True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
None	Normal (1.00)	Normal	0.17	[CLS] motors starting [SEP]
None	Normal (1.00)	Normal	0.64	[CLS] flight mode changed to starting motors [SEP]
None	Normal (1.00)	Normal	0.02	[CLS] data recorder file index is 88 . [SEP]
None	Normal (1.00)	Normal	0.40	[CLS] set return to home (rth) altitude to 100 m (328 ft) [SEP]
None	Normal (1.00)	Normal	-1.61	[CLS] set maximum flight altitude to 500 m (1640 ft) [SEP]
None	Normal (1.00)	Normal	0.17	[CLS] motors starting [SEP]
None	Normal (1.00)	Normal	0.87	[CLS] flight mode changed to manual takeoff [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] home point updated [SEP]
None	Normal (1.00)	Normal	-0.31	[CLS] rth altitude adjusted to 100m [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p - gps [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] home point updated [SEP]
None	Normal (1.00)	Normal	-0.31	[CLS] rth altitude adjusted to 100m [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] home point updated [SEP]
None	Normal (1.00)	Normal	-0.31	[CLS] rth altitude adjusted to 100m [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] home point updated [SEP]
None	Normal (1.00)	Normal	-0.31	[CLS] rth altitude adjusted to 100m [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance

				unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.51	[CLS] auto rth in 9 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.51	[CLS] auto rth in 9 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.52	[CLS] auto rth in 8 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.52	[CLS] auto rth in 8 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.49	[CLS] auto rth in 7 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]

None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] auto rth in 6 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.46	[CLS] auto rth in 5 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.48	[CLS] auto rth in 4 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]

None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.52	[CLS] auto rth in 3 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.53	[CLS] auto rth in 2 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.56	[CLS] auto rth in 1 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.56	[CLS] auto rth in 1 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance

				unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.56	[CLS] auto rth in 1 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	Normal (1.00)	Normal	-1.27	[CLS] remaining battery only enough for rth [SEP]
None	Normal (1.00)	Normal	0.20	[CLS] aircraft returning [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	HardwareFault (0.99)	HardwareFault	1.64	[CLS] low battery rth [SEP]
None	Normal (1.00)	Normal	0.86	[CLS] flight mode changed to go home [SEP]
None	HardwareFault (0.99)	HardwareFault	1.64	[CLS] low battery rth [SEP]
None	HardwareFault (0.99)	HardwareFault	1.59	[CLS] low battery [SEP]
None	Normal (1.00)	Normal	0.56	[CLS] auto rth in 1 s [SEP]
None	Normal (1.00)	Normal	0.10	[CLS] press the start / stop button to cancel [SEP]
None	Normal (1.00)	Normal	-1.27	[CLS] remaining battery only enough for rth [SEP]
None	Normal (1.00)	Normal	0.20	[CLS] aircraft returning [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
	SurroundingEnvironment			[CLS] downward ambient light too

None	(0.99)	SurroundingEnvironment	2.13	low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	HardwareFault (0.99)	HardwareFault	1.64	[CLS] low battery rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	Normal (1.00)	Normal	-1.27	[CLS] remaining battery only enough for rth [SEP]
None	Normal (1.00)	Normal	0.20	[CLS] aircraft returning [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	HardwareFault (0.99)	HardwareFault	1.64	[CLS] low battery rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	Normal (1.00)	Normal	-1.27	[CLS] remaining battery only enough for rth [SEP]
None	Normal (1.00)	Normal	0.20	[CLS] aircraft returning [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p -

				gps [SEP]
None	HardwareFault (0.99)	HardwareFault	1.64	[CLS] low battery rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	Normal (1.00)	Normal	-1.27	[CLS] remaining battery only enough for rth [SEP]
None	Normal (1.00)	Normal	0.20	[CLS] aircraft returning [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	HardwareFault (0.99)	HardwareFault	1.64	[CLS] low battery rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.01	[CLS] forward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.07	[CLS] flight mode changed to confirm landing [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] auto landing in progress [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] auto landing in progress [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p - gps [SEP]