

Legend: ■ Negative □ Neutral ■ Positive

| True Label | Predicted Label | Attribution Label | Attribution Score | Word Importance |
|------------------------|-----------------------|-------------------|-------------------|--|
| SurroundingEnvironment | Normal (0.99) | Normal | 0.81 | [CLS] a passenger aircraft is nearby . [SEP] |
| | | | | [CLS] fly with caution [SEP] |
| | | | | [CLS] account not logged in . [SEP] |
| Normal | Normal (1.00) | Normal | 0.91 | |
| Normal | Normal (0.87) | Normal | -0.30 | |
| ParamViolation | ParamViolation (0.99) | ParamViolation | 0.75 | [CLS] flight altitude and distance restricted to nnn and nnn . [SEP] |
| | | | | [CLS] check and log in [SEP] |
| | | | | [CLS] activetrack flight paused [SEP] |
| Normal | Normal (1.00) | Normal | -0.34 | |
| Normal | Normal (1.00) | Normal | 1.80 | |
| Normal | Normal (1.00) | Normal | 2.45 | [CLS] aircraft activetrack available at max speed . [SEP] |
| | | | | [CLS] obstacle avoidance is not available [SEP] |
| | | | | [CLS] aircraft activetrack available at max speed . [SEP] |
| Normal | Normal (1.00) | Normal | 0.48 | |
| Normal | Normal (1.00) | Normal | 2.45 | |
| Normal | ParamViolation (0.45) | ParamViolation | -0.26 | [CLS] when exceeding nnn , obstacle avoidance is not available [SEP] |
| | | | | [CLS] aircraft |
| | | | | |

| | | | | |
|---------------------|----------------------------|---------------------|-------|---|
| Normal | Normal (1.00) | Normal | 1.18 | activetrack max speed of nnn and obstacle avoidance functions normally [SEP] |
| | | | | [CLS] aircraft core board overheated [SEP] |
| | | | | [CLS] aircraft entered fixed - wing mode . [SEP] |
| | | | | [CLS] current flight speed is nnn . [SEP] |
| | | | | [CLS] press c2 to exit [SEP] |
| Normal | Normal (1.00) | Normal | 1.70 | [CLS] aircraft flight control unlocked [SEP] |
| | | | | [CLS] aircraft in restricted zones . [SEP] |
| | | | | [CLS] check map to find recommended zones [SEP] |
| | | | | [CLS] aircraft is in attitude mode , so that it will not hover . [SEP] |
| | | | | [CLS] please fly with caution . [SEP] |
| Normal | Normal (1.00) | Normal | 1.89 | [CLS] aircraft is in tripod mode . [SEP] |
| | | | | [CLS] exit this mode and try again |
| | | | | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 0.96 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| RegulationViolation | RegulationViolation (0.97) | RegulationViolation | 1.80 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 2.34 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 1.01 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 0.95 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 0.82 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| Normal | Normal (0.52) | Normal | -1.12 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 0.13 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.89 | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| Normal | Normal (1.00) | Normal | 1.18 | |
| | | | | |
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|---------------------|----------------------------|---------------------|------|--|
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 0.72 | [CLS] aircraft is returning to the starting point [SEP] |
| ParamViolation | ParamViolation (0.95) | ParamViolation | 1.35 | [CLS] aircraft out of range [SEP] |
| RegulationViolation | RegulationViolation (0.86) | RegulationViolation | 1.89 | [CLS] approaching a no - fly zone . [SEP] |
| Normal | Normal (1.00) | Normal | 1.97 | [CLS] rth may be affected . [SEP] |
| Normal | Normal (1.00) | Normal | 0.91 | [CLS] fly with caution [SEP] |
| Normal | Normal (1.00) | Normal | 1.40 | [CLS] arrived at start point . [SEP] |
| Normal | Normal (1.00) | Normal | 2.10 | [CLS] starting waypoint mission [SEP] |
| Normal | Normal (1.00) | Normal | 0.71 | [CLS] auto landing initiated [SEP] |
| Normal | Normal (1.00) | Normal | 1.47 | [CLS] auxiliary bottom light turned off [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.93 | [CLS] backward obstacle sensing is not functioning . [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.60 | [CLS] battery cell broken , please replace the battery [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 0.84 | [CLS] battery error . [SEP] |
| | | | | [CLS] aircraft returning to |

| | | | | |
|------------------------|-----------------------|----------------|------|---|
| Normal | Normal (1.00) | Normal | 0.54 | home automatically [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.71 | [CLS] battery power low . [SEP] |
| Normal | Normal (1.00) | Normal | 1.10 | [CLS] check battery status and charge or warm up battery [SEP] |
| HardwareFault | HardwareFault (0.74) | HardwareFault | 0.90 | [CLS] cache space full [SEP] |
| SurroundingEnvironment | SoftwareFault (0.59) | SoftwareFault | 0.19 | [CLS] calibration subject is too close . [SEP] |
| Normal | Normal (1.00) | Normal | 2.21 | [CLS] recalibrate using a subject that is farther away [SEP] |
| HardwareFault | SoftwareFault (0.97) | SoftwareFault | 0.13 | [CLS] camera busy , cannot enter playback [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.16 | [CLS] cannot enable intelligent flight mode [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.57 | [CLS] low battery [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.57 | [CLS] cannot start return to home due to weak gps signal [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.20 | [CLS] cannot start self - timer . [SEP] |
| SoftwareFault | ParamViolation (0.97) | ParamViolation | 0.82 | [CLS] exposure time is too long [SEP] |

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|------------------------|----------------------|---------------|-------|---|
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.09 | [CLS] cannot switch flight mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.83 | [CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 0.51 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.92) | SoftwareFault | -0.15 | [CLS] no image [SEP] |
| Normal | Normal (1.00) | Normal | 1.80 | [CLS] please retry [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 0.51 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (1.00) | SoftwareFault | 0.42 | [CLS] subject too large [SEP] |
| Normal | Normal (1.00) | Normal | -0.51 | [CLS] move away and retry [SEP] |
| Normal | Normal (1.00) | Normal | -0.08 | [CLS] color display in the liveview has been enhanced . [SEP] |
| Normal | Normal (1.00) | Normal | 2.93 | [CLS] videos and photos will still be shot in d - log mode [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.52 | [CLS] compass abnormal . [SEP] |
| Normal | Normal (1.00) | Normal | 0.34 | [CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft . |

| | | | | |
|------------------------|-------------------------------|------------------------|------|---|
| | | | | [SEP] |
| Normal | Normal (0.99) | Normal | 1.46 | [CLS] the ground or walls may contain metal . [SEP] |
| Normal | Normal (1.00) | Normal | 1.60 | [CLS] move away from sources of interference before attempting flight . [SEP] |
| Normal | Normal (1.00) | Normal | 1.29 | [CLS] 2 . calibrate compass before takeoff [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.44 | [CLS] compass error [SEP] |
| HardwareFault | HardwareFault (0.57) | HardwareFault | 0.58 | [CLS] compass error , calibration required [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.16 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.16 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.71 | [CLS] compass disconnected [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.16 | [CLS] compass error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.29 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | 2.03 | [CLS] exit p - gps mode [SEP] |

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|---------------|----------------------|---------------|------|--|
| | | | | [CLS] |
| SoftwareFault | HardwareFault (1.00) | HardwareFault | 0.76 | compass initialization failed . [SEP] |
| Normal | Normal (1.00) | Normal | 0.73 | [CLS] restart aircraft [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.64 | [CLS] critical low battery . [SEP] |
| Normal | Normal (1.00) | Normal | 0.14 | [CLS] aircraft in auto power off protection . [SEP] |
| Normal | Normal (1.00) | Normal | 1.85 | [CLS] forced landing in progress [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.64 | [CLS] critical low battery . [SEP] |
| Normal | Normal (1.00) | Normal | 1.15 | [CLS] aircraft landing automatically [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.64 | [CLS] critical low battery . [SEP] |
| Normal | Normal (1.00) | Normal | 2.26 | [CLS] return to home or land promptly [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.64 | [CLS] critically low power . [SEP] |
| Normal | Normal (0.99) | Normal | 0.79 | [CLS] aircraft is landing [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.64 | [CLS] critically low power . [SEP] |
| Normal | Normal (1.00) | Normal | 0.39 | [CLS] aircraft landing . [SEP] |
| Normal | Normal (1.00) | Normal | 0.39 | [CLS] aircraft landing . [SEP] |
| | | | | [CLS] throttle up to reduce |

| | | | | |
|---------------|----------------------|---------------|-------|--|
| Normal | Normal (1.00) | Normal | 2.93 | the speed of descent and use sticks to avoid obstacles [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 0.66 | [CLS] critically low voltage warning . [SEP] |
| Normal | Normal (0.95) | Normal | -1.00 | [CLS] aircraft will be forced to land [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.58 | [CLS] critically low voltage . [SEP] |
| Normal | Normal (1.00) | Normal | -0.58 | [CLS] aircraft will land [SEP] |
| Normal | Normal (1.00) | Normal | 1.95 | [CLS] data recorder file index is 15 . [SEP] |
| Normal | Normal (1.00) | Normal | 2.02 | [CLS] data recorder file index is 17 . [SEP] |
| Normal | Normal (1.00) | Normal | 2.07 | [CLS] data recorder file index is 30 . [SEP] |
| Normal | Normal (1.00) | Normal | 1.85 | [CLS] data recorder file index is 45 . [SEP] |
| Normal | Normal (1.00) | Normal | 2.05 | [CLS] data recorder file index is 46 . [SEP] |
| Normal | Normal (1.00) | Normal | 1.83 | [CLS] data recorder file index is 65 . [SEP] |
| Normal | Normal (1.00) | Normal | 2.65 | [CLS] disable sd card read and write |

| | | | | |
|------------------------|----------------------------------|------------------------|-------|---|
| | | | | protection or change card [SEP] |
| CommunicationIssue | CommunicationIssue (0.95) | CommunicationIssue | 1.31 | [CLS] downlink lost . [SEP] |
| Normal | Normal (1.00) | Normal | 1.96 | [CLS] downlink restored (after 0m 2 . 9s) . [SEP] |
| Normal | Normal (0.66) | Normal | 1.01 | [CLS] drone is vibrating [SEP] |
| Normal | Normal (1.00) | Normal | 1.90 | [CLS] entered cruise control mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.95 | [CLS] press c1 or c2 to exit [SEP] |
| ParamViolation | ParamViolation (0.99) | ParamViolation | 1.05 | [CLS] excessive attitude angle detected [SEP] |
| SoftwareFault | Normal (1.00) | Normal | -0.93 | [CLS] forward obstacle avoidance has stopped working [SEP] |
| Normal | Normal (1.00) | Normal | 0.65 | [CLS] exit backward sensing system [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 2.08 | [CLS] ambient light is too weak [SEP] |
| Normal | Normal (1.00) | Normal | 1.72 | [CLS] exited visual avoidance system . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.06 | [CLS] exiting gps mode : unknown error [SEP] |

| | | | | |
|----------------|-----------------------|----------------|-------|---|
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.13 | [CLS] extra payload detected . [SEP] |
| Normal | Normal (1.00) | Normal | 1.28 | [CLS] flight performance will be affected . [SEP] |
| Normal | Normal (1.00) | Normal | 0.91 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.19 | [CLS] forward obstacle sensing is not functioning . [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 1.05 | [CLS] forward obstacle sensing not responding [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.95 | [CLS] gimbal motor overloaded . [SEP] |
| Normal | Normal (1.00) | Normal | -0.28 | [CLS] check whether gimbal can rotate freely [SEP] |
| HardwareFault | HardwareFault (0.87) | HardwareFault | 1.37 | [CLS] gimbal pitch limit reached . [SEP] |
| Normal | Normal (0.77) | Normal | -0.08 | [CLS] ground plain . [SEP] |
| Normal | Normal (1.00) | Normal | 2.20 | [CLS] safe to land . [SEP] |
| ParamViolation | ParamViolation (0.73) | ParamViolation | 1.08 | [CLS] high altitude . [SEP] |
| Normal | Normal (0.66) | Normal | -0.68 | [CLS] aircraft braking distance increased and flight time decreased . [SEP] |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| Normal | Normal (1.00) | Normal | 0.91 | [CLS] fly with caution [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.44 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 2.60 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.44 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 2.60 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.44 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 1.91 | [CLS] fly with caution and land in a safe place asap . [SEP] |
| Normal | ParamViolation (0.91) | ParamViolation | -0.65 | [CLS] high - altitude flight [SEP] |
| Normal | Normal (1.00) | Normal | 0.91 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.99) | Normal | -0.12 | [CLS] aircraft braking distance is extended [SEP] |
| Normal | Normal (1.00) | Normal | -0.61 | [CLS] flight time is shortened . [SEP] |
| Normal | Normal (1.00) | Normal | 0.14 | [CLS] home |

| | | | | |
|----------------|-----------------------|----------------|-------|--|
| ParamViolation | ParamViolation (0.92) | ParamViolation | 1.67 | point updated . [SEP] |
| | | | | [CLS] imu attitude restricted . [SEP] |
| | | | | [CLS] ensure aircraft is level [SEP] |
| | | | | [CLS] imu not calibrated . [SEP] |
| Normal | Normal (1.00) | Normal | -0.33 | [CLS] calibrate imu [SEP] |
| SoftwareFault | Normal (0.95) | Normal | 1.04 | [CLS] landing canceled . [SEP] |
| Normal | Normal (1.00) | Normal | 1.99 | [CLS] landing gear function restored [SEP] |
| Normal | SoftwareFault (0.98) | SoftwareFault | -0.98 | [CLS] landing gear paused . [SEP] |
| Normal | Normal (1.00) | Normal | -0.31 | [CLS] landing gear raising . [SEP] |
| Normal | Normal (0.99) | Normal | 1.64 | [CLS] home point recorded [SEP] |
| Normal | Normal (1.00) | Normal | 2.02 | [CLS] live stream video frame rate less than 9hz . [SEP] |
| Normal | Normal (1.00) | Normal | 1.60 | [CLS] fly with caution [SEP] |
| Normal | ParamViolation (0.97) | ParamViolation | -0.34 | [CLS] low power . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.56 | [CLS] aircraft is returning to the home point . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.88 | [CLS] low power . [SEP] |
| HardwareFault | HardwareFault (1.00) | HardwareFault | 1.56 | [CLS] low power . [SEP] |

| | | | | |
|------------------------|-------------------------------|------------------------|------|--|
| Normal | Normal (1.00) | Normal | 1.60 | [CLS] returning home . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.29 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | 2.24 | [CLS] exit p - gps mode . [SEP] |
| HardwareFault | HardwareFault (0.97) | HardwareFault | 1.34 | [CLS] yaw error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.35) | SurroundingEnvironment | 1.46 | [CLS] manned aircraft detected nearby . [SEP] |
| Normal | Normal (1.00) | Normal | 0.91 | [CLS] fly with caution [SEP] |
| ParamViolation | ParamViolation (0.96) | ParamViolation | 1.31 | [CLS] max altitude approached . [SEP] |
| Normal | Normal (1.00) | Normal | 2.36 | [CLS] wait for the gps satellite signal recovery before ascend [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.76 | [CLS] max flight altitude reached . [SEP] |
| Normal | Normal (1.00) | Normal | 0.44 | [CLS] adjust in main controller settings if necessary [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.56 | [CLS] max flight distance reached . [SEP] |
| | | | | [CLS] adjust |

| | | | | |
|----------------|-----------------------|----------------|------|---|
| Normal | Normal (1.00) | Normal | 2.04 | in main controller settings if necessary . [SEP] |
| ParamViolation | ParamViolation (1.00) | ParamViolation | 1.81 | [CLS] maximum flight distance reached . [SEP] |
| Normal | Normal (1.00) | Normal | 2.47 | [CLS] adjust the distance in mc settings if required . [SEP] |
| HardwareFault | Normal (0.99) | Normal | 0.52 | [CLS] mobile device cpu fully loaded . [SEP] |
| Normal | Normal (1.00) | Normal | 2.05 | [CLS] related performance will be affected . [SEP] |
| SoftwareFault | Normal (0.75) | Normal | 1.22 | [CLS] mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP] |
| Normal | Normal (1.00) | Normal | 0.52 | [CLS] motor is blocked . [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 0.28 | [CLS] motor stuck . [SEP] |
| Normal | Normal (1.00) | Normal | 1.38 | [CLS] check for objects blocking motor or contact dji support for |

| | | | | |
|---------------|----------------------|---------------|-------|----------------|
| | | | | assistance |
| | | | | [SEP] |
| Normal | Normal (0.99) | Normal | 1.31 | [CLS] motors |
| | | | | started . |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 0.55 | [CLS] no gps |
| | | | | signal . [SEP] |
| Normal | HardwareFault (0.93) | HardwareFault | -0.33 | [CLS] aircraft |
| | | | | unable to |
| Normal | Normal (1.00) | Normal | 0.91 | hover . [SEP] |
| | | | | [CLS] fly with |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 0.55 | caution [SEP] |
| | | | | [CLS] no gps |
| Normal | HardwareFault (0.93) | HardwareFault | -1.01 | signal . [SEP] |
| | | | | [CLS] unable |
| Normal | Normal (1.00) | Normal | 0.91 | to hover . |
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 1.79 | [CLS] fly with |
| | | | | caution [SEP] |
| Normal | Normal (1.00) | Normal | 2.24 | [CLS] |
| | | | | obstacle |
| Normal | Normal (1.00) | Normal | 1.79 | avoidance |
| | | | | disabled . |
| Normal | Normal (1.00) | Normal | 2.24 | [SEP] |
| | | | | [CLS] landing |
| Normal | Normal (1.00) | Normal | 1.79 | gear lowered |
| | | | | . [SEP] |
| Normal | Normal (1.00) | Normal | 1.79 | [CLS] |
| | | | | obstacle |
| Normal | Normal (1.00) | Normal | 1.79 | avoidance |
| | | | | disabled . |
| Normal | Normal (1.00) | Normal | 2.24 | [SEP] |
| | | | | [CLS] landing |
| Normal | Normal (1.00) | Normal | 1.90 | gear lowered |
| | | | | . [SEP] |
| Normal | Normal (1.00) | Normal | 0.96 | [CLS] |
| | | | | obstacle |
| Normal | Normal (1.00) | Normal | 0.96 | avoidance has |
| | | | | been disabled |
| Normal | Normal (1.00) | Normal | 0.96 | . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 0.96 | precision |
| | | | | |

| | | | | |
|------------------------|-------------------------------|------------------------|-------|--|
| | | | | landing [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 1.34 | quickshot has ended [SEP] |
| | | | | [CLS] |
| Normal | Normal (0.91) | Normal | -0.31 | recenter gimbal pan [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | -0.55 | rectifying aircraft position [SEP] |
| | | | | [CLS] |
| SurroundingEnvironment | SurroundingEnvironment (0.99) | SurroundingEnvironment | 1.87 | remote controller in high interference environment . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 2.79 | manually adjust flight route or return to home [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 0.32 | return - to - home altitude : 65ft [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 0.24 | return - to - home altitude : 98ft . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 0.87 | rth : ascending to rth altitude . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 2.01 | rth : heading alignment . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 1.12 | rth altitude : 65ft . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 1.48 | rth altitude : 98ft . [SEP] |
| | | | | [CLS] |
| CommunicationIssue | CommunicationIssue (0.64) | CommunicationIssue | 0.72 | [CLS] signal |

| | | | | |
|------------------------|-------------------------------|------------------------|------|---|
| | | | | lost . [SEP] |
| | | | | [CLS] aircraft |
| Normal | Normal (1.00) | Normal | 1.83 | returning to home point [SEP] |
| | | | | [CLS] sprayer |
| Normal | Normal (1.00) | Normal | 2.18 | turned on [SEP] |
| | | | | [CLS] strong |
| SurroundingEnvironment | SurroundingEnvironment (1.00) | SurroundingEnvironment | 1.39 | wind warning [SEP] |
| | | | | [CLS] aircraft |
| | | | | unable to |
| SoftwareFault | SoftwareFault (0.96) | SoftwareFault | 0.88 | return to home automatically [SEP] |
| | | | | [CLS] lower |
| | | | | altitude |
| | | | | immediately |
| Normal | Normal (1.00) | Normal | 1.92 | and return to home manually [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 0.17 | switched to s (sport) - mode . [SEP] |
| | | | | [CLS] |
| Normal | Normal (1.00) | Normal | 0.85 | switched to t (tripod) - mode . [SEP] |
| | | | | [CLS] take off |
| Normal | Normal (1.00) | Normal | 2.49 | in p - mode [SEP] |
| | | | | [CLS] vision |
| SoftwareFault | SoftwareFault (0.94) | SoftwareFault | 1.50 | sensor error . [SEP] |
| | | | | [CLS] contact |
| Normal | Normal (1.00) | Normal | 2.09 | dji support for assistance [SEP] |
| | | | | [CLS] vision |
| | | | | systems and |
| | | | | obstacle |
| Normal | Normal (1.00) | Normal | 1.96 | avoidance disabled [SEP] |

| | | | | |
|---------------------|----------------------------|---------------------|------|---|
| Normal | Normal (1.00) | Normal | 1.86 | [CLS] waypoint mission paused [SEP] |
| SoftwareFault | SoftwareFault (1.00) | SoftwareFault | 0.67 | [CLS] weak gps signal . [SEP] |
| Normal | Normal (0.99) | Normal | 1.10 | [CLS] aircraft is in attitude mode and hovering may be unstable . [SEP] |
| Normal | Normal (1.00) | Normal | 1.90 | [CLS] fly with caution . [SEP] |
| CommunicationIssue | CommunicationIssue (0.98) | CommunicationIssue | 1.13 | [CLS] weak signal . [SEP] |
| Normal | Normal (1.00) | Normal | 1.33 | [CLS] adjust antennas [SEP] |
| RegulationViolation | RegulationViolation (0.91) | RegulationViolation | 2.37 | [CLS] your aircraft is flying in an altitude zone (nnn) . [SEP] |
| Normal | Normal (1.00) | Normal | 1.93 | [CLS] please fly with caution [SEP] |