

**Legend:** ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	<b>Normal (1.00)</b>	Normal	<b>0.15</b>	[CLS] a passenger aircraft is nearby . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.17</b>	[CLS] fly with caution [SEP] [CLS] account
Normal	<b>Normal (0.98)</b>	Normal	<b>-1.17</b>	not logged in . [SEP] [CLS] flight altitude and distance restricted to nnn and nnn . [SEP]
ParamViolation	<b>ParamViolation (0.97)</b>	ParamViolation	<b>2.27</b>	[CLS] check and log in [SEP] [CLS] activetrack flight paused [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.12</b>	[CLS] aircraft activetrack available at max speed . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.50</b>	[CLS] obstacle avoidance is not available [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.69</b>	[CLS] aircraft activetrack available at max speed . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] when exceeding nnn , obstacle avoidance is not available [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.69</b>	[CLS] aircraft activetrack available at max speed . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.06</b>	[CLS] aircraft nnn , obstacle avoidance is not available [SEP]

Normal	<b>Normal (1.00)</b>	Normal	<b>0.01</b>	activetrack max speed of nnn and obstacle avoidance functions normally [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>2.57</b>	[CLS] aircraft core board overheated [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.39</b>	[CLS] aircraft entered fixed - wing mode . [SEP]
Normal	<b>Normal (0.62)</b>	Normal	<b>-2.06</b>	[CLS] current flight speed is nnn . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.68</b>	[CLS] press c2 to exit [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.51</b>	[CLS] aircraft flight control unlocked [SEP]
RegulationViolation	<b>RegulationViolation (0.92)</b>	RegulationViolation	<b>1.93</b>	[CLS] aircraft in restricted zones . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.37</b>	[CLS] check map to find recommended zones [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.06</b>	[CLS] aircraft is in attitude mode , so that it will not hover . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.81</b>	[CLS] please fly with caution . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.16</b>	[CLS] aircraft is in tripod mode . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.23</b>	[CLS] exit this mode and try again

[SEP]

[CLS] aircraft  
is returning

Normal	<b>Normal (1.00)</b>	Normal	<b>0.65</b>	to the starting point [SEP]
ParamViolation	<b>ParamViolation (0.97)</b>	ParamViolation	<b>2.05</b>	[CLS] aircraft out of range [SEP]
RegulationViolation	<b>RegulationViolation (0.91)</b>	RegulationViolation	<b>2.13</b>	[CLS] approaching a no - fly zone . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.15</b>	[CLS] rth may be affected . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.17</b>	[CLS] fly with caution [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.49</b>	[CLS] arrived at start point . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.44</b>	[CLS] starting waypoint mission [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.95</b>	[CLS] auto landing initiated [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.11</b>	[CLS] auxiliary bottom light turned off [SEP]
SoftwareFault	<b>SoftwareFault (0.98)</b>	SoftwareFault	<b>1.93</b>	[CLS] backward obstacle sensing is not functioning . [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.87</b>	[CLS] battery cell broken , please replace the battery [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.23</b>	[CLS] battery error . [SEP]
				[CLS] aircraft returning to

<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.50</b>	home automatically [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.89</b>	[CLS] battery power low . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.83</b>	[CLS] check battery status and charge or warm up battery [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.79)</b>	<b>HardwareFault</b>	<b>1.83</b>	[CLS] cache space full [SEP]
<b>SurroundingEnvironment</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.33</b>	[CLS] calibration subject is too close . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] recalibrate using a subject that is farther away [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.98)</b>	<b>HardwareFault</b>	<b>1.99</b>	[CLS] camera busy , cannot enter playback [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.10</b>	[CLS] cannot enable intelligent flight mode [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.67</b>	[CLS] low battery [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.57</b>	[CLS] cannot start return to home due to weak gps signal [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.26</b>	[CLS] cannot start self - timer . [SEP]
<b>SoftwareFault</b>	<b>ParamViolation (0.80)</b>	<b>ParamViolation</b>	<b>0.18</b>	exposure time is too long [SEP]

<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.11</b>	[CLS] cannot switch flight mode . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.95</b>	[CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.18</b>	[CLS] cannot track subject [SEP]
<b>SurroundingEnvironment</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.07</b>	[CLS] no image [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.88</b>	[CLS] please retry [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.18</b>	[CLS] cannot track subject [SEP]
<b>SurroundingEnvironment</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.41</b>	[CLS] subject too large [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.94</b>	[CLS] move away and retry [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.44</b>	[CLS] color display in the liveview has been enhanced . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.66</b>	[CLS] videos and photos will still be shot in d - log mode [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.65</b>	[CLS] compass abnormal . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.02</b>	[CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft .

[SEP]

Normal	<b>Normal (1.00)</b>	Normal	<b>-0.24</b>	[CLS] the ground or walls may contain metal . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.59</b>	[CLS] move away from sources of interference before attempting flight . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.40</b>	[CLS] 2 . calibrate compass before takeoff [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.26</b>	[CLS] compass error [SEP]
HardwareFault	<b>HardwareFault (0.54)</b>	HardwareFault	<b>1.23</b>	[CLS] compass error , calibration required [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.30</b>	[CLS] compass error . [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.30</b>	[CLS] compass error . [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.58</b>	[CLS] compass disconnected [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.30</b>	[CLS] compass error . [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (0.97)</b>	SurroundingEnvironment	<b>1.50</b>	[CLS] magnetic filed interference . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.47</b>	[CLS] exit p - gps mode [SEP]

<b>SoftwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>0.07</b>	[CLS] compass initialization failed. [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.92</b>	[CLS] restart aircraft [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.95</b>	[CLS] critical low battery . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.72</b>	[CLS] aircraft in auto power off protection . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.44</b>	[CLS] forced landing in progress [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.95</b>	[CLS] critical low battery . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.66</b>	[CLS] aircraft landing automatically [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.95</b>	[CLS] critical low battery . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.60</b>	[CLS] return to home or land promptly [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>2.02</b>	[CLS] critically low power . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.63</b>	[CLS] aircraft is landing [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>2.02</b>	[CLS] critically low power . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.46</b>	[CLS] aircraft landing . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.46</b>	[CLS] aircraft landing . [SEP]
				[CLS] throttle up to reduce

Normal	<b>Normal (1.00)</b>	Normal	<b>0.53</b>	the speed of descent and use sticks to avoid obstacles [SEP] [CLS] critically low voltage warning . [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.89</b>	[CLS] aircraft
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.04</b>	will be forced to land [SEP] [CLS] critically low voltage . [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>2.03</b>	[CLS] aircraft
Normal	<b>Normal (1.00)</b>	Normal	<b>0.60</b>	will land [SEP] [CLS] data recorder file index is 15 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.37</b>	[CLS] data recorder file index is 17 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.33</b>	[CLS] data recorder file index is 30 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.43</b>	[CLS] data recorder file index is 45 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.28</b>	[CLS] data recorder file index is 46 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.29</b>	[CLS] data recorder file index is 65 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.73</b>	[CLS] disable sd card read and write

				protection or change card [SEP]
				[CLS]
<b>CommunicationIssue</b>	<b>CommunicationIssue (0.93)</b>	<b>CommunicationIssue</b>	<b>1.75</b>	downlink lost . [SEP]
				[CLS]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.41</b>	downlink restored (
				after 0m 2 .
				9s ) . [SEP]
<b>Normal</b>	<b>HardwareFault (0.92)</b>	<b>HardwareFault</b>	<b>-1.75</b>	[CLS] drone is vibrating [SEP]
				[CLS] entered
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.68</b>	cruise control mode . [SEP]
				[CLS] press
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.28</b>	c1 or c2 to exit [SEP]
				[CLS]
<b>ParamViolation</b>	<b>ParamViolation (0.96)</b>	<b>ParamViolation</b>	<b>2.13</b>	excessive attitude angle detected [SEP]
				[CLS] forward obstacle
<b>SoftwareFault</b>	<b>SoftwareFault (0.96)</b>	<b>SoftwareFault</b>	<b>1.24</b>	avoidance has stopped working [SEP]
				[CLS] exit
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.19</b>	backward sensing system [SEP]
				[CLS]
<b>SurroundingEnvironment</b>	<b>SurroundingEnvironment (0.97)</b>	<b>SurroundingEnvironment</b>	<b>2.08</b>	ambient light is too weak [SEP]
				[CLS] exited visual
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.49</b>	avoidance system . [SEP]
				[CLS] exiting gps mode : unknown
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.25</b>	error [SEP]

<b>ParamViolation</b>	<b>ParamViolation (0.97)</b>	<b>ParamViolation</b>	<b>1.87</b>	[CLS] extra payload detected . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.66</b>	[CLS] flight performance will be affected . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.17</b>	[CLS] fly with caution [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.81</b>	[CLS] forward obstacle sensing is not functioning . [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.88</b>	[CLS] forward obstacle sensing not responding [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>2.16</b>	[CLS] gimbal motor overloaded . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.45</b>	[CLS] check whether gimbal can rotate freely [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.88</b>	[CLS] gimbal pitch limit reached . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.64</b>	[CLS] ground plain . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.67</b>	[CLS] safe to land . [SEP]
<b>ParamViolation</b>	<b>ParamViolation (0.95)</b>	<b>ParamViolation</b>	<b>1.67</b>	[CLS] high altitude . [SEP]
<b>Normal</b>	<b>ParamViolation (0.85)</b>	<b>ParamViolation</b>	<b>-2.38</b>	[CLS] aircraft braking distance increased and flight time decreased . [SEP]

Normal	<b>Normal (1.00)</b>	Normal	<b>1.17</b>	[CLS] fly with caution [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (0.97)</b>	SurroundingEnvironment	<b>1.76</b>	[CLS] high wind velocity . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.59</b>	[CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (0.97)</b>	SurroundingEnvironment	<b>1.76</b>	[CLS] high wind velocity . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.59</b>	[CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (0.97)</b>	SurroundingEnvironment	<b>1.76</b>	[CLS] high wind velocity . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.57</b>	[CLS] fly with caution and land in a safe place asap . [SEP]
Normal	<b>ParamViolation (0.95)</b>	ParamViolation	<b>-2.01</b>	[CLS] high - altitude flight [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.17</b>	[CLS] fly with caution [SEP]
Normal	<b>Normal (0.88)</b>	Normal	<b>-0.60</b>	[CLS] aircraft braking distance is extended [SEP]
Normal	<b>ParamViolation (0.92)</b>	ParamViolation	<b>-2.01</b>	[CLS] flight time is shortened . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.59</b>	[CLS] home

				point updated
				. [SEP]
				[CLS] imu
				attitude
				restricted .
				[SEP]
				[CLS] ensure
ParamViolation	<b>ParamViolation (0.58)</b>	<b>ParamViolation</b>	<b>1.44</b>	aircraft is
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.78</b>	level [SEP]
SoftwareFault	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.35</b>	[CLS] imu not
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.42</b>	calibrated .
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.86</b>	[CLS]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.78</b>	calibrate imu
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[CLS] landing
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	canceled .
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.91</b>	[SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.17</b>	[CLS] landing
HardwareFault	<b>HardwareFault (0.60)</b>	<b>HardwareFault</b>	<b>1.79</b>	gear function
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.51</b>	restored
HardwareFault	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.79</b>	[SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.51</b>	[CLS] landing
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	gear paused .
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[CLS] landing
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	gear raising .
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[CLS] home
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	point
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	recorded
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[CLS] live
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	stream video
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	[CLS] fly with
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	caution [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.79</b>	[CLS] low
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.51</b>	power . [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.79</b>	[CLS] aircraft
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.51</b>	is returning
HardwareFault	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.79</b>	to the home
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.51</b>	point . [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.79</b>	[CLS] low
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.51</b>	power . [SEP]

<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.83</b>	[CLS] returning home . [SEP]
<b>SurroundingEnvironment</b>	<b>SurroundingEnvironment (0.97)</b>	<b>SurroundingEnvironment</b>	<b>1.50</b>	[CLS] magnetic filed interference . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.35</b>	[CLS] exit p - gps mode . [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>2.14</b>	[CLS] yaw error . [SEP]
<b>SurroundingEnvironment</b>	<b>SurroundingEnvironment (0.78)</b>	<b>SurroundingEnvironment</b>	<b>0.85</b>	[CLS] manned aircraft detected nearby . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.17</b>	[CLS] fly with caution [SEP]
<b>ParamViolation</b>	<b>ParamViolation (0.96)</b>	<b>ParamViolation</b>	<b>1.49</b>	[CLS] max altitude approached . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] wait for the gps satellite
<b>ParamViolation</b>	<b>ParamViolation (0.97)</b>	<b>ParamViolation</b>	<b>1.95</b>	signal recovery before ascend [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.59</b>	[CLS] max flight altitude reached . [SEP]
<b>ParamViolation</b>	<b>ParamViolation (0.97)</b>	<b>ParamViolation</b>	<b>1.97</b>	[CLS] adjust in main controller settings if necessary [SEP]

<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.47</b>	in main controller settings if necessary . [SEP]
<b>ParamViolation</b>	<b>ParamViolation (0.97)</b>	<b>ParamViolation</b>	<b>2.08</b>	[CLS] maximum flight distance reached . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.64</b>	[CLS] adjust the distance in mc settings if required . [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>2.26</b>	[CLS] mobile device cpu fully loaded . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.59</b>	[CLS] related performance will be affected . [SEP]
<b>SoftwareFault</b>	<b>Normal (0.99)</b>	<b>Normal</b>	<b>0.02</b>	[CLS] mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.25</b>	[CLS] motor is blocked . [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.56</b>	[CLS] motor stuck . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.45</b>	[CLS] check for objects blocking motor or contact dji support for

				assistance
				[SEP]
<b>Normal</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>-1.82</b>	[CLS] motors started . [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.65</b>	[CLS] no gps signal . [SEP]
<b>Normal</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>-1.34</b>	[CLS] aircraft unable to hover . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.17</b>	[CLS] fly with caution [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>1.65</b>	[CLS] no gps signal . [SEP]
<b>Normal</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>-1.48</b>	[CLS] unable to hover . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.17</b>	[CLS] fly with caution [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.35</b>	[CLS] obstacle avoidance disabled . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.65</b>	[CLS] landing gear lowered . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.35</b>	[CLS] obstacle avoidance disabled . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.35</b>	[CLS] obstacle avoidance disabled . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.65</b>	[CLS] landing gear lowered . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.31</b>	[CLS] obstacle avoidance has been disabled . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.24</b>	[CLS] precision

Normal	<b>Normal (1.00)</b>	Normal	<b>0.60</b>	landing [SEP] [CLS] quickshot has ended [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.08</b>	[CLS] recenter gimbal pan [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.35</b>	[CLS] rectifying aircraft position [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (0.97)</b>	SurroundingEnvironment	<b>1.92</b>	[CLS] remote controller in high interference environment . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.76</b>	[CLS] manually adjust flight route or return to home [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.49</b>	[CLS] return - to - home altitude : 65ft [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.37</b>	[CLS] return - to - home altitude : 98ft . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.22</b>	[CLS] rth : ascending to rth altitude . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.40</b>	[CLS] rth : heading alignment . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.07</b>	[CLS] rth altitude : 65ft . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.03</b>	[CLS] rth altitude : 98ft . [SEP]
CommunicationIssue	<b>CommunicationIssue (0.93)</b>	CommunicationIssue	<b>1.45</b>	[CLS] signal

Normal	<b>Normal (1.00)</b>	Normal	<b>0.43</b>	lost . [SEP] [CLS] aircraft returning to home point [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.94</b>	[CLS] sprayer turned on [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (0.97)</b>	SurroundingEnvironment	<b>1.64</b>	[CLS] strong wind warning . [SEP]
SoftwareFault	<b>SoftwareFault (0.98)</b>	SoftwareFault	<b>1.49</b>	[CLS] aircraft unable to return to home automatically . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.70</b>	[CLS] lower altitude immediately and return to home manually [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.48</b>	[CLS] switched to s ( sport ) - mode . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.34</b>	[CLS] switched to t ( tripod ) - mode . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.56</b>	[CLS] take off in p - mode [SEP]
SoftwareFault	<b>HardwareFault (0.98)</b>	HardwareFault	<b>0.18</b>	[CLS] vision sensor error. [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.54</b>	[CLS] contact dji support for assistance [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.20</b>	[CLS] vision systems and obstacle avoidance disabled [SEP]

Normal	<b>Normal (1.00)</b>	Normal	<b>0.51</b>	[CLS] waypoint mission paused [SEP]
SoftwareFault	<b>SoftwareFault (0.98)</b>	SoftwareFault	<b>1.54</b>	[CLS] weak gps signal. [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.49</b>	[CLS] aircraft is in attitude mode and hovering may be unstable . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.79</b>	[CLS] fly with caution. [SEP]
CommunicationIssue	<b>CommunicationIssue (0.93)</b>	CommunicationIssue	<b>1.46</b>	[CLS] weak signal. [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.87</b>	[CLS] adjust antennas [SEP]
RegulationViolation	<b>RegulationViolation (0.92)</b>	RegulationViolation	<b>2.58</b>	[CLS] your aircraft is flying in an altitude zone ( nnn ) . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.96</b>	[CLS] please fly with caution [SEP]