

◆ Step-by-Step Working Process

1 System Power ON & Initialization

When the device is powered on, the Arduino begins by initializing all connected components such as:

- **RFID Module**
- **LCD Display**
- **Servo Motor**
- **Load Cell (HX711 Sensor)**
- **Buzzer/LED (Output Pin)**

The LCD turns ON and the servo is moved to a **closed position (160°)** so no rice is dispensed at the start.

2 Calibration of Load Cell (Weight Sensor)

The system runs the calibrate() function. During this process:

- The load cell takes **100 sample readings**.
- The average of these readings is stored as the **baseline (tare value)**.
- This ensures the weighing scale starts from **zero**.

The LCD displays "**Calibrating...**" and after completion shows "**Calibration OK**".

3 Waiting for RFID Card

Now the system asks the user to scan their RFID card:



The code continuously checks for the presence of a card.

4 RFID Authentication

Once a card is detected, the system:

- Reads the **UID (Unique ID)** from the RFID tag.

- Compares it with stored authorized UIDs.

✓ If the UID matches:

- LCD shows "**Access Granted**"
- LED/Buzzer blinks once

✗ If not authorized:

- LCD shows "**ACCESS DENIED**"
 - Alarm/Buzzer blinks multiple times
 - System restarts waiting for another RFID scan
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5 Detecting Rice Container

After successful authentication, the system waits for a container to be placed on the weighing platform (load cell).

 **LCD shows: "Place Container"**

The system checks weight continuously.

If the detected weight is greater than **3g**, it assumes a container is placed.

6 User Enters Required Weight

Once a container is detected:

 **LCD shows: "Enter Quantity:"**

The user now enters the desired rice amount (for example: 100, 250, 500g) through the **serial monitor**.

The entered weight is stored in variable **y**.

7 Rice Dispensing Process

The system now starts dispensing rice:

- The servo motor rotates to **90° (open)**.
- Rice starts falling into the container.
- Load cell continuously measures weight:

LCD shows two values:

Display Line Meaning

Current: X g Current rice weight

Target: Y g Weight user requested

8 Automatic Stop of Servo

Once the current weight **reaches or exceeds** the target value:

- The servo returns to **closed position (160°)**.
 - The buzzer/LED signals the user.
 - LCD shows "**Collect Rice**"
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9 System Reset

After dispensing is complete:

- The target weight resets to **0**
 - The system restarts from the **RFID scanning stage**
 - Ready for next user
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✓ Summary of the Process Flow

Step Action

- 1 System initializes
- 2 Load cell calibrates
- 3 User scans RFID card
- 4 Authentication check
- 5 System waits for container
- 6 User enters required quantity

Step Action

- 7 Servo dispenses rice
- 8 Automatically stops when target reached
- 9 System resets for next user