| True Label | Predicted Label | Attribution Label | Attribution Score | Word Importance |
|---|---|---|---|---|
| SurroundingEnvironment | Normal (0.21) | Normal | 0.73 | [CLS] a passenger aircraft is nearby . [SEP] |
| Normal | Normal (0.21) | Normal | 1.01 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.20) | Normal | -0.50 | [CLS] account not logged in . [SEP] |
| ParamViolation | ParamViolation (0.37) | ParamViolation | 1.88 | [CLS] flight altitude and distance restricted to nnn and nnn . [SEP] |
| Normal | Normal (0.21) | Normal | 1.12 | [CLS] check and log in [SEP] |
| Normal | Normal (0.21) | Normal | 0.35 | [CLS] activetrack flight paused [SEP] |
| Normal | Normal (0.21) | Normal | 0.14 | [CLS] aircraft activetrack available at max speed . [SEP] |
| Normal | Normal (0.21) | Normal | 0.20 | [CLS] obstacle avoidance is not available [SEP] |
| Normal | Normal (0.21) | Normal | 0.14 | [CLS] aircraft activetrack available at max speed . [SEP] |
| Normal | Normal (0.21) | Normal | 0.12 | [CLS] when exceeding nnn , obstacle avoidance is not available [SEP] |
|  |  |  |  | [CLS] aircraft |

| | | | | |
|---|---|---|---|---|
| Normal | Normal (0.21) | Normal | 0.01 | activetrack max speed of nnn and obstacle avoidance functions normally [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 2.36 | [CLS] aircraft core board overheated [SEP] |
| Normal | Normal (0.21) | Normal | 0.33 | [CLS] aircraft entered fixed - wing mode . [SEP] |
| Normal | Normal (0.21) | Normal | -1.95 | [CLS] current flight speed is nnn . [SEP] |
| Normal | Normal (0.21) | Normal | 1.61 | [CLS] press c2 to exit [SEP] |
| Normal | Normal (0.21) | Normal | 0.40 | [CLS] aircraft flight control unlocked [SEP] |
| RegulationViolation | RegulationViolation (0.25) | RegulationViolation | 1.88 | [CLS] aircraft in restricted zones . [SEP] |
| Normal | Normal (0.21) | Normal | 0.32 | [CLS] check map to find recommended zones [SEP] |
| Normal | Normal (0.21) | Normal | 0.32 | [CLS] aircraft is in attitude mode , so that it will not hover . [SEP] |
| Normal | Normal (0.21) | Normal | 0.43 | [CLS] please fly with caution . [SEP] |
| Normal | Normal (0.21) | Normal | 0.72 | [CLS] aircraft is in tripod mode . [SEP] |
| Normal | Normal (0.21) | Normal | 1.96 | [CLS] exit this mode and try again |

| | | | | [SEP] |
|---|---|---|---|---|
| Normal | Normal (0.21) | Normal | 1.53 | [CLS] aircraft is returning to the starting point [SEP] |
| ParamViolation | ParamViolation (0.37) | ParamViolation | 2.07 | [CLS] aircraft out of range [SEP] |
| RegulationViolation | RegulationViolation (0.23) | RegulationViolation | 2.02 | [CLS] approaching a no - fly zone . [SEP] |
| Normal | Normal (0.21) | Normal | 1.09 | [CLS] rth may be affected . [SEP] |
| Normal | Normal (0.21) | Normal | 1.01 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.21) | Normal | 1.10 | [CLS] arrived at start point . [SEP] |
| Normal | Normal (0.21) | Normal | 0.37 | [CLS] starting waypoint mission [SEP] |
| Normal | Normal (0.21) | Normal | 1.44 | [CLS] auto landing initiated [SEP] |
| Normal | Normal (0.21) | Normal | 1.00 | [CLS] auxiliary bottom light turned off [SEP] |
| SoftwareFault | SoftwareFault (0.43) | SoftwareFault | 1.74 | [CLS] backward obstacle sensing is not functioning . [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.86 | [CLS] battery cell broken , please replace the battery [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.27 | [CLS] battery error . [SEP] |
| | | | | [CLS] aircraft returning to |

| | | | | |
|---|---|---|---|---|
| Normal | Normal (0.21) | Normal | 0.92 | home automatically [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.99 | [CLS] battery power low . [SEP] |
| Normal | Normal (0.21) | Normal | 1.70 | [CLS] check battery status and charge or warm up battery [SEP] |
| HardwareFault | HardwareFault (0.24) | HardwareFault | 1.83 | [CLS] cache space full [SEP] |
| SurroundingEnvironment | SoftwareFault (0.43) | SoftwareFault | 1.27 | [CLS] calibration subject is too close . [SEP] |
| Normal | Normal (0.21) | Normal | 0.11 | [CLS] recalibrate using a subject that is farther away [SEP] |
| HardwareFault | HardwareFault (0.24) | HardwareFault | 1.82 | [CLS] camera busy , cannot enter playback [SEP] |
| SoftwareFault | SoftwareFault (0.43) | SoftwareFault | 1.01 | [CLS] cannot enable intelligent flight mode [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.62 | [CLS] low battery [SEP] |
| SoftwareFault | SoftwareFault (0.43) | SoftwareFault | 1.38 | [CLS] cannot start return to home due to weak gps signal [SEP] |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.15 | [CLS] cannot start self - timer . [SEP] |
| SoftwareFault | ParamViolation (0.28) | ParamViolation | 0.03 | [CLS] exposure time is too long [SEP] |

| SoftwareFault | SoftwareFault (0.43) | SoftwareFault | 1.03 | [CLS] cannot switch flight mode . [SEP] |
| Normal | Normal (0.22) | Normal | 1.41 | [CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP] |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.05 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.39) | SoftwareFault | -1.12 | [CLS] no image [SEP] |
| Normal | Normal (0.21) | Normal | 0.88 | [CLS] please retry [SEP] |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.05 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.42) | SoftwareFault | -0.05 | [CLS] subject too large [SEP] |
| Normal | Normal (0.21) | Normal | 0.96 | [CLS] move away and retry [SEP] |
| Normal | Normal (0.21) | Normal | 1.10 | [CLS] color display in the liveview has been enhanced . [SEP] |
| Normal | Normal (0.21) | Normal | 0.78 | [CLS] videos and photos will still be shot in d - log mode [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.48 | [CLS] compass abnormal . [SEP] |
| Normal | Normal (0.21) | Normal | 0.01 | [CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft . |

| | | | | |
|---|---|---|---|---|
| | | | | [SEP] |
| Normal | Normal (0.21) | Normal | 0.19 | [CLS] the ground or walls may contain metal . [SEP] |
| Normal | Normal (0.21) | Normal | 0.16 | [CLS] move away from sources of interference before attempting flight . [SEP] |
| Normal | Normal (0.21) | Normal | 1.03 | [CLS] 2 . calibrate compass before takeoff [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.33 | [CLS] compass error [SEP] |
| HardwareFault | HardwareFault (0.22) | HardwareFault | 1.13 | [CLS] compass error , calibration required [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.45 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.45 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.49 | [CLS] compass disconnected [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.45 | [CLS] compass error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.38) | SurroundingEnvironment | 1.28 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (0.21) | Normal | 1.52 | [CLS] exit p - gps mode [SEP] |

| | | | | |
|---|---|---|---|---|
| **SoftwareFault** | **HardwareFault (0.24)** | **HardwareFault** | **-0.18** | [CLS] compass initialization failed . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.28** | [CLS] restart aircraft [SEP] |
| **HardwareFault** | **HardwareFault (0.25)** | **HardwareFault** | **1.90** | [CLS] critical low battery . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **2.03** | [CLS] aircraft in auto power off protection . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **1.92** | [CLS] forced landing in progress [SEP] |
| **HardwareFault** | **HardwareFault (0.25)** | **HardwareFault** | **1.90** | [CLS] critical low battery . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.42** | [CLS] aircraft landing automatically [SEP] |
| **HardwareFault** | **HardwareFault (0.25)** | **HardwareFault** | **1.90** | [CLS] critical low battery . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.52** | [CLS] return to home or land promptly [SEP] |
| **HardwareFault** | **HardwareFault (0.25)** | **HardwareFault** | **1.96** | [CLS] critically low power . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.43** | [CLS] aircraft is landing [SEP] |
| **HardwareFault** | **HardwareFault (0.25)** | **HardwareFault** | **1.96** | [CLS] critically low power . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.73** | [CLS] aircraft landing . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.73** | [CLS] aircraft landing . [SEP] |
| | | | | [CLS] throttle up to reduce |

| | | | | |
|---|---|---|---|---|
| **Normal** | **Normal (0.21)** | **Normal** | **0.32** | the speed of descent and use sticks to avoid obstacles [SEP] |
| **HardwareFault** | **HardwareFault (0.25)** | **HardwareFault** | **1.85** | [CLS] critically low voltage warning . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.45** | [CLS] aircraft will be forced to land [SEP] |
| **HardwareFault** | **HardwareFault (0.25)** | **HardwareFault** | **1.95** | [CLS] critically low voltage . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.53** | [CLS] aircraft will land [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.30** | [CLS] data recorder file index is 15 . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.36** | [CLS] data recorder file index is 17 . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.40** | [CLS] data recorder file index is 30 . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.38** | [CLS] data recorder file index is 45 . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.40** | [CLS] data recorder file index is 46 . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.41** | [CLS] data recorder file index is 65 . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.61** | [CLS] disable sd card read and write |

| | | | | |
|---|---|---|---|---|
| | | | | protection or change card [SEP] |
| CommunicationIssue | CommunicationIssue (0.36) | CommunicationIssue | 1.66 | [CLS] downlink lost . [SEP] |
| Normal | Normal (0.21) | Normal | 0.37 | [CLS] downlink restored ( after 0m 2 . 9s ) . [SEP] |
| Normal | HardwareFault (0.24) | HardwareFault | -1.22 | [CLS] drone is vibrating [SEP] |
| Normal | Normal (0.21) | Normal | 1.66 | [CLS] entered cruise control mode . [SEP] |
| Normal | Normal (0.21) | Normal | 0.93 | [CLS] press c1 or c2 to exit [SEP] |
| ParamViolation | ParamViolation (0.34) | ParamViolation | 2.05 | [CLS] excessive attitude angle detected [SEP] |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.63 | [CLS] forward obstacle avoidance has stopped working [SEP] |
| Normal | Normal (0.21) | Normal | 0.56 | [CLS] exit backward sensing system [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.38) | SurroundingEnvironment | 1.95 | [CLS] ambient light is too weak [SEP] |
| Normal | Normal (0.21) | Normal | 1.31 | [CLS] exited visual avoidance system . [SEP] |
| SoftwareFault | SoftwareFault (0.43) | SoftwareFault | 1.08 | [CLS] exiting gps mode : unknown error [SEP] |

| | | | | |
|---|---|---|---|---|
| ParamViolation | ParamViolation (0.38) | ParamViolation | 1.90 | [CLS] extra payload detected . [SEP] |
| Normal | Normal (0.21) | Normal | 0.80 | [CLS] flight performance will be affected . [SEP] |
| Normal | Normal (0.21) | Normal | 1.01 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (0.43) | SoftwareFault | 1.50 | [CLS] forward obstacle sensing is not functioning . [SEP] |
| SoftwareFault | SoftwareFault (0.43) | SoftwareFault | 1.54 | [CLS] forward obstacle sensing not responding [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 2.08 | [CLS] gimbal motor overloaded . [SEP] |
| Normal | Normal (0.21) | Normal | 0.79 | [CLS] check whether gimbal can rotate freely [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 2.00 | [CLS] gimbal pitch limit reached . [SEP] |
| Normal | Normal (0.21) | Normal | 0.61 | [CLS] ground plain . [SEP] |
| Normal | Normal (0.21) | Normal | 0.46 | [CLS] safe to land . [SEP] |
| ParamViolation | ParamViolation (0.33) | ParamViolation | 1.72 | [CLS] high altitude . [SEP] |
| Normal | HardwareFault (0.22) | HardwareFault | -2.27 | [CLS] aircraft braking distance increased and flight time decreased . [SEP] |

| | | | | |
|---|---|---|---|---|
| Normal | Normal (0.21) | Normal | 1.01 | [CLS] fly with caution [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.37) | SurroundingEnvironment | 1.70 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (0.22) | Normal | 0.22 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.37) | SurroundingEnvironment | 1.70 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (0.22) | Normal | 0.22 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.37) | SurroundingEnvironment | 1.70 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (0.21) | Normal | 0.83 | [CLS] fly with caution and land in a safe place asap . [SEP] |
| Normal | ParamViolation (0.29) | ParamViolation | -1.76 | [CLS] high - altitude flight [SEP] |
| Normal | Normal (0.21) | Normal | 1.01 | [CLS] fly with caution [SEP] |
| Normal | ParamViolation (0.29) | ParamViolation | -1.32 | [CLS] aircraft braking distance is extended [SEP] |
| Normal | ParamViolation (0.28) | ParamViolation | -1.22 | [CLS] flight time is shortened . [SEP] |
| Normal | Normal (0.21) | Normal | 0.68 | [CLS] home |

| | | | | point updated . [SEP] |
|---|---|---|---|---|
| ParamViolation | ParamViolation (0.29) | ParamViolation | 1.55 | [CLS] imu attitude restricted . [SEP] |
| Normal | Normal (0.21) | Normal | 0.48 | [CLS] ensure aircraft is level [SEP] |
| SoftwareFault | Normal (0.21) | Normal | -0.86 | [CLS] imu not calibrated . [SEP] |
| Normal | Normal (0.21) | Normal | 1.68 | [CLS] calibrate imu [SEP] |
| Normal | Normal (0.20) | Normal | 0.48 | [CLS] landing canceled . [SEP] |
| Normal | Normal (0.21) | Normal | 1.52 | [CLS] landing gear function restored [SEP] |
| Normal | Normal (0.21) | Normal | 0.69 | [CLS] landing gear paused . [SEP] |
| Normal | Normal (0.21) | Normal | 0.52 | [CLS] landing gear raising . [SEP] |
| Normal | Normal (0.21) | Normal | 1.25 | [CLS] home point recorded [SEP] |
| Normal | HardwareFault (0.19) | HardwareFault | -1.90 | [CLS] live stream video frame rate less than 9hz . [SEP] |
| Normal | Normal (0.21) | Normal | 1.01 | [CLS] fly with caution [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.73 | [CLS] low power . [SEP] |
| Normal | Normal (0.21) | Normal | 1.05 | [CLS] aircraft is returning to the home point . [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.73 | [CLS] low power . [SEP] |

| Normal | Normal (0.21) | Normal | 0.62 | [CLS] returning home . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.38) | SurroundingEnvironment | 1.28 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (0.21) | Normal | 1.28 | [CLS] exit p - gps mode . [SEP] |
| HardwareFault | HardwareFault (0.25) | HardwareFault | 1.73 | [CLS] yaw error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.35) | SurroundingEnvironment | 1.12 | [CLS] manned aircraft detected nearby . [SEP] |
| Normal | Normal (0.21) | Normal | 1.01 | [CLS] fly with caution [SEP] |
| ParamViolation | ParamViolation (0.31) | ParamViolation | 0.95 | [CLS] max altitude approached . [SEP] |
| Normal | Normal (0.21) | Normal | 0.20 | [CLS] wait for the gps satellite signal recovery before ascend [SEP] |
| ParamViolation | ParamViolation (0.38) | ParamViolation | 1.86 | [CLS] max flight altitude reached . [SEP] |
| Normal | Normal (0.21) | Normal | 1.72 | [CLS] adjust in main controller settings if necessary [SEP] |
| ParamViolation | ParamViolation (0.38) | ParamViolation | 1.82 | [CLS] max flight distance reached . [SEP] |
| | | | | [CLS] adjust |

| | | | | |
|---|---|---|---|---|
| **Normal** | **Normal (0.21)** | **Normal** | **1.51** | in main controller settings if necessary . [SEP] |
| **ParamViolation** | **ParamViolation (0.38)** | **ParamViolation** | **2.01** | [CLS] maximum flight distance reached . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **1.02** | [CLS] adjust the distance in mc settings if required . [SEP] |
| **HardwareFault** | **HardwareFault (0.24)** | **HardwareFault** | **2.03** | [CLS] mobile device cpu fully loaded . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **1.02** | [CLS] related performance will be affected . [SEP] |
| **SoftwareFault** | **SoftwareFault (0.26)** | **SoftwareFault** | **0.47** | [CLS] mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.30** | [CLS] motor is blocked . [SEP] |
| **HardwareFault** | **HardwareFault (0.25)** | **HardwareFault** | **1.46** | [CLS] motor stuck . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.82** | [CLS] check for objects blocking motor or contact dji support for |

| | | | | assistance [SEP] |
|---|---|---|---|---|
| **Normal** | **HardwareFault (0.24)** | **HardwareFault** | **-2.10** | [CLS] motors started . [SEP] |
| **SoftwareFault** | **SoftwareFault (0.42)** | **SoftwareFault** | **1.76** | [CLS] no gps signal . [SEP] |
| **Normal** | **HardwareFault (0.25)** | **HardwareFault** | **-0.72** | [CLS] aircraft unable to hover . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **1.01** | [CLS] fly with caution [SEP] |
| **SoftwareFault** | **SoftwareFault (0.42)** | **SoftwareFault** | **1.76** | [CLS] no gps signal . [SEP] |
| **Normal** | **HardwareFault (0.25)** | **HardwareFault** | **-0.94** | [CLS] unable to hover . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **1.01** | [CLS] fly with caution [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.57** | [CLS] obstacle avoidance disabled . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.73** | [CLS] landing gear lowered . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.57** | [CLS] obstacle avoidance disabled . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.57** | [CLS] obstacle avoidance disabled . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.73** | [CLS] landing gear lowered . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.84** | [CLS] obstacle avoidance has been disabled . [SEP] |
| **Normal** | **Normal (0.21)** | **Normal** | **0.54** | [CLS] precision |

| | | | | |
|---|---|---|---|---|
| | | | | landing [SEP] |
| Normal | Normal (0.21) | Normal | 1.20 | [CLS] quickshot has ended [SEP] |
| Normal | Normal (0.21) | Normal | 0.70 | [CLS] recenter gimbal pan [SEP] |
| Normal | Normal (0.21) | Normal | 0.22 | [CLS] rectifying aircraft position [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.38) | SurroundingEnvironment | 1.70 | [CLS] remote controller in high interference environment . [SEP] |
| Normal | Normal (0.21) | Normal | 1.43 | [CLS] manually adjust flight route or return to home [SEP] |
| Normal | Normal (0.21) | Normal | 0.83 | [CLS] return - to - home altitude : 65ft [SEP] |
| Normal | Normal (0.21) | Normal | 0.51 | [CLS] return - to - home altitude : 98ft . [SEP] |
| Normal | Normal (0.21) | Normal | 1.50 | [CLS] rth : ascending to rth altitude . [SEP] |
| Normal | Normal (0.21) | Normal | 2.00 | [CLS] rth : heading alignment . [SEP] |
| Normal | Normal (0.21) | Normal | 0.85 | [CLS] rth altitude : 65ft . [SEP] |
| Normal | Normal (0.21) | Normal | 0.82 | [CLS] rth altitude : 98ft . [SEP] |
| CommunicationIssue | CommunicationIssue (0.36) | CommunicationIssue | 1.51 | [CLS] signal |

| | | | | |
|---|---|---|---|---|
| | | | | lost . [SEP] |
| Normal | Normal (0.21) | Normal | 0.80 | [CLS] aircraft returning to home point [SEP] |
| Normal | Normal (0.21) | Normal | 1.74 | [CLS] sprayer turned on [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.37) | SurroundingEnvironment | 1.57 | [CLS] strong wind warning . [SEP] |
| SoftwareFault | SoftwareFault (0.43) | SoftwareFault | 1.25 | [CLS] aircraft unable to return to home automatically . [SEP] |
| Normal | Normal (0.21) | Normal | 1.75 | [CLS] lower altitude immediately and return to home manually [SEP] |
| Normal | Normal (0.21) | Normal | 0.73 | [CLS] switched to s ( sport ) - mode . [SEP] |
| Normal | Normal (0.21) | Normal | 0.38 | [CLS] switched to t ( tripod ) - mode . [SEP] |
| Normal | Normal (0.21) | Normal | 1.46 | [CLS] take off in p - mode [SEP] |
| SoftwareFault | HardwareFault (0.24) | HardwareFault | -0.02 | [CLS] vision sensor error . [SEP] |
| Normal | Normal (0.21) | Normal | 1.09 | [CLS] contact dji support for assistance [SEP] |
| Normal | Normal (0.21) | Normal | 0.77 | [CLS] vision systems and obstacle avoidance disabled [SEP] |

| Normal | Normal (0.21) | Normal | 1.05 | [CLS] waypoint mission paused [SEP] |
|---|---|---|---|---|
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.64 | [CLS] weak gps signal . [SEP] |
| Normal | Normal (0.21) | Normal | 0.74 | [CLS] aircraft is in attitude mode and hovering may be unstable . [SEP] |
| Normal | Normal (0.21) | Normal | 0.50 | [CLS] fly with caution . [SEP] |
| CommunicationIssue | CommunicationIssue (0.37) | CommunicationIssue | 1.50 | [CLS] weak signal . [SEP] |
| Normal | Normal (0.21) | Normal | 0.78 | [CLS] adjust antennas [SEP] |
| RegulationViolation | RegulationViolation (0.23) | RegulationViolation | 2.49 | [CLS] your aircraft is flying in an altitude zone ( nnn ) . [SEP] |
| Normal | Normal (0.21) | Normal | 0.61 | [CLS] please fly with caution [SEP] |