

Legend: ■ Negative □ Neutral ■ Positive

| True Label | Predicted Label | Attribution Label | Attribution Score | Word Importance |
|------------------------|-----------------------|------------------------|-------------------|--|
| SurroundingEnvironment | Normal (1.00) | SurroundingEnvironment | 0.35 | [CLS] a passenger aircraft is nearby . |
| | | | | [SEP] |
| | | | | [CLS] fly with caution [SEP] |
| Normal | Normal (1.00) | Normal | 0.90 | |
| Normal | Normal (1.00) | Normal | 0.63 | [CLS] account not logged in . |
| | | | | [SEP] |
| | | | | |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.87 | [CLS] flight altitude and distance restricted to nnn and nnn . |
| | | | | [SEP] |
| | | | | |
| Normal | Normal (1.00) | Normal | 0.53 | [CLS] check and log in |
| | | | | [SEP] |
| | | | | |
| Normal | Normal (1.00) | Normal | 0.98 | [CLS] activetrack flight paused |
| | | | | [SEP] |
| | | | | |
| Normal | Normal (1.00) | Normal | 1.61 | [CLS] aircraft activetrack available at max speed . |
| | | | | [SEP] |
| | | | | |
| Normal | Normal (1.00) | Normal | 0.17 | [CLS] obstacle avoidance is not available |
| | | | | [SEP] |
| | | | | |
| Normal | Normal (1.00) | Normal | 1.61 | [CLS] aircraft activetrack available at max speed . |
| | | | | [SEP] |
| | | | | |
| Normal | Normal (1.00) | Normal | -0.65 | [CLS] when exceeding nnn , obstacle avoidance is not available |
| | | | | [SEP] |
| | | | | [CLS] aircraft |

| | | | | |
|---------------------|----------------------------|---------------------|-------|-----------------|
| Normal | Normal (1.00) | Normal | 0.85 | activetrack |
| | | | | max speed of |
| | | | | nnn and |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.56 | obstacle |
| | | | | avoidance |
| | | | | functions |
| Normal | Normal (1.00) | Normal | 1.21 | normally |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | -1.97 | core board |
| | | | | overheated |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 1.01 | [CLS] aircraft |
| | | | | entered fixed |
| | | | | - wing mode . |
| Normal | Normal (1.00) | Normal | 0.13 | [SEP] |
| | | | | [CLS] current |
| | | | | flight speed is |
| Normal | Normal (1.00) | Normal | 1.37 | nnn . [SEP] |
| | | | | [CLS] press |
| | | | | c2 to exit |
| Normal | Normal (1.00) | Normal | 0.81 | [SEP] |
| | | | | [CLS] aircraft |
| | | | | flight control |
| RegulationViolation | RegulationViolation (1.00) | RegulationViolation | 1.03 | unlocked |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | 1.24 | in restricted |
| | | | | zones . [SEP] |
| | | | | [CLS] check |
| Normal | Normal (1.00) | Normal | 1.39 | map to find |
| | | | | recommended |
| | | | | zones [SEP] |
| Normal | Normal (1.00) | Normal | 1.65 | [CLS] aircraft |
| | | | | is in attitude |
| | | | | mode , so that |
| Normal | Normal (1.00) | Normal | 1.24 | it will not |
| | | | | hover . [SEP] |
| | | | | [CLS] please |
| Normal | Normal (1.00) | Normal | 1.39 | fly with |
| | | | | caution . |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 1.65 | [CLS] aircraft |
| | | | | is in tripod |
| | | | | mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.65 | [CLS] exit |
| | | | | this mode and |
| | | | | try again |

| | | | | |
|---------------------|----------------------------|---------------------|------|-----------------|
| Normal | Normal (1.00) | Normal | 1.62 | [SEP] |
| | | | | [CLS] aircraft |
| | | | | is returning |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 2.08 | to the |
| | | | | starting point |
| | | | | [SEP] |
| RegulationViolation | RegulationViolation (1.00) | RegulationViolation | 2.09 | [CLS] aircraft |
| | | | | out of range |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 1.83 | [CLS] |
| | | | | approaching |
| | | | | a no - fly zone |
| Normal | Normal (1.00) | Normal | 0.90 | . [SEP] |
| | | | | [CLS] rth may |
| | | | | be affected . |
| Normal | Normal (1.00) | Normal | 2.21 | [SEP] |
| | | | | [CLS] fly with |
| | | | | caution [SEP] |
| Normal | Normal (1.00) | Normal | 0.80 | [CLS] arrived |
| | | | | at start point |
| | | | | . [SEP] |
| Normal | Normal (1.00) | Normal | 0.37 | [CLS] starting |
| | | | | waypoint |
| | | | | mission [SEP] |
| Normal | Normal (1.00) | Normal | 0.93 | [CLS] auto |
| | | | | landing |
| | | | | initiated |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.78 | [SEP] |
| | | | | [CLS] |
| | | | | auxiliary |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.79 | bottom light |
| | | | | turned off |
| | | | | [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.68 | [CLS] |
| | | | | backward |
| | | | | obstacle |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.62 | sensing is not |
| | | | | functioning . |
| | | | | [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 2.08 | [CLS] battery |
| | | | | cell broken , |
| | | | | please |
| RegulationViolation | RegulationViolation (1.00) | RegulationViolation | 2.09 | replace the |
| | | | | battery [SEP] |
| | | | | [CLS] battery |
| Normal | Normal (1.00) | Normal | 1.83 | error . [SEP] |
| | | | | [CLS] aircraft |
| | | | | returning to |

| | | | | |
|------------------------|-----------------------|------------------------|------|---|
| Normal | Normal (1.00) | Normal | 0.91 | home automatically [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.97 | [CLS] battery power low . [SEP] |
| Normal | Normal (1.00) | Normal | 1.83 | [CLS] check battery status and charge or warm up battery [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.87 | [CLS] cache space full [SEP] |
| SurroundingEnvironment | SoftwareFault (1.00) | SurroundingEnvironment | 1.02 | [CLS] calibration subject is too close . [SEP] |
| Normal | Normal (1.00) | Normal | 1.32 | [CLS] recalibrate using a subject that is farther away [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.06 | [CLS] camera busy , cannot enter playback [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.01 | [CLS] cannot enable intelligent flight mode [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.72 | [CLS] low battery [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.20 | [CLS] cannot start return to home due to weak gps signal [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.13 | [CLS] cannot start self - timer . [SEP] |
| SoftwareFault | ParamViolation (1.00) | SoftwareFault | 0.04 | [CLS] exposure time is too long [SEP] |

| | | | | |
|------------------------|----------------------|------------------------|------|---|
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.08 | [CLS] cannot switch flight mode . [SEP] |
| Normal | Normal (1.00) | Normal | 2.50 | [CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 0.99 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (1.00) | SurroundingEnvironment | 1.36 | [CLS] no image [SEP] |
| Normal | Normal (1.00) | Normal | 1.06 | [CLS] please retry [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 0.99 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (1.00) | SurroundingEnvironment | 1.99 | [CLS] subject too large [SEP] |
| Normal | Normal (1.00) | Normal | 0.85 | [CLS] move away and retry [SEP] |
| Normal | Normal (1.00) | Normal | 2.14 | [CLS] color display in the liveview has been enhanced . [SEP] |
| Normal | Normal (1.00) | Normal | 2.17 | [CLS] videos and photos will still be shot in d - log mode [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.58 | [CLS] compass abnormal . [SEP] |
| Normal | Normal (1.00) | Normal | 1.16 | [CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft . |

| | | | | |
|------------------------|-------------------------------|------------------------|------|---|
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 1.49 | [CLS] the ground or walls may contain metal . [SEP] |
| Normal | Normal (1.00) | Normal | 1.64 | [CLS] move away from sources of interference before attempting flight . [SEP] |
| Normal | Normal (1.00) | Normal | 1.35 | [CLS] 2 . calibrate compass before takeoff [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.56 | [CLS] compass error [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.06 | [CLS] compass error , calibration required [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.69 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.69 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.45 | [CLS] compass disconnected [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.69 | [CLS] compass error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.34 | [CLS] magnetic field interference . [SEP] |
| Normal | Normal (1.00) | Normal | 0.95 | [CLS] exit p - gps mode [SEP] |

| | | | | |
|---------------|----------------------|---------------|------|--|
| | | | | [CLS] |
| SoftwareFault | SoftwareFault (0.80) | SoftwareFault | 0.78 | compass initialization failed. [SEP] |
| Normal | Normal (1.00) | Normal | 0.50 | [CLS] restart aircraft [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.01 | [CLS] critical low battery. [SEP] |
| Normal | Normal (1.00) | Normal | 1.25 | [CLS] aircraft in auto power off protection . [SEP] |
| Normal | Normal (1.00) | Normal | 1.08 | [CLS] forced landing in progress [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.01 | [CLS] critical low battery. [SEP] |
| Normal | Normal (1.00) | Normal | 0.59 | [CLS] aircraft landing automatically [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.01 | [CLS] critical low battery. [SEP] |
| Normal | Normal (1.00) | Normal | 1.29 | [CLS] return to home or land promptly [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.97 | [CLS] critically low power. [SEP] |
| Normal | Normal (1.00) | Normal | 0.57 | [CLS] aircraft is landing [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.97 | [CLS] critically low power. [SEP] |
| Normal | Normal (1.00) | Normal | 0.14 | [CLS] aircraft landing. [SEP] |
| Normal | Normal (1.00) | Normal | 0.14 | [CLS] aircraft landing. [SEP] |
| | | | | [CLS] throttle up to reduce |

| | | | | |
|---------------|----------------------|---------------|------|--|
| Normal | Normal (1.00) | Normal | 1.92 | the speed of descent and use sticks to avoid obstacles [SEP] [CLS] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.10 | critically low voltage warning . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 1.32 | [CLS] aircraft will be forced to land [SEP] [CLS] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.94 | critically low voltage . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 0.63 | [CLS] aircraft will land [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 0.73 | data recorder file index is 15 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 0.76 | data recorder file index is 17 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 0.80 | data recorder file index is 30 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 0.88 | data recorder file index is 45 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 0.85 | data recorder file index is 46 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 0.83 | data recorder file index is 65 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 1.17 | [CLS] disable sd card read and write |

| | | | | |
|------------------------|----------------------------------|------------------------|-------|--|
| | | | | protection or change card [SEP] |
| CommunicationIssue | CommunicationIssue (1.00) | CommunicationIssue | 1.70 | [CLS] downlink lost . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 1.56 | downlink restored (after 0m 2 . 9s) . [SEP] |
| Normal | Normal (1.00) | Normal | -1.48 | [CLS] drone is vibrating [SEP] |
| Normal | Normal (1.00) | Normal | 1.23 | [CLS] entered cruise control mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.22 | [CLS] press c1 or c2 to exit [SEP] |
| | | | | [CLS] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.56 | excessive attitude angle detected [SEP] |
| | | | | [CLS] forward obstacle |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.70 | avoidance has stopped working [SEP] |
| | | | | [CLS] exit |
| Normal | Normal (1.00) | Normal | 0.47 | backward sensing system [SEP] |
| | | | | [CLS] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.93 | ambient light is too weak [SEP] |
| | | | | [CLS] exited |
| Normal | Normal (1.00) | Normal | 1.01 | visual avoidance system . [SEP] |
| | | | | [CLS] exiting gps mode : unknown error [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.01 | |

| | | | | |
|----------------|-----------------------|----------------|-------|---|
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.80 | [CLS] extra payload detected . [SEP] |
| Normal | Normal (1.00) | Normal | -0.32 | [CLS] flight performance will be affected . [SEP] |
| Normal | Normal (1.00) | Normal | 0.90 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.68 | [CLS] forward obstacle sensing is not functioning . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.72 | [CLS] forward obstacle sensing not responding [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.33 | [CLS] gimbal motor overloaded . [SEP] |
| Normal | Normal (1.00) | Normal | 1.49 | [CLS] check whether gimbal can rotate freely [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.22 | [CLS] gimbal pitch limit reached . [SEP] |
| Normal | Normal (1.00) | Normal | -0.89 | [CLS] ground plain . [SEP] |
| Normal | Normal (1.00) | Normal | 0.83 | [CLS] safe to land . [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.76 | [CLS] high altitude . [SEP] |
| Normal | ParamViolation (1.00) | Normal | -2.60 | [CLS] aircraft braking distance increased and flight time decreased . [SEP] |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| Normal | Normal (1.00) | Normal | 0.90 | [CLS] fly with caution [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.90 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 2.00 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.90 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 2.00 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.90 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 1.94 | [CLS] fly with caution and land in a safe place asap . [SEP] |
| Normal | ParamViolation (1.00) | Normal | -1.74 | [CLS] high - altitude flight [SEP] |
| Normal | Normal (1.00) | Normal | 0.90 | [CLS] fly with caution [SEP] |
| Normal | ParamViolation (1.00) | Normal | -1.73 | [CLS] aircraft braking distance is extended [SEP] |
| Normal | ParamViolation (1.00) | Normal | -2.18 | [CLS] flight time is shortened . [SEP] |
| Normal | Normal (1.00) | Normal | 0.35 | [CLS] home |

| | | | | |
|----------------|-----------------------|----------------|-------|--|
| ParamViolation | ParamViolation (0.44) | ParamViolation | 1.59 | point updated . [SEP] |
| | | | | [CLS] imu attitude restricted . [SEP] |
| | | | | [CLS] ensure aircraft is level [SEP] |
| | | | | [CLS] imu not calibrated . [SEP] |
| Normal | Normal (1.00) | Normal | 0.45 | [CLS] calibrate imu [SEP] |
| SoftwareFault | Normal (1.00) | SoftwareFault | -0.80 | [CLS] landing canceled . [SEP] |
| Normal | Normal (1.00) | Normal | 0.37 | [CLS] landing gear function restored [SEP] |
| Normal | Normal (1.00) | Normal | 0.81 | [CLS] landing gear paused . [SEP] |
| Normal | Normal (1.00) | Normal | 0.73 | [CLS] landing gear raising . [SEP] |
| Normal | Normal (1.00) | Normal | 0.75 | [CLS] landing gear raising . [SEP] |
| Normal | Normal (1.00) | Normal | 0.79 | [CLS] home point recorded [SEP] |
| Normal | Normal (1.00) | Normal | 0.01 | [CLS] live stream video frame rate less than 9hz . [SEP] |
| Normal | ParamViolation (0.98) | Normal | -1.17 | [CLS] fly with caution [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.89 | [CLS] low power . [SEP] |
| Normal | Normal (1.00) | Normal | 1.37 | [CLS] aircraft is returning to the home point . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.89 | [CLS] low power . [SEP] |

| | | | | |
|------------------------|-------------------------------|------------------------|------|--|
| Normal | Normal (1.00) | Normal | 0.18 | [CLS] returning home . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.34 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | 1.17 | [CLS] exit p - gps mode . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.02 | [CLS] yaw error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.99) | SurroundingEnvironment | 1.61 | [CLS] manned aircraft detected nearby . [SEP] |
| Normal | Normal (1.00) | Normal | 0.90 | [CLS] fly with caution [SEP] |
| ParamViolation | ParamViolation (0.99) | ParamViolation | 1.71 | [CLS] max altitude approached . [SEP] |
| Normal | Normal (1.00) | Normal | 1.19 | [CLS] wait for the gps satellite signal recovery before ascend [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 2.06 | [CLS] max flight altitude reached . [SEP] |
| Normal | Normal (1.00) | Normal | 1.09 | [CLS] adjust in main controller settings if necessary [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 2.21 | [CLS] max flight distance reached . [SEP] |
| | | | | [CLS] adjust |

| | | | | |
|----------------|-----------------------|----------------|------|---|
| Normal | Normal (1.00) | Normal | 1.23 | in main controller settings if necessary . [SEP] [CLS] maximum |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 2.19 | flight distance reached . [SEP] [CLS] adjust the distance |
| Normal | Normal (1.00) | Normal | 1.99 | in mc settings if required . [SEP] [CLS] mobile |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 2.15 | device cpu fully loaded . [SEP] [CLS] related |
| Normal | Normal (1.00) | Normal | 1.24 | performance will be affected . [SEP] [CLS] mobile device version too |
| SoftwareFault | Normal (0.98) | SoftwareFault | 0.82 | old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP] [CLS] motor |
| Normal | Normal (1.00) | Normal | 0.80 | is blocked . [SEP] [CLS] motor stuck . [SEP] [CLS] check for objects |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.58 | blocking motor or |
| Normal | Normal (1.00) | Normal | 1.82 | contact dji support for |

| | | | | |
|---------------|----------------------|---------------|-------|--|
| | | | | assistance [SEP] |
| | | | | [CLS] motors started . [SEP] |
| Normal | Normal (1.00) | Normal | 0.15 | |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.25 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (1.00) | Normal | -1.23 | [CLS] aircraft unable to hover . [SEP] |
| Normal | Normal (1.00) | Normal | 0.90 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.25 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (1.00) | Normal | -1.39 | [CLS] unable to hover . [SEP] |
| Normal | Normal (1.00) | Normal | 0.90 | [CLS] fly with caution [SEP] |
| | | | | [CLS] obstacle avoidance disabled . [SEP] |
| | | | | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (1.00) | Normal | 0.70 | |
| Normal | Normal (1.00) | Normal | 0.70 | [CLS] obstacle avoidance disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 0.70 | [CLS] obstacle avoidance disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 0.98 | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (1.00) | Normal | 0.97 | [CLS] obstacle avoidance has been disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 1.17 | [CLS] precision |

| | | | | |
|------------------------|-------------------------------|------------------------|------|--|
| | | | | landing [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 0.93 | quickshot has ended [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 1.76 | recenter gimbal pan [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 0.93 | rectifying aircraft position [SEP] |
| | | | | [CLS] remote controller in high interference environment . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 2.42 | [CLS] |
| | | | | manually adjust flight route or return to home [SEP] |
| Normal | Normal (1.00) | Normal | 1.52 | [CLS] return - to - home altitude : 65ft [SEP] |
| | | | | [CLS] return - to - home altitude : 98ft . [SEP] |
| Normal | Normal (1.00) | Normal | 1.48 | [CLS] return - to - home altitude : 98ft . [SEP] |
| | | | | [CLS] rth : ascending to rth altitude . [SEP] |
| Normal | Normal (1.00) | Normal | 1.52 | [CLS] rth : ascending to rth altitude . [SEP] |
| | | | | [CLS] rth : heading alignment . [SEP] |
| Normal | Normal (1.00) | Normal | 1.30 | [CLS] rth altitude : 65ft . [SEP] |
| | | | | [CLS] rth altitude : 98ft . [SEP] |
| Normal | Normal (1.00) | Normal | 1.04 | [CLS] rth altitude : 98ft . [SEP] |
| | | | | [CLS] signal |
| CommunicationIssue | CommunicationIssue (1.00) | CommunicationIssue | 1.61 | [CLS] signal |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| | | | | lost . [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | 0.86 | returning to home point [SEP] |
| Normal | Normal (1.00) | Normal | 0.85 | [CLS] sprayer turned on [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.84 | [CLS] strong wind warning . [SEP] |
| | | | | [CLS] aircraft unable to return to home automatically . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.21 | [CLS] lower altitude immediately and return to home manually [SEP] |
| Normal | Normal (1.00) | Normal | 1.44 | [CLS] switched to s (sport) - mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.92 | [CLS] switched to t (tripod) - mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.59 | [CLS] take off in p - mode [SEP] |
| Normal | Normal (1.00) | Normal | 1.80 | [CLS] vision sensor error . [SEP] |
| SoftwareFault | HardwareFault (1.00) | SoftwareFault | -0.13 | [CLS] contact dji support for assistance [SEP] |
| Normal | Normal (1.00) | Normal | 1.60 | [CLS] vision systems and obstacle avoidance disabled [SEP] |
| Normal | Normal (1.00) | Normal | 0.87 | |

| | | | | |
|---------------------|----------------------------|---------------------|------|---|
| Normal | Normal (1.00) | Normal | 0.66 | [CLS] waypoint mission paused [SEP] |
| | | | | [CLS] weak gps signal . [SEP] |
| | | | | [CLS] aircraft is in attitude mode and hovering may be unstable . [SEP] |
| | | | | [CLS] fly with caution . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.17 | [CLS] weak signal . [SEP] |
| Normal | Normal (1.00) | Normal | 1.98 | [CLS] aircraft is in attitude mode and hovering may be unstable . [SEP] |
| | | | | [CLS] fly with caution . [SEP] |
| | | | | [CLS] weak signal . [SEP] |
| | | | | [CLS] adjust antennas [SEP] |
| CommunicationIssue | CommunicationIssue (1.00) | CommunicationIssue | 1.56 | [CLS] your aircraft is flying in an altitude zone (nnn) . [SEP] |
| Normal | Normal (1.00) | Normal | 0.62 | [CLS] please fly with caution [SEP] |
| | | | | |
| | | | | |
| | | | | |
| RegulationViolation | RegulationViolation (0.99) | RegulationViolation | 1.90 | |
| Normal | Normal (1.00) | Normal | 0.95 | |
| | | | | |
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