Optimal mechanism design for multiple agents

In this context, we will call a mechanism optimal if it is BIC and IIR and maximizes revenue.

By previous results, this reduces to

1) fi's are NDE, tiEN,

② $\pi_i(t_i)$ has a specific formula and $\pi_i(0) = 0$.

The expected payment made by agent i is

$$T_i \int \pi_i(t_i) g_i(t_i) dt_i$$
; $T_i = [0, b_i]$

in a way similar to the earlier exercise, simplify to the following

$$\int_{0}^{b_{i}} \omega_{i}(t_{i}) g_{i}(t_{i}) \alpha_{i}(t_{i}) dt_{i} \qquad \omega_{i}(t_{i}) = t_{i} - \frac{1 - G_{i}(t_{i})}{g_{i}(t_{i})}$$

=
$$\int f_i(t_i, t_i) g_i(t_i) dt_i$$
 also called vintual valuation of player i

$$= \int_{T} \omega_{i}(t) f_{i}(t) g(t) dt$$

Hence, The total neverme generated by all players is

$$\sum_{i \in N} \int_{T} \omega_{i}(t_{i}) f_{i}(t) g(t) dt$$

=
$$\int \left(\sum_{i \in \mathbb{N}} \omega_i(t_i) f_i(t)\right) g(t) dt$$
 expected total virtual valuation

Hence The optimal mechanism design problem reduces to

max
$$\int_{i \in \mathbb{N}} \left(\sum_{i \in \mathbb{N}} w_i(t_i) f_i(t) \right) g(t) dt$$
, s.t. f is NDE.

As before, we attempt to solve the unconstrained optimization problem. $f_i(t) = \begin{cases} 1 & \text{if } w_i(t_i) \geqslant w_j(t_j) & \text{if } (\text{sold}) \\ 0 & \text{ow} \end{cases}$

fi(t)=0, tien, if wi(ti)<0 tien (moold)

But it can lead to a situation where f is not NDE (for an example, see Mycrson (1981): "Optimal Auction Design"The example is such that The following condition is violated)

Defn: A vintual valuation w_i is regular if $\forall s_i, t_i \in T_i$ with $s_i < t_i$, it holds that $w_i(s_i) < w_i(t_i)$.

This condition is weaker than the MHR condition as MHR implies regularity.

Lemma: Suppose every agent's valuations are negular. The allocation rule of the optimal mechanism is same as the solution of the unconstrained problem.

Proof sketch: The solution is as given in equ. 1.

Regularity ensures that $W_i(t_i) > W_i(s_i) + s_i < t_i$

Then The optimal allocation rule also satisfies

$$f_i(t_i, \underline{t}_i) \geqslant f_i(s_i, \underline{t}_i) \quad \forall \, \underline{t}_i \in \underline{T}_i, \, \forall \, s_i < t_i$$

i.e., f_i is non-decreasing (hence NDE).