# CS711: Introduction to Game Theory and Mechanism Design

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Mixed Strategies, Nash Theorem

#### **Proof of the Characterization Theorem**

#### Theorem (Characterization of a MSNE)

A mixed strategy profile  $(\sigma_i^*, \sigma_{-i}^*)$  is a MSNE iff  $\forall i \in N$ 

- 1.  $u_i(s_i, \sigma_{-i}^*)$  is the same for all  $s_i \in \delta(\sigma_i^*)$ , and
- 2.  $u_i(s_i, \sigma_{-i}^*) \ge u_i(s_i', \sigma_{-i}^*), \ \forall \ s_i \in \delta(\sigma_i^*), s_i' \notin \delta(\sigma_i^*).$ 
  - Observations:
- first:

$$\max_{\sigma_i \in \Delta(S_i)} u_i(\sigma_i, \sigma_{-i}^*) = \max_{s_i \in S_i} u_i(s_i, \sigma_{-i}^*)$$

- maximizing w.r.t. a distribution ≡ whole probability mass at the maximum value (or splits arbitrarily over the maximum values)
- second

$$\max_{\sigma_i \in \Delta(S_i)} u_i(\sigma_i, \sigma_{-i}^*) = \max_{s_i \in S_i} u_i(s_i, \sigma_{-i}^*) = \max_{s_i \in \delta(\sigma_i^*)} u_i(s_i, \sigma_{-i}^*)$$

• a maximizer  $s_i$  must lie in  $\delta(\sigma_i^*)$  – if none of the maximizers live in  $\delta(\sigma_i^*)$ , then one can construct a mixed strategy by placing all mass on that  $s_i' \notin \delta(\sigma_i^*)$  which will be strictly better than the utility at the MSNE – a contradiction

# **Proof (contd.)**

- **Proof:** ( $\Rightarrow$ ) given  $(\sigma_i^*, \sigma_{-i}^*)$  is an MSNE, the two conditions hold
- ullet given  $(\sigma_i^*,\sigma_{-i}^*)$  is an MSNE

$$u_{i}(\sigma_{i}^{*}, \sigma_{-i}^{*}) = \max_{\sigma_{i} \in \Delta(S_{i})} u_{i}(\sigma_{i}, \sigma_{-i}^{*})$$

$$= \max_{s_{i} \in S_{i}} u_{i}(s_{i}, \sigma_{-i}^{*})$$

$$= \max_{s_{i} \in \delta(\sigma_{i}^{*})} u_{i}(s_{i}, \sigma_{-i}^{*})$$
(1)

by definition of expected utility for the given strategy profile we have

$$u_{i}(\sigma_{i}^{*}, \sigma_{-i}^{*}) = \sum_{s_{i} \in S_{i}} \sigma_{i}^{*}(s_{i}) \cdot u_{i}(s_{i}, \sigma_{-i}^{*})$$

$$= \sum_{s_{i} \in \delta(\sigma_{i}^{*})} \sigma_{i}^{*}(s_{i}) \cdot u_{i}(s_{i}, \sigma_{-i}^{*})$$
(2)

Equating the 1 and 2: expectation and the maximum value of a set are equal

 happen only when either the set is singleton or all the elements take the
 same value – condition 1 proved

# **Proof** (contd.)

• to prove condition 2: suppose for contradiction

$$\exists s_i \in \delta(\sigma_i^*), s_i' \notin \delta(\sigma_i^*) \text{ s.t. } u_i(s_i, \sigma_{-1}^*) < u_i(s_i', \sigma_{-i}^*)$$

- transfer all the mass of  $\sigma_i^*(s_i)$  to  $s_i'$  this new mixed strategy will yield a strictly better utility contradiction to MSNE
- (⇐) given the two conditions of the characterization theorem hold
- define  $u_i(s_i, \sigma_{-i}^*) =: m_i(\sigma_{-i}^*)$ , for all  $s_i \in \delta(\sigma_i^*)$  possible to define due to condition 1
- using condition 2, we conclude  $m_i(\sigma_{-i}^*) = \max_{s_i \in S_i} u_i(s_i, \sigma_{-i}^*)$

# **Proof** (contd.)

$$u_{i}(\sigma_{i}^{*}, \sigma_{-i}^{*}) = \sum_{s_{i} \in \delta(\sigma_{i}^{*})} \sigma_{i}^{*}(s_{i}) \cdot u_{i}(s_{i}, \sigma_{-i}^{*})$$

$$= m_{i}(\sigma_{-i}^{*})$$

$$= \max_{s_{i} \in S_{i}} u_{i}(s_{i}, \sigma_{-i}^{*})$$

$$= \max_{\sigma_{i} \in \Delta(S_{i})} u_{i}(\sigma_{i}, \sigma_{-i}^{*})$$

$$\geq u_{i}(\sigma_{i}, \sigma_{-1}^{*}) \quad \forall \sigma_{i} \in \Delta(S_{i})$$

$$(3)$$

- first equality holds by definition of  $\delta(\sigma_i^*)$
- next two equalities hold due to conditions (1) and (2) as explained before
- last equality is by the observation
- ullet  $\Longrightarrow$   $(\sigma_i^*,\sigma_{-i}^*)$  is an MSNE

**Summary:** this theorem gives an algorithm to find an MSNE **Question:** is this algorithm guaranteed to yield an outcome? Yes!

# Algorithm to find MSNE

- NFG  $G = \langle N, (S_i)_{i \in N}, (u_i)_{i \in N} \rangle$
- all possible supports of  $S_1 \times S_2 \times \cdots \times S_n$
- $K = (2^{|S_1|} 1) \times (2^{|S_2|} 1) \times \cdots \times (2^{|S_n|} 1)$
- ullet given a support profile  $X_1 imes X_2 imes \cdots imes X_n$ , where  $X_i \subseteq S_i$
- solve the following feasibility program

$$\begin{split} w_i &= \sum_{s_{-i} \in S_{-i}} \left( \prod_{j \neq i} \sigma_j(s_j) \right) u_i(s_i, s_{-i}), \forall s_i \in X_i, \forall i \in N \\ w_i &\geqslant \sum_{s_{-i} \in S_{-i}} \left( \prod_{j \neq i} \sigma_j(s_j) \right) u_i(s_i, s_{-i}), \forall s_i \in S_i \setminus X_i, \forall i \in N \\ \sigma_j(s_j) &\geqslant 0, s_j \in S_j, j \in N, \text{ and } \sum_{s_j \in S_j} \sigma_j(s_j) = 1, \forall j \in N \end{split}$$

variables  $w_i, i \in N$ ,  $\sigma_j(s_j), s_j \in S_j, j \in N$ 

# Algorithm to find MSNE (contd.)

• feasibility program

$$\begin{split} w_i &= \sum_{s_{-i} \in S_{-i}} \left( \prod_{j \neq i} \sigma_j(s_j) \right) u_i(s_i, s_{-i}), \forall s_i \in X_i, \forall i \in N \\ w_i &\geqslant \sum_{s_{-i} \in S_{-i}} \left( \prod_{j \neq i} \sigma_j(s_j) \right) u_i(s_i, s_{-i}), \forall s_i \in S_i \setminus X_i, \forall i \in N \\ \sigma_j(s_j) &\geqslant 0, s_j \in S_j, j \in N, \text{ and } \sum_{s_j \in S_j} \sigma_j(s_j) = 1, \forall j \in N \end{split}$$

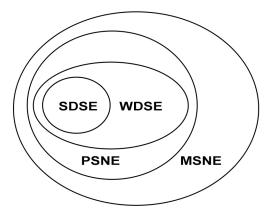
variables  $w_i, i \in N$ ,  $\sigma_j(s_j), s_j \in S_j, j \in N$ 

- linear if n=2, otherwise non-linear
- for general games, there is no known poly-time algorithm
- problem of finding a MSNE is PPAD complete Daskalakis et al.  $(2009)^1$

<sup>&</sup>lt;sup>1</sup>Daskalakis, Constantinos, Paul W. Goldberg, and Christos H. Papadimitriou. "The complexity of computing a Nash equilibrium." SIAM Journal on Computing 39.1 (2009): 195-259.

# Relation between the Equilibria Concepts

- Equilibria concepts discussed: SDSE, WDSE, PSNE, MSNE
- What is the relationship expressed as implications?
- Let  $(s_i^*, s_{-i}^*)$  is an SDSE
- ullet Hence the utility is strictly better at  $s_i^*$  for i for every  $s_{-i}$
- Implies WDSE
- Extend similar arguments for the rest of the equilibria



#### **MSNE** and Dominance

- The previous algorithm can be applied to a smaller set of strategies by removing the dominated strategies
- Is there any dominated strategy for any player

<b>1</b> \2	L	R
Т	4,1	2,5
М	1,3	6,2
В	2,2	3,3

- domination can be by another pure strategy or a mixed strategy
- but for weakly dominated strategies it may remove certain equilibria too
- for the strictly dominated strategies, the following holds

#### **Theorem**

Consider an NFG  $G=\langle N,(S_i)_{i\in N},(u_i)_{i\in N}\rangle$ . If a pure strategy  $s_i$  is strictly dominated by a mixed strategy  $\sigma_i\in\Delta(S_i)$ , then in every MSNE of the game, the pure strategy  $s_i$  is chosen with probability 0.

ullet Hence  $s_i$  can be removed without loss of equilibria

#### **Existence of MSNE**

• **Finite game:** A game in which the number of players and the strategies are finite.

### Theorem (Nash (1951))

Every finite game has a (mixed) Nash equilibrium.

- proof needs a few definitions and a known result
  - ▶ A set  $S \subseteq \mathbb{R}^n$  is **convex** if  $\forall x, y \in S$  and  $\forall \lambda \in [0, 1]$ ,  $\lambda x + (1 \lambda)y \in S$ .
  - A set  $S \subseteq \mathbb{R}^n$  is **closed** if it contains all its limit points (points whose every neighborhood contains a point in S e.g., for the point 1 in the interval [0,1), consider a ball of radius  $\epsilon > 0$ , arbitrary, clearly, each such ball will contain a point in [0,1)).
  - A set  $S \subseteq \mathbb{R}^n$  is **bounded** if  $\exists x_0 \in \mathbb{R}^n$  and  $R \in (0, \infty)$  such that  $\forall x \in S, \|x x_0\|_2 < R$ .
  - ▶ A set  $S \subseteq \mathbb{R}^n$  is **compact** if it is *closed* and *bounded*.
- a result from real analysis without proof

#### Theorem (Brouwer's Fixed Point Theorem)

If  $S \subseteq \mathbb{R}^n$  is convex and compact and  $T: S \mapsto S$  is continuous, then T has a fixed point, i.e.,  $\exists$  a point  $x^* \in S$  s.t.  $T(x^*) = x^*$ .