

**Legend:** ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	Normal (0.95)	SurroundingEnvironment	1.76	[CLS] a passenger aircraft is nearby . [SEP]
Normal	Normal (1.00)	Normal	1.50	[CLS] fly with caution [SEP]
Normal	SoftwareFault (0.97)	Normal	-0.40	[CLS] account not logged in . [SEP]
ParamViolation	ParamViolation (0.79)	ParamViolation	0.07	[CLS] flight altitude and distance restricted to nnn and nnn . [SEP]
Normal	Normal (1.00)	Normal	1.43	[CLS] check and log in [SEP]
Normal	Normal (1.00)	Normal	1.02	[CLS] activetrack flight paused [SEP]
Normal	Normal (1.00)	Normal	-0.58	[CLS] aircraft activetrack available at max speed . [SEP]
Normal	Normal (1.00)	Normal	-1.16	[CLS] obstacle avoidance is not available [SEP]
Normal	Normal (1.00)	Normal	-0.58	[CLS] aircraft activetrack available at max speed . [SEP]
Normal	Normal (0.99)	Normal	1.09	[CLS] when exceeding nnn , obstacle avoidance is not available [SEP]

Normal	<b>Normal (1.00)</b>	Normal	<b>1.16</b>	activetrack max speed of nnn and obstacle avoidance functions normally [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	HardwareFault	<b>1.69</b>	[CLS] aircraft core board overheated [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.27</b>	[CLS] aircraft entered fixed - wing mode . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-1.51</b>	[CLS] current flight speed is nnn . [SEP]
Normal	<b>Normal (0.99)</b>	Normal	<b>1.54</b>	[CLS] press c2 to exit [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.10</b>	[CLS] aircraft flight control unlocked [SEP]
RegulationViolation	<b>RegulationViolation (1.00)</b>	RegulationViolation	<b>-0.75</b>	[CLS] aircraft in restricted zones . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.14</b>	[CLS] check map to find recommended zones [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.78</b>	[CLS] aircraft is in attitude mode , so that it will not hover . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.99</b>	[CLS] please fly with caution . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.09</b>	[CLS] aircraft is in tripod mode . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.18</b>	[CLS] exit this mode and try again

[SEP]

[CLS] aircraft

is returning

to the

starting point

[SEP]

[CLS] aircraft

out of range

[SEP]

[CLS]

approaching

a no - fly zone

. [SEP]

[CLS] rth may

be affected .

[SEP]

[CLS] fly with  
caution [SEP]

[CLS] arrived

at start point

. [SEP]

[CLS] starting

waypoint  
mission [SEP]

[CLS] auto

landing

initiated

[SEP]

[CLS]

auxiliary

bottom light  
turned off

[SEP]

[CLS]

backward

obstacle  
sensing is not

functioning .

[SEP]

[CLS] battery  
cell broken ,please  
replace the  
battery [SEP][CLS] battery  
error . [SEP][CLS] aircraft  
returning to

Normal	<b>Normal (1.00)</b>	Normal	<b>0.35</b>	[SEP]
ParamViolation	<b>ParamViolation (0.55)</b>	ParamViolation	<b>-0.64</b>	[CLS] aircraft is returning to the starting point [SEP]
RegulationViolation	<b>RegulationViolation (0.99)</b>	RegulationViolation	<b>2.41</b>	[CLS] aircraft out of range [SEP] [CLS] approaching a no - fly zone . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.13</b>	[CLS] rth may be affected . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.50</b>	[CLS] fly with caution [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.98</b>	[CLS] arrived at start point . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.04</b>	[CLS] starting waypoint mission [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.18</b>	[CLS] auto landing initiated [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.00</b>	[CLS] auxiliary bottom light turned off [SEP]
SoftwareFault	<b>SoftwareFault (1.00)</b>	SoftwareFault	<b>2.10</b>	[CLS] backward obstacle sensing is not functioning . [SEP]
HardwareFault	<b>HardwareFault (0.99)</b>	HardwareFault	<b>1.31</b>	[CLS] battery cell broken , please replace the battery [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	HardwareFault	<b>1.18</b>	[CLS] battery error . [SEP] [CLS] aircraft returning to

<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.57</b>	home automatically [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>-0.18</b>	[CLS] battery power low . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.76</b>	[CLS] check battery status and charge or warm up battery [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.89)</b>	<b>HardwareFault</b>	<b>-0.82</b>	[CLS] cache space full [SEP]
<b>SurroundingEnvironment</b>	<b>SoftwareFault (1.00)</b>	<b>SurroundingEnvironment</b>	<b>1.85</b>	[CLS] calibration subject is too close . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.44</b>	[CLS] recalibrate using a subject that is farther away [SEP]
<b>HardwareFault</b>	<b>SoftwareFault (0.91)</b>	<b>HardwareFault</b>	<b>-1.39</b>	[CLS] camera busy , cannot enter playback [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>1.60</b>	[CLS] cannot enable intelligent flight mode [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>-0.50</b>	[CLS] low battery [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>1.34</b>	[CLS] cannot start return to home due to weak gps signal [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.99)</b>	<b>SoftwareFault</b>	<b>0.79</b>	[CLS] cannot start self - timer . [SEP]
<b>SoftwareFault</b>	<b>ParamViolation (0.53)</b>	<b>SoftwareFault</b>	<b>-0.70</b>	[CLS] exposure time is too long [SEP]

<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>1.34</b>	[CLS] cannot switch flight mode . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.32</b>	[CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>1.59</b>	[CLS] cannot track subject [SEP]
<b>SurroundingEnvironment</b>	<b>SoftwareFault (0.98)</b>	<b>SurroundingEnvironment</b>	<b>-1.17</b>	[CLS] no image [SEP]
<b>Normal</b>	<b>Normal (0.99)</b>	<b>Normal</b>	<b>-1.02</b>	[CLS] please retry [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>1.59</b>	[CLS] cannot track subject [SEP]
<b>SurroundingEnvironment</b>	<b>SoftwareFault (1.00)</b>	<b>SurroundingEnvironment</b>	<b>0.81</b>	[CLS] subject too large [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.42</b>	[CLS] move away and retry [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.12</b>	[CLS] color display in the liveview has been enhanced . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.20</b>	[CLS] videos and photos will still be shot in d - log mode [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>-0.92</b>	[CLS] compass abnormal . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.31</b>	[CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft .

				[SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.26</b>	[CLS] the ground or walls may contain metal . [SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.05</b>	[CLS] move away from sources of interference before attempting flight . [SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.41</b>	[CLS] 2 . calibrate compass before takeoff [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>-0.48</b>	[CLS] compass error [SEP]
HardwareFault	<b>HardwareFault (0.74)</b>	<b>HardwareFault</b>	<b>-0.79</b>	[CLS] compass error , calibration required [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>-0.79</b>	[CLS] compass error . [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>-0.79</b>	[CLS] compass error . [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.13</b>	[CLS] compass disconnected [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>-0.79</b>	[CLS] compass error . [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (1.00)</b>	<b>SurroundingEnvironment</b>	<b>-0.18</b>	[CLS] magnetic field interference . [SEP]
Normal	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.08</b>	[CLS] exit p - gps mode [SEP]

<b>SoftwareFault</b>	<b>HardwareFault (0.96)</b>	<b>SoftwareFault</b>	<b>0.59</b>	[CLS] compass initialization failed . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.03</b>	[CLS] restart aircraft [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.32</b>	[CLS] critical low battery . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.69</b>	[CLS] aircraft in auto power off protection . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.29</b>	[CLS] forced landing in progress [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.32</b>	[CLS] critical low battery . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.08</b>	[CLS] aircraft landing automatically [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.32</b>	[CLS] critical low battery . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.10</b>	[CLS] return to home or land promptly [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.64</b>	[CLS] critically low power . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.97</b>	[CLS] aircraft is landing [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.64</b>	[CLS] critically low power . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.14</b>	[CLS] aircraft landing . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.14</b>	[CLS] aircraft landing . [SEP]
				[CLS] throttle up to reduce

Normal	<b>Normal (1.00)</b>	Normal	<b>1.63</b>	the speed of descent and use sticks to avoid obstacles [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	HardwareFault	<b>1.17</b>	[CLS] critically low voltage warning . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.11</b>	[CLS] aircraft will be forced to land [SEP]
HardwareFault	<b>HardwareFault (1.00)</b>	HardwareFault	<b>1.17</b>	[CLS] critically low voltage . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.44</b>	[CLS] aircraft will land [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.26</b>	[CLS] data recorder file index is 15 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.59</b>	[CLS] data recorder file index is 17 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.32</b>	[CLS] data recorder file index is 30 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.61</b>	[CLS] data recorder file index is 45 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.34</b>	[CLS] data recorder file index is 46 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.44</b>	[CLS] data recorder file index is 65 . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.43</b>	[CLS] disable sd card read and write

				protection or change card [SEP]
<b>CommunicationIssue</b>	<b>CommunicationIssue (1.00)</b>	<b>CommunicationIssue</b>	<b>-0.92</b>	[CLS] downlink lost . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.39</b>	[CLS] downlink restored ( [SEP] after 0m 2 . 9s ) . [SEP]
<b>Normal</b>	<b>HardwareFault (0.73)</b>	<b>Normal</b>	<b>0.98</b>	[CLS] drone is vibrating [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.06</b>	[CLS] entered cruise control mode . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.10</b>	[CLS] press c1 or c2 to exit [SEP]
<b>ParamViolation</b>	<b>ParamViolation (0.88)</b>	<b>ParamViolation</b>	<b>1.74</b>	[CLS] excessive attitude angle detected [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (0.98)</b>	<b>SoftwareFault</b>	<b>-0.51</b>	[CLS] forward obstacle avoidance has stopped working [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.08</b>	[CLS] exit backward sensing system [SEP]
<b>SurroundingEnvironment</b>	<b>SurroundingEnvironment (1.00)</b>	<b>SurroundingEnvironment</b>	<b>-0.43</b>	[CLS] ambient light is too weak [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.74</b>	[CLS] exited visual [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>-0.64</b>	[CLS] exiting gps mode : unknown error [SEP]

<b>ParamViolation</b>	<b>ParamViolation (1.00)</b>	<b>ParamViolation</b>	<b>0.87</b>	[CLS] extra payload detected . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.08</b>	will be affected . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.50</b>	[CLS] fly with caution [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>1.87</b>	[CLS] forward obstacle sensing is not functioning . [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>-0.10</b>	[CLS] forward obstacle sensing not responding [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>-0.73</b>	[CLS] gimbal motor overloaded . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.13</b>	[CLS] check whether gimbal can rotate freely [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.43</b>	[CLS] gimbal pitch limit reached . [SEP]
<b>Normal</b>	<b>Normal (0.98)</b>	<b>Normal</b>	<b>1.15</b>	[CLS] ground plain . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.02</b>	[CLS] safe to land . [SEP]
<b>ParamViolation</b>	<b>ParamViolation (0.64)</b>	<b>ParamViolation</b>	<b>1.98</b>	[CLS] high altitude . [SEP]
<b>Normal</b>	<b>Normal (0.97)</b>	<b>Normal</b>	<b>0.87</b>	[CLS] aircraft braking distance increased and flight time decreased . [SEP]

Normal	<b>Normal (1.00)</b>	Normal	<b>1.50</b>	[CLS] fly with caution [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (1.00)</b>	SurroundingEnvironment	<b>1.23</b>	[CLS] high wind velocity . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.74</b>	[CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (1.00)</b>	SurroundingEnvironment	<b>1.23</b>	[CLS] high wind velocity . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.74</b>	[CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (1.00)</b>	SurroundingEnvironment	<b>1.23</b>	[CLS] high wind velocity . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.82</b>	[CLS] fly with caution and land in a safe place asap . [SEP]
Normal	<b>Normal (0.97)</b>	Normal	<b>1.16</b>	[CLS] high - altitude flight [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.50</b>	[CLS] fly with caution [SEP]
Normal	<b>ParamViolation (0.92)</b>	Normal	<b>0.00</b>	[CLS] aircraft braking distance is extended [SEP]
Normal	<b>Normal (0.98)</b>	Normal	<b>0.60</b>	[CLS] flight time is shortened . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.18</b>	[CLS] home

				point updated
				. [SEP]
				[CLS] imu
				attitude
				restricted .
				[SEP]
				[CLS] ensure
<b>ParamViolation</b>	<b>SoftwareFault (0.46)</b>	<b>ParamViolation</b>	<b>-0.63</b>	aircraft is
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.69</b>	level [SEP]
<b>SoftwareFault</b>	<b>Normal (0.95)</b>	<b>SoftwareFault</b>	<b>1.18</b>	[CLS] imu not
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.25</b>	calibrated .
<b>Normal</b>	<b>SoftwareFault (0.84)</b>	<b>Normal</b>	<b>0.84</b>	[SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.11</b>	[CLS]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.80</b>	calibrate imu
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.39</b>	[SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.12</b>	[CLS] landing
<b>Normal</b>	<b>Normal (0.89)</b>	<b>Normal</b>	<b>-1.12</b>	canceled .
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.50</b>	[SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.24</b>	[CLS] landing
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.57</b>	gear function
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.24</b>	restored
				[SEP]
				[CLS] landing
				gear paused .
				[SEP]
				[CLS] landing
				gear raising .
				[SEP]
				[CLS] home
				point
				recorded
				[SEP]
				[CLS] live
				stream video
				frame rate
				less than 9hz
				. [SEP]
				[CLS] fly with
				caution [SEP]
				[CLS] low
				power . [SEP]
				[CLS] aircraft
				is returning
				to the home
				point . [SEP]
				[CLS] low
				power . [SEP]

<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.19</b>	[CLS] returning home . [SEP]
<b>SurroundingEnvironment</b>	<b>SurroundingEnvironment (1.00)</b>	<b>SurroundingEnvironment</b>	<b>-0.18</b>	[CLS] magnetic filed interference . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.57</b>	[CLS] exit p - gps mode . [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.38</b>	[CLS] yaw error . [SEP]
<b>SurroundingEnvironment</b>	<b>SurroundingEnvironment (0.69)</b>	<b>SurroundingEnvironment</b>	<b>1.61</b>	[CLS] manned aircraft detected nearby . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.50</b>	[CLS] fly with caution [SEP]
<b>ParamViolation</b>	<b>ParamViolation (0.92)</b>	<b>ParamViolation</b>	<b>1.44</b>	[CLS] max altitude approached . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.47</b>	[CLS] wait for the gps satellite signal recovery before ascend [SEP]
<b>ParamViolation</b>	<b>ParamViolation (1.00)</b>	<b>ParamViolation</b>	<b>-0.30</b>	[CLS] max flight altitude reached . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.14</b>	[CLS] adjust in main controller settings if necessary [SEP]
<b>ParamViolation</b>	<b>ParamViolation (1.00)</b>	<b>ParamViolation</b>	<b>0.61</b>	[CLS] max flight distance reached . [SEP]

<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-1.15</b>	in main controller settings if necessary . [SEP]
<b>ParamViolation</b>	<b>ParamViolation (1.00)</b>	<b>ParamViolation</b>	<b>1.95</b>	[CLS] maximum flight distance reached . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.68</b>	[CLS] adjust the distance in mc settings if required . [SEP]
<b>HardwareFault</b>	<b>HardwareFault (0.63)</b>	<b>HardwareFault</b>	<b>-0.75</b>	[CLS] mobile device cpu fully loaded . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.76</b>	[CLS] related performance will be affected . [SEP]
<b>SoftwareFault</b>	<b>Normal (0.99)</b>	<b>SoftwareFault</b>	<b>-0.13</b>	[CLS] mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.18</b>	[CLS] motor is blocked . [SEP]
<b>HardwareFault</b>	<b>HardwareFault (1.00)</b>	<b>HardwareFault</b>	<b>1.82</b>	[CLS] motor stuck . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.74</b>	[CLS] check for objects blocking motor or contact dji support for

				assistance
				[SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.12</b>	[CLS] motors started . [SEP]
SoftwareFault	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>1.63</b>	[CLS] no gps signal . [SEP]
Normal	<b>HardwareFault (0.91)</b>	Normal	<b>0.97</b>	[CLS] aircraft unable to hover . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.50</b>	[CLS] fly with caution [SEP]
SoftwareFault	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>1.63</b>	[CLS] no gps signal . [SEP]
Normal	<b>HardwareFault (0.95)</b>	Normal	<b>-0.28</b>	[CLS] unable to hover . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.50</b>	[CLS] fly with caution [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.17</b>	[CLS] obstacle avoidance disabled . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.25</b>	[CLS] landing gear lowered . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.17</b>	[CLS] obstacle avoidance disabled . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.17</b>	[CLS] obstacle avoidance disabled . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.25</b>	[CLS] landing gear lowered . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.89</b>	[CLS] obstacle avoidance has been disabled . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>0.81</b>	[CLS] precision

Normal	<b>Normal (0.96)</b>	Normal	<b>-1.13</b>	landing [SEP] [CLS] quickshot has ended [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.02</b>	[CLS] recenter gimbal pan [SEP] [CLS]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.13</b>	[CLS] rectifying aircraft position [SEP] [CLS] remote controller in
SurroundingEnvironment	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>1.99</b>	high interference environment . [SEP] [CLS] manually adjust flight route or return to home [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.24</b>	[CLS] return - to - home altitude : 65ft [SEP] [CLS] return - to - home altitude : 98ft . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.30</b>	[CLS] rth : ascending to rth altitude . [SEP] [CLS] rth : heading alignment . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.92</b>	[CLS] rth altitude : 65ft . [SEP] [CLS] rth altitude : 98ft . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.03</b>	[CLS] signal
CommunicationIssue	<b>CommunicationIssue (0.99)</b>	CommunicationIssue	<b>2.01</b>	

Normal	<b>Normal (1.00)</b>	Normal	<b>1.28</b>	lost . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-1.00</b>	[CLS] aircraft returning to home point [SEP]
SurroundingEnvironment	<b>SurroundingEnvironment (1.00)</b>	SurroundingEnvironment	<b>2.06</b>	[CLS] sprayer turned on [SEP]
SoftwareFault	<b>SoftwareFault (1.00)</b>	SoftwareFault	<b>-0.96</b>	[CLS] strong wind warning . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.91</b>	[CLS] aircraft unable to return to home automatically . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.31</b>	[CLS] lower altitude immediately and return to home manually [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.99</b>	[CLS] switched to s ( sport ) - mode . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-0.70</b>	[CLS] switched to t ( tripod ) - mode . [SEP]
SoftwareFault	<b>SoftwareFault (0.98)</b>	SoftwareFault	<b>-0.70</b>	[CLS] take off in p - mode [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>1.11</b>	[CLS] vision sensor error . [SEP]
Normal	<b>Normal (1.00)</b>	Normal	<b>-1.16</b>	[CLS] contact dji support for assistance [SEP]
Normal	<b>Normal (1.00)</b>	Normal		[CLS] vision systems and obstacle avoidance disabled [SEP]

<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.84</b>	[CLS] waypoint mission paused [SEP]
<b>SoftwareFault</b>	<b>SoftwareFault (1.00)</b>	<b>SoftwareFault</b>	<b>0.70</b>	[CLS] weak gps signal . [SEP]
<b>Normal</b>	<b>Normal (0.96)</b>	<b>Normal</b>	<b>0.81</b>	[CLS] aircraft is in attitude mode and hovering may be unstable . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.37</b>	[CLS] fly with caution . [SEP]
<b>CommunicationIssue</b>	<b>CommunicationIssue (1.00)</b>	<b>CommunicationIssue</b>	<b>-0.60</b>	[CLS] weak signal . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.20</b>	[CLS] adjust antennas [SEP]
<b>RegulationViolation</b>	<b>RegulationViolation (0.97)</b>	<b>RegulationViolation</b>	<b>0.71</b>	[CLS] your aircraft is flying in an altitude zone ( nnn ) . [SEP]
<b>Normal</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.91</b>	[CLS] please fly with caution [SEP]