Legend: ☐ Negative ☐ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
high	high (0.75)	normal	-2.26	#s propeller fell off . motor idle . check whether propellers are installed #/s
high	low (0.77)	normal	-2.59	#s another aircraft is nearby . another aircraft is approaching . descend as soon as possible #/s
high	high (0.74)	normal	1.30	#s downward sensor error . aircraft unstable at low altitude . please fly with caution #/s
high	high (0.78)	normal	-1.50	#s aircraft in restricted zone . unable to take off . check map to find recommended zones #/s
high	low (0.78)	normal	0.25	#s error : course angle control error . please ensure the propellers are installed on the correct motors #/s
high	medium (0.77)	normal	-1.55	#s battery not installed properly . return to home immediately . check and re - install battery #/s
high	low (0.71)	normal	-2.32	#s motor nnn propeller detached or installed incorrectly #/s
high	low (0.70)	normal	-2.42	#s a passenger aircraft is approaching . descend as soon as possible #/s
low	low (0.71)	normal	-2.94	#s braking now ! no use to move the stick right . avoid the obstacle #/s
low	low (0.73)	normal	-1.47	#s remote controller signal weak . adjust remote controller antennas #/s
low	low (0.70)	normal	1.29	#s gimbal pitch limit reached . #/s
low	low (0.80)	normal	-1.72	#s extra payload detected . return aircraft to an area nearby the home point promptly and fly in a wind - free environment to ensure flight safety #/s
low	low (0.71)	normal	-1.64	#s target lost . quickshots stopped #/s
low	low (0.79)	normal	-1.76	#s compass error . ensure there are no metal or magnetic objects near the aircraft and calibrate it before use #/s
low	low (0.77)	normal	-2.04	#s camera rcam not connected . image quality affected . contact dji support for assistance #/s
low	low (0.74)	normal	-1.98	#s cannot track subject : no image . please retry #/s
low	low (0.77)	normal	-0.40	#s compass error . compass data error . please contact dji support . compass disconnected #/s
low	low (0.75)	normal	1.16	#s altitude less than nnn . cannot enable follow me mode #/s
low	low (0.70)	normal	-1.21	#s obstacle avoidance disabled . fly with caution #/s
low	low (0.79)	normal	-1.73	#s failed to take off . check the usb connection with aircraft . contact dji support if this error persists after restarting #/s
low	low (0.68)	normal	-1.84	#s camera busy , cannot enter playback #/s
low	low (0.73)	normal	-2.00	#s subject too large . move away and retry #/s
low	low (0.70)	normal	-0.98	#s gimbal roll limit reached . #/s

low	**low (0.76)**	**normal**	**0.46**	#s forward obstacle sensing is not functioning . ambient light is too weak #/s
low	**low (0.70)**	**normal**	**-0.32**	#s cannot track subject . cannot identify subject #/s
low	**normal (0.30)**	**normal**	**-0.90**	#s activetrack flight paused #/s
low	**medium (0.52)**	**normal**	**-2.13**	#s cannot takeoff in travel mode . exit travel mode . #/s
low	**low (0.70)**	**normal**	**-1.87**	#s capture failed cannot enter pano mode #/s
low	**low (0.73)**	**normal**	**-1.33**	#s compass error . magnetic filed interference . exit p - gps mode #/s
low	**low (0.72)**	**normal**	**-1.87**	#s strong interference now . fly with caution . #/s
low	**low (0.73)**	**normal**	**-1.40**	#s compass data error . please contact dji support #/s
low	**high (0.52)**	**normal**	**-3.65**	#s check whether propellers are installed correctly . if the propellers are installed correctly and the aircraft still cannot takeoff , a motor error may exist . contact dji support for assistance #/s
low	**medium (0.67)**	**normal**	**-1.77**	#s battery nnn requires maintenance #/s
low	**low (0.69)**	**normal**	**-0.10**	#s forward obstacle sensing not working . #/s
low	**low (0.76)**	**normal**	**1.61**	#s max flight distance reached . adjust in main controller settings if necessary . #/s
low	**low (0.80)**	**normal**	**-1.19**	#s mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . #/s
low	**medium (0.72)**	**normal**	**-1.83**	#s cannot takeoff in a no - fly zone #/s
low	**medium (0.72)**	**normal**	**-2.52**	#s gps signal weak . hovering unstable . fly with caution #/s
low	**low (0.71)**	**normal**	**-0.73**	#s visual positioning inaccurate . fly with caution #/s
low	**medium (0.55)**	**normal**	**-2.06**	#s gps signal weak . fly with caution . aircraft in altitude zone . max altitude set to nnn #/s
low	**low (0.75)**	**normal**	**-1.57**	#s no gps signal . unable to hover . fly with caution #/s
low	**low (0.74)**	**normal**	**-0.83**	#s compass interference . temp max altitude : nnn #/s
low	**low (0.76)**	**normal**	**0.68**	#s cannot track subject : subject too small . get closer and retry #/s
low	**low (0.76)**	**normal**	**-0.03**	#s downward altitude sensor data error . please contact dji support for help #/s
low	**low (0.77)**	**normal**	**0.95**	#s camera not calibrated . image quality affected . contact dji support for assistance #/s
low	**low (0.73)**	**normal**	**0.28**	#s compass error solution : move away from ground magnetic interference #/s
low	**low (0.75)**	**normal**	**0.30**	#s cannot start self - timer . exposure time is too long #/s
low	**low (0.75)**	**normal**	**-1.55**	#s strong interference detected . be careful when flying long distances . #/s
low	**low (0.77)**	**normal**	**-1.05**	#s exit backward forward downward upward sensing system , ambient light is too weak #/s
low	**low (0.73)**	**normal**	**-1.33**	#s cannot track subject : forward obstacle sensing not responding #/s

low	**low (0.67)**	**normal**	**-1.55**	#s forward obstacle sensing not responding #/s
medium	**medium (0.70)**	**normal**	**1.60**	#s low battery . recharge promptly #/s
medium	**medium (0.76)**	**normal**	**0.35**	#s aircraft activetrack available at max speed . obstacle avoidance is not available #/s
medium	**low (0.70)**	**normal**	**-2.14**	#s gps position mismatch . #/s
medium	**medium (0.77)**	**normal**	**-2.48**	#s critically low voltage warning land as soon as possible , otherwise the battery will be damaged #/s
medium	**low (0.68)**	**normal**	**-2.01**	#s aircraft is too far away #/s
medium	**medium (0.74)**	**normal**	**0.67**	#s critical low battery . return to home or land promptly #/s
medium	**medium (0.62)**	**normal**	**-1.52**	#s cache space full #/s
medium	**normal (0.20)**	**normal**	**-0.51**	#s aircraft will automatically descend in nnn #/s
medium	**medium (0.64)**	**normal**	**-1.42**	#s forward vision sensor error . contact dji support for assistance #/s
medium	**medium (0.76)**	**normal**	**-0.49**	#s the remaining battery is only enough for rth . return home now . #/s
medium	**low (0.76)**	**normal**	**-1.13**	#s no gps signal . aircraft unable to hover . fly with caution #/s
medium	**medium (0.75)**	**normal**	**-1.03**	#s battery alert battery installation error . please check the batteries are inserted correctly #/s
medium	**medium (0.74)**	**normal**	**0.39**	#s battery installed incorrectly . detach battery and reinstall it #/s
medium	**medium (0.78)**	**normal**	**-3.03**	#s high wind velocity : fly with caution and ensure the aircraft remains within your line of sight #/s
medium	**low (0.71)**	**normal**	**-1.30**	#s vision sensor error . contact dji support for assistance #/s
medium	**medium (0.78)**	**normal**	**0.43**	#s approaching nfz or pre - set distance limit of (nnn) . revise flight route #/s
medium	**medium (0.67)**	**normal**	**-1.88**	#s warning : command timeout #/s
medium	**medium (0.76)**	**normal**	**-1.95**	#s battery power restricted . aircraft performance decreased to ensure flight safety . return to home promptly #/s
medium	**medium (0.73)**	**normal**	**-2.10**	#s critically low voltage warning aircraft will be forced to land #/s
medium	**medium (0.65)**	**normal**	**1.08**	#s critical low battery voltage #/s
medium	**medium (0.72)**	**normal**	**-1.20**	#s cannot enable intelligent flight mode : low battery #/s
medium	**normal (0.14)**	**normal**	**1.03**	#s aircraft exceeded distance limit and has exited hyperlapse mode #/s
medium	**medium (0.71)**	**normal**	**-1.57**	#s large wind velocity . fly with caution . #/s
medium	**medium (0.62)**	**normal**	**0.89**	#s critical low battery #/s
medium	**medium (0.68)**	**normal**	**-1.56**	#s critically low power . aircraft is landing #/s
medium	**medium (0.72)**	**normal**	**-1.81**	#s high wind velocity . fly with caution . #/s

normal	**normal (0.20)**	**normal**	**1.55**	#s data recorder file index is 13 . #/s
normal	**normal (0.21)**	**normal**	**1.32**	#s rth altitude : 65ft . #/s
normal	**normal (0.20)**	**normal**	**2.38**	#s data recorder file index is 45 . #/s
normal	**normal (0.13)**	**normal**	**2.28**	#s pano shooting completed . the sky part is filled automatically #/s
normal	**normal (0.26)**	**normal**	**1.71**	#s gimbal recenter #/s
normal	**normal (0.16)**	**normal**	**1.24**	#s rth : ascending to rth altitude . #/s
normal	**normal (0.27)**	**normal**	**1.93**	#s compass redundancy switch #/s
normal	**normal (0.19)**	**normal**	**-0.60**	#s tap fly flight ended landing gear lowered #/s
normal	**normal (0.15)**	**normal**	**2.49**	#s arrived at start point . starting waypoint mission #/s
normal	**normal (0.20)**	**normal**	**1.95**	#s auxiliary bottom light set to automatic mode #/s
normal	**normal (0.11)**	**normal**	**1.50**	#s home point recorded . return - to - home altitude : 98ft #/s
normal	**normal (0.16)**	**normal**	**2.23**	#s image transmission recovered . aircraft is returning home . #/s
normal	**normal (0.13)**	**normal**	**0.19**	#s aircraft is in sport mode . exit this mode and try again #/s
normal	**normal (0.39)**	**normal**	**1.09**	#s landing . #/s
normal	**low (0.53)**	**normal**	**-0.55**	#s motor idle . check whether propellers are installed #/s
normal	**normal (0.14)**	**normal**	**1.40**	#s gimbal nnn pitch axis endpoint reached #/s
normal	**normal (0.08)**	**normal**	**2.89**	#s aircraft is in quickshot mode . ensure your enviornment is free of potential obstacles . #/s
normal	**normal (0.11)**	**normal**	**1.48**	#s downlink restored (after 0m 2 . 3s) . #/s
normal	**normal (0.11)**	**normal**	**1.50**	#s fly with caution and ensure the aircraft remains within your line of sight . #/s
normal	**normal (0.34)**	**normal**	**0.12**	#s locating landing point #/s
normal	**normal (0.17)**	**normal**	**2.54**	#s aircraft is flying back to the start point #/s
normal	**normal (0.21)**	**normal**	**1.36**	#s ensure control sticks are centered during takeoff #/s
normal	**normal (0.17)**	**normal**	**0.72**	#s propulsion output has been limited to ensure battery health . #/s
normal	**normal (0.08)**	**normal**	**2.28**	#s aircraft is close to the home point . initiating return to home will now trigger auto landing . #/s
normal	**normal (0.15)**	**normal**	**-0.09**	#s entered cruise control mode . press c1 or c2 to exit #/s
normal	**normal (0.18)**	**normal**	**2.26**	#s aircraft flight control obtained by remote controller b #/s

normal	**normal (0.19)**	**normal**	**2.11**	#s landing gear raising . home point recorded #/s
normal	**normal (0.11)**	**normal**	**2.82**	#s drag a box around or tap a target on screen . then tap go . #/s
normal	**normal (0.18)**	**normal**	**2.39**	#s landing gear lowered . obstacle avoidance disabled . #/s
normal	**normal (0.20)**	**normal**	**-1.56**	#s data recorder file index is 7 . #/s
normal	**normal (0.20)**	**normal**	**1.96**	#s aircraft is returning to the starting point #/s
normal	**normal (0.14)**	**normal**	**2.21**	#s landing gear lowered . obstacle avoidance has been disabled . #/s
normal	**normal (0.24)**	**normal**	**1.59**	#s rth : heading alignment . #/s
normal	**normal (0.14)**	**normal**	**1.97**	#s switched to t (tripod) - mode . #/s
normal	**normal (0.26)**	**normal**	**1.52**	#s apas has been enabled #/s
normal	**normal (0.20)**	**normal**	**1.31**	#s data recorder file index is 3 . #/s
normal	**normal (0.20)**	**normal**	**0.97**	#s rtk base station data not received #/s
normal	**normal (0.09)**	**normal**	**-0.67**	#s payload mode enabled . max altitude set to nnn and max distance set to nnn to ensure flight safety #/s
normal	**normal (0.12)**	**normal**	**0.65**	#s during smart track , you can control lens zoom within a certain limit #/s
normal	**normal (0.34)**	**normal**	**1.64**	#s api automatic takeoff #/s