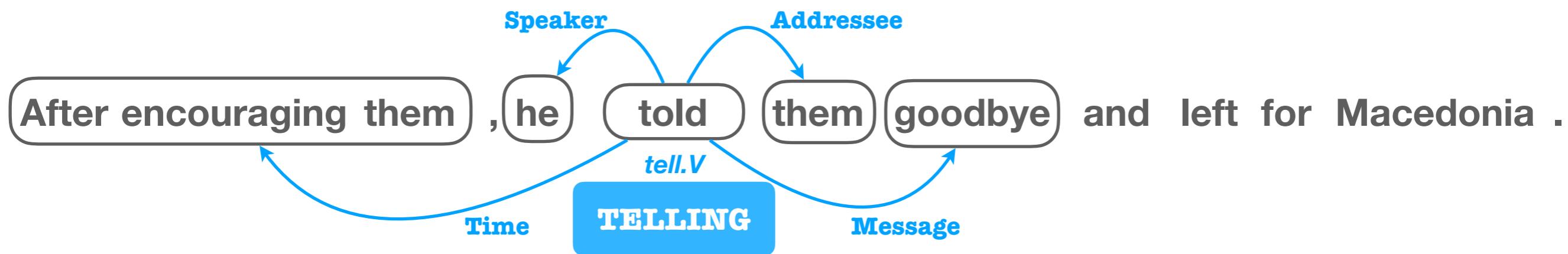
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- **Nodes:** tokens / spans in the sentence. Could represent both targets and arguments.

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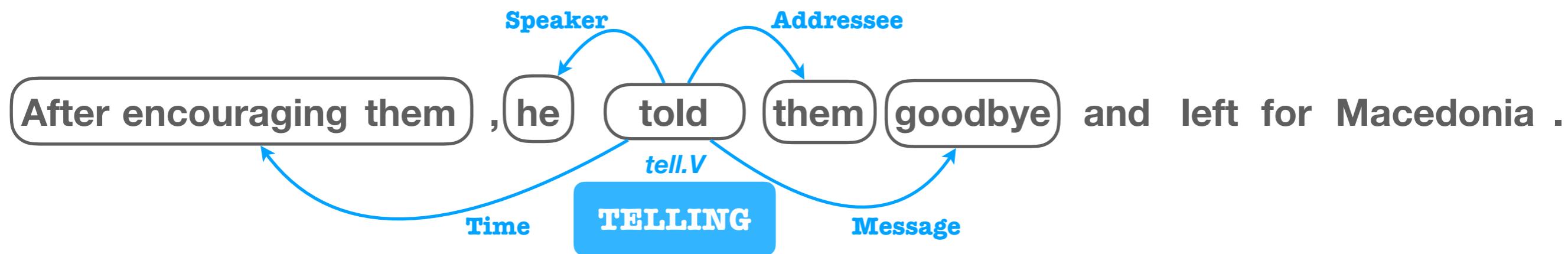
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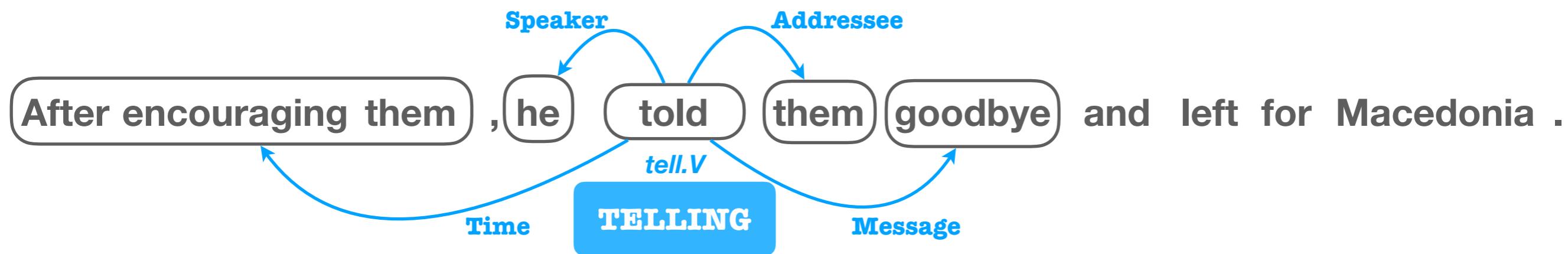
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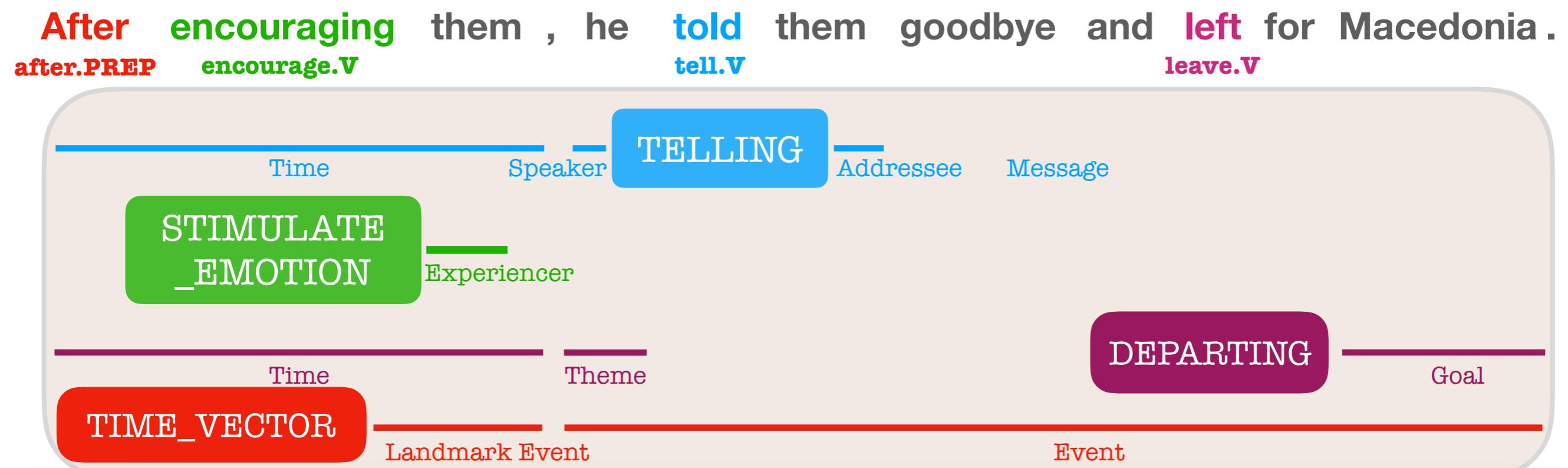
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- **Edges:** Between target nodes and argument nodes
- **Edge Labels:** roles of arguments / frame-elements

Frame-Semantic Graphs: Overlapping Nodes

After encouraging them , he **told** them goodbye and left for Macedonia .
tell.v



Frame-Semantic Graphs: Overlapping Nodes



Frame-SRL: Subtasks

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STIMULATE
_EMOTION

TIME_VECTOR

2. Frame Identification

TELLING

DEPARTING

Frame-SRL: Subtasks

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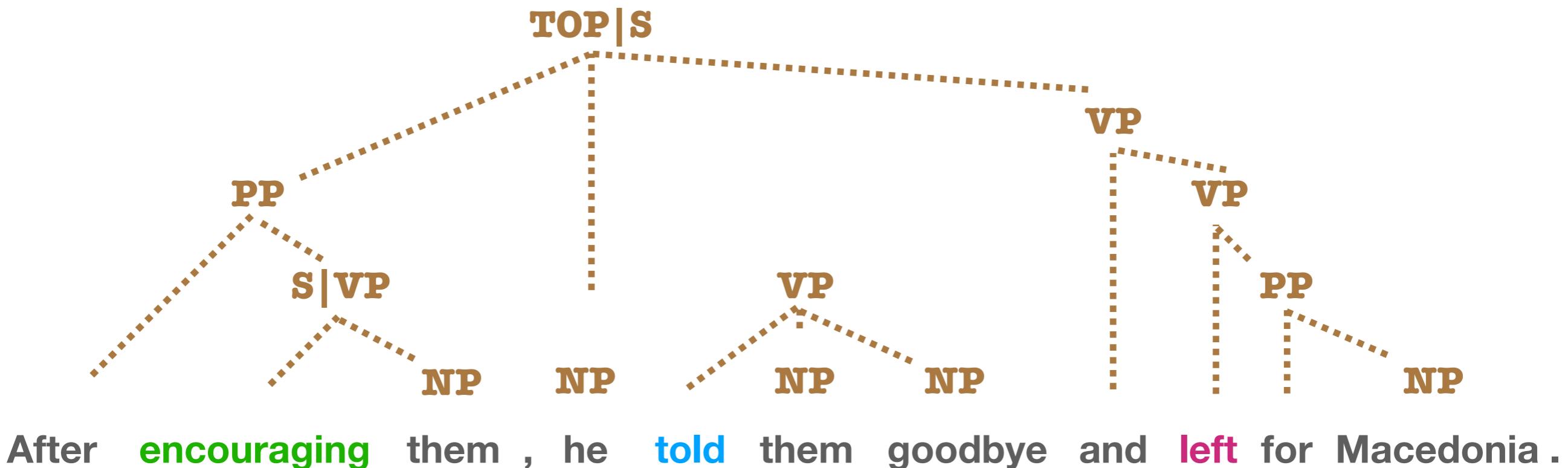
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A close relative: PropBank SRL

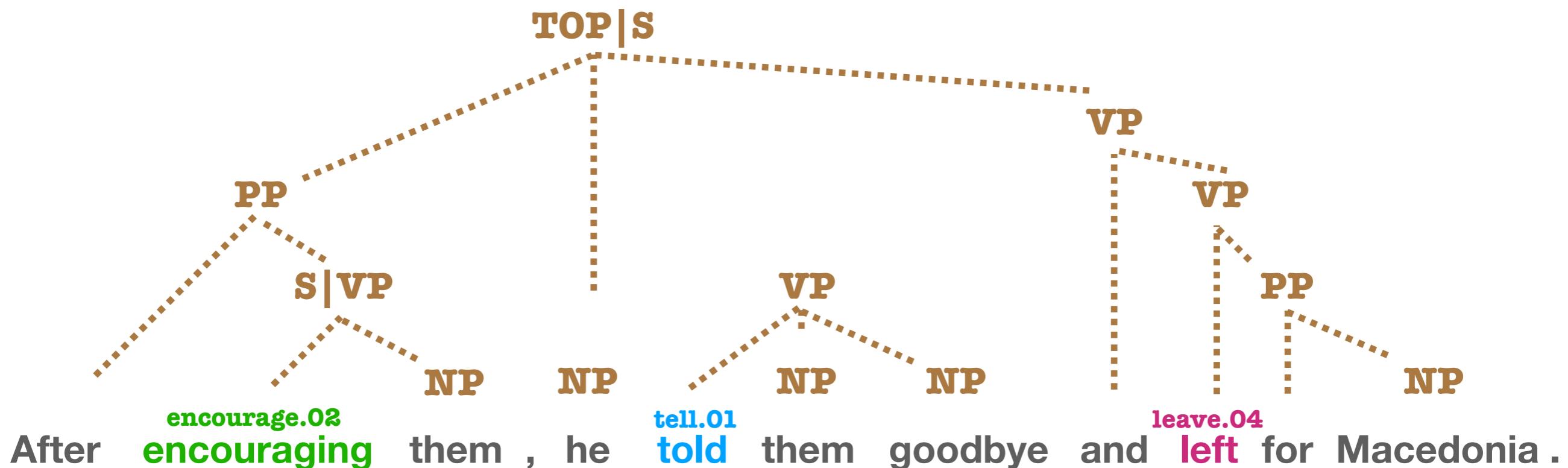
1. Target Predicate Identification



A close relative: PropBank SRL

**1. Target
Predicate
Identification**

**2. Frame
Sense
Identification**

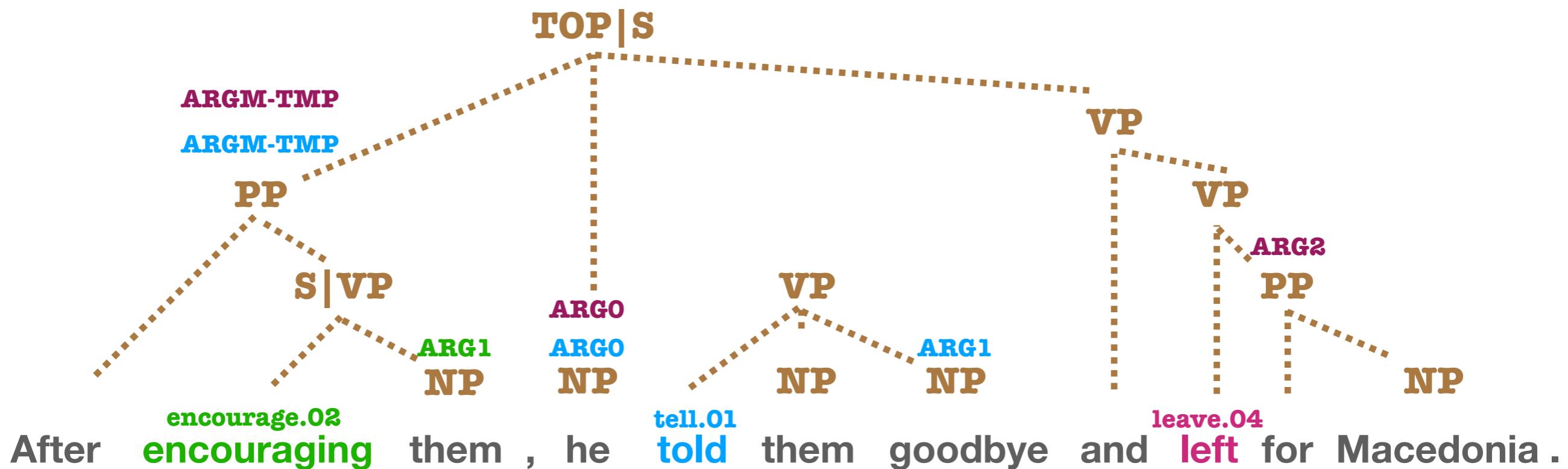


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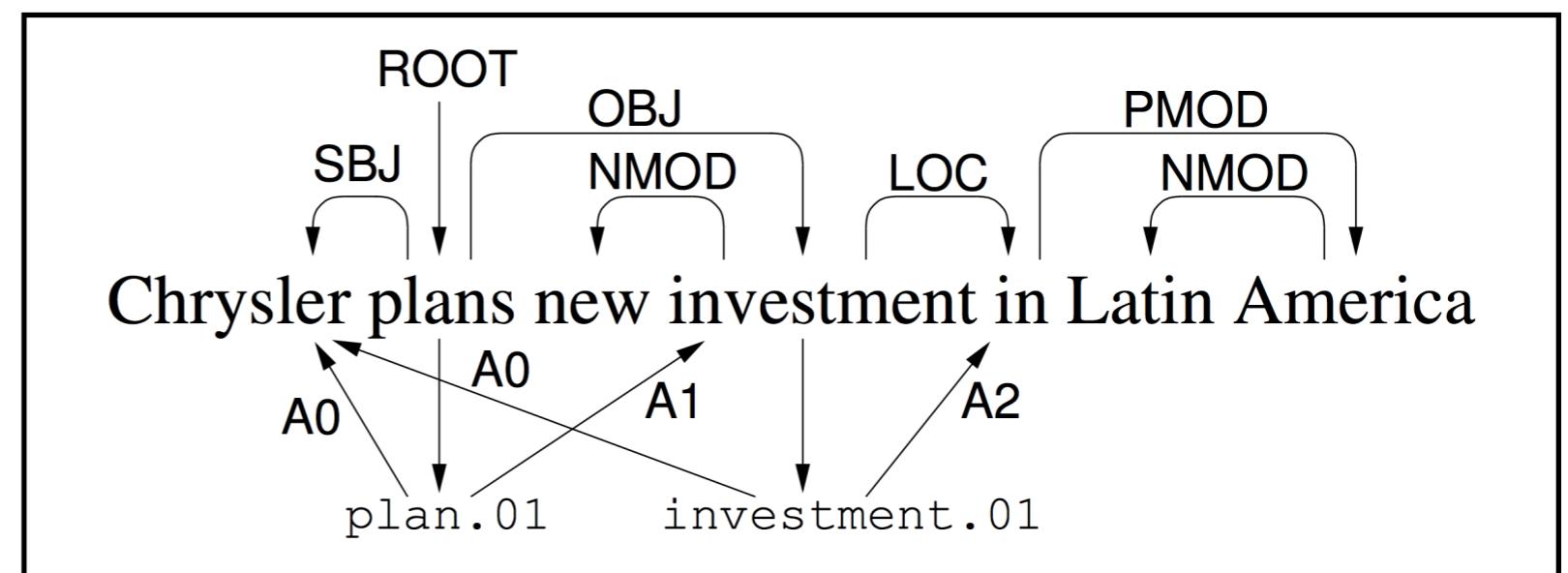
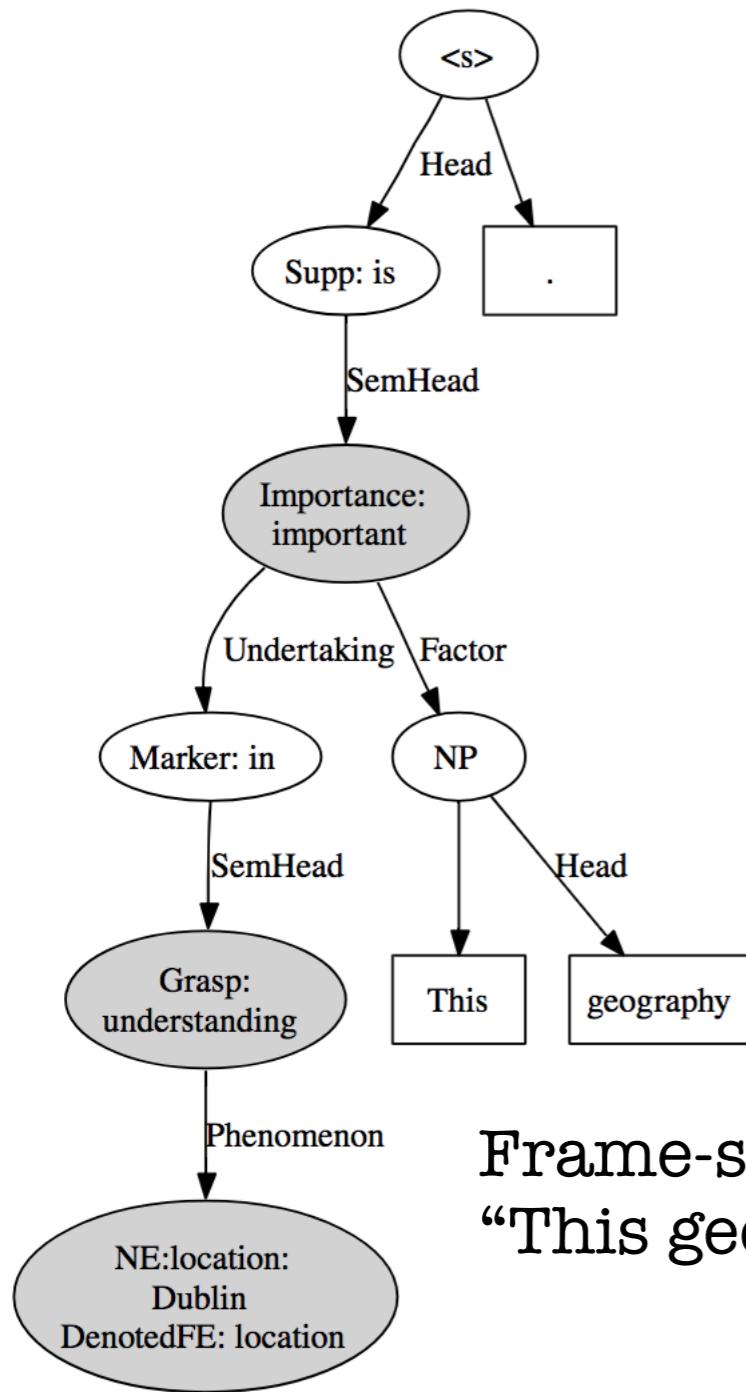
**1. Target
Predicate
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Argument
Identification**



Dependency Graphs



PropBank-style dependency graph for sentence, along with syntactic dependencies.

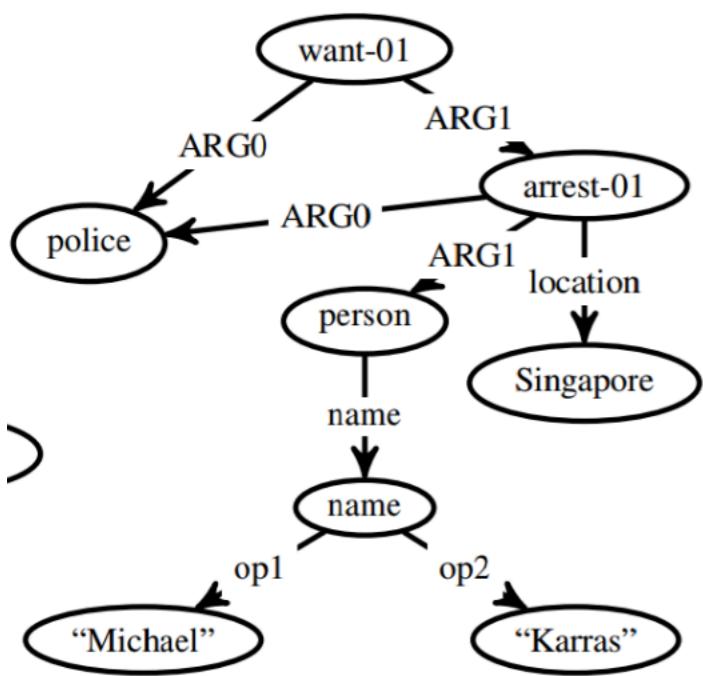
Johannsson & Nugues (ACL, 2008)

Frame-semantic dependency graph for sentence "This geography is important for understanding Dublin.".

Baker et. al. (SemEval, 2007)

Related tasks

Abstract Meaning Representation



Banarescu et. al. (2013)

QA -SRL

A much larger super eruption in Colorado **produced** over 5,000 cubic kilometers of material.

Produced	What produced something?	A much larger super eruption
	Where did something produce something?	in Colorado
	What did something produce?	over 5,000 cubic kilometers of material

He et. al. (2015)
Fitzgerald et. al. (2018)

Semantic proto-roles

Sentences	Property	(A)	(B)	(C)
(A) She was untrained and, in one botched job <i>killed</i> a client.	instigated	5	5	5
(B) The antibody then <i>kills</i> the cell.	volitional	2	1	5
(C) An assassin in Colombia <i>killed</i> a federal judge on a Medellin street. PropBank KILL.01, ARG ₀ -PAG: killer	awareness	3	1	5
VerbNet MURDER-42.1-1, AGENT: ACTOR in an event who initiates and carries out the event intentionally or consciously, and who exists independently of the event	sentient	5	1	5
FrameNet KILLING, KILLER/CAUSE: (The person or sentient entity) / (An inanimate entity or process) that causes the death of the VICTIM.	moved	3	3	3
	phys_existed	5	5	5
	created	1	1	1
	destroyed	1	3	1
	changed_poss	1	1	1
	changed_state	3	3	3
	stationary	3	3	3

Reisinger et. al. (2015)

A little bit of history

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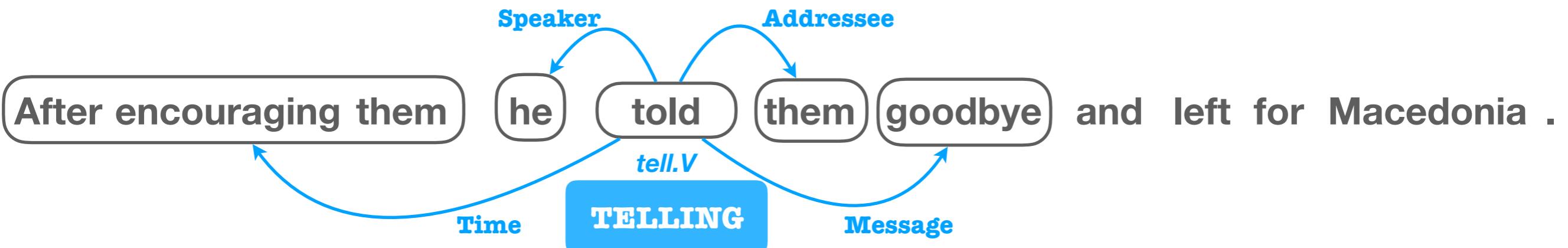
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 - Shared tasks in 2005, 2008, 2009, 2012
- SemEval 2007 Shared Task 19 (Baker, Ellsworth & Erk, 2007) sparked interest in automatic frame-SRL.

Frame-SRL data for supervised training



- Full-text annotations
 - 22 K targets
 - Train (70%) / Dev (10%) / Test (20%)
- Mapping between LUs and frames
 - 11.8 K LUs : 1 K frames
- Mapping between frames and frame-elements:
 - 1 K frames : 9 K frame-elements
- Exemplars
 - 153 K

FrameNet 1.5

Model architectures

Model architectures

- Most common approach: **Supervised learning**

Model architectures

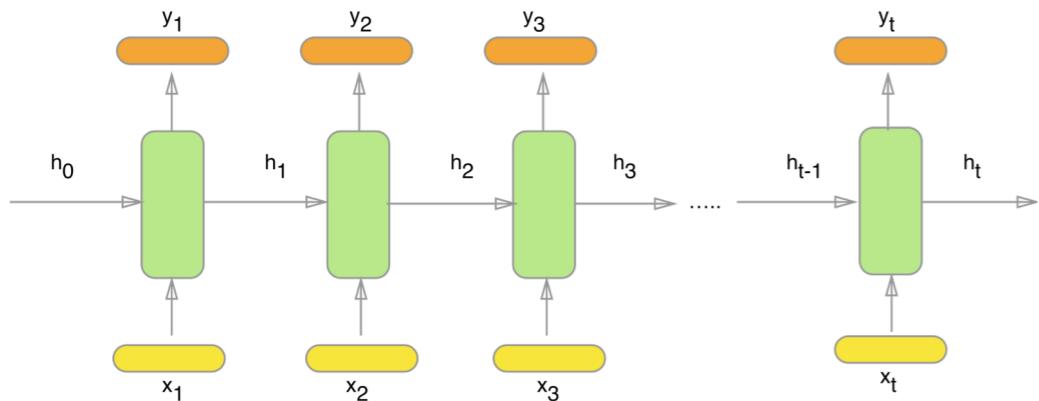
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- Linear models - most models prior to 2015
 - May use distributional representations

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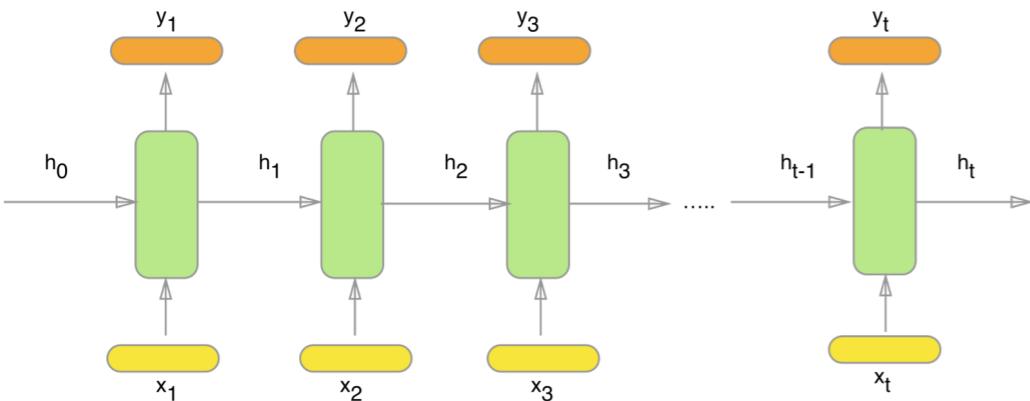
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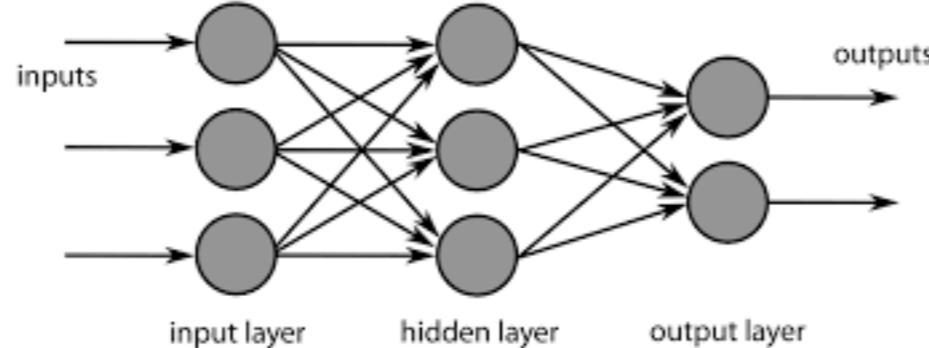
Recurrent Neural Nets

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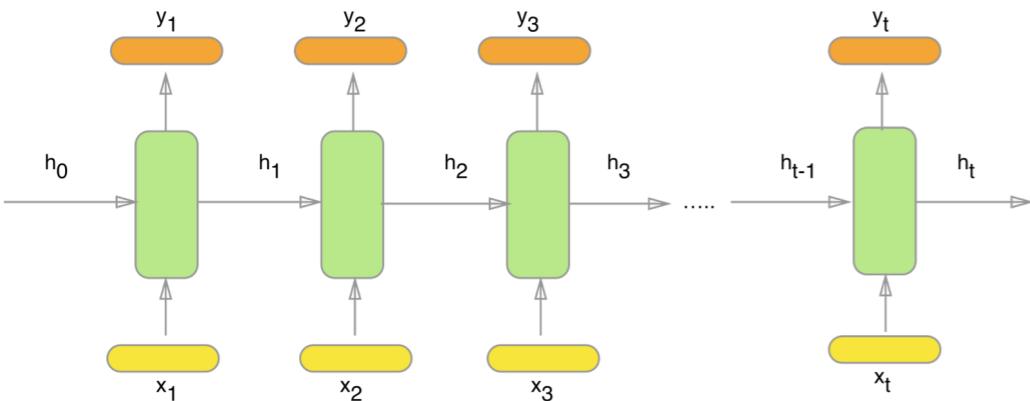
Recurrent Neural Net



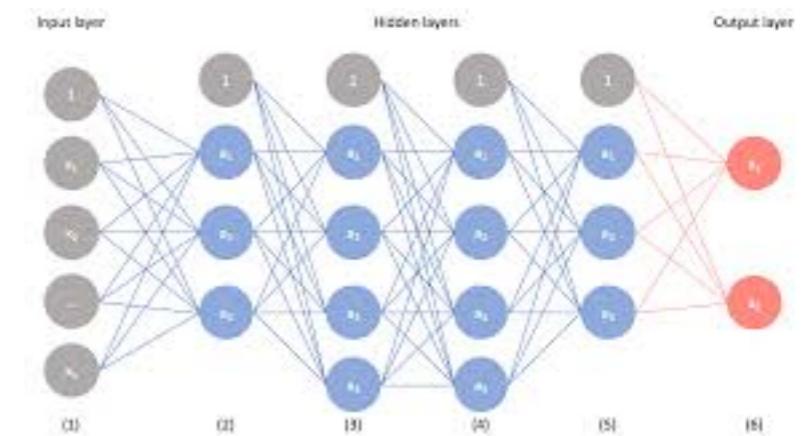
Feed-forward Nets

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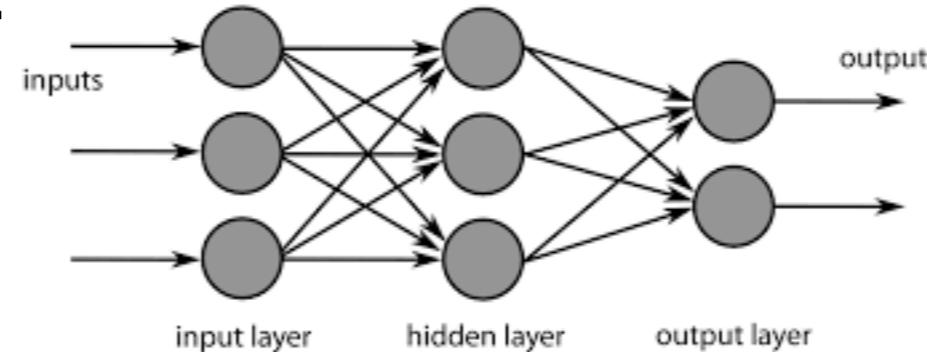
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Recurrent Neural Net



Convolutional Neural Nets

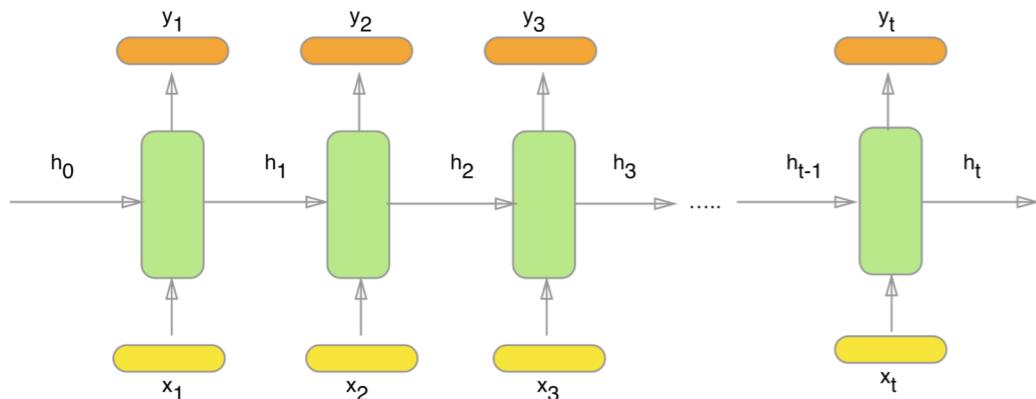


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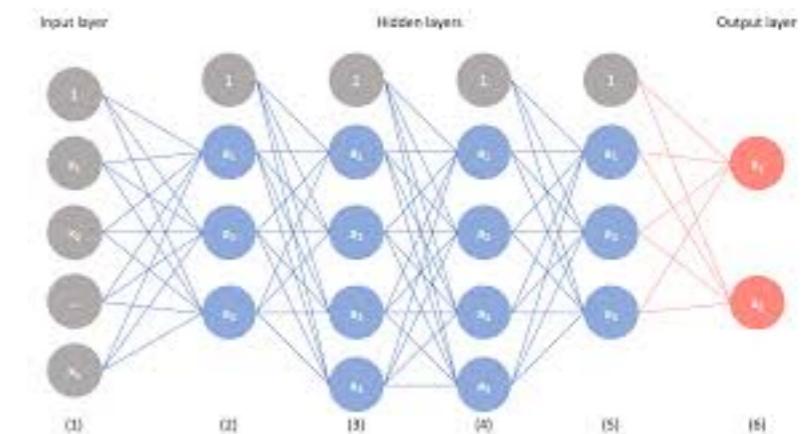
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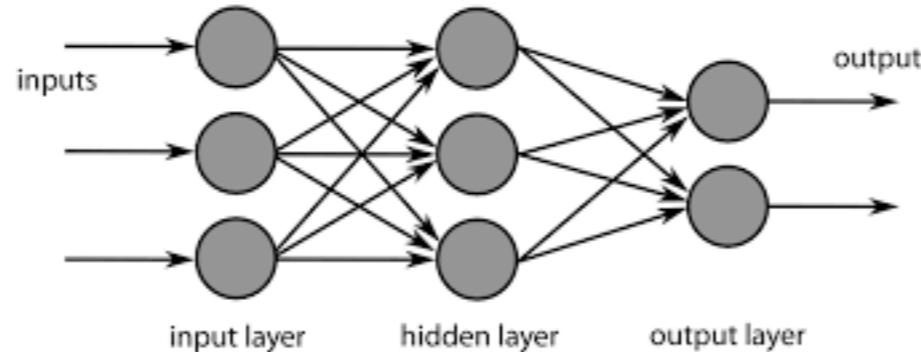
**FrameNet / PropBank
/ Span-based graphs /
Dependency Graphs**



Recurrent Neural Net



Convolutional Neural Nets



Feed-forward Nets

Why automatic frame-SRL?

Why automatic frame-SRL?

- Information extraction (Surdeanu, et al., 2003)
- Textual entailment (Tatu & Moldovan, 2005; Burchardt & Frank, 2006)
- Text categorization (Moschitti, 2008)
- Question answering (Narayanan & Harabagiu, 2004; Frank, et. al., 2007; Moschitti, et. al., 2007; Shen & Lapata, 2007)
- Machine Translation (Wu & Fung, 2009, Marcheggiani et. al., 2017) and its evaluation (Giménez & Márquez, 2007)
- Text-to-scene generation (Coyne et. al., 2012)
- Dialog systems (Chen et. al., 2013)
- Social network extraction (Agrawal et. al., 2014)
- Knowledge Extraction from Twitter (Søgaard et. al., 2015)

Summary of Part 1

- Frame-SRL as a graph induction task
 - ▶ Subtasks
- Related tasks:
 - ▶ Propbank SRL, QA-SRL, AMR, Semantic Prototypes
- What's in the dataset?
- Supervised Learning: Shift from linear to non-linear models

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Target Identification

After encouraging them , he told them goodbye and left for Macedonia .
after.PREP encourage.V tell.V leave.V

- Predict “semantically salient” tokens as targets in the sentence.
- Also, identify the lexical units (LUs) = lemma + POS tag of targets
 - ▶ There might be ambiguity here! Example “**encourage.V**” vs “**encouraging.A**”
- Average in FN 1.5: 6 targets per sentence.

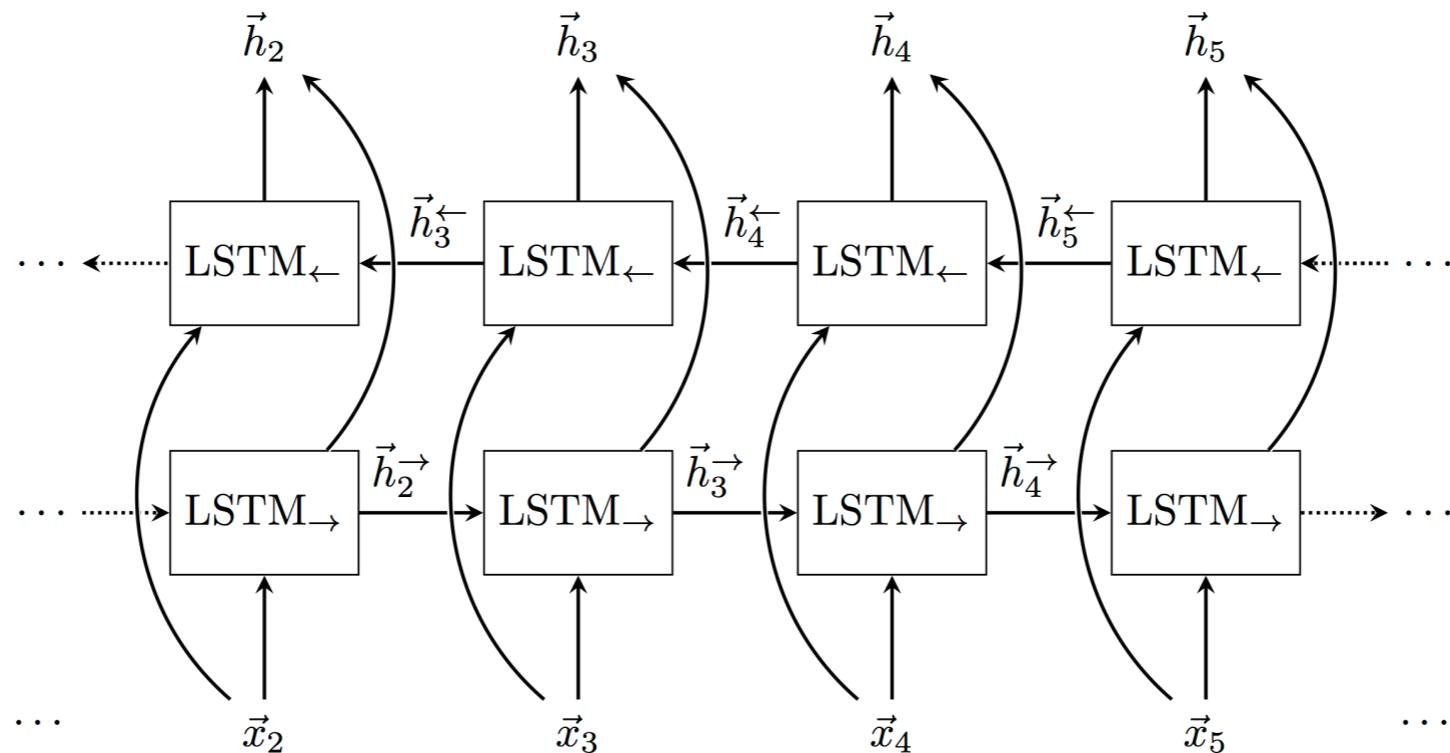
Target ID: challenges

- Data sparsity, cannot use exemplar data.
- No simple POS tag based bijection, unlike in PropBank, where targets are almost always verbs.
- FrameNet: Verbs, nouns, adjectives and prepositions can be targets, BUT not always!
- Multi-word expressions also considered valid targets. About 4% of all targets in FN 1.5.
 - ▶ Span “**tell apart**” gets labeled with LU “**tell_apart.V**”
- Targets can be discontinuous
 - ▶ Span “**there would have been**” gets labeled as LU “**there_be.V**”.

Target ID: model based on heuristics

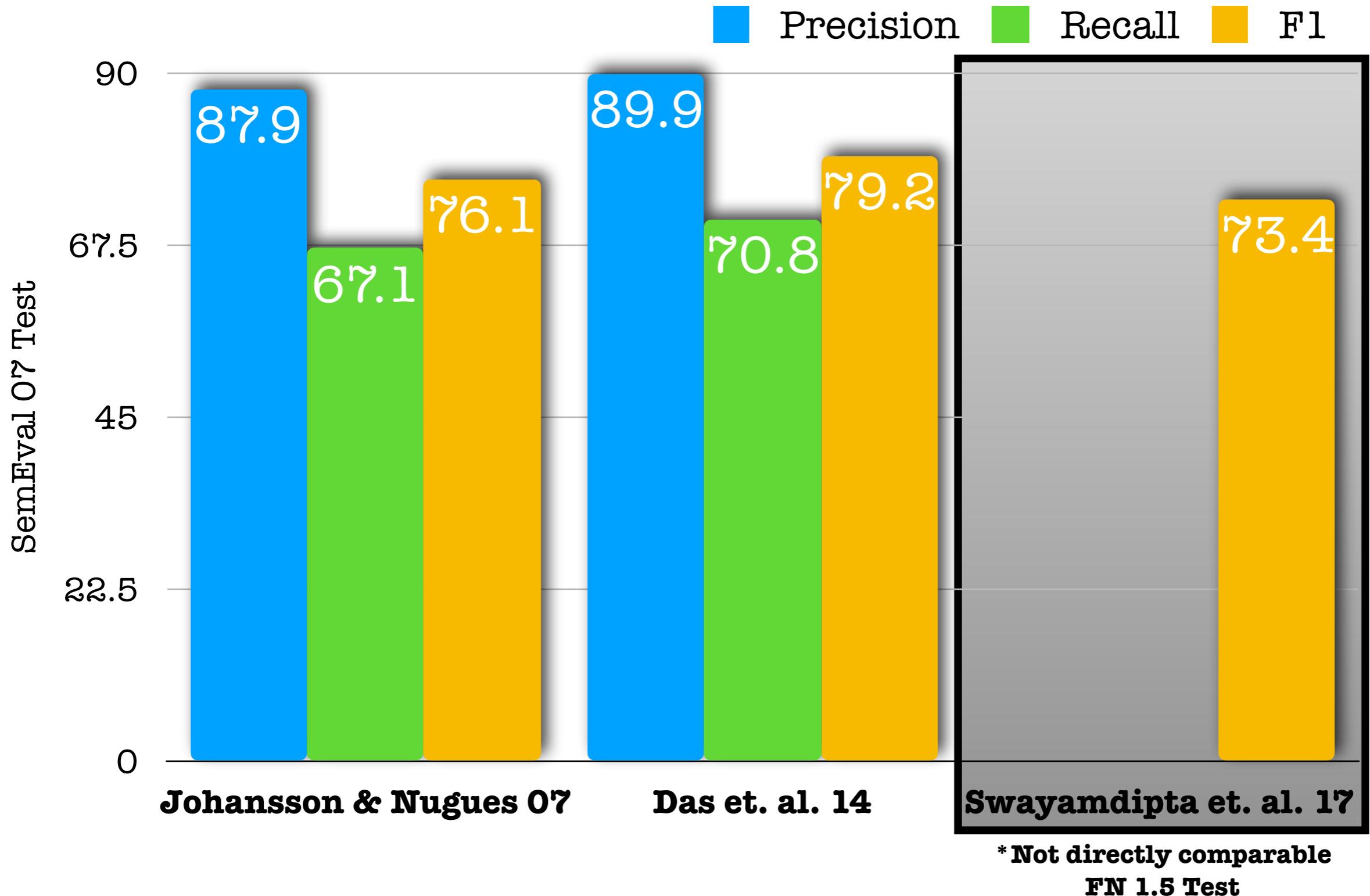
- **have** was retained only if had an object,
- **be** was retained only if it was preceded by **there**,
- **will** was removed in its modal sense,
- **of course** and **in particular** were removed,
- the prepositions **above**, **against**, **at**, **below**, **beside**, **by**, **in**, **on**, **over**, and **under** were removed unless their head was marked as locative,
- **after** and **before** were removed unless their head was marked as temporal,
- **into**, **to**, and **through** were removed unless their head was marked as direction,
- **as**, **for**, **so**, and **with** were always removed,
- because the only sense of the word was the frame PARTITIVE, it was removed unless it was preceded by **only**, **member**, **one**, **most**, **many**, **some**, **few**, **part**, **majority**, **minority**, **proportion**, **half**, **third**, **quarter**, **all**, or **none**, or it was followed by **all**, **group**, **them**, or **us**,
- all targets marked as support verbs for some other target were removed.

Target ID: Neural Model



- Bidirectional RNNs (Open-SESAME; Swayamdipta et. al., 2017) and no syntax!
- Does significantly worse than heuristics-based model.

Target ID: Evaluation



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STIMULATE
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- Given a target (lexical unit) token in the sentence, identify the frame evoked by it.
- On an average, about 2 frames per lexical unit.
- Lexical units play a critical role here, because of the mapping between lexical units and frames.
 - ▶ Errors in identifying targets / lexical units directly impact frame identification.

Frame ID models

- Simple Classification

$$\text{frame} = \arg \max_{\text{frame} \in \text{LU}} p(\text{frame} | \text{target}, \text{LU}, \text{sentence})$$

- When LU is ambiguous:
 - Treat it as another unknown
 - Learn a distribution for it (Das et. al., 2014)

Linear Frame ID Models

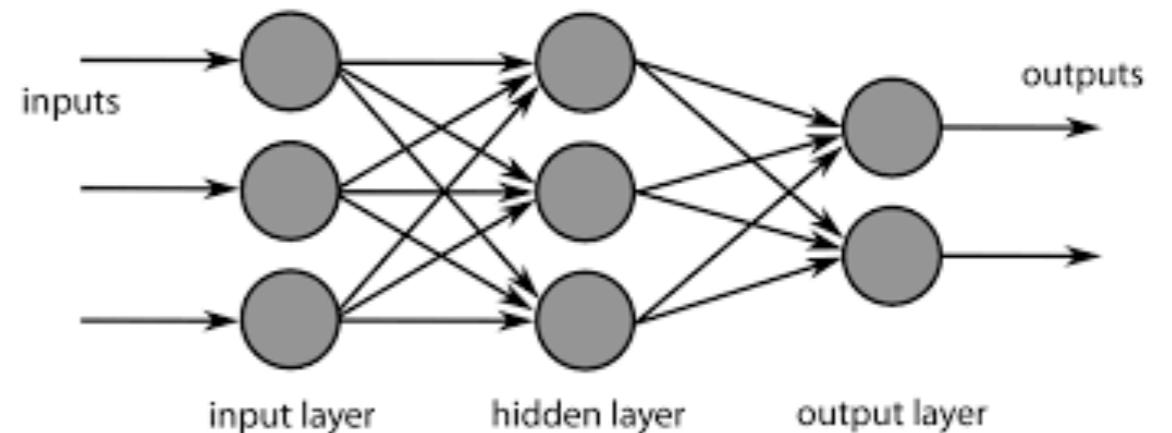
- With features from syntax (Das et. al., CL 2014)
 - the POS of the parent of the head word of t_i
 - * the set of syntactic dependencies of the head word²¹ of t_i
 - * if the head word of t_i is a verb, then the set of dependency labels of its children
 - the dependency label on the edge connecting the head of t_i and its parent
 - the sequence of words in the prototype, w_ℓ
 - the lemmatized sequence of words in the prototype
 - the lemmatized sequence of words in the prototype and their part-of-speech tags π_ℓ
 - WordNet relation²² ρ holds between ℓ and t_i
 - WordNet relation²² ρ holds between ℓ and t_i , and the prototype is ℓ
 - WordNet relation²² ρ holds between ℓ and t_i , the POS tag sequence of ℓ is π_ℓ , and the POS tag sequence of t_i is π_t

Neural Models for Frame ID

- Feed-forward nets
 - With syntactic features
(Hermann et. al., 2015)
 - Without syntactic features
(Swayamdipta et. al., 2017)
- Distributional and visual
features (Hartmann et. al.,
2017; Botschen et. al., 2018)
- With Argument ID (Yang et. al.
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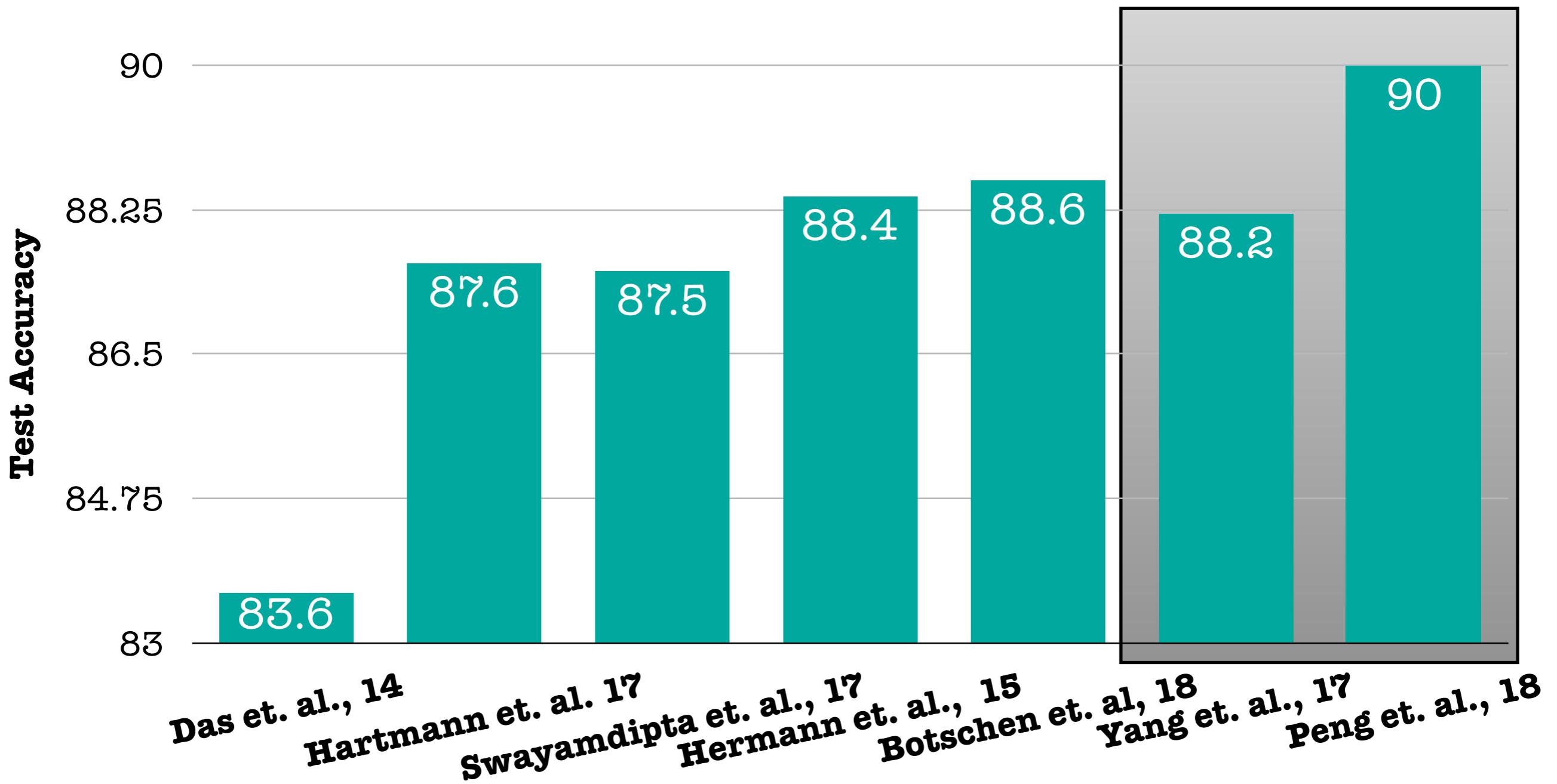
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Feed-forward Nets

Frame ID: Evaluation

Given GOLD targets!



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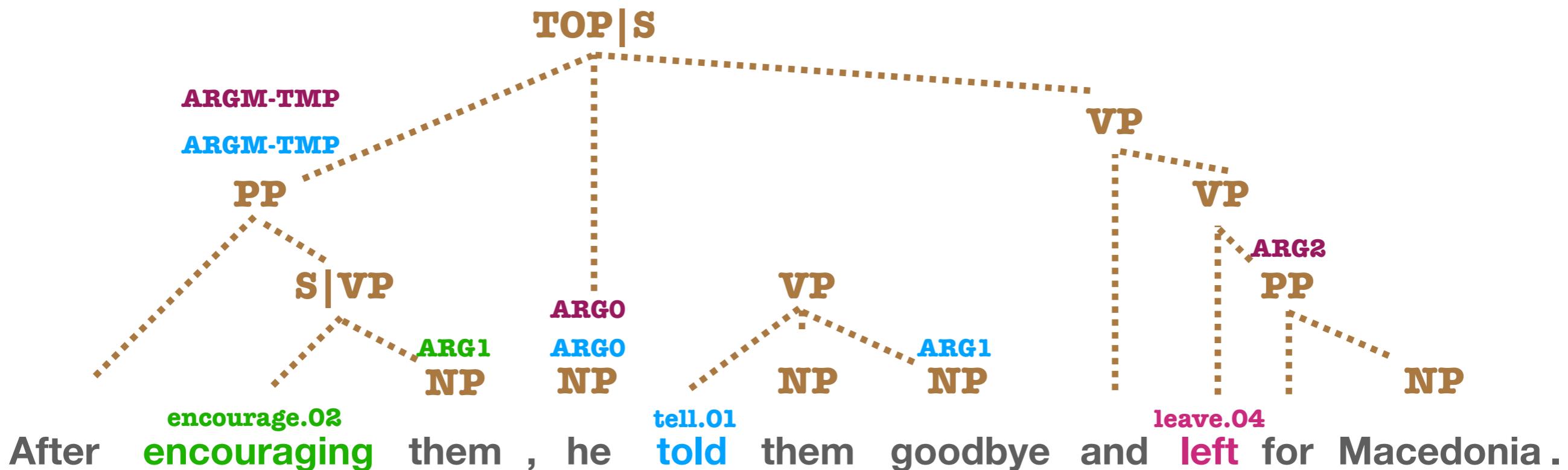
Argument Identification

After encouraging them , he told them goodbye and left for Macedonia .
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- Given a target and the frame it evokes, identify
 - ▶ all the spans in the sentence which are arguments to the frame,
 - ▶ and their respective labels (frame-elements)

PropBank vs FrameNet arguments



- Primary difference between PropBank SRL and Frame SRL arg ID:

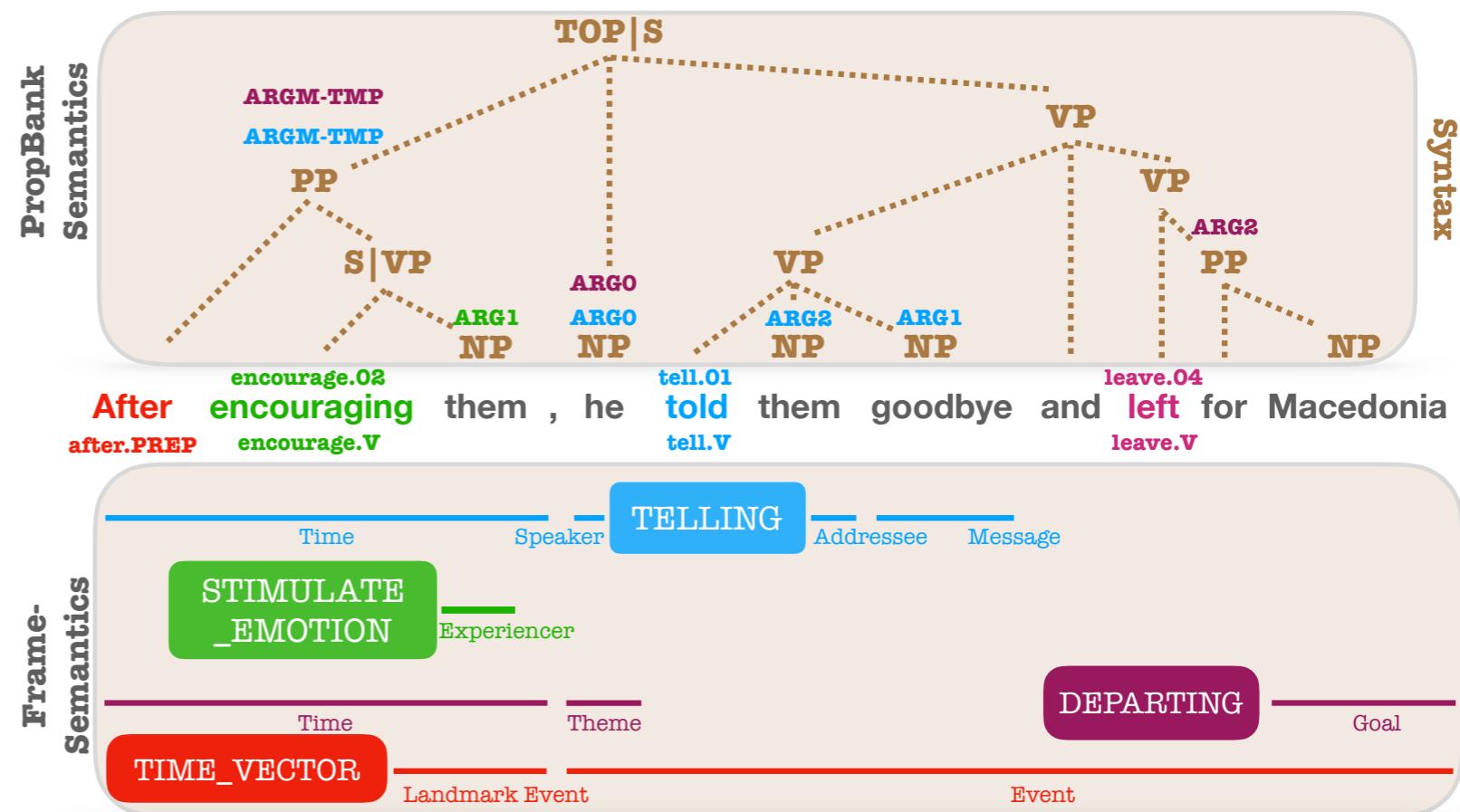
- ▶ PropBank role labels ($\text{ARG}_0 - \text{ARG}_n$) are uniform across predicates.
- ▶ ARG_0 and ARG_1 correspond to Dowty's (1991) proto-agent and proto-patient, respectively.
- ▶ Higher ARG_n have verb-specific definitions.

Arg ID: Basics

- Arguably, the most challenging task!
- Each predicate/ target (and its frame) considered independently
- Arguments as spans
- Arguments as sequences

Role of syntax

- Traditional feature design (Das et. al. 2014)
- Heuristics for potential argument identification (Das et. al., 2014)
- Continuous valued features (Roth & Lapata, 2016; Yang et. al., 2017)
- Constraints during decoding (He et. al., 2017)



Linear Arg ID models

$$\text{role} = \arg \max_{\text{role} \in \text{frame}} p(\text{role} | \text{frame}, \text{LU}, \text{target}, \text{span})$$

- Span classification task
- Candidate spans pruned by syntactic rules
- Features rely heavily on syntax

Features with both null and non-null variants: These features come in two flavors: if the argument is null, then one version fires; if it is overt (non-null), then another version fires.

- some word in t has lemma λ
- some word in t has lemma λ , and the sentence uses PASSIVE voice
- the head of t has subcategorization sequence $\tau = \langle \tau_1, \tau_2, \dots \rangle$
- the head of t has c syntactic dependents

- some word in t has POS π
- some word in t has lemma λ , and the sentence uses ACTIVE voice
- some syntactic dependent of the head of t has dependency type τ
- bias feature (always fires)

Span content features: apply to overt argument candidates.

- POS tag π occurs for some word in s
- the first word of s has POS π
- the last word of s has POS π
- the head word of s has syntactic dependency type τ
- w_{s_2} and its closed-class POS tag π_{s_2} , provided that $|s| \geq 2$
- the head word of s has lemma λ
- the last word of s : $w_{s_{|s|}}$ has lemma λ
- $w_{s_{|s|}}$, and its closed-class POS tag $\pi_{s_{|s|}}$, provided that $|s| \geq 3$
- lemma λ is realized in some word in s , the voice denoted in the span (ACTIVE or PASSIVE)

- the head word of s has POS π
- $|s|$, the number of words in the span
- the first word of s has lemma λ
- the first word of s : w_{s_1} , and its POS tag π_{s_1} , if π_{s_1} is a closed-class POS
- the syntactic dependency type τ_{s_1} of the first word with respect to its head
- τ_{s_2} , provided that $|s| \geq 2$
- $\tau_{s_{|s|}}$, provided that $|s| \geq 3$
- lemma λ is realized in some word in s
- lemma λ is realized in some word in s , the voice denoted in the span, s 's position with respect to t (BEFORE, AFTER, or OVERLAPPING)

Syntactic features: apply to overt argument candidates.

- dependency path: sequence of labeled, directed edges from the head word of s to the head word of t

- length of the dependency path

Span context POS features: for overt candidates, up to 6 of these features will be active.

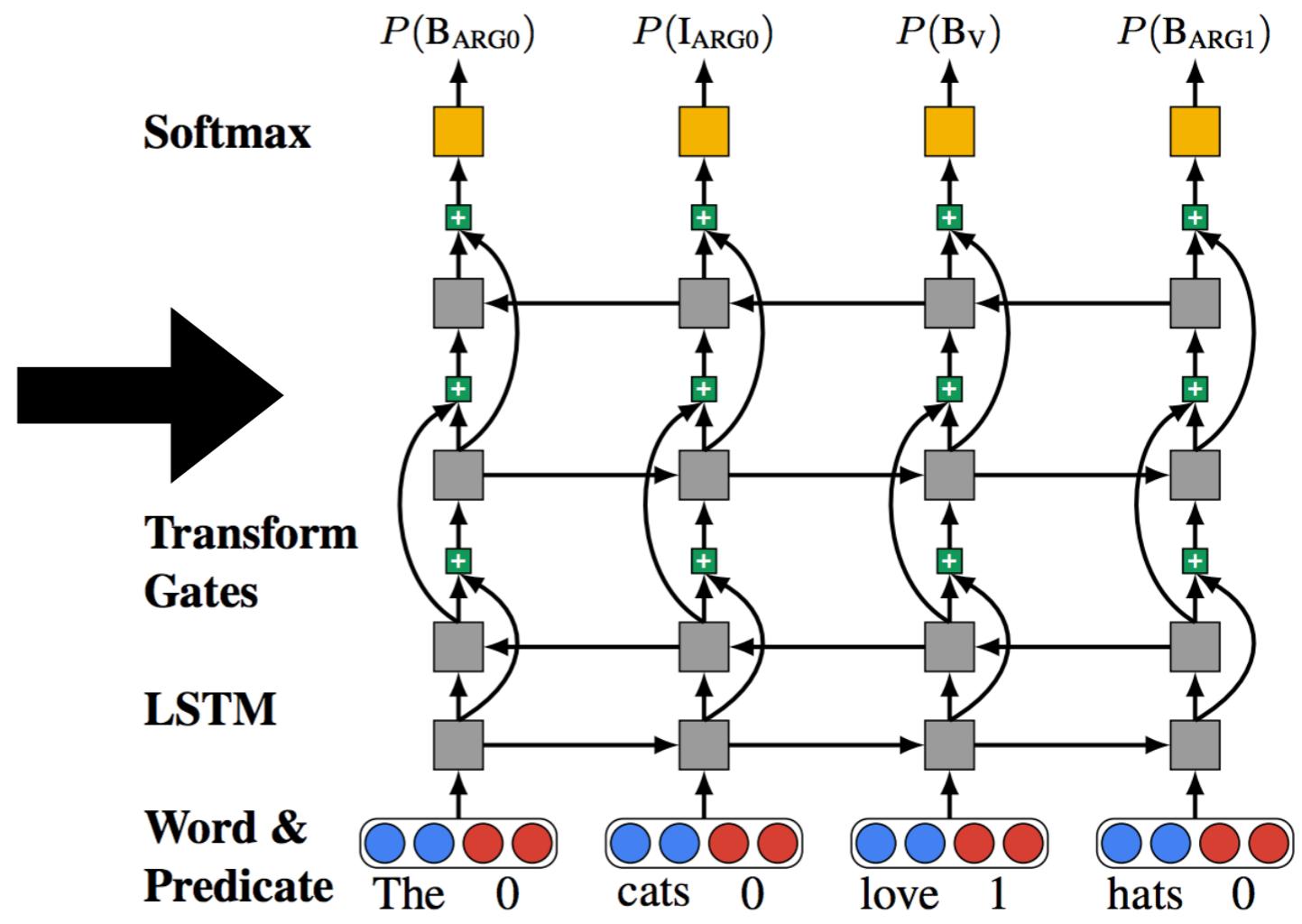
- a word with POS π occurs up to 3 words before the first word of s
- a word with POS π occurs up to 3 words after the last word of s

Ordering features: apply to overt argument candidates.

- the position of s with respect to the span of t : BEFORE, AFTER, or OVERLAPPING (i.e. there is at least one word shared by s and t)
- linear word distance between the nearest word of s and the nearest word of t , provided s and t do not overlap
- target-argument crossing: there is at least one word shared by s and t , at least one word in s that is not in t , and at least one word in t that is not in s
- linear word distance between the middle word of s and the middle word of t , provided s and t do not overlap

Neural models for Arg ID

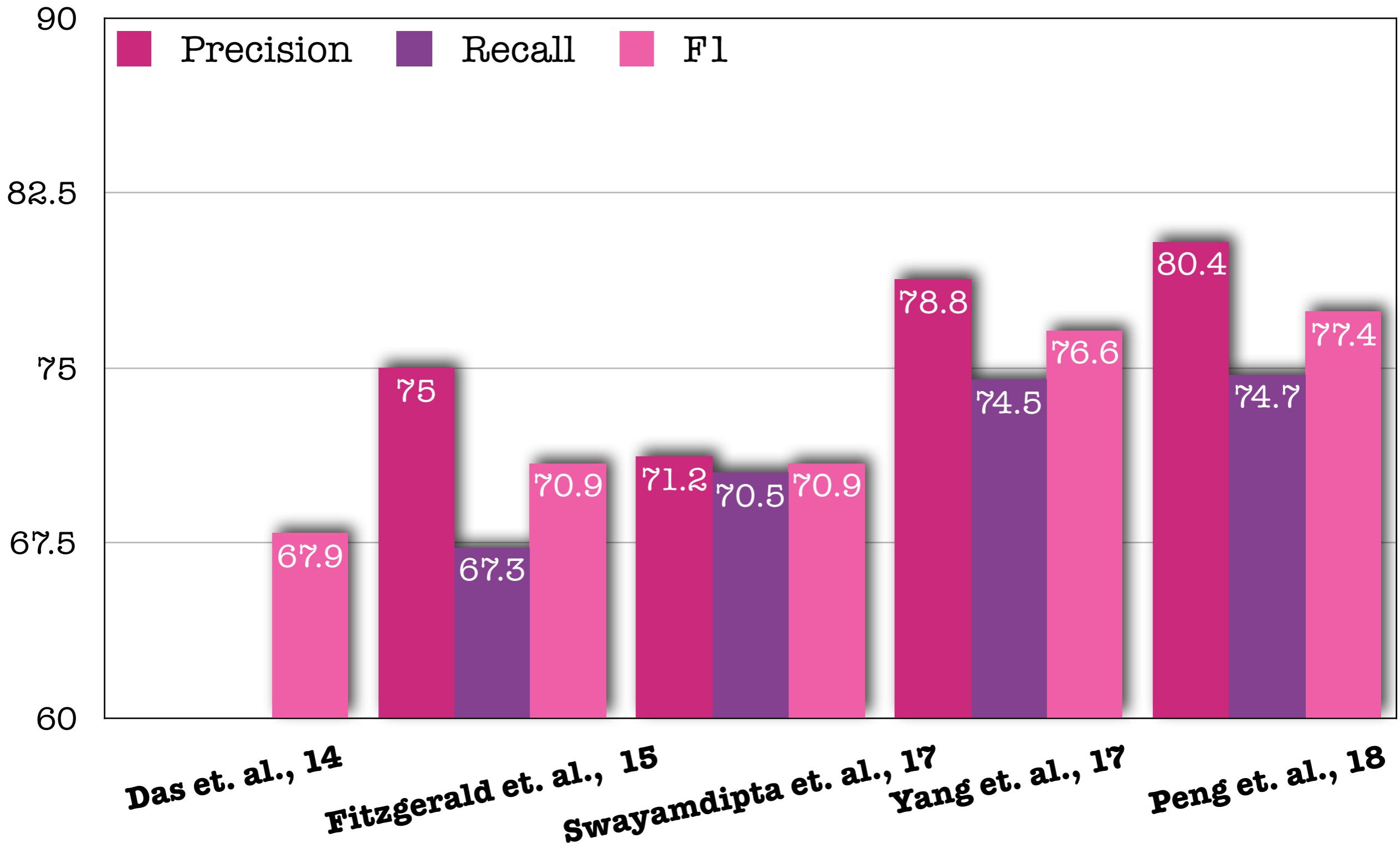
- BIO specification
- Deep bidirectional, highway
(Zhou & Xu, 2015;
He et. al. ACL 2017)
- Transformers
(Tan et. al., AAAI
2018; Strubell et. al.,
2018)



He et. al. (2017)

Frame + Arg ID: Evaluation

Given GOLD targets!



End-to-end Frame SRL evaluation



Summary of Part 2

- Subtasks have their own intricacies.
- Automation is coming along fast, we have seen big gains.
- Non-uniformity of evaluation is an issue.
- Can we do better? [Part 3]

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Biggest Challenge

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- Availability of data

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- Part 3: Make the best of available supervision through advanced modeling
 - ▶ Joint prediction
 - ▶ Multitask learning

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 - ▶ Joint prediction
 - ▶ Multitask learning
- Part 4: Enhance the amount of supervision

Getting the most out of data

- Frame-semantic parsing with heterogenous annotations
(Kshirsagar et. al., 2015)
 - Frame Hierarchy
 - Exemplar annotations
 - PropBank
- Relatively unused: Grammatical Functions and Phrase Types of frame-elements
 - Only for gold arguments

Joint prediction

Joint prediction

- Pipelining the subtasks is lossy
 - ▶ Targets, frames, frame-elements are mutually informative!

Joint prediction

- Pipelining the subtasks is lossy
 - ▶ Targets, frames, frame-elements are mutually informative!
- All frame-elements together:
 - Reranking with global features (Toutanova et. al. 2008)
 - Approximate prediction with global constraints (AD³ : Das et. al. 2012)

Joint prediction

- Pipelining the subtasks is lossy
 - ▶ Targets, frames, frame-elements are mutually informative!
- All frame-elements together:
 - Reranking with global features (Toutanova et. al. 2008)
 - Approximate prediction with global constraints (AD³ : Das et. al. 2012)
- Frames + frame-elements:
 - Approximate prediction with AD³ (Yang et. al., 2017; Peng et. al., 2018)

Joint prediction

- Pipelining the subtasks is lossy
 - ▶ Targets, frames, frame-elements are mutually informative!
- All frame-elements together:
 - Reranking with global features (Toutanova et. al. 2008)
 - Approximate prediction with global constraints (AD³ : Das et. al. 2012)
- Frames + frame-elements:
 - Approximate prediction with AD³ (Yang et. al., 2017; Peng et. al., 2018)
- Joint prediction of predicates, senses and arguments (Labeled Span Graphs, He et. al., ACL 2018)

Multitask learning

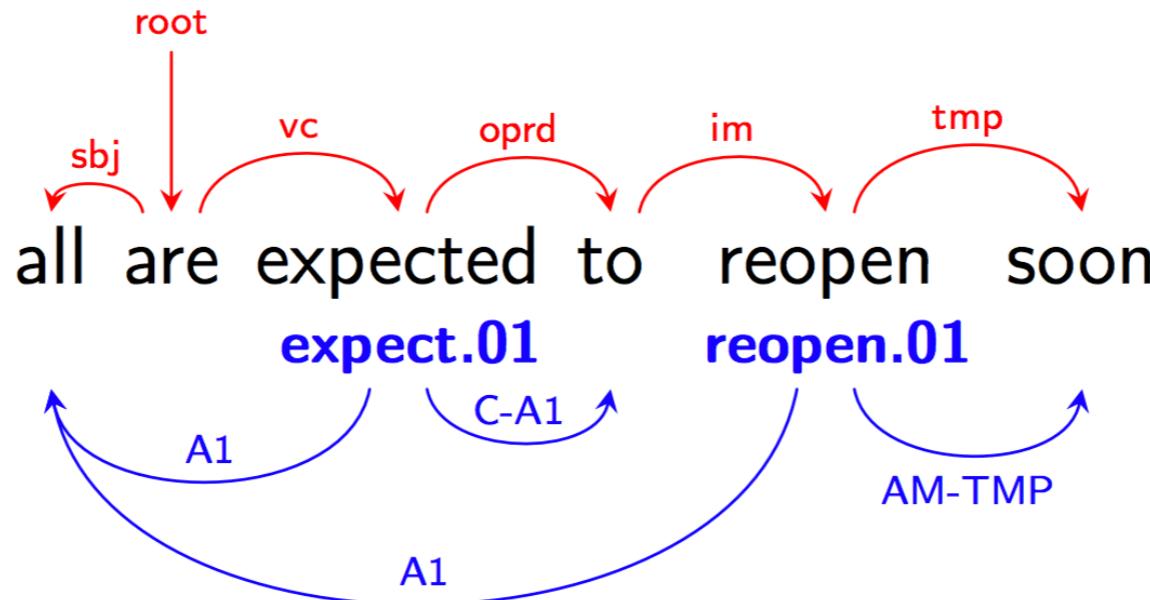
Multitask learning

- With syntax
 - Full syntactic tree (CoNLL shared tasks 2008, 2009)
 - Only relevant parts -Scaffolding (Swayamdipta et. al., EMNLP 2018)

Multitask learning

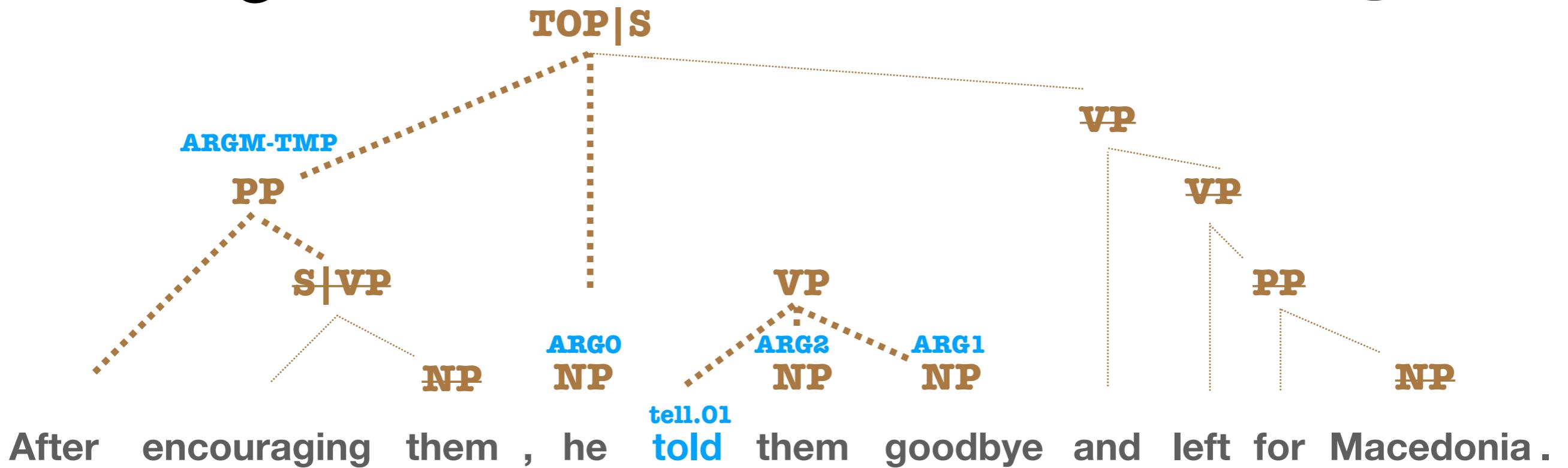
- With syntax
 - Full syntactic tree (CoNLL shared tasks 2008, 2009)
 - Only relevant parts -Scaffolding (Swayamdipta et. al., EMNLP 2018)
- With multiple semantic formalisms:
 - PropBank + FrameNet (Kshirsagar et. al. NAACL 2015; Fitzgerald et. al. EMNLP 2015)
 - Semantic dependencies + FrameNet (Peng et. al. NAACL 2018)

Syntactic tree + semantic graph

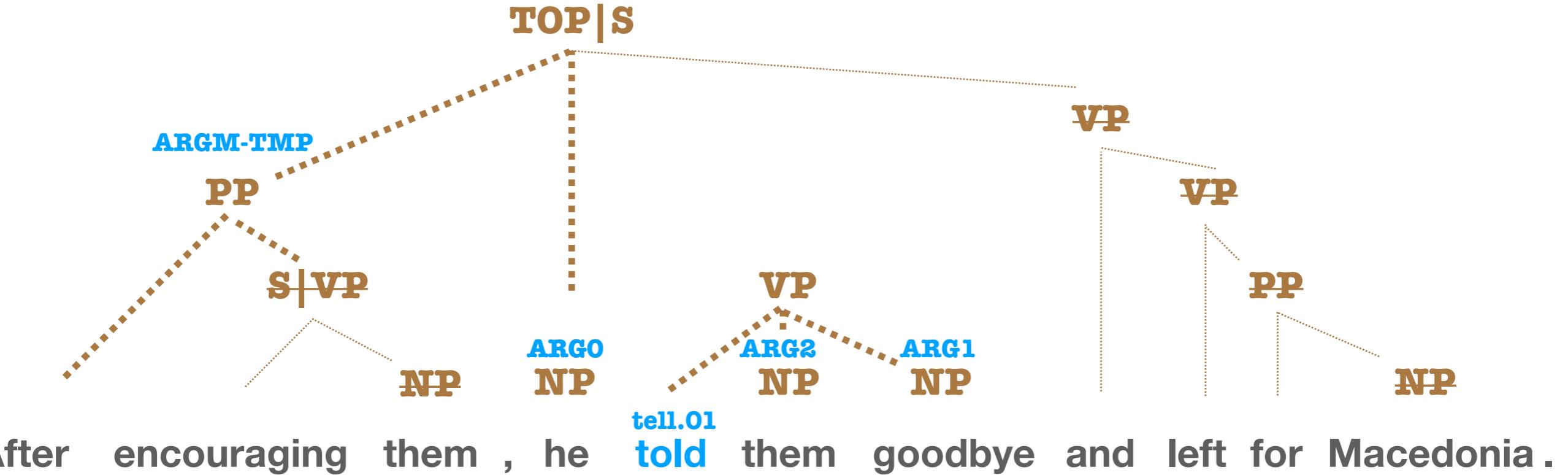


- CoNLL 2008 (Surdeaneau et. al., 2008)
- CoNLL 2009, multilingual (Hajič et. al., 2009)
- Pipelined models : Syntax → Semantics
- Joint models
 - Graph-based (Lluis et. al., 2008, 2013)
 - Transition-based (Titov et. al., 2009; Swayamdipta et. al., 2016)

Syntactic Scaffolding

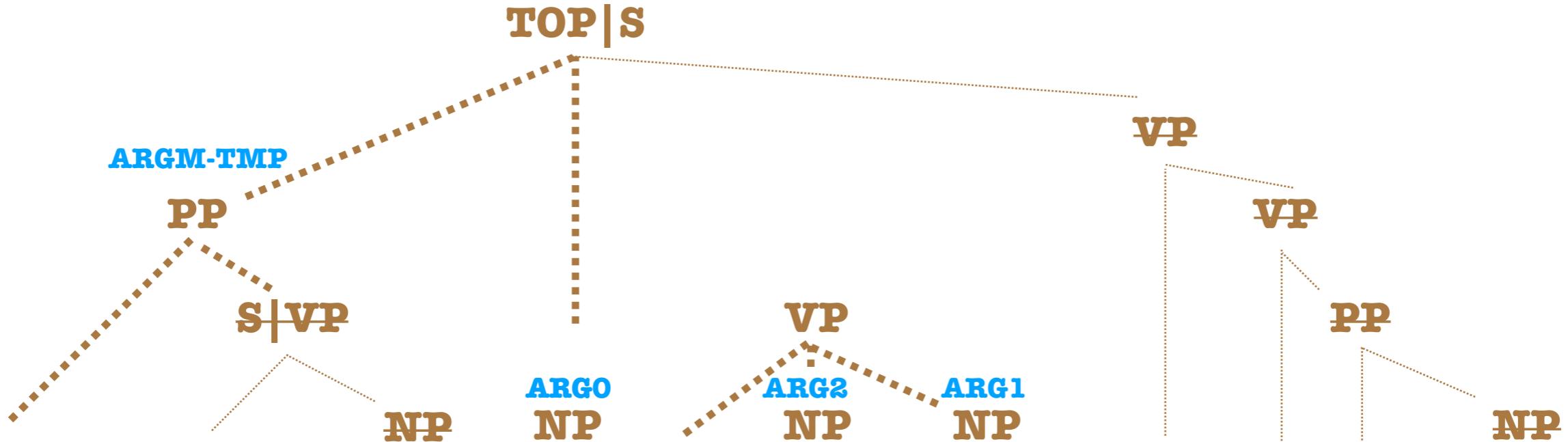


Syntactic Scaffolding



- Instead of learning entire syntactic trees, **only learn parts of the tree** which are relevant for SRL.

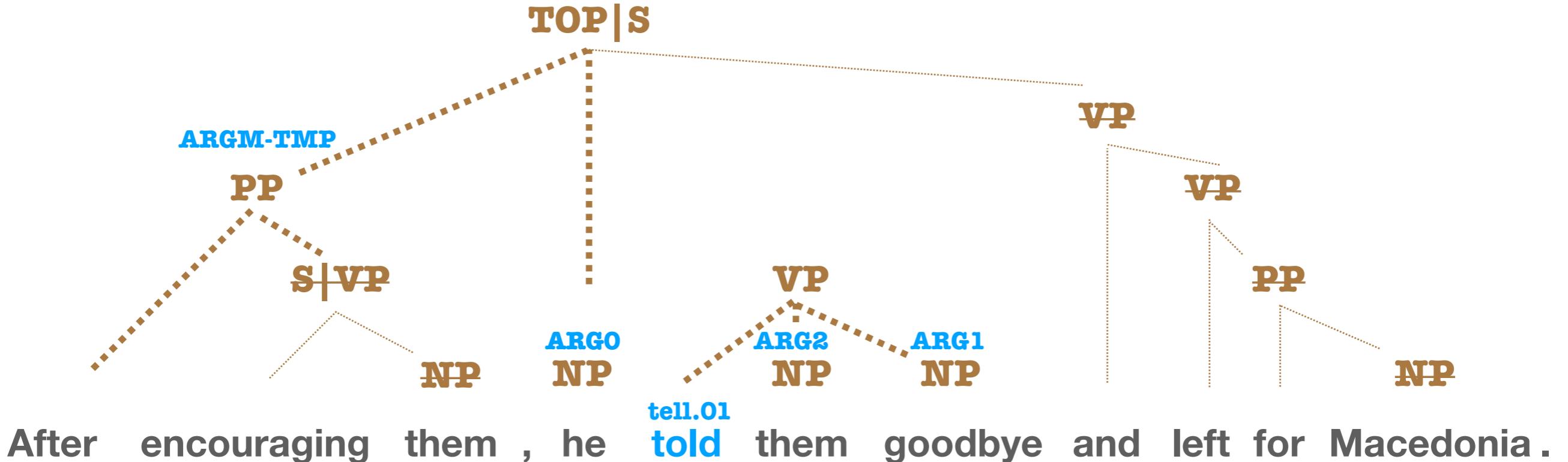
Syntactic Scaffolding



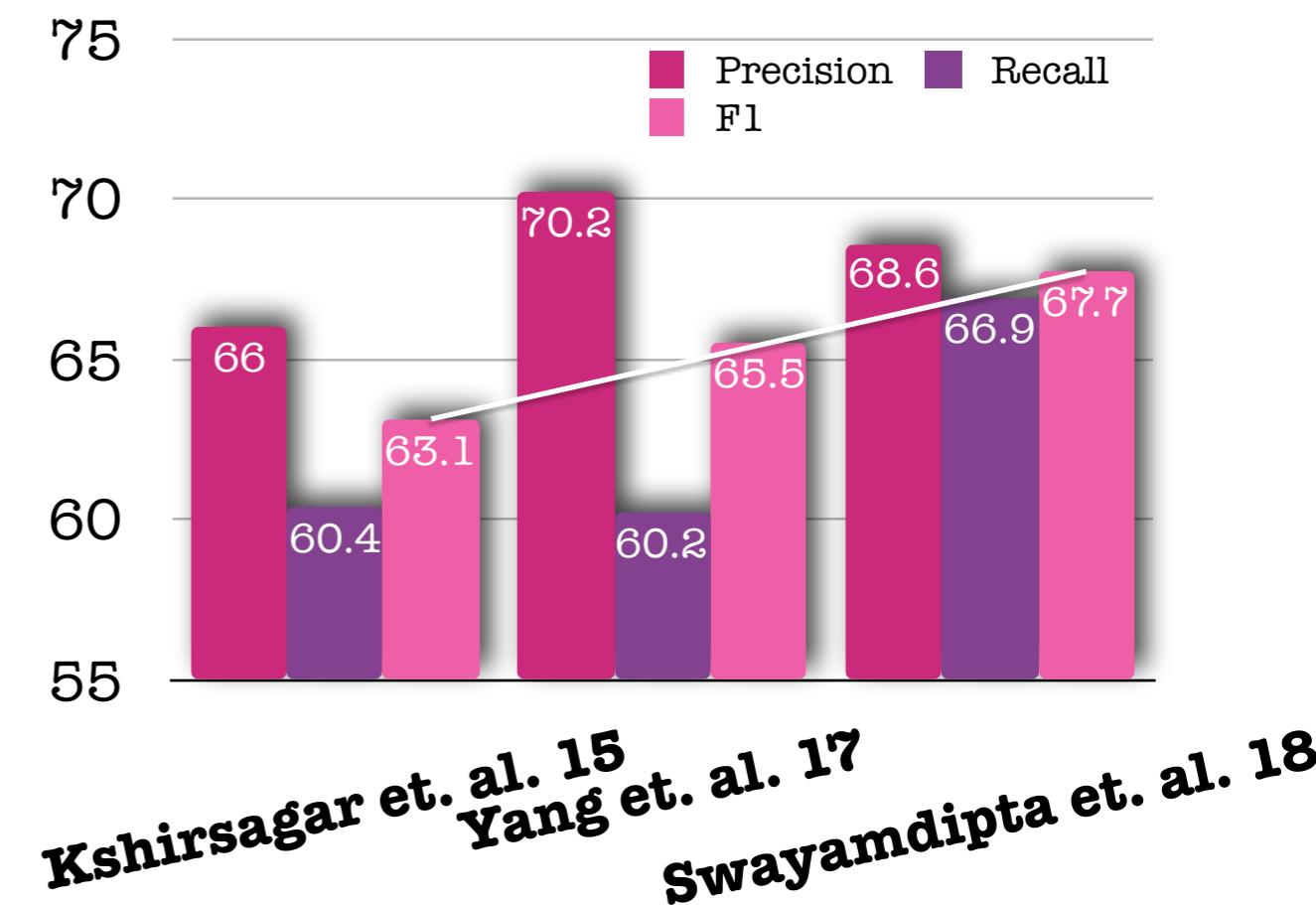
After encouraging them , he told them goodbye and left for Macedonia .

- Instead of learning entire syntactic trees, **only learn parts of the tree** which are relevant for SRL.
- “Scaffold” - can be discarded after training.

Syntactic Scaffolding

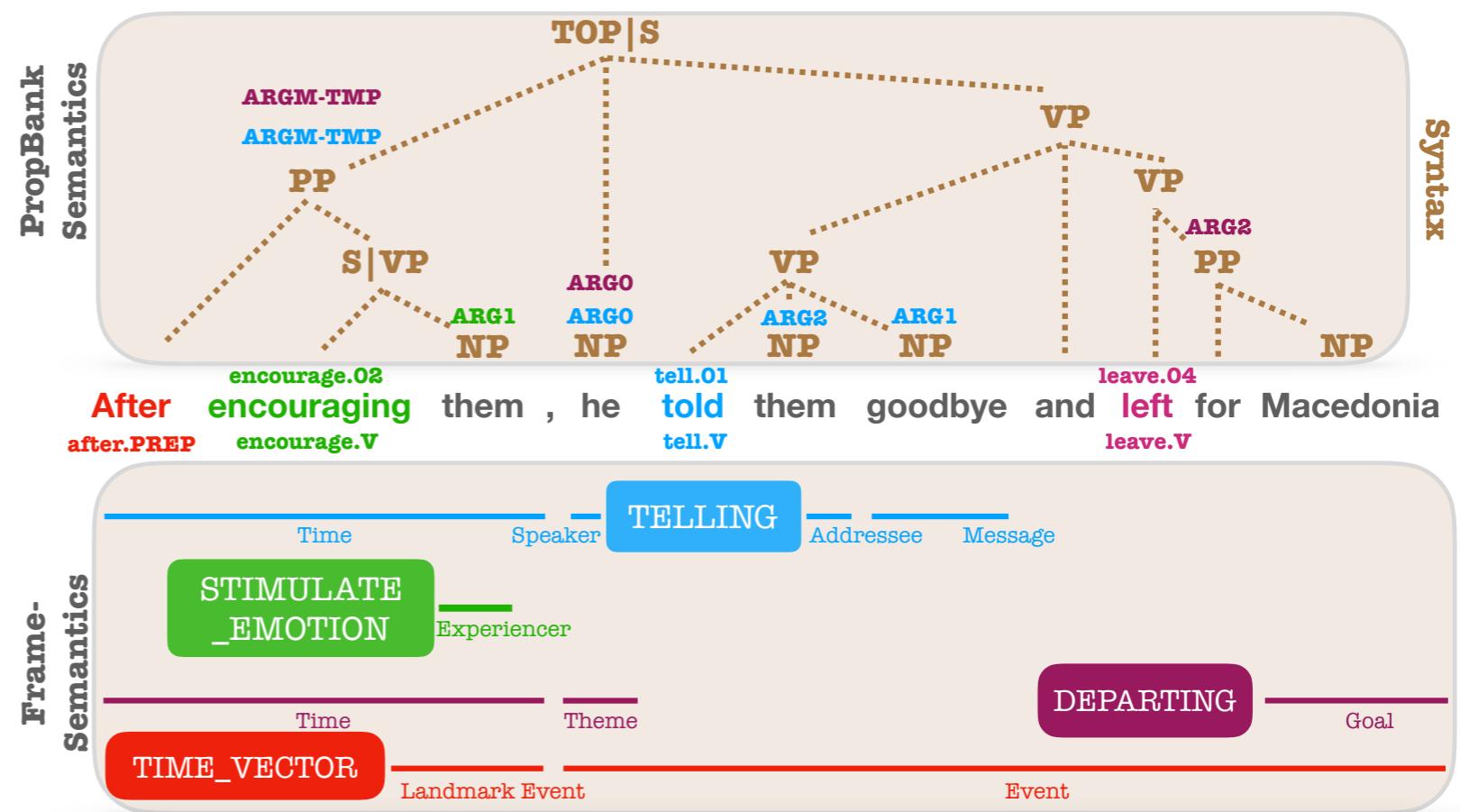


- Instead of learning entire syntactic trees, **only learn parts of the tree** which are relevant for SRL.
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PropBank + Frame-SRL

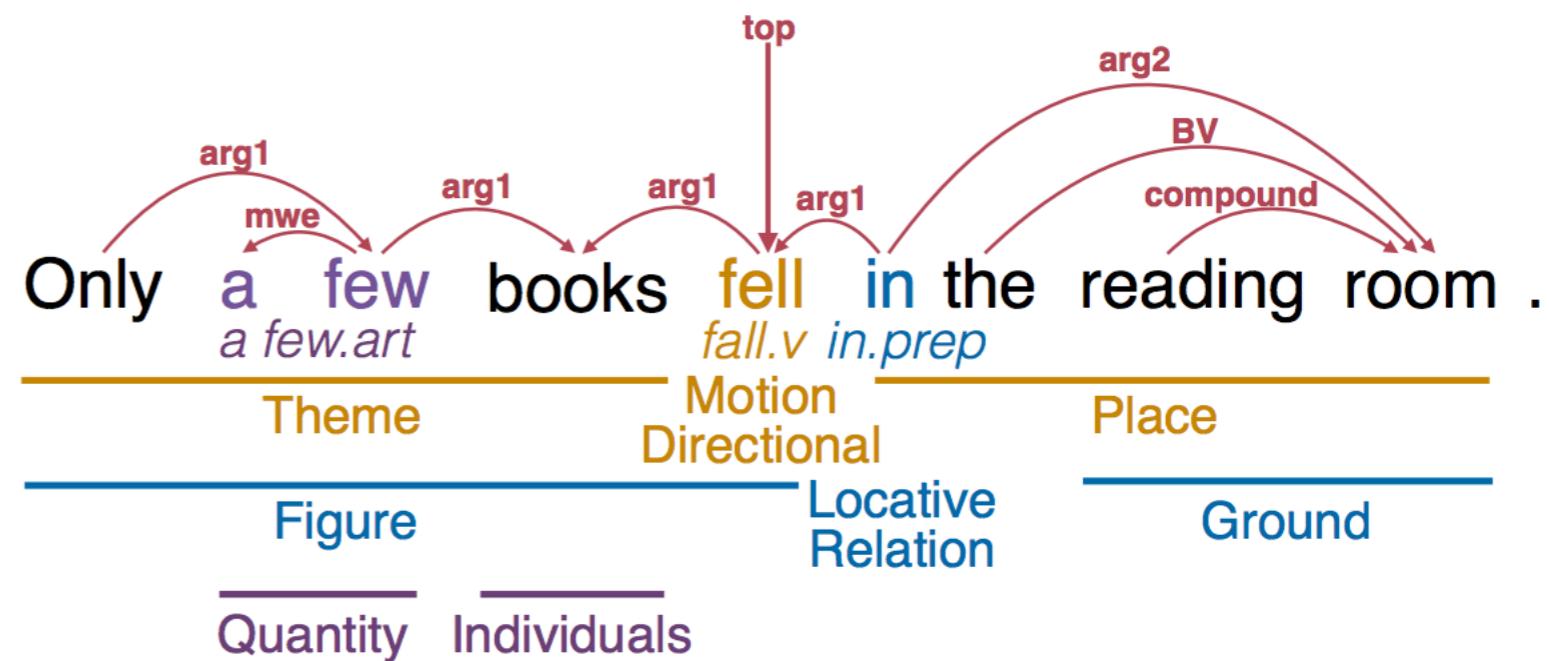
- Significant overlaps between formalisms
- PropBank much larger than FrameNet, so helps FrameSRL performance



Fitzgerald et. al. (2015)
Kshirsagar et. al. (2015)

Semantic Dependencies + Frame-SRL

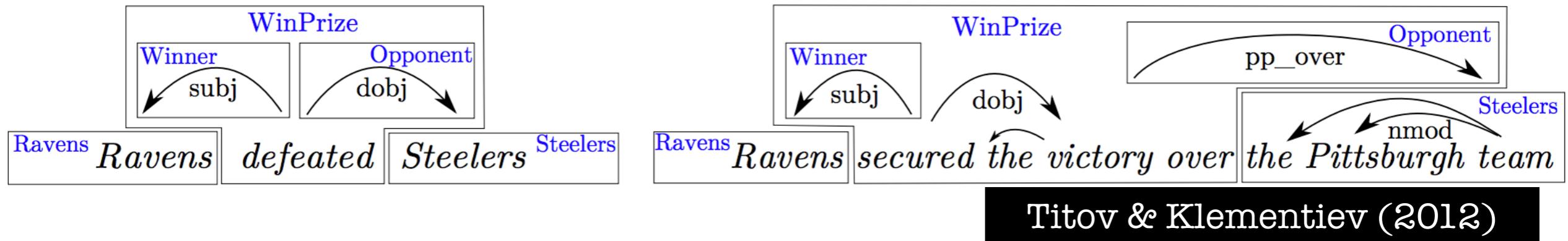
- SemEval 2015 Semantic Dependencies (Oepen et. al., 2015)
- Disjoint formalisms : span-based vs. dependency-based.
- Treat semantic dependencies as “latent” when predicting frame-elements.



Peng et. al. (2018)

Alternatives to supervised learning

Unsupervised approaches



- Two different syntactic trees with a common semantic representation.
- Clusters of syntactic structures correspond to semantic roles.

Semi-supervised approaches

- Pre-trained embeddings, based on language models.
- Seed examples and projection (Fursteau & Lapata, 2012; Das et. al., CL 2014)

Summary of Part 3

- Vanilla classifiers for subtasks can be improved on.
- Joint prediction
- Multi-task learning
- Still need more data... [Part 4]

Outline

1. Task of frame-SRL
2. Primary Subtasks
 - a. Linear
 - b. Neural models
3. Advanced Modeling
- 4. Looking Forward / Multilingual Extensions**

Increasing supervision

- Coverage (Palmer & Sporleder, 2010)
 - Augmentation via Paraphrases (Pavlick et. al. 2015; Rastogi & Van Durme, 2015)
- Domain Adaptation
 - Distributional methods (Croce et. al., 2010)
 - FrameID (Hartmann et. al. EACL 2017)

One glaring gap

One glaring gap

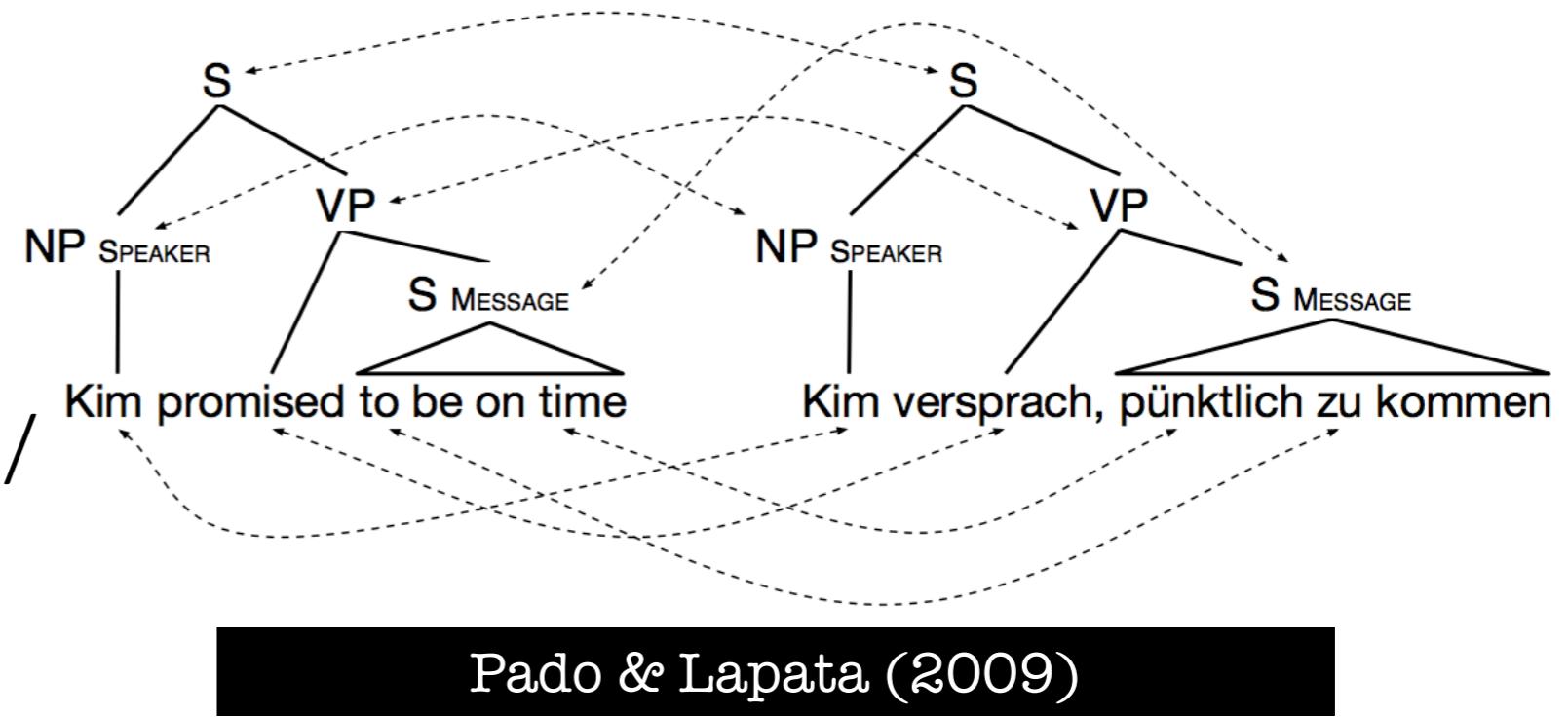


Multilingual SRL: Generating Annotations via Projection

Multilingual SRL:

Generating Annotations via Projection

- Needs parallel corpora
- Projection of annotations via lexical / syntactic alignments between sentences
- Not feasible without parallel data / highly accurate syntax
- Not directly translatable (Akbik et. al., 2015)



SL

A0	need.01	A1				
A0		hold.01	A1		A2	
We	need	to	hold	people	responsible	

TL

Il	faut	qu'	il	y	ait	des	responsables
it	needs	that	there		exist	those	responsible
	need.01	A1			exist.01		A1

Multilingual FN: Generating Annotations

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- Wiktionary + FrameNet for English - German FrameNet
(Hartmann & Gurevych, ACL 2013)

Multilingual FN: Generating Annotations

- Wiktionary + FrameNet for English - German FrameNet
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- Danish Thesaurus + valencies (Pederson et. al., 2018)

Multilingual FN: Generating Annotations

- Wiktionary + FrameNet for English - German FrameNet (Hartmann & Gurevych, ACL 2013)
- Danish Thesaurus + valencies (Pederson et. al., 2018)
- Any language frame-semantic parsing (Johannsen et. al. 2015)
 - ▶ Using word-word translation
 - ▶ 9 languages in 2 domains
 - ▶ Inter-annotator agreement issues stemming from automatic target identification through word-word translation

Models for multilingual SRL

Models for multilingual SRL

- Encouraged by CoNLL 2009 for PropBank SRL

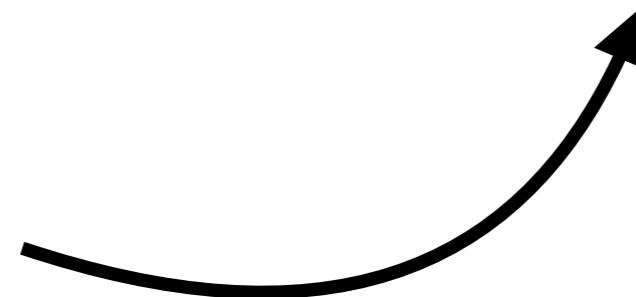
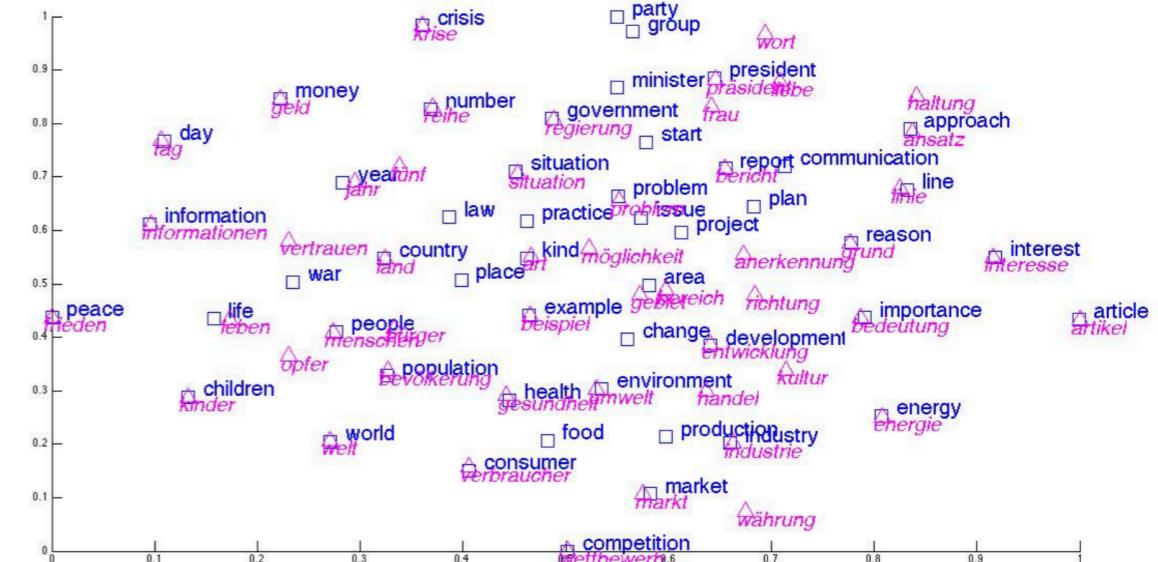
Models for multilingual SRL

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- Primary approach: One model per language
 - Build a single model for SRL
 - Apply to others via language-specific features / embeddings

Models for multilingual SRL

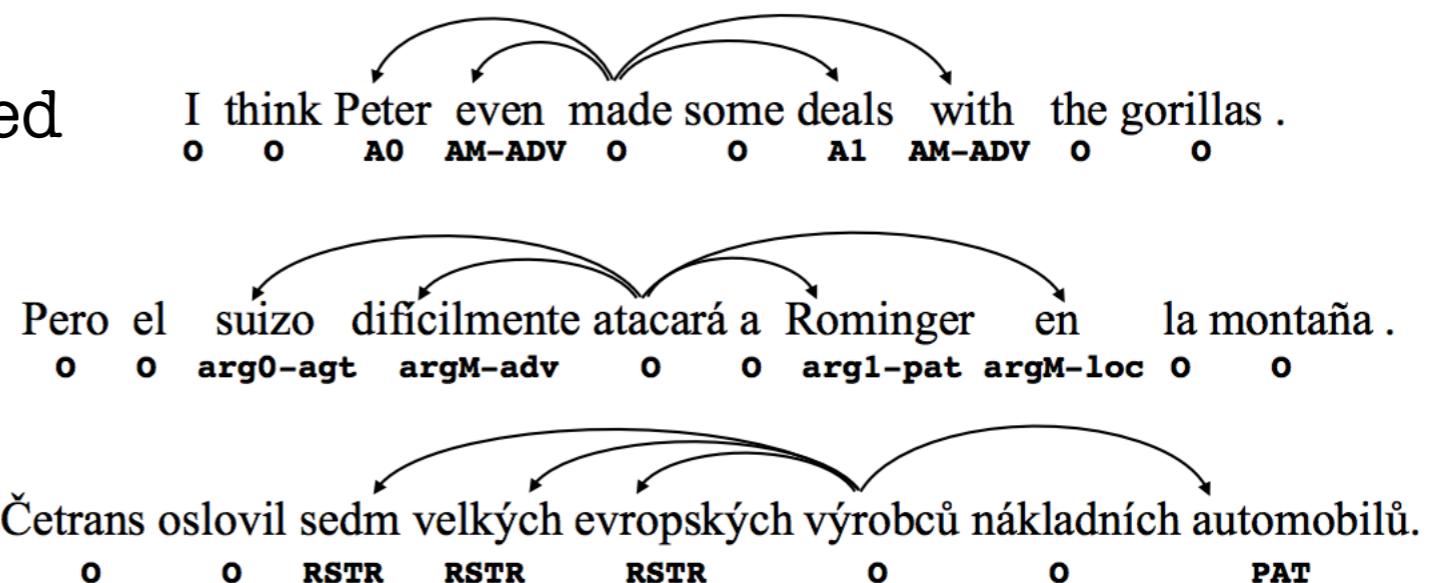
- Encouraged by CoNLL 2009 for PropBank SRL
 - Primary approach: One model per language
 - Build a single model for SRL
 - Apply to others via language-specific features / embeddings
 - Moving towards single multilingual models: Cross-lingual embeddings learned from cross-lingual alignments (Ammar et. al., 2016)

Luong et. al. (2015)



Polyglot SRL

- Training data from pairs of CoNLL 2009 languages merged
- Challenge: Differences in annotation schemes across languages.
- Multilingual word embeddings, learned from cross-lingual alignments (Ammar et. al., 2016)
- Maximum benefit reported for low-resource languages such as Catalan, when combined with English.



Mulcaire et. al. (ACL, 2018)

- Label unification helps (Akbik & Li, 2016) but needs more annotation efforts

Applications of Multilingual FrameNet

- Translation using semantics as pivot.
- Cross-lingual transfer for downstream applications such as knowledge | information | relation extraction.
- Particular benefits for low-resource languages



Summary

- | | | |
|---|--|---|
| <ul style="list-style-type: none">• Part 1:
Frame-SRLa. Graph inductionb. Supervised Learning | <ul style="list-style-type: none">• Part 2:
Subtasks<ul style="list-style-type: none">a. Target Identificationb. Frame Identificationc. Frame-Element Identification | <ul style="list-style-type: none">• Part 3:
Advanced Modeling• Part 4:
Looking Forward / Multilinguality |
|---|--|---|

Slides and references at

<https://github.com/swabhs/coling18tutorial>