References:

1. J. Zhang, J. Nezan and J. Cousin, "Implementation of Motion Estimation Based on Heterogeneous Parallel Computing System with OpenCL," 2012 IEEE 14th International Conference on High Performance Computing and Communication & 2012 IEEE 9th International Conference on Embedded Software and Systems, 2012, pp. 41-45, doi: 10.1109/HPCC.2012.16.
2. Ambrosch K., Humenberger M., Kubinger W., Steininger A. Hardware Implement of an SAD Based Stereo Vision Algorithm. Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition; Minneapolis, MN, USA. 17–22 June 2007; pp. 1–6.
3. Rostam Affendi Hamzah, Haidi Ibrahim, "Literature Survey on Stereo Vision Disparity Map Algorithms", Journal of Sensors, vol. 2016, Article ID 8742920, 23 pages, 2016. https://doi.org/10.1155/2016/8742920
4. https://stackoverflow.com/questions/49524329/disparity-map-block-matching
5. https://sites.google.com/site/5kk73gpu2010/assignments/stereo-vision
6. https://www.programmersought.com/article/93105038292/
7. <https://medium.com/analytics-vidhya/significance-of-kernel-size-200d769aecb1>