Elektrobit

UDACITY

Technical Safety Concept Lane Assistance

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Document history

Date	Version	Editor	Description
06/13/2018	1.0	Swapnil More	First Draft

Table of Contents

Purpose of the Technical Safety Concept

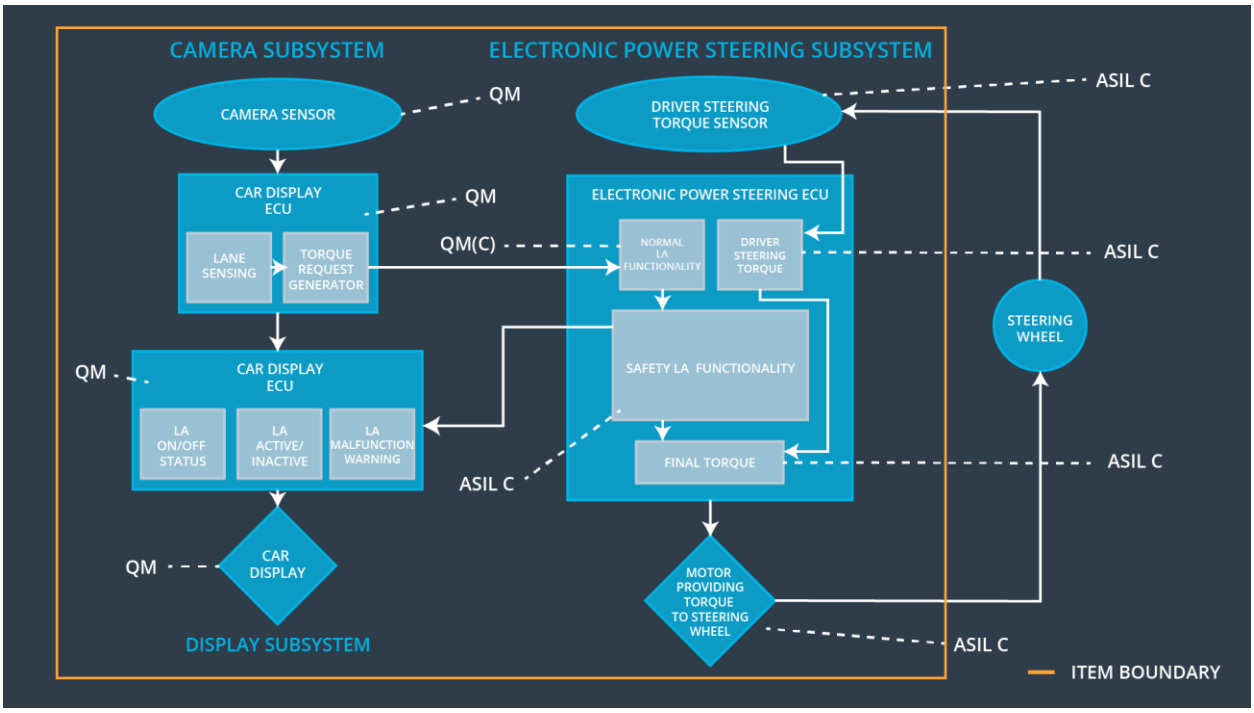
The purpose of the technical safety concept is to look at the item from a system-level perspective, refine the functional safety requirements as technical safety requirements. It is defined in the product development phase as it is more concrete and gets into the details of the item's technology. It assigns functions to specific sub-level of the systems according to ISO 26262.

Inputs to the Technical Safety Concept

Functional Safety Requirements

ID	Functional Safety Requirement	ASIL	Fault Tolerant Time Interval	Safe State
Functional Safety Requirement 01-01	The electronic power steering ECU shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude.	C	50 ms	Vibration torque amplitude below Max_Torque_Amplitude.
Functional Safety Requirement 01-02	The electronic power steering ECU shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency.	C	50 ms	Vibration frequency is below Max_Torque_Frequency.
Functional Safety Requirement 02-01	The electronic power steering ECU shall ensure that the Lane Keeping Assistance torque is applied only Max_Assist_Time	B	500 ms	Assistance time is below Max_Assist_Time

Refined System Architecture from Functional Safety Concept

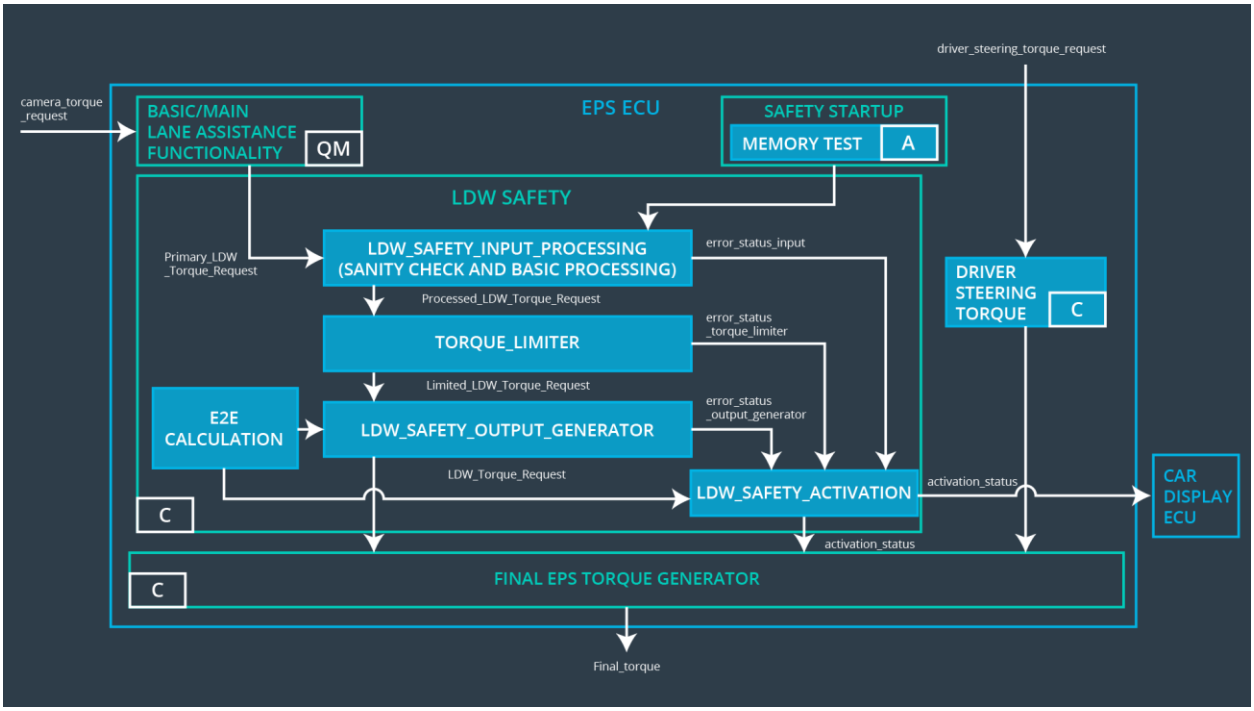


Functional overview of architecture elements

Element	Description
Camera Sensor	Capture images and send them to the Camera Sensor ECU
Camera Sensor ECU - Lane Sensing	Process Images to detect lane lines and calculate vehicle position w.r.t. the lane lines
Camera Sensor ECU - Torque request generator	Calculate the torque required to maintain vehicle in the lane.
Car Display	Display the Lane Departure Warning and status of the Lane Assistance System
Car Display ECU - Lane Assistance On/Off Status	Identify the status of the Lane Assistance System (ON/OFF)
Car Display ECU - Lane Assistant Active/Inactive	Identify the status of the Lane Assistance System (Active/Inactive)
Car Display ECU - Lane Assistance malfunction warning	Identify Lane Assistance Malfunction

Driver Steering Torque Sensor	Measure the torque applied to the steering wheel by the driver.
Electronic Power Steering (EPS) ECU - Driver Steering Torque	Software module receiving the driver’s torque request from the steering wheel.
EPS ECU - Normal Lane Assistance Functionality	Software module receiving the Camera Sensor ECU torque request.
EPS ECU - Lane Departure Warning Safety Functionality	Software module ensuring the torque amplitude is below Max_Torque_Amplitude and torque frequency is below Max_Torque_Frequency.
EPS ECU - Lane Keeping Assistant Safety Functionality	Software module ensuring the Lane Keeping Assistance functionality application is not activate more than Max_Assist_Time time.
EPS ECU - Final Torque	Combine the torque request from the Lane Keeping and Lane Departure Warning functionalities and sends them to the Motor.
Motor	Applies the required torque to the steering wheel

Technical Safety Concept



Technical Safety Requirements

Lane Departure Warning (LDW) Requirements:

Functional Safety Requirement 01-01 with its associated system elements (derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-01	The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude	X		

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01-01-01	The Lane Departure Warning safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Amplitude.'	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.
Technical Safety Requirement 01-01-02	When the Lane Departure Warning is deactivated, the 'LDW Safety' software module shall send a signal to the Car Display ECU to turn on a warning signal.	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.
Technical Safety Requirement 01-01-03	When a failure is detected by the Lane Departure Warning functionality, it shall deactivate the Lane Departure Warning feature and set 'LDW_Torque_Request' to zero.	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.
Technical Safety Requirement 01-01-04	The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.
Technical Safety Requirement 01-01-05	Memory test shall be conducted at startup of the EPS ECU to check for any memory problems	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.

Functional Safety Requirement 01-2 with its associated system elements (derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 01-02	The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency	X		

Technical Safety Requirements related to Functional Safety Requirement 01-02 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01-02-01	The Lane Departure Warning safety component shall ensure the frequency of the 'LDW_Torque_Reques' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Frequency.'	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.

Lane Departure Warning (LDW) Verification and Validation Acceptance Criteria:

ID	Validation Acceptance Criteria and Method	Verification Acceptance Criteria and Method
Technical Safety Requirement 01-01-01	Validate the Max_Torque_Amplitude is the chosen from the Lane Departure Warning Validation	Verify the Lane Departure Warning functionality is turned off.
Technical Safety Requirement 01-01-02	Validate the 'TORQUE_LIMITER' sends the error_status_torque_limiter signal to the LDW_SAFETY_ACTIVATION.	Verify the Car Display ECU displays the Lane Departure Warning malfunction warning signal.
Technical Safety Requirement 01-01-03	Validate the 'TORQUE_LIMITER' sends 'LDW_Torque_Request' with zero.	Verify the Final EPS Torque generator receives a LDW_Torque_Request of zero.
Technical Safety Requirement 01-01-04	Validate the 'TORQUE_LIMITER' calculate and sends the correct cyclic redundancy check (CRC) and Alive counter for data transmission validity and integrity.	Verify the functionality is turn off if there is a CRC or Alive counter discrepancy.
Technical Safety Requirement 01-01-05	Validate the Safety Startup Memory test to check memory faults catch memory faults.	Verify the Lane Departure Warning is turned off when the Safety Startup Memory fails.
Technical Safety Requirement 01-02-01	Validate the Max_Torque_Frequency set is chosen from the Lane Departure Warning Acceptance Criteria.	Max_Torque_Request.

Lane Keeping Assistance (LKA) Requirements:

Functional Safety Requirement 02-1 with its associated system elements (derived in the functional safety concept)

ID	Functional Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Functional Safety Requirement 02-01	The lane keeping item shall ensure that the lane keeping assistance torque is applied for only Max_Duration	X		

Technical Safety Requirements related to Functional Safety Requirement 02-01 are:

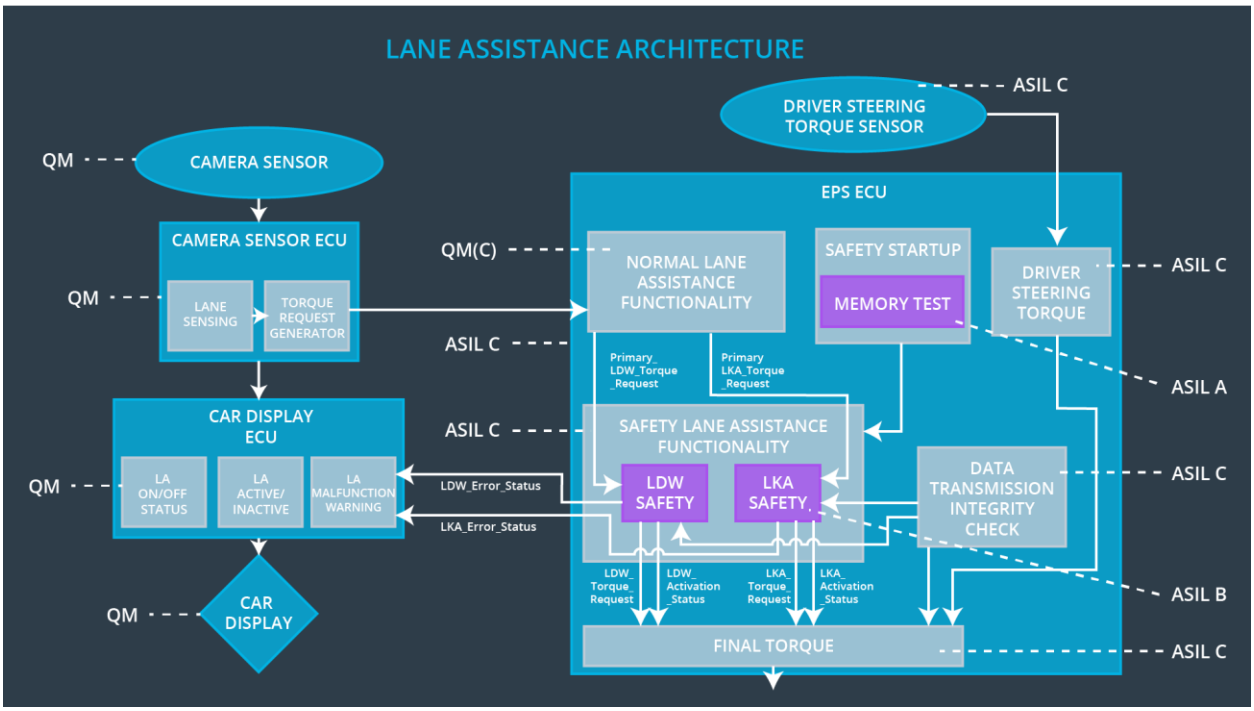
ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 02-01-01	The Lane Keeping Assistance safety component shall ensure the duration of the lane keeping assistance torque is applied for less than Max_Duration	C	500 ms	LKA Safety	Lane Keeping Assistance torque to zero.
Technical Safety Requirement 02-01-02	When the Lane Keeping Assistance function deactivates, the 'LKA Safety' shall send a signal to the Car Display ECU to turn on a warning light.	C	500 ms	LKA Safety	Lane Keeping Assistance torque to zero.
Technical Safety Requirement 02-01-03	When a failure is detected, the Lane Keeping Assistance function shall deactivate and the 'LKA_Torque_Request' shall be zero.	C	500 ms	LKA Safety	Lane Keeping Assistance torque to zero.
Technical Safety Requirement 02-01-04	The validity and integrity of the data transmission for 'LKA_Torque_Request' signal shall be ensured.	C	500 ms	LKA Safety	Lane Keeping Assistance torque to zero.
Technical	Memory test shall be conducted	A	Ignition	Data	Lane

Safety Requirement 02-01-05	at start up of the EPS ECU to check for any memory problems		cycle	Transmission Integrity Check	Departure Warning torque to zero.

Lane Keeping Assistance (LKA) Verification and Validation Acceptance Criteria:

ID	Validation Acceptance Criteria and Method	Verification Acceptance Criteria and Method
Technical Safety Requirement 02-01-01	Validate the Max_Duration is set to the chosen value from LKA Validation Assistance Criteria	Verify the functionality is turned off after it is applied for Max_Duration.
Technical Safety Requirement 02-01-02	Validate the 'TORQUE_LIMITER' sends the error_status_torque_limiter signal to the LKA_SAFETY_ACTIVATION.	Verify the Car Display ECU displays the Lane Keeping Assistance malfunction warning signal.
Technical Safety Requirement 02-01-03	Validate the 'TORQUE_LIMITER' sends 'LKA_Torque_Request' with zero.	Verify the Final EPS Torque generator receives a LKA_Torque_Request of zero.
Technical Safety Requirement 02-01-04	Validate the 'TORQUE_LIMITER' calculate and sends the correct cyclic redundancy check (CRC) and Alive counter for data transmission validity and integrity.	Verify the functionality is turn off if there is a CRC or Alive counter discrepancy.
Technical Safety Requirement 02-01-05	Validate the Safety Startup Memory test to check memory faults catch memory faults.	Verify the Lane Keeping Assistance is turned off when the Safety Startup Memory fails.

Refinement of the System Architecture



Allocation of Technical Safety Requirements to Architecture Elements

ID	Technical Safety Requirement	Electronic Power Steering ECU	Camera ECU	Car Display ECU
Technical Safety Requirement 01-01-01	The Lane Departure Warning safety component shall ensure that the amplitude of the ‘LDW_Torque_Request’ sent to the ‘Final electronic power steering Torque’ component is below ‘Max_Torque_Amplitude.’	**X**		
Technical Safety Requirement 01-01-02	When the Lane Departure Warning is deactivated, the ‘LDW Safety’ software module shall send a signal to the Car Display ECU to turn on a warning signal.	**X**		

Technical Safety Requirement 01-01-03	When a failure is detected by the Lane Departure Warning functionality, it shall deactivate the Lane Departure Warning feature and set 'LDW_Torque_Request' to zero.	**X**		
Technical Safety Requirement 01-01-04	The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.	**X**		
Technical Safety Requirement 01-01-05	Memory test shall be conducted at start up of the EPS ECU to check for any memory problems	**X**		
Technical Safety Requirement 01-02-01	The Lane Departure Warning safety component shall ensure the frequency of the 'LDW_Torque_Reques' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Frequency.'	**X**		
Technical Safety Requirement 02-01-01	The Lane Keeping Assistance safety component shall ensure the duration of the lane keeping assistance torque is applied for less than Max_Duration	**X**		
Technical Safety Requirement 02-01-02	When the Lane Keeping Assistance function deactivates, the 'LKA Safety' shall send a signal to the Car Display ECU to turn on a warning light.	**X**		
Technical Safety Requirement 02-01-03	When a failure is detected, the Lane Keeping Assistance function shall deactivate and the 'LKA_Torque_Request' shall be zero.	**X**		
Technical Safety Requirement	The validity and integrity of the data transmission for	**X**		

02-01-04	‘LKA_Torque_Request’ signal shall be ensured.			
Technical Safety Requirement 02-01-05	Memory test shall be conducted at start up of the EPS ECU to check for any memory problems	**X**		

Warning and Degradation Concept

ID	Degradation Mode	Trigger for Degradation Mode	Safe State invoked?	Driver Warning
WDC-01	Turn off Lane Departure Warning functionality	Malfunction_01, Malfunction_02, Malfunction_05	Yes	Lane Departure Warning Malfunction Warning on Car Display
WDC-02	Turn off Lane Keeping Assistance functionality	Malfunction_03, Malfunction_04	Yes	Lane Keeping Assistance Malfunction Warning on Car Display