

Legend: ■ Negative □ Neutral ■ Positive

| True Label | Predicted Label | Attribution Label | Attribution Score | Word Importance |
|------------------------|-----------------------|------------------------|-------------------|---|
| SurroundingEnvironment | Normal (1.00) | SurroundingEnvironment | -0.69 | [CLS] a passenger aircraft is nearby . [SEP] |
| | | | | [CLS] fly with caution [SEP] |
| | | | | [CLS] account not logged in . [SEP] |
| Normal | Normal (1.00) | Normal | 1.26 | [CLS] flight altitude and distance restricted to nnn and nnn . [SEP] |
| | | | | [CLS] check and log in [SEP] |
| | | | | [CLS] activetrack flight paused [SEP] |
| ParamViolation | ParamViolation (0.95) | ParamViolation | -0.39 | [CLS] aircraft activetrack available at max speed . [SEP] |
| | | | | [CLS] obstacle avoidance is not available [SEP] |
| | | | | [CLS] aircraft activetrack available at max speed . [SEP] |
| Normal | Normal (1.00) | Normal | 1.60 | [CLS] when exceeding nnn , obstacle avoidance is not available [SEP] |
| | | | | [CLS] aircraft |
| | | | | |
| Normal | Normal (1.00) | Normal | 1.09 | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 1.60 | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 0.91 | |
| | | | | |
| | | | | |

| | | | | |
|---------------------|----------------------------|---------------------|-------|-----------------|
| | | | | activetrack |
| | | | | max speed of |
| Normal | Normal (1.00) | Normal | 1.13 | nnn and |
| | | | | obstacle |
| | | | | avoidance |
| | | | | functions |
| | | | | normally |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.08 | core board |
| | | | | overheated |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | -0.54 | entered fixed |
| | | | | - wing mode . |
| | | | | [SEP] |
| | | | | [CLS] current |
| Normal | Normal (0.99) | Normal | -0.63 | flight speed is |
| | | | | nnn . [SEP] |
| | | | | [CLS] press |
| Normal | Normal (0.99) | Normal | 1.12 | c2 to exit |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | 0.95 | flight control |
| | | | | unlocked |
| | | | | [SEP] |
| RegulationViolation | RegulationViolation (0.99) | RegulationViolation | 0.86 | [CLS] aircraft |
| | | | | in restricted |
| | | | | zones . [SEP] |
| | | | | [CLS] check |
| Normal | Normal (1.00) | Normal | 1.16 | map to find |
| | | | | recommended |
| | | | | zones [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (0.97) | Normal | 0.04 | is in attitude |
| | | | | mode , so that |
| | | | | it will not |
| | | | | hover . [SEP] |
| | | | | [CLS] please |
| Normal | Normal (1.00) | Normal | 1.19 | fly with |
| | | | | caution . |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | 1.24 | is in tripod |
| | | | | mode . [SEP] |
| | | | | [CLS] exit |
| Normal | Normal (1.00) | Normal | 1.23 | this mode and |
| | | | | try again |

| | | | | |
|---------------------|----------------------------|---------------------|-------|--|
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] aircraft is returning to the starting point [SEP] |
| ParamViolation | ParamViolation (0.64) | ParamViolation | 1.85 | [CLS] aircraft out of range [SEP] |
| RegulationViolation | RegulationViolation (0.99) | RegulationViolation | 1.90 | [CLS] approaching a no - fly zone . [SEP] |
| Normal | Normal (1.00) | Normal | -0.92 | [CLS] rth may be affected . [SEP] |
| Normal | Normal (1.00) | Normal | 1.26 | [CLS] fly with caution [SEP] |
| Normal | Normal (1.00) | Normal | 0.48 | [CLS] arrived at start point . [SEP] |
| Normal | Normal (1.00) | Normal | 1.27 | [CLS] starting waypoint mission [SEP] |
| Normal | Normal (1.00) | Normal | 1.42 | [CLS] auto landing initiated [SEP] |
| Normal | Normal (1.00) | Normal | -1.09 | [CLS] auxiliary bottom light turned off [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 2.00 | [CLS] backward obstacle sensing is not functioning . [SEP] |
| HardwareFault | HardwareFault (0.86) | HardwareFault | 1.61 | [CLS] battery cell broken , please replace the battery [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.34 | [CLS] battery error . [SEP] |
| | | | | [CLS] aircraft returning to |

| | | | | |
|------------------------|-----------------------|------------------------|-------|---|
| Normal | Normal (1.00) | Normal | 1.08 | home automatically [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.86 | [CLS] battery power low . [SEP] |
| Normal | Normal (1.00) | Normal | -0.72 | [CLS] check battery status and charge or warm up battery [SEP] |
| HardwareFault | Normal (0.90) | HardwareFault | 0.82 | [CLS] cache space full [SEP] |
| SurroundingEnvironment | SoftwareFault (0.91) | SurroundingEnvironment | -1.05 | [CLS] calibration subject is too close . [SEP] |
| Normal | Normal (1.00) | Normal | 1.15 | [CLS] recalibrate using a subject that is farther away [SEP] |
| HardwareFault | SoftwareFault (0.91) | HardwareFault | 0.66 | [CLS] camera busy , cannot enter playback [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | -0.12 | [CLS] cannot enable intelligent flight mode [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | -0.46 | [CLS] low battery [SEP] [CLS] cannot |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | -0.19 | start return to home due to weak gps signal [SEP] |
| SoftwareFault | SoftwareFault (0.92) | SoftwareFault | 1.22 | [CLS] cannot start self - timer . [SEP] |
| SoftwareFault | ParamViolation (0.53) | SoftwareFault | 1.30 | [CLS] exposure time is too long [SEP] |

| | | | | |
|------------------------|----------------------|------------------------|-------|---|
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | -0.37 | [CLS] cannot switch flight mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.34 | [CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP] |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.55 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | Normal (0.65) | SurroundingEnvironment | 0.22 | [CLS] no image [SEP] |
| Normal | Normal (1.00) | Normal | 1.18 | [CLS] please retry [SEP] |
| SoftwareFault | SoftwareFault (0.98) | SoftwareFault | 1.55 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.99) | SurroundingEnvironment | -1.50 | [CLS] subject too large [SEP] |
| Normal | Normal (1.00) | Normal | 0.74 | [CLS] move away and retry [SEP] |
| Normal | Normal (1.00) | Normal | 1.32 | [CLS] color display in the liveview has been enhanced . [SEP] |
| Normal | Normal (1.00) | Normal | 1.14 | [CLS] videos and photos will still be shot in d - log mode [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.42 | [CLS] compass abnormal . [SEP] |
| Normal | Normal (1.00) | Normal | 1.52 | [CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft . |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|---|
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -1.19 | [CLS] the ground or walls may contain metal . [SEP] |
| Normal | Normal (1.00) | Normal | -0.85 | [CLS] move away from sources of interference before attempting flight . [SEP] |
| Normal | Normal (1.00) | Normal | 0.51 | [CLS] 2 . calibrate compass before takeoff [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | -0.55 | [CLS] compass error [SEP] |
| HardwareFault | SoftwareFault (0.89) | HardwareFault | 0.54 | [CLS] compass error , calibration required [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | -1.00 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | -1.00 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | -0.58 | [CLS] compass disconnected [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | -1.00 | [CLS] compass error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.99) | SurroundingEnvironment | 0.10 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | -0.63 | [CLS] exit p - gps mode [SEP] |

| | | | | |
|---------------|----------------------|---------------|-------|----------------|
| SoftwareFault | HardwareFault (1.00) | SoftwareFault | 1.37 | [CLS] |
| | | | | compass |
| | | | | initialization |
| | | | | failed . [SEP] |
| Normal | Normal (1.00) | Normal | 0.12 | [CLS] restart |
| | | | | aircraft [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 0.04 | [CLS] critical |
| | | | | low battery . |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | -0.10 | [CLS] aircraft |
| | | | | in auto power |
| | | | | off protection |
| Normal | Normal (1.00) | Normal | 1.32 | . [SEP] |
| | | | | [CLS] forced |
| | | | | landing in |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 0.04 | progress |
| | | | | [SEP] |
| | | | | [CLS] critical |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 0.04 | low battery . |
| | | | | [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | 1.10 | landing |
| | | | | automatically |
| | | | | [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 0.04 | [CLS] critical |
| | | | | low battery . |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 1.13 | [CLS] return |
| | | | | to home or |
| | | | | land promptly |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.70 | [SEP] |
| | | | | [CLS] |
| | | | | critically low |
| Normal | Normal (1.00) | Normal | -1.25 | power . [SEP] |
| | | | | [CLS] aircraft |
| | | | | is landing |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.70 | [SEP] |
| | | | | [CLS] |
| | | | | critically low |
| Normal | Normal (1.00) | Normal | 0.07 | power . [SEP] |
| | | | | [CLS] aircraft |
| | | | | landing . |
| Normal | Normal (1.00) | Normal | 0.07 | [SEP] |
| | | | | [CLS] aircraft |
| | | | | landing . |
| Normal | Normal (1.00) | Normal | 0.07 | [SEP] |
| | | | | [CLS] throttle |
| | | | | up to reduce |

| | | | | |
|---------------|----------------------|---------------|-------|--|
| Normal | Normal (1.00) | Normal | 1.66 | the speed of descent and use sticks to avoid obstacles [SEP] [CLS] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.36 | critically low voltage warning . [SEP] [CLS] |
| Normal | Normal (0.99) | Normal | 1.25 | aircraft will be forced to land [SEP] [CLS] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.15 | critically low voltage . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 1.13 | aircraft will land [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 1.45 | data recorder file index is 15 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | -0.48 | data recorder file index is 17 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 1.16 | data recorder file index is 30 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 1.23 | data recorder file index is 45 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 1.21 | data recorder file index is 46 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 1.49 | data recorder file index is 65 . [SEP] [CLS] |
| Normal | Normal (1.00) | Normal | 0.65 | disable sd card read and write |

| | | | | |
|------------------------|----------------------------------|------------------------|-------|---|
| | | | | protection or change card [SEP] |
| CommunicationIssue | CommunicationIssue (0.98) | CommunicationIssue | -0.73 | [CLS] downlink lost [SEP] |
| Normal | Normal (1.00) | Normal | 1.37 | [CLS] downlink restored (after 0m 2 . 9s) . [SEP] |
| Normal | Normal (0.71) | Normal | 0.84 | [CLS] drone is vibrating [SEP] |
| Normal | Normal (1.00) | Normal | 1.27 | [CLS] entered cruise control mode . [SEP] |
| Normal | Normal (0.99) | Normal | 1.08 | [CLS] press c1 or c2 to exit [SEP] |
| ParamViolation | ParamViolation (0.76) | ParamViolation | 1.36 | [CLS] excessive attitude angle detected [SEP] |
| SoftwareFault | Normal (0.64) | SoftwareFault | 1.39 | [CLS] forward obstacle avoidance has stopped working [SEP] |
| Normal | Normal (1.00) | Normal | 0.78 | [CLS] exit backward sensing system [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 2.13 | [CLS] ambient light is too weak [SEP] |
| Normal | Normal (1.00) | Normal | -0.88 | [CLS] exited visual avoidance system . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.87 | [CLS] exiting gps mode : unknown error [SEP] |

| | | | | |
|----------------|-----------------------|----------------|-------|---|
| ParamViolation | ParamViolation (1.00) | ParamViolation | 2.19 | [CLS] extra payload detected . [SEP] |
| Normal | Normal (1.00) | Normal | -0.75 | [CLS] flight performance will be affected . [SEP] |
| Normal | Normal (1.00) | Normal | 1.26 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.57 | [CLS] forward obstacle sensing is not functioning . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.88 | [CLS] forward obstacle sensing not responding [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 0.72 | [CLS] gimbal motor overloaded . [SEP] |
| Normal | Normal (1.00) | Normal | -0.31 | [CLS] check whether gimbal can rotate freely [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.82 | [CLS] gimbal pitch limit reached . [SEP] |
| Normal | Normal (1.00) | Normal | 0.65 | [CLS] ground plain . [SEP] |
| Normal | Normal (1.00) | Normal | 1.05 | [CLS] safe to land . [SEP] |
| ParamViolation | ParamViolation (0.61) | ParamViolation | -1.08 | [CLS] high altitude . [SEP] |
| Normal | Normal (0.86) | Normal | -0.94 | [CLS] aircraft braking distance increased and flight time decreased . [SEP] |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| Normal | Normal (1.00) | Normal | 1.26 | [CLS] fly with caution [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.62 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 1.40 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.62 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 1.40 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.62 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 1.41 | [CLS] fly with caution and land in a safe place asap . [SEP] |
| Normal | Normal (0.80) | Normal | 0.57 | [CLS] high - altitude flight [SEP] |
| Normal | Normal (1.00) | Normal | 1.26 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.97) | Normal | -0.19 | [CLS] aircraft braking distance is extended [SEP] |
| Normal | Normal (1.00) | Normal | -1.03 | [CLS] flight time is shortened . [SEP] |
| Normal | Normal (1.00) | Normal | 1.10 | [CLS] home |

| | | | | |
|----------------|-----------------------|----------------|-------|--|
| | | | | point updated . [SEP] |
| | | | | [CLS] imu attitude restricted . [SEP] |
| ParamViolation | ParamViolation (0.75) | ParamViolation | -0.82 | |
| Normal | Normal (1.00) | Normal | 0.54 | [CLS] ensure aircraft is level [SEP] |
| SoftwareFault | Normal (1.00) | SoftwareFault | 1.54 | [CLS] imu not calibrated . [SEP] |
| Normal | Normal (1.00) | Normal | 1.11 | [CLS] calibrate imu [SEP] |
| Normal | Normal (1.00) | Normal | 0.92 | [CLS] landing canceled . [SEP] |
| Normal | Normal (1.00) | Normal | 1.13 | [CLS] landing gear function restored [SEP] |
| Normal | Normal (0.98) | Normal | 1.11 | [CLS] landing gear paused . [SEP] |
| Normal | Normal (1.00) | Normal | -1.01 | [CLS] landing gear raising . [SEP] |
| Normal | Normal (1.00) | Normal | 1.40 | [CLS] home point recorded [SEP] |
| Normal | SoftwareFault (0.56) | Normal | 1.17 | [CLS] live stream video frame rate less than 9hz . [SEP] |
| Normal | Normal (1.00) | Normal | 1.26 | [CLS] fly with caution [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | -0.18 | [CLS] low power . [SEP] |
| Normal | Normal (1.00) | Normal | 1.46 | [CLS] aircraft is returning to the home point . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | -0.18 | [CLS] low power . [SEP] |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| Normal | Normal (1.00) | Normal | -1.52 | [CLS] returning home . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.99) | SurroundingEnvironment | 0.10 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | 1.33 | [CLS] exit p - gps mode . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.56 | [CLS] yaw error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.50) | SurroundingEnvironment | -1.12 | [CLS] manned aircraft detected nearby . [SEP] |
| Normal | Normal (1.00) | Normal | 1.26 | [CLS] fly with caution [SEP] |
| ParamViolation | ParamViolation (0.93) | ParamViolation | 1.39 | [CLS] max altitude approached . [SEP] |
| Normal | Normal (0.99) | Normal | 1.18 | [CLS] wait for the gps satellite signal recovery before ascend [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.92 | [CLS] max flight altitude reached . [SEP] |
| Normal | Normal (1.00) | Normal | 1.57 | [CLS] adjust in main controller settings if necessary [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 2.13 | [CLS] max flight distance reached . [SEP] |
| | | | | [CLS] adjust |

| | | | | |
|----------------|-----------------------|----------------|-------|--|
| Normal | Normal (1.00) | Normal | 1.33 | in main controller settings if necessary . [SEP] [CLS] maximum |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 0.43 | flight distance reached . [SEP] [CLS] adjust the distance |
| Normal | Normal (1.00) | Normal | -0.67 | in mc settings if required . [SEP] [CLS] mobile device cpu fully loaded . [SEP] |
| HardwareFault | Normal (0.77) | HardwareFault | 1.64 | [CLS] related performance will be affected . [SEP] [CLS] mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP] |
| SoftwareFault | Normal (0.99) | SoftwareFault | -1.39 | [CLS] motor is blocked . [SEP] [CLS] motor stuck . [SEP] [CLS] check for objects blocking motor or |
| Normal | Normal (0.95) | Normal | 1.13 | contact dji support for |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 0.99 | |
| Normal | Normal (1.00) | Normal | -0.54 | |

| | | | | |
|---------------|----------------------|---------------|-------|---|
| Normal | Normal (0.85) | Normal | 0.28 | assistance [SEP] |
| | | | | [CLS] motors started . |
| | | | | [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.38 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (0.85) | Normal | -1.65 | [CLS] aircraft unable to hover . [SEP] |
| | | | | [CLS] fly with caution [SEP] |
| | | | | [CLS] no gps signal . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.38 | [CLS] unable to hover . [SEP] |
| Normal | Normal (1.00) | Normal | 1.26 | [CLS] fly with caution [SEP] |
| | | | | [CLS] |
| | | | | obstacle avoidance disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 1.29 | [CLS] landing gear lowered . [SEP] |
| | | | | [CLS] |
| | | | | obstacle avoidance disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 1.29 | [CLS] |
| | | | | obstacle avoidance disabled . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 1.02 | [CLS] landing gear lowered . [SEP] |
| | | | | [CLS] |
| | | | | obstacle avoidance has been disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 1.05 | [CLS] |
| | | | | precision |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| | | | | landing [SEP] |
| Normal | Normal (1.00) | Normal | 1.25 | [CLS] quickshot has ended [SEP] |
| Normal | Normal (1.00) | Normal | 1.23 | [CLS] recenter gimbal pan [SEP] |
| Normal | Normal (1.00) | Normal | 1.16 | [CLS] rectifying aircraft position [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.99) | SurroundingEnvironment | 1.27 | [CLS] remote controller in high interference environment . [SEP] |
| Normal | Normal (1.00) | Normal | -0.88 | [CLS] manually adjust flight route or return to home [SEP] |
| Normal | Normal (1.00) | Normal | 1.46 | [CLS] return - to - home altitude : 65ft [SEP] |
| Normal | Normal (1.00) | Normal | -0.30 | [CLS] return - to - home altitude : 98ft . [SEP] |
| Normal | Normal (1.00) | Normal | 0.02 | [CLS] rth : ascending to rth altitude . [SEP] |
| Normal | Normal (1.00) | Normal | 1.39 | [CLS] rth : heading alignment . [SEP] |
| Normal | Normal (1.00) | Normal | -0.97 | [CLS] rth altitude : 65ft . [SEP] |
| Normal | Normal (1.00) | Normal | -0.71 | [CLS] rth altitude : 98ft . [SEP] |
| CommunicationIssue | CommunicationIssue (0.92) | CommunicationIssue | -0.72 | [CLS] signal |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|---|
| | | | | lost . [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | -0.12 | returning to home point [SEP] |
| | | | | [CLS] sprayer |
| Normal | Normal (1.00) | Normal | 1.01 | turned on [SEP] |
| | | | | [CLS] strong |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.43 | wind warning . [SEP] |
| | | | | [CLS] aircraft |
| | | | | unable to |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.31 | return to home automatically . [SEP] |
| | | | | [CLS] lower |
| | | | | altitude |
| | | | | immediately |
| Normal | Normal (1.00) | Normal | 1.68 | and return to home manually [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -1.27 | switched to s (sport) - mode . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -0.98 | switched to t (tripod) - mode . [SEP] |
| | | | | [CLS] take off |
| Normal | Normal (1.00) | Normal | 1.83 | in p - mode [SEP] |
| | | | | [CLS] vision |
| SoftwareFault | SoftwareFault (0.82) | SoftwareFault | -0.29 | sensor error . [SEP] |
| | | | | [CLS] contact |
| Normal | Normal (1.00) | Normal | 2.00 | dji support for assistance [SEP] |
| | | | | [CLS] vision |
| | | | | systems and |
| | | | | obstacle |
| Normal | Normal (1.00) | Normal | 1.28 | avoidance disabled [SEP] |

| | | | | |
|---------------------|----------------------------|---------------------|-------|---|
| Normal | Normal (0.99) | Normal | 0.91 | [CLS] waypoint mission paused [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | -0.88 | [CLS] weak gps signal . [SEP] |
| Normal | Normal (0.96) | Normal | 1.32 | [CLS] aircraft is in attitude mode and hovering may be unstable . [SEP] |
| Normal | Normal (1.00) | Normal | 1.05 | [CLS] fly with caution . [SEP] |
| CommunicationIssue | CommunicationIssue (0.99) | CommunicationIssue | 0.54 | [CLS] weak signal . [SEP] |
| Normal | Normal (1.00) | Normal | -0.90 | [CLS] adjust antennas [SEP] |
| RegulationViolation | RegulationViolation (0.98) | RegulationViolation | 2.16 | [CLS] your aircraft is flying in an altitude zone (nnn) . [SEP] |
| Normal | Normal (1.00) | Normal | -1.01 | [CLS] please fly with caution [SEP] |