True Label	Predicted		n Attribution Score	Word Importance
high	high (0.75)	high	2.26	#s propeller fell off. motor idle . check whether propellers are installed #/s
high	low (0.77)	high	2.44	#s another aircraft is nearby . another aircraft is approaching . descend as soon as possible $#/s$
high	high (0.74)	high	0.93	#s downward sensor error . aircraft unstable at low altitude . please fly with caution #/s
high	high (0.78)	high	1.90	#s aircraft in restricted zone . unable to take off . check map to find recommended zones #/s
high	low (0.78)	high	-1.39	#s error : course angle control error . please ensure the propellers are installed on the correct motors $#/s$
high	medium (0.77)	high	0.29	# s battery not installed properly . return to home immediately . check and re - install battery $#/s$
high	low (0.71)	high	0.20	#s motor nnn propeller detached or installed incorrectly #/s
high	low (0.70)	high	1.94	#s a passenger aircraft is approaching. descend as soon as possible #/s
low	low (0.71)	high	2.20	#s braking now! no use to move the stick right . avoid the obstacle #/s
low	low (0.73)	high	0.03	#s remote controller signal weak . adjust remote controller antennas #/s
low	low (0.70)	high	-1.30	#s gimbal pitch limit reached . #/s
low	low (0.80)	high	-0.36	#s extra payload detected . return aircraft to an area nearby the home point promptly and fly in a wind - free environment to ensure flight safety $#/s$
low	low (0.71)	high	1.60	#s target lost . quickshots stopped #/s
low	low (0.79)	high	1.16	$\#$ s compass $\frac{1}{2}$ error. ensure there are no metal or magnetic objects near the aircraft and calibrate it before use $\#$ s
low	low (0.77)	high	1.78	$\#s \ camera \ ream \\ \hline {\color{red} \textbf{not}} \ connected \ . \ image \ quality \ affected \ . \ contact \ dji \ support \ for \ assistance \ \#/s$
low	low (0.74)	high	2.10	#s cannot track subject : no image . please retry #/s
low	low (0.77)	high	-1.48	#s compass error . compass data error . please contact dji support . compass disconnected $#/s$
low	low (0.75)	high	-1.20	#s altitude less than nnn . cannot enable follow me mode $#/s$
low	low (0.70)	high	1.26	#s obstacle avoidance disabled . fly with caution #/s
low	low (0.79)	high	1.24	#s failed to take off. check the usb connection with aircraft . contact dji support if this error persists after restarting $#/s$
low	low (0.68)	high	1.88	#s camera busy, cannot enter playback #/s
low	low (0.73)	high	-0.69	#s subject too large . move away and retry #/s
low	low (0.70)	high	0.82	#s gimbal roll limit reached . #/s
low	low (0.76)	high	2.46	#s forward obstacle sensing is not functioning. ambient light is too weak #/s

	1			
low	low (0.70)	high	-0.96	#s cannot track subject . cannot identify subject #/s
low	normal (0.30)	high	0.58	#s activetrack flight paused #/s
low	medium (0.52)	high	2.27	#s cannot takeoff in travel mode . exit travel mode . #/s
low	low (0.70)	high	-1.46	#s capture failed cannot enter pano mode #/s
low	low (0.73)	high	1.75	#s compass error . magnetic filed interference . exit p - gps mode #/s
low	low (0.72)	high	1.90	#s strong interference now . fly with caution . #/s
low	low (0.73)	high	1.84	#s compass data error . please contact dji support #/s
low	high (0.52)	high	1.57	#s check whether propellers are installed correctly . if the propellers are installed correctly and the aircraft still cannot takeoff, a motor error may exist . contact dji support for assistance #/s
low	medium (0.67)	high	1.61	#s battery nnn requires maintenance #/s
low	low (0.69)	high	-0.44	#s forward obstacle sensing not working . #/s
low	low (0.76)	high	-1.54	#s max flight distance reached . adjust in main controller settings if necessary . $#/s$
low	low (0.80)	high	-0.68	#s mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . $#/s$
low	medium (0.72)	high	-1.74	#s cannot takeoff in a no - fly zone #/s
low	medium (0.72)	high	0.60	#s gps signal weak . hovering unstable . fly with caution #/s
low	low (0.71)	high	-0.89	#s visual positioning inaccurate . fly with caution #/s
low	medium (0.55)	high	2.36	#s $#s$ $#s$ signal weak . $#s$ $#s$ $#s$ $#s$ $#s$ $#s$ $#s$ $#s$
low	low (0.75)	high	0.63	#s no gps signal . unable to hover . fly with caution #/s
low	low (0.74)	high	0.97	#s compass interference . temp max altitude : nnn #/s
low	low (0.76)	high	-0.12	#s cannot track subject : subject too small . get closer and retry #/s
low	low (0.76)	high	-0.44	$\#s$ downward altitude sensor data \overline{error} . please contact dji support for help $\#/s$
low	low (0.77)	high	-1.13	#s camera not calibrated . image quality affected . contact dji support for assistance $#/s$
low	low (0.73)	high	-1.31	#s compass error solution: move away from ground magnetic interference #/s
low	low (0.75)	high	-0.77	#s cannot start self - timer . exposure time is too long #/s
low	low (0.75)	high	-0.92	$\mbox{\#s}$ strong interference detected . be careful when flying long distances . $\mbox{\#/s}$
low	low (0.77)	high	-1.05	#s exit backward forward downward upward sensing system, ambient light is too weak #/s
low	low (0.73)	high	0.67	#s cannot track subject : forward obstacle sensing not responding #/s
low	low (0.67)	high	0.09	#s forward obstacle sensing not responding #/s

	medium			
medium	(0.70)	high	-1.70	#s low battery . recharge promptly #/s
medium	medium (0.76)	high	-2.47	#s aircraft activetrack available at max speed . obstacle avoidance is not available $#/s$
medium	low (0.70)	high	1.06	#s gps position mismatch. #/s
medium	medium (0.77)	high	-1.82	$\# s$ critically low voltage warning $\underline{ land}$ as soon as possible , otherwise the battery will be damaged $\# / s$
medium	low (0.68)	high	1.19	#s aircraft is too far away #/s
medium	medium (0.74)	high	0.92	#s critical low battery . return to home or land promptly #/s
medium	medium (0.62)	high	1.45	#s cache space full #/s
medium	normal (0.20)	high	0.57	#s aircraft will automatically descend in nnn #/s
medium	medium (0.64)	high	1.33	#s forward vision sensor error. contact dji support for assistance #/s
medium	medium (0.76)	high	-1.29	$\mbox{\#s}$ the remaining battery is only enough for \mbox{rth} . return home now . $\mbox{\#/s}$
medium	low (0.76)	high	1.22	#s no gps signal . aircraft unable to hover . fly with caution #/s
medium	medium (0.75)	high	0.19	#s battery alert battery installation error . please check the batteries are inserted correctly #/s
medium	medium (0.74)	high	0.08	#s battery installed incorrectly . detach battery and reinstall it #/s
medium	medium (0.78)	high	-1.23	#s high wind velocity: fly with caution and ensure the aircraft remains within your line of sight #/s
medium	low (0.71)	high	1.63	#s vision sensor error . contact dji support for assistance #/s
medium	medium (0.78)	high	-0.55	$\mbox{\#s}$ approaching nfz or pre - set distance limit of (\mbox{mn}) . \mbox{revise} flight route $\mbox{\#/s}$
medium	medium (0.67)	high	1.89	#s warning: command timeout #/s
medium	medium (0.76)	high	-2.09	#s battery power restricted . aircraft performance decreased to ensure flight safety . return to home promptly $#/s$
medium	medium (0.73)	high	-0.48	#s critically low voltage warning aircraft will be forced to land #/s
medium	medium (0.65)	high	-0.95	#s critical low battery voltage #/s
medium	medium (0.72)	high	1.09	#s cannot enable intelligent flight mode : low battery #/s
medium	normal (0.14)	high	-1.44	#s aircraft exceeded distance limit and has exited hyperlapse mode #/s
medium	medium (0.71)	high	1.67	#s large wind velocity . fly with caution . #/s
medium	medium (0.62)	high	-0.82	#s critical low battery #/s
medium	medium (0.68)	high	1.77	#s critically low power . aircraft is landing #/s
medium	medium (0.72)	high	1.83	#s high wind velocity . fly with caution . #/s
normal	normal (0.20)	high	-0.96	#s data recorder file index is 13. #/s

normal	normal (0.21)	high	-1.37	#s rth altitude: 65ft. #/s
normal	normal (0.20)	high	-2.04	#s data recorder file index is 45 . #/s
normal	normal (0.13)	high	-2.09	#s pano shooting completed . the sky part is filled automatically $#/s$
normal	normal (0.26)	high	-1.28	#s gimbal recenter #/s
normal	normal (0.16)	high	-1.27	#s rth: ascending to rth altitude. #/s
normal	normal (0.27)	high	2.03	#s compass redundancy switch #/s
normal	normal (0.19)	high	-2.04	#s tap fly flight ended landing gear lowered #/s
normal	normal (0.15)	high	-1.71	#s arrived at start point . starting waypoint mission #/s
normal	normal (0.20)	high	-0.92	#s auxiliary bottom light set to automatic mode #/s
normal	normal (0.11)	high	-1.18	#s home point recorded . return - to - home altitude : 98ft #/s
normal	normal (0.16)	high	0.71	#s image transmission recovered . aircraft is returning home . #/s
normal	normal (0.13)	high	-1.11	#s aircraft is in sport mode . exit this mode and try again #/s
normal	normal (0.39)	high	-1.13	#s landing . #/s
normal	low (0.53)	high	1.14	#s motor idle . check whether propellers are installed #/s
normal	normal (0.14)	high	-2.55	#s gimbal nnn pitch axis endpoint reached #/s
normal	normal (0.08)	high	-0.86	#s aircraft is in quickshot mode . ensure your environment is free of potential obstacles . #/s
normal	normal (0.11)	high	-1.48	#s downlink restored (after $0m2.3s$) . #/s
normal	normal (0.11)	high	-1.25	#s fly with caution and ensure the aircraft remains within your line of sight . #/s
normal	normal (0.34)	high	-0.11	#s locating landing point #/s
normal	normal (0.17)	high	1.92	#s aircraft is flying back to the start point #/s
normal	normal (0.21)	high	-1.36	#s ensure control sticks are centered during takeoff #/s
normal	normal (0.17)	high	0.19	#s propulsion output has been limited to ensure battery health . #/s
normal	normal (0.08)	high	-2.29	#s aircraft is close to the home point . initiating return to home will now trigger auto landing . $#/s$
normal	normal (0.15)	high	-1.79	#s entered cruise control mode . press c1 or c2 to exit #/s
normal	normal (0.18)	high	-2.32	#s aircraft flight control obtained by remote controller b #/s
normal	normal (0.19)	high	0.37	#s landing gear raising . home point recorded #/s
normal	normal (0.11)	high	-2.87	#s drag a box around or tap a target on screen . then tap go . $#/s$

normal	normal (0.18)	high	-1.53	#s landing gear lowered . obstacle avoidance disabled . #/s
normal	normal (0.20)	high	1.42	#s data recorder file index is 7. #/s
normal	normal (0.20)	high	1.31	#s aircraft is returning to the starting point #/s
normal	normal (0.14)	high	-1.25	#s landing gear lowered . obstacle avoidance has been disabled . #/s
normal	normal (0.24)	high	-0.31	#s rth: heading alignment. #/s
normal	normal (0.14)	high	-0.95	#s switched to t (tripod) - mode. #/s
normal	normal (0.26)	high	-1.84	#s apas has been enabled #/s
normal	normal (0.20)	high	-0.87	#s data recorder file index is 3. #/s
normal	normal (0.20)	high	-2.19	#s rtk base station data not received #/s
normal	normal (0.09)	high	0.64	$\#s$ payload mode enabled . max altitude set to nnn \mbox{and} max distance set to nnn to ensure flight safety $\#/s$
normal	normal (0.12)	high	-0.63	#s during smart track, you can control lens zoom within a certain limit #/s
normal	normal (0.34)	high	-1.67	#s api automatic takeoff#/s