

Lecture 32: October 31, 2017

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32.1 Single Object Auction Model

Let the type set of agent i be $T_i \subseteq \mathbb{R}$ and $t_i \in T_i$ be the value agent i gets if he wins the object.

An allocation a is a vector of length n , where a_i denotes the probability that i wins the object. The set of allocations is denoted by

$$\Delta A = \{a \in \mathbb{R}_{\geq 0}^n : \sum_{i=1}^n a_i = 1\},$$

and the allocation rule is a function $f : T_1 \times T_2 \times \cdots \times T_n \rightarrow \Delta A$ where $f_i(t_i, t_{-i})$ is the probability that i wins the object when type profile is (t_i, t_{-i}) .

Given an allocation $a = (a_1, \dots, a_n)$, the valuation of agent i is given by the *product form* $a_i \cdot t_i$.

The setting and results can be extended to setting where a_i is the amount of an object allocated to agent i . For example, in sponsored search auctions, a_i is replaced by CTR_i . In general, the analysis presented here is similar if the valuation of every agent is in the product form, where one factor in the product comes as the outcome of the allocation rule and the other factor is a scalar type of the agent. This domain of valuations is called “single parameter domain”.

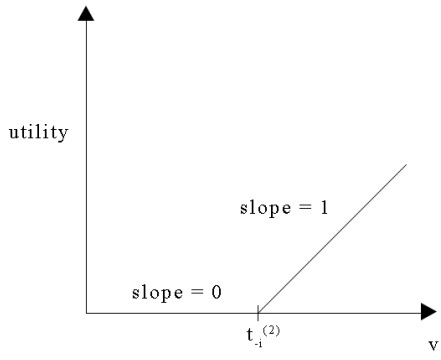
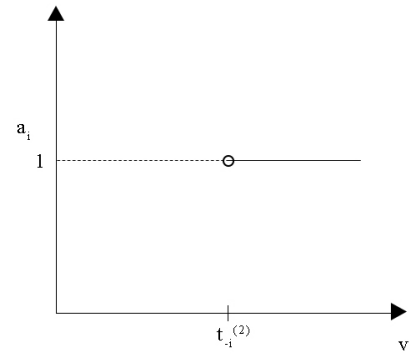
32.1.1 Vickrey (Second Price) Auction

Consider the utility and allocation of the object of agent i w.r.t. the type of the agent as shown in Figures 32.1 and 32.2 respectively. Agent i wins if $v_i > t_{-i}^{(2)}$ and loses if $v_i < t_{-i}^{(2)}$ where v_i is the type of agent i , i.e., the value of the object if i wins. $t_{-i}^{(2)}$ is defined as $\max_{j \neq i} v_j$.

The utility u_i of agent i (Figure 32.1) is defined as

$$u_i = \begin{cases} 0 & \text{if } v_i \leq t_{-i}^{(2)} \\ v_i - t_{-i}^{(2)} & \text{if } v_i > t_{-i}^{(2)} \end{cases}$$

We see that the utility is a convex function. The derivative of the utility function is 0 for $v_i < t_{-i}^{(2)}$ and 1 for $v_i > t_{-i}^{(2)}$, and the function is not differentiable at $v_i = t_{-i}^{(2)}$. Also, its derivative coincides with the probability of winning wherever it exists (Figure 32.2).

Figure 32.1: Utility of agent i Figure 32.2: Allocation of agent i

32.2 Some Results from Convex Analysis

We are interested in functions $g : \mathbb{I} \rightarrow \mathbb{R}$, where $\mathbb{I} \subseteq \mathbb{R}$ is an interval.

Definition 32.1 : A function $g : \mathbb{I} \rightarrow \mathbb{R}$ is convex if for every $x, y \in \mathbb{I}$ and $\lambda \in [0, 1]$,

$$\lambda g(x) + (1 - \lambda)g(y) \geq g(\lambda x + (1 - \lambda)y)$$

Facts:

1. Convex functions are continuous in the interior of its domain; jumps can only occur only at the boundaries.
2. Convex functions are differentiable “almost everywhere” in \mathbb{I} . Formally, there exists a $\mathbb{I}' \subseteq \mathbb{I}$ such that $\mathbb{I} \setminus \mathbb{I}'$ has countable points (has measure zero) and g is differentiable at every point of \mathbb{I}' .

32.2.1 Subgradient

Definition 32.2 For any $x \in \mathbb{I}$, x^* is a subgradient of the function $g : \mathbb{I} \rightarrow \mathbb{R}$ at x if

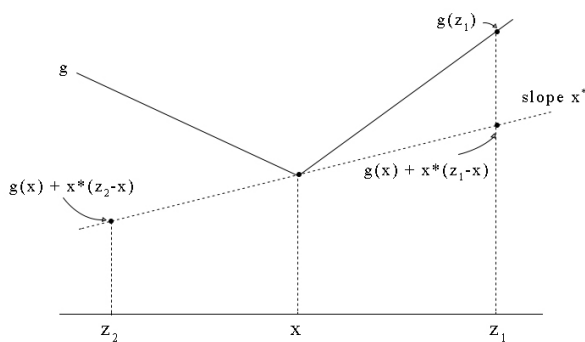
$$g(z) \geq g(x) + x^* \cdot (z - x), \quad \forall z \in \mathbb{I}$$

Lemma 32.3 Let $g : \mathbb{I} \rightarrow \mathbb{R}$ is a convex function. Suppose x is in the interior of \mathbb{I} and g is differentiable at x . Then $g'(x)$ is the unique subgradient of g at x .

Proof: Consider $z \in \mathbb{I}$ such that $z > x$ (a similar proof works if $z < x$). Consider h such that $(z - x) \geq h > 0$.

$$x + h = \frac{h}{z - x}z + \left(1 - \frac{h}{z - x}\right)x$$

Since g is convex,

Figure 32.3: $g(x)$

$$\begin{aligned} \frac{h}{z-x} g(z) + \left(1 - \frac{h}{z-x}\right) g(x) &\geq g(x+h) \\ \implies \frac{g(z) - g(x)}{z-x} &\geq \frac{g(x+h) - g(x)}{h} \end{aligned}$$

The above result holds for any $h > 0$. So when $h \rightarrow 0$,

$$g(z) - g(x) \geq g'(x) (z - x)$$

Hence $g'(x)$ is a subgradient of g at x .

Now, we need to show uniqueness. Say for contradiction, there exists another subgradient $x^* \neq g'(x)$ at x .

Case 1: $x^* > g'(x)$. By definition,

$$\begin{aligned} g(x+h) - g(x) &\geq x^* h \\ \implies \frac{g(x+h) - g(x)}{h} &\geq x^* > g'(x) \end{aligned}$$

Taking limit as $h \rightarrow 0$

$$g'(x) \geq x^* > g'(x)$$

But this is a contradiction.

Case 2: $x^* < g'(x)$. A similar contradiction can be reached. ■

Lemma 32.4 Let $g : \mathbb{I} \rightarrow \mathbb{R}$ be a convex function. Then for every $x \in \mathbb{I}$, the subgradient of g at x exists.

Fact: For points in $\mathbb{I} \setminus \mathbb{I}'$, the set of subgradients at a point forms a convex set.

$$\text{Define } g'_+(x) = \lim_{\substack{z \rightarrow x \\ z \in \mathbb{I}, z > x}} g'(x) \text{ and } g'_-(x) = \lim_{\substack{z \rightarrow x \\ z \in \mathbb{I}, z < x}} g'(x)$$

The set of subgradients at $x \in \mathbb{I} \setminus \mathbb{I}'$ is $[g'_-(x), g'_+(x)]$

The set of subgradients of g at a point $x \in \mathbb{I}$ is denoted by $\partial g(x)$.

Lemma 32.3 says that $\partial g(x)$ is $\{g'(x)\}$ for $x \in \mathbb{I}'$ and Lemma 32.4 says that it is non-empty for all $x \in \mathbb{I}$.

Lemma 32.5 *Let $g : \mathbb{I} \rightarrow \mathbb{R}$ be a convex function. Let $\phi : \mathbb{I} \rightarrow \mathbb{R}$ such that $\phi(z) \in \partial g(z), \forall z \in \mathbb{I}$. Then $\forall x, y \in \mathbb{I}$ such that $x > y$, we have $\phi(x) \geq \phi(y)$.*

Proof: By definition,

$$g(x) \geq g(y) + \phi(y)(x - y)$$

$$g(y) \geq g(x) + \phi(x)(y - x)$$

Adding the above two equations, $(\phi(x) - \phi(y))(x - y) \geq 0$

$$\implies \phi(x) \geq \phi(y) \quad (\text{because } x > y)$$

■

If g was differentiable everywhere, then we know that

$$g(x) = g(y) + \int_y^x g'(z) dz$$

An extension of this result holds for convex functions with subgradients.

Lemma 32.6 *Let $g : \mathbb{I} \rightarrow \mathbb{R}$ be a convex function. Then for any $x, y \in \mathbb{I}$,*

$$g(x) = g(y) + \int_y^x \phi(z) dz$$

where $\phi : \mathbb{I} \rightarrow \mathbb{R}$ is such that $\phi(z) \in \partial g(z), \forall z \in \mathbb{I}$.