Legend: □ N	legati	ive	Ne	eutra	al 🗖	Pos	sitive
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True Label	Predicted		n Attribution Score	Word Importance
high	high (0.75)	low	1.31	#s propeller fell off. motor idle . check whether propellers are installed #/s
high	low (0.77)	low	2.59	$\#s$ another aircraft is $\frac{\ }{\ }$ another aircraft is $\frac{\ }{\ }$ approaching . descend as soon as possible $\#/s$
high	high (0.74)	low	-1.96	$\#s$ downward sensor $\overline{error}$ . aircraft unstable at low altitude . please fly with caution $\#/s$
high	high (0.78)	low	1.18	#s aircraft in restricted zone . unable to take off . check map to find recommended zones #/s
high	low (0.78)	low	0.71	$\#s$ $\overline{\text{error}}$ : course angle control $\overline{\text{error}}$ . please ensure the propellers are installed on the correct motors $\#/s$
high	medium (0.77)	low	-0.37	# s battery not installed properly . return to home immediately . check and re - install battery $# / s$
high	low (0.71)	low	1.59	#s motor nnn propeller detached or installed incorrectly #/s
high	low (0.70)	low	1.79	$\#$ s a passenger aircraft is approaching . $\frac{descend}{descend}$ as soon as possible $\#$ /s
low	low (0.71)	low	2.89	#s braking now! no use to move the stick right . avoid the obstacle #/s
low	low (0.73)	low	1.68	#s remote controller signal weak . adjust remote controller antennas #/s
low	low (0.70)	low	-1.33	#s gimbal pitch limit reached . #/s
low	low (0.80)	low	1.79	#s extra payload detected . return aircraft to an area nearby the home point promptly and fly in a wind - free environment to ensure flight safety #/s
low	low (0.71)	low	1.64	#s target lost . quickshots stopped #/s
low	low (0.79)	low	1.84	#s compass error. ensure there are no metal or magnetic objects near the aircraft and calibrate it before use #/s
low	low (0.77)	low	1.77	$\#s\ camera\ rcam \\ \hline {\color{red} \textbf{not}\ connected}\ .\ image\ quality\ affected}\ .\ contact\ dji\ support\ for\ assistance\ \#/s$
low	low (0.74)	low	1.97	#s cannot track subject : no image . please retry #/s
low	low (0.77)	low	1.52	$\# s$ compass $\underline{\text{error}}$ . compass data $\underline{\text{error}}$ . please contact dji support . compass disconnected $\#/s$
low	low (0.75)	low	-1.22	#s altitude less than nnn . cannot enable follow me mode $#/s$
low	low (0.70)	low	1.16	#s obstacle avoidance disabled . fly with caution #/s
low	low (0.79)	low	1.81	#s failed to take off. check the usb connection with aircraft. contact dji support if this error persists after restarting #/s
low	low (0.68)	low	1.85	#s camera busy, cannot enter playback #/s
low	low (0.73)	low	2.16	#s subject too large. move away and retry #/s
low	low (0.70)	low	0.98	#s gimbal roll limit reached . #/s
low	low (0.76)	low	-0.46	#s forward obstacle sensing is not functioning . ambient light is too weak #/s

low	low (0.70)	low	1.78	#s cannot track subject. cannot identify subject #/s
low	normal (0.30)	low	-0.22	#s activetrack flight paused #/s
low	medium (0.52)	low	1.93	#s cannot takeoff in travel mode . exit travel mode . #/s
low	low (0.70)	low	1.90	#s capture failed cannot enter pano mode #/s
low	low (0.73)	low	1.24	#s compass error. magnetic filed interference . exit p - gps mode #/s
low	low (0.72)	low	1.95	#s strong interference now . fly with caution . #/s
low	low (0.73)	low	0.96	#s compass data error . please contact dji support #/s
low	high (0.52)	low	2.91	#s check whether propellers are installed correctly. if the propellers are installed correctly and the aircraft still cannot takeoff, a motor error may exist. contact dji support for assistance #/s
low	medium (0.67)	low	0.69	#s battery nnn requires maintenance #/s
low	low (0.69)	low	0.13	#s forward obstacle sensing not working. #/s
low	low (0.76)	low	-1.87	#s max flight distance reached . adjust in main controller settings if necessary . $#/s$
low	low (0.80)	low	1.41	#s mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . #/s
low	medium (0.72)	low	-0.74	#s cannot takeoff in a no - fly zone #/s
low	medium (0.72)	low	2.14	#s gps signal weak . hovering unstable . fly with caution #/s
low	low (0.71)	low	0.86	#s visual positioning inaccurate. fly with caution #/s
low	medium (0.55)	low	1.87	#s gps signal weak .
low	low (0.75)	low	1.45	#s no gps signal. unable to hover. fly with caution #/s
low	low (0.74)	low	0.79	#s compass interference . temp max altitude : nnn #/s
low	low (0.76)	low	-0.67	#s cannot track subject : subject too small . get closer and retry #/s
low	low (0.76)	low	0.81	$\#$ s downward altitude sensor data $\frac{\text{error}}{\text{or}}$ . please contact dji support for help $\#$ /s
low	low (0.77)	low	-0.87	#s camera not calibrated . image quality affected . contact dji support for assistance $#/s$
low	low (0.73)	low	-0.06	#s compass error solution: move away from ground magnetic interference #/s
low	low (0.75)	low	0.27	#s cannot start self - timer . exposure time is too long #/s
low	low (0.75)	low	2.18	#s strong interference detected . be careful when flying long distances . $#/s$
low	low	low	2.01	#s exit backward forward downward upward sensing system, ambient light is too weak #/s
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low		low	1.30	#s cannot track subject: forward obstacle sensing not responding #/s

	medium			
medium	(0.70)	low	-1.67	#s low battery . recharge promptly #/s
medium	medium (0.76)	low	-1.61	#s aircraft activetrack available at max speed . obstacle avoidance is not available #/s
medium	low (0.70)	low	2.15	#s gps position mismatch. #/s
medium	medium (0.77)	low	2.44	#s critically low voltage warning land as soon as possible, otherwise the battery will be damaged #/s
medium	low (0.68)	low	2.02	#s aircraft is too far away #/s
medium	medium (0.74)	low	-1.37	#s critical low battery . return to home or land promptly $#/s$
medium	medium (0.62)	low	1.17	#s cache space full #/s
medium	normal (0.20)	low	0.27	#s aircraft will automatically descend in nnn #/s
medium	medium (0.64)	low	0.10	#s forward vision sensor error . contact dji support for assistance #/s
medium	medium (0.76)	low	-0.66	#s the remaining battery is only enough for $#$ th . return home now . $#$ /s
medium	low (0.76)	low	0.64	#s no gps signal . aircraft unable to hover . fly with caution #/s
medium	medium (0.75)	low	0.74	#s battery alert battery installation error. please check the batteries are inserted correctly #/s
medium	medium (0.74)	low	-2.33	#s battery installed incorrectly . detach battery and reinstall it $#/s$
medium	medium (0.78)	low	0.82	#s high wind velocity: fly with caution and ensure the aircraft remains within your line of sight #/s
medium	low (0.71)	low	0.31	#s vision sensor error . contact dji support for assistance #/s
medium	medium (0.78)	low	-1.27	#s approaching nfz or pre - set distance limit of ( $nnn$ ) . revise flight route $#/s$
medium	medium (0.67)	low	1.87	#s warning: command timeout #/s
medium	medium (0.76)	low	-0.09	$\#s$ battery power restricted . aircraft performance $\frac{\text{decreased}}{\text{decreased}}$ to ensure flight safety . return to home promptly $\#/s$
medium	medium (0.73)	low	1.96	#s critically low voltage warning aircraft will be forced to land #/s
medium	medium (0.65)	low	-1.22	#s critical low battery voltage #/s
medium	medium (0.72)	low	0.10	#s cannot enable intelligent flight mode : low battery #/s
medium	normal (0.14)	low	-0.59	#s aircraft exceeded distance limit and has exited hyperlapse mode #/s
medium	medium (0.71)	low	0.06	#s large wind velocity . fly with caution . #/s
medium	medium (0.62)	low	-0.83	#s critical low battery #/s
medium	medium (0.68)	low	1.42	#s critically low power . aircraft is landing #/s
medium	medium (0.72)	low	-0.69	#s high wind velocity . fly with caution . #/s
normal	normal (0.20)	low	-1.70	#s data recorder file index is 13 . #/s

normal	normal (0.21)	low	-1.32	#s rth altitude: 65ft. #/s
normal	normal (0.20)	low	-2.33	#s data recorder file index is 45 . #/s
normal	normal (0.13)	low	-2.16	#s pano shooting completed . the sky part is filled automatically $#/s$
normal	normal (0.26)	low	-1.46	#s gimbal recenter #/s
normal	normal (0.16)	low	-1.23	#s rth: ascending to rth altitude. #/s
normal	normal (0.27)	low	-1.99	#s compass redundancy switch #/s
normal	normal (0.19)	low	0.89	#s tap fly flight ended landing gear lowered #/s
normal	normal (0.15)	low	-2.46	#s arrived at start point . starting waypoint mission #/s
normal	normal (0.20)	low	-1.68	#s auxiliary bottom light set to automatic mode #/s
normal	normal (0.11)	low	-1.55	#s home point recorded . return - to - home altitude : 98ft $#/s$
normal	normal (0.16)	low	-1.86	#s image transmission recovered . aircraft is returning home . #/s
normal	normal (0.13)	low	0.82	#s aircraft is in sport mode . exit this mode and try again #/s
normal	normal (0.39)	low	-1.08	#s landing . #/s
normal	low (0.53)	low	1.06	#s motor idle . check whether propellers are installed #/s
normal	normal (0.14)	low	-1.19	#s gimbal nnn pitch axis endpoint reached #/s
normal	normal (0.08)	low	-3.15	#s aircraft is in quickshot mode . ensure your enviornment is free of potential obstacles . $#/s$
normal	normal (0.11)	low	-1.48	#s downlink restored ( after $0m2$ . $3s$ ) . $#$ /s
normal	normal (0.11)	low	-1.25	#s fly with caution and ensure the aircraft remains within your line of sight . #/s
normal	normal (0.34)	low	-0.09	#s locating landing point #/s
normal	normal (0.17)	low	-2.59	#s aircraft is flying back to the start point #/s
normal	normal (0.21)	low	-1.36	#s ensure control sticks are centered during takeoff #/s
normal	normal (0.17)	low	-2.45	#s propulsion output has been limited to ensure battery health . #/s
normal	normal (0.08)	low	-2.48	#s aircraft is close to the home point . initiating return to home will now trigger auto landing . $#/s$
normal	normal (0.15)	low	0.27	#s entered cruise control mode . press c1 or c2 to exit #/s
normal	normal (0.18)	low	-2.28	#s aircraft flight control obtained by remote controller b #/s
normal	normal (0.19)	low	-2.17	#s landing gear raising . home point recorded #/s
normal	normal (0.11)	low	-2.83	$\mbox{\#s}$ drag a box around or tap a target on screen . then tap go . $\mbox{\#/s}$

normal	normal (0.18)	low	-2.19	#s landing gear lowered . obstacle avoidance disabled . #/s
normal	normal (0.20)	low	1.65	#s data recorder file index is 7. #/s
normal	normal (0.20)	low	-2.09	#s aircraft is returning to the starting point #/s
normal	normal (0.14)	low	-1.83	#s landing gear lowered . obstacle avoidance has been disabled . #/s
normal	normal (0.24)	low	-1.34	#s rth : heading alignment . #/s
normal	normal (0.14)	low	-1.77	#s switched to t (tripod) - mode. #/s
normal	normal (0.26)	low	-1.45	#s apas has been enabled #/s
normal	normal (0.20)	low	-1.44	#s data recorder file index is 3. #/s
normal	normal (0.20)	low	-0.51	#s rtk base station data not received #/s
normal	normal (0.09)	low	0.22	#s payload mode enabled . max altitude set to nnn and max distance set to nnn to ensure flight safety $#/s$
normal	normal (0.12)	low	-0.73	#s during smart track, you can control lens zoom within a certain limit #/s
normal	normal (0.34)	low	-1.86	#s api automatic takeoff#/s