

## ◆ Step-by-Step Working Process

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### 1 System Power ON & Initialization

When the device is powered on, the Arduino begins by initializing all connected components such as:

- **RFID Module**
- **LCD Display**
- **Servo Motor**
- **Load Cell (HX711 Sensor)**
- **Buzzer/LED (Output Pin)**

The LCD turns ON and the servo is moved to a **closed position (160°)** so no rice is dispensed at the start.

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### 2 Calibration of Load Cell (Weight Sensor)

The system runs the `calibrate()` function. During this process:

- The load cell takes **100 sample readings**.
- The average of these readings is stored as the **baseline (tare value)**.
- This ensures the weighing scale starts from **zero**.

The LCD displays "**Calibrating...**" and after completion shows "**Calibration OK**".

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### 3 Waiting for RFID Card

Now the system asks the user to scan their RFID card:

📌 LCD displays: "**Scan RFID Card...**"

The code continuously checks for the presence of a card.

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### 4 RFID Authentication

Once a card is detected, the system:

- Reads the **UID (Unique ID)** from the RFID tag.

- Compares it with stored authorized UIDs.

✓ **If the UID matches:**

- LCD shows "**Access Granted**"
- LED/Buzzer blinks once

✗ **If not authorized:**

- LCD shows "**ACCESS DENIED**"
  - Alarm/Buzzer blinks multiple times
  - System restarts waiting for another RFID scan
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## **5 Detecting Rice Container**

After successful authentication, the system waits for a container to be placed on the weighing platform (load cell).

✚ LCD shows: "**Place Container**"

The system checks weight continuously.

If the detected weight is greater than **3g**, it assumes a container is placed.

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## **6 User Enters Required Weight**

Once a container is detected:

✚ LCD shows: "**Enter Quantity:**"

The user now enters the desired rice amount (for example: 100, 250, 500g) through the **serial monitor**.

The entered weight is stored in variable **y**.

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## **7 Rice Dispensing Process**

The system now starts dispensing rice:

- The servo motor rotates to **90° (open)**.
- Rice starts falling into the container.
- Load cell continuously measures weight:

LCD shows two values:

### Display Line Meaning

Current: X g    Current rice weight

Target: Y g    Weight user requested

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### Automatic Stop of Servo

Once the current weight **reaches or exceeds** the target value:

- The servo returns to **closed position (160°)**.
  - The buzzer/LED signals the user.
  - LCD shows "**Collect Rice**"
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### System Reset

After dispensing is complete:

- The target weight resets to **0**
  - The system restarts from the **RFID scanning stage**
  - Ready for next user
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### Summary of the Process Flow

#### Step Action

- 1    System initializes
- 2    Load cell calibrates
- 3    User scans RFID card
- 4    Authentication check
- 5    System waits for container
- 6    User enters required quantity

**Step Action**

- 7     Servo dispenses rice
- 8     Automatically stops when target reached
- 9     System resets for next user