

Legend: ■ Negative □ Neutral ■ Positive

Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
None	Normal (1.00)	Normal	-1.71	[CLS] <span style="color: red;">motors starting</span> . [SEP]
None	Normal (1.00)	Normal	0.48	[CLS] flight <span style="color: green;">mode changed</span> to starting <span style="color: red;">motors</span> . [SEP]
None	Normal (1.00)	Normal	0.02	<span style="color: green;">[CLS]</span> data recorder file index is 88 . [SEP]
None	Normal (1.00)	Normal	0.69	[CLS] <span style="color: green;">set return</span> to <span style="color: green;">home</span> ( rth ) altitude to 100 m ( 328 ft ) . [SEP]
None	Normal (1.00)	Normal	-1.69	[CLS] set <span style="color: red;">maximum</span> flight altitude to <span style="color: green;">500</span> m ( <span style="color: red;">1640</span> ft ) . [SEP]
None	Normal (1.00)	Normal	-1.71	[CLS] <span style="color: red;">motors starting</span> . [SEP]
None	Normal (1.00)	Normal	0.88	[CLS] flight <span style="color: green;">mode changed</span> to <span style="color: red;">manual takeoff</span> . [SEP]
None	Normal (1.00)	Normal	0.42	<span style="color: green;">[CLS]</span> home point updated . [SEP]
None	Normal (1.00)	Normal	-0.27	[CLS] rth altitude <span style="color: red;">adjusted to 100m</span> . [SEP]
None	Normal (1.00)	Normal	1.36	<span style="color: green;">[CLS]</span> flight <span style="color: green;">mode changed</span> to p - gps . [SEP]
None	Normal (1.00)	Normal	0.42	<span style="color: green;">[CLS]</span> home point updated . [SEP]
None	Normal (1.00)	Normal	-0.27	[CLS] rth altitude <span style="color: red;">adjusted to 100m</span> . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] <span style="color: green;">downward ambient light</span> too low . [SEP]
None	Normal (1.00)	Normal	0.08	<span style="color: green;">[CLS]</span> obstacle avoidance <span style="color: red;">unavailable</span> . [SEP]
None	Normal (1.00)	Normal	0.16	<span style="color: green;">[CLS]</span> fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward <span style="color: green;">ambient light</span> too low . [SEP]
None	Normal (1.00)	Normal	0.08	<span style="color: green;">[CLS]</span> obstacle avoidance <span style="color: red;">unavailable</span> . [SEP]
None	Normal (1.00)	Normal	0.16	<span style="color: green;">[CLS]</span> fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] <span style="color: green;">ambient light</span> too low . [SEP]
None	Normal (1.00)	Normal	0.08	<span style="color: green;">[CLS]</span> obstacle avoidance <span style="color: red;">unavailable</span> . [SEP]
None	Normal (1.00)	Normal	0.42	<span style="color: green;">[CLS]</span> home point updated . [SEP]
None	Normal (1.00)	Normal	-0.27	[CLS] rth altitude <span style="color: red;">adjusted to 100m</span> . [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.42	[CLS] home point updated . [SEP]
None	Normal (1.00)	Normal	-0.27	[CLS] rth altitude adjusted to 100m . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]

None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.54	[CLS] auto rth in 9 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]

None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.54	[CLS] auto rth in 9 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] auto rth in 8 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] auto rth in 8 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.53	[CLS] auto rth in 7 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.58	[CLS] auto rth in 6 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.49	[CLS] auto rth in 5 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]

None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.48	[CLS] auto rth in 4 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.56	[CLS] auto rth in 3 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] auto rth in 2 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.59	[CLS] auto rth in 1 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.59	[CLS] auto rth in 1 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.59	[CLS] auto rth in 1 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	Normal (1.00)	Normal	-1.38	[CLS] remaining battery only enough for rth . [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] aircraft returning . [SEP]



None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.71	[CLS] low battery rth . [SEP]
None	Normal (1.00)	Normal	1.21	[CLS] flight mode changed to go home . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.71	[CLS] low battery rth . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.68	[CLS] low battery . [SEP]
None	Normal (1.00)	Normal	0.59	[CLS] auto rth in 1 s . [SEP]
None	Normal (1.00)	Normal	0.36	[CLS] press the start / stop button to cancel . [SEP]
None	Normal (1.00)	Normal	-1.38	[CLS] remaining battery only enough for rth . [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] aircraft returning . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.71	[CLS] low battery rth . [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth . [SEP]
None	Normal (1.00)	Normal	-1.38	[CLS] remaining battery only enough for rth . [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] aircraft returning . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]



None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.71	[CLS] low battery rth . [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth . [SEP]
None	Normal (1.00)	Normal	-1.38	[CLS] remaining battery only enough for rth . [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] aircraft returning . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	Normal (1.00)	Normal	0.20	[CLS] rth ascending . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	Normal (1.00)	Normal	-0.05	[CLS] controller triggered aircraft to descend . [SEP]
None	Normal (1.00)	Normal	0.19	[CLS] auto rth canceled . [SEP]
None	Normal (1.00)	Normal	1.36	[CLS] flight mode changed to p - gps . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.71	[CLS] low battery rth . [SEP]
None	Normal (1.00)	Normal	-0.05	[CLS] controller triggered aircraft to descend . [SEP]
None	Normal (1.00)	Normal	0.19	[CLS] auto rth canceled . [SEP]
None	Normal (1.00)	Normal	-1.38	[CLS] remaining battery only enough for rth . [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] aircraft returning . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]

None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	Normal (1.00)	Normal	0.20	[CLS] rth ascending . [SEP]
None	HardwareFault (0.99)	HardwareFault	1.71	[CLS] low battery rth . [SEP]
None	Normal (1.00)	Normal	-0.05	[CLS] controller triggered aircraft to descend . [SEP]
None	Normal (1.00)	Normal	0.19	[CLS] auto rth canceled . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.95	[CLS] forward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.08	[CLS] downward ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] fly with caution . [SEP]
None	Normal (1.00)	Normal	0.20	[CLS] rth ascending . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]

None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	0.50	[CLS] flight mode changed to confirm landing . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.80	[CLS] ambient light too low . [SEP]
None	Normal (1.00)	Normal	0.08	[CLS] obstacle avoidance unavailable . [SEP]
None	Normal (1.00)	Normal	-0.05	[CLS] auto landing in progress . [SEP]
None	Normal (1.00)	Normal	-0.05	[CLS] auto landing in progress . [SEP]
None	Normal (1.00)	Normal	1.36	[CLS] flight mode changed to p - gps . [SEP]