

Legend: ■ Negative □ Neutral ■ Positive

| True Label | Predicted Label | Attribution Label | Attribution Score | Word Importance |
|------------------------|------------------------------|-------------------|-------------------|---|
| SurroundingEnvironment | Normal (0.20) | Normal | 0.25 | [CLS] a passenger aircraft is nearby . [SEP] |
| Normal | Normal (0.19) | Normal | 0.73 | [CLS] fly with caution [SEP] |
| Normal | SoftwareFault (0.30) | SoftwareFault | -0.70 | [CLS] account not logged in . [SEP] |
| ParamViolation | ParamViolation (0.62) | ParamViolation | 2.20 | [CLS] flight altitude and distance restricted to nnn and nnn . [SEP] |
| Normal | Normal (0.20) | Normal | 0.70 | [CLS] check and log in [SEP] |
| Normal | Normal (0.20) | Normal | 1.66 | [CLS] activetrack flight paused [SEP] |
| Normal | Normal (0.20) | Normal | 2.40 | [CLS] aircraft activetrack available at max speed . [SEP] |
| Normal | Normal (0.20) | Normal | 0.18 | [CLS] obstacle avoidance is not available [SEP] |
| Normal | Normal (0.20) | Normal | 2.40 | [CLS] aircraft activetrack available at max speed . [SEP] |
| Normal | Normal (0.20) | Normal | 0.04 | [CLS] when exceeding nnn , obstacle avoidance is not available [SEP] |
| | | | | [CLS] aircraft |

| | | | | |
|---------------------|-----------------------------------|---------------------|--------------|---|
| Normal | Normal (0.20) | Normal | -0.05 | activetrack max speed of nnn and obstacle avoidance functions normally [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 2.23 | [CLS] aircraft core board overheated [SEP] |
| Normal | Normal (0.20) | Normal | 0.95 | [CLS] aircraft entered fixed - wing mode . [SEP] |
| Normal | ParamViolation (0.32) | ParamViolation | -1.84 | [CLS] current flight speed is nnn . [SEP] |
| Normal | Normal (0.19) | Normal | 0.38 | [CLS] press c2 to exit [SEP] |
| Normal | Normal (0.20) | Normal | 1.03 | [CLS] aircraft flight control unlocked [SEP] |
| RegulationViolation | RegulationViolation (0.74) | RegulationViolation | 1.68 | [CLS] aircraft in restricted zones . [SEP] |
| Normal | Normal (0.19) | Normal | 0.47 | [CLS] check map to find recommended zones [SEP] |
| Normal | Normal (0.20) | Normal | 0.70 | [CLS] aircraft is in attitude mode , so that it will not hover . [SEP] |
| Normal | Normal (0.20) | Normal | 2.02 | [CLS] please fly with caution . [SEP] |
| Normal | Normal (0.20) | Normal | 1.24 | [CLS] aircraft is in tripod mode . [SEP] |
| Normal | Normal (0.20) | Normal | 1.43 | [CLS] exit this mode and try again |

| | | | | |
|---------------------|-----------------------------------|----------------------------|-------------|---|
| | | | | [SEP] |
| Normal | Normal (0.20) | Normal | 1.68 | [CLS] aircraft is returning to the starting point [SEP] |
| ParamViolation | ParamViolation (0.61) | ParamViolation | 1.89 | [CLS] aircraft out of range [SEP] [CLS] |
| RegulationViolation | RegulationViolation (0.74) | RegulationViolation | 2.11 | approaching a no - fly zone . [SEP] |
| Normal | Normal (0.20) | Normal | 1.41 | [CLS] rth may be affected . [SEP] |
| Normal | Normal (0.19) | Normal | 0.73 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.20) | Normal | 1.91 | [CLS] arrived at start point . [SEP] |
| Normal | Normal (0.20) | Normal | 1.01 | [CLS] starting waypoint mission [SEP] |
| Normal | Normal (0.19) | Normal | 0.11 | [CLS] auto landing initiated [SEP] |
| Normal | Normal (0.19) | Normal | 0.77 | [CLS] auxiliary bottom light turned off [SEP] |
| SoftwareFault | SoftwareFault (0.58) | SoftwareFault | 1.96 | [CLS] backward obstacle sensing is not functioning . [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.13 | [CLS] battery cell broken , please replace the battery [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 0.65 | [CLS] battery error . [SEP] [CLS] aircraft returning to |

| | | | | |
|-------------------------------|----------------------------------|-----------------------|--------------|---|
| Normal | Normal (0.19) | Normal | 0.55 | home automatically [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.20 | [CLS] battery power low . [SEP] |
| Normal | Normal (0.20) | Normal | 2.11 | [CLS] check battery status and charge or warm up battery [SEP] |
| HardwareFault | HardwareFault (0.39) | HardwareFault | 1.68 | [CLS] cache space full [SEP] |
| SurroundingEnvironment | SoftwareFault (0.54) | SoftwareFault | -1.44 | [CLS] calibration subject is too close . [SEP] |
| Normal | Normal (0.20) | Normal | -0.01 | [CLS] recalibrate using a subject that is farther away [SEP] |
| HardwareFault | HardwareFault (0.42) | HardwareFault | 1.22 | [CLS] camera busy , cannot enter playback [SEP] |
| SoftwareFault | SoftwareFault (0.57) | SoftwareFault | 0.96 | [CLS] cannot enable intelligent flight mode [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.64 | [CLS] low battery [SEP] |
| SoftwareFault | SoftwareFault (0.59) | SoftwareFault | 1.19 | [CLS] cannot start return to home due to weak gps signal [SEP] |
| SoftwareFault | SoftwareFault (0.57) | SoftwareFault | 1.19 | [CLS] cannot start self - timer . [SEP] |
| SoftwareFault | ParamViolation (0.45) | ParamViolation | -0.37 | [CLS] exposure time is too long [SEP] |

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|-------------------------------|-----------------------------|----------------------|--------------|---|
| SoftwareFault | SoftwareFault (0.57) | SoftwareFault | 1.01 | [CLS] cannot switch flight mode . [SEP] |
| Normal | Normal (0.19) | Normal | 1.44 | [CLS] turn on "multiple flight modes " to enable attitude and sport modes . [SEP] |
| SoftwareFault | SoftwareFault (0.56) | SoftwareFault | 1.11 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.52) | SoftwareFault | -1.08 | [CLS] no image [SEP] |
| Normal | Normal (0.19) | Normal | 0.54 | [CLS] please retry [SEP] |
| SoftwareFault | SoftwareFault (0.56) | SoftwareFault | 1.11 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.56) | SoftwareFault | -1.05 | [CLS] subject too large [SEP] |
| Normal | Normal (0.20) | Normal | 1.25 | [CLS] move away and retry [SEP] |
| Normal | Normal (0.20) | Normal | 2.11 | [CLS] color display in the liveview has been enhanced . [SEP] |
| Normal | Normal (0.20) | Normal | 1.31 | [CLS] videos and photos will still be shot in d - log mode [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 0.68 | [CLS] compass abnormal . [SEP] |
| Normal | Normal (0.19) | Normal | 0.08 | [CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft . |

[SEP]

| | | | | |
|------------------------|--------------------------------------|-------------------------------|-------------|---|
| Normal | Normal (0.20) | Normal | 0.11 | [CLS] the ground or walls may contain metal . [SEP] |
| Normal | Normal (0.20) | Normal | 1.10 | [CLS] move away from sources of interference before attempting flight . [SEP] |
| Normal | Normal (0.20) | Normal | 1.51 | [CLS] 2 . calibrate compass before takeoff [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 0.74 | [CLS] compass error [SEP] |
| HardwareFault | HardwareFault (0.37) | HardwareFault | 0.76 | [CLS] compass error , calibration required [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 0.69 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 0.69 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.56 | [CLS] compass disconnected [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 0.69 | [CLS] compass error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.61) | SurroundingEnvironment | 1.48 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (0.19) | Normal | 0.38 | [CLS] exit p - gps mode [SEP] |

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|----------------------|-----------------------------|----------------------|--------------|--|
| SoftwareFault | HardwareFault (0.41) | HardwareFault | 0.18 | [CLS] compass initialization failed. [SEP] |
| Normal | Normal (0.19) | Normal | -0.02 | [CLS] restart aircraft [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.21 | [CLS] critical low battery. [SEP] |
| Normal | Normal (0.20) | Normal | 1.54 | [CLS] aircraft in auto power off protection . [SEP] |
| Normal | Normal (0.20) | Normal | 1.92 | [CLS] forced landing in progress [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.21 | [CLS] critical low battery. [SEP] |
| Normal | Normal (0.19) | Normal | -0.07 | [CLS] aircraft landing automatically [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.21 | [CLS] critical low battery. [SEP] |
| Normal | Normal (0.20) | Normal | 1.74 | [CLS] return to home or land promptly [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.32 | [CLS] critically low power. [SEP] |
| Normal | Normal (0.19) | Normal | 0.51 | [CLS] aircraft is landing [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.32 | [CLS] critically low power. [SEP] |
| Normal | Normal (0.20) | Normal | 0.75 | [CLS] aircraft landing [SEP] |
| Normal | Normal (0.20) | Normal | 0.75 | [CLS] aircraft landing [SEP] |

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|---------------|-----------------------------|---------------|-------------|--|
| Normal | Normal (0.20) | Normal | 0.44 | the speed of descent and use sticks to avoid obstacles [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.32 | [CLS] critically low voltage warning . [SEP] |
| Normal | Normal (0.20) | Normal | 1.09 | [CLS] aircraft will be forced to land [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.60 | [CLS] critically low voltage . [SEP] |
| Normal | Normal (0.20) | Normal | 0.62 | [CLS] aircraft will land [SEP] |
| Normal | Normal (0.20) | Normal | 1.92 | [CLS] data recorder file index is 15 . [SEP] |
| Normal | Normal (0.20) | Normal | 1.94 | [CLS] data recorder file index is 17 . [SEP] |
| Normal | Normal (0.20) | Normal | 1.98 | [CLS] data recorder file index is 30 . [SEP] |
| Normal | Normal (0.20) | Normal | 1.97 | [CLS] data recorder file index is 45 . [SEP] |
| Normal | Normal (0.20) | Normal | 1.79 | [CLS] data recorder file index is 46 . [SEP] |
| Normal | Normal (0.20) | Normal | 1.75 | [CLS] data recorder file index is 65 . [SEP] |
| Normal | Normal (0.20) | Normal | 1.25 | [CLS] disable sd card read and write |

| | | | | |
|-------------------------------|--|-------------------------------|--------------|---|
| | | | | protection or change card [SEP] |
| CommunicationIssue | CommunicationIssue (0.82) | CommunicationIssue | 1.74 | [CLS] downlink lost . [SEP] |
| Normal | Normal (0.20) | Normal | 0.72 | [CLS] downlink restored (after 0m 2 9s) . [SEP] |
| Normal | HardwareFault (0.42) | HardwareFault | -1.51 | [CLS] drone is vibrating [SEP] |
| Normal | Normal (0.20) | Normal | 0.94 | [CLS] entered cruise control mode . [SEP] |
| Normal | Normal (0.20) | Normal | 1.39 | [CLS] press c1 or c2 to exit [SEP] |
| ParamViolation | ParamViolation (0.57) | ParamViolation | 1.88 | [CLS] excessive attitude angle detected [SEP] |
| SoftwareFault | SoftwareFault (0.57) | SoftwareFault | 1.48 | [CLS] forward obstacle avoidance has stopped working [SEP] |
| Normal | Normal (0.19) | Normal | -0.02 | [CLS] exit backward sensing system [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.62) | SurroundingEnvironment | 1.54 | [CLS] ambient light is too weak [SEP] |
| Normal | Normal (0.20) | Normal | 0.80 | [CLS] exited visual avoidance system . [SEP] |
| SoftwareFault | SoftwareFault (0.57) | SoftwareFault | 1.05 | [CLS] exiting gps mode : unknown error [SEP] |

| | | | | |
|-----------------------|----------------------------------|-----------------------|--------------|---|
| ParamViolation | ParamViolation (0.61) | ParamViolation | 1.68 | [CLS] extra payload detected . [SEP] |
| Normal | Normal (0.20) | Normal | 1.90 | [CLS] flight performance will be affected . [SEP] |
| Normal | Normal (0.19) | Normal | 0.73 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (0.58) | SoftwareFault | 1.56 | [CLS] forward obstacle sensing is not functioning . [SEP] |
| SoftwareFault | SoftwareFault (0.57) | SoftwareFault | 1.62 | [CLS] forward obstacle sensing not responding [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.61 | [CLS] gimbal motor overloaded . [SEP] |
| Normal | Normal (0.20) | Normal | 1.54 | [CLS] check whether gimbal can rotate freely [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.89 | [CLS] gimbal pitch limit reached . [SEP] |
| Normal | Normal (0.18) | Normal | -1.13 | [CLS] ground plain . [SEP] |
| Normal | Normal (0.20) | Normal | 1.19 | [CLS] safe to land . [SEP] |
| ParamViolation | ParamViolation (0.57) | ParamViolation | 1.69 | [CLS] high altitude . [SEP] |
| Normal | ParamViolation (0.36) | ParamViolation | -2.31 | [CLS] aircraft braking distance increased and flight time decreased . [SEP] |

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|-------------------------------|--------------------------------------|-------------------------------|--------------|---|
| Normal | Normal (0.19) | Normal | 0.73 | [CLS] fly with caution [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.61) | SurroundingEnvironment | 1.50 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (0.20) | Normal | 0.35 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.61) | SurroundingEnvironment | 1.50 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (0.20) | Normal | 0.35 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.61) | SurroundingEnvironment | 1.50 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (0.20) | Normal | 2.65 | [CLS] fly with caution and land in a safe place asap . [SEP] |
| Normal | ParamViolation (0.58) | ParamViolation | -2.18 | [CLS] high - altitude flight [SEP] |
| Normal | Normal (0.19) | Normal | 0.73 | [CLS] fly with caution [SEP] |
| Normal | ParamViolation (0.54) | ParamViolation | -2.05 | [CLS] aircraft braking distance is extended [SEP] |
| Normal | ParamViolation (0.41) | ParamViolation | -1.89 | [CLS] flight time is shortened . [SEP] |
| Normal | Normal (0.20) | Normal | 0.58 | [CLS] home |

| | | | | |
|----------------|----------------------------------|-----------------------|--------------|----------------|
| | | | | point updated |
| | | | | . [SEP] |
| | | | | [CLS] imu |
| | | | | attitude |
| | | | | restricted. |
| | | | | [SEP] |
| | | | | [CLS] ensure |
| | | | | aircraft is |
| | | | | level [SEP] |
| | | | | [CLS] imu not |
| | | | | calibrated. |
| | | | | [SEP] |
| | | | | [CLS] |
| | | | | calibrate imu |
| | | | | [SEP] |
| | | | | [CLS] landing |
| | | | | canceled. |
| | | | | [SEP] |
| | | | | [CLS] landing |
| | | | | gear function |
| | | | | restored |
| | | | | [SEP] |
| | | | | [CLS] landing |
| | | | | gear paused. |
| | | | | [SEP] |
| | | | | [CLS] landing |
| | | | | gear raising. |
| | | | | [SEP] |
| | | | | [CLS] home |
| | | | | point |
| | | | | recorded |
| | | | | [SEP] |
| | | | | [CLS] live |
| | | | | stream video |
| | | | | frame rate |
| | | | | less than 9hz |
| | | | | . [SEP] |
| | | | | [CLS] fly with |
| | | | | caution [SEP] |
| | | | | [CLS] low |
| | | | | power. [SEP] |
| | | | | [CLS] aircraft |
| | | | | is returning |
| | | | | to the home |
| | | | | point. [SEP] |
| | | | | [CLS] low |
| | | | | power. [SEP] |
| ParamViolation | ParamViolation (0.51) | ParamViolation | 1.58 | point updated |
| Normal | Normal (0.20) | Normal | 0.82 | . [SEP] |
| SoftwareFault | Normal (0.20) | Normal | -0.36 | [CLS] imu |
| Normal | Normal (0.19) | Normal | 0.61 | attitude |
| Normal | Normal (0.20) | Normal | 0.80 | restricted. |
| Normal | Normal (0.20) | Normal | 0.90 | [SEP] |
| Normal | Normal (0.20) | Normal | 0.51 | [CLS] |
| Normal | Normal (0.20) | Normal | 0.76 | calibrate imu |
| Normal | Normal (0.19) | Normal | 0.54 | [SEP] |
| Normal | ParamViolation (0.21) | ParamViolation | -1.56 | [CLS] landing |
| Normal | Normal (0.19) | Normal | 0.73 | gear paused. |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.34 | [SEP] |
| Normal | Normal (0.20) | Normal | 1.77 | [CLS] live |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.34 | stream video |

| | | | | |
|-------------------------------|--------------------------------------|-------------------------------|-------------|--|
| Normal | Normal (0.19) | Normal | 0.58 | [CLS] returning home . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.61) | SurroundingEnvironment | 1.48 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (0.19) | Normal | 0.63 | [CLS] exit p - gps mode . [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.10 | [CLS] yaw error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.58) | SurroundingEnvironment | 1.36 | [CLS] manned aircraft detected nearby . [SEP] |
| Normal | Normal (0.19) | Normal | 0.73 | [CLS] fly with caution [SEP] |
| ParamViolation | ParamViolation (0.59) | ParamViolation | 1.46 | [CLS] max altitude approached . [SEP] |
| Normal | Normal (0.20) | Normal | 0.10 | [CLS] wait for the gps satellite |
| ParamViolation | ParamViolation (0.62) | ParamViolation | 1.96 | signal recovery before ascend [SEP] |
| Normal | Normal (0.20) | Normal | 1.97 | [CLS] max flight altitude reached . [SEP] |
| ParamViolation | ParamViolation (0.62) | ParamViolation | 1.98 | [CLS] adjust in main controller settings if necessary [SEP] |

| | | | | |
|----------------|-----------------------|----------------|------|---|
| Normal | Normal (0.20) | Normal | 2.27 | in main controller settings if necessary . [SEP] |
| ParamViolation | ParamViolation (0.62) | ParamViolation | 2.03 | [CLS] maximum flight distance reached . [SEP] |
| Normal | Normal (0.20) | Normal | 1.51 | [CLS] adjust the distance in mc settings if required . [SEP] |
| HardwareFault | HardwareFault (0.42) | HardwareFault | 2.09 | [CLS] mobile device cpu fully loaded . [SEP] |
| Normal | Normal (0.20) | Normal | 2.73 | [CLS] related performance will be affected . [SEP] |
| SoftwareFault | Normal (0.19) | Normal | 0.02 | [CLS] mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP] |
| Normal | Normal (0.20) | Normal | 0.30 | [CLS] motor is blocked . [SEP] |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 1.71 | [CLS] motor stuck . [SEP] |
| Normal | Normal (0.20) | Normal | 1.65 | [CLS] check for objects blocking motor or contact dji support for |

| | | | | |
|---------------|-----------------------------|----------------------|--------------|--|
| | | | | assistance |
| | | | | [SEP] |
| Normal | HardwareFault (0.41) | HardwareFault | -1.82 | [CLS] motors started . [SEP] |
| SoftwareFault | SoftwareFault (0.57) | SoftwareFault | 1.89 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (0.43) | HardwareFault | -1.02 | [CLS] aircraft unable to hover . [SEP] |
| Normal | Normal (0.19) | Normal | 0.73 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (0.57) | SoftwareFault | 1.89 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (0.43) | HardwareFault | -1.53 | [CLS] unable to hover . [SEP] |
| Normal | Normal (0.19) | Normal | 0.73 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.20) | Normal | 0.67 | [CLS] obstacle avoidance disabled . [SEP] |
| Normal | Normal (0.20) | Normal | 0.60 | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (0.20) | Normal | 0.67 | [CLS] obstacle avoidance disabled . [SEP] |
| Normal | Normal (0.20) | Normal | 0.67 | [CLS] obstacle avoidance disabled . [SEP] |
| Normal | Normal (0.20) | Normal | 0.60 | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (0.20) | Normal | 1.03 | [CLS] obstacle avoidance has been disabled . [SEP] |
| Normal | Normal (0.19) | Normal | -0.16 | [CLS] precision |

| | | | | |
|------------------------|--------------------------------------|------------------------|-------------|---|
| Normal | Normal (0.20) | Normal | 0.82 | landing [SEP] [CLS] quickshot has ended [SEP] |
| Normal | Normal (0.20) | Normal | 1.61 | [CLS] recenter gimbal pan [SEP] |
| Normal | Normal (0.20) | Normal | 2.03 | [CLS] rectifying aircraft position [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.61) | SurroundingEnvironment | 1.52 | [CLS] remote controller in high interference environment . [SEP] |
| Normal | Normal (0.20) | Normal | 2.10 | [CLS] manually adjust flight route or return to home [SEP] |
| Normal | Normal (0.20) | Normal | 1.34 | [CLS] return - to - home altitude : 65ft [SEP] |
| Normal | Normal (0.20) | Normal | 1.70 | [CLS] return - to - home altitude : 98ft . [SEP] |
| Normal | Normal (0.20) | Normal | 2.24 | [CLS] rth : ascending to rth altitude . [SEP] |
| Normal | Normal (0.20) | Normal | 1.41 | [CLS] rth : heading alignment . [SEP] |
| Normal | Normal (0.20) | Normal | 1.59 | [CLS] rth altitude : 65ft . [SEP] |
| Normal | Normal (0.20) | Normal | 1.51 | [CLS] rth altitude : 98ft . [SEP] |
| CommunicationIssue | CommunicationIssue (0.82) | CommunicationIssue | 1.33 | [CLS] signal |

| | | | | |
|------------------------|--------------------------------------|------------------------|-------------|--|
| Normal | Normal (0.20) | Normal | 1.61 | lost . [SEP] [CLS] aircraft returning to home point [SEP] |
| Normal | Normal (0.20) | Normal | 1.21 | [CLS] sprayer turned on [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.61) | SurroundingEnvironment | 1.38 | [CLS] strong wind warning . [SEP] |
| SoftwareFault | SoftwareFault (0.58) | SoftwareFault | 1.26 | [CLS] aircraft unable to return to home automatically . [SEP] |
| Normal | Normal (0.20) | Normal | 1.87 | [CLS] lower altitude immediately and return to home manually [SEP] |
| Normal | Normal (0.20) | Normal | 1.59 | [CLS] switched to s (sport) - mode . [SEP] |
| Normal | Normal (0.20) | Normal | 1.32 | [CLS] switched to t (tripod) - mode . [SEP] |
| Normal | Normal (0.20) | Normal | 1.99 | [CLS] take off in p - mode [SEP] |
| SoftwareFault | HardwareFault (0.39) | HardwareFault | 0.17 | [CLS] vision sensor error. [SEP] |
| Normal | Normal (0.20) | Normal | 1.96 | [CLS] contact dji support for assistance [SEP] |
| Normal | Normal (0.20) | Normal | 0.68 | [CLS] vision systems and obstacle avoidance disabled [SEP] |

| | | | | |
|---------------------|-----------------------------------|---------------------|--------------|--|
| Normal | Normal (0.20) | Normal | 0.48 | [CLS] waypoint mission paused [SEP] [CLS] weak |
| SoftwareFault | SoftwareFault (0.56) | SoftwareFault | 1.86 | gps signal . [SEP] [CLS] aircraft is in attitude |
| Normal | Normal (0.20) | Normal | 1.37 | mode and hovering may be unstable . [SEP] [CLS] fly with |
| Normal | Normal (0.20) | Normal | 0.95 | caution . [SEP] |
| CommunicationIssue | CommunicationIssue (0.82) | CommunicationIssue | 1.28 | [CLS] weak signal . [SEP] [CLS] adjust |
| Normal | Normal (0.19) | Normal | -0.11 | antennas [SEP] [CLS] your aircraft is |
| RegulationViolation | RegulationViolation (0.75) | RegulationViolation | 2.20 | flying in an altitude zone (nnn) . [SEP] [CLS] please |
| Normal | Normal (0.20) | Normal | 1.74 | fly with caution [SEP] |