

**Legend:** ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
None	<b>Normal (1.00)</b>	Normal	<b>0.17</b>	[CLS] motors starting [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.64</b>	[CLS] flight mode changed to starting motors [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.02</b>	[CLS] data recorder file index is 88 . [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.40</b>	[CLS] set return to home ( rth ) altitude to 100 m ( 328 ft ) [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>-1.61</b>	[CLS] set maximum flight altitude to 500 m ( 1640 ft ) [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.17</b>	[CLS] motors starting [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.87</b>	[CLS] flight mode changed to manual takeoff [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.55</b>	[CLS] home point updated [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>-0.31</b>	[CLS] rth altitude adjusted to 100m [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>1.50</b>	[CLS] flight mode changed to p - gps [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.55</b>	[CLS] home point updated [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>-0.31</b>	[CLS] rth altitude adjusted to 100m [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.55</b>	[CLS] home point updated [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>-0.31</b>	[CLS] rth altitude adjusted to 100m [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.23</b>	[CLS] fly with caution [SEP]



None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.51</b>	[CLS] auto rth in 9 s [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.51</b>	[CLS] auto rth in 9 s [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]

<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.52</b>	[CLS] auto rth in 8 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.52</b>	[CLS] auto rth in 8 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.49</b>	[CLS] auto rth in 7 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]

<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.55</b>	[CLS] auto rth in 6 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.46</b>	[CLS] auto rth in 5 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.48</b>	[CLS] auto rth in 4 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]

<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.52</b>	[CLS] auto rth in 3 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.53</b>	[CLS] auto rth in 2 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.56</b>	[CLS] auto rth in 1 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.56</b>	[CLS] auto rth in 1 s [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance

None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] fly with caution [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] fly with caution [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] ambient light too low [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.56</b>	[CLS] low battery [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] auto rth in 1 s [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.27</b>	[CLS] press the start / stop button to cancel [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.20</b>	[CLS] remaining battery only enough for rth [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] aircraft returning [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] fly with caution [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.64</b>	[CLS] low battery rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.86</b>	[CLS] flight mode changed to go home [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.64</b>	[CLS] low battery rth [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.59</b>	[CLS] low battery [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.56</b>	[CLS] auto rth in 1 s [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.10</b>	[CLS] press the start / stop button to cancel [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.27</b>	[CLS] remaining battery only enough for rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.20</b>	[CLS] aircraft returning [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
	<b>SurroundingEnvironment</b>			[CLS] downward ambient light too

<b>None</b>	<b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.22</b>	[CLS] press brake button to cancel rth [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.64</b>	[CLS] low battery rth [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.22</b>	[CLS] press brake button to cancel rth [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.27</b>	[CLS] remaining battery only enough for rth [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.20</b>	[CLS] aircraft returning [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.64</b>	[CLS] low battery rth [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.22</b>	[CLS] press brake button to cancel rth [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.27</b>	[CLS] remaining battery only enough for rth [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.20</b>	[CLS] aircraft returning [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] rth ascending [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.01</b>	[CLS] controller triggered aircraft to descend [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.32</b>	[CLS] auto rth canceled [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.50</b>	[CLS] flight mode changed to p -

None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.64</b>	gps [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.01</b>	[CLS] low battery rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.32</b>	[CLS] controller triggered aircraft to descend [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.27</b>	[CLS] auto rth canceled [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.20</b>	[CLS] remaining battery only enough for rth [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] aircraft returning [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] fly with caution [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] fly with caution [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.64</b>	[CLS] rth ascending [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.01</b>	[CLS] low battery rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.32</b>	[CLS] controller triggered aircraft to descend [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] auto rth canceled [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] fly with caution [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] rth ascending [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]

<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.07</b>	[CLS] flight mode changed to confirm landing [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment</b> <b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.16</b>	[CLS] auto landing in progress [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.16</b>	[CLS] auto landing in progress [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.50</b>	[CLS] flight mode changed to p - gps [SEP]