

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	Normal (0.28)	Normal	0.60	#s a <span style="color: green;">■</span>
				passenger <span style="color: green;">■</span>
				aircraft is <span style="color: red;">■</span>
Normal	Normal (0.28)	Normal	1.51	nearby . #/s <span style="color: red;">■</span>
				#s fly with <span style="color: green;">■</span>
				caution #/s <span style="color: green;">■</span>
Normal	Normal (0.27)	Normal	-1.44	#s account <span style="color: green;">■</span>
				not logged in <span style="color: red;">■</span>
				. #/s <span style="color: red;">■</span>
ParamViolation	ParamViolation (0.80)	ParamViolation	0.42	#s flight <span style="color: green;">■</span>
				altitude and <span style="color: green;">■</span>
				distance <span style="color: green;">■</span>
Normal	Normal (0.28)	Normal	1.98	restricted to <span style="color: red;">■</span>
				nnn and nnn . <span style="color: red;">■</span>
				#/s <span style="color: red;">■</span>
Normal	Normal (0.28)	Normal	1.59	#s check and <span style="color: green;">■</span>
				log in #/s <span style="color: green;">■</span>
				#s <span style="color: green;">■</span>
Normal	Normal (0.28)	Normal	1.20	activetrack <span style="color: green;">■</span>
				flight paused <span style="color: green;">■</span>
				#/s <span style="color: green;">■</span>
Normal	Normal (0.28)	Normal	1.92	#s aircraft <span style="color: green;">■</span>
				activetrack <span style="color: green;">■</span>
				available at <span style="color: green;">■</span>
Normal	Normal (0.28)	Normal	1.20	max speed . <span style="color: green;">■</span>
				#/s <span style="color: green;">■</span>
				#s obstacle <span style="color: green;">■</span>
Normal	ParamViolation (0.80)	ParamViolation	-0.88	avoidance is <span style="color: green;">■</span>
				not available <span style="color: red;">■</span>
				#/s <span style="color: red;">■</span>
Normal	Normal (0.28)	Normal	1.60	#s when <span style="color: red;">■</span>
				exceeding <span style="color: red;">■</span>
				nnn , obstacle <span style="color: green;">■</span>
Normal	Normal (0.28)	Normal	1.60	avoidance is <span style="color: red;">■</span>
				not available <span style="color: green;">■</span>
				#/s <span style="color: red;">■</span>
Normal	Normal (0.28)	Normal	1.60	#s aircraft <span style="color: red;">■</span>
				activetrack <span style="color: green;">■</span>
				max speed of <span style="color: green;">■</span>
Normal	Normal (0.28)	Normal	1.60	nnn and <span style="color: green;">■</span>
				#/s <span style="color: green;">■</span>
				#/s <span style="color: green;">■</span>

HardwareFault	HardwareFault (0.67)	HardwareFault	1.44	obstacle avoidance functions normally #/s #s aircraft core board overheated #/s
				#s aircraft entered fixed - wing mode . #/s
				#s current flight speed is nnn . #/s
				#s press c2 to exit #/s
				#s aircraft flight control unlocked #/s
RegulationViolation	RegulationViolation (0.86)	RegulationViolation	1.88	#s aircraft in restricted zones . #/s
Normal	Normal (0.28)	Normal	2.03	#s check map to find recommended zones #/s
Normal	Normal (0.28)	Normal	0.64	#s aircraft is in attitude mode , so that it will not hover . #/s
Normal	Normal (0.28)	Normal	1.40	#s please fly with caution . #/s
Normal	Normal (0.28)	Normal	2.11	#s aircraft is in tripod mode . #/s
Normal	Normal (0.28)	Normal	2.06	#s exit this mode and try again #/s
Normal	Normal (0.28)	Normal	-1.16	#s aircraft is returning to the starting point #/s
ParamViolation	ParamViolation (0.80)	ParamViolation	1.92	#s aircraft out of range #/s

RegulationViolation	RegulationViolation (0.86)	RegulationViolation	1.82	#s approaching a no - fly zone . #/s
Normal	Normal (0.28)	Normal	-0.94	#s rth may be affected . #/s
Normal	Normal (0.28)	Normal	1.51	#s fly with caution #/s
Normal	Normal (0.28)	Normal	1.41	#s arrived at start point . #/s
Normal	Normal (0.28)	Normal	1.93	#s starting waypoint mission #/s
Normal	Normal (0.28)	Normal	1.45	#s auto landing initiated #/s
Normal	Normal (0.28)	Normal	1.80	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.73	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.63	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.08	#s battery error . #/s
Normal	Normal (0.28)	Normal	1.74	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.51	#s battery power low . #/s
Normal	Normal (0.28)	Normal	2.20	#s check battery status and charge or warm up battery #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.57	#s cache space full #/s

SurroundingEnvironment	SoftwareFault (0.70)	SoftwareFault	-1.01	#s calibration subject is too close . #/s #s recalibrate
Normal	Normal (0.28)	Normal	1.96	using a subject that is farther away #/s
HardwareFault	HardwareFault (0.65)	HardwareFault	1.48	#s camera busy , cannot enter playback #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.48	#s cannot enable intelligent flight mode #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.48	#s low battery #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.42	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	0.82	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.80)	ParamViolation	-1.33	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.31	#s cannot switch flight mode . #/s #s turn on " multiple flight modes " to enable atti and sport modes . #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.35	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.70)	SoftwareFault	-1.04	#s no image #/s
Normal	Normal (0.28)	Normal	1.46	#s please retry #/s #s cannot

SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.35	track subject #/s
SurroundingEnvironment	SoftwareFault (0.70)	SoftwareFault	0.67	#s subject too large #/s
Normal	Normal (0.28)	Normal	2.02	#s move away and retry #/s
Normal	Normal (0.28)	Normal	2.26	#s color display in the liveview has been enhanced . #/s
Normal	Normal (0.28)	Normal	1.12	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	-1.10	#s compass abnormal . #/s
Normal	Normal (0.28)	Normal	3.19	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	Normal (0.28)	Normal	-0.83	#s the ground or walls may contain metal . #/s
Normal	Normal (0.28)	Normal	1.35	#s move away from sources of interference before attempting flight . #/s
Normal	Normal (0.28)	Normal	1.90	#s 2 . calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	0.87	#s compass error #/s #s compass

HardwareFault	HardwareFault (0.67)	HardwareFault	1.23	error , calibration required #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	0.70	#s compass error . #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	0.70	#s compass error . #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.48	#s compass disconnected #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	0.70	#s compass error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.75)	SurroundingEnvironment	1.69	#s magnetic filed interference . #/s
Normal	Normal (0.28)	Normal	2.06	#s exit p - gps mode #/s
SoftwareFault	HardwareFault (0.67)	HardwareFault	-1.39	#s compass initialization failed . #/s
Normal	Normal (0.28)	Normal	1.22	#s restart aircraft #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.42	#s critical low battery . #/s
Normal	Normal (0.28)	Normal	1.06	#s aircraft in auto power off protection . #/s
Normal	Normal (0.28)	Normal	1.88	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.42	#s critical low battery . #/s
Normal	Normal (0.28)	Normal	1.10	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.42	#s critical low battery . #/s
Normal	Normal (0.28)	Normal	1.30	#s return to home or land promptly #/s
				#s critically

HardwareFault	HardwareFault (0.67)	HardwareFault	1.36	low power. #/s
Normal	Normal (0.28)	Normal	0.42	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.36	#s critically low power. #/s
Normal	Normal (0.27)	Normal	1.11	#s aircraft landing. #/s
Normal	Normal (0.27)	Normal	1.11	#s aircraft landing. #/s
Normal	Normal (0.28)	Normal	2.17	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.38	#s critically low voltage warning. #/s
Normal	Normal (0.28)	Normal	1.76	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.80	#s critically low voltage. #/s
Normal	Normal (0.28)	Normal	1.49	#s aircraft will land #/s
Normal	Normal (0.28)	Normal	-1.97	#s data recorder file index is 15. #/s
Normal	Normal (0.28)	Normal	1.17	#s data recorder file index is 17. #/s
Normal	Normal (0.28)	Normal	2.37	#s data recorder file index is 30. #/s
Normal	Normal (0.28)	Normal	1.52	#s data recorder file index is 45. #/s
Normal	Normal (0.28)	Normal	0.94	#s data recorder file index is 46. #/s

				#/s
				#s data recorder file index is 65 .
Normal	Normal (0.28)	Normal	1.73	#/s
				#s disable sd card read and write
Normal	Normal (0.28)	Normal	1.84	protection or change card
				#/s
CommunicationIssue	CommunicationIssue (0.87)	CommunicationIssue	1.41	#s downlink lost . #/s
				#s downlink
Normal	Normal (0.28)	Normal	2.22	restored ( after 0m 2 . 9s ) . #/s
Normal	Normal (0.28)	Normal	1.90	#s drone is vibrating #/s
				#s entered
Normal	Normal (0.28)	Normal	0.88	cruise control mode . #/s
				#s press c1 or c2 to exit
Normal	Normal (0.28)	Normal	1.12	#/s
ParamViolation	ParamViolation (0.80)	ParamViolation	1.60	#s excessive attitude angle detected #/s
				#s forward obstacle
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.60	avoidance has stopped
				working #/s
				#s exit
Normal	Normal (0.28)	Normal	0.46	backward sensing system #/s
				#s ambient light is too weak #/s
SurroundingEnvironment	SurroundingEnvironment (0.75)	SurroundingEnvironment	1.61	#s exited
Normal	Normal (0.28)	Normal	1.12	visual avoidance system . #/s
				#s exiting
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	-1.01	gps mode : unknown

ParamViolation	ParamViolation (0.80)	ParamViolation	1.26	error #/s
				#s extra payload detected . #/s
				#s flight performance will be affected . #/s
Normal	Normal (0.28)	Normal	1.88	#s fly with caution #/s
Normal	Normal (0.28)	Normal	1.51	#s forward obstacle sensing is not functioning . #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.85	#s forward obstacle sensing not responding #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.69	#s gimbal motor overloaded . #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	2.32	#s check whether gimbal can rotate freely #/s
Normal	Normal (0.28)	Normal	1.88	#s gimbal pitch limit reached . #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.04	#s ground plain . #/s
Normal	Normal (0.27)	Normal	1.40	#s safe to land . #/s
Normal	Normal (0.28)	Normal	-0.83	#s high altitude . #/s
ParamViolation	ParamViolation (0.74)	ParamViolation	1.49	#s aircraft braking distance increased and flight time decreased . #/s
Normal	Normal (0.28)	Normal	1.08	#s fly with caution #/s
Normal	Normal (0.28)	Normal	1.51	#s high wind
SurroundingEnvironment				

SurroundingEnvironment	(0.75)	SurroundingEnvironment	-0.62	velocity . #/s
Normal	Normal (0.28)	Normal	-1.37	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.75)	SurroundingEnvironment	-0.62	#s high wind velocity . #/s
Normal	Normal (0.28)	Normal	-1.37	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.75)	SurroundingEnvironment	-0.62	#s high wind velocity . #/s
Normal	Normal (0.28)	Normal	2.20	#s fly with caution and land in a safe place asap . #/s
Normal	ParamViolation (0.55)	ParamViolation	-1.58	#s high - altitude flight #/s
Normal	Normal (0.28)	Normal	1.51	#s fly with caution #/s
Normal	Normal (0.28)	Normal	1.23	#s aircraft braking distance is extended #/s
Normal	Normal (0.28)	Normal	0.60	#s flight time is shortened . #/s
Normal	Normal (0.28)	Normal	1.56	#s home point updated . #/s
ParamViolation	SoftwareFault (0.53)	SoftwareFault	-0.14	#s imu attitude restricted . #/s
Normal	Normal (0.28)	Normal	1.45	#s ensure aircraft is level #/s
SoftwareFault	Normal (0.28)	Normal	-1.45	#s imu not

				calibrated . #/s
Normal	Normal (0.28)	Normal	1.46	#s calibrate imu #/s
Normal	SoftwareFault (0.69)	SoftwareFault	-1.20	#s landing canceled . #/s
Normal	Normal (0.28)	Normal	1.83	#s landing gear function restored #/s
Normal	Normal (0.28)	Normal	1.76	#s landing gear paused . #/s
Normal	Normal (0.28)	Normal	0.95	#s landing gear raising . #/s
Normal	Normal (0.28)	Normal	1.25	#s home point recorded #/s
Normal	ParamViolation (0.75)	ParamViolation	0.11	#s live stream video frame rate less than 9hz . #/s
Normal	Normal (0.28)	Normal	1.51	#s fly with caution #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.51	#s low power . #/s
Normal	Normal (0.28)	Normal	2.05	#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.51	#s low power . #/s
Normal	Normal (0.27)	Normal	1.45	#s returning home . #/s
SurroundingEnvironment	SurroundingEnvironment (0.75)	SurroundingEnvironment	1.69	#s magnetic filed interference . #/s
Normal	Normal (0.28)	Normal	1.54	#s exit p - gps mode . #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.01	#s yaw error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.59)	SurroundingEnvironment	0.73	#s manned aircraft detected

Normal	Normal (0.28)	Normal	1.51	nearby . #/s
				#s fly with caution #/s
ParamViolation	ParamViolation (0.80)	ParamViolation	1.50	#s max altitude approached . #/s
				#s wait for the gps satellite signal recovery before ascend #/s
ParamViolation	ParamViolation (0.80)	ParamViolation	1.81	#s max flight altitude reached . #/s
				#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.80)	ParamViolation	-0.80	#s max flight distance reached . #/s
				#s adjust in main controller settings if necessary . #/s
ParamViolation	ParamViolation (0.80)	ParamViolation	0.17	#s maximum flight distance reached . #/s
				#s adjust the distance in mc settings if required . #/s
HardwareFault	HardwareFault (0.67)	HardwareFault	1.58	#s mobile device cpu fully loaded . #/s
				#s related performance will be affected . #/s
Normal	Normal (0.28)	Normal	2.03	#s mobile

SoftwareFault	CommunicationIssue (0.22)	CommunicationIssue	-0.53	device
				version too
				old to support
				hd image
				transmission
Normal	Normal (0.28)	Normal	-1.70	and the
				image
				transmission
				mode has
				been switch
HardwareFault	HardwareFault (0.67)	HardwareFault	1.36	to normal
				mode . #/s
				#s motor is
				blocked . #/s
				#s motor
Normal	Normal (0.28)	Normal	2.40	stuck . #/s
				#s check for
				objects
				blocking
				motor or
Normal	Normal (0.27)	Normal	1.43	contact dji
				support for
				assistance
				#/s
				#s motors
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.58	started . #/s
				#s no gps
				signal . #/s
				#s aircraft
				unable to
Normal	Normal (0.28)	Normal	1.51	hover . #/s
				#s fly with
				caution #/s
				#s no gps
				signal . #/s
Normal	Normal (0.28)	Normal	1.60	#s unable to
				hover . #/s
				#s fly with
				caution #/s
				#s obstacle
Normal	Normal (0.28)	Normal	1.83	avoidance
				disabled . #/s
				#s landing
				gear lowered
				. #/s
Normal	Normal (0.28)	Normal	1.60	#s obstacle
				avoidance
				disabled . #/s

Normal	Normal (0.28)	Normal	1.60	#s obstacle avoidance disabled . #/s
Normal	Normal (0.28)	Normal	1.83	#s landing gear lowered . #/s
Normal	Normal (0.28)	Normal	1.43	#s obstacle avoidance has been disabled . #/s
Normal	Normal (0.28)	Normal	1.43	#s precision landing #/s
Normal	Normal (0.28)	Normal	1.11	#s quickshot has ended #/s
Normal	Normal (0.28)	Normal	1.66	#s recenter gimbal pan #/s
Normal	Normal (0.28)	Normal	0.47	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.75)	SurroundingEnvironment	1.71	#s remote controller in high interference environment . #/s
Normal	Normal (0.28)	Normal	1.85	#s manually adjust flight route or return to home #/s
Normal	Normal (0.28)	Normal	1.60	#s return - to - home altitude : 65ft #/s
Normal	Normal (0.28)	Normal	1.55	#s return - to - home altitude : 98ft . #/s
Normal	Normal (0.28)	Normal	2.09	#s rth : ascending to rth altitude . #/s
Normal	Normal (0.28)	Normal	-0.74	#s rth : heading alignment . #/s

Normal	Normal (0.28)	Normal	1.72	#s rth altitude : 65ft . #/s
Normal	Normal (0.28)	Normal	2.08	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.87)	CommunicationIssue	1.11	#s signal lost . #/s
Normal	Normal (0.28)	Normal	2.22	#s aircraft returning to home point #/s
Normal	Normal (0.28)	Normal	1.74	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.75)	SurroundingEnvironment	1.50	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.17	#s aircraft unable to return to home automatically . #/s
Normal	Normal (0.28)	Normal	1.17	#s lower altitude immediately and return to home manually #/s
Normal	Normal (0.28)	Normal	1.77	#s switched to s ( sport ) - mode . #/s
Normal	Normal (0.28)	Normal	1.76	#s switched to t ( tripod ) - mode . #/s
Normal	Normal (0.28)	Normal	-0.67	#s take off in p - mode #/s
SoftwareFault	SoftwareFault (0.41)	SoftwareFault	0.54	#s vision sensor error . #/s
Normal	Normal (0.28)	Normal	1.54	#s contact dji support for assistance #/s
Normal	Normal (0.28)	Normal	0.95	#s vision systems and obstacle avoidance

Normal	Normal (0.28)	Normal	1.59	disabled #/s
				#s waypoint
				mission
SoftwareFault	SoftwareFault (0.70)	SoftwareFault	1.16	paused #/s
				#s weak gps
				signal . #/s
Normal	Normal (0.28)	Normal	1.80	#s aircraft is
				in attitude
				mode and
Normal	Normal (0.28)	Normal	1.43	hovering may
				be unstable .
				#/s
CommunicationIssue	CommunicationIssue (0.87)	CommunicationIssue	1.17	#s fly with
				caution . #/s
				#s weak
Normal	Normal (0.28)	Normal	1.62	signal . #/s
				#s adjust
				antennas #/s
RegulationViolation	RegulationViolation (0.86)	RegulationViolation	2.84	#s your
				aircraft is
				flying in an
Normal	Normal (0.28)	Normal	1.11	altitude zone
				( nnn ) . #/s
				#s please fly
Normal	Normal (0.28)	Normal	1.11	with caution
				#/s