True Label	Predicted Label	Attribution Label	Attribution Score	n Word Importance [CLS] a
SurroundingEnvironment	Normal (1.00)	SurroundingEnvironment	0.35	passenger aircraft is nearby. [SEP]
Normal	Normal (1.00)	Normal	0.90	[CLS] fly wit caution [SEF
Normal	Normal (1.00)	Normal	0.63	[CLS] account not logged in . [SEP]
ParamViolation	ParamViolation (1.00)	ParamViolation	1.87	[CLS] flight altitude and distance restricted to nnn and nnn [SEP]
Normal	Normal (1.00)	Normal	0.53	[CLS] check and log in [SEP]
Normal	Normal (1.00)	Normal	0.98	[CLS] activetrack flight paused [SEP]
Normal	Normal (1.00)	Normal	1.61	[CLS] aircra activetrack available at max speed. [SEP]
Normal	Normal (1.00)	Normal	0.17	[CLS] obstacle avoidance is not available [SEP]
Normal	Normal (1.00)	Normal	1.61	[CLS] aircra activetrack available at max speed. [SEP]
Normal	Normal (1.00)	Normal	-0.65	[CLS] when exceeding nnn, obstact avoidance is not available [SEP]

Normal HardwareFault	Normal (1.00) HardwareFault (1.00)	Normal HardwareFault	0.85 2.56	activetrack max speed of nnn and obstacle avoidance functions normally [SEP] [CLS] aircraft core board overheated
Normal	Normal (1.00)	Normal	1.21	[SEP] [CLS] aircraft entered fixed - wing mode . [SEP]
Normal	Normal (1.00)	Normal	-1.97	[CLS] current flight speed is nnn . [SEP]
Normal	Normal (1.00)	Normal	1.01	[CLS] press c2 to exit [SEP]
Normal	Normal (1.00)	Normal	0.13	[CLS] aircraft flight control unlocked [SEP]
RegulationViolation	Regulation V io lation (1.00)	RegulationViolation	1.37	[CLS] aircraft in restricted zones . [SEP]
Normal	Normal (1.00)	Normal	0.81	[CLS] check map to find recommended zones [SEP]
Normal	Normal (1.00)	Normal	1.03	[CLS] aircraft is in attitude mode, so that it will not hover. [SEP]
Normal	Normal (1.00)	Normal	1.24	[CLS] please fly with caution . [SEP]
Normal	Normal (1.00)	Normal	1.39	[CLS] aircraft is in tripod mode . [SEP]
Normal	Normal (1.00)	Normal	1.65	[CLS] exit this mode and try again

				[SEP]
Normal	Normal (1.00)	Normal	1.62	[CLS] aircraft is returning to the starting point [SEP]
ParamViolation	ParamViolation (1.00)	ParamViolation	2.08	<pre>[CLS] aircraft out of range [SEP]</pre>
RegulationViolation	Regulation V io lation (1.00)	RegulationViolation	2.09	[CLS] approaching a no - fly zone . [SEP]
Normal	Normal (1.00)	Normal	1.83	[CLS] rth may be affected . [SEP]
Normal	Normal (1.00)	Normal	0.90	[CLS] fly with caution [SEP]
Normal	Normal (1.00)	Normal	2.21	[CLS] arrived at start point . [SEP]
Normal	Normal (1.00)	Normal	0.80	[CLS] starting waypoint mission [SEP]
Normal	Normal (1.00)	Normal	0.37	[CLS] auto landing initiated [SEP]
Normal	Normal (1.00)	Normal	0.93	[CLS] auxiliary bottom light turned off [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.78	[CLS] backward obstacle sensing is not functioning. [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.79	[CLS] battery cell broken, please replace the battery [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.68	[CLS] battery error . [SEP] [CLS] aircraft returning to

Normal	Normal (1.00)	Normal	0.91	home automatically [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.97	[CLS] battery power low . [SEP] [CLS] check
Normal	Normal (1.00)	Normal	1.83	battery status and charge or warm up battery [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.87	[CLS] cache space full [SEP]
SurroundingEnvironment	SoftwareFault (1.00)	SurroundingEnvironment	1.02	[CLS] calibration subject is too close. [SEP]
Normal	Normal (1.00)	Normal	1.32	[CLS] recalibrate using a subject that is farther away [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	2.06	[CLS] camera busy, cannot enter playback [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.01	[CLS] cannot enable intelligent flight mode [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.72	[CLS] <mark>low</mark> battery [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.20	[CLS] cannot start return to home due to weak gps signal [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.13	[CLS] cannot start self - timer . [SEP]
SoftwareFault	ParamViolation (1.00)	SoftwareFault	0.04	[CLS] exposure time is too long [SEP]

SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.08	[CLS] cannot switch flight mode . [SEP]
Normal	Normal (1.00)	Normal	2.50	[CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	0.99	[CLS] <mark>cannot</mark> track subject [SEP]
SurroundingEnvironment	SoftwareFault (1.00)	SurroundingEnvironment	1.36	[CLS] <mark>no</mark> image [SEP]
Normal	Normal (1.00)	Normal	1.06	[CLS] please retry [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	0.99	[CLS] <mark>cannot</mark> track subject [SEP]
SurroundingEnvironment	SoftwareFault (1.00)	SurroundingEnvironment	1.99	[CLS] subject too large [SEP]
Normal	Normal (1.00)	Normal	0.85	[CLS] move away and retry [SEP]
Normal	Normal (1.00)	Normal	2.14	[CLS] color display in the liveview has been enhanced. [SEP]
Normal	Normal (1.00)	Normal	2.17	[CLS] videos and photos will still be shot in d - log mode [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.58	[CLS] compass abnormal. [SEP]
Normal	Normal (1.00)	Normal	1.16	solution: 1. ensure there are no magnets or metal objects near the aircraft.

				[SEP]
Normal	Normal (1.00)	Normal	1.49	[CLS] the ground or walls may contain metal . [SEP]
Normal	Normal (1.00)	Normal	1.64	[CLS] move away from sources of interference before attempting flight . [SEP]
Normal	Normal (1.00)	Normal	1.35	[CLS] 2 . calibrate compass before takeoff [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.56	[CLS] compass error [SEP]
HardwareFault	HardwareFault (0.99)	HardwareFault	1.06	[CLS] compass error, calibration required [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.69	[CLS] compass error . [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.69	[CLS] compass error . [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.45	[CLS] compass disconnected [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.69	[CLS] compass error . [SEP]
SurroundingEnvironment	SurroundingEnvironmen (1.00)	^{nt} SurroundingEnvironment	1.34	[CLS] magnetic filed interference. [SEP]
Normal	Normal (1.00)	Normal	0.95	[CLS] exit p - gps mode [SEP]

SoftwareFault	SoftwareFault (0.80)	SoftwareFault	0.78	[CLS] compass initialization failed. [SEP]
Normal	Normal (1.00)	Normal	0.50	[CLS] restart aircraft [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	2.01	[CLS] critical low battery . [SEP]
Normal	Normal (1.00)	Normal	1.25	[CLS] aircraft in auto power off protection . [SEP]
Normal	Normal (1.00)	Normal	1.08	[CLS] forced landing in progress [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	2.01	[CLS] critical low battery . [SEP]
Normal	Normal (1.00)	Normal	0.59	[CLS] aircraft landing automatically [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	2.01	[CLS] critical low battery . [SEP]
Normal	Normal (1.00)	Normal	1.29	[CLS] return to home or land promptly [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.97	[CLS] critically <mark>low</mark> power . [SEP]
Normal	Normal (1.00)	Normal	0.57	<pre>[CLS] aircraft is landing [SEP]</pre>
HardwareFault	HardwareFault (1.00)	HardwareFault	1.97	[CLS] critically <mark>low</mark> power . [SEP]
Normal	Normal (1.00)	Normal	0.14	[CLS] <mark>aircraft</mark> landing . [SEP]
Normal	Normal (1.00)	Normal	0.14	[CLS] aircraftlanding .[SEP][CLS] throttle
				<mark>up to</mark> reduce

Normal	Normal (1.00)	Normal	1.92	the speed of descent and use sticks to avoid obstacles
HardwareFault	HardwareFault (1.00)	HardwareFault	2.10	[CLS] critically low voltage warning . [SEP]
Normal	Normal (1.00)	Normal	1.32	[CLS] aircraft will be forced to land [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.94	[CLS] critically low voltage . [SEP]
Normal	Normal (1.00)	Normal	0.63	[CLS] aircraft will land [SEP]
Normal	Normal (1.00)	Normal	0.73	[CLS] data recorder file index is 15. [SEP]
Normal	Normal (1.00)	Normal	0.76	[CLS] data recorder file index is 17. [SEP]
Normal	Normal (1.00)	Normal	0.80	[CLS] data recorder file index is 30. [SEP]
Normal	Normal (1.00)	Normal	0.88	[CLS] data recorder file index is 45. [SEP]
Normal	Normal (1.00)	Normal	0.85	[CLS] data recorder file index is 46. [SEP]
Normal	Normal (1.00)	Normal	0.83	[CLS] data recorder file index is 65. [SEP]
				[CLS] disable sd card read
Normal	Normal (1.00)	Normal	1.17	and write

				protection or change card [SEP]
CommunicationIssue	CommunicationIssue (1.00)	CommunicationIssue	1.70	[CLS] downlink <mark>lost</mark> . [SEP]
Normal	Normal (1.00)	Normal	1.56	[CLS] downlink restored (
				after 0m 2 . 9s) . [SEP] [CLS] drone
Normal	Normal (1.00)	Normal	-1.48	is vibrating[SEP][CLS] entered
Normal	Normal (1.00)	Normal	1.23	cruise control mode . [SEP] [CLS] press
Normal	Normal (1.00)	Normal	1.22	c1 or c2 to exit [SEP]
ParamViolation	ParamViolation (1.00)	ParamViolation	1.56	[CLS] excessive attitude angle detected [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.70	[CLS] forward obstacle avoidance has stopped working [SEP]
Normal	Normal (1.00)	Normal	0.47	[CLS] exit backward sensing system [SEP]
SurroundingEnvironment	SurroundingEnvironmen (1.00)	^{it} SurroundingEnvironment	1.93	[CLS] ambient light is too weak [SEP]
Normal	Normal (1.00)	Normal	1.01	[CLS] exited visual avoidance system.
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.01	[CLS] exiting gps mode: unknown error [SEP]

ParamViolation	ParamViolation (1.00)	ParamViolation	1.80	[CLS] extra payload detected . [SEP] [CLS] flight
Normal	Normal (1.00)	Normal	-0.32	performance will be affected . [SEP]
Normal	Normal (1.00)	Normal	0.90	[CLS] fly with caution [SEP] [CLS] forward
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.68	obstacle sensing is <mark>not functioning</mark> . [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.72	[CLS] forward obstacle sensing not responding [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	2.33	[CLS] gimbal motor overloaded . [SEP]
Normal	Normal (1.00)	Normal	1.49	[CLS] check whether gimbal can rotate freely [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	2.22	[CLS] gimbal pitch limit reached . [SEP]
Normal	Normal (1.00)	Normal	-0.89	[CLS] <mark>ground</mark> plain . [SEP]
Normal	Normal (1.00)	Normal	0.83	[CLS] safe to land . [SEP]
ParamViolation	ParamViolation (1.00)	ParamViolation	1.76	[CLS] <mark>high</mark> altitude . [SEP]
Normal	ParamViolation (1.00)	Normal	-2.60	[CLS] aircraft braking distance increased and flight time decreased.

Normal	Normal (1.00)	Normal	0.90	[CLS] fly with caution [SEP]
SurroundingEnvironment	SurroundingEnvironment (1.00)	SurroundingEnvironment	1.90	[CLS] high wind velocity . [SEP]
Normal	Normal (1.00)	Normal	2.00	[CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP]
SurroundingEnvironment	SurroundingEnvironment (1.00)	SurroundingEnvironment	1.90	[CLS] high wind velocity . [SEP]
Normal	Normal (1.00)	Normal	2.00	[CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP]
SurroundingEnvironment	SurroundingEnvironment (1.00)	SurroundingEnvironment	1.90	[CLS] high wind velocity . [SEP]
Normal	Normal (1.00)	Normal	1.94	[CLS] fly with caution and land in a safe place asap . [SEP]
Normal	ParamViolation (1.00)	Normal	-1.74	[CLS] high - altitude flight [SEP]
Normal	Normal (1.00)	Normal	0.90	[CLS] fly with caution [SEP]
Normal	ParamViolation (1.00)	Normal	-1.73	[CLS] aircraft braking distance is extended [SEP]
Normal	ParamViolation (1.00)	Normal	-2.18	[CLS] flight time is shortened.
Normal	Normal (1.00)	Normal	0.35	[CLS] home

				<pre>point updated . [SEP]</pre>
ParamViolation	ParamViolation (0.44)	ParamViolation	1.59	[CLS] imu attitude restricted . [SEP]
Normal	Normal (1.00)	Normal	0.45	[CLS] ensure aircraft is level [SEP]
SoftwareFault	Normal (1.00)	SoftwareFault	-0.80	[CLS] imu not calibrated. [SEP]
Normal	Normal (1.00)	Normal	0.37	[CLS] calibrate imu [SEP]
Normal	Normal (1.00)	Normal	0.81	[CLS] landing canceled . [SEP]
Normal	Normal (1.00)	Normal	0.73	[CLS] landing gear function restored
Normal	Normal (1.00)	Normal	0.75	[CLS] landing gear paused.
Normal	Normal (1.00)	Normal	0.79	[CLS] landing gear raising. [SEP]
Normal	Normal (1.00)	Normal	0.01	[CLS] home point recorded [SEP]
Normal	ParamViolation (0.98)	Normal	-1.17	[CLS] live stream video frame rate less than 9hz . [SEP]
Normal	Normal (1.00)	Normal	0.90	[CLS] fly with caution [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.89	[CLS] <mark>low</mark> power . [SEP]
Normal	Normal (1.00)	Normal	1.37	[CLS] aircraft is returning to the home point. [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.89	[CLS] <mark>low</mark> power . [SEP]

Normal	Normal (1.00)	Normal	0.18	[CLS] returning home . [SEP]
SurroundingEnvironment	SurroundingEnvironmen (1.00)	^{nt} SurroundingEnvironment	1.34	[CLS] magnetic filed interference.
Normal	Normal (1.00)	Normal	1.17	<pre>[CLS] exit p - gps mode . [SEP]</pre>
HardwareFault	HardwareFault (1.00)	HardwareFault	2.02	[CLS] <mark>yaw</mark> error . [SEP]
SurroundingEnvironment	SurroundingEnvironmen (0.99)	^{nt} SurroundingEnvironment	1.61	[CLS] manned aircraft detected nearby. [SEP]
Normal	Normal (1.00)	Normal	0.90	[CLS] fly with caution [SEP]
ParamViolation	ParamViolation (0.99)	ParamViolation	1.71	[CLS] max altitude approached. [SEP]
Normal	Normal (1.00)	Normal	1.19	[CLS] wait for the gps satellite signal recovery before ascend [SEP]
ParamViolation	ParamViolation (1.00)	ParamViolation	2.06	[CLS] max flight altitude reached. [SEP]
Normal	Normal (1.00)	Normal	1.09	[CLS] adjust in main controller settings if necessary [SEP]
ParamViolation	ParamViolation (1.00)	ParamViolation	2.21	[CLS] max flight distance reached. [SEP]
				[CLS] adjust

Normal	Normal (1.00)	Normal	1.23	in main controller settings if necessary.
ParamViolation	ParamViolation (1.00)	ParamViolation	2.19	[CLS] maximum flight distance reached. [SEP]
Normal	Normal (1.00)	Normal	1.99	[CLS] adjust the distance in mc settings if required.
HardwareFault	HardwareFault (1.00)	HardwareFault	2.15	[CLS] mobile device cpu fully loaded . [SEP]
Normal	Normal (1.00)	Normal	1.24	[CLS] related performance will be affected.
SoftwareFault	Normal (0.98)	SoftwareFault	0.82	[CLS] mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP]
Normal	Normal (1.00)	Normal	0.80	[CLS] motor is blocked. [SEP]
HardwareFault	HardwareFault (1.00)	HardwareFault	1.58	[CLS] motor stuck . [SEP]
Normal	Normal (1.00)	Normal	1.82	[CLS] check for objects blocking motor or contact dji support for

				assistance [SEP]
Normal	Normal (1.00)	Normal	0.15	[CLS] motors started. [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.25	[CLS] <mark>no gps</mark> signal . [SEP]
Normal	HardwareFault (1.00)	Normal	-1.23	[CLS] aircraft unable to hover . [SEP]
Normal	Normal (1.00)	Normal	0.90	[CLS] fly with caution [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.25	[CLS] <mark>no g</mark> ps signal . [SEP]
Normal	HardwareFault (1.00)	Normal	-1.39	[CLS] unable to hover . [SEP]
Normal	Normal (1.00)	Normal	0.90	[CLS] fly with caution [SEP]
Normal	Normal (1.00)	Normal	0.70	[CLS] obstacle avoidance disabled. [SEP]
Normal	Normal (1.00)	Normal	0.98	[CLS] landing gear lowered . [SEP]
Normal	Normal (1.00)	Normal	0.70	[CLS] obstacle avoidance disabled . [SEP]
Normal	Normal (1.00)	Normal	0.70	[CLS] obstacle avoidance disabled . [SEP]
Normal	Normal (1.00)	Normal	0.98	[CLS] landing gear lowered . [SEP]
Normal	Normal (1.00)	Normal	0.97	[CLS] obstacle avoidance has been disabled . [SEP]
Normal	Normal (1.00)	Normal	1.17	[CLS] precision

Normal	Normal (1.00)	Normal	0.93	landing [SEP] [CLS] quickshot has ended [SEP]
Normal	Normal (1.00)	Normal	1.76	[CLS] recenter gimbal pan [SEP]
Normal	Normal (1.00)	Normal	0.93	[CLS] rectifying aircraft position [SEP]
SurroundingEnvironment	SurroundingEnvironmen (1.00)	^t SurroundingEnvironment	2.42	[CLS] remote controller in high interference environment.
Normal	Normal (1.00)	Normal	1.52	manually adjust flight route or return to home [SEP]
Normal	Normal (1.00)	Normal	1.51	<pre>[CLS] return - to - home altitude : 65ft [SEP]</pre>
Normal	Normal (1.00)	Normal	1.48	[CLS] return - to - home altitude : 98ft . [SEP]
Normal	Normal (1.00)	Normal	1.52	[CLS] rth: ascending to rth altitude. [SEP]
Normal	Normal (1.00)	Normal	1.30	[CLS] rth: heading alignment. [SEP]
Normal	Normal (1.00)	Normal	1.15	[CLS] rth altitude: 65ft . [SEP]
Normal	Normal (1.00)	Normal	1.04	[CLS] rth altitude: 98ft . [SEP]
CommunicationIssue	CommunicationIssue (1.00)	CommunicationIssue	1.61	[CLS] <mark>signal</mark>

Normal Normal	Normal (1.00) Normal (1.00)	Normal Normal	0.86	lost . [SEP] [CLS] aircraft returning to home point [SEP] [CLS] sprayer turned on
SurroundingEnvironment		t SurroundingEnvironment	1.84	[SEP] [CLS] strong wind warning
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.21	. [SEP] [CLS] aircraft unable to return to home automatically . [SEP]
Normal	Normal (1.00)	Normal	1.44	[CLS] lower altitude immediately and return to home manually [SEP]
Normal	Normal (1.00)	Normal	1.92	[CLS] switched to s (sport) - mode . [SEP]
Normal	Normal (1.00)	Normal	1.59	[CLS] switched to t (tripod) - mode . [SEP]
Normal	Normal (1.00)	Normal	1.80	[CLS] take off in p - mode [SEP]
SoftwareFault	HardwareFault (1.00)	SoftwareFault	-0.13	[CLS] vision sensor error [SEP]
Normal	Normal (1.00)	Normal	1.60	[CLS] contact dji support for assistance [SEP]
Normal	Normal (1.00)	Normal	0.87	[CLS] vision systems and obstacle avoidance disabled [SEP]

Normal	Normal (1.00)	Normal	0.66	waypoint mission paused [SEP]
SoftwareFault	SoftwareFault (1.00)	SoftwareFault	1.17	[CLS] weak gps signal . [SEP]
Normal	Normal (1.00)	Normal	1.98	[CLS] aircraft is in attitude mode and hovering may be unstable.
Normal	Normal (1.00)	Normal	1.03	[CLS] fly with caution . [SEP]
CommunicationIssue	CommunicationIssue (1.00)	CommunicationIssue	1.56	[CLS] <mark>weak</mark> signal . [SEP]
Normal	Normal (1.00)	Normal	0.62	[CLS] adjust antennas [SEP]
RegulationViolation	RegulationViolation (0.99)	RegulationViolation	1.90	[CLS] your aircraft is flying in an altitude zone (nnn).[SEP]
Normal	Normal (1.00)	Normal	0.95	[CLS] please fly with caution [SEP]

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