

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	Normal (0.96)	Normal	-0.07	#s a <span style="background-color: #d9ead3;"></span> passenger <span style="background-color: #d9ead3;"></span> aircraft is <span style="background-color: #d9ead3;"></span> nearby . #/s <span style="background-color: #d9ead3;"></span>
				#s fly <span style="background-color: #d9ead3;"></span> with <span style="background-color: #d9ead3;"></span> caution #/s <span style="background-color: #d9ead3;"></span>
				#s account <span style="background-color: #d9ead3;"></span> not <span style="background-color: #d9ead3;"></span> logged in <span style="background-color: #d9ead3;"></span> . #/s <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.96)	Normal	-0.86	#s flight <span style="background-color: #d9ead3;"></span> altitude and <span style="background-color: #d9ead3;"></span> distance <span style="background-color: #d9ead3;"></span> restricted to <span style="background-color: #d9ead3;"></span> nnn and nnn . <span style="background-color: #d9ead3;"></span> #/s <span style="background-color: #d9ead3;"></span>
				#s check and <span style="background-color: #d9ead3;"></span> log in #/s <span style="background-color: #d9ead3;"></span>
				#s <span style="background-color: #d9ead3;"></span> activetrack <span style="background-color: #d9ead3;"></span> flight paused <span style="background-color: #d9ead3;"></span> #/s <span style="background-color: #d9ead3;"></span>
ParamViolation	ParamViolation (0.93)	ParamViolation	-0.63	#s aircraft <span style="background-color: #d9ead3;"></span> activetrack <span style="background-color: #d9ead3;"></span> available at <span style="background-color: #d9ead3;"></span> max speed . <span style="background-color: #d9ead3;"></span> #/s <span style="background-color: #d9ead3;"></span>
				#s <span style="background-color: #d9ead3;"></span> obstacle <span style="background-color: #d9ead3;"></span> avoidance is <span style="background-color: #d9ead3;"></span> not available <span style="background-color: #d9ead3;"></span> #/s <span style="background-color: #d9ead3;"></span>
				#s aircraft <span style="background-color: #d9ead3;"></span> activetrack <span style="background-color: #d9ead3;"></span> available at <span style="background-color: #d9ead3;"></span> max speed . <span style="background-color: #d9ead3;"></span> #/s <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.96)	Normal	2.58	#s <span style="background-color: #d9ead3;"></span> when <span style="background-color: #d9ead3;"></span> exceeding <span style="background-color: #d9ead3;"></span> nnn , obstacle <span style="background-color: #d9ead3;"></span> avoidance is <span style="background-color: #d9ead3;"></span> not available <span style="background-color: #d9ead3;"></span> #/s <span style="background-color: #d9ead3;"></span>
				#s aircraft <span style="background-color: #d9ead3;"></span> activetrack <span style="background-color: #d9ead3;"></span> max speed of <span style="background-color: #d9ead3;"></span> nnn and <span style="background-color: #d9ead3;"></span>
				#s aircraft <span style="background-color: #d9ead3;"></span> activetrack <span style="background-color: #d9ead3;"></span> max speed of <span style="background-color: #d9ead3;"></span> nnn and <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.96)	Normal	-0.93	#s aircraft <span style="background-color: #d9ead3;"></span> activetrack <span style="background-color: #d9ead3;"></span> max speed of <span style="background-color: #d9ead3;"></span> nnn and <span style="background-color: #d9ead3;"></span>

HardwareFault	HardwareFault (0.96)	HardwareFault	-0.11	obstacle avoidance functions normally #/s #s aircraft core board overheated #/s
				#s aircraft entered fixed - wing mode . #/s
				#s current flight speed is nnn . #/s
				#s press c2 to exit #/s
				#s aircraft flight control unlocked #/s
RegulationViolation	RegulationViolation (0.85)	RegulationViolation	1.63	#s aircraft in restricted zones . #/s
Normal	Normal (0.96)	Normal	1.78	#s check map to find recommended zones #/s
Normal	Normal (0.96)	Normal	3.26	#s aircraft is in attitude mode , so that it will not hover . #/s
Normal	Normal (0.96)	Normal	0.94	#s please fly with caution . #/s
Normal	Normal (0.96)	Normal	2.01	#s aircraft is in tripod mode . #/s
Normal	Normal (0.96)	Normal	2.18	#s exit this mode and try again #/s
Normal	Normal (0.96)	Normal	2.38	#s aircraft is returning to the starting point #/s
ParamViolation	ParamViolation (0.93)	ParamViolation	1.58	#s aircraft out of range #/s

				#s
RegulationViolation	RegulationViolation (0.85)	RegulationViolation	-1.49	approaching a no - fly zone . #/s
Normal	Normal (0.96)	Normal	2.03	#s rth may be affected . #/s
Normal	Normal (0.96)	Normal	-0.86	#s fly with caution #/s
Normal	Normal (0.96)	Normal	-0.07	#s arrived at start point . #/s
Normal	Normal (0.96)	Normal	1.17	#s starting waypoint mission #/s
Normal	Normal (0.96)	Normal	-1.59	#s auto landing initiated #/s
Normal	Normal (0.96)	Normal	1.82	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	2.03	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.72	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.38	#s battery error . #/s
Normal	Normal (0.96)	Normal	1.41	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.42	#s battery power low . #/s
Normal	Normal (0.96)	Normal	2.04	#s check battery status and charge or warm up battery #/s
HardwareFault	ParamViolation (0.61)	ParamViolation	0.37	#s cache space full #/s

SurroundingEnvironment	SoftwareFault (0.95)	SoftwareFault	0.61	#s calibration subject is too close . #/s  #s recalibrate using a subject that is farther away #/s
Normal	Normal (0.96)	Normal	-1.63	#s camera busy , cannot enter playback #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.38	#s cannot enable intelligent flight mode #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	1.81	#s low battery #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.04	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	-0.47	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.93)	ParamViolation	-1.54	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	1.56	#s cannot switch flight mode . #/s  #s turn on " multiple flight modes " to enable atti and sport modes . #/s
Normal	Normal (0.96)	Normal	2.81	#s cannot track subject #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	1.53	#s no image #/s
SurroundingEnvironment	SoftwareFault (0.95)	SoftwareFault	-0.12	#s please retry #/s
Normal	Normal (0.96)	Normal	1.03	#s cannot

SoftwareFault	SoftwareFault (0.95)	SoftwareFault	1.53	track subject #/s
SurroundingEnvironment	SoftwareFault (0.95)	SoftwareFault	1.07	#s subject too large #/s
Normal	Normal (0.96)	Normal	1.81	#s move away and retry #/s
Normal	Normal (0.96)	Normal	2.70	#s color display in the liveview has been enhanced . #/s
Normal	Normal (0.96)	Normal	3.07	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.23	#s compass abnormal . #/s
Normal	Normal (0.96)	Normal	3.39	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	Normal (0.96)	Normal	2.16	#s the ground or walls may contain metal . #/s
Normal	Normal (0.96)	Normal	2.76	#s move away from sources of interference before attempting flight . #/s
Normal	Normal (0.96)	Normal	2.24	#s 2 . calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.22	#s compass error #/s #s compass

HardwareFault	HardwareFault (0.96)	HardwareFault	1.50	error , calibration required #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.87	#s compass error . #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.87	#s compass error . #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.68	#s compass disconnected #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.87	#s compass error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.95)	SurroundingEnvironment	1.47	#s magnetic filed interference . #/s
Normal	Normal (0.96)	Normal	1.77	#s exit p - gps mode #/s
SoftwareFault	HardwareFault (0.96)	HardwareFault	-0.21	#s compass initialization failed . #/s
Normal	Normal (0.96)	Normal	-1.18	#s restart aircraft #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.41	#s critical low battery . #/s
Normal	Normal (0.96)	Normal	2.10	#s aircraft in auto power off protection . #/s
Normal	Normal (0.96)	Normal	1.83	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.41	#s critical low battery . #/s
Normal	Normal (0.96)	Normal	0.36	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.41	#s critical low battery . #/s
Normal	Normal (0.96)	Normal	1.39	#s return to home or land promptly #/s
				#s critically

HardwareFault	HardwareFault (0.96)	HardwareFault	1.63	low power . #/s
Normal	Normal (0.96)	Normal	0.47	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.63	#s critically low power . #/s
Normal	Normal (0.96)	Normal	1.36	#s aircraft landing . #/s
Normal	Normal (0.96)	Normal	1.36	#s aircraft landing . #/s
Normal	Normal (0.96)	Normal	3.24	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.67	#s critically low voltage warning . #/s
Normal	Normal (0.69)	Normal	-1.78	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	-1.59	#s critically low voltage . #/s
Normal	Normal (0.96)	Normal	0.88	#s aircraft will land #/s
Normal	Normal (0.96)	Normal	2.07	#s data recorder file index is 15 . #/s
Normal	Normal (0.96)	Normal	2.08	#s data recorder file index is 17 . #/s
Normal	Normal (0.96)	Normal	2.12	#s data recorder file index is 30 . #/s
Normal	Normal (0.96)	Normal	2.27	#s data recorder file index is 45 . #/s
Normal	Normal (0.96)	Normal	2.12	#s data recorder file index is 46 .

				#/s
Normal	Normal (0.96)	Normal	2.21	#s data recorder file index is 65 . #/s
Normal	Normal (0.96)	Normal	-0.47	#s disable sd card read and write protection or change card #/s
CommunicationIssue	CommunicationIssue (0.89)	CommunicationIssue	0.14	#s downlink lost . #/s
Normal	Normal (0.96)	Normal	2.65	#s downlink restored ( after 0m 2 . 9s ) . #/s
Normal	Normal (0.96)	Normal	-0.13	#s drone is vibrating #/s
Normal	Normal (0.96)	Normal	1.86	#s entered cruise control mode . #/s
Normal	Normal (0.96)	Normal	2.19	#s press c1 or c2 to exit #/s
ParamViolation	ParamViolation (0.93)	ParamViolation	0.96	#s excessive attitude angle detected #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	0.40	#s forward obstacle avoidance has stopped working #/s
Normal	Normal (0.96)	Normal	1.20	#s exit backward sensing system #/s
SurroundingEnvironment	SurroundingEnvironment (0.95)	SurroundingEnvironment	0.45	#s ambient light is too weak #/s
Normal	Normal (0.96)	Normal	1.45	#s exited visual avoidance system . #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	0.04	#s exiting gps mode : unknown



ParamViolation	ParamViolation (0.93)	ParamViolation	1.58	error #/s
				#s extra payload detected . #/s
				#s flight performance will be affected . #/s
Normal	Normal (0.96)	Normal	1.42	
Normal	Normal (0.96)	Normal	-0.86	#s fly with caution #/s
				#s forward obstacle sensing is not functioning . #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	1.31	
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	1.95	#s forward obstacle sensing not responding #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.12	#s gimbal motor overloaded . #/s
Normal	Normal (0.96)	Normal	2.56	#s check whether gimbal can rotate freely #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.72	#s gimbal pitch limit reached . #/s
Normal	Normal (0.96)	Normal	-1.24	#s ground plain . #/s
Normal	Normal (0.96)	Normal	0.46	#s safe to land . #/s
ParamViolation	HardwareFault (0.72)	HardwareFault	1.72	#s high altitude . #/s
				#s aircraft braking distance increased and flight time decreased . #/s
Normal	Normal (0.96)	Normal	2.65	
Normal	Normal (0.96)	Normal	-0.86	#s fly with caution #/s
SurroundingEnvironment				#s high wind

SurroundingEnvironment	(0.95)	SurroundingEnvironment	-0.26	velocity . #/s
Normal	Normal (0.96)	Normal	3.35	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.95)	SurroundingEnvironment	-0.26	#s high wind velocity . #/s
Normal	Normal (0.96)	Normal	3.35	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.95)	SurroundingEnvironment	-0.26	#s high wind velocity . #/s
Normal	Normal (0.96)	Normal	2.93	#s fly with caution and land in a safe place asap . #/s
Normal	Normal (0.96)	Normal	0.45	#s high - altitude flight #/s
Normal	Normal (0.96)	Normal	-0.86	#s fly with caution #/s
Normal	Normal (0.96)	Normal	1.47	#s aircraft braking distance is extended #/s
Normal	Normal (0.96)	Normal	0.43	#s flight time is shortened . #/s
Normal	Normal (0.96)	Normal	0.75	#s home point updated . #/s
ParamViolation	SoftwareFault (0.94)	SoftwareFault	-1.60	#s imu attitude restricted . #/s
Normal	Normal (0.96)	Normal	1.45	#s ensure aircraft is level #/s
SoftwareFault	Normal (0.96)	Normal	-1.85	#s imu not

				calibrated . #/s
Normal	Normal (0.96)	Normal	1.83	#s calibrate imu #/s
Normal	Normal (0.96)	Normal	0.51	#s landing canceled . #/s
Normal	Normal (0.96)	Normal	1.47	#s landing gear function restored #/s
Normal	Normal (0.96)	Normal	0.65	#s landing gear paused . #/s
Normal	Normal (0.96)	Normal	0.71	#s landing gear raising . #/s
Normal	Normal (0.96)	Normal	-1.33	#s home point recorded #/s
Normal	Normal (0.96)	Normal	-2.16	#s live stream video frame rate less than 9hz . #/s
Normal	Normal (0.96)	Normal	-0.86	#s fly with caution #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.78	#s low power . #/s
Normal	Normal (0.96)	Normal	2.42	#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	0.78	#s low power . #/s
Normal	Normal (0.96)	Normal	1.36	#s returning home . #/s
SurroundingEnvironment	SurroundingEnvironment (0.95)	SurroundingEnvironment	1.47	#s magnetic filed interference . #/s
Normal	Normal (0.96)	Normal	0.75	#s exit p - gps mode . #/s
HardwareFault	HardwareFault (0.96)	HardwareFault	1.50	#s yaw error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	1.18	#s manned aircraft detected

Normal	Normal (0.96)	Normal	-0.86	nearby . #/s
				#s fly with caution #/s
ParamViolation	ParamViolation (0.90)	ParamViolation	0.95	#s max altitude approached . #/s
				#s wait for the gps satellite signal recovery before ascend #/s
Normal	Normal (0.96)	Normal	2.56	#s max flight altitude reached . #/s
				#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.93)	ParamViolation	1.57	#s max flight distance reached . #/s
				#s adjust in main controller settings if necessary . #/s
Normal	Normal (0.96)	Normal	2.36	#s maximum flight distance reached . #/s
				#s adjust the distance in mc settings if required . #/s
ParamViolation	ParamViolation (0.93)	ParamViolation	-1.08	#s mobile device cpu fully loaded . #/s
				#s related performance will be affected . #/s
Normal	Normal (0.96)	Normal	2.46	#s mobile
ParamViolation	ParamViolation (0.93)	ParamViolation	1.39	
Normal	Normal (0.96)	Normal	2.76	
HardwareFault	HardwareFault (0.96)	HardwareFault	1.19	
Normal	Normal (0.96)	Normal	1.48	

SoftwareFault	Normal (0.94)	Normal	-2.42	device
				version too
				old to support
				hd image
				transmission
Normal	Normal (0.96)	Normal	0.93	and the
				image
				transmission
				mode has
				been switch
HardwareFault	HardwareFault (0.96)	HardwareFault	1.38	to normal
				mode . #/s
				#s motor is
				blocked . #/s
				#s motor
Normal	Normal (0.96)	Normal	2.92	stuck . #/s
				#s check for
				objects
				blocking
				motor or
Normal	Normal (0.96)	Normal	1.16	contact dji
				support for
				assistance
				#/s
				#s motors
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	1.27	started . #/s
				#s no gps
				signal . #/s
				#s aircraft
				unable to
Normal	Normal (0.96)	Normal	-0.86	hover . #/s
				#s fly with
				caution #/s
				#s no gps
				signal . #/s
Normal	Normal (0.96)	Normal	-0.79	#s unable to
				hover . #/s
				#s fly with
				caution #/s
				#s obstacle
Normal	Normal (0.96)	Normal	1.45	avoidance
				disabled . #/s
				#s landing
				gear lowered
				. #/s
Normal	Normal (0.96)	Normal	0.92	#s obstacle
				avoidance
				disabled . #/s

Normal	Normal (0.96)	Normal	0.92	#s obstacle avoidance disabled . #/s
Normal	Normal (0.96)	Normal	1.45	#s landing gear lowered . #/s
Normal	Normal (0.96)	Normal	0.56	#s obstacle avoidance has been disabled . #/s
Normal	Normal (0.96)	Normal	1.15	#s precision landing #/s
Normal	Normal (0.96)	Normal	0.66	#s quickshot has ended #/s
Normal	Normal (0.96)	Normal	1.27	#s recenter gimbal pan #/s
Normal	Normal (0.96)	Normal	1.93	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.95)	SurroundingEnvironment	2.10	#s remote controller in high interference environment . #/s
Normal	Normal (0.96)	Normal	2.40	#s manually adjust flight route or return to home #/s
Normal	Normal (0.96)	Normal	2.73	#s return - to - home altitude : 65ft #/s
Normal	Normal (0.96)	Normal	2.69	#s return - to - home altitude : 98ft . #/s
Normal	Normal (0.96)	Normal	2.28	#s rth : ascending to rth altitude . #/s
Normal	Normal (0.96)	Normal	1.33	#s rth : heading alignment . #/s

Normal	Normal (0.96)	Normal	1.60	#s rth altitude : 65ft . #/s
Normal	Normal (0.96)	Normal	1.90	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.89)	CommunicationIssue	0.90	#s signal lost . #/s
Normal	Normal (0.96)	Normal	1.59	#s aircraft returning to home point #/s
Normal	Normal (0.96)	Normal	0.69	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.95)	SurroundingEnvironment	1.47	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	0.95	#s aircraft unable to return to home automatically . #/s
Normal	Normal (0.96)	Normal	1.69	#s lower altitude immediately and return to home manually #/s
Normal	Normal (0.96)	Normal	2.62	#s switched to s ( sport ) - mode . #/s
Normal	Normal (0.96)	Normal	2.49	#s switched to t ( tripod ) - mode . #/s
Normal	Normal (0.96)	Normal	2.20	#s take off in p - mode #/s
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	2.03	#s vision sensor error . #/s
Normal	Normal (0.96)	Normal	-1.41	#s contact dji support for assistance #/s
Normal	Normal (0.96)	Normal	1.88	#s vision systems and obstacle avoidance

Normal	Normal (0.96)	Normal	1.04	disabled #/s
				#s waypoint
				mission
SoftwareFault	SoftwareFault (0.95)	SoftwareFault	1.56	paused #/s
				#s weak gps
				signal . #/s
Normal	Normal (0.96)	Normal	2.62	#s aircraft is
				in attitude
				mode and
Normal	Normal (0.96)	Normal	-0.05	hovering may
				be unstable .
				#/s
CommunicationIssue	CommunicationIssue (0.89)	CommunicationIssue	0.98	#s fly with
				caution . #/s
				#s weak
Normal	Normal (0.96)	Normal	0.57	signal . #/s
				#s adjust
				antennas #/s
RegulationViolation	RegulationViolation (0.85)	RegulationViolation	0.80	#s your
				aircraft is
				flying in an
Normal	Normal (0.96)	Normal	-0.68	altitude zone
				( nnn ) . #/s
				#s please fly
Normal	Normal (0.96)	Normal	-0.68	with caution
				#/s