

Name: S U Swakath  
Roll No: 180202036

colab link: <https://colab.research.google.com/drive/1veZsh2N4K59HfR5a-1633AOeYWTz4?usp=sharing>

1. Linear regression
2. Logistic regression
3. Support vector machine

## Linear regression

1. Generate 1D data synthetically
2. Take the earlier designed linear regression class
3. Find the fitting line
4. Taking 0.5 as threshold, see the classification

In [171].

```
import numpy as np
import matplotlib.pyplot as plt

# Insert your code here

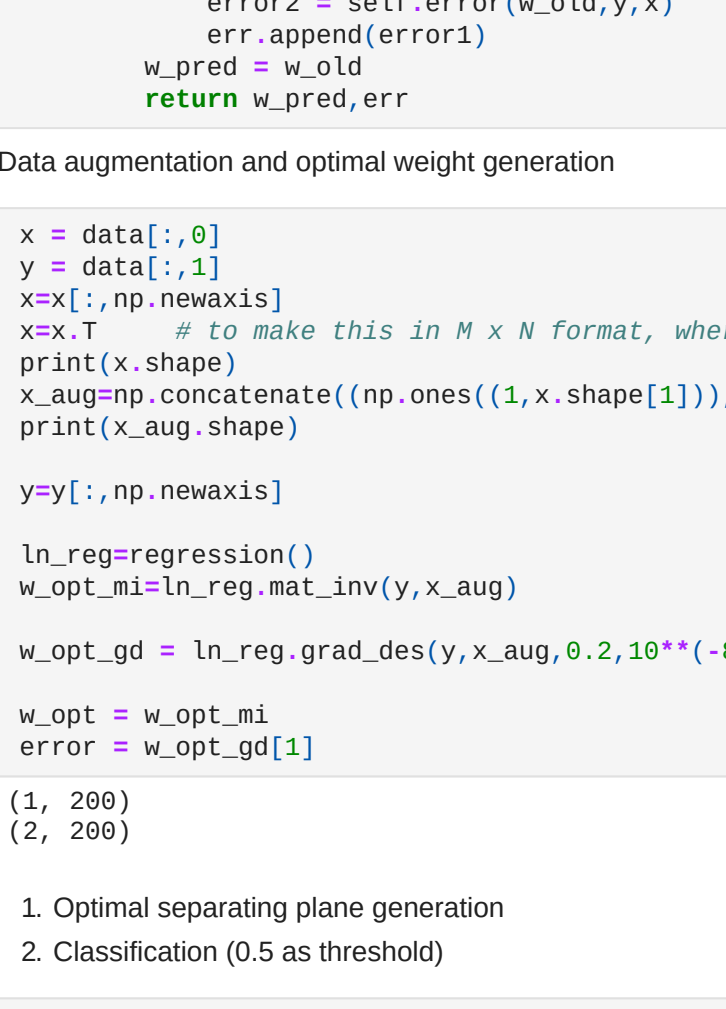
#generating class 0
numPoints = 100
values = np.linspace(0,0.6,numPoints)
dataClass = np.zeros(numPoints)
data = np.vstack((values,dataClass))
data = data.T

#generating class 1
numPoints = 100
values = np.linspace(0.8,1.3,numPoints)
dataClass = np.ones(numPoints)
data1 = np.vstack((values,dataClass))
data1 = data1.T

#merging data
data = np.vstack((data,data1))

#plotting
print(np.shape(data[:,0]))
plt.plot(data[:,0],data[:,1],'.')
(200,)
```

Out[171].



Defining linear regression class

```
In [172]. # Linear regression class
class regression:
    # constructor
    def __init__(self, name='reg'):
        self.name = name # Create an instance variable
    # def f(x)
    # return 1/x
    def grad_update(self,w_old,lr,y,x):
        # write your code here
        w = w_old + (2*lr)*(x*(y-(x.T@w_old)))/(y.shape[0])
        return w
    def error(self,w,y,x):
        return np.sum(np.square(y - (x.T@w)))/(y.shape[0]) # write your code here
    def mat_inv(self,y,x,x_aug):
        return np.linalg.pinv(x_aug@x_aug.T)@(x_aug@y) # write your code here
    # by Gradient descent
    def grad_des(self,y,x,lr,eps=0.000001):
        # write your code here
        w_old = np.random.rand(x.shape[0],1)
        error1 = 100001.
        error2 = 100000.
        err = []
        while (error1 - error2)>eps:
            error1 = self.error(w_old,y,x)
            w_old = self.grad_update(w_old,lr,y,x)
            error2 = self.error(w_old,y,x)
            err.append(error1)
            w_pred = w_old
            return w_pred,err

Data augmentation and optimal weight generation
```

In [173].

```
x = data[:,0]
y = data[:,1]
x=x[:,np.newaxis]
print(x.shape)
x_aug=np.concatenate((np.ones((1,x.shape[1])), x),axis=0)
print(x_aug.shape)
y=y[:,np.newaxis]

ln_reg=regression()
w_opt_m1=ln_reg.mat_inv(y,x_aug)

w_opt_gd = ln_reg.grad_des(y,x_aug,0.2,10**(-8))

w_opt = w_opt_m1
error = w_opt_gd[1]

(1, 200)
(2, 200)
```

1. Optimal separating plane generation  
2. Classification (0.5 as threshold)

In [174].

```
print(w_opt)
lr=0.01

x_axis = range(len(error))
plt.plot(x_axis,error)
plt.title("Error in gradient descent")
plt.xlabel("Iterations")
plt.ylabel("Error")
plt.show()

x_plot = np.linspace(0,1.3,1000)
x_plot=x_plot[:,np.newaxis]
x_plot=x_plot.T # to make this in M x N format, where M is the dimension
x_augplot=np.concatenate((np.ones((1,x_plot.shape[1])), x_plot),axis=0)

y_plot = w_opt.T@x_augplot
print(y_plot.shape)
print(x_aug.shape)
print(x.shape)
plt.plot(x_plot.T,y_plot.T,'g')
# insert your code here

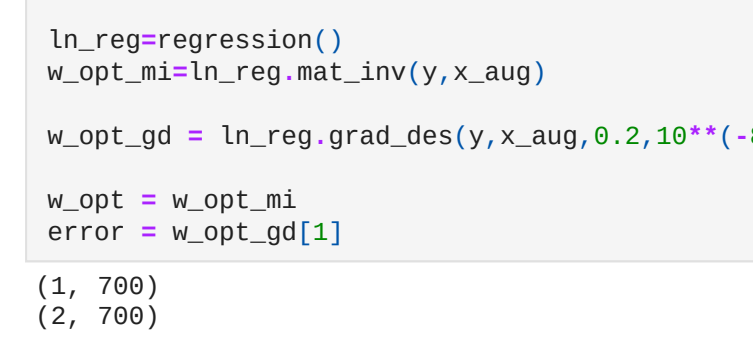
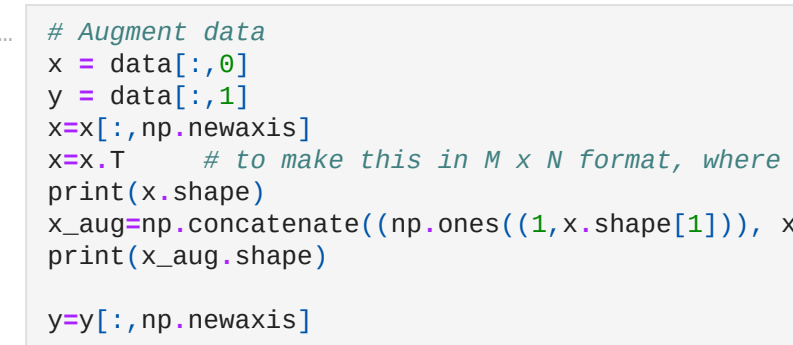
th = 0.5
x_th = (th - w_opt[0])/w_opt[1]
print(x_th)

class1 = []
class2 = []

for point in x.T:
    if(point< x_th):
        class1.append(point)
    else:
        class2.append(point)

class1 = np.array(class1)
class2 = np.array(class2)
plt.plot(data[:,0],data[:,1],'.')
plt.plot(class1,np.zeros(len(class1)),'.r.')
plt.plot(class2,np.ones(len(class2)),'.y.')
plt.show()
```

[[ -0.25989351  
 1.32753531]]



## Draw back of linear regression based classification

1. Generate data (have outliers noise)
2. Find the fitting line.
3. Using 0.5 as threshold, see the classification
4. using matrix inversion (home work)

In [175].

```
import numpy as np
import matplotlib.pyplot as plt

# Insert your code here

#generating class 0
numPoints = 300
values = np.linspace(0,0.6,numPoints)
dataClass = np.zeros(numPoints)
data = np.vstack((values,dataClass))
data = data.T

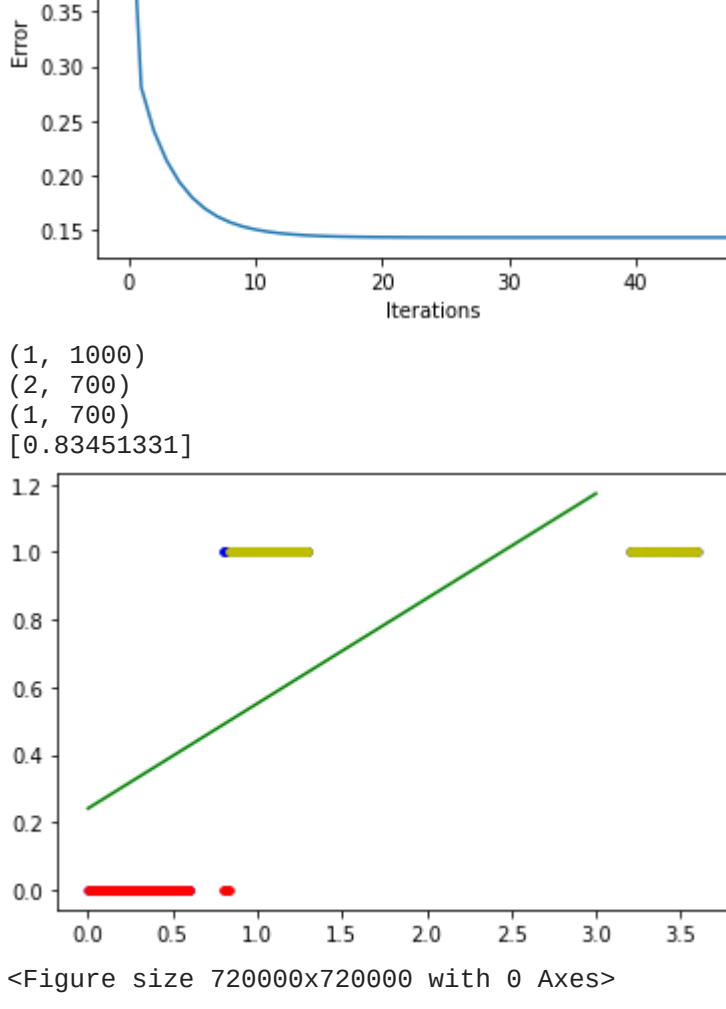
#generating class 1
numPoints = 300
values = np.linspace(0.8,1.3,numPoints)
dataClass = np.ones(numPoints)
data1 = np.vstack((values,dataClass))
data1 = data1.T

numPoints = 100
values = np.linspace(3.2,3.6,numPoints)
dataClass = np.ones(numPoints)
data_temp = np.vstack((values,dataClass))
data_temp = data_temp.T
data1 = np.vstack((data1,data_temp))

#merging data
data = np.vstack((data,data1))

#plotting
print(np.shape(data[:,0]))
plt.plot(data[:,0],data[:,1],'.')
(700,)
```

Out[175].



Augment data

In [176].

```
# Augment data
x = data[:,0]
y = data[:,1]
x=x[:,np.newaxis]
x=x.T # to make this in M x N format, where M is the dimension
print(x.shape)
x_aug=np.concatenate((np.ones((1,x.shape[1])), x),axis=0)
print(x_aug.shape)
y=y[:,np.newaxis]

ln_reg=regression()
w_opt_m1=ln_reg.mat_inv(y,x_aug)

w_opt_gd = ln_reg.grad_des(y,x_aug,0.2,10**(-8))

w_opt = w_opt_m1
errors = w_opt_gd[1]

(1, 700)
(2, 700)
```

1. find optimal weight  
2. perform classification (0.5 as threshold)

In [177].

```
print("Matrix inversion",w_opt)
print("Gradient decent",w_opt_gd[0])
lr=0.01

x_axis = range(len(error))
plt.plot(x_axis,error)
plt.title("Error in gradient descent")
plt.xlabel("Iterations")
plt.ylabel("Error")
plt.show()

x_plot = np.linspace(0,3,1000)
x_plot=x_plot[:,np.newaxis]
x_plot=x_plot.T # to make this in M x N format, where M is the dimension
x_augplot=np.concatenate((np.ones((1,x_plot.shape[1])), x_plot),axis=0)

y_plot = w_opt.T@x_augplot
print(y_plot.shape)
print(x_aug.shape)
print(x.shape)
plt.plot(x_plot.T,y_plot.T,'g')
# insert your code here

th = 0.5
x_th = (th - w_opt[0])/w_opt[1]
print(x_th)

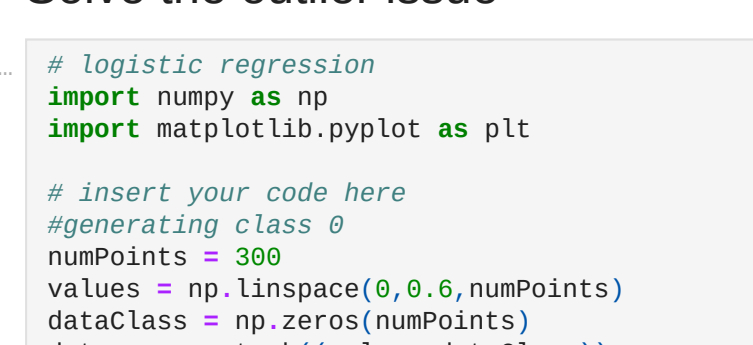
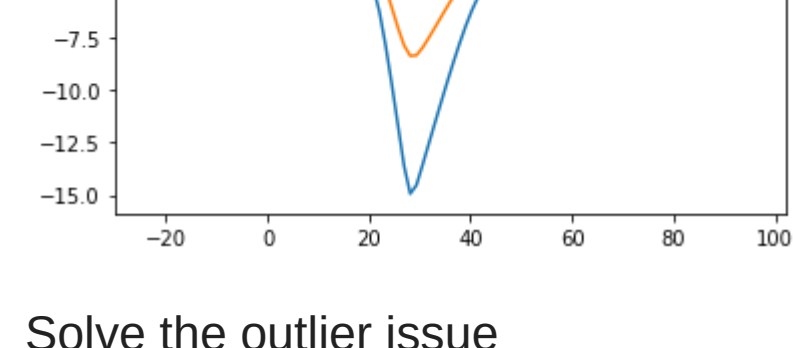
class1 = []
class2 = []

for point in x.T:
    if(point< x_th):
        class1.append(point)
    else:
        class2.append(point)

class1 = np.array(class1)
class2 = np.array(class2)

plt.plot(data[:,0],data[:,1],'.')
plt.plot(class1,np.zeros(len(class1)),'.r.')
plt.plot(class2,np.ones(len(class2)),'.y.')
plt.figure(figsize=(1000,1000))
plt.show()
```

Matrix inversion [[0.24857767  
0.31886662]]  
Gradient decent [[0.24079655  
0.31874156]]



## logistic regression

1. Error surface (logistic loss vs. MSE)
2. Solve the outlier issue
3. Circularly separable data classification
4. Multiclass classification

## Error surface (logistic loss vs. MSE)

In [178].

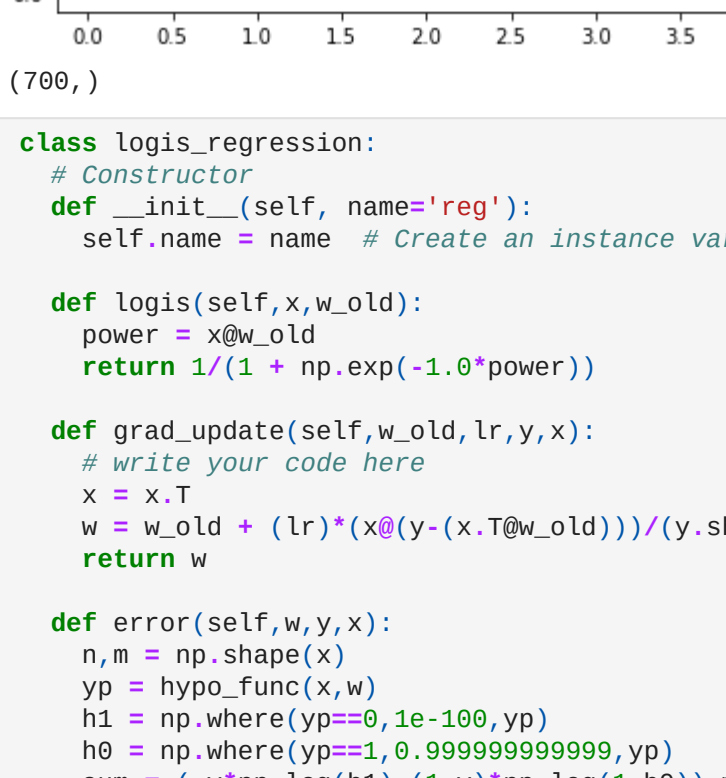
```
import numpy as np
import matplotlib.pyplot as plt

x=np.linspace(-5,5,25)
y=np.zeros(x.shape)
y[np.where(x>0.7314)]=1

plt.plot(x,y,'.r')
print(np.shape(x))
print(np.shape(y))

m = len(x)
ones = np.ones((m,2))
ones[:,1:] = np.array([x]).T
x_aug = ones
print(np.shape(x_aug))

(25,)
(25, 2)
```



1.  $MSE = \frac{1}{2} \sum_{i=1}^N (y_i - \hat{y}_i)^2$  where  $\hat{y}_i = \frac{1}{1 + e^{-w^T x_i}}$
2. Logistic loss =  $-\frac{1}{N} \sum_{i=1}^N [y_i \log(\hat{y}_i) + (1 - y_i) \log(1 - \hat{y}_i)]$

In [129].

```
import math
# search space (only w1 is searched, where w0 is fixed)
w1_in=np.linspace(0,1,x[0])
w0=-w1_in*0.7314
w1=np.linspace(-w1_in,4*w1_in,100)

def hypo_func(x,w):
    power = x@w
    np.shape(power)
    return 1/(1 + np.exp(-1.0*power))

def mse(y,x,w):
    m = np.shape(x)
    diff = hypo_func(x,w)-y
    sq = np.square(diff)
    sum = np.sum(sq)
    return sum/(2*m)

def logisticLoss(y,x,w):
    n,m = np.shape(x)
    yp = hypo_func(x,w)
    h1 = np.where(yp==0,1e-100,yp)
    h0 = np.where(yp==1,0.999999999999,yp)
    sum = (-y*np.log(h1)-(1-y)*np.log(1-h0)).mean()
    return sum

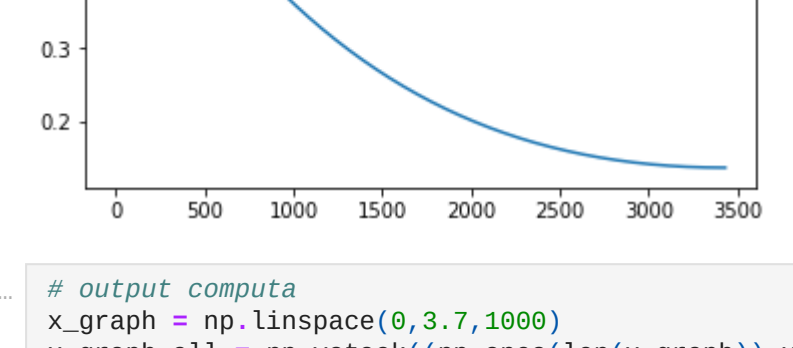
X = x_aug
Y = np.array([y])
Y = Y.T

cost_fn_mse=[]
for i in range(w1.shape[0]):
    w = np.array([w0,w1[i]])
    cost_mse = mse(Y,X,w)
    cost_fn_mse.append(cost_mse)

# Cost function using log
cost_fn_logis=logisticLoss(Y,X,w)
cost_fn_logis.append(cost_logis)
```

In [130].

```
# plotting of error surface
plt.figure()
plt.plot(w1,np.log(cost_fn_mse))
plt.plot(w1,np.log(cost_fn_logis))
plt.show()
```



## Solve the outlier issue

In [131].

```
# logistic regression
import numpy as np
import matplotlib.pyplot as plt

# Insert your code here

#generating class 0
numPoints = 300
values = np.linspace(0,0.6,numPoints)
dataClass = np.zeros(numPoints)
data = np.vstack((values,dataClass))
data = data.T

#generating class 1
numPoints = 300
values = np.linspace(0.8,1.3,numPoints)
dataClass = np.ones(numPoints)
data1 = np.vstack((values,dataClass))
data1 = data1.T

numPoints = 100
values = np.linspace(3.2,3.6,numPoints)
dataClass = np.ones(numPoints)
data_temp = np.vstack((values,dataClass))
data_temp = data_temp.T
data1 = np.vstack((data1,data_temp))

#merging data
data = np.vstack((data,data1))

x= data[:,0]
y= data[:,1]

plt.figure()
plt.plot(x,y,'.r')
print(np.shape(x))
print(np.shape(y))

(700,)
(700, 2)
(700, 1)
```

In [132].

```
class logis_regression:
    # constructor
    def __init__(self, name='reg'):
        self.name = name # Create an instance variable
    # def logis(self,w_old):
    # power = x@w
    # np.shape(power)
    # return 1/(1 + np.exp(-1.0*power))
    def grad_update(self,w_old,lr,y,x):
        # write your code here
        w = w_old + (lr)*(x*(y-(x.T@w_old)))/(y.shape[0])
        return w
    def error(self,w,y,x):
        m = np.shape(x)
        yp = hypo_func(x,w)
        h1 = np.where(yp==0,1e-100,yp)
        h0 = np.where(yp==1,0.999999999999,yp)
        sum = (-y*np.log(h1)-(1-y)*np.log(1-h0)).mean()
        return sum
    # by Gradient descent
    def Regression_grad_des(self,x,y,w_in,lr,eps = 1e-20):
        w_old = w_in
        print("Inside function",w_old)
        error1 = self.error(w_old,y,x)
        err=[]
        err.append(error1)
        i = 1
        while (1):
            w_old = self.grad_update(w_old,lr,y,x)
            error1 = self.error(w_old,y,x)
            err.append(error1)
            if ((err[i-1]-err[i])<eps):
                i=i+1
            if (i>10000 == 0):
                print("In progress...",i)
                w_pred=w_old
                print("Inside fun",w_pred.shape)
                return w_pred,err
```

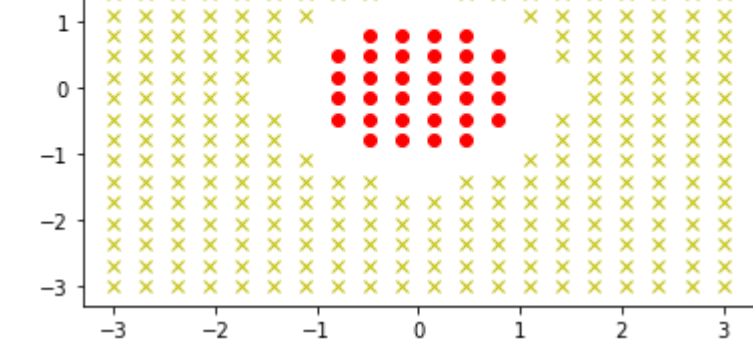
In [133].

```
# augmentation and data forming
x = data[:,0]
y = data[:,1]
y=y[:,np.newaxis]
print(x.shape)
x_aug=np.vstack((np.ones(x.shape[0]),x))
print(x_aug.shape)
print(y.shape)
(700,)
(700, 2)
(700, 1)
```

In [134].

```
log_reg=logis_regression()
eps = 10**(-20)
w_in = np.array([[-2],[3],[3],[0]])
w1=np.vstack(log_reg.Registration_grad_des(x_aug,y,w_in,0.0001,eps))
print(w_pred1)
print(len(err_list))
plt.plot(err)
```

Inside function [[-2]  
[3]  
[3]  
[0]]  
Inside fun (4, 1)



Plot Classification using 0.5 as threshold

In [142].

```
y_pred_circ=log_reg.circ_logis(x_aug_circ,w_pred_circ)
print(y_pred_circ.shape)
# insert your code here
ind1 = np.where(y_pred_circ[:,0]==0.5)
ind2 = np.where(y_pred_circ[:,0]<0.5)
class1 = np.array(ind1)
class2 = np.array(ind2)
x1=x_aug_circ[class1,:]
x2=x_aug_circ[class2,:]
print(x1.shape)
print(x2.shape)
print(x1.shape)
print(x2.shape)
print(x1.shape)
plt.figure()
plt.plot(x1[:,0],x1[:,1],'.r',color='y')
plt.plot(x2[:,0],x2[:,1],'.r',color='r')
plt.show()

(364, 1)
(364, 1)
(364, 2)
(364, 2)
(364, 2)
(364, 2)
```



As in case of circularly separated data, the boundary is nonlinear, so squared feature is taken.

In [139].

```
# perform logistic regression
y1=np.zeros((inner.shape[0]))
y2=np.ones((outer.shape[0]))
y_circ=np.concatenate((y1,y2))
y_circ = y_circ[:,np.newaxis]
print(y.shape)
all_x = circData[:,0]
all_y = circData[:,1]
sqx = np.square(all_x)
sqy = np.square(all_y)
XY = np.multiply(all_x,all_y)
print(sqx.shape)
print(sqy.shape)
print(XY.shape)
print(ones.shape)
x_aug_circ=np.vstack((ones,sqx,sqy,XY))
x_aug_circ = x_aug_circ.T
print(x_aug_circ.shape)

(700, 1)
(364, 0)
(364, 1)
(364, 2)
(364, 4)
```

In [140].

```
log_reg_circ = logis_regression()
w_in = np.array([[-1],[3],[3],[0]])
eps = 1e-20
lr = 0.00001
w_pred_circ,err_circ=log_reg_circ.Registration_grad_des(x_aug_circ,y_circ,w_in,lr,eps)
plt.plot(err_circ)
plt.show()

Inside function [[-1]  
[3]  
[3]  
[0]]  
Inside fun (4, 1)
```



Plot Classification using 0.5 as threshold

In [142].

```
y_pred_circ=log_reg_circ.logis(x_aug_circ,w_pred_circ)
print(y_pred_circ.shape)
# insert your code here
ind1 = np.where(y_pred_circ[:,0]==0.5)
ind2 = np.where(y_pred_circ[:,0]<0.5)
class1 = np.array(ind1)
class2 = np.array(ind2)
x1=x_aug_circ[class1,:]
x2=x_aug_circ[class2,:]
print(x1.shape)
print(x2.shape)
print(x1.shape)
plt.figure()
plt.plot(x1[:,0],x1[:,1],'.r',color='y')
plt.plot(x2[:,0],x2[:,1],'.r',color='r')
plt.show()

(364, 1)
(364, 1)
(364, 2)
(364, 2)
(364, 2)
(364, 2)
```



## Multiclass logistic regression

1. Generate 1D data with 3 classes

## One vs rest classification

1. lets take polynomial of order 2 (by seeing the data distribution)

In [143].

```
import numpy as np
import matplotlib.pyplot as plt

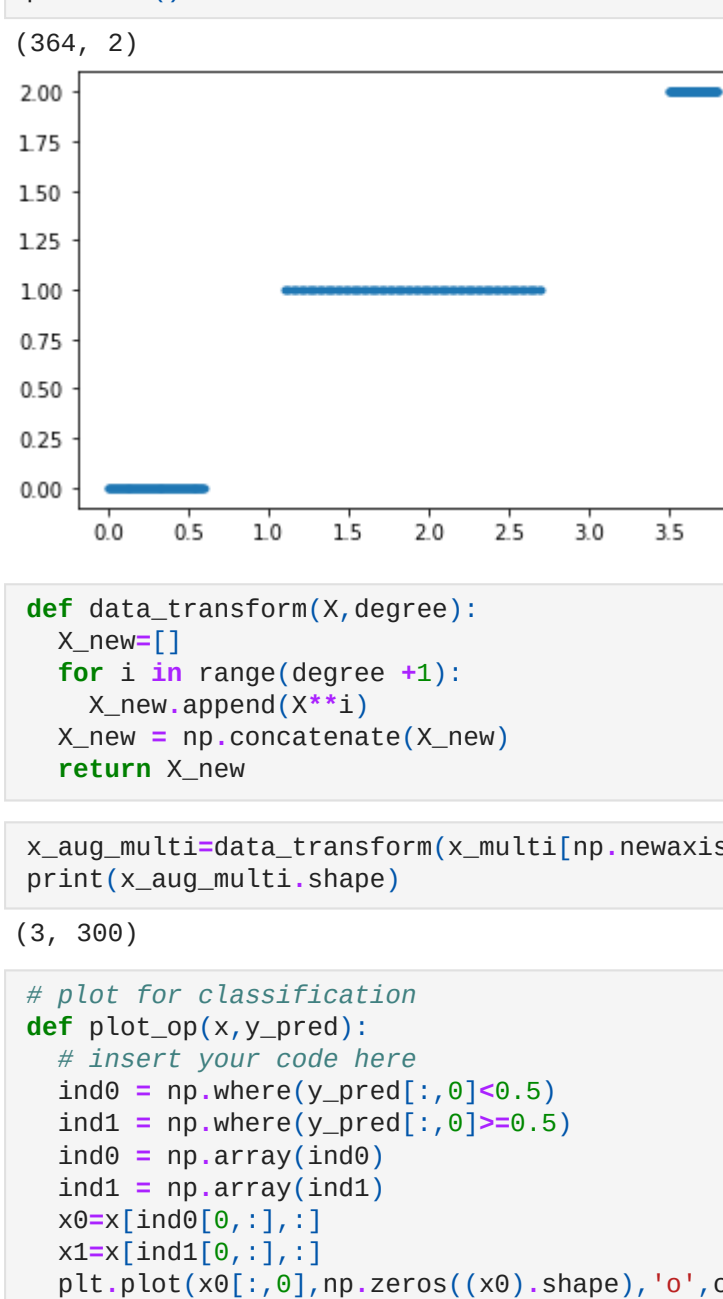
x1=np.linspace(0,0.6,100)
x2=np.linspace(1,1.2,7,100)
x3=np.linspace(3,3.5,8,100)

x_multi=np.concatenate((x1,x2,x3))
print(x.shape)
```



```
y=np.zeros(x1.shape)
y2=np.ones(x2.shape)
y3=np.tile([2,3],x3.shape)

y_multi=np.concatenate((y1,y2,y3))
```



```
In [144.]: def data_transform(X,degree):
X_new=[]
for i in range(degree +1):
X_new.append(X**i)
X_new = np.concatenate(X_new)
return X_new
```

```
In [145.]: x_aug_multi=data_transform(x_multi[np.newaxis,:],2)
print(x_aug_multi.shape)

(3, 360)
```

```
In [146.]: # plot for classification
def plot_op(x,y,pred):
# insert your code here
ind0 = np.where(y_pred[:,0]<=0.5)
ind1 = np.where(y_pred[:,0]>=0.5)
ind0 = np.array(ind0)
ind1 = np.array(ind1)
x0=x[ind0[:,1:]]
x1=x[ind1[:,1:]]
plt.plot(x0[:,0],np.zeros(x0.shape),'o',color='y')
plt.plot(x1[:,0],np.ones(x1.shape),'x',color='r')

In [147.]: #Working on class1
# insert your code here
log_reg_multi = logis_regression()

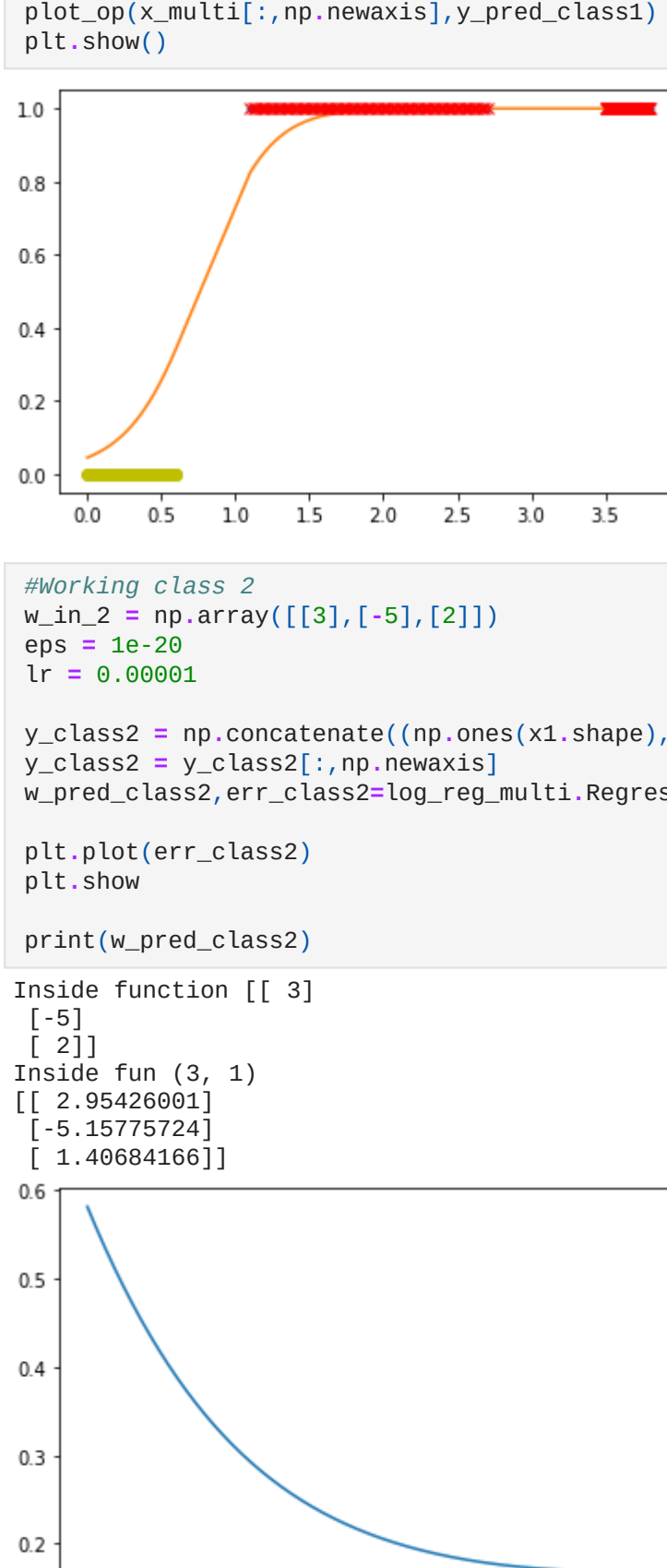
w_in_1 = np.array([[ -3],[4],[1]])
eps = 1e-20
lr = 0.00001

y_class1 = np.concatenate((np.zeros(x1.shape),np.ones(x2.shape),np.ones(x3.shape)))
y_class1 = y_class1[:,np.newaxis]
w_pred_class1=log_reg_multi.Regression_grad_des(x_aug_multi.T,y_class1,w_in_1,lr,eps)

plt.plot(err_class1)
plt.show

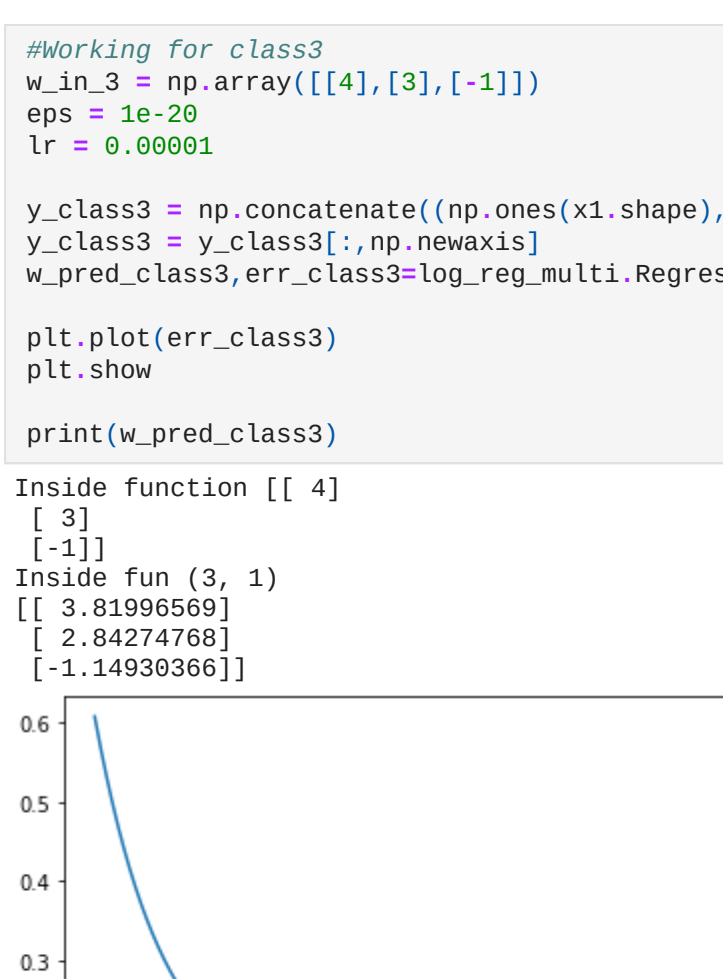
print(w_pred_class1)

Inside function [[-3]
[4]
[1]]
Inside fun (3, 1)
[[-3.85492455]
[ 3.80932087]
[ 0.34159628]]
```



```
In [148.]: # plotting for class1
plt.figure()
plt.plot(x_multi,y_multi[:,0],'.')

y_pred_class1=log_reg_multi.logis(x_aug_multi.T,w_pred_class1)
plt.plot(x_multi,y_pred_class1)
plot_op(x_multi[:,np.newaxis],y_pred_class1)
plt.show()
```



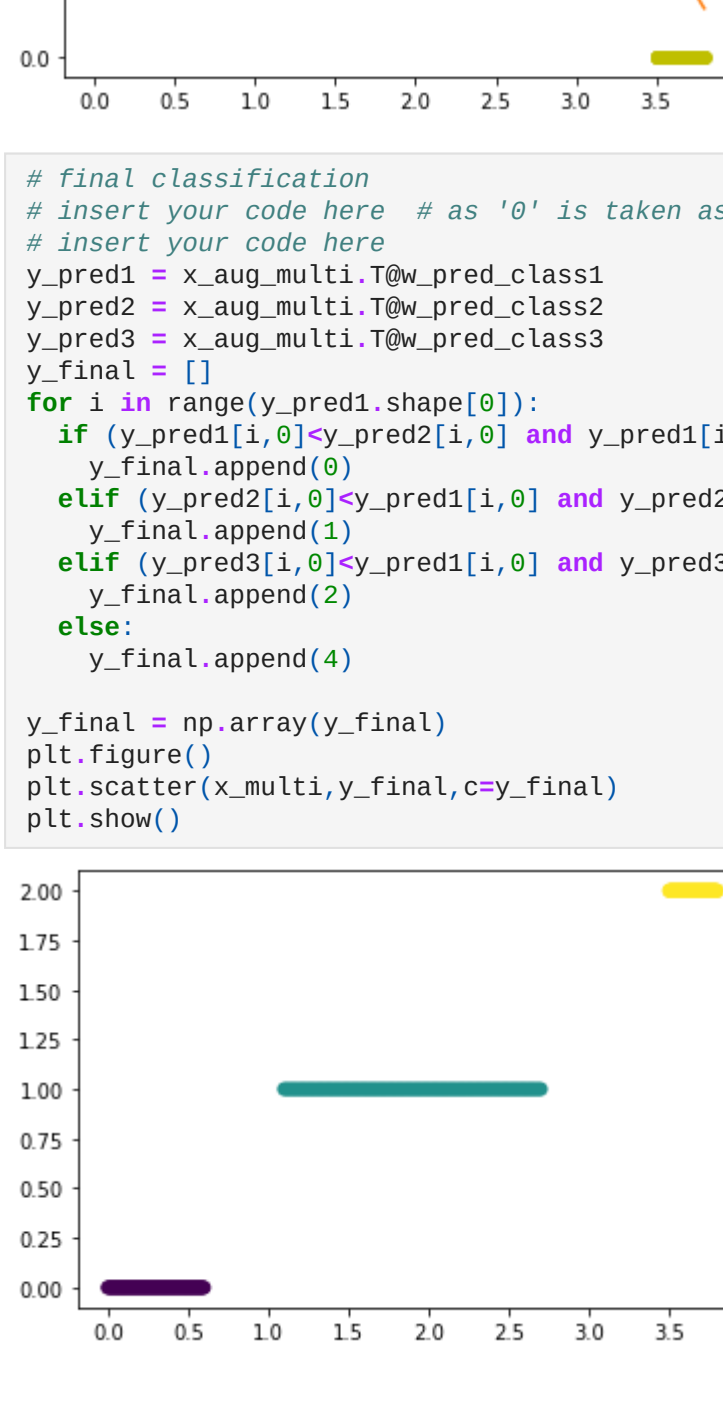
```
In [149.]: #Working class 2
w_in_2 = np.array([[1],[3],[ -5],[2]])
eps = 1e-20
lr = 0.00001

y_class2 = np.concatenate((np.ones(x1.shape),np.zeros(x2.shape),np.zeros(x3.shape)))
y_class2 = y_class2[:,np.newaxis]
w_pred_class2=log_reg_multi.Regression_grad_des(x_aug_multi.T,y_class2,w_in_2,lr,eps)

plt.plot(err_class2)
plt.show

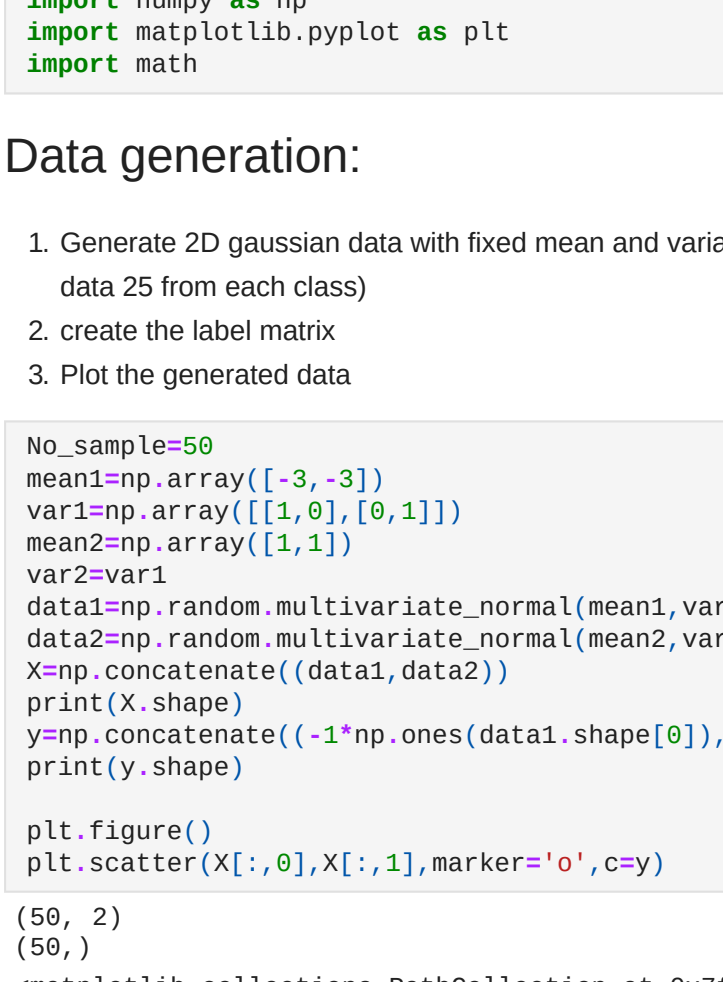
print(w_pred_class2)

Inside function [[ 3]
[ -5]
[ 2]]
Inside fun (3, 1)
[[-3.95420951]
[ -5.15775724]
[ 1.40684166]]
```



```
In [150.]: # plotting class 2
plt.figure()
plt.plot(x_multi,y_class2[:,0],'.')

y_pred_class2=log_reg_multi.logis(x_aug_multi.T,w_pred_class2)
plt.plot(x_multi,y_pred_class2)
plot_op(x_multi[:,np.newaxis],y_pred_class2)
plt.show()
```



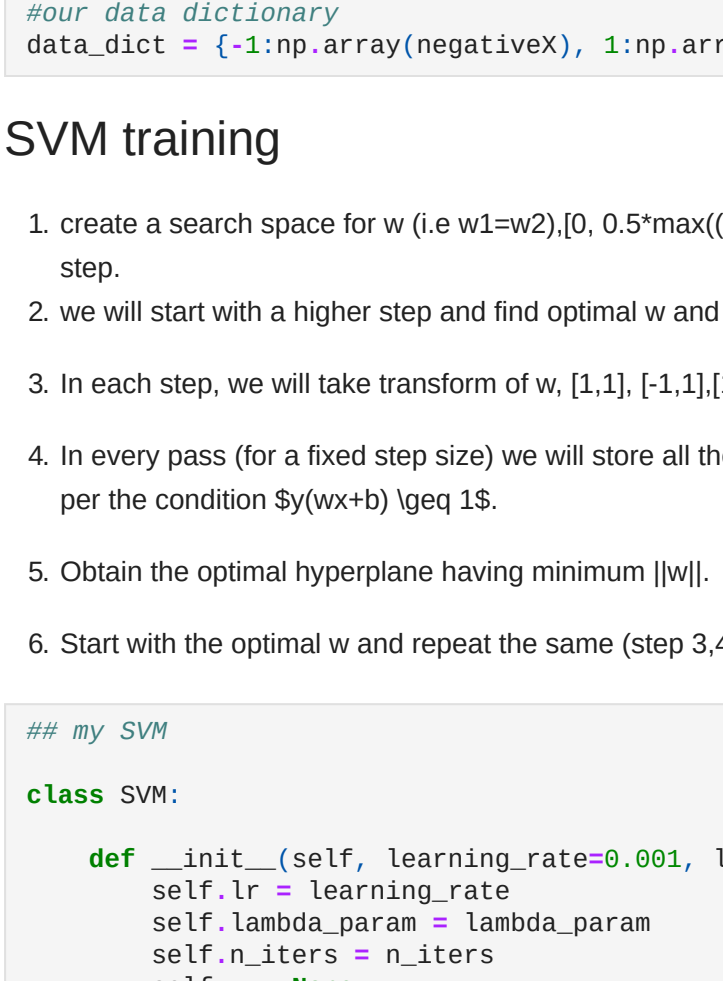
```
In [151.]: #Working for class3
w_in_3 = np.array([[1],[4],[3],[ -1]])
eps = 1e-20
lr = 0.00001

y_class3 = np.concatenate((np.ones(x1.shape),np.ones(x2.shape),np.zeros(x3.shape)))
y_class3 = y_class3[:,np.newaxis]
w_pred_class3=log_reg_multi.Regression_grad_des(x_aug_multi.T,y_class3,w_in_3,lr,eps)

plt.plot(err_class3)
plt.show

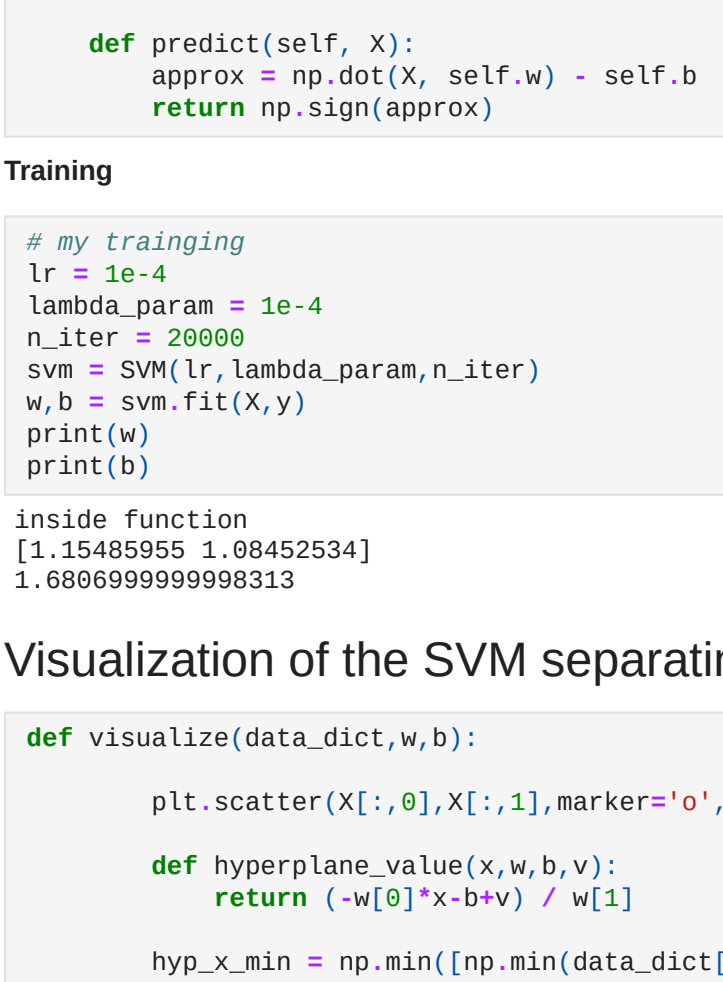
print(w_pred_class3)

Inside function [[ 4]
[ 3]
[ -1]]
Inside fun (3, 1)
[[-3.8996569]
[ 2.84274768]
[ -1.14938366]]
```



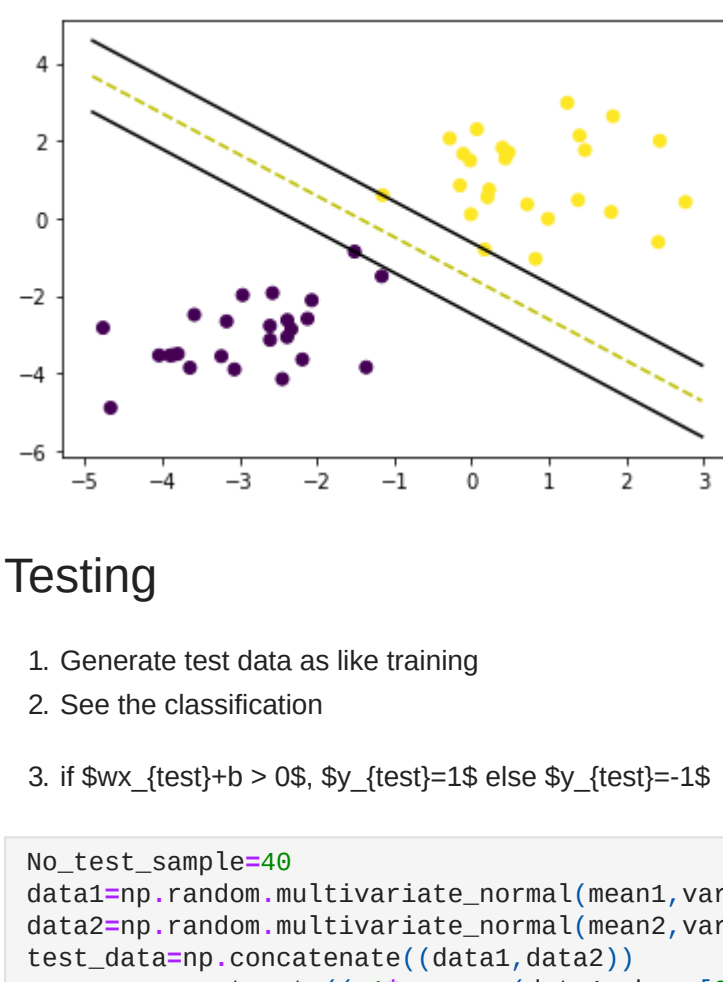
```
In [152.]: #Plotting class3
plt.figure()
plt.plot(x_multi,y_class3[:,0],'.')

y_pred_class3=log_reg_multi.logis(x_aug_multi.T,w_pred_class3)
plt.plot(x_multi,y_pred_class3)
plot_op(x_multi[:,np.newaxis],y_pred_class3)
plt.show()
```



```
In [153.]: # final classification
# insert your code here # as '0' is taken as reference
# insert your code here
y_pred1 = x_aug_multi.T@w_pred_class1
y_pred2 = x_aug_multi.T@w_pred_class2
y_pred3 = x_aug_multi.T@w_pred_class3
y_final = []
for i in range(y_pred1.shape[0]):
if (y_pred1[i,0]<y_pred2[i,0] and y_pred1[i,0]<y_pred3[i,0]):
y_final.append(0)
elif (y_pred2[i,0]<y_pred1[i,0] and y_pred2[i,0]<y_pred3[i,0]):
y_final.append(1)
elif (y_pred3[i,0]<y_pred1[i,0] and y_pred3[i,0]<y_pred2[i,0]):
y_final.append(2)
else:
y_final.append(4)

y_final = np.array(y_final)
plt.figure()
plt.scatter(x_multi,y_final,c=y_final)
plt.show()
```



## Support vector machine

1. Try to maximize the margin of separation between data.
2. Instead of learning  $wx+b=0$  separating hyperplane directly (like logistic regression), SVM try to learn  $wx+b=0$ , such that, the margin between two hyperplanes  $wx+b=1$  and  $wx+b=-1$  (also known as support vectors) is maximum.
3. Margin between  $wx+b=1$  and  $wx+b=-1$  hyperplane is  $\frac{2}{\|w\|}$
4. We have a constraint optimization problem of maximizing  $\frac{2}{\|w\|}$  with constraints  $wx+b \geq 1$  (for +ve class) and  $wx+b \leq -1$  (for -ve class).
5. As  $\frac{2}{\|w\|} = \frac{1}{\|w\|}$  for +ve class and  $\frac{2}{\|w\|} = -\frac{1}{\|w\|}$  for -ve class, the constraint can be re-written as:  $\|w\| \leq 1$  for +ve class and  $\|w\| \geq 1$  for -ve class.
6. Final optimization is (i.e to find  $w$  and  $b$ ):  $\min_{w,b} \frac{1}{\|w\|} \text{ s.t. } \|w\| \leq 1, \|w\| \geq 1, \forall x \in \{x_1, \dots, x_n\}$

Acknowledgement:

<https://pythonprogramming.net/predictions-svm-machine-learning-tutorial/>

<https://medium.com/deep-math-machine-learning-ai/chapter-3-1-svm-from-scratch-in-python-8693f853dc>

```
In [154.]: import numpy as np
import matplotlib.pyplot as plt
import math
```

## Data generation:

1. Generate 2D gaussian data with fixed mean and variance for 2 class.(var=identity, class1: mean=[-4,-4], class2: mean=[1,1], No. of data 25 from each class)
2. create the label matrix
3. Plot the generated data

```
In [155.]: No_sample=50
mean1=np.array([-3,-3])
var1=np.array([[1,0],[0,1]])
mean2=np.array([1,1])
var2=np.array([[1,0],[0,1]])
data1=np.random.multivariate_normal(mean1,var1,int(No_sample/2))
data2=np.random.multivariate_normal(mean2,var2,int(No_sample/2))
X=np.concatenate((data1,data2))
print(X.shape)
y=np.concatenate((-1*np.ones(data1.shape[0]),np.ones(data2.shape[0])))
print(y.shape)

plt.figure()
plt.scatter(X[:,0],X[:,1],marker='o',c=y)
```

```
Out[155.]: <matplotlib.collections.PathCollection at 0x7f3d7169c3c8>
```



Create a data dictionary, which contains both label and data points.

```
In [156.]: positive=[]
negative=[]
for i in enumerate(y):
if y[i]==1:
negative.append(X[i])
else:
positive.append(X[i])

# data dictionary
data_dict = {-1*np.array(negativeX), 1*np.array(positiveX)}
```

## SVM training

1. create a search space for  $w$  (i.e  $w_1=w_2=0$ ,  $0.5 \cdot \max(|\text{abs}(\text{feat})|)$ ) and for  $b$ ,  $[-\max(|\text{abs}(\text{feat})|), \max(|\text{abs}(\text{feat})|)]$ , with appropriate step.
2. We will start with a higher step and find optimal  $w$  and  $b$ , then we will reduce the step and again re-evaluate the optimal one.
3. In each step, we will take transform of  $w$ ,  $[1,1]$ ,  $[-1,1]$  and  $[-1,-1]$  to search around the  $w$ .
4. In every pass (for a fixed step size) we will store all the  $w$ ,  $b$  and its corresponding  $\|w\|$ , which make the data correctly classified as per the condition  $\|w\| \leq 1$ .
5. Obtain the optimal hyperplane having minimum  $\|w\|$ .
6. Start with the optimal  $w$  and repeat the same (step 3.4 and 5) for a reduced step size.

```
In [157.]: ## my SVM

class SVM:
def __init__(self, learning_rate=0.001, lambda_param=0.01, n_iters=1000):
self.lr = learning_rate
self.lambda_param = lambda_param
self.n_iters = n_iters
self.w = None
self.b = None

def fit(self, X, y):
n_samples, n_features = X.shape

self.w = np.zeros(n_features)
self.b = 0
print('inside function')
for i in range(self.n_iters):
for idx, x_i in enumerate(X):
condition = y[idx] * (np.dot(x_i, self.w) - self.b) >= 1
if condition:
self.w = self.lr * (2 * self.lambda_param * self.w)
else:
self.w = self.lr * (2 * self.lambda_param * self.w - np.dot(x_i, y[idx]))
self.b = self.lr * y[idx]
return self.w, self.b

def predict(self, X):
approx = np.dot(X, self.w) - self.b
return np.sign(approx)
```

## Training

```
In [168.]: # my training
lr = 1e-4
lambda_param = 1e-4
n_iter = 20000
svm = SVM(lr,lambda_param,n_iter)
w,b = svm.fit(X,y)
print(w)
print(b)

inside function
[1.15488955 1.08452534]
1.6809999999998313
```

## Visualization of the SVM separating hyperplanes (after training)

```
In [162.]: def visualize(data_dict,w,b):

plt.scatter(X[:,0],X[:,1],marker='o',c=y)

def hyperplane_value(x,w,b,v):
return (-w[0]*x-b+v) / w[1]

hyp_x_min = np.min([np.min(data_dict[1]), np.min(data_dict[-1])])
hyp_x_max = np.max([np.max(data_dict[1]), np.max(data_dict[-1])])

# (w.x+b) = 1
# positive support vector hyperplane
psv1 = hyperplane_value(hyp_x_min, w, b, 1)
psv2 = hyperplane_value(hyp_x_max, w, b, 1)
plt.plot([hyp_x_min,hyp_x_max],[psv1,psv2], 'k')

# (w.x+b) = -1
# negative support vector hyperplane
nsv1 = hyperplane_value(hyp_x_min, w, b, -1)
nsv2 = hyperplane_value(hyp_x_max, w, b, -1)
plt.plot([hyp_x_min,hyp_x_max],[nsv1,nsv2], 'k')

# (w.x+b) = 0
# positive support vector hyperplane
db1 = hyperplane_value(hyp_x_min, w, b, 0)
db2 = hyperplane_value(hyp_x_max, w, b, 0)
plt.plot([hyp_x_min,hyp_x_max],[db1,db2], 'y--')
```



## Testing

1. Generate test data as like training
2. See the classification
3. If  $\|w_{\text{test}}\| > 0.5$ ,  $\|y_{\text{test}}\| = 1$  else  $\|y_{\text{test}}\| = -1$

```
In [168.]: No_test_sample=40
data1=np.random.multivariate_normal(mean1,var1,int(No_test_sample/2))
data2=np.random.multivariate_normal(mean2,var2,int(No_test_sample/2))
test_data=np.concatenate((data1,data2))
y_gr=np.concatenate((-1*np.ones(data1.shape[0]),np.ones(data2.shape[0])))

# evaluate with the trained model
y_pred=svm.predict(test_data)

sum=0
count=0
for yi,yp in zip(y_gr,y_pred):
count +=1
if(yi==yp):
sum += 1

accuracy=(sum/count)*100
print('test accuracy=',accuracy)

# Visualization
plt.figure()
visualize(data_dict,w,b)
plt.scatter(test_data[:,0],test_data[:,1],marker='x',c=y_gr)

test accuracy= 100.0
```

```
Out[168.]: <matplotlib.collections.PathCollection at 0x7f3d7147e788>
```

