

**Legend:** ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	Normal (0.51)	Normal	-0.10	#s a passenger aircraft is nearby . #/s
Normal	Normal (0.51)	Normal	1.75	#s fly with caution #/s
Normal	Normal (0.51)	Normal	1.10	#s account not logged in . #/s
ParamViolation	ParamViolation (0.34)	ParamViolation	1.48	#s flight altitude and distance restricted to nnn and nnn . #/s
Normal	Normal (0.51)	Normal	1.66	#s check and log in #/s
Normal	Normal (0.51)	Normal	-1.19	#s activetrack flight paused #/s
Normal	Normal (0.51)	Normal	2.49	#s aircraft activetrack available at max speed . #/s
Normal	Normal (0.51)	Normal	0.75	#s obstacle avoidance is not available #/s
Normal	Normal (0.51)	Normal	2.49	#s aircraft activetrack available at max speed . #/s
Normal	ParamViolation (0.32)	ParamViolation	-1.29	#s when exceeding nnn , obstacle avoidance is not available #/s
Normal	Normal (0.51)	Normal	1.68	#s aircraft activetrack max speed of nnn and

				obstacle avoidance functions normally #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>2.20</b>	#s aircraft core board overheated #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.79</b>	#s aircraft entered fixed - wing mode . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.38</b>	#s current flight speed is mnn . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>0.95</b>	#s press c2 to exit #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.01</b>	#s aircraft flight control unlocked #/s
<b>RegulationViolation</b>	<b>RegulationViolation (0.23)</b>	<b>RegulationViolation</b>	<b>0.89</b>	#s aircraft in restricted zones . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-2.22</b>	#s check map to find recommended zones #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>3.16</b>	#s aircraft is in attitude mode , so that it will not hover . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-1.72</b>	#s please fly with caution . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.31</b>	#s aircraft is in tripod mode . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-2.25</b>	#s exit this mode and try again #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.24</b>	#s aircraft is returning to the starting point #/s
<b>ParamViolation</b>	<b>ParamViolation (0.34)</b>	<b>ParamViolation</b>	<b>1.05</b>	#s aircraft out of range #/s

<b>RegulationViolation</b>	<b>RegulationViolation (0.23)</b>	<b>RegulationViolation</b>	<b>2.40</b>	#s approaching a no - fly zone . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-1.84</b>	#s rth may be affected . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.75</b>	#s fly with caution #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>0.66</b>	#s arrived at start point . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>0.98</b>	#s starting waypoint mission #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.26</b>	#s auto landing initiated #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.58</b>	#s auxiliary bottom light turned off #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>1.91</b>	#s backward obstacle sensing is not functioning . #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.69</b>	#s battery cell broken , please replace the battery #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.34</b>	#s battery error . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.74</b>	#s aircraft returning to home automatically #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.67</b>	#s battery power low . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.59</b>	#s check battery status and charge or warm up battery #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-1.45</b>	#s cache space full #/s

<b>SurroundingEnvironment</b>	<b>SoftwareFault (0.38)</b>	<b>SoftwareFault</b>	<b>0.88</b>	#s calibration subject is too close . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.91</b>	#s recalibrate using a subject that is farther away #/s
<b>HardwareFault</b>	<b>SoftwareFault (0.33)</b>	<b>SoftwareFault</b>	<b>1.75</b>	#s camera busy , cannot enter playback #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>2.02</b>	#s cannot enable intelligent flight mode #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.28</b>	#s low battery #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>-1.53</b>	#s cannot start return to home due to weak gps signal #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>-1.97</b>	#s cannot start self - timer . #/s
<b>SoftwareFault</b>	<b>ParamViolation (0.34)</b>	<b>ParamViolation</b>	<b>-0.70</b>	#s exposure time is too long #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>-1.78</b>	#s cannot switch flight mode . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.51</b>	#s turn on " multiple flight modes " to enable atti and sport modes . #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>1.19</b>	#s cannot track subject #/s
<b>SurroundingEnvironment</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>1.44</b>	#s no image #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.17</b>	#s please retry #/s
				#s cannot

<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>1.19</b>	track subject #/s
<b>SurroundingEnvironment</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>-0.40</b>	#s subject too large #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.08</b>	#s move away and retry #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.63</b>	#s color display in the liveview has been enhanced . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-0.45</b>	#s videos and photos will still be shot in d - log mode #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-0.39</b>	#s compass abnormal . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-0.01</b>	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.46</b>	#s the ground or walls may contain metal . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.55</b>	#s move away from sources of interference before attempting flight . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.97</b>	#s 2 . calibrate compass before takeoff #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.41</b>	#s compass error #/s
				#s compass

<b>HardwareFault</b>	<b>HardwareFault (0.31)</b>	<b>HardwareFault</b>	<b>1.81</b>	error , calibration required #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-1.60</b>	#s compass error . #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-1.60</b>	#s compass error . #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.35</b>	#s compass disconnected #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-1.60</b>	#s compass error . #/s
<b>SurroundingEnvironment</b>	<b>SurroundingEnvironment (0.32)</b>	<b>SurroundingEnvironment</b>	<b>1.32</b>	#s magnetic filed interference . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.86</b>	#s exit p - gps mode #/s
<b>SoftwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>0.41</b>	#s compass initialization failed . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>0.95</b>	#s restart aircraft #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.25</b>	#s critical low battery . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.45</b>	#s aircraft in auto power off protection . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.89</b>	#s forced landing in progress #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.25</b>	#s critical low battery . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>0.76</b>	#s aircraft landing automatically #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.25</b>	#s critical low battery . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.66</b>	#s return to home or land promptly #/s
				#s critically

<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.72</b>	low power . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.75</b>	#s aircraft is landing #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.72</b>	#s critically low power . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.84</b>	#s aircraft landing . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.84</b>	#s aircraft landing . #/s
				#s throttle up to reduce the speed of
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.89</b>	descent and use sticks to avoid obstacles #/s
				#s critically
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>2.14</b>	low voltage warning . #/s
				#s aircraft
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.07</b>	will be forced to land #/s
				#s critically
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-1.92</b>	low voltage . #/s
				#s aircraft will land #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.74</b>	#s data recorder file index is 15 . #/s
				#s data recorder file index is 17 . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-0.93</b>	#s data recorder file index is 30 . #/s
				#s data recorder file index is 45 . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.03</b>	#s data recorder file index is 46 .
				#s data recorder file index is 46 .

				#/s
Normal	Normal (0.51)	Normal	1.77	#s data recorder file index is 65 . #/s
Normal	Normal (0.51)	Normal	0.50	#s disable sd card read and write protection or change card #/s
CommunicationIssue	CommunicationIssue (0.26)	CommunicationIssue	1.02	#s downlink lost . #/s
Normal	Normal (0.51)	Normal	-2.30	#s downlink restored ( after 0m 2 . 9s ) . #/s
Normal	Normal (0.51)	Normal	-1.70	#s drone is vibrating #/s
Normal	Normal (0.51)	Normal	1.99	#s entered cruise control mode . #/s
Normal	Normal (0.51)	Normal	2.11	#s press c1 or c2 to exit #/s
ParamViolation	ParamViolation (0.34)	ParamViolation	1.60	#s excessive attitude angle detected #/s
SoftwareFault	Normal (0.51)	Normal	0.01	#s forward obstacle avoidance has stopped working #/s
Normal	Normal (0.51)	Normal	1.57	#s exit backward sensing system #/s
SurroundingEnvironment	SurroundingEnvironment (0.32)	SurroundingEnvironment	2.14	#s ambient light is too weak #/s
Normal	Normal (0.51)	Normal	0.85	#s exited visual avoidance system . #/s
SoftwareFault	SoftwareFault (0.39)	SoftwareFault	1.32	#s exiting gps mode : unknown

<b>ParamViolation</b>	<b>ParamViolation (0.34)</b>	<b>ParamViolation</b>	<b>1.63</b>	error #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.03</b>	#s extra payload detected . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.75</b>	#s flight performance will be affected . #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>2.29</b>	#s fly with caution #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>1.72</b>	#s forward obstacle sensing is not functioning . #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>2.02</b>	#s forward obstacle sensing not responding #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-0.27</b>	#s gimbal motor overloaded . #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-2.39</b>	#s check whether gimbal can rotate freely #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.77</b>	#s gimbal pitch limit reached . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.88</b>	#s ground plain . #/s
<b>ParamViolation</b>	<b>SurroundingEnvironment (0.32)</b>	<b>SurroundingEnvironment</b>	<b>0.59</b>	#s safe to land . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.64</b>	#s high altitude . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.75</b>	#s aircraft braking distance increased and flight time decreased . #/s
		<b>SurroundingEnvironment</b>		#s fly with caution #/s
				#s high wind

<b>SurroundingEnvironment</b>	<b>(0.32)</b>	<b>SurroundingEnvironment</b>	<b>1.71</b>	velocity . #/s
Normal	Normal (0.51)	Normal	-0.03	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.32)	SurroundingEnvironment	1.71	#s high wind velocity . #/s
Normal	Normal (0.51)	Normal	-0.03	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.32)	SurroundingEnvironment	1.71	#s high wind velocity . #/s
Normal	Normal (0.51)	Normal	2.02	#s fly with caution and land in a safe place asap . #/s
Normal	Normal (0.51)	Normal	1.71	#s high - altitude flight #/s
Normal	Normal (0.51)	Normal	1.75	#s fly with caution #/s
Normal	Normal (0.51)	Normal	-2.07	#s aircraft braking distance is extended #/s
Normal	Normal (0.51)	Normal	1.41	#s flight time is shortened . #/s
Normal	Normal (0.51)	Normal	1.94	#s home point updated . #/s
ParamViolation	SoftwareFault (0.39)	SoftwareFault	-0.91	#s imu attitude restricted . #/s
Normal	Normal (0.51)	Normal	1.68	#s ensure aircraft is level #/s
SoftwareFault	Normal (0.51)	Normal	-1.59	#s imu not

				calibrated .
				#/s
Normal	<b>Normal (0.51)</b>	Normal	<b>0.31</b>	#s calibrate imu #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>1.85</b>	#s landing canceled . #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>1.97</b>	#s landing gear function restored #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>1.56</b>	#s landing gear paused . #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>1.67</b>	#s landing gear raising . #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>1.19</b>	#s home point recorded #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>-1.96</b>	#s live stream video frame rate less than 9hz . #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>1.75</b>	#s fly with caution #/s
HardwareFault	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.26</b>	#s low power . #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>2.26</b>	#s aircraft is returning to the home point . #/s
HardwareFault	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.26</b>	#s low power . #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>1.02</b>	#s returning home . #/s
SurroundingEnvironment	<b>SurroundingEnvironment (0.32)</b>	<b>SurroundingEnvironment</b>	<b>1.32</b>	#s magnetic field interference . #/s
Normal	<b>Normal (0.51)</b>	Normal	<b>-0.47</b>	#s exit p - gps mode . #/s
HardwareFault	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-1.69</b>	#s yaw error . #/s
SurroundingEnvironment	<b>Normal (0.51)</b>	Normal	<b>-0.10</b>	#s manned aircraft detected

Normal	<b>Normal (0.51)</b>	Normal	1.75	nearby . #/s #s fly with caution #/s
ParamViolation	<b>ParamViolation (0.34)</b>	ParamViolation	1.25	#s max altitude approached . #/s #s wait for the gps satellite
Normal	<b>Normal (0.51)</b>	Normal	2.29	#s signal recovery before ascend #/s
ParamViolation	<b>ParamViolation (0.34)</b>	ParamViolation	0.47	#s max flight altitude reached . #/s #s adjust in main
Normal	<b>Normal (0.51)</b>	Normal	-0.26	#s controller settings if necessary #/s #s max flight distance reached . #/s
ParamViolation	<b>ParamViolation (0.34)</b>	ParamViolation	0.99	#s adjust in main #s controller settings if necessary . #/s
Normal	<b>Normal (0.51)</b>	Normal	-2.16	#s maximum flight distance reached . #/s #s adjust the distance in mc settings if required . #/s
ParamViolation	<b>ParamViolation (0.34)</b>	ParamViolation	1.01	#s mobile device cpu fully loaded . #/s #s related performance will be affected . #/s
Normal	<b>Normal (0.51)</b>	Normal	2.42	#s mobile
HardwareFault	<b>HardwareFault (0.32)</b>	HardwareFault	-1.38	device cpu fully loaded . #/s #s related performance will be affected . #/s
Normal	<b>Normal (0.51)</b>	Normal	1.79	#s mobile

<b>SoftwareFault</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>3.54</b>	device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.52</b>	#s motor is blocked . #/s
<b>HardwareFault</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>1.41</b>	#s motor stuck . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>3.02</b>	#s check for objects blocking motor or contact dji support for assistance #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>0.93</b>	#s motors started . #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.38)</b>	<b>SoftwareFault</b>	<b>1.51</b>	#s no gps signal . #/s
<b>Normal</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-1.06</b>	#s aircraft unable to hover . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.75</b>	#s fly with caution #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.38)</b>	<b>SoftwareFault</b>	<b>1.51</b>	#s no gps signal . #/s
<b>Normal</b>	<b>HardwareFault (0.32)</b>	<b>HardwareFault</b>	<b>-1.30</b>	#s unable to hover . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.75</b>	#s fly with caution #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.80</b>	#s obstacle avoidance disabled . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.71</b>	#s landing gear lowered . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.80</b>	#s obstacle avoidance disabled . #/s

Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.80</b>	#s obstacle avoidance disabled . #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.71</b>	#s landing gear lowered . #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.38</b>	#s obstacle avoidance has been disabled . #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.49</b>	#s precision landing #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.30</b>	#s quickshot has ended #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.04</b>	#s recenter gimbal pan #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.94</b>	#s rectifying aircraft position #/s
SurroundingEnvironment	<b>SurroundingEnvironment (0.32)</b>	<b>SurroundingEnvironment</b>	<b>1.45</b>	#s remote controller in high interference environment . #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-2.15</b>	#s manually adjust flight route or return to home #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.42</b>	#s return - to - home altitude : 65ft #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.58</b>	#s return - to - home altitude : 98ft . #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.46</b>	#s rth : ascending to rth altitude . #/s
Normal	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-1.13</b>	#s rth : heading alignment . #/s

<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.46</b>	#s rth altitude : 65ft . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.55</b>	#s rth altitude : 98ft . #/s
<b>CommunicationIssue</b>	<b>CommunicationIssue (0.26)</b>	<b>CommunicationIssue</b>	<b>1.39</b>	#s signal lost . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.15</b>	#s aircraft returning to home point . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.14</b>	#s sprayer turned on #/s
<b>SurroundingEnvironment</b>	<b>SurroundingEnvironment (0.32)</b>	<b>SurroundingEnvironment</b>	<b>1.78</b>	#s strong wind warning . #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>2.13</b>	#s aircraft unable to return to home automatically . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.72</b>	#s lower altitude immediately and return to home manually #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-2.04</b>	#s switched to s ( sport ) - mode . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.27</b>	#s switched to t ( tripod ) - mode . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>-2.44</b>	#s take off in p - mode #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.39)</b>	<b>SoftwareFault</b>	<b>-0.55</b>	#s vision sensor error . . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.16</b>	#s contact dji support for assistance . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.21</b>	#s vision systems and obstacle avoidance

<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.27</b>	disabled #/s #s waypoint mission paused #/s
<b>SoftwareFault</b>	<b>SoftwareFault (0.38)</b>	<b>SoftwareFault</b>	<b>0.74</b>	#s weak gps signal . #/s #s aircraft is in attitude mode and hovering may be unstable . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>2.96</b>	#s fly with caution . #/s #s weak signal . #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.62</b>	#s adjust antennas #/s #s your aircraft is flying in an altitude zone ( nnn ) . #/s
<b>CommunicationIssue</b>	<b>CommunicationIssue (0.26)</b>	<b>CommunicationIssue</b>	<b>1.50</b>	#s please fly with caution #/s
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.08</b>	
<b>RegulationViolation</b>	<b>RegulationViolation (0.22)</b>	<b>RegulationViolation</b>	<b>2.66</b>	
<b>Normal</b>	<b>Normal (0.51)</b>	<b>Normal</b>	<b>1.14</b>	