

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.17	#s a
				passenger
				aircraft is nearby . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	#s fly with
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.16	caution #/s
				#s account
				not logged in . #/s
ParamViolation	ParamViolation (0.22)	ParamViolation	0.65	#s flight
				altitude and
				distance
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.75	restricted to
				nnn and nnn .
				#/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.37	#s check and
				log in #/s
				#s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.13	activetrack
				flight paused
				#/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.13	#s aircraft
				activetrack
				available at
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.24	max speed .
				#/s
				#s obstacle
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.13	avoidance is
				not available
				#/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.13	#s aircraft
				activetrack
				available at
Normal	ParamViolation (0.21)	ParamViolation	-1.20	max speed .
				#/s
				#s when
Normal	ParamViolation (0.21)	ParamViolation	-1.20	exceeding
				nnn , obstacle
				avoidance is
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.61	not available
				#/s
				#s aircraft
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.61	activetrack
				max speed of
				nnn and

				obstacle
				avoidance
				functions
				normally #/s
				#s aircraft
HardwareFault	HardwareFault (0.16)	HardwareFault	1.36	core board
				overheated
				#/s
				#s aircraft
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.41	entered fixed
				- wing mode .
				#/s
				#s current
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.06	flight speed is
				nnn . #/s
				#s press c2
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.98	to exit #/s
				#s aircraft
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.38	flight control
				unlocked #/s
				#s aircraft in
RegulationViolation	RegulationViolation (0.19)	RegulationViolation	0.93	restricted
				zones . #/s
				#s check map
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.74	to find
				recommended
				zones #/s
				#s aircraft is
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.90	in attitude
				mode , so that
				it will not
				hover . #/s
				#s please fly
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.46	with caution .
				#/s
				#s aircraft is
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.10	in tripod
				mode . #/s
				#s exit this
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.02	mode and try
				again #/s
				#s aircraft is
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.99	returning to
				the starting
				point #/s
				#s aircraft
ParamViolation	ParamViolation (0.22)	ParamViolation	1.38	out of range
				#/s

RegulationViolation	RegulationViolation (0.19)	RegulationViolation	1.58	#s approaching a no - fly zone . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.05	#s rth may be affected . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	#s fly with caution #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.54	#s arrived at start point . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.46	#s starting waypoint mission #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.44	#s auto landing initiated #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.80	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.78	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	-0.89	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.08	#s battery error . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.71	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.38	#s battery power low . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.34	#s check battery status and charge or warm up battery #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.47	#s cache space full #/s

SurroundingEnvironment	SoftwareFault (0.18)	SoftwareFault	0.30	#s calibration subject is too close . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.39	#s recalibrate using a subject that is farther away #/s
HardwareFault	HardwareFault (0.15)	HardwareFault	1.32	#s camera busy , cannot enter playback #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.44	#s cannot enable intelligent flight mode #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.39	#s low battery #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	0.54	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	0.99	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.22)	ParamViolation	-0.61	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	-0.28	#s cannot switch flight mode . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.65	#s turn on " multiple flight modes " to enable atti and sport modes . #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	0.99	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.18)	SoftwareFault	-1.05	#s no image #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.13	#s please retry #/s

SoftwareFault	SoftwareFault (0.18)	SoftwareFault	0.99	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.18)	SoftwareFault	-1.66	#s subject too large #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.44	#s move away and retry #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.40	#s color display in the liveview has been enhanced . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.01	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.50	#s compass abnormal . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.65	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.89	#s the ground or walls may contain metal . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.26	#s move away from sources of interference before attempting flight . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.08	#s 2 . calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.28	#s compass error #/s

HardwareFault	SoftwareFault (0.16)	SoftwareFault	1.70	#s compass error , calibration required #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.35	#s compass error . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.35	#s compass error . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.30	#s compass disconnected #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.35	#s compass error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	0.89	#s magnetic filed interference . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.87	#s exit p - gps mode #/s
SoftwareFault	HardwareFault (0.16)	HardwareFault	0.56	#s compass initialization failed . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.44	#s restart aircraft #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.38	#s critical low battery . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.42	#s aircraft in auto power off protection . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.96	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.38	#s critical low battery . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.57	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.38	#s critical low battery . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.36	#s return to home or land promptly #/s

HardwareFault	HardwareFault (0.16)	HardwareFault	1.75	#s critically low power . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.32	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.75	#s critically low power . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.07	#s aircraft landing . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.07	#s aircraft landing . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.71	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.66	#s critically low voltage warning . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.24	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.77	#s critically low voltage . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.68	#s aircraft will land #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.82	#s data recorder file index is 15 . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.15	#s data recorder file index is 17 . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.37	#s data recorder file index is 30 . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.41	#s data recorder file index is 45 . #/s
	SurroundingEnvironment			#s data recorder file

Normal	(0.15)	SurroundingEnvironment	-1.41	index is 46 . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.25	#s data recorder file index is 65 . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.96	#s disable sd card read and write protection or change card #/s
CommunicationIssue	CommunicationIssue (0.17)	CommunicationIssue	1.78	#s downlink lost . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	2.61	#s downlink restored (after 0m 2 . 9s) . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.10	#s drone is vibrating #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.44	#s entered cruise control mode . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.45	#s press c1 or c2 to exit #/s
ParamViolation	ParamViolation (0.22)	ParamViolation	1.86	#s excessive attitude angle detected #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	2.03	#s forward obstacle avoidance has stopped working #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.49	#s exit backward sensing system #/s
SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	0.90	#s ambient light is too weak #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.20	#s exited visual avoidance system . #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.33	#s exiting gps mode :

				unknown error #/s #s extra payload detected . #/s
ParamViolation	ParamViolation (0.21)	ParamViolation	1.75	#s flight performance will be affected . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.22	#s fly with caution #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	#s forward obstacle sensing is not functioning . #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	-0.72	#s forward obstacle sensing not responding #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	2.11	#s gimbal motor overloaded . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	2.15	#s check whether gimbal can rotate freely #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.57	#s gimbal pitch limit reached . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	-0.42	#s ground plain . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.30	#s safe to land . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.81	#s high altitude . #/s
ParamViolation	SurroundingEnvironment (0.20)	SurroundingEnvironment	-1.53	#s aircraft braking distance increased and flight time decreased . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.62	#s fly with caution #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	

SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	1.43	#s high wind velocity . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.04	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	1.43	#s high wind velocity . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.04	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	1.43	#s high wind velocity . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.45	#s fly with caution and land in a safe place asap . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.80	#s high - altitude flight #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	#s fly with caution #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.15	#s aircraft braking distance is extended #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.87	#s flight time is shortened . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.54	#s home point updated . #/s
ParamViolation	SoftwareFault (0.18)	SoftwareFault	0.39	#s imu attitude restricted . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.73	#s ensure aircraft is level #/s

SoftwareFault	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.88	#s imu not calibrated . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.06	#s calibrate imu #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.35	#s landing canceled . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.21	#s landing gear function restored #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.33	#s landing gear paused . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.09	#s landing gear raising . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.53	#s home point recorded #/s
Normal	ParamViolation (0.21)	ParamViolation	-1.03	#s live stream video frame rate less than 9hz . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	#s fly with caution #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.50	#s low power . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.23	#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	1.50	#s low power . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.92	#s returning home . #/s
SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	0.89	#s magnetic filed interference . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.23	#s exit p gps mode . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	-0.30	#s yaw error . #/s
				#s manned

SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	1.14	aircraft detected nearby . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	#s fly with caution #/s
ParamViolation	ParamViolation (0.21)	ParamViolation	1.17	#s max altitude approached . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.15	#s wait for the gps satellite signal recovery before ascend #/s
ParamViolation	ParamViolation (0.22)	ParamViolation	1.38	#s max flight altitude reached . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.34	#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.22)	ParamViolation	1.33	#s max flight distance reached . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.26	#s adjust in main controller settings if necessary . #/s
ParamViolation	ParamViolation (0.22)	ParamViolation	1.25	#s maximum flight distance reached . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.14	#s adjust the distance in mc settings if required . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	2.03	#s mobile device cpu fully loaded . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.45	#s related performance will be

SoftwareFault	ParamViolation (0.15)	ParamViolation	-1.99	affected . #/s
				#s mobile device
				version too old to support
				hd image transmission
				and the image transmission mode has been switch to normal mode . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.20	#s motor is blocked . #/s
HardwareFault	HardwareFault (0.16)	HardwareFault	0.45	#s motor stuck . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.95	#s check for objects blocking
				motor or contact dji support for assistance #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.78	#s motors started . #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.83	#s no gps signal . #/s
Normal	HardwareFault (0.16)	HardwareFault	1.04	#s aircraft unable to hover . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	#s fly with caution #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.83	#s no gps signal . #/s
Normal	HardwareFault (0.16)	HardwareFault	-1.35	#s unable to hover . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.53	#s fly with caution #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.39	#s obstacle avoidance disabled . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.01	#s landing gear lowered . #/s

Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.39	#s obstacle avoidance disabled . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.39	#s obstacle avoidance disabled . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.01	#s landing gear lowered . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.35	#s obstacle avoidance has been disabled . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.51	#s precision landing #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.98	#s quickshot has ended #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	0.78	#s recenter gimbal pan #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.66	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	1.24	#s remote controller in high interference environment . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.85	#s manually adjust flight route or return to home #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.06	#s return - to - home altitude : 65ft #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.75	#s return - to - home altitude : 98ft . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.50	#s rth : ascending to rth altitude . #/s
	SurroundingEnvironment			#s rth : heading

Normal	(0.15)	SurroundingEnvironment	1.87	alignment . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.08	#s rth altitude : 65ft . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.97	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.17)	CommunicationIssue	0.96	#s signal lost . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.87	#s aircraft returning to home point #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.06	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.21)	SurroundingEnvironment	1.66	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	2.07	#s aircraft unable to return to home automatically . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.71	#s lower altitude immediately and return to home manually #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.49	#s switched to s (sport) - mode . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.50	#s switched to t (tripod) - mode . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.33	#s take off in p - mode #/s
SoftwareFault	HardwareFault (0.16)	HardwareFault	0.15	#s vision sensor error . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.72	#s contact dji support for assistance #/s #s vision

Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-2.07	systems and obstacle avoidance disabled #/s #s waypoint
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.82	mission paused #/s #s weak gps
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.38	signal . #/s #s aircraft is in attitude
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.60	mode and hovering may be unstable . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-1.22	#s fly with caution . #/s
CommunicationIssue	CommunicationIssue (0.17)	CommunicationIssue	1.22	#s weak signal . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	1.18	#s adjust antennas #/s #s your aircraft is
RegulationViolation	RegulationViolation (0.19)	RegulationViolation	2.65	flying in an altitude zone (nnn) . #/s
Normal	SurroundingEnvironment (0.15)	SurroundingEnvironment	-0.76	#s please fly with caution #/s