

Legend: ■ Negative □ Neutral ■ Positive

| True Label | Predicted Label | Attribution Label | Attribution Score | Word Importance |
|------------------------|------------------------------|-------------------|-------------------|---|
| SurroundingEnvironment | Normal (1.00) | Normal | 1.83 | [CLS] a passenger aircraft is nearby . [SEP] |
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.92) | Normal | -1.17 | [CLS] account not logged in . [SEP] |
| ParamViolation | ParamViolation (0.97) | ParamViolation | 2.25 | [CLS] flight altitude and distance restricted to nnn and nnn . [SEP] |
| Normal | Normal (1.00) | Normal | 1.23 | [CLS] check and log in [SEP] |
| Normal | Normal (1.00) | Normal | 1.27 | [CLS] activetrack flight paused [SEP] |
| Normal | Normal (1.00) | Normal | 1.33 | [CLS] aircraft activetrack available at max speed . [SEP] |
| Normal | Normal (1.00) | Normal | 0.13 | [CLS] obstacle avoidance is not available [SEP] |
| Normal | Normal (1.00) | Normal | 1.33 | [CLS] aircraft activetrack available at max speed . [SEP] |
| Normal | Normal (1.00) | Normal | 0.10 | [CLS] when exceeding nnn , obstacle avoidance is not available [SEP] |
| | | | | [CLS] aircraft |

| | | | | |
|---------------------|-----------------------------------|---------------------|--------------|---|
| Normal | Normal (1.00) | Normal | 0.11 | activetrack max speed of nnn and obstacle avoidance functions normally [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 2.56 | [CLS] aircraft core board overheated [SEP] |
| Normal | Normal (1.00) | Normal | 0.82 | [CLS] aircraft entered fixed - wing mode . [SEP] |
| Normal | Normal (1.00) | Normal | -1.85 | [CLS] current flight speed is nnn . [SEP] |
| Normal | Normal (1.00) | Normal | 1.02 | [CLS] press c2 to exit [SEP] |
| Normal | Normal (1.00) | Normal | 1.04 | [CLS] aircraft flight control unlocked [SEP] |
| RegulationViolation | RegulationViolation (0.74) | RegulationViolation | 1.91 | [CLS] aircraft in restricted zones . [SEP] |
| Normal | Normal (1.00) | Normal | 1.17 | [CLS] check map to find recommended zones [SEP] |
| Normal | Normal (1.00) | Normal | 0.41 | [CLS] aircraft is in attitude mode , so that it will not hover . [SEP] |
| Normal | Normal (1.00) | Normal | 1.16 | [CLS] please fly with caution . [SEP] |
| Normal | Normal (1.00) | Normal | 0.73 | [CLS] aircraft is in tripod mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.46 | [CLS] exit this mode and try again |

| | | | | |
|---------------------|-----------------------------------|----------------------------|-------------|--|
| | | | | [SEP] |
| Normal | Normal (1.00) | Normal | 1.21 | [CLS] aircraft is returning to the starting point [SEP] |
| ParamViolation | ParamViolation (0.97) | ParamViolation | 2.02 | [CLS] aircraft out of range [SEP] [CLS] |
| RegulationViolation | RegulationViolation (0.67) | RegulationViolation | 2.14 | approaching a no - fly zone . [SEP] [CLS] rth may |
| Normal | Normal (1.00) | Normal | 0.63 | be affected . [SEP] |
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] fly with caution [SEP] [CLS] arrived |
| Normal | Normal (1.00) | Normal | 0.97 | at start point . [SEP] [CLS] starting |
| Normal | Normal (1.00) | Normal | 1.36 | waypoint mission [SEP] [CLS] auto |
| Normal | Normal (1.00) | Normal | 1.38 | landing initiated [SEP] [CLS] auxiliary |
| Normal | Normal (1.00) | Normal | 0.74 | bottom light turned off [SEP] [CLS] backward obstacle |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.92 | sensing is not functioning . [SEP] [CLS] battery cell broken , |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.99 | please replace the battery [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.49 | [CLS] battery error . [SEP] [CLS] aircraft returning to |

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|-------------------------------|----------------------------------|-----------------------|--------------|---|
| Normal | Normal (1.00) | Normal | 1.19 | home automatically [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.73 | [CLS] battery power low . [SEP] |
| Normal | Normal (1.00) | Normal | 1.27 | [CLS] check battery status and charge or warm up battery [SEP] |
| HardwareFault | Normal (0.94) | Normal | 1.88 | [CLS] cache space full [SEP] |
| SurroundingEnvironment | SoftwareFault (0.99) | SoftwareFault | -2.03 | [CLS] calibration subject is too close . [SEP] |
| Normal | Normal (1.00) | Normal | 0.26 | [CLS] recalibrate using a subject that is farther away [SEP] |
| HardwareFault | HardwareFault (0.98) | HardwareFault | 2.05 | [CLS] camera busy , cannot enter playback [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.04 | [CLS] cannot enable intelligent flight mode [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.67 | [CLS] low battery [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.42 | [CLS] cannot start return to home due to weak gps signal [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.22 | [CLS] cannot start self - timer . [SEP] |
| SoftwareFault | ParamViolation (0.86) | ParamViolation | 0.20 | [CLS] exposure time is too long [SEP] |

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|-------------------------------|-----------------------------|----------------------|--------------|---|
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.05 | [CLS] cannot switch flight mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.33 | [CLS] turn on " multiple flight modes " to enable atti and sport modes . [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.24 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.99) | SoftwareFault | -1.34 | [CLS] no image [SEP] |
| Normal | Normal (1.00) | Normal | 0.99 | [CLS] please retry [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.24 | [CLS] cannot track subject [SEP] |
| SurroundingEnvironment | SoftwareFault (0.99) | SoftwareFault | -1.64 | [CLS] subject too large [SEP] |
| Normal | Normal (1.00) | Normal | 1.18 | [CLS] move away and retry [SEP] |
| Normal | Normal (1.00) | Normal | 1.17 | [CLS] color display in the liveview has been enhanced . [SEP] |
| Normal | Normal (1.00) | Normal | 1.12 | [CLS] videos and photos will still be shot in d - log mode [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.62 | [CLS] compass abnormal . [SEP] |
| Normal | Normal (1.00) | Normal | 0.08 | [CLS] solution : 1 . ensure there are no magnets or metal objects near the aircraft . |

[SEP]

| | | | | |
|------------------------|--------------------------------------|------------------------|-------------|---|
| Normal | Normal (1.00) | Normal | 0.19 | [CLS] the ground or walls may contain metal . [SEP] |
| Normal | Normal (1.00) | Normal | 0.69 | [CLS] move away from sources of interference before attempting flight . [SEP] |
| Normal | Normal (1.00) | Normal | 0.67 | [CLS] 2 . calibrate compass before takeoff [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.50 | [CLS] compass error [SEP] |
| HardwareFault | HardwareFault (0.74) | HardwareFault | 1.44 | [CLS] compass error , calibration required [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.58 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.58 | [CLS] compass error . [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.54 | [CLS] compass disconnected [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.58 | [CLS] compass error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.54 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | 1.12 | [CLS] exit p - gps mode [SEP] |

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|----------------------|-----------------------------|----------------------|-------------|--|
| SoftwareFault | HardwareFault (0.97) | HardwareFault | 0.14 | [CLS] compass initialization failed. [SEP] |
| Normal | Normal (1.00) | Normal | 0.77 | [CLS] restart aircraft [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.89 | [CLS] critical low battery. [SEP] |
| Normal | Normal (1.00) | Normal | 1.10 | [CLS] aircraft in auto power off protection . [SEP] |
| Normal | Normal (1.00) | Normal | 1.14 | [CLS] forced landing in progress [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.89 | [CLS] critical low battery. [SEP] |
| Normal | Normal (1.00) | Normal | 0.86 | [CLS] aircraft landing automatically [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.89 | [CLS] critical low battery. [SEP] |
| Normal | Normal (1.00) | Normal | 1.23 | [CLS] return to home or land promptly [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 2.03 | [CLS] critically low power. [SEP] |
| Normal | Normal (1.00) | Normal | 1.23 | [CLS] aircraft is landing [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 2.03 | [CLS] critically low power. [SEP] |
| Normal | Normal (1.00) | Normal | 0.82 | [CLS] aircraft landing. [SEP] |
| Normal | Normal (1.00) | Normal | 0.82 | [CLS] aircraft landing. [SEP] |

| | | | | |
|----------------------|-----------------------------|----------------------|-------------|--|
| Normal | Normal (1.00) | Normal | 0.70 | the speed of descent and use sticks to avoid obstacles [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 2.09 | [CLS] critically low voltage warning . [SEP] |
| Normal | Normal (1.00) | Normal | 0.59 | [CLS] aircraft will be forced to land [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 2.02 | [CLS] critically low voltage . [SEP] |
| Normal | Normal (1.00) | Normal | 1.07 | [CLS] aircraft will land [SEP] |
| Normal | Normal (1.00) | Normal | 0.78 | [CLS] data recorder file index is 15 . [SEP] |
| Normal | Normal (1.00) | Normal | 0.83 | [CLS] data recorder file index is 17 . [SEP] |
| Normal | Normal (1.00) | Normal | 0.83 | [CLS] data recorder file index is 30 . [SEP] |
| Normal | Normal (1.00) | Normal | 0.75 | [CLS] data recorder file index is 45 . [SEP] |
| Normal | Normal (1.00) | Normal | 0.78 | [CLS] data recorder file index is 46 . [SEP] |
| Normal | Normal (1.00) | Normal | 0.79 | [CLS] disable sd card read and write |
| Normal | Normal (1.00) | Normal | 1.09 | |

| | | | | |
|------------------------|----------------------------------|------------------------|-------|---|
| | | | | protection or change card [SEP] |
| CommunicationIssue | CommunicationIssue (0.86) | CommunicationIssue | 1.71 | [CLS] downlink lost . [SEP] |
| Normal | Normal (1.00) | Normal | 0.80 | [CLS] downlink restored ([SEP] after 0m 2 9s) . [SEP] |
| Normal | HardwareFault (0.97) | HardwareFault | -1.81 | [CLS] drone is vibrating [SEP] |
| Normal | Normal (1.00) | Normal | 1.14 | [CLS] entered cruise control mode . [SEP] |
| Normal | Normal (1.00) | Normal | 0.68 | [CLS] press c1 or c2 to exit [SEP] |
| ParamViolation | ParamViolation (0.96) | ParamViolation | 1.97 | [CLS] excessive attitude angle detected [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.73 | [CLS] forward obstacle avoidance has stopped working [SEP] |
| Normal | Normal (1.00) | Normal | 0.73 | [CLS] exit backward sensing system [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.95 | [CLS] ambient light is too weak [SEP] |
| Normal | Normal (1.00) | Normal | 0.86 | [CLS] exited visual [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.16 | [CLS] exiting gps mode : unknown error [SEP] |

| | | | | |
|-----------------------|----------------------------------|-----------------------|--------------|---|
| ParamViolation | ParamViolation (0.97) | ParamViolation | 1.80 | [CLS] extra payload detected . [SEP] |
| Normal | Normal (1.00) | Normal | 0.75 | [CLS] flight performance will be affected . [SEP] |
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.78 | [CLS] forward obstacle sensing is not functioning . [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.80 | [CLS] forward obstacle sensing not responding [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 2.14 | [CLS] gimbal motor overloaded . [SEP] |
| Normal | Normal (1.00) | Normal | 0.90 | [CLS] check whether gimbal can rotate freely [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.93 | [CLS] gimbal pitch limit reached . [SEP] |
| Normal | Normal (1.00) | Normal | 0.24 | [CLS] ground plain . [SEP] |
| Normal | Normal (1.00) | Normal | 0.87 | [CLS] safe to land . [SEP] |
| ParamViolation | ParamViolation (0.96) | ParamViolation | 1.66 | [CLS] high altitude . [SEP] |
| Normal | ParamViolation (0.95) | ParamViolation | -2.52 | [CLS] aircraft braking distance increased and flight time decreased . [SEP] |

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|------------------------|--------------------------------------|------------------------|--------------|--|
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] fly with caution [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.74 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 0.83 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.74 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 0.83 | [CLS] ensure the aircraft remains within your line of sight and fly with caution . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.74 | [CLS] high wind velocity . [SEP] |
| Normal | Normal (1.00) | Normal | 1.01 | [CLS] high land in a safe place asap . [SEP] |
| Normal | ParamViolation (0.97) | ParamViolation | -1.92 | [CLS] high - altitude flight [SEP] |
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] fly with caution [SEP] |
| Normal | Normal (0.48) | Normal | -1.08 | [CLS] aircraft braking distance is extended [SEP] |
| Normal | ParamViolation (0.96) | ParamViolation | -1.91 | [CLS] flight time is shortened . [SEP] |
| Normal | Normal (1.00) | Normal | 0.87 | [CLS] home |

| | | | | |
|----------------|----------------------------------|-----------------------|--------------|----------------|
| | | | | point updated |
| | | | | . [SEP] |
| | | | | [CLS] imu |
| | | | | attitude |
| | | | | restricted . |
| | | | | [SEP] |
| | | | | [CLS] ensure |
| ParamViolation | ParamViolation (0.76) | ParamViolation | 1.54 | aircraft is |
| Normal | Normal (1.00) | Normal | 0.99 | level [SEP] |
| SoftwareFault | Normal (1.00) | Normal | -0.02 | [CLS] imu not |
| Normal | Normal (1.00) | Normal | 0.58 | calibrated . |
| Normal | Normal (1.00) | Normal | -1.13 | [SEP] |
| Normal | Normal (1.00) | Normal | 1.08 | [CLS] |
| Normal | Normal (1.00) | Normal | 0.84 | calibrate imu |
| Normal | Normal (1.00) | Normal | 1.14 | [SEP] |
| Normal | Normal (1.00) | Normal | 1.19 | [CLS] landing |
| Normal | Normal (1.00) | Normal | -1.41 | canceled . |
| Normal | Normal (1.00) | Normal | 1.36 | [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.74 | [CLS] landing |
| Normal | Normal (1.00) | Normal | 1.10 | gear function |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.74 | restored |
| | | | | [SEP] |
| | | | | [CLS] landing |
| | | | | gear paused . |
| | | | | [SEP] |
| | | | | [CLS] landing |
| | | | | gear raising . |
| | | | | [SEP] |
| | | | | [CLS] home |
| | | | | point |
| | | | | recorded |
| | | | | [SEP] |
| | | | | [CLS] live |
| | | | | stream video |
| | | | | frame rate |
| | | | | less than 9hz |
| | | | | . [SEP] |
| | | | | [CLS] fly with |
| | | | | caution [SEP] |
| | | | | [CLS] low |
| | | | | power . [SEP] |
| | | | | [CLS] aircraft |
| | | | | is returning |
| | | | | to the home |
| | | | | point . [SEP] |
| | | | | [CLS] low |
| | | | | power . [SEP] |

| | | | | |
|-------------------------------|--------------------------------------|-------------------------------|-------------|--|
| Normal | Normal (1.00) | Normal | 1.00 | [CLS] returning home . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.54 | [CLS] magnetic filed interference . [SEP] |
| Normal | Normal (1.00) | Normal | 0.89 | [CLS] exit p - gps mode . [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 2.09 | [CLS] yaw error . [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.79) | SurroundingEnvironment | 0.99 | [CLS] manned aircraft detected nearby . [SEP] |
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] fly with caution [SEP] |
| ParamViolation | ParamViolation (0.94) | ParamViolation | 1.18 | [CLS] max altitude approached . [SEP] |
| Normal | Normal (1.00) | Normal | 0.32 | [CLS] wait for the gps satellite |
| ParamViolation | ParamViolation (0.97) | ParamViolation | 2.02 | signal recovery before ascend [SEP] |
| Normal | Normal (1.00) | Normal | 1.08 | [CLS] max flight altitude reached . [SEP] |
| ParamViolation | ParamViolation (0.97) | ParamViolation | 2.01 | [CLS] adjust in main controller settings if necessary [SEP] |
| | | | | [CLS] max flight distance reached . [SEP] |
| | | | | [CLS] adjust |

| | | | | |
|-----------------------|------------------------------|-----------------------|-------------|---|
| Normal | Normal (1.00) | Normal | 0.93 | in main controller settings if necessary . [SEP] |
| ParamViolation | ParamViolation (0.97) | ParamViolation | 2.08 | [CLS] maximum flight distance reached . [SEP] |
| Normal | Normal (1.00) | Normal | 0.92 | [CLS] adjust the distance in mc settings if required . [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 2.22 | [CLS] mobile device cpu fully loaded . [SEP] |
| Normal | Normal (1.00) | Normal | 0.60 | [CLS] related performance will be affected . [SEP] |
| SoftwareFault | Normal (0.92) | Normal | 0.42 | [CLS] mobile device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . [SEP] |
| Normal | Normal (1.00) | Normal | 0.39 | [CLS] motor is blocked . [SEP] |
| HardwareFault | HardwareFault (0.99) | HardwareFault | 1.65 | [CLS] motor stuck . [SEP] |
| Normal | Normal (1.00) | Normal | 0.93 | [CLS] check for objects blocking motor or contact dji support for |

| | | | | |
|----------------------|-----------------------------|----------------------|--------------|--|
| | | | | assistance |
| | | | | [SEP] |
| Normal | HardwareFault (0.99) | HardwareFault | -1.87 | [CLS] motors started . [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.64 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (0.99) | HardwareFault | -1.25 | [CLS] aircraft unable to hover . [SEP] |
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] fly with caution [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.64 | [CLS] no gps signal . [SEP] |
| Normal | HardwareFault (0.99) | HardwareFault | -1.39 | [CLS] unable to hover . [SEP] |
| Normal | Normal (1.00) | Normal | 1.36 | [CLS] fly with caution [SEP] |
| Normal | Normal (1.00) | Normal | 0.48 | [CLS] obstacle avoidance disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 0.99 | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (1.00) | Normal | 0.48 | [CLS] obstacle avoidance disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 0.48 | [CLS] obstacle avoidance disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 0.99 | [CLS] landing gear lowered . [SEP] |
| Normal | Normal (1.00) | Normal | 0.49 | [CLS] obstacle avoidance has been disabled . [SEP] |
| Normal | Normal (1.00) | Normal | 1.80 | [CLS] precision |

| | | | | |
|------------------------|--------------------------------------|------------------------|-------------|---|
| Normal | Normal (1.00) | Normal | 1.11 | landing [SEP] [CLS] quickshot has ended [SEP] |
| Normal | Normal (1.00) | Normal | 0.94 | [CLS] recenter gimbal pan [SEP] |
| Normal | Normal (1.00) | Normal | 0.86 | [CLS] rectifying aircraft position [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.96 | [CLS] remote controller in high interference environment . [SEP] |
| Normal | Normal (1.00) | Normal | 1.50 | [CLS] manually adjust flight route or return to home [SEP] |
| Normal | Normal (1.00) | Normal | 0.81 | [CLS] return - to - home altitude : 65ft [SEP] |
| Normal | Normal (1.00) | Normal | 0.58 | [CLS] return - to - home altitude : 98ft . [SEP] |
| Normal | Normal (1.00) | Normal | 0.91 | [CLS] rth : ascending to rth altitude . [SEP] |
| Normal | Normal (1.00) | Normal | 1.00 | [CLS] rth : heading alignment . [SEP] |
| Normal | Normal (1.00) | Normal | 0.76 | [CLS] rth altitude : 65ft . [SEP] |
| Normal | Normal (1.00) | Normal | 0.57 | [CLS] rth altitude : 98ft . [SEP] |
| CommunicationIssue | CommunicationIssue (0.88) | CommunicationIssue | 1.38 | [CLS] signal |

| | | | | |
|------------------------|--------------------------------------|------------------------|-------------|--|
| Normal | Normal (1.00) | Normal | 1.42 | lost . [SEP] |
| Normal | Normal (1.00) | Normal | 1.38 | [CLS] aircraft returning to home point [SEP] |
| SurroundingEnvironment | SurroundingEnvironment (0.98) | SurroundingEnvironment | 1.66 | [CLS] sprayer turned on [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.29 | [CLS] strong wind warning . [SEP] |
| Normal | Normal (1.00) | Normal | 1.19 | [CLS] aircraft unable to return to home automatically . [SEP] |
| Normal | Normal (1.00) | Normal | 1.01 | [CLS] lower altitude immediately and return to home manually [SEP] |
| Normal | Normal (1.00) | Normal | 0.74 | [CLS] switched to s (sport) - mode . [SEP] |
| Normal | Normal (1.00) | Normal | 1.13 | [CLS] switched to t (tripod) - mode . [SEP] |
| SoftwareFault | HardwareFault (0.96) | HardwareFault | 0.18 | [CLS] take off in p - mode [SEP] |
| Normal | Normal (1.00) | Normal | 0.97 | [CLS] vision sensor error. [SEP] |
| Normal | Normal (1.00) | Normal | 0.44 | [CLS] contact dji support for assistance [SEP] |
| Normal | Normal (1.00) | Normal | 0.44 | [CLS] vision systems and obstacle avoidance disabled [SEP] |

| | | | | |
|---------------------|-----------------------------------|---------------------|-------------|--|
| Normal | Normal (1.00) | Normal | 0.98 | [CLS] waypoint mission paused [SEP] |
| SoftwareFault | SoftwareFault (0.99) | SoftwareFault | 1.72 | [CLS] weak gps signal . [SEP] |
| Normal | Normal (1.00) | Normal | 0.82 | [CLS] aircraft is in attitude mode and hovering may be unstable . [SEP] |
| Normal | Normal (1.00) | Normal | 0.99 | [CLS] fly with caution . [SEP] |
| CommunicationIssue | CommunicationIssue (0.88) | CommunicationIssue | 1.49 | [CLS] weak signal . [SEP] |
| Normal | Normal (1.00) | Normal | 1.03 | [CLS] adjust antennas [SEP] |
| RegulationViolation | RegulationViolation (0.72) | RegulationViolation | 2.71 | [CLS] your aircraft is flying in an altitude zone (nnn) . [SEP] |
| Normal | Normal (1.00) | Normal | 1.32 | [CLS] please fly with caution [SEP] |