

Legend: ■ Negative □ Neutral ■ Positive

| True Label | Predicted Label | Attribution Label | Attribution Score | Word Importance |
|------------------------|-----------------------|-------------------|-------------------|---|
| SurroundingEnvironment | Normal (1.00) | Normal | 1.69 | [CLS] a |
| | | | | passenger |
| | | | | aircraft is |
| | | | | nearby . |
| Normal | Normal (1.00) | Normal | -0.69 | [SEP] |
| | | | | [CLS] fly with |
| | | | | caution [SEP] |
| | | | | [CLS] account |
| Normal | Normal (0.99) | Normal | -1.32 | not logged in |
| | | | | . [SEP] |
| | | | | [CLS] flight |
| | | | | altitude and |
| ParamViolation | ParamViolation (0.94) | ParamViolation | 2.22 | distance |
| | | | | restricted to |
| | | | | nnn and nnn . |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -0.87 | [CLS] check |
| | | | | and log in |
| | | | | [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -1.49 | activetrack |
| | | | | flight paused |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | -1.83 | activetrack |
| | | | | available at |
| | | | | max speed . |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -0.63 | [CLS] |
| | | | | obstacle |
| | | | | avoidance is |
| | | | | not available |
| Normal | Normal (1.00) | Normal | -1.83 | [SEP] |
| | | | | [CLS] aircraft |
| | | | | activetrack |
| | | | | available at |
| Normal | Normal (1.00) | Normal | -0.42 | max speed . |
| | | | | [SEP] |
| | | | | [CLS] when |
| | | | | exceeding |
| Normal | Normal (1.00) | Normal | -0.42 | nnn , obstacle |
| | | | | avoidance is |
| | | | | not available |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -0.42 | [CLS] aircraft |
| | | | | |
| | | | | |
| | | | | |

| | | | | |
|---------------------|----------------------------|---------------------|-------|-----------------|
| Normal | Normal (1.00) | Normal | -0.41 | activetrack |
| | | | | max speed of |
| | | | | nnn and |
| | | | | obstacle |
| | | | | avoidance |
| HardwareFault | HardwareFault (0.96) | HardwareFault | 2.53 | functions |
| | | | | normally |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| | | | | core board |
| Normal | Normal (1.00) | Normal | -1.70 | overheated |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| | | | | entered fixed |
| | | | | - wing mode . |
| Normal | Normal (1.00) | Normal | -2.35 | [SEP] |
| | | | | [CLS] current |
| | | | | flight speed is |
| | | | | nnn . [SEP] |
| | | | | [CLS] press |
| Normal | Normal (1.00) | Normal | -0.29 | c2 to exit |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| | | | | flight control |
| | | | | unlocked |
| RegulationViolation | RegulationViolation (0.76) | RegulationViolation | 1.94 | [SEP] |
| | | | | [CLS] aircraft |
| | | | | in restricted |
| | | | | zones . [SEP] |
| | | | | [CLS] check |
| Normal | Normal (1.00) | Normal | -1.21 | map to find |
| | | | | recommended |
| | | | | zones [SEP] |
| | | | | [CLS] aircraft |
| | | | | is in attitude |
| Normal | Normal (1.00) | Normal | -1.56 | mode , so that |
| | | | | it will not |
| | | | | hover . [SEP] |
| | | | | [CLS] please |
| | | | | fly with |
| Normal | Normal (1.00) | Normal | -0.52 | caution . |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| | | | | is in tripod |
| | | | | mode . [SEP] |
| Normal | Normal (1.00) | Normal | -2.50 | [CLS] exit |
| | | | | this mode and |
| | | | | try again |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | -1.77 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |

| | | | | |
|---------------------|----------------------------|---------------------|-------|-----------------|
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| | | | | is returning |
| Normal | Normal (1.00) | Normal | -2.42 | to the |
| | | | | starting point |
| | | | | [SEP] |
| ParamViolation | ParamViolation (0.94) | ParamViolation | 2.09 | [CLS] aircraft |
| | | | | out of range |
| | | | | [SEP] |
| RegulationViolation | RegulationViolation (0.75) | RegulationViolation | 2.06 | [CLS] |
| | | | | approaching |
| | | | | a no - fly zone |
| | | | | . [SEP] |
| Normal | Normal (1.00) | Normal | -2.38 | [CLS] rth may |
| | | | | be affected . |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -0.69 | [CLS] fly with |
| | | | | caution [SEP] |
| Normal | Normal (1.00) | Normal | -2.06 | [CLS] arrived |
| | | | | at start point |
| | | | | . [SEP] |
| Normal | Normal (1.00) | Normal | -1.68 | [CLS] starting |
| | | | | waypoint |
| | | | | mission [SEP] |
| Normal | Normal (1.00) | Normal | -1.07 | [CLS] auto |
| | | | | landing |
| | | | | initiated |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -2.07 | [CLS] |
| | | | | auxiliary |
| | | | | bottom light |
| | | | | turned off |
| | | | | [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.87 | [CLS] |
| | | | | backward |
| | | | | obstacle |
| | | | | sensing is not |
| | | | | functioning . |
| | | | | [SEP] |
| HardwareFault | HardwareFault (0.96) | HardwareFault | 1.90 | [CLS] battery |
| | | | | cell broken , |
| | | | | please |
| | | | | replace the |
| | | | | battery [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.50 | [CLS] battery |
| | | | | error . [SEP] |
| | | | | [CLS] aircraft |
| | | | | returning to |

| | | | | |
|------------------------|-----------------------|----------------|-------|--|
| Normal | Normal (1.00) | Normal | -1.85 | home [CLS] automatically [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.78 | [CLS] battery power low . [SEP] [CLS] check battery status |
| Normal | Normal (1.00) | Normal | -1.89 | and charge or warm up battery [SEP] [CLS] cache |
| HardwareFault | Normal (0.99) | Normal | 1.25 | space full [SEP] [CLS] |
| SurroundingEnvironment | SoftwareFault (0.98) | SoftwareFault | -0.06 | calibration subject is too close . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -0.97 | recalibrate using a subject that is farther away [SEP] [CLS] camera busy , cannot |
| HardwareFault | HardwareFault (0.96) | HardwareFault | 1.83 | enter playback [SEP] [CLS] cannot |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.06 | enable intelligent flight mode [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.64 | [CLS] low battery [SEP] [CLS] cannot |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.31 | start return to home due to weak gps signal [SEP] [CLS] cannot |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.22 | start self - timer . [SEP] [CLS] |
| SoftwareFault | ParamViolation (0.75) | ParamViolation | 0.51 | exposure time is too long [SEP] |

| | | | | |
|------------------------|----------------------|---------------|-------|---|
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.09 | [CLS] cannot switch flight mode . [SEP] |
| Normal | Normal (1.00) | Normal | -1.20 | [CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP] |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.19 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.97) | SoftwareFault | -1.21 | [CLS] no image [SEP] |
| Normal | Normal (1.00) | Normal | -0.41 | [CLS] please retry [SEP] |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.19 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.98) | SoftwareFault | 0.38 | [CLS] subject too large [SEP] |
| Normal | Normal (1.00) | Normal | -1.68 | [CLS] move away and retry [SEP] |
| Normal | Normal (1.00) | Normal | -2.49 | [CLS] color display in the liveview has been enhanced . [SEP] |
| Normal | Normal (1.00) | Normal | -1.93 | [CLS] videos and photos will still be shot in d - log mode [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.57 | [CLS] compass abnormal . [SEP] |
| Normal | Normal (1.00) | Normal | -0.65 | [CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft . |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|---|
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -1.98 | [CLS] the ground or walls may contain metal . [SEP] |
| Normal | Normal (1.00) | Normal | -0.86 | [CLS] move away from sources of interference before attempting flight . [SEP] |
| Normal | Normal (1.00) | Normal | -2.22 | [CLS] 2 . calibrate compass before takeoff [SEP] |
| HardwareFault | HardwareFault (0.96) | HardwareFault | 1.45 | [CLS] compass error [SEP] |
| HardwareFault | HardwareFault (0.84) | HardwareFault | 1.37 | [CLS] compass error , calibration required [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.52 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.52 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (0.96) | HardwareFault | 1.59 | [CLS] compass disconnected [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.52 | [CLS] compass error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.97) | SurroundingEnvironment | 1.57 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | -2.13 | [CLS] exit p - gps mode [SEP] |

| | | | | |
|---------------|----------------------|---------------|-------|-----------------------|
| SoftwareFault | HardwareFault (0.95) | HardwareFault | 0.38 | [CLS] |
| | | | | compass |
| | | | | initialization |
| | | | | failed. [SEP] |
| Normal | Normal (1.00) | Normal | -0.68 | [CLS] restart |
| | | | | aircraft [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.89 | [CLS] critical |
| | | | | low battery. [SEP] |
| Normal | Normal (1.00) | Normal | -1.69 | [CLS] aircraft |
| | | | | in auto power |
| | | | | off protection. [SEP] |
| Normal | Normal (1.00) | Normal | -2.21 | [CLS] forced |
| | | | | landing in |
| | | | | progress [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.89 | [CLS] critical |
| | | | | low battery. [SEP] |
| Normal | Normal (1.00) | Normal | -1.21 | [CLS] aircraft |
| | | | | landing |
| | | | | automatically [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.89 | [CLS] critical |
| | | | | low battery. [SEP] |
| Normal | Normal (1.00) | Normal | -2.50 | [CLS] return |
| | | | | to home or |
| | | | | land promptly [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.94 | [CLS] |
| | | | | critically low |
| | | | | power. [SEP] |
| Normal | Normal (1.00) | Normal | -1.93 | [CLS] aircraft |
| | | | | is landing [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.94 | [CLS] |
| | | | | critically low |
| Normal | Normal (1.00) | Normal | -1.97 | power. [SEP] |
| | | | | [CLS] aircraft |
| | | | | landing. [SEP] |
| Normal | Normal (1.00) | Normal | -1.97 | [CLS] aircraft |
| | | | | landing. [SEP] |
| | | | | [CLS] throttle |
| | | | | up to reduce |

| | | | | |
|---------------|----------------------|---------------|-------|--|
| Normal | Normal (1.00) | Normal | -0.73 | the speed of descent and use sticks to avoid obstacles [SEP] [CLS] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.93 | critically low voltage warning . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -1.53 | aircraft will be forced to land [SEP] [CLS] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.92 | critically low voltage . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -1.36 | aircraft will land [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -1.63 | data recorder file index is 15 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -1.82 | data recorder file index is 17 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -1.81 | data recorder file index is 30 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -1.88 | data recorder file index is 45 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -1.73 | data recorder file index is 46 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -1.77 | data recorder file index is 65 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -0.41 | disable sd card read and write |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| CommunicationIssue | CommunicationIssue (0.79) | CommunicationIssue | 1.65 | protection or change card [SEP] |
| | | | | [CLS] downlink lost . [SEP] |
| | | | | [CLS] downlink restored (after 0m 2 . 9s) . [SEP] |
| Normal | Normal (1.00) | Normal | -1.49 | [CLS] drone is vibrating [SEP] |
| Normal | HardwareFault (0.85) | HardwareFault | -1.76 | [CLS] entered cruise control mode . [SEP] |
| Normal | Normal (1.00) | Normal | -1.15 | [CLS] press c1 or c2 to exit [SEP] |
| Normal | Normal (1.00) | Normal | -0.82 | [CLS] excessive attitude angle detected [SEP] |
| ParamViolation | ParamViolation (0.91) | ParamViolation | 1.97 | [CLS] forward obstacle avoidance has stopped working [SEP] |
| SoftwareFault | Normal (0.99) | Normal | 1.22 | [CLS] exit backward sensing system [SEP] |
| Normal | Normal (1.00) | Normal | -1.22 | [CLS] ambient light is too weak [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.97) | SurroundingEnvironment | 1.90 | [CLS] exited visual avoidance system . [SEP] |
| Normal | Normal (1.00) | Normal | -0.85 | [CLS] exiting gps mode : unknown error [SEP] |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.24 | |

| | | | | |
|----------------|-----------------------|----------------|-------|---|
| ParamViolation | ParamViolation (0.94) | ParamViolation | 1.88 | [CLS] extra payload detected . [SEP] |
| Normal | Normal (1.00) | Normal | -2.31 | [CLS] flight performance will be affected . [SEP] |
| Normal | Normal (1.00) | Normal | -0.69 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.79 | [CLS] forward obstacle sensing is not functioning . [SEP] |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.91 | [CLS] forward obstacle sensing not responding [SEP] |
| HardwareFault | HardwareFault (0.96) | HardwareFault | 2.22 | [CLS] gimbal motor overloaded . [SEP] |
| Normal | Normal (1.00) | Normal | -1.37 | [CLS] check whether gimbal can rotate freely [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.76 | [CLS] gimbal pitch limit reached . [SEP] |
| Normal | Normal (1.00) | Normal | -1.81 | [CLS] ground plain . [SEP] |
| Normal | Normal (1.00) | Normal | -1.94 | [CLS] safe to land . [SEP] |
| ParamViolation | ParamViolation (0.93) | ParamViolation | 1.55 | [CLS] high altitude . [SEP] |
| Normal | Normal (0.78) | Normal | -0.97 | [CLS] aircraft braking distance increased and flight time decreased . [SEP] |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| Normal | Normal (1.00) | Normal | -0.69 | [CLS] fly with caution [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.97) | SurroundingEnvironment | 1.69 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | -0.65 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.97) | SurroundingEnvironment | 1.69 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | -0.65 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.97) | SurroundingEnvironment | 1.69 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | -2.62 | [CLS] fly with caution and land in a safe place asap . [SEP] |
| Normal | Normal (0.82) | Normal | -1.62 | [CLS] high - altitude flight [SEP] |
| Normal | Normal (1.00) | Normal | -0.69 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.89) | Normal | -0.69 | [CLS] aircraft braking distance is extended [SEP] |
| Normal | ParamViolation (0.73) | ParamViolation | -1.96 | [CLS] flight time is shortened . [SEP] |
| Normal | Normal (1.00) | Normal | -1.98 | [CLS] home |

| | | | | |
|----------------|-----------------------|----------------|-------|--|
| ParamViolation | ParamViolation (0.58) | ParamViolation | 1.81 | point updated . [SEP] |
| | | | | [CLS] imu attitude restricted . [SEP] |
| | | | | [CLS] ensure |
| Normal | Normal (1.00) | Normal | -0.00 | aircraft is level [SEP] |
| SoftwareFault | Normal (1.00) | Normal | -0.90 | [CLS] imu not calibrated . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -2.33 | calibrate imu [SEP] |
| Normal | Normal (1.00) | Normal | -1.13 | [CLS] landing canceled . [SEP] |
| | | | | [CLS] landing gear function restored [SEP] |
| Normal | Normal (1.00) | Normal | -1.64 | [CLS] landing gear paused . [SEP] |
| Normal | Normal (1.00) | Normal | -1.51 | [CLS] landing gear raising . [SEP] |
| | | | | [CLS] home point recorded [SEP] |
| Normal | Normal (1.00) | Normal | -1.68 | [CLS] live stream video frame rate less than 9hz . [SEP] |
| | | | | [CLS] fly with caution [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.70 | [CLS] low power . [SEP] |
| Normal | Normal (1.00) | Normal | -2.43 | [CLS] aircraft is returning to the home point . [SEP] |
| | | | | [CLS] low power . [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.70 | |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| Normal | Normal (1.00) | Normal | -1.93 | [CLS] returning home . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.97) | SurroundingEnvironment | 1.57 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | -2.05 | [CLS] exit p - gps mode . [SEP] |
| HardwareFault | HardwareFault (0.96) | HardwareFault | 1.99 | [CLS] yaw error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.70) | SurroundingEnvironment | 1.24 | [CLS] manned aircraft detected nearby . [SEP] |
| Normal | Normal (1.00) | Normal | -0.69 | [CLS] fly with caution [SEP] |
| ParamViolation | Normal (0.97) | Normal | 0.90 | [CLS] max altitude approached . [SEP] |
| Normal | Normal (1.00) | Normal | -0.17 | [CLS] wait for the gps satellite signal recovery before ascend [SEP] |
| ParamViolation | ParamViolation (0.95) | ParamViolation | 1.90 | [CLS] max flight altitude reached . [SEP] |
| Normal | Normal (1.00) | Normal | -2.35 | [CLS] adjust in main controller settings if necessary [SEP] |
| ParamViolation | ParamViolation (0.95) | ParamViolation | 1.91 | [CLS] max flight distance reached . [SEP] |
| | | | | [CLS] adjust |

| | | | | |
|----------------|-----------------------|----------------|-------|---|
| Normal | Normal (1.00) | Normal | -2.40 | in main controller settings if necessary . [SEP] [CLS] maximum |
| ParamViolation | ParamViolation (0.94) | ParamViolation | 2.00 | flight distance reached . [SEP] [CLS] adjust the distance |
| Normal | Normal (1.00) | Normal | -2.39 | in mc settings if required . [SEP] [CLS] mobile device cpu fully loaded . [SEP] [CLS] related performance |
| HardwareFault | HardwareFault (0.88) | HardwareFault | 1.55 | will be affected . [SEP] [CLS] mobile device version too old to support hd image transmission |
| Normal | Normal (1.00) | Normal | -2.46 | and the image transmission mode has been switch to normal mode . [SEP] [CLS] motor is blocked . [SEP] |
| SoftwareFault | Normal (0.99) | Normal | 0.49 | [CLS] motor stuck . [SEP] [CLS] check for objects blocking motor or contact dji support for |
| Normal | Normal (1.00) | Normal | -1.64 | |
| HardwareFault | HardwareFault (0.96) | HardwareFault | 1.59 | |
| Normal | Normal (1.00) | Normal | -1.65 | |

| | | | | |
|---------------|----------------------|---------------|-------|--|
| | | | | assistance |
| | | | | [SEP] |
| Normal | HardwareFault (0.90) | HardwareFault | -1.77 | [CLS] motors started . [SEP] |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.48 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (0.96) | HardwareFault | -1.20 | [CLS] aircraft unable to hover . [SEP] |
| Normal | Normal (1.00) | Normal | -0.69 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.48 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (0.96) | HardwareFault | -1.31 | [CLS] unable to hover . [SEP] |
| Normal | Normal (1.00) | Normal | -0.69 | [CLS] fly with caution [SEP] |
| Normal | Normal (1.00) | Normal | -1.40 | [CLS] obstacle avoidance disabled . [SEP] |
| | | | | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (1.00) | Normal | -1.40 | [CLS] obstacle avoidance disabled . [SEP] |
| | | | | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (1.00) | Normal | -1.40 | [CLS] obstacle avoidance disabled . [SEP] |
| | | | | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (1.00) | Normal | -1.80 | [CLS] obstacle avoidance has been disabled . [SEP] |
| Normal | Normal (1.00) | Normal | -1.12 | [CLS] precision |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| | | | | landing [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -1.73 | quickshot has ended [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -2.60 | recenter gimbal pan [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -0.49 | rectifying aircraft position [SEP] |
| | | | | [CLS] remote controller in high interference environment . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.97) | SurroundingEnvironment | 1.99 | |
| | | | | [CLS] manually adjust flight route or return to home [SEP] |
| Normal | Normal (1.00) | Normal | -1.98 | |
| | | | | [CLS] return - to - home altitude : 65ft [SEP] |
| Normal | Normal (1.00) | Normal | -1.37 | |
| | | | | [CLS] return - to - home altitude : 98ft . [SEP] |
| Normal | Normal (1.00) | Normal | -0.77 | |
| | | | | [CLS] rth : ascending to rth altitude . [SEP] |
| Normal | Normal (1.00) | Normal | -2.65 | |
| | | | | [CLS] rth : heading alignment . [SEP] |
| Normal | Normal (1.00) | Normal | -2.10 | |
| | | | | [CLS] rth altitude : 65ft . [SEP] |
| Normal | Normal (1.00) | Normal | -2.20 | |
| | | | | [CLS] rth altitude : 98ft . [SEP] |
| Normal | Normal (1.00) | Normal | -2.08 | |
| | | | | [CLS] signal |
| CommunicationIssue | CommunicationIssue (0.82) | CommunicationIssue | 1.40 | |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|---|
| | | | | lost . [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | -2.41 | returning to home point [SEP] |
| | | | | [CLS] sprayer |
| Normal | Normal (1.00) | Normal | -2.09 | turned on [SEP] |
| | | | | [CLS] strong |
| SurroundingEnvironment | SurroundingEnvironment (0.97) | SurroundingEnvironment | 1.58 | wind warning [SEP] |
| | | | | [CLS] aircraft |
| | | | | unable to |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.23 | return to home automatically [SEP] |
| | | | | [CLS] lower |
| | | | | altitude |
| Normal | Normal (1.00) | Normal | -1.19 | immediately and return to home manually [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -2.37 | switched to s (sport) - mode . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -1.70 | switched to t (tripod) - mode . [SEP] |
| | | | | [CLS] take off |
| Normal | Normal (1.00) | Normal | -2.53 | in p - mode [SEP] |
| | | | | [CLS] vision |
| SoftwareFault | SoftwareFault (0.49) | SoftwareFault | 0.76 | sensor error . [SEP] |
| | | | | [CLS] contact |
| Normal | Normal (1.00) | Normal | -2.61 | dji support for assistance [SEP] |
| | | | | [CLS] vision |
| | | | | systems and |
| Normal | Normal (1.00) | Normal | -1.78 | obstacle avoidance disabled [SEP] |

| | | | | |
|---------------------|----------------------------|---------------------|-------|-----------------|
| Normal | Normal (1.00) | Normal | -1.14 | [CLS] |
| | | | | waypoint |
| | | | | mission |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.64 | paused [SEP] |
| | | | | [CLS] weak |
| | | | | gps signal . |
| Normal | Normal (1.00) | Normal | -1.43 | [SEP] |
| | | | | [CLS] aircraft |
| | | | | is in attitude |
| Normal | Normal (1.00) | Normal | -0.70 | mode and |
| | | | | hovering may |
| | | | | be unstable . |
| CommunicationIssue | CommunicationIssue (0.79) | CommunicationIssue | 1.42 | [SEP] |
| | | | | [CLS] fly with |
| | | | | caution . |
| Normal | Normal (1.00) | Normal | -0.40 | [SEP] |
| | | | | [CLS] weak |
| | | | | signal . [SEP] |
| RegulationViolation | RegulationViolation (0.37) | RegulationViolation | 1.30 | [CLS] adjust |
| | | | | antennas |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -0.43 | [CLS] your |
| | | | | aircraft is |
| | | | | flying in an |
| Normal | Normal (1.00) | Normal | -0.43 | altitude zone |
| | | | | (nnn) . [SEP] |
| | | | | [CLS] please |
| Normal | Normal (1.00) | Normal | -0.43 | fly with |
| | | | | caution [SEP] |
| | | | | |