ABES Engineering College, Ghaziabad

(Affiliated to Dr.A.P.J AKTU, Lucknow)

Department of Computer Science & Engineering



Lab Manual

Session 2019-20 (Odd Semester)

Subject Name : Data Structures Using 'C'

Subject Code : KCS 351

Semester : B.Tech. CSE III (A,B,C)

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Tools & Software

Recommended Systems/Software Requirements:

Turbo C/C++
Code Block
Any Online C/C++ Compiler

Data Structure Lab (KCS 351)/ Data Structure Lab					
	List of Experiments				
S.N o.	Program	DOMAIN			
1	Program for Array Inserion, Deletion and traversal	Array			
2	Program for Insertion in Sorted Array	Array			
	Program to Find the number which is not repeated in Array of integers, others are present				
3	for two times				
4	Program For Linear Search				
5	Program for Binary Search				
6	Program for Index Sequential Search	Array			
7	Program for Bubble, Selection and Insertion Sort				
8	Program for Implementation of Shell Sort				
	Program for Quick Sort	Array Array			
9	Program for Randomized Quick Sort	Array			
	Program for Quick Sort using Median element as Pivot	Array			
10	Program for Merge Sort	Array			
11	Program for Merging of two Sorted Arrays	Array			
12	Program for Finding set elements of A that belongs to set B	Array			
13	Program for Finding set elements of A that does not belong to set B	Array			
14	Program for Set Union	Array			
15	Program for Set Intersection	Array			
16	Program for Set DIFference	Array			
17	Program for Counting Sort	Array			
18	Program for Radix Sort	Array			
19	Program for Matrix Addition	Array			
20	Program for Matrix Multiplication	Array			
21	Program for Matrix transposition	Array			
22	Program for Matrix transposition without second matrix	Array			
23	Program to Print a given matrix in spiral form	Array			
24	Program for Sorting the given Complex Numbers	Array			
25	Program for Creation of Max Heap and Min Heap	Неар			
26	Program for Insertion in Max Heap/Min Heap	Heap			
27	Program for Deletion from Max Heap and Min Heap	Неар			
<u> </u>	Program for Realizing Heap as Ascending/Descending Priority Queue	Неар			
	Project 1: Program for Heap Sort				
Project 2: Performance Comparision of Sorting ALGORITHMs					
29	Program for Hash Table Implementation for Basic Hash Function (Without collisions)	Hashing			
30	Program for Hash Table Implementation for Collision Resolution using Linear Probing	Hashing			
31	Program for Hash Table Implementation for Collision Resolution using Quadratic Probing	Hashing			

	Program for Hash Table Implementation for Collision Resolution using Double				
32	Hashing/Rehashing	Hashing			
33	Program for Hash Table Implementation for Collision Resolution using Chaining	Hashing			
34	Finding Anagrams: There are two strings. Find out which characters should be deleted such that both strings contain the same characters (May be in dIFferent Order)	Hashing			
35	re some numbers in which some are appearing twice but one is not repeated. Find number which appears once. Hashing				
36	There are two arrays containing some elements. Find out what are the elements which are there in both the arrays what are not.	Hashing			
37	find out the values of a,b,c,d (a,b,c,d<=1000) for which a3+b3=c3+d3.	Hashing			
	Project 3: IdentIFication of tokens and identIFiers and storage in Hash Table				
38	Program for finding the length of a string	String			
39	Program for reversing the given string	String			
40	Program for finding IF the given string is a palindrome	String			
41	Program for finding word count in the Paragraph	String			
	Program for converting all lower case letters to upper case and vice versa in the given				
42	sentence	String			
43	Program for finding IF the given word is present in the sentence and at what location	String			
44	Program for sorting the given names in the dictionary order	String			
45	Program for reversing all words in a sentence	String			
	Project 4: Program for automatic word spelling correction using Minimum Edit Dista	nce			
46	Program for Decimal to Binary Conversion	Stack			
47	Program for Decimal to Octal Conversion	Stack			
48	Program for Decimal to Hexadecimal Conversion	Stack			
49	Program for Decimal to Any Base Conversion				
50	Program for Stack Primitive Operations	Stack			
51	Program for Postfix Evaluation	Stack			
<i>52</i>	Program for Infix to Postfix Conversion	Stack			
<i>53</i>	Program for Infix to Prefix Conversion	Stack			
54	Program for Prefix Evaluation	Stack			
<i>55</i>	Program to check the validity of Parenthesized Arithmetic Expressions using Stack	Stack			
<i>56</i>	Program to check the validity of Bracketed Arithmetic Expressions using Stack	Stack			
<i>57</i>	Program to check IF the given number is a palindrome using stacks	Stack			
<i>58</i>	Program to Reverse the given String using Stack	Stack			
Project 5: Program for evaluation of given arithmetic expression. The Expression may have variables and constants					
59	Program for finding factorial of a given number using recursion	Recursion			
60	Program for Towers of Hanoi for n disk (user defined)	Recursion			
61	Program for Computing A raised to power n using Recursion	Recursion			
62	Program for Computing A raised to power n using Divide and Conquer	Recursion			
63	Program for finding nth Fibonacci number using Recursion and improving its run time to	Recursion			
	save stack operations Program for finding the GCD of two numbers using Possursion				
64	Program for finding the GCD of two numbers using Recursion	Recursion			

65	Program to reverse the given number using Recursion	Recursion	
66	Program of Array Implementation of Linear Queue	Queue	
67	Program of Array Implementation of CircularQueue	Queue	
68	Program for Array Implementation of Double Ended Queue	Queue	
69	Program for Array Implementation of Priority Queue	Queue	
70	Program for 1-D array implementation of Upper Triangular Sparse Matrix	Sparse Matrix	
71	Program for 1-D array implementation of Lower Triangular Sparse Matrix	Sparse Matrix	
72	Program for 1-D array implementation of Tridiagonal Sparse Matrix	Sparse Matrix	
73	Program for Vector Representation of General Sparse Matrix	Sparse Matrix	
74	Program For Linked List Implementation of General Sparse Matrix	Sparse Matrix	
<i>75</i>	Program for Addition of two sparse Matrices	Sparse Matrix	
76	Program for Linear Linked List Primitive operations	Linked List	
77	Program for Pair wise swap of elements in linked list	Linked List	
78	Program to print Linked List contents in reverse order	Linked List	
79	Program for Reversing the Linear Linked List	Linked List	
80	Program for concatenation of Linear Linked List	Linked List	
81	Program for Creation of Ascending Order Linear Linked List	Linked List	
82	Program for Merging two sorted Linked List	Linked List	
83	Program for Union of two sorted Linked List (consider lists as sets)	Linked List	
84	Program for Intersection of two sorted Linked List (consider lists as sets)	Linked List	
85	Program for finding dIFference of two linked list (consider lists as sets)	Linked List	
86	Program for Sorting the Linear Linked List	Linked List	
87	Program for Splitting a Linked List	Linked List	
	To Detect IF there is any cycle in the linked list. (use two pointers, once moves at a speed		
88	of one node, other moves at a speed of two nodes. IF they collide with each other it	Linked List	
	means there is a cycle. Dragger for Delynamical Addition using Linked List		
89	Program for Polynomial Addition using Linked List	Linked List	
90	Program for Circular Linked List Primitive Operations	Linked List	
	Program for concatenation of Circular Linked List	Linked List	
92	Program for Circular Doubly Linked List Primitive Operations	Linked List	
93	Program for Circular Doubly Linked List Primitive Operations	Linked List	
94	Program for Linked List Implementation of Linear Queue	Linked List	
95	Program for Linked List Implementation of Circular Queue	Linked List	
96	Program for Linked List Implementation of Priority Queue	Linked List	
97	Program for Linked List Implementation of Stacks	Linked List	
Project 6: Program for Addition of Two very long Numbers			
98	Project 7: Implementatio of Josephus Problem Program for recursive creation of Binary Tree and Traversals	Binary Tree	
		-	
99	Program for creation of Binary Tree and finding its height	Binary Tree	
100	Program for creation of Binary Tree and finding count of nodes having 2 children Program for creation of Binary Tree and finding count of nodes having 1 child	Binary Tree	
101 102		Binary Tree Binary Tree	
102	rrogram for creation of binary free and finding count of flodes having o child	billary free	

		Binary Tree			
103	103 Program for finding IF the given Binary Tree is complete				
104	104 Program for Level Order Traversal				
105	105 Program for finding Balance factor of a given node				
	Project 8: Program for Huffman Coding				
	Project 9: Creation of Binary Tree from Pre-Order and Inorder Traversal				
	Project 10: Program to Create Expression Tree and its Traversal				
		Binary Search			
106	Program for BST Insertion, traversal, Minimum, maximum and Successor operations	Tree			
		Binary Search			
107	Program for BST Deletion	Tree			
		Binary Search			
108	Program to convert the given BST to Max Heap	Tree			
		Binary Search			
109	Program to check IF a Binary Tree is BST or not	Tree			
	Project 11: Program for Binary Search Tree Deletions				
110	Program for AVL Tree Rotations, Insertion and Traversal operations	AVL Tree			
	Project 12: Program for Implementation of Interval Tree				
111	Program for BFS on a Graph	Graph			
112	Program for DFS on a Graph	Graph			
113	Program for Warshall's ALGORITHM for APSP	Graph			
114	Program for Dijikstra's ALGORITHM for SSSP	Graph			
115	Program for Warhall's ALGORITHM for Transitive Closure	Graph			
116	Prorgram for Prim's ALGORITHM for Minimal Spanning Tree	Graph			
117	Prorgram for Kruskal's ALGORITHM for Minimal Spanning Tree	Graph			
118	Program for topological sorting of given graph	Graph			
Project 13: Program for implemenation of Travelling Salesman Problem					

```
Object: Write an ALGORITHM for array insertion, deletion and traversal.
DOMAIN: Array
ALGORITHM Traverse(A[], N)
BEGIN:
        FOR i=1 TO N DO
              WRITE(A[i])
END;
Time Complexity:Θ(N)
Space Complexity:Θ(1)
ALGORITHM Insertion(A[], N, i, key)
BEGIN:
        FOR j=N TO i STEP-1 DO
              A[j+1]=A[j]
              A[i]=key
              N=N+1
END;
Time Complexity:Θ(N)
Space Complexity:Θ(1)
ALGORITHM Deletion(A[], N, i)
BEGIN:
       X=A[i]
        FOR j=i+1 TO N DO
              A[j-1]=A[i]
              N=N-1
       RETURN x
END;
Time Complexity:Θ(N)
Space Complexity:Θ(1)
```

EXPERIMENT No 2

```
Object-Write an ALGORITHM for insertion in sorted array. DOMAIN-Array
```

```
ALGORITHM Sorted(A[], N, key)
BEGIN:
       i=0
       WHILE A[i]<key DO
              i=i+1
              RETURN i
END;
Time Complexity:Θ(N)
Space Complexity:Θ(1)
ALGORITHM: INS_sorted(A[], N ,i, key)
BEGIN:
       FOR j=N-1 TO i STEP-1 DO
              A[j+1]=A[j]
       A[i]=key
       N=N+1
END;
Time Complexity:Θ(N)
```

Space Complexity:⊖(1)

Object:-Write an ALGORITHM to Find the number which is not repeated in Array of integers, others are present for two times.

DOMAIN:-Array

```
ALGORITHM: Arr_func(A[], N)
BEGIN:

K=0,c,B[20]
FOR i=0 TO N DO
c=0
FOR j=0 TO N DO
IF A[j]==A[i] THEN
c=c+1
IF c==1 THEN
B[k++]=A[i]
FOR i=0 TO k DO
WRITE(B[i])
END;
Time Complexity:\Theta(N^2)
```

Space Complexity:Θ(1)

```
Object- Write an ALGORITHM For Linear Search.

DOMAIN-Searching

ALGORITHM Linear_search(A[], N, key)

BEGIN:

FOR i=1 TO N DO

IF A[i]==key THEN

RETURN i

RETURN -1

END;

Worst Case Time Complexity: O(N)

Best Case Time Complexity: □(1)

Space Complexity: Θ(1)
```

```
Object-Write an ALGORITHM for Binary Search.
DOMAIN-Searching
ALGORITHM Binary_search(A[], N, key)
BEGIN:
       HIGH=N-1
       LOW=0
      WHILE LOW<=HIGH DO
             MID=(LOW+HIGH)/2
             IF A[MID]==key THEN
                   RETURN MID
             ELSE
                    IF key<A[MID] THEN
                          HIGH=MID-1
                    ELSE
                          LOW=MID+1
        RETURN -1
END;
Worst Case Time Complexity: O(logN)
Best Case Time Complexity: ②(1)
```

Space Complexity: Θ(1)

```
Object- Write an ALGORITHM for Index Sequential Search. DOMAIN-Searching
```

```
ALGORITHM: INDsearch(data[N],KEY,index[M][2]) BEGIN:
```

```
FOR i=0 TO M-1 DO

IF KEY==index[i][1] THEN

RETURN index[i][0]

ELSE

IF KEY <index[i][1] THEN

high=index[i][0]-1

Low =index[i-1][0]+1

BREAK

FOR i=low TO high DO

IF KEY ==data[i] THEN

RETURN i

RETURN -1
```

END;

Worst Case Time Complexity: O(N/K+K)

Best Case Time Complexity: 2(1)

Space Complexity: Θ(1)

Experiment No 7

```
DOMAIN:Sorting
ALGORITHM: BubbleSort(A[], N)
BEGIN:
        FOR i=1 TO N-1 DO
               FOR j=1 TO N-i DO
                       IF A[j]>A[j+1]
                              k=A[j]
                              A[j]=A[j+1]
                              A[j+1]=k
END;
Worst Case Time Complexity:O(N2)
Best Case Time Complexity: Omega(N)
Space Complexity:Θ(1)
ALGORITHM: InsertionSort(A[], N)
BEGIN:
        FOR i=2 TO N DO
               key=A[i]
               j=i-1
               WHILE j>=1 AND A[j]>key DO
                      A[j+1]=A[j]
                      j=j-1
                A[j+1]=key
END;
Worst Case Time Complexity:O(N<sup>2</sup>)
Best Case Time Complexity: Omega(N)
Space Complexity:Θ(1)
ALGORITHM: SelectionSort(A[], N)
BEGIN:
       FOR i=1 TO N-1 DO
               min=i
               FOR j=i+1 TO N DO
                       IF A[j]<A[min] THEN
                       min=j
               Exchange(A[min], A[i])
END;
Time Complexity: \Theta(N^2)
```

Space Complexity:Θ(1)

Object- Write an ALGORITHM for Bubble, Selection and Insertion Sort.

Experiment No 8

Object- Write an ALGORITHM for Shell Sort. DOMAIN:Sorting

```
ALGORITHM shellSort(array, n):
    gap = n // 2
    WHILE gap > 0 DO
        FOR i=gap to n DO
            temp = array[i]
            j = i
        WHILE j >= gap AND array[j - gap] > temp DO
            array[j] = array[j - gap]
            j -= gap

            array[j] = temp
            gap //= 2
Time Complexity: Θ(N²)
```

Time Complexity: $\Theta(N^2)$ Space Complexity: $\Theta(1)$

```
Object-Write an ALGORITHM for Quick Sort.
DOMAIN-Sorting
ALGORITHM: QuickSort(A[],low,high)
BEGIN:
        IF low<high THEN
               j=Partition(A[],low,high)
               QuickSort(A[],low,j-1)
               QuickSort(A[],j+1,high)
END;
ALGORITHM: Partition(A[],low,high)
BEGIN:
        i=low, j=high+1,pivot=A[low]
        DO
               DO
                       i=i+1
               WHILE(A[i]<pivot)
               DO
                       J=j-1
               WHILE(A[j]>pivot)
               IF i<j THEN
                       Exchange(A[i],A[j])
        WHILE(i<j)
         Exchange(A[j],A[low])
        RETURN j
END;
Worst Case Time Complexity:O(N2)
Best Case Time Complexity: \square (Nlog<sub>2</sub> N)
```

Space Complexity: $\Box(\log_2 N)$

```
Object-Write an ALGORITHM for Merge Sort.
DOMAIN-Sorting
ALGORITHM: MergeSort(A[],low,high)
BEGIN:
       IF low<high DO
               Mid=(low+high)/2
               MergeSort(A[],low,mid)
               MergeSort(A[],mid+1, high)
               Merge(A, low,mid,high)
END;
ALGORITHM: Merge(A[], low,mid,high)
BEGIN:
       i=low,j=mid+1,k=high
       WHILE i<=mid AND j<=high DO
               IF A[i]<A[j] THEN
                      C[k]=A[i]
                      i=i+1
                      k=k+1
               ELSE
                      C[k]=A[j]
                      j=j+1
                      k=k+1
       WHILE i<=mid DO
               C[k]=A[i]
               i=i+1
               k=k+1
       WHILE j<=high DO
               C[k]=A[j]
               J=j+1
             k=k+1
       FOR i=low TO high DO
               A[i]=C[i]
END;
Time Complexity: O(Nlog<sub>2</sub> N)
```

Space Complexity: □(N)

Object- Write an ALGORITHM for merging of two sorted arrays. DOMAIN-Array

```
ALGORITHM: MergeArr(A[],m,B[],n)
BEGIN:
       C[m+n]
       i=1, j=1, k=1
       WHILE i<=m AND j<=n DO
              IF A[i]<B[j] THEN
                      C[k]=A[i]
                      i=i+1
                      k=k+1
              ELSE
                      C[k]=B[j]
                      J=j+1
                      k=k+1
       WHILE i<=m DO
              C[k]=A[i]
              i=i+1
              k=k+1
       WHILE j<=n DO
              C[k]=B[j]
              J=j+1
              k=k+1
       RETURN C
END;
Time Complexity: □(N)
Space Complexity: □(N)
```

Object-Write an ALGORITHM for finding set elements of A that belong to B. DOMAIN-Array

```
ALGORITHM: A_AND_B(A[],m,B[],n)
BEGIN:
       C[m+n]
       i=1, j=1, k=1
       WHILE i<=m AND j<=n DO
              IF A[i]<B[j] THEN
                      i=i+1
              ELSE
                      IF A[i]==B[j] THEN
                      C[k]=B[j]
                      i=i+1
                      j=j+1
                      k=k+1
              ELSE
                      j=j+1
              RETURN C
END;
Time Complexity: Θ(N)
Space Complexity:Θ(N)
```

Object-Write an ALGORITHM for finding set elements of A that does not belong to B. DOMAIN-Array

```
ALGORITHM: A_AND_NOT_B(A[],m,B[],n)
BEGIN:
       C[m+n]
       i=1, j=1, k=1
       WHILE i<=m AND j<=n DO
               IF A[i]<B[j] THEN
                      C[k]=A[i]
                      k=k+1
                      i=i+1
               ELSE
                      IF A[i]==B[j] THEN
                             i=i+1
                             j=j+1
                      ELSE
                             j=j+1
       WHILE i<=m DO
              C[k]=A[i]
              i=i+1
              k=k+1
       RETURN C
END;
Time Complexity: Θ(N)
Space Complexity:Θ(N)
```

Experiment.14.

```
Object-Write an ALGORITHM for Set Union. DOMAIN-Array
```

```
ALGORITHM: SetUnion(A[],m,B[],n)
BEGIN:
       C[m+n]
       i=1, j=1, k=1
       WHILE i<=m AND j<=n DO
              IF A[i]<B[j] THEN
                      C[k]=A[i]
                      i=i+1
                      k=k+1
               ELSE
                      IF A[i]==B[j] THEN
                             C[k]=B[j]
                             i=i+1
                             j=j+1
                             k=k+1
                      ELSE
                             C[k]=B[j]
                             j=j+1
                             k=k+1
       WHILE i<=m DO
              C[k]=A[i]
              i=i+1
              k=k+1
       WHILE j<=n DO
              C[k]=B[j]
              J=j+1
              k=k+1
RETURN C
END;
Time Complexity:Θ(N)
Space Complexity:Θ(N)
```

Experiment.15.

```
Object-Write an ALGORITHM for set Intersection. DOMAIN-Array
```

```
ALGORITHM: SetIntersection(A[],m,B[],n)
BEGIN:
       C[m+n]
       i=1, j=1, k=1
       WHILE i<=m AND j<=n DO
              IF A[i]<B[j] THEN
                      i=i+1
              ELSE
                      IF A[i]==B[j] THEN
                             C[k]=B[j]
                      i=i+1
                      j=j+1
                      k=k+1
                      ELSE
                             j=j+1
       RETURN C
END;
Time Complexity:Θ(N)
```

Time Complexity:Θ(N)
Space Complexity:Θ(N)

Object-Write an ALGORITHM for set DIFference. DOMAIN:Array

```
ALGORITHM: SetDIFference(A[],m,B[],n)
BEGIN:
       C[m+n]
       i=1, j=1, k=1
       WHILE i<=m AND j<=n DO
              IF A[i]<B[j] THEN
                      i=i+1
              ELSE
                      IF A[i]==B[j] THEN
                      i=i+1
                     j=j+1
              ELSE
                      C[k]=B[j]
                      j=j+1
                      k=k+1
       WHILE j<=n DO
              C[k]=B[j]
              J=j+1
              k=k+1
       RETURN C
END;
Time Complexity:⊖(N)
Space Complexity:Θ(N)
```

Experiment.17.

Object-Write an ALGORITHM for Counting Sort. DOMAIN-Sorting

```
ALGORITHM: CountingSort(A[],k,n) BEGIN:
```

```
\begin{aligned} & \text{FOR i} = 0 \text{ TO k DO} \\ & & c[i] = 0 \\ & \text{FOR j} = 0 \text{ TO n DO} \\ & & c[A[j]] = c[A[j]] + 1 \\ & \text{FOR i} = 1 \text{ TO k DO} \\ & & c[i] = c[i] + c[i-1] \\ & \text{FOR j} = \text{n-1 TO 0 STEP-1 DO} \\ & & B[\ c[A[j]] - 1\ ] = A[j] \\ & & c[A[j]] = c[A[j]] - 1 \end{aligned}
```

END;

Time Complexity: Omega(N)
Space Complexity:Θ(N)

Object-Write an ALGORITHM for Radix Sort. DOMAIN-Sorting

ALGORITHM: RadixSort(A[],N,d)

BEGIN:

FOR i=1 TO d DO

Apply counting Sort on A[] at radix i

END;

Time Complexity: $\Theta(N)$ Space Complexity: $\Theta(N)$

Experiment 19.

```
Object- Write an ALGORITHM for Matrix Addition. DOMAIN-Array

ALGORITHM: Matrixadd(A[][], B[][], M,N)

BEGIN:C[M][N]

FOR i=1 TO M DO

FOR j=1 TO N DO

C[i][j]=A[i][j]+B[i][j]

RETURN C

END;

Time Complexity: \Theta(N^2)
Space Complexity: \Theta(N^2)
```

```
Object-Write an ALGORITHM for matrix Multiplication. DOMAIN-Arrray

ALGORITHM: Matrixmultiply(A[][], M,N, B[][], P,Q)

BEGIN:

C[M][Q]
IF N!=P THEN
FOR i=1 TO M DO
FOR j=1 TO Q DO
C[i][j]=0
FOR k=1 TO N DO
C[i][j]=C[i][j]+A[i][k]*B[k][j]
RETURN C
END;

Time Complexity: \Theta(N^3)
Space Complexity: \Theta(N^2)
```

```
Object- Write an ALGORITHM for Matrix Transposition. DOMAIN:Array

ALGORITHM: Matrixtranspose(A[][], M,N)

BEGIN:

B[N][M]
FOR i=1 TO M DO
FOR j=1 TO N DO
B[j][i]=A[i][j]
RETURN B
END;

Time Complexity: \Theta(N^2)
Space Complexity: \Theta(N^2)
```

Object-Write an ALGORITHM for matrix transposition without using second matrix. DOMAIN-Array

```
ALGORITHM: Matrixtranspose(A[][], M,N)
BEGIN:

FOR i=1 TO M DO

FOR j=1 TO i DO

temp=A[i][j]

A[i][j]=A[j][i]

A[j][i]=temp

RETURN A

END;

Time Complexity: \Theta(N^2)
Space Complexity: \Theta(1)
```

Object-Write a program to print a given matrix in spiral form. DOMAIN-Array

```
ALGORITHM MatrixInSpiralForm(int[][100],int,int) BEGIN:
```

```
int i,k=0,l=0;
     WHILE k<r and l<c DO
              for(i=l;i<c;i++)
                 write(a[k][i])
      k++
      FOR(i=k;i<r;i++) DO
              write(a[i][c-1])
      C--
      IF(k<r) THEN
              for(i=c-1;i>=l;i--)
                       write(a[r-1][i])
      r--
      IF(I<c) THEN
              for(i=r-1;i>=k;i--) DO
                       printf("%d ",a[i][l])
      l++;
END;
```

Time Complexity: Θ(N) Space Complexity:Θ(1)

Object-Write an ALGORITHM for creation of min heap and max heap. DOMAIN-Heap

```
ALGORITHM MaxHeapIFy(A[],N)
BEGIN:
       FOR i=N/2 TO STEP-1 DO
              Adjust(A,i,N)
END;
ALGORITHM Adjust(A[],i,N)
BEGIN:
       WHILE 2*i<=N DO
              j=2*i
              IF j+1<=N THEN
                      IF A[j+1]>A[j]
                      j=j+1
             IF A[j]>A[i] THEN
                      Exchange(A[j],A[i])
              ELSE
                      BREAK
       i=j
END;
ALGORITHM MinHeapIFy(A[],N)
BEGIN:
      FOR i=N/2 TO STEP-1 DO
              Adjust(A,i,N)
END;
ALGORITHM Adjust(A[],i,N)
BEGIN:
       WHILE 2*i<=N DO
              j=2*i
              IF j+1<=N THEN
                      IF A[j+1]<A[j]
                      j=j+1
              IF A[j]<A[i] THEN
                      Exchange(A[j],A[i])
              ELSE
                      BREAK
       i=j
END;
Time Complexity: Θ(NlogN)
Space Complexity:Θ(1)
```

```
Write an ALGORITHM for insertion in min or max heap.

ALGORITHM InsertHeap(A[],N,key)

BEGIN:

A[N+1]=key
i=N+1
WHILE i>1 AND A[i]<A[i/2] DO
Exchange(A[i],A[i/2])
I=i/2
N=N+1

END;
```

Time Complexity: Θ(N) Space Complexity:Θ(1)

Write an ALGORITHM for deletion from min or max heap.

```
ALGORITHM DeleteHeap(A[],N)
BEGIN:

x=A[i]

A[i]=A[N]

Adjust(A[],1,N-1)

RETURN x

END;

Time Complexity: Θ(logN)

Space Complexity:Θ(1)
```

```
Write an ALGORITHM for realizing Heap as Ascending/ Descending Priority Queue
ALGORITHM PQInser(A[],N,key)
BEGIN:
       A[N+1]=key
       i=N+1
       WHILE i>1 AND A[i]<A[i/2] DO
             Exchange(A[i],A[i/2])
              I=i/2
       N=N+1
END;
Time Complexity: Θ(LogN)
Space Complexity:⊖(1)
ALGORITHM PQDelete (A[],N)
BEGIN:
       x=A[i]
     A[i]=A[N]
     Adjust(A[],1,N-1)
    RETURN x
END;
Time Complexity: Θ(logN)
Space Complexity:⊖(1)
ALGORITHM Adjust(A[],i,N)
BEGIN:
       WHILE 2*i<=N DO
              j=2*i
              IF j+1<=N THEN
                      IF A[j+1]>A[j]
                      j=j+1
             IF A[j]>A[i] THEN
                      Exchange(A[j],A[i])
              ELSE
                      BREAK
       i=j
END;
Time Complexity: Θ(logN)
Space Complexity:Θ(1)
```

Object: Program for Hash Table Implementation for Basic Hash Function (Without

```
collisions)
DOMAIN-String
ALGORITHM DivisionHash(Key, TS)
BEGIN:
      NearestPrime(TS)
      h=Key%TS
      RETURN h
END;
Time Complexity: \theta(1)
Space Complexity:θ(1)
ALGORITHM MidsquareHash(Key, TS)
BEGIN:
      L=LengthOfKey(Key)
      n=key*key
      x=Ceil((2*L-TS)/2)
      n=n/10↑x
      h=n%10↑L
      RETURN h
END;
Time Complexity: \theta(1)
Space Complexity:θ(1)
ALGORITHM FoldingHash(Key, TS)
BEGIN:
      L=LengthOfKey(Key)
      n=key
      Sum=0
      WHILE n>=0 DO
             r=n%TS
             Sum=Sum+r
             n=n/TS
      h=Sum%TS
      RETURN h
END;
Time Complexity: \theta(1)
Space Complexity:\theta(1)
```

Object: Program for Hash Table Implementation for Collision Resolution using Linear Probing ALGORITHM LinearProbing (T[], N, Key,h) BEGIN: $\begin{array}{c} i=h \\ DO \\ IF\ T[i]==key\ THEN \\ RETURN\ i \\ ELSE \\ IF\ T[i]==Blank\ THEN \\ RETURN\ -1 \\ ELSE \\ i=(i+1)\%N \\ \end{array}$ WHILE(1)

Time Complexity: $\theta(N)$ Space Complexity: $\theta(1)$

Program for Hash Table Implementation for Collision Resolution using Quadratic Probing ALGORITHM QuadraticProbing (T[], N, Key,h) BEGIN:

```
i=0 x=h DO IF T[x]==key THEN RETURN \ x ELSE IF \ T[x]==Blank THEN RETURN \ -1 ELSE x=(h+a^*i+bi\uparrow 2)\%N i=i+1 WHILE(1)
```

Program for Hash Table Implementation for Collision Resolution using Double Hashing/Rehashing

Time Complexity: $\theta(N)$ Space Complexity: $\theta(1)$

```
ALGORITHM DoubleHashingProbe (T[ ], N, Key,h,h')
BEGIN:
      i=1
      x=h
      DO
             IF T[x]==key THEN
                   RETURN x
            ELSE
                   IF T[x]==Blank THEN
                          RETURN -1
                   ELSE
                          x=(h+i*h')%N
                          i=i+1
      WHILE(1)
END;
Time Complexity: \theta(N)
Space Complexity:θ(1)
```

Program for Hash Table Implementation for Collision Resolution using Chaining

```
Search
ALGORITHM HashCollisionResolutionChaining (SparseChain[], N, Key,h)
BEGIN:
      i=1
p=SparseChain[h]
WHILE p!=NULL DO
      IF p→data == key THEN
            RETURN p
      ELSE
            P=p→ Next
RETURN -1
END;
Storage
ALGORITHM HashCollisionResolutionChaining (SparseChain[], N, Key,h)
BEGIN:
p=SparseChain[h]
WHILE p→Next! = NULL DO
      p=p→ Next
q=GetNode(key)
p→Next=q
```

END;

Finding Anagrams: There are two strings. Find out which characters should be deleted such that both strings contain the same characters (May be in different Order)

ALGORITHM Anagrams(str1,str2) BEGIN:

```
Counting[52] = \{0\}
       i=0
       WHILE str1[i]!='\0' DO
              IF str1[i]>='a' AND str1[i]<='z' THEN
                      Counting[str[i]-'a']++
              ELSE
                      IF str1[i]>='A' AND str1[i]<='Z' THEN
                      Counting[str[i]-'A'+26]++
              i++
       i=0
       WHILE str2[j]!='\0' DO
              IF str2[j]>='a' AND str2[j]<='z' THEN
                      IF(Counting[str2[j]-'a'] == 0)
                              WRITE(str2[j])
              IF str2[j]>='A' AND str2[j]<='Z' THEN
                      IF(Counting[str2[j]-'A'+26] == 0)
                              WRITE(str2[j])
              j++
END;
```

Time Complexity: $\theta(M+N)$ Space Complexity: $\theta(C)$

There are some numbers in which some are appearing twice but one is not repeated. Find out the number which appears once.

```
ALGORITHM RepeatedElements(A[],N) BEGIN:
```

```
Maximum = - IntMax

FOR i=0 TO N-1 DO

IF A[i] < Maximum THEN

Maximum = A[i]

C[Maximum] = {0}

FOR i=0 TO N-1 DO

C[A[i]]++

FOR i=0 TO Maximum DO

IF C[i] == 1 THEN

WRITE(C[i])
```

END;

Time Complexity: θ(Maximum+N) Space Complexity:θ(Maximum)

There are two arrays containing some elements. Find out what are the elements which are there in both the arrays what are not.

ALGORITHM RepeatedElements(A[], N, B[], M) BEGIN:

```
Maximum1 = -IntMax
FOR i=0 TO N-1 DO
      IF A[i] < Maximum1 THEN
             Maximum1 = A[i]
CA[Maximum1] = \{0\}
FOR i=0 TO N-1 DO
      CA[A[i]]++
Maximum2 = -IntMax
FOR i=0 TO M-1 DO
      IF B[i] < Maximum2 THEN
             Maximum2 = B[i]
CB[Maximum2] = \{0\}
FOR i=0 TO N-1 DO
      CB[B[i]]++
i=0
WHILE i<= Maximum1 AND i<=Maximum2 DO
      IF CA[i] >0 AND CB[i]>0 THEN
             WRITE(CA[i])
      i++
```

END;

Time Complexity: $\theta(M+N)$

Space Complexity: θ (CA+CB) where CA is the Maximum element of A array and CB is the Maximum size of B array

```
Find out the values of a,b,c,d (a,b,c,d<=1000) for which a^3+b^3=c^3+d^3.
Struct DAT
int a;
int b;
};
ALGORITHM DirectAddressTableApplication()
BEGIN:
      FOR i=0 TO 1000 DO
             FOR j=0 TO 1000 DO
                    Sum=i*i*i+j*j*j
                    DAT[Sum].a=i
                    DAT[Sum].b=j
      FOR c=0 TO 1000 DO
             FOR d=0 TO 1000 DO
                    X=c*c*c+d*d*d
                    WRITE(DAT[X].a)
                    WRITE(DAT[X].b)
```

Time Complexity: $\theta(1000^2)$ Space Complexity: $\theta(1000^2)$

```
Object-Write an ALGORITHM to find length of a string. DOMAIN-String
```

```
ALGORITHM LengthOfString( String str[])
BEGIN:

i = 0

WHILE str[i]!= '\0'

i = i + 1

RETURN i

END;
```

Time Complexity: $\theta(n)$ Space Complexity: $\theta(1)$

```
Object-Write an ALGORITHM to reverse a given string. DOMAIN-String
```

```
ALGORITHM ReverseOfString( String str 1[])
BEGIN:

String str 2[]

L = LengthOf String( str 1[])

i = 0

WHILE L!= '0'

str 2[i]= str 2[L-1]

i = i + 1

L = L - 1

RETURN str 2

END;

Time Complexity: θ(L)
```

Space Complexity:θ(1)

Object-Write an ALGORITHM to find IF the given string is palindrome or not. DOMAIN-String

```
ALGORITHM StringPalindrome( String str[])

BEGIN:

L = Length Of String( str[])

i = 0

WHILE i!= L/2

IF str[i] = str[L-i]

c = c +1

IF c == L/2

RETURN TRUE

ELSE

RETURN FALSE

END;
```

Time Complexity: $\theta(L)$ Space Complexity: $\theta(1)$

Object-Write an ALGORITHM to find number of words in a paragraph. DOMAIN-String

```
ALGORITHM Word Count( String str[])
BEGIN:

c = 0
i = 0
WHILE \ str[i]!='\setminus 0'
IF \ str[i] == " \ "
c = c + 1
RETURN \ c + 1
END;
Time Complexity: \theta(L)
Space Complexity:\theta(1)
```

OBJECT-Write an ALGORITHM to convert all lowercase letters to uppercase letters and vice versa.

```
ALGORITHM conversion(string a[])
BEGIN:

i=0;
WHILE a[i]!='\0' DO

IF a[i]>='a'&&a[i]<='z' THEN

a[i]=a[i]-32;

ELSE IF a[i]>='A'&&a[i]<='Z' THEN

a[i]=a[i]+32;
i++;

END;

TIME COMPLEXITY - Θ (n)
SPACE COMPLEXITY - Θ (n)
```

OBJECT-Write an **ALGORITHM** to find the given word is present in the sentence and at what location.

ALGORITHM wordcheck(string str[], string search[]) BEGIN:

```
count1 = 0, count2 = 0
WHILE str[count1] != '\0' DO
      count1=count1+1
WHILE search[count2] != '\0' DO
     count2=count2+1
FOR i = 0 TO count1 - count2 DO
  FOR j = i TO i + count2 DO
    flag = 1
    IF str[j] != search[j - i] THEN
      flag = 0
      break
  IF flag == 1 THEN
    break
IF flag == 1
  WRITE("SEARCH SUCCESSFUL")
ELSE
  WRITE("SEARCH UNSUCCESSFUL")
```

END;

```
OBJECT-Write an ALGORITHM to sort names in a dictionary order. ALGORITHM sortingofnames(string name[],int n)
```

```
ALGORITHM sortingofnames(string name[],in

BEGIN:

FOR i = 0 TO n DO

strcpy(tname[i], name[i])

FOR i = 0 TO n - 1 DO

FOR j = i + 1 TO n DO

IF strcmp(name[i], name[j]>0) THEN

strcpy(temp, name[i])

strcpy(name[i], name[j])

strcpy(name[j], temp)

RETURN name

END;
```

Experiment No-45

OBJECT-Write an ALGORITHM for reversing all words in a string.

```
ALGORITHM reversingwords(string str[])
BEGIN:
  FOR i = 0 TO str[i] != '\0' DO
    IF str[i] == ' ' THEN
      str1[k][j]='\0'
      k=k+1
      j=0
    ELSE
      str1[k][j]=str[i]
      j=j+1
  str1[k][j] = '\0'
  FOR i = 0 TO k DO
    len = strlen(str1[i])
    FOR j = 0, x = len - 1 TO x STEP+1,STEP-1 DO
      temp = str1[i][j]
      str1[i][j] = str1[i][x]
      str1[i][x] = temp
  RETURN str
END;
```

Write an ALGORITHM for Decimal to Binary Conversion.

```
ALGORITHM Decimal to Binary(n)
BEGIN:

Stack S
Initialize(s)
WHILE n!=0 DO
r=n%2
PUSH(S,r)
n=n/2
WHILE ! Empty (s) DO
X=Pop(s)
Write(x)
END;

Time Complexity- θ(logN)
Space Complexity- θ(N)
```

Write an ALGORITHM for Decimal to octal conversion.

```
ALGORITHM Decimal to Octal(n)
BEGIN:

Stack S
Initialize(s)
WHILE n!=0 DO
r=n%8
PUSH(S,r)
n=n/8
WHILE ! Empty (s) DO
X=Pop(s)
Write(x)
END;

Time Complexity- θ(logN)
Space Complexity- θ(N)
```

Write an ALGORITHM for Decimal to hexadecimal Conversion.

```
ALGORITHM
              Decimal to Hexadecimal(n)
BEGIN:
       Stack S
       Initialize(s)
       WHILE n!=0 DO
              r=n%16
              PUSH(S,r)
              n=n/16
       WHILE ! Empty (s) DO
              X=Pop(s)
            IF(x<10) THEN
              WRITE x
              ELSE
             IF(x==10) THEN
              WRITE A
            IF(x==11) THEN
              WRITE B
            IF(x==12) THEN
              WRITE C
            IF(x==13) THEN
              WRITE D
                IF(x==14) THEN
              WRITE E
            IF(x<15) THEN
              WRITE F
END
Time Complexity- \theta(logN)
Space Complexity- \theta(N)
```

Write an ALGORITHM for Decimal to any base conversion.

```
ALGORITHM Decimal to AnyBase(n,b)
BEGIN:

Stack S
Initialize(s)
WHILE n!=0 DO
r=n%b
PUSH(S,r)
n=n/b
WHILE ! Empty (s) DO
X=Pop(s)
Write(x)
END;

Time Complexity- θ(logN)
Space Complexity- θ(N)
```

Write An ALGORITHM for Stack Primitive Operations.

```
ALGORITHM
                    Initialize stack(Stack S)
Begin:
         S.TOP=-1
End;
Time Complexity- \theta(1)
Space Complexity- \theta(1)
ALGORITHM
                   Push(Stack S,key)
Begin:
        IF S.TOP==SIZE-1 THEN
             WRITE("Stack Overflows")
             EXIT (1)
        S.TOP++
        S.ITEM[S.TOP]=key
End;
Time Complexity- \theta(N), Space Complexity- \theta(1)
ALGORITHM
                   Empty (Stack S)
Begin:
        IF S.TOP==-1 THEN
            RETURN TRUE
        ELSE
            RETURN FALSE
End;
Time Complexity- \theta(1) , Space Complexity- \theta(1)
ALGORITHM
                   Pop (Stack S, key)
 Begin:
        IF EMPTY(S) THEN
            WRITE ("Stack underflows")
            EXIT(1)
     X=S.ITEM[S.TOP]
       S.TOP--
          RETURN X
End;
Time Complexity- \theta(1), Space Complexity- \theta(1)
ALGORITHM
                   STACKTOP (Stack S)
Begin:
        RETURN (S.ITEM[S.TOP])
End;
Time Complexity- \theta(1), Space Complexity- \theta(1)
```

```
OBJECT: To write an ALGORITHM for Evaluation postfix expression.
DOMAIN: STACK
ALGORITHIM POSTFIX EVALUATION (Postfix Expression)
BEGIN:
       STACK OpndStack
      Initialize (OpndStack)
  WHILE not end of input from postfix expression Do
      Symbol = Next character from postfix expression
    IF Symbol is an operand THEN
       push (OpndStack ,symbol)
   ELSE
       oprnd 2=POP (OpndStack)
       oprnd 1=POP(OpndStack)
       value=Result of applying symbol to oprnd1 and oprnd2
      push(OpndStack,value)
  Result = pop(OpndStack)
 RETURN Result
END;
TIME COMPLEXITY- ⊖(N)
```

SPACE COMPLEXITY- $\Theta(N)$

OBJECT: To write an ALGORITHM for infix to postfix conversion.

SPACE COMPLEXITY- Θ(N)

```
DOMAIN: STACK
ALGORITHM
                Infix to postfix (Infix expression)
BEGIN:
          STACK (Opstack)
          Initialize (Opstack)
       WHILE not the end of input from Infix Expression DO
               Symbol = next symbol from Infix Expression
       IF Symbol is an operand THEN
               Add symbol to postfix expression
       ELSE
                       WHILE (! Empty (Opstack) && Prcd (Stack Top(Opstack), Symbol)
                              x=pop (Opstack)
                              Add x to postfix Expresssion
                       IF Symbol = = ')' THEN
                              x = pop(Opstack)
                       ELSE
                       PUSH( Opstack , Symbol)
       PUSH( Opstack ,Symbol)
       WHILE ! Empty(Opstack) DO
               x= pop(Opstack)
               Add x to Postfix Expression
RETURN Postfix Expression
END;
TIME COMPLEXITY- \Theta(N)
```

OBJECT: To write an ALGORITHM for infix to prefix conversion.

```
DOMAIN: STACK
ALGORITHM
                Infix to postfix (Infix expression)
BEGIN:
       Reverse (Infix Expression)
       STACK (Opstack)
       Initialize (Opstack)
       WHILE not the end of Symbol from Infix Expression DO
               Symbol = next symbol from Infix Expression
               IF Symbol is an operand THEN
                      Add symbol to postfix expression
               ELSE
                      WHILE (! Empty (Opstack) && ! Prcd (Symbol, Stack Top(Opstack))
                                      x=pop (Opstack)
                                      Add x to postfix Expresssion
                              IF Symbol = = ')' THEN
                              x = pop(Opstack)
                              ELSE
                              PUSH( Opstack ,Symbol)
                      PUSH( Opstack ,Symbol)
       WHILE ! Empty(Opstack) DO
               x= pop(Opstack)
               Add x to Postfix Expression
       RETURN Reverse (Prefix Expression)
END;
TIME COMPLEXITY- Θ(n2)
SPACE COMPLEXITY- Θ(n)
```

OBJECT: To write an ALGORITHM for prefix evaluation.

```
DOMAIN: STACK
ALGORITHIM PREFIX EVALUATION (Prefix Expression)
BEGIN:
       Reverse (Prefix Expression)
       STACK OpStack
      Initialize (OpStack)
  WHILE not end of input from prefix expression DO
      Symbol = Next character from prefix equation
    IF Symbol is an operand THEN
       push (OpStack ,symbol)
   ELSE
       oprnd 1=push(OpStack)
       oprnd 2=push(OpStack)
       value=Result of applying symbol to oprnd1 and oprnd2
      push(OpStack ,value)
  Result = pop(OpStack)
  RETURN Result
END;
TIME COMPLEXITY- Θ(N)
```

SPACE COMPLEXITY- $\Theta(N)$

OBJECT - Program to check the validity of Paranthesized Arithmetic Expression using Stack. DOMAIN - Stack

```
ALGORITHM
                       Valid Expression (String Exp[])
BEGIN:
               Valid=1
               Stack S
               Initialize S
       WHILE Exp[i] !='$' DO
               IF Exp[i] = = '('THEN)
               PUSH (S,Exp[i])
               ELSE
                       IF Exp[i] = = '('THEN)
                       IF (Empty (S)) THEN
                            Valid=0
                       BREAK
                       ELSE
                          Pop(S)
       j++
               IF valid = =0 THEN
               WRITE("Valid Expression")
               ELSE
               IF Empty(S) THEN
                  WRITE("Valid Expression")
               ELSE
                  WRITE("Invalid Expression")
       END;
TIME COMPLEXITY-⊖(n)
```

SPACE COMPLEXITY-O(n)

OBJECT-Write an ALGORITHM to check IF given number is palindrome using stack. DOMAIN -Stack

```
ALGORITHM palindrome check (str[])
Begin:
       i=0
       Stack S
       Initialize (s)
      WHILE str[i] !='\0' DO
       PUSH (s, str[i])
       j++
       i=0
       WHILE str[i]!='\0' DO
               IF Str[i]==StackTOP(S) THEN
                 POP(s)
               ELSE
                 Break;
       IF Empty (s) THEN
               WRITE ("Palindrome")
       ELSE
               WRITE (" Not Palindrome")
End;
TIME COMPLEXITY - ⊖ (n)
SPACE COMPLEXITY - Θ (n)
```

OBJECT - Write an ALGORITHM to reverse a string using Stack. DOMAIN- Stack

```
ALGORITHM String Reverse(String str[])
Begin:

i=0
Stack S
Initialize (s)
WHILE str[i]!='\0' DO
PUSH (s, str[i])
i++
WHILE ! Empty(s) DO
x=pop(s)
WRITE(x)
End;
TIME COMPLEXITY - Θ(1)
SPACE COMPLEXITY - Θ (1)
```

Q. Write an ALGORITHM to calculate factorial of a number using recursion.

Q. Write an ALGORITHM for tower of Hanoi for n disk.

ALGORITHM TOH(N,S,M,D)

BEGIN:

IF N==1 THEN

Transfer disk from S to D

ELSE

TOH(N-1,S,M,D)

Transfer Disk From S to D

TOH(N-1M,S,D)

End;

Time Complexity: Θ (2ⁿ) Space Complexity: Θ (n)

Q. Write an ALGORITHM to calculate power of a given number using recursion.

```
ALGORITHM POWER(a,b)
BEGIN:

IF b==0 THEN

RETURN 1

ELSE

RETURN a*POWER(a,b-1)
END;

Time Complexity: O(b)
```

Space Complexity: Θ(b)

```
Object: Write an ALGORITHM to calculate power of a given number using divide and Conquer ALGORITHM POWER(a,b)

BEGIN:

IF b == 0 THEN

RETURN 1

ELSE

IF b%2 == 0 THEN

RETURN POWER(a,b/2) * POWER(a,b/2)

ELSE

RETURN a+ POWER(a,b/2) * POWER(a,b/2)
```

Time Complexity: O(log b) Space Complexity: Θ(log b)

Q. Write an ALGORITHM to Calculate n terms of Fibonacci series using recursion.

```
ALGORITHM Fibo(a)

BEGIN:

IF a==1 THEN

RETURN 0

ELSE

IF a==2 THEN

RETURN 1

ELSE

RETURN Fibo(a-1)+Fibo(a-2)

END;

Time Complexity: Θ (2<sup>N</sup>)

Space Complexity: Θ(N)
```

Q. Write an ALGORITHM to calculate HCF of 2 numbers.

```
ALGORITHM HCF(a,b)
BEGIN:

IF a==b THEN

RETURN a

ELSE IF a>b THEN

RETURN HCF(a-b,b)

ELSE

RETURN HCF (a,b-a)
END;
```

Time Complexity: O(log n) Space Complexity: Θ(1)

Q. Write an ALGORITHM to calculate reverse of a number using recursion.

```
ALGORITHM REV (a,len)

BEGIN:

IF len ==1

RETURN a

ELSE

RETURN((a%10)*pow(10,len-1))+REV(a/10,len-1)

END;

Time Complexity: Θ (log n)

Space Complexity: Θ (log n)
```

```
ALGORITHM INTIALIZE(QUEUE Q)
BEGIN:
  Q.REAR=0
  Q.FRONT=1
END;

    ALGORITHM ENQUEUE(QUEUE Q,key)

BEGIN:
IF Q.REAR ==SIZE THEN
      write (Queue overflow)
       Exit 1
    Q.REAR=Q.REAR+1
    Q.item[Q.REAR]=key
END;
• ALGORITHM DEQUEUE(QUEUE Q)
BEGIN:
IF Q.REAR-Q.FRONT+1==0 THEN
       Exit(1)
x=Q.item[Q.FRONT]
Q.FRONT =Q.FRONT +1
RETURN x
END;
ALGORITHM EMPTY(QUEUE Q)
BEGIN:
       IF Q.REAR - Q.FRONT +1 == 0 THEN
             RETURN TRUE
       ELSE
             RETURN FALSE
END;
For all the above ALGORITHM
Time Complexity: Θ (1)
```

Space Complexity: Θ (1)

OBJECT: Program for Array implementation of Circular Queue

```
    ALOGRITHM INTIALIZATION(QUEUE Q)

   BEGIN:
              CQ.REAR=Size-1
              CQ.FRONT=Size-1
   END;

    ALGORITHM ENQUEUE(CQUEUE CQ,KEY)

 BEGIN:
     IF (CQ.REAR+1)%SIZE==CQ.FRONT THEN
         write(Queue overflows)
         Exit(1)
     CQ.REAR=(CQ.REAR+1)%SIZE
     CQ.item[CQ.REAR]=key
END;

    ALGORITHM DEQUEUE(CQUEUE CQ)

 BEGIN:
       IF CQ.REAR==CQ.FRONT
         write( queue overflow)
         Exit(1)
       CQ.FRONT=(CQ.FRONT+1)%Size
       x=CQ.item[CQ.FRONT]
       RETURN(x)
  END;

    ALGORITHM EMPTY(CQUEUE CQ)

BEGIN:
       IF CQ.REAR = CQ.FRONT THEN
              RETURN TRUE
       ELSE
              RETURN FALSE
END;
For all the above ALGORITHM
```

Time Complexity: Θ (1) Space Complexity: Θ (1)

OBJECT: Program for Array implementation of Double Ended Queue

```
• ALGORITHM INSREAR (DQUEUE DQ)
       BEGIN:
              IF(DQ.REAR==SIZE-1) THEN
                  Write(queue overflow)
                  Exit(1)
              ELSE
                     REAR=REAR+1
                     DQ.REAR=item
              IF(REAR=0) THEN:
                     REAR=REAR+1
              IF(FRONT=0) THEN:
                     FRONT= FRONT +1
       END;

    ALGORITHM INSFRONT(DQUEUE DQ)

       BEGIN:
              IF(FRONT<=1) THEN:
                  Write(cannot add item at FRONT end)
                  Exit(1)
              ELSE
                     FRONT=FRONT-1;
                     DQ.FRONT=item
       END;
 ALGORITHM DELFRONT(DQUEUE DQ)
       BEGIN:
              IF(FRONT=0) THEN:
                Write(queue underflow)
                Exit(1)
```

ELSE

```
Item=DQ.FRONT
                     Write(item)
              IF(FRONT=REAR) THEN:
                     FRONT=0
                     REAR=0
              ELSE
                     FRONT=FRONT+!
       RETURN item
       END;

    ALGORITHM DELREAR(DQUEUE DQ)

       BEGIN:
              IF(REAR=0) THEN:
                 Write(cannot delete value at REAR end)
                 Exit(1)
              ELSE
                     Item=DQ.REAR
                     Write(item)
                     IF(FRONT=REAR) THEN:
                            FRONT=0
                            REAR=0
                     ELSE
                           REAR=REAR-1
              RETURN item
       END;
For all the above ALGORITHM
Time Complexity: Θ (1)
```

Space Complexity: Θ (1)

OBJECT: Program for Array implementation of priority Queue

```
ALGORITHM ARRAY INSERTION(pq[],i,key,:*N)
   BEGIN:
       For j=*N-1to i STEP-1 Do
              pq[j+1]=pq[j]
       pq[i]=key
       *N=*N+1
   END;
TIME COMPLEXITY: \Omega (1), O(N)
SPACE COMPLEXITY: (1)
ALGORITHM ARRAYDELETE(pq[],*N,i)
   BEGIN: y=pq[i]
       For j=i+1 to *N-1 Do
              pq[j-1]=pq[j]
       *N=*N-1
       RETURN y
   END;
TIME COMPLEXITY: \Omega (1), O(N)
SPACE COMPLEXITY: \Theta (1)
ALGORITHM ARRAYINSERTION(pq[],*N,key)
  BEGIN:
       i=0
       WHILE i<=*N && key>pq[i]
          i=i+1
       Arrayinsertion(pq,i,key,N)
  END;
ALGORITHM REMOVE (pq[],*N)
  BEGIN:
       x=Arraydelete(pq,N,1)
       RETURN x
  END;
```

Object: Program for 1-D array implementation of Upper Traingular Sparse Matrix ALGORITHM UpperTriangularSparse (Key, i,j,A[],N)
BEGIN:

$$K = (i-1)*((2*N-(i-2))/2 + j - N + 1$$

A[K] = key

END;

Time Complexity: Θ (1) Space Complexity: Θ (1)

Object: Program for 1-D array implementation of Lower Traingular Sparse Matrix
ALGORITHM LowerTriangularSparse (Key, i,j,A[])
BEGIN:
Sparse Matrix

$$K = i*(i-1)/2 + (j-1) + 1$$

A[K] = key

END;

Time Complexity: Θ (1) Space Complexity: Θ (1)

Object: Program for 1-D array implementation of Tridiagonal Sparse Matrix ALGORITHM Tridiagonal Sparse (Key, i,j, A[])
BEGIN:

$$K = 3 * (i - 2) + 2 + (j - i + 1) + 1$$

A[K] = key

END;

Time Complexity: Θ (1) Space Complexity: Θ (1)

```
Program for Vector Representation of General Sparse Matrix Sparse Matrix
Struct Sparse
{
int row;
int column;
int data;
};
Algorithm VectorSparse (S [ ], NoOfNonZeroEle)
BEGIN:
       FOR i=0 TO NoOfNonZeroEle - 1 DO
              READ(rowNo,columnNo,dataElement)
              S[i].row=rowNo
              S[i].column=columnNo
              S[i].data=dataElement
END;
Time Complexity: Θ (1) for each storage element
```

Space Complexity: Θ (1) for each storage element

```
Object: Program For Linked List Implementation of General Sparse Matrix
                                                                       Sparse Matrix
Struct Node
int row;
int column;
int data;
struct node *Next;
};
Algorithm LinkedListSparse (NoOfNonZeroEle)
BEGIN:
       START=NULL
       P=START
       FOR i=0 TO NoOfNonZeroEle - 1 DO
              READ(rowNo,columnNo,dataElement)
              q=GetNode()
              q→row=rowNo
              q→column=columnNo
              q→data=dataElement
              q→Next=NULL
              p->Next=q
              p=q
END;
Time Complexity: Θ (1) for each storage element
```

Space Complexity: Θ (1) for each storage element

```
Sparse Matrix
Program for Addition of two sparse Matrices
ALGORITHM AddSparseMarix(s1[],M,s2[],N)
BEGIN:
       s3[]
       i=1
       j=1
       k=1
       WHILE i<=M AND j<=N DO
               IF s1[i].row == s2[j].row THEN
                      IF s1.column[i] == s2[j].column THEN
                              s3[k].data=s1[i].data+s2[j].data
                              s3[k].row=s1[i].row
                              s3[k].column=s1[i].column
                              i++
                                     j++
                                             k++
                      ELSE
                              IF s1.column[i] < s2[j].column THEN
                                     i++
                              ELSE
                                     j++
               ELSE
                      IF s1[i].row < s2[j].row THEN
                              i++
                      ELSE
                             j++
       WHILE i<=M DO
               s3[k].data=s1[i].data
               s3[k].row=s1[i].row
               s3[k].column=s1[i].column
               i++
                      k++
       WHILE j<=N DO
               s3[k].data=s2[j].data
               s3[k].row=s2[j].row
               s3[k].column=s2[j].column
               j++
                      k++
       RETURN s3
END;
```

OBJECT-Program for Linear Linked List primitive operations

DOMAIN-Linked List

ALGORITHM:

ALGORITHM: InsertBeginning(START,key)

BEGIN: p=getnode()

p->info=key p->next=START

START=p

END;

TIME COMPLEXITY: Θ (1) SAPCE COMPLEXITY: Θ (1)

ALGORITHM: InsertAfter(p,key)

BEGIN: q=getnode()

q->info=key q->next=p->next p->next=q

END;

TIME COMPLEXITY: Θ (1) SAPCE COMPLEXITY: Θ (1)

ALGORITHM: InsertEnd(START,key)
BEGIN: IF START==NULL THEN

InsertBeginning (START,key) p=START

ELSE

P=START

WHILE(p!=NULL) DO q=getnode() q->info=key q->next=NULL p->next=q

END;

TIME COMPLEXITY: Θ (N) SAPCE COMPLEXITY: Θ (1)

ALGORITHM: DelBeg(START)

BEGIN: IF START==NULL THEN

Write("void deletion")

Exit(1)

ELSE

p=START START=p->next

x=p->info RETURN x

TIME COMPLEXITY: Θ (1) SAPCE COMPLEXITY: Θ (1)

ALGORITHM: DelEnd(START)
BEGIN:

p=START q=NULL

WHILE(next(p)!=NULL)

q=p p=p->next q->next=NULL x=p->info

freenode(p) RETURN x

END;

TIME COMPLEXITY: Θ (1) SAPCE COMPLEXITY: Θ (1)

OBJECT-Program for pair wise swapping of elements of Linked List

DOMAIN-Linked List

ALGORITHM:

ALGORITHM PairWiseSwap(START)

BEGIN:

p=START

WHILE(p!=NULL&&p->next!=NULL) DO swap(p->info,p->next->info)

p=p->next->next
traverse(START)

END;

TIME COMPLEXITY: (N)
SPACE COMPLEXITY: (1)

```
OBJECT-Program for printing the elements of Linked List in Reverse Order DOMAIN-Linked List
ALGORITHM:
ALGORITHM ReverseTraversal(START)
BEGIN:

IF p!=NULL THEN

ReverseTraversal (p→next)

WRITE (p→data)

END;

TIME COMPLEXITY: ⊕ (N)
SPACE COMPLEXITY: ⊕ (N)
```

OBJECT-Program for reversing contents of Linear Linked List

DOMAIN:Linked List

ALGORITHM:

ALGORITHM Reverse Linked LIST(START)

BEGIN:

current=START

previous=START->next WHILE(current!=NULL) q=current->next

current->next=previous

previous=current
current=previous

pevious=q

START->next=NULL RETURN START

End;

TIME COMPLEXITY: Θ (N) SPACE COMPLEXITY: Θ (1)

OBJECT- Program for concatenation of linear linked list.

DOMAIN- Linked LIst

ALGORITHM Concatenate(START1,START2)

BEGIN: IF START1==null THEN

RETURN (START2)

ELSE

IF START2==null THEN

RETURN (START1)

ELSE

p=START1

WHILE (p->next != null) do

p=p->next

p->next=START2 RETURN (START1)

END;

TIME COMPLEXITY: **\(\text{O}\)** (N): N is the length of Linked List 1

SPACE COMPLEXITY: Θ (1)

```
OBJECT: Program for Creation of Ascending Order Linked List
DOMAIN:Linked List
ALGORITHM:
ALGORITHM INSERT(START,x)
BEGIN:
       P=NULL
        q = START
              WHILE( q->next != NULL and q->data <= data )
                      P=q
                      q=q->next
              IF p==NULL THEN
                      InsBeg(START,x)
              ELSE
                      InsAft(p, x)
END;
TIME COMPLEXITY: \Omega (1), O(N)
```

SPACE COMPLEXITY: Θ (1)

Experiment 82:

```
Object: Program for merging two Linked Lists
DOMAIN:Linked List
ALGORITHM:
ALGORITHM Merge(list1,list2)
BEGIN:
       p=list1
       q=list2
       WHILE(p!=NULL&&q!=NULL) DO
               IF(info(p)<info(q)) THEN
                      insertend(list3,info(p))
                      p=next(p)
               ELSE
                      insertend(list3,info(q))
                      q=next(q)
       WHILE(p!=NULL) DO
               insertend(list3,info(p))
               p=next(p)
       WHILE(q!=NULL) DO
               insertend(list3,info(q))
               q=next(q)
RETURN list3
END;
Time complexity:O(M+N)
Space complexity:O(M+N)
```

Experiment. 83:

```
Object: Program for Union of two Linked Lists
DOMAIN:Linked List
ALGORITHM:
ALGORITHM Union(START1,START2)
BEGIN:
       START3=NULL
       p=START 1
       q=START2
       WHILE(p!=NULL&&q!=NULL) DO
                IF(info(p)==info(q)) THEN
                      p=next(p)
                      q=next(q)
                ELSE
                        IF(info(p)<info(q)) THEN
                             insertend(START3,info(p))
                             p=next(p)
                        ELSE
                             insertend(START3,info(p))
                             q=next(q)
       WHILE(p!=NULL) DO
              insertend(START3,info(p))
              p=next(p)
       WHILE(q!=NULL)
              insertend(START3,info(q))
              q=next(q)
       RETURN START3
END;
Time complexity:O(M+N)
Space complexity:O(M+N)
```

Object: Program for finding Intersection of two linked list (consider lists as sets)
DOMAIN:Linked List

```
ALGORITHM Intersection(list1,list2)
BEGIN:
        list3=NULL
        p=list1
        q=list2
       WHILE(p!=NULL&&q!=NULL) DO
               IF(info(p) == info(q)) THEN
                       insend(list3,info(p))
                       p=next(p)
                       q=next(q)
                ELSE
                       IF(info(p)<info(q)) THEN</pre>
                               p=next(p)
                       ELSE
                               q=next(q)
END:
Time Complexity:O(M+N)
Space Complexity:O(N): N is the length of first Linked List
```

```
Object: Program for finding difference of two linked list (consider lists as sets)
DOMAIN:Linked List
This finds A – B (A is the first Linked List and B the Second one)
ALGORITHM Difference(list1,list2)
BEGIN:
       list3=NULL
       p=list1
       q=list2
       WHILE(p!=NULL&&q!=NULL) DO
               IF(info(p) == info(q)) THEN
                       p=next(p)
                       q=next(q)
                ELSE
                       IF(info(p)<info(q)) THEN</pre>
                               insend(list3,info(p))
                               p=next(p)
                       ELSE
                               q=next(q)
       WHILE(p!=NULL) DO
                insertend(START3,info(p))
               p=next(p)
       RETURN list3
END:
Time Complexity:O(M+N)
```

Space Complexity:O(N): N is the length of first Linked List

Object:program for sorting of Linked List. DOMAIN:Linked List

```
ALGORITHM: SortingLinked List(START)
Begin: sortingLinked List(START)

p=START
q=NULL
temp=0
WHILE(p->next!=q) DO
IF(p->info>p->next->info)THEN
temp=p->info
p->info=p->next->info
p->next->info=temp
p=p->next
q=p
END;

Space Complexity: Θ(1)
Time complexity: Θ(n)
```

Object: Program for splitting a Linked List. DOMAIN:Linked List

```
ALGORITHM: split(START1)
  p=START1
  START2=NULL
 i=1,j=1
 WHILE(p->next!=NULL) DO
   i=i+1
    p=p->next
  p=START1
  WHILE(p!=NULL)
       IF(j==i/2) THEN
       START2=p->next
   p->next=NULL
   BREAK
  ELSE
       j=j+1
       p=p->next
TIME COMPLEXITY: \Theta (N)
SPACE COMPLEXITY: 0 (1)
```

Object: To Detect if there is any cycle in the linked list. (use two pointers, once moves at a speed of one node, other moves at a speed of two nodes. If they collide with each other it means there is a cycle.

DOMAIN: Linked List

Time complexity: $\Theta(1)$

ALGORITHM:

```
ALGORITHM: CycleDetection(START)
Begin:
       P=START
       Q=START
       WHILE(1) DO
             IF p→Next==NULL THEN
                     RETURN FALSE
             ELSE
                     P=p→Next
             IF q→Next==NULL THEN
                    RETURN FALSE
             ELSE
                     IF q→Next→Next==NULL THEN
                           RETURN FALSE
                     ELSE
                           q=q \rightarrow Next \rightarrow Next
             IF p==q THEN
                     RETURN TRUE
END;
Space Complexity: \Theta(N)
```

Object: Program for polynomial addition using Linked List.

DOMAIN: Linked List

ALGORITHM:

```
ALGORITHM: PolynomialAdditionLinked List(poly1,poly2)
             poly3=NULL
Begin:
             p=poly1
             q=poly2
             WHILE(p!=NULL AND q!=NULL) DO
             IF p->Exp==q->Exp THEN
             InsEnd(poly3,p->coeffi+q->coeffi,p->Exp)
             p=p->next
             q=q->next
       ELSE
             IF p->Exp>q->Exp THEN
             InsEnd(poly3,p->coeffi,p->Exp)
             p=p->next
       ELSE
             InsEnd(poly3,q->coeffi,q->Exp)
             q=q->next
       WHILE p!=NULL DO
             InsEnd(poly3,p->coeffi,p->Exp)
             p=p->next
       WHILE q!=NULL DO
             InsEnd(poly3,q->coeffi,p->Exp)
             q=q->next
       RETURN ploy3
END;
Space Complexity: \Theta(m+n)
Time complexity: \Theta(m+n)
```

OBJECT:Program for primitive operations of Circular Linked List DOMAIN:Linked List ALGORITHM:

ALGORITHM InsertBeginning(START, key)

BEGIN:

```
p=GetNode()

p\rightarrow Info=key

p\rightarrow Next=START

START=p
```

END;

Time Complexity:Θ(1)

The number executed statements are 4 in the above algorithm.

Space Complexity:Θ(1)

An extra variable p is used. Also, the space is allocated in the memory to the new node.

ALGORITHM InsertAfter(p, key)

BEGIN:

```
q=GetNode()

q \rightarrow Info=key

q \rightarrow Next=p \rightarrow Next

p \rightarrow Next=q
```

END;

Time Complexity:Θ(1)

The number executed statements are 4 in the above algorithm.

Space Complexity:⊖(1)

An extra variable **q** is used. Also, the space is allocated in the memory to the new node.

ALGORITHMInsertEnd(START, key)

BEGIN:

```
p=START
```

```
WHILE p!=NULL DO
p=p \rightarrow Next
q = GetNode()
q \rightarrow Info=key
q \rightarrow Next=NULL
p \rightarrow Next=q
```

Time Complexity:⊖(N)

The while loop runs until the end of the linked list is reached. Hence, for a linked list of N items, N+5 statements will be executed

Space Complexity:Θ(1)

Extra variables used here are \mathbf{p} and \mathbf{q} . Also, the space is allocated in the memory to the new node

ALGORITHM DelBeg(START)

BEGIN:

```
p=START
START=START\rightarrowNext
x=p \rightarrow Info
FreeNode(p)
RETURN x
```

END;

Time Complexity:Θ(1)

The above algorithm executes four statements unconditionally

Space Complexity:Θ(1)

Two extra variables, p & x are used

ALGORITHM DeleteEnd(START)

BEGIN:

```
p=START
q=NULL
```

```
WHILE p \rightarrow Next!=NULL DO
q=p
p=p \rightarrow Next
q \rightarrow Next=NULL
x=p \rightarrow Info
FreeNode(p)
RETURN x
```

Time Complexity:⊖(N)

The while loop executes two statements repetitively until the last element is reached. Also, five more statements are executed outside the loop

Space Complexity:Θ(1)

Three extra variables namely p, q & x are utilized

ALGORITHM DeleteAft(p)

BEGIN:

```
IF p = = NULL OR p \rightarrow Next = = NULL THEN

WRITE ("Void Deletion")

EXIT(1)

q=p \rightarrow Next

x=q \rightarrow Info

p \rightarrow Next=q \rightarrow Next

FreeNode(q)

RETURN x
```

END;

Time Complexity:⊖(1)

Here, statements are executed

Space Complexity:Θ(1)

Two extra variables q & x are used apart from the parameters passed

ALGORITHM Traverse(START)

BEGIN:

```
p=START WHILE p!=NULL D WRITE p \rightarrow Info p=p \rightarrow Next
```

Time Complexity:Θ(N)

It takes 2n statement executions by the while loop where n elements are present in the list. Also, one more statement is executed to initialize p

Space Complexity:⊖(1)

p is taken as an extra variable

START1->Next=q START2->Next=p

RETURN (START2)

```
OBJECT:Program for Cocatenation of Circular Linked List
DOMAIN:Linked List
ALGORITHM:
ALGORITHM ConcatList(cList1, cList2)
BEGIN:

IF START1==null THEN
RETURN (START2)
ELSE
IF START2==null THEN
RETURN (START1)
ELSE
p=START1->Next
q=START2->Next
```

END;

Space Complexity: $\Theta(1)$ Time complexity: $\Theta(1)$

```
OBJECT:Program for primitive operations of Doubly Linked List
DOMAIN:Linked List
ALGORITHM:

    ALGORITHM InsertBeg(dSTART,key)

BEGIN:
       p=getnode()
       info(p)=key
       left(p)=NULL
       right(p)=dSTART
       IF(dSTART!=NULL) THEN
                left(dSTART)=p
                dSTART=p
END;
TIME COMPLEXITY: (1)
SPACE COMPLEXITY: (1)

    ALGORITHM Insertend(dSTART,key)

BEGIN:
       p=dSTART
       q=getnode()
       info(q)=key
       IF(dSTART==NULL)THEN
              insertbeg(dSTART,key)
       ELSE
              WHILE(right(p)!=NULL)
                       p=right(p)
                       right(p)=q
                        right(q)=NULL
                        left(q)=p
END;
TIME COMPLEXITY: (N)
SPACE COMPLEXITY: 0 (1)

    ALGORITHM Insertleft(p,key)

BEGIN:
       IF(left(p)==NULL) THEN
              insertbeg(p,key)
       ELSE
                IF(left(p)!=NULL) THEN
                        q=getnode()
                              r=left(p)
                        info(q)=key
                        left(q)=r
                       right(r)=q
                       right(q)=p
                       left(p)=q
```

```
ELSE
               insertbeg(p,key)
END;
TIME COMPLEXITY: \Theta (1)
SPACE COMPLEXITY: \Theta (1)
       • ALGORITHM Insertright(p,key)
BEGIN:
       q=getnode()
       info(q)=key
       r=right(p)
       right(p)=q
       left(q)=p
       IF(right(p)!=NULL) THEN
                right(q)=r
                left(r)=q
       ELSE
               right(q)=NULL
END;
TIME COMPLEXITY: \Theta (1)
SPACE COMPLEXITY: (1)

    ALGORITHM Delbeg(dSTART)

BEGIN:
       IF(dSTART==NULL) THEN
                write("void deletion")
                 exit(1)
       ELSE
               p=dSTART
               dSTART=right(dSTART)
                IF(right(p)!=NULL)THEN
                              left(dSTART)=NULL
                              x=info(p)
                         freenode(p)
         RETURN x
TIME COMPLEXITY: \Theta (1)
SPACE COMPLEXITY: (1)
END;

    ALGORITHM DelEnd(dSTART)

BEGIN:
       IF(dSTART==NULL)
                write("void deletion")
                exit(1)
       ELSE
               p=dSTART
               q=NULL
               WHILE(right(p)!=NULL)DO
```

```
q=p
                       p=right(p)
                       IF(q==NULL) THEN
                   dSTART=NULL
               ELSE
               right(q)=NULL
       x=info(p)
       freenode(p)
       RETURN x
END;
TIME COMPLEXITY: O (N)
SPACE COMPLEXITY: O (1)
       • ALGORITHM DelLeft(p)
BEGIN:
       IF(p==NULL||left(p)==NULL) THEN
                write("void deletion")
                 exit(1)
       ELSE
               q=left(p)
               r=left(q)
               right(r)=p
               right(p)=r
               x=info(q)
               freenode(q)
       RETURN x
END;
TIME COMPLEXITY: \(\theta\) (1)
SPACE COMPLEXITY: 0 (1)
       • ALGORITHM DelRight(p)
BEGIN:
       IF(p==NULL||right(p)==NULL) THEN
                write("void deletion")
                 exit(1)
       ELSE
               q=right(q)
               r=right(q)
               right(p)=r
               left(r)=p
               x=info(q)
               freenode(q)
       RETURN x
END;
TIME COMPLEXITY: \Theta (1)
SPACE COMPLEXITY: 0 (1)
```

ALGORITHM Traverse(dSTART)

BEGIN:

p=dSTART
WHILE(p!=NULL) DO
write(info(p))

p=right(p)

END;

TIME COMPLEXITY: Θ (1) SPACE COMPLEXITY: Θ (1)

OBJECT-Program for primitive operations of Circular Doubly Linked List DOMAIN:Linked List

```
ALGORITHM:

    ALGORITHM InsertEnd

BEGIN:
       p=d.START
       q=getnode()
       IF(d.START==NULL) THEN
               insertbeg()
       ELSE
                right(q)=right(p)
                left(q)=p
                left(p)=q
                info(q)=key
                d.START=q
END;
TIME COMPLEXITY: \(\theta\) (1)
SPACE COMPLEXITY: 0 (1)
       • ALGORITHM DeleteBeginning
BEGIN:
       IF(d.START=NULL) THEN
         write("void deletion")
       ELSE
         p=d.START
         q=right(p)
               left(p)=right(q)
          IF(right(q)!=q) THEN
                      left(right(q))=p
                      x=info(p)
               ELSE
                    d.START=NULL
                      x=info(p)
       RETURN x
       free q
END;
TIME COMPLEXITY: (1)
SPACE COMPLEXITY: 0 (1)
       • ALGORITHM InsertLeft(p,key)
BEGIN:
       IF(p==NULL) THEN
       ELSE
          IF(left(p)==NULL) THEN
               insertbeg()
```

```
ELSE
                               q=getnode()
                               left(q)=left(p)
                               right(q)=p
                               info(q)=key
                               right(left(p))=q
END;
TIME COMPLEXITY: \(\theta\) (1)
SPACE COMPLEXITY: (1)
       • ALGORITHM InsertRight(p,key)
BEGIN:
       IF(p==NULL)
               insertbeg()
       ELSE
                q=getnode()
                 left(q)=p
                 right(q)=right(p)
                 left(right(p))=q
                       right(p)=q
END;
TIME COMPLEXITY: \(\theta\) (1)
SPACE COMPLEXITY: O (1)

    ALGORITHM Traverse(cdSTART)

BEGIN:
       p=cdSTART
       WHILE(p!=NULL) DO
               write(info(p))
               p=right(p)
END;
TIME COMPLEXITY: 0 (1)
SPACE COMPLEXITY: (1)
```

```
OBJECT:Program for linear linked list implementation of Linear Queue
DOMAIN:Linked List
ALGORITHM:
ALGORITHM Initialize(FRONT, REAR)
BEGIN:
       REAR=NULL
       FRONT=NULL
END;
TIME COMPLEXITY: \(\theta\) (1)
SPACE COMPLEXITY: \(\theta\) (1)
ALGORITHM Empty(FRONT)
BEGIN:
       IF(FRONT==NULL) THEN
              RETURN TRUE
ELSE
       RETURN FALSE
END;
TIME COMPLEXITY: \Theta (1)
SPACE COMPLEXITY: (1)
ALGORITHM ENQUEUE(FRONT, REAR, x)
BEGIN:
       IF(REAR==NULL) THEN
                insertbeg(REAR,x)
                      FRONT=REAR
       ELSE
               insertsafter(REAR,x)
                      REAR=REAR(next)
END;
TIME COMPLEXITY: O (1)
SPACE COMPLEXITY: 0 (1)
ALGORITHM Dequeue(FRONT, REAR)
BEGIN:
              IF(FRONT==NULL) THEN
                       write("void deletion")
                        exit(1)
              ELSE
                       x=delbeg(FRONT)
                        IF(FRONT==NULL)
                             REAR=NULL
              RETURN x
END;
TIME COMPLEXITY: \(\theta\) (1)
```

SPACE COMPLEXITY: Θ (1)

ALGORITHM Traverse(FRONT)

BEGIN:

WHILE FRONT!=NULL
write(FRONT(info))
FRONT=FRONT(next)

END;

TIME COMPLEXITY: Θ (1) SPACE COMPLEXITY: Θ (1)

```
OBJECT:Program for linear linked list implementation of Circular Queue
DOMAIN:Linked List
ALGORITHM:
ALGORITHM ENQUEUE(x)
BEGIN:
       q=getnode()
       IF(REAR==NULL) THEN
              q(next)=q
       ELSE
               q(next)=REAR(next)
              REAR(next)=q
        REAR=q
END;
TIME COMPLEXITY: O (1)
SPACE COMPLEXITY: (1)
ALGORITHM Dequeue()
BEGIN:
              IF(REAR==NULL) THEN
                       write("void deletion")
                       exit(1)
              x=REAR.next.data
            IF REAR.next==REAR)
               REAR=NULL
            ELSE
               REAR.next=REAR.next.next
              RETURN x
              END;
TIME COMPLEXITY: \Theta (1)
```

SPACE COMPLEXITY: **(**1)

```
OBJECT:Program for linear linked list implementation of Priority Queue
DOMAIN:Linked List
ALGORITHM:
ALGORITHM INSERT(prn,x)
BEGIN:
       tmp->info = x
       tmp->prn = prn
       IF( FRONT == NULL or prn < FRONT->prn )
              tmp->next = FRONT
              FRONT = tmp
       ELSE
                q = FRONT
              WHILE( q->next != NULL and q->next->prn <= prn )
                      q=q->next
              tmp->next = q->next
              q->next = tmp
END;
TIME COMPLEXITY: \Omega (1), O(N)
SPACE COMPLEXITY: \Theta (1)
ALGORITHM DEL()
BEGIN:
         IF(FRONT == NULL)
              write(Queue Underflow)
                 exit(1)
         ELSE
              tmp = FRONT;
              write(tmp->info);
              FRONT = FRONT->next;
              free(tmp);
END
TIME COMPLEXITY: 6 (1)
SPACE COMPLEXITY: 0 (1)
ALGORITHM DISPLAY()
BEGIN:
       ptr = FRONT;
       IF(FRONT == NULL)
              write(Queue is empty)
       ELSE
                WHILE(ptr != NULL)
                      write(ptr->info)
                      ptr = ptr->next;
END;
TIME COMPLEXITY: \(\theta\) (N)
```

```
OBJECT:Program for linked list implementation of stack DOMAIN:Linked List
```

```
ALGORITHM:
ALGORITHM Initialize(FRONT, REAR)
BEGIN:
  top=NULL
END;
TIME COMPLEXITY: O (1)
SPACE COMPLEXITY: (1)
ALGORITHM:
ALGORITHM Push(top,x)
BEGIN:
       insertbeg(top,x)
END;
ALGORITHM Pop(top)
BEGIN:
       IF(top==NULL) THEN
             write("underflow")
              exit(1)
       ELSE
             x=delbeg(top)
       RETURN x
END;
ALGORITHM Empty(top)
BEGIN:
       IF(top==NULL) THEN
             RETURN TRUE
       ELSE
             RETURN FALSE
END;
ALGORITHM StackTop(top)
BEGIN:
```

RETURN(info(top))

END;

```
OBJECT:Program for recursive creation and traversal of Binary Tree and traversal
DOMAIN:Tree
ALGORITHM:
ALGORITHM PreorderTraversal(root)
BEGIN:
       IF root != NULL THEN
              WRITE(Data(root))
              PreorderTraversal(Left(root))
              PreorderTraversal(Right(root))
END;
TIME COMPLEXITY: (N)
SPACE COMPLEXITY: O (LogN) for balanced trees
ALGORITHM PostorderTraversal(root)
BEGIN:
       IF root != NULL THEN
              PostorderTraversal(Left(root))
              PostorderTraversal(Right(root))
              WRITE(Data(root))
END;
TIME COMPLEXITY: O (N)
SPACE COMPLEXITY: O (LogN) for balanced trees
ALGORITHM InorderTraversal(root)
BEGIN:
       WHILE root != NULL THEN
              InorderTraversal(Left(root))
              WRITE(Data(root))
              InorderTraversal(Right(root))
END;
TIME COMPLEXITY: (N)
SPACE COMPLEXITY: O (LogN) for balanced trees
ALGORITHM CreateTree(tree)
BEGIN:
       WRITE("Whether Left of DATA(tree) exists (1/0)")
       READ(choice)
       IF (choice = = 1) THEN
              WRITE("Input the information of Left node")
              READ(x)
              p \leftarrow MakeNode(x)
```

 $LEFT(tree) \leftarrow p$

```
CreateTree(p)
       WRITE("Whether Right of DATA(tree) exists (1/0)")
       READ(choice)
       IF (choice = = 1) THEN
               WRITE("Input the information of Right node")
               READ(x)
               p \leftarrow MakeNode(x)
               Right(tree) \leftarrow p
               CreateTree(p)
END;
```

Time Complexity: $\Theta(N)$

There are N elements for creating nodes.

Space Complexity: Θ(N)

There are N nodes created

```
Object: Program for creation of Binary Tree and finding its height
DOMAIN:Tree
ALGORITHM:

ALGORITHM HEIGHT(root)
BEGIN:

IF root==NULL THEN

RETURN 0

ELSE

IF Left(root)==NULL AND Right(root)==NULL

RETURN 0

ELSE

RETURN 1+ Max(HEIGHT(Left(root)), Height(Right(root)))
```

END;

TIME COMPLEXITY: Θ (Log N) for balanced Trees. N for Skewed Trees SPACE COMPLEXITY: Θ (1)

```
Object: Program for finding count of nodes having 1 child (N1 Nodes) in a Binary Tree
DOMAIN:Tree
ALGORITHM:

ALGORITHM CountOfN1(root)

BEGIN:

IF tree = = NULL THEN

RETURN 0

ELSE

IF LEFT(tree) == NULL && Right(tree) == NULL THEN

RETURN 0

ELSE

IF LEFT(tree) != NULL && Right(tree) != NULL THEN

RETURN 0

ELSE

IF LEFT(tree) != NULL && Right(tree) != NULL THEN

RETURN CountOfN1(LEFT(tree))+CountOfN1(Right(tree));

ELSE
```

RETURN 1+CountOfN1(LEFT(tree))+CountOfN1(Right(tree))

```
Object: Program for finding count of nodes having 2 child (N<sub>1</sub> Nodes) in a Binary Tree DOMAIN:Tree ALGORITHM:

ALGORITHM CountOfN2(tree)

BEGIN:

IF tree == NULL THEN

RETURN 0

ELSE

IF LEFT(tree) == NULL && Right(tree) == NULL THEN

RETURN 0

ELSE

IF LEFT(tree) != NULL && Right(tree) != NULL THEN

RETURN 1+ CountOfN1(LEFT(tree))+CountOfN1(Right(tree))
```

RETURN CountOfN1(LEFT(tree))+CountOfN1(Right(tree))

ELSE

Object: Program for finding count of Leaf Nodes (No Nodes) in a Binary Tree

DOMAIN:Tree ALGORITHM:

Finding count of nodes having 0 children in Binary Tree

ALGORITHM CountOfN0(root)

BEGIN:

Time Complexity: $\Theta(N)$

Need to reach all the node once for computing height

Space Complexity: $\Omega(\text{Log }_2N)$, O(N)

If the tree is balanced, Call stack will have $\log_2 n + 1$ entries to the maximum at any moment in case the tree is balanced. If the tree is skewed then the call stack can be grow up to n activation records

Object: Program for Finding if the Binary Tree is Complete

DOMAIN:Tree ALGORITHM:

ALGORITHM isComplete (root, index, number_nodes)

BEGIN:

END;

```
IF tree = = NULL THEN

RETURN True;

// If index assigned to current node is more than

// number of nodes in tree, then tree is not complete

IF index >= number_nodes THEN

RETURN False;

// Recursive for Left and Right subtrees

RETURN (isComplete(LEFT(root), 2*index + 1, number_nodes) AND isComplete(Right(root), 2*index + 2, number_nodes))
```

Time Complexity: $\Theta(N)$

Need to reach all the node once for computing height

Space Complexity: $\Omega(\log_2 N)$, O(N)

If the tree is balanced, Call stack will have $\log_2 n + 1$ entries to the maximum at any moment in case the tree is balanced. If the tree is skewed then the call stack can be grow upto n activation records

Object: Program for Level Order Traversal of Binary Tree DOMAIN:Tree

ALGORITHM:

$ALGORITHM\ Level Order Traversal (root)$

BEGIN:

```
Queue Q
Initialize(Q)
Enqueue(root)
WHILE !Empty(Q) DO
x \leftarrow DeQueue(Q)
WRITE(Data(x))
IF LEFT(x) !=NULL THEN
EnQueue(x)
IF Right(x) !=NULL THEN
```

EnQueue(x)

END;

Time Complexity: Θ(N)

Each node is inserted in the queue once and deleted from queue once. Total of 2*N operations of constant time.

Space Complexity: Θ(N)

Queue size is N

Object:Program for finding balancing factor of a node

DOMAIN:Tree

ALGORITHM BalanceFactor(N)

Finding Balancing factor of a node

LH represents the Left height and RH represents right height. LH – RH is the balance Factor of the given node.

ALGORITHM BalanceFactor(N)

BEGIN:

IF Left(N)!=NULL
$$LH \leftarrow 1 + h(Left(N))$$
ELSE
$$LH \leftarrow 0$$
IF Right(N)!=NULL
$$RH \leftarrow 1 + h(Right(N))$$
ELSE
$$RH \leftarrow 0$$
RETURN(LH – RH)

END;

Time Complexity: $\Theta(N)$

Need to reach all the node once for computing height

Space Complexity: $\Omega(\log_2 N)$, O(N)

If the tree is balanced, Call stack will have $\log_2 n + 1$ entries to the maximum at any moment in case the tree is balanced. If the tree is skewed then the call stack can be grow upto n activation records

```
Object:Program for BST Insertion, traversal, Minimum, maximum and Successor operations
DOMAIN: BST
ALGORITHM:
ALGORITHM BST Minimum(Tree)
BEGIN:
       P = Tree
       WHILE Left(P) != NULL Do
               P = Left(P)
               RETURN P
END;
Time Complexity: \Theta(LogN) if Tree is balanced
Space Complexity: \Theta(1)
ALGORITHM BST Maximum(Tree)
BEGIN:
       P = Tree
       WHILE Right(P) != NULL Do
               P = Right(P)
               RETURN P
END;
Time Complexity: \Theta(LogN) if Tree is balanced
Space Complexity: \Theta(1)
ALGORITHM BSTSearch(Tree,key)
BEGIN:
       P = Tree
       WHILE P!=NULL
               IF key == Data(P) THEN
                       RETURN P
               ELSE
                       IF key &It; Data(P) THEN
                       P = Left(P)
               ELSE
                       P = Right(P)
END;
Time Complexity: \Theta(LogN) if Tree is balanced
Space Complexity: \Theta(1)
```

```
ALGORITHM BSTInsert(Tree,key)
BEGIN:
       P = Tree
       Q = Null
       R = MakeNode(key)
       WHILE P!=NULL Do
               IF key < Data(P)
                       Q = P
                       P = Left(P)
               ELSE
                       Q = P
                       P = Right(P)
               IF key &It; Data(Q) THEN
                       Left(Q) = R
                       Father(R) = Q
               ELSE
                       Right(Q) = R
                       Father(R) = Q
END;
Time Complexity: \Theta(LogN) if Tree is balanced
Space Complexity: \Theta(1)
ALGORITHM BSTSuccesor(P)
BEGIN:
       IF Right(P) != NULL THEN
               q = BSTMinimum(Right(P))
               RETURN q
       ELSE
               q = Father(P)
       WHILE q!=NULL AND Right(q)==P Do
               p=q
               q=Father(q)
       RETURN q
END;
Time Complexity: \Theta(LogN) if Tree is balanced
Space Complexity: \Theta(1)
ALGORITHM BSTPredecessor(P)
BEGIN:
       IF Left(P) != NULL THEN
               q = BSTMinimum(Left(P))
```

RETURN q

```
ELSE q = Father(P) WHILE \ q!=NULL \ AND \ Left(q)==P \ Do p=q q=Father(q) RETURN \ q END; Time \ Complexity: \ \Theta(LogN) \ if \ Tree \ is \ balanced Space \ Complexity: \ \Theta(1)
```

```
Object:Program for BST Deletion
DOMAIN: BST
ALGORITHM:
ALGORITHM BSTDelete(p)
BEGIN:
                       IF Left(p)==NULL AND RIGHT(q)==NULL THEN
                              IF IsLeft(p) THEN
                                      Left(Father(p))=NULL
                              ELSE
                                      Right(Father(p))=NULL
                              X=Data(p)
                              FreeNode(p)
                              RETURN X
                       ELSE
                              IF Left(p) == NULL THEN
                                      q=Right(p)
                                      IF IsLeft(p) THEN
                                              Left(Father(p))=q
                                              Father(q)=Father(p)
                                      ELSE
                                              Right(Father(p))=q
                                              Father(q)=Father(p)
                              ELSE
                                      IF Right(p) == NULL THEN
                                                     q=Right(p)
                                              IF IsLeft(p) THEN
                                                     Left(Father(p))=q
                                                     Father(q)=Father(p)
                                              ELSE
                                                     Right(Father(p))=q
                                                     Father(q)=Father(p)
                                              X=Data(p)
                                              FreeNode(p)
                                              RETURN X
                                      ELSE
                                              q=BSTSuccessor(p)
                                              y=BSTDelete(q)
                                              x=Data(p)
                                              Data(p)=y
                                              RETURN
                       Right(Q) = R
                       Father(R) = Q
END;
Time Complexity: \Theta(LogN) if Tree is balanced
Space Complexity: \Theta(1)
```

```
Object:Program for insertion in AVL Tree,Rotations in AVL Tree & traversal operations
DOMAIN:AVL Tree
ALGORITHM:
ALGORITHM RotateRight (x)
BEGIN:
        y=x\rightarrow Left
        z=y\rightarrow Right
        y \rightarrow Right = z
        x \rightarrow Left = z
        RETURN y
END;
Time Complexity: \Theta(1)
Space Complexity: \Theta(1)
ALGORITHM RotateLeft(x)
BEGIN:
        y=x\rightarrow Right
        z=y\rightarrow Left
        y\rightarrow Left=z
        x \rightarrow Right = z
        RETURN y
END;
Time Complexity: \Theta(1)
Space Complexity: \Theta(1)
ALGORITHM LL(T)
BEGIN:
                T=RotateRight(T)
                RETURN T
END;
Time Complexity: \Theta(1)
Space Complexity: \Theta(1)
ALGORITHM RR(T)
BEGIN:
```

T=RotateLeft(T)

```
RETURN T
END;
Time Complexity: \Theta(1)
Space Complexity: Θ(1)
ALGORITHM LR(T)
BEGIN:
               x=T\rightarrow Left
               x=RotateLeft(x)
               T\rightarrow Left=x
               T=RotateRight(T)
               RETURN T
END;
Time Complexity: \Theta(1)
Space Complexity: Θ(1)
ALGORITHM RL(T)
BEGIN:
               x=T\rightarrow Right
               x = RotateRight(x)
               T \rightarrow Right = x
               T=RotateLeft(T)
               RETURN T
END;
Time Complexity: \Theta(1)
Space Complexity: Θ(1)
```

BEGIN: IF N = = NULL THEN N = MakeNode(Key)

ALGORITHM AVLInsertion(N, Key)

```
ELSE
```

IF Key\rightarrowDataTHEN

$$N\rightarrow$$
Left = AVLInsertion(N \rightarrow Left, Key)

IF Balance(N) == 2 THEN

IF Key\rightarrowLeft \rightarrow Data

 $N = LL(N)$

ELSE

 $N = LR(N)$

ELSE

 $N\rightarrow$ Right = AVLInsertion(N \rightarrow Right, Key)

IF Balance(N) == -2 THEN

IF Key > N \rightarrow Left \rightarrow Data

 $N = RR(N)$

ELSE

 $N = RL(N)$

 $N \rightarrow h=Height(N)$

RETURN N

END;

Time Complexity: $\Omega(\text{Log }2\text{N}), \ \text{O(N)}$

Experiment 111:

```
DOMAIN:Graph
ALGORITHM:
ALGORITHM BFS (G, s)
BEGIN:
        QUEUE Q
        Initialize (Q)
        For all u \in V[G] DO
                 \Pi[u] \leftarrow Nil
                 Color[u] \leftarrow White
        EnQueue (Q, s)
        Color[s] \leftarrow Grey
        d[s] \leftarrow 0
        WHILE (!Empty(Q)) Do
                 u \leftarrow DeQueue(Q)Do
                 For each V ε Adj [u]
                         If Color[u] = = White
                                  Color [u] \leftarrow Grey
                                  EnQueue (Q, u)
                                  d[v] \leftarrow d[u]+1
                                  \Pi[u] \leftarrow u
                                  Color[u] \leftarrow Black
                 WRITE (u)
END;
Time Complexity: \Theta(|V|+|E|)
```

Space Complexity: $\Theta(|V|)$

Object:Program for implementation of BFS

Experiment 112:

```
Object:Program for DFS on graph
DOMAIN:Graph
ALGORITHM:
ALGORITHM DFS (G)
BEGIN:
         For all u ε V [G] Do
        Color[u] \leftarrow White
        Time ← 0
        For all u \in V[u] Do
                 IF Color[u] \leftarrow White
                          DFS \leftarrow Visit (u)
END;
ALGORITHM DFS-VISIT (U)
BEGIN:
        Color[u] \leftarrow Grey
        S[u] \leftarrow Time+1
        For all V \epsilon Adj [U] Do
                 IF Color [V] \leftarrow White
                          \Pi[V] \leftarrow U
                          DFS \leftarrow Visit [V]
                          Color\left[U\right] \leftarrow Black
                          F[U] \leftarrow Time{+}1
                          Time ← Time+1
END;
Time Complexity: \Theta(|V|+|E|)
Space Complexity: \Theta(|V|)
```

Object:Program for All pairs Shortest Path using Flloyd-Warshall ALGORITHM DOMAIN:Graph ALGORITHM:

ALGORITHM APSPFloydWarshall (W[][], N)

BEGIN:

FOR i
$$\leftarrow$$
 1 To N DO
FOR i \leftarrow 1 To N DO
IF W [i] [j] = = 0
IF i != j THEN
W [i] [j]= ∞
FOR k \leftarrow 1 To N DO
FOR i \leftarrow 1 To N DO
FOR j \leftarrow 1 To N DO
W [i] [j] \leftarrow Min (W [i] [j], W [i] [k]+ W [k] [j])

END;

Time Complexity: $\Theta(N^3)$ Space Complexity: $\Theta(1)$

```
Object:Program for Dijikistra ALGORITHM DOMAIN:Graph ALGORITHM:
```

ALGORITHM SSSPDijkstra (G , W [] [], S)

BEGIN:

```
Priority Queue PQ

Initialize (PQ)

For all U \in V [G] DO

D[U] \leftarrow \infty
\Pi[U] \leftarrow NIL
PQ \text{ Insert (PQ, U)}
D[S] \leftarrow 0

WHILE! Empty (PQ) DO

U \leftarrow \text{ExtractMin(PQ)}
For All V \in Adj [U] \text{ AND } V \in PQ
IF d[V] < d[U] + W [U][V]
d[V] \leftarrow d[U] + W [U][V]
\Pi[V] \leftarrow U
```

END;

Time Complexity: O(|E|+|V|Log|V|)

Object:Program for Warshall's ALGORITHM for Transitive Closure DOMAIN:Graph

```
ALGORITHM TransitiveClosureWarshall ( A[ ][ ], N)
```

BEGIN:

FOR k
$$\leftarrow$$
 1 To N Do
FOR J \leftarrow 1 To N DO
FOR j \leftarrow 1 To N DO
A [i] [j] \leftarrow A [i] [j] | (A [i] [k] & A [k] [j])

END;

Time Complexity: $\Theta(N^3)$ Space Complexity: $\Theta(1)$

Alternate Method

ALGORITHM TransitiveClosure(A[][], N)

BEGIN:

END;

Object:Program for Prim's ALGORITHM for Minimal Spanning Tree DOMAIN:Graph ALGORITHM:

ALGORITHM MST Prims (G, W[][], R) BEGIN:

Priority Queue PQ

For all
$$U \in V[G]$$
 Do

 $Key[U] \leftarrow \infty$
 $\Pi[U] \leftarrow NIL$

PQ Insert (PQ, U)

 $Key[R] \leftarrow 0$

WHILE !Empty(PQ) Do

 $U \leftarrow ExtarctMin (PQ)$

For all $V \in Adj[U]$ AND $V \in PQ$ DO

 $IF W[U][V] < Key[V]$ DO

 $Key[V] \leftarrow W[V][U]$
 $\Pi[U] \leftarrow U$

END;

Time Complexity: O(|E|+|V|Log |V|)

```
Object: Program for Kruskal's ALGORITHM for Minimal Spanning Tree
DOMAIN:Graph
ALGORITHM:
ALGORITHM MST- Kruskal (G, W[][])
BEGIN:
       Sort all Edges In E According To their Weights
       Set of Edges of MST E'\leftarrow \emptyset
       For all U \epsilon V [G] DO
               MakeSet (U)
       For Each Edge(U , V) \epsilon E [G] DO
               IF FindSet (U)! = FindSet (V)
                       Union(U, V)
                       Select(U, V) In E'
       RETURN E'
END;
Time Complexity: O(|E|+|V|Log |V|)
```

```
Object: Program for topological sorting of given graph
DOMAIN:Graph
ALGORITHM:
ALGORITHM Topological Sort (G, Indeg [])
BEGIN:
       Queue Q
      Initialize (Q)
      FOR All U ε V [G]
              IF Indeg [U] = 0
                     Enqueue (Q, U)
       WHILE! Empty (Q) DO
              U \leftarrow Dequeue(Q)
              WRITE (U)
      FOR All V ε Adj [U] DO
              IF Indeg [V] = 0
              Enqueue (Q, U)
END;
Time Complexity: \Theta(|V|+|E|)
```