The Heat Equation: Theory and Implementation

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Heat Equation: Mathematical Formulation

 The heat equation describes how temperature distribution changes over time:

$$\frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2}$$

- Where:
 - u(x, t) is temperature at position x and time t
 - ullet α is thermal diffusivity coefficient
- Physical Intuition:
 - Rate of change of temperature $\left(\frac{\partial u}{\partial t}\right)$ is proportional to the curvature $\left(\frac{\partial^2 u}{\partial x^2}\right)$
 - Heat flows from hot to cold regions
 - System tends toward thermal equilibrium

Finite Difference Approximation

We discretize space and time:

• Space: $x_i = i\Delta x$, where $i = 0, 1, ..., N_x$

• Time: $t_n = n\Delta t$, where $n = 0, 1, ..., N_t$

Approximate derivatives:

$$\frac{\partial u}{\partial t} \approx \frac{u_i^{n+1} - u_i^n}{\Delta t}$$
$$\frac{\partial^2 u}{\partial x^2} \approx \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta x)^2}$$

• Leads to explicit scheme:

$$u_i^{n+1} = u_i^n + \alpha \frac{\Delta t}{(\Delta x)^2} (u_{i+1}^n - 2u_i^n + u_{i-1}^n)$$

Numerical Implementation

Algorithm 1 Explicit Finite Difference Method for Heat Equation

- 1: **Initialize:** Domain length L, grid points N_x , time T2: Set $\Delta x = L/N_x$, α , $\Delta t \leq \frac{(\Delta x)^2}{2\alpha}$ 3: Create spatial grid: $x_i = i\Delta x$, $i = 0, \dots, N_x$
- 4: Set initial condition: $u_i^0 = f(x_i)$
- 5: Set boundary conditions: $u_0^n = u_{N_x}^n = 0$

6: **for**
$$n = 0$$
 to $N_t - 1$ **do**

7: **for**
$$i = 1$$
 to $N_x - 1$ **do**

8:
$$u_i^{n+1} = u_i^n + \alpha \frac{\Delta t}{(\Delta x)^2} (u_{i+1}^n - 2u_i^n + u_{i-1}^n)$$

- 9: **end for**
- 10: Update boundary conditions
- 11: **if** visualization step **then**
- 12: Plot current solution
- 13: end if
- 14: end for

Stability and Convergence

Stability Condition:

$$\Delta t \leq \frac{(\Delta x)^2}{2\alpha}$$

- This is known as the CFL (Courant-Friedrichs-Lewy) condition
- Key Implementation Considerations:
 - Choose Δt to satisfy stability condition
 - Handle boundary conditions consistently
 - Consider mesh refinement for accuracy
 - Monitor solution behavior for instabilities