

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	CommunicationIssue (0.17)	CommunicationIssue	-0.29	#s a <span style="color: green;">■</span>
				passenger <span style="color: green;">■</span>
				aircraft <span style="color: red;">■</span>
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	nearby . #/s
				#s fly <span style="color: green;">■</span> with <span style="color: green;">■</span>
				caution #/s <span style="color: green;">■</span>
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.51	#s <span style="color: red;">■</span> account <span style="color: red;">■</span>
				not logged in <span style="color: green;">■</span>
				. #/s
ParamViolation	ParamViolation (0.52)	ParamViolation	-0.57	#s flight
				altitude and
				distance <span style="color: red;">■</span>
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.62	restricted to <span style="color: green;">■</span>
				nnn and nnn . <span style="color: red;">■</span>
				#/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.43	#s <span style="color: green;">■</span> check <span style="color: green;">■</span> and <span style="color: green;">■</span>
				log in #/s <span style="color: green;">■</span>
				#s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.51	<span style="color: green;">■</span> activetrack <span style="color: green;">■</span>
				flight <span style="color: green;">■</span> paused <span style="color: green;">■</span>
				#/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.51	#s aircraft
				<span style="color: red;">■</span> activetrack <span style="color: red;">■</span>
				available at <span style="color: red;">■</span>
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.44	max speed .
				#/s
				#s obstacle <span style="color: red;">■</span>
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.51	avoidance is <span style="color: green;">■</span>
				not available <span style="color: green;">■</span>
				#/s
Normal	ParamViolation (0.46)	ParamViolation	-1.18	#s aircraft
				<span style="color: red;">■</span> activetrack <span style="color: red;">■</span>
				available at <span style="color: red;">■</span>
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.55	max speed .
				#/s
				#s when
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.55	<span style="color: red;">■</span> exceeding <span style="color: red;">■</span>
				nnn , obstacle <span style="color: red;">■</span>
				avoidance is <span style="color: red;">■</span>
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.55	not available <span style="color: green;">■</span>
				#/s
				#s aircraft
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.55	<span style="color: red;">■</span> activetrack <span style="color: red;">■</span>
				max speed of
				nnn and <span style="color: red;">■</span>

HardwareFault	HardwareFault (0.30)	HardwareFault	1.39	obstacle
				avoidance
				functions
				normally #/s
				#s aircraft
Normal	CommunicationIssue (0.17)	CommunicationIssue	-2.40	core board
				overheated
				#/s
				#s aircraft
				entered fixed
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.17	- wing mode .
				#/s
				#s current
				flight speed is
				nnn . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.02	#s press c2
				to exit #/s
				#s aircraft
				flight control
				unlocked #/s
RegulationViolation	RegulationViolation (0.49)	RegulationViolation	0.87	#s aircraft in
				restricted
				zones . #/s
				#s check map
				to find
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.73	recommended
				zones #/s
				#s aircraft is
				in attitude
				mode , so that
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.51	it will not
				hover . #/s
				#s please fly
				with caution .
				#/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.08	#s aircraft is
				in tripod
				mode . #/s
				#s exit this
				mode and try
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.96	again #/s
				#s aircraft is
				returning to
				the starting
				point #/s
ParamViolation	ParamViolation (0.52)	ParamViolation	1.38	#s aircraft
				out of range
				#/s

RegulationViolation	RegulationViolation (0.50)	RegulationViolation	1.63	#s approaching a no-fly zone . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.97	#s rth may be affected . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	#s fly with caution #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.57	#s arrived at start point . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.23	#s starting waypoint mission #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.18	#s auto landing initiated #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.65	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	1.80	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	-0.27	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.17	#s battery error . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.56	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.40	#s battery power low . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.38	#s check battery status and charge or warm up battery #/s
HardwareFault	HardwareFault (0.29)	HardwareFault	1.45	#s cache space full #/s

SurroundingEnvironment	SoftwareFault (0.38)	SoftwareFault	0.91	#s calibration subject is too close . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.91	#s recalibrate using a subject that is farther away #/s
HardwareFault	HardwareFault (0.27)	HardwareFault	1.41	#s camera busy , cannot enter playback #/s
SoftwareFault	SoftwareFault (0.39)	SoftwareFault	1.49	#s cannot enable intelligent flight mode #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.43	#s low battery #/s
SoftwareFault	SoftwareFault (0.39)	SoftwareFault	0.30	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	0.98	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.51)	ParamViolation	-0.71	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	1.57	#s cannot switch flight mode . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.77	#s turn on " multiple flight modes " to enable atti and sport modes . #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	1.17	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.38)	SoftwareFault	1.32	#s no image #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.08	#s please retry #/s

SoftwareFault	SoftwareFault (0.38)	SoftwareFault	1.17	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.38)	SoftwareFault	1.71	#s subject too large #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.14	#s move away and retry #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.69	#s color display in the liveview has been enhanced . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.43	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.29)	HardwareFault	1.48	#s compass abnormal . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.20	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.20	#s the ground or walls may contain metal . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.67	#s move away from sources of interference before attempting flight . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.05	#s 2 . calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	0.94	#s compass error #/s

HardwareFault	SoftwareFault (0.25)	SoftwareFault	1.69	#s compass error, calibration required #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.42	#s compass error. #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.42	#s compass error. #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.31	#s compass disconnected #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.42	#s compass error. #/s
SurroundingEnvironment	SurroundingEnvironment (0.44)	SurroundingEnvironment	0.95	#s magnetic filed interference. #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.38	#s exit p - gps mode #/s
SoftwareFault	HardwareFault (0.30)	HardwareFault	0.57	#s compass initialization failed. #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.50	#s restart aircraft #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.18	#s critical low battery. #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-2.11	#s aircraft in auto power off protection. #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.11	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.18	#s critical low battery. #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.39	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.18	#s critical low battery. #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.55	#s return to home or land promptly #/s

HardwareFault	HardwareFault (0.30)	HardwareFault	1.70	#s critically low power . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.73	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.70	#s critically low power . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.98	#s aircraft landing . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.98	#s aircraft landing . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-2.10	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.67	#s critically low voltage warning . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.56	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	1.78	#s critically low voltage . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.75	#s aircraft will land #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.55	#s data recorder file index is 15 . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.65	#s data recorder file index is 17 . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.12	#s data recorder file index is 30 . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.24	#s data recorder file index is 45 . #/s
	CommunicationIssue			#s data recorder file

Normal	(0.17)	CommunicationIssue	-1.38	index is 46 . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.66	#s data recorder file index is 65 . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.94	#s disable sd card read and write protection or change card #/s
CommunicationIssue	CommunicationIssue (0.48)	CommunicationIssue	1.80	#s downlink lost . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.06	#s downlink restored ( after 0m 2 . 9s ) . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.11	#s drone is vibrating #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.57	#s entered cruise control mode . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.26	#s press c1 or c2 to exit #/s
ParamViolation	ParamViolation (0.52)	ParamViolation	1.63	#s excessive attitude angle detected #/s
SoftwareFault	SoftwareFault (0.39)	SoftwareFault	2.06	#s forward obstacle avoidance has stopped working #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.02	#s exit backward sensing system #/s
SurroundingEnvironment	SurroundingEnvironment (0.45)	SurroundingEnvironment	1.01	#s ambient light is too weak #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.86	#s exited visual avoidance system . #/s
SoftwareFault	SoftwareFault (0.39)	SoftwareFault	1.42	#s exiting gps mode :



				unknown error #/s #s extra payload detected . #/s
ParamViolation	ParamViolation (0.51)	ParamViolation	1.80	#s flight performance will be affected . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.21	#s fly with caution #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	#s forward obstacle sensing is not functioning . #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	-0.70	#s forward obstacle sensing not responding #/s
SoftwareFault	SoftwareFault (0.39)	SoftwareFault	2.13	#s gimbal motor overloaded . #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	2.18	#s check whether gimbal can rotate freely #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.10	#s gimbal pitch limit reached . #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	-0.29	#s ground plain . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.31	#s safe to land . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.34	#s high altitude . #/s
ParamViolation	SurroundingEnvironment (0.40)	SurroundingEnvironment	-1.67	#s aircraft braking distance increased and flight time decreased . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.45	#s fly with caution #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	

SurroundingEnvironment	SurroundingEnvironment (0.44)	SurroundingEnvironment	1.39	#s high wind velocity . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.99	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.44)	SurroundingEnvironment	1.39	#s high wind velocity . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.99	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.44)	SurroundingEnvironment	1.39	#s high wind velocity . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.93	#s fly with caution and land in a safe place asap . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.67	#s high - altitude flight #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	#s fly with caution #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.06	#s aircraft braking distance is extended #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.62	#s flight time is shortened . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.27	#s home point updated . #/s
ParamViolation	SoftwareFault (0.37)	SoftwareFault	0.26	#s imu attitude restricted . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.45	#s ensure aircraft is level #/s

SoftwareFault	CommunicationIssue (0.17)	CommunicationIssue	-2.12	#s imu not calibrated . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.14	#s calibrate imu #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.35	#s landing canceled . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.27	#s landing gear function restored #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.79	#s landing gear paused . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.31	#s landing gear raising . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.41	#s home point recorded #/s
Normal	ParamViolation (0.45)	ParamViolation	-1.03	#s live stream video frame rate less than 9hz . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	#s fly with caution #/s
HardwareFault	HardwareFault (0.29)	HardwareFault	1.51	#s low power . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.69	#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.29)	HardwareFault	1.51	#s low power . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.64	#s returning home . #/s
SurroundingEnvironment	SurroundingEnvironment (0.44)	SurroundingEnvironment	0.95	#s magnetic filed interference . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.35	#s exit p - gps mode . #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	-0.14	#s yaw error . #/s
				#s manned

SurroundingEnvironment	SurroundingEnvironment (0.44)	SurroundingEnvironment	1.01	aircraft detected nearby . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	#s fly with caution #/s
ParamViolation	ParamViolation (0.50)	ParamViolation	1.14	#s max altitude approached . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-2.28	#s wait for the gps satellite signal recovery before ascend #/s
ParamViolation	ParamViolation (0.51)	ParamViolation	1.41	#s max flight altitude reached . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-2.14	#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.51)	ParamViolation	1.35	#s max flight distance reached . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.92	#s adjust in main controller settings if necessary . #/s
ParamViolation	ParamViolation (0.51)	ParamViolation	1.35	#s maximum flight distance reached . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.10	#s adjust the distance in mc settings if required . #/s
HardwareFault	HardwareFault (0.30)	HardwareFault	2.01	#s mobile device cpu fully loaded . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.58	#s related performance will be

SoftwareFault	CommunicationIssue (0.18)	CommunicationIssue	-2.07	affected . #/s
				#s mobile device
				version too old to support
				hd image transmission
				and the image transmission mode has been switch to normal mode . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.10	#s motor is blocked . #/s
HardwareFault	HardwareFault (0.29)	HardwareFault	-1.27	#s motor stuck . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.76	#s check for objects blocking motor or contact dji support for assistance #/s
				#s motors started . #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	1.81	#s no gps signal . #/s
Normal	HardwareFault (0.30)	HardwareFault	-0.72	#s aircraft unable to hover . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	#s fly with caution #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	1.81	#s no gps signal . #/s
Normal	HardwareFault (0.30)	HardwareFault	-1.40	#s unable to hover . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.53	#s fly with caution #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.39	#s obstacle avoidance disabled . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.10	#s landing gear lowered . #/s

Normal	CommunicationIssue (0.17)	CommunicationIssue	1.39	#s obstacle avoidance disabled . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.39	#s obstacle avoidance disabled . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.10	#s landing gear lowered . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.22	#s obstacle avoidance has been disabled . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.47	#s precision landing #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.92	#s quickshot has ended #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.05	#s recenter gimbal pan #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.86	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.45)	SurroundingEnvironment	1.09	#s remote controller in high interference environment . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.98	#s manually adjust flight route or return to home #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.06	#s return - to - home altitude : 65ft #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.61	#s return - to - home altitude : 98ft . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.96	#s rth : ascending to rth altitude . #/s
	CommunicationIssue			#s rth : heading

Normal	(0.17)	CommunicationIssue	1.77	alignment . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.95	#s rth altitude : 65ft . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.00	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.47)	CommunicationIssue	0.86	#s signal lost . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.87	#s aircraft returning to home point #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.07	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.44)	SurroundingEnvironment	1.70	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	2.09	#s aircraft unable to return to home automatically . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.17	#s lower altitude immediately and return to home manually #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.49	#s switched to s ( sport ) - mode . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.94	#s switched to t ( tripod ) - mode . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.23	#s take off in p - mode #/s
SoftwareFault	HardwareFault (0.30)	HardwareFault	0.30	#s vision sensor error . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.61	#s contact dji support for assistance #/s #s vision

Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.54	systems and obstacle avoidance disabled #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-0.66	#s waypoint mission paused #/s
SoftwareFault	SoftwareFault (0.38)	SoftwareFault	1.33	#s weak gps signal . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.12	#s aircraft is in attitude mode and hovering may be unstable . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	-1.29	#s fly with caution . #/s
CommunicationIssue	CommunicationIssue (0.47)	CommunicationIssue	1.22	#s weak signal . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	1.19	#s adjust antennas #/s
RegulationViolation	RegulationViolation (0.51)	RegulationViolation	2.86	#s your aircraft is flying in an altitude zone ( nnn ) . #/s
Normal	CommunicationIssue (0.17)	CommunicationIssue	0.39	#s please fly with caution #/s