

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	Normal (0.99)	Normal	-0.53	#s a <span style="background-color: #d9ead3;"></span>
				passenger <span style="background-color: #d9ead3;"></span>
				aircraft is <span style="background-color: #f4cccc;"></span>
Normal	Normal (0.99)	Normal	-0.40	nearby . #/s <span style="background-color: #d9ead3;"></span>
				#s fly <span style="background-color: #d9ead3;"></span> with <span style="background-color: #d9ead3;"></span>
				caution #/s <span style="background-color: #f4cccc;"></span>
Normal	Normal (0.98)	Normal	1.62	#s account <span style="background-color: #f4cccc;"></span>
				not logged in <span style="background-color: #d9ead3;"></span>
				. #/s <span style="background-color: #d9ead3;"></span>
ParamViolation	ParamViolation (0.87)	ParamViolation	0.09	#s flight <span style="background-color: #d9ead3;"></span>
				altitude and <span style="background-color: #f4cccc;"></span>
				distance <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.99)	Normal	1.83	restricted to <span style="background-color: #d9ead3;"></span>
				nnn and nnn . <span style="background-color: #f4cccc;"></span>
				#/s <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.99)	Normal	0.64	#s check and <span style="background-color: #d9ead3;"></span>
				log in #/s <span style="background-color: #d9ead3;"></span>
				#s <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.99)	Normal	0.94	activetrack <span style="background-color: #d9ead3;"></span>
				flight paused <span style="background-color: #d9ead3;"></span>
				#/s <span style="background-color: #f4cccc;"></span>
Normal	Normal (0.99)	Normal	0.94	#s aircraft <span style="background-color: #f4cccc;"></span>
				activetrack <span style="background-color: #d9ead3;"></span>
				available at <span style="background-color: #f4cccc;"></span>
Normal	Normal (0.98)	Normal	-0.53	max speed . <span style="background-color: #d9ead3;"></span>
				#/s <span style="background-color: #f4cccc;"></span>
				#s obstacle <span style="background-color: #f4cccc;"></span>
Normal	ParamViolation (0.87)	ParamViolation	-1.64	avoidance is <span style="background-color: #f4cccc;"></span>
				not available <span style="background-color: #d9ead3;"></span>
				#/s <span style="background-color: #f4cccc;"></span>
Normal	Normal (0.99)	Normal	0.86	#s aircraft <span style="background-color: #f4cccc;"></span>
				activetrack <span style="background-color: #d9ead3;"></span>
				max speed of <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.99)	Normal	0.86	nnn and <span style="background-color: #d9ead3;"></span>
				#/s <span style="background-color: #f4cccc;"></span>
				#s aircraft <span style="background-color: #d9ead3;"></span>

HardwareFault	HardwareFault (0.95)	HardwareFault	1.63	obstacle avoidance functions normally #/s
				#s aircraft core board overheated #/s
				#s aircraft entered fixed - wing mode . #/s
				#s current flight speed is nnn . #/s
				#s press c2 to exit #/s
Normal	Normal (0.99)	Normal	1.86	#s aircraft flight control unlocked #/s
Normal	Normal (0.99)	Normal	1.95	#s aircraft in restricted zones . #/s
Normal	Normal (0.99)	Normal	0.94	#s check map to find recommended zones #/s
Normal	Normal (0.99)	Normal	1.10	#s aircraft is in attitude mode , so that it will not hover . #/s
RegulationViolation	RegulationViolation (0.62)	RegulationViolation	-0.73	#s please fly with caution . #/s
Normal	Normal (0.99)	Normal	2.17	#s aircraft is in tripod mode . #/s
Normal	Normal (0.99)	Normal	-2.21	#s exit this mode and try again #/s
Normal	Normal (0.99)	Normal	0.49	#s aircraft is returning to the starting point #/s
Normal	Normal (0.99)	Normal	2.30	#s aircraft out of range #/s
Normal	Normal (0.99)	Normal	2.23	
Normal	Normal (0.99)	Normal	-0.14	
ParamViolation	ParamViolation (0.87)	ParamViolation	0.88	

RegulationViolation	RegulationViolation (0.62)	RegulationViolation	2.32	#s approaching a no - fly zone . #/s
Normal	Normal (0.99)	Normal	1.96	#s rth may be affected . #/s
Normal	Normal (0.99)	Normal	-0.40	#s fly with caution #/s
Normal	Normal (0.99)	Normal	1.33	#s arrived at start point . #/s
Normal	Normal (0.99)	Normal	1.58	#s starting waypoint mission #/s
Normal	Normal (0.99)	Normal	0.68	#s auto landing initiated #/s
Normal	Normal (0.99)	Normal	1.29	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	2.00	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.35	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	-1.16	#s battery error . #/s
Normal	Normal (0.99)	Normal	0.67	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.50	#s battery power low . #/s
Normal	Normal (0.99)	Normal	2.89	#s check battery status and charge or warm up battery #/s
HardwareFault	HardwareFault (0.81)	HardwareFault	1.79	#s cache space full #/s

SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	1.47	#s calibration subject is too close . #/s
Normal	Normal (0.99)	Normal	2.76	#s recalibrate using a subject that is farther away #/s
HardwareFault	HardwareFault (0.88)	HardwareFault	-0.18	#s camera busy , cannot enter playback #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	0.88	#s cannot enable intelligent flight mode #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.16	#s low battery #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	1.36	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	-0.82	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.87)	ParamViolation	-0.68	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	1.36	#s cannot switch flight mode . #/s
Normal	Normal (0.99)	Normal	1.25	#s turn on " multiple flight modes " to enable atti and sport modes . #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	0.71	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.92)	SoftwareFault	-0.93	#s no image #/s
Normal	Normal (0.99)	Normal	0.14	#s please retry #/s
				#s cannot

SoftwareFault	SoftwareFault (0.92)	SoftwareFault	0.71	track subject #/s
SurroundingEnvironment	SoftwareFault (0.92)	SoftwareFault	1.19	#s subject too large #/s
Normal	Normal (0.99)	Normal	1.90	#s move away and retry #/s
Normal	Normal (0.99)	Normal	-1.37	#s color display in the liveview has been enhanced . #/s
Normal	Normal (0.99)	Normal	2.86	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	0.48	#s compass abnormal . #/s
Normal	Normal (0.99)	Normal	2.38	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	Normal (0.99)	Normal	1.78	#s the ground or walls may contain metal . #/s
Normal	Normal (0.99)	Normal	2.76	#s move away from sources of interference before attempting flight . #/s
Normal	Normal (0.99)	Normal	2.72	#s 2 . calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.27	#s compass error #/s #s compass

HardwareFault	HardwareFault (0.87)	HardwareFault	0.87	error , calibration required #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	0.94	#s compass error . #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	0.94	#s compass error . #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.71	#s compass disconnected #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	0.94	#s compass error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	1.38	#s magnetic filed interference . #/s
Normal	Normal (0.99)	Normal	1.91	#s exit p - gps mode #/s
SoftwareFault	SoftwareFault (0.74)	SoftwareFault	-1.36	#s compass initialization failed . #/s
Normal	Normal (0.99)	Normal	-0.99	#s restart aircraft #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.80	#s critical low battery . #/s
Normal	Normal (0.99)	Normal	2.31	#s aircraft in auto power off protection . #/s
Normal	Normal (0.99)	Normal	1.94	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.80	#s critical low battery . #/s
Normal	Normal (0.99)	Normal	-0.89	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.80	#s critical low battery . #/s
Normal	Normal (0.99)	Normal	1.32	#s return to home or land promptly #/s
				#s critically

HardwareFault	HardwareFault (0.95)	HardwareFault	0.27	low power . #/s
Normal	Normal (0.99)	Normal	0.29	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	0.27	#s critically low power . #/s
Normal	Normal (0.99)	Normal	-1.08	#s aircraft landing . #/s
Normal	Normal (0.99)	Normal	-1.08	#s aircraft landing . #/s
Normal	Normal (0.99)	Normal	1.63	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	0.26	#s critically low voltage warning . #/s
Normal	Normal (0.98)	Normal	1.72	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.86	#s critically low voltage . #/s
Normal	Normal (0.99)	Normal	1.10	#s aircraft will land #/s
Normal	Normal (0.99)	Normal	1.76	#s data recorder file index is 15 . #/s
Normal	Normal (0.99)	Normal	1.96	#s data recorder file index is 17 . #/s
Normal	Normal (0.99)	Normal	2.06	#s data recorder file index is 30 . #/s
Normal	Normal (0.99)	Normal	2.13	#s data recorder file index is 45 . #/s
Normal	Normal (0.99)	Normal	1.75	#s data recorder file index is 46 .

				#/s
				#s data recorder file index is 65 .
Normal	Normal (0.99)	Normal	2.38	#/s
				#s disable sd card read and write
Normal	Normal (0.99)	Normal	3.09	protection or change card
				#/s
CommunicationIssue	CommunicationIssue (0.70)	CommunicationIssue	-0.92	#s downlink lost . #/s
				#s downlink restored ( after 0m 2 . 9s ) . #/s
Normal	Normal (0.99)	Normal	1.51	
Normal	Normal (0.98)	Normal	-1.08	#s drone is vibrating #/s
				#s entered cruise control mode . #/s
Normal	Normal (0.99)	Normal	1.50	
Normal	Normal (0.99)	Normal	2.28	#s press c1 or c2 to exit #/s
				#s excessive attitude angle detected #/s
ParamViolation	ParamViolation (0.87)	ParamViolation	1.90	#s forward obstacle
				avoidance has stopped working #/s
SoftwareFault	Normal (0.99)	Normal	1.10	
				#s exit backward sensing system #/s
Normal	Normal (0.99)	Normal	1.28	
SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	-1.09	#s ambient light is too weak #/s
				#s exited visual avoidance system . #/s
Normal	Normal (0.99)	Normal	1.50	
				#s exiting gps mode : unknown
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	0.85	



				error #/s
ParamViolation	ParamViolation (0.87)	ParamViolation	1.51	#s extra payload detected . #/s
Normal	Normal (0.99)	Normal	2.07	#s flight performance will be affected . #/s
Normal	Normal (0.99)	Normal	-0.40	#s fly with caution #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	1.84	#s forward obstacle sensing is not functioning . #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	0.76	#s forward obstacle sensing not responding #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	2.24	#s gimbal motor overloaded . #/s
Normal	Normal (0.99)	Normal	1.95	#s check whether gimbal can rotate freely #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	0.75	#s gimbal pitch limit reached . #/s
Normal	Normal (0.99)	Normal	-0.96	#s ground plain . #/s
Normal	Normal (0.99)	Normal	0.57	#s safe to land . #/s
ParamViolation	ParamViolation (0.33)	ParamViolation	1.39	#s high altitude . #/s
Normal	Normal (0.99)	Normal	2.75	#s aircraft braking distance increased and flight time decreased . #/s
Normal	Normal (0.99)	Normal	-0.40	#s fly with caution #/s
	SurroundingEnvironment			#s high wind

SurroundingEnvironment	(0.88)	SurroundingEnvironment	1.26	velocity . #/s
Normal	Normal (0.99)	Normal	2.93	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	1.26	#s high wind velocity . #/s
Normal	Normal (0.99)	Normal	2.93	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	1.26	#s high wind velocity . #/s
Normal	Normal (0.99)	Normal	1.97	#s fly with caution and land in a safe place asap . #/s
Normal	Normal (0.94)	Normal	-1.74	#s high - altitude flight #/s
Normal	Normal (0.99)	Normal	-0.40	#s fly with caution #/s
Normal	Normal (0.99)	Normal	0.73	#s aircraft braking distance is extended #/s
Normal	Normal (0.99)	Normal	0.83	#s flight time is shortened . #/s
Normal	Normal (0.99)	Normal	1.67	#s home point updated . #/s
ParamViolation	SoftwareFault (0.64)	SoftwareFault	0.86	#s imu attitude restricted . #/s
Normal	Normal (0.99)	Normal	1.94	#s ensure aircraft is level #/s
SoftwareFault	Normal (0.99)	Normal	-2.11	#s imu not

Normal	Normal (0.99)	Normal	2.09	calibrated . #/s
				#s calibrate imu #/s
				#s landing canceled . #/s
Normal	Normal (0.99)	Normal	0.88	#s landing gear function restored #/s
Normal	Normal (0.99)	Normal	1.02	#s landing gear paused . #/s
Normal	Normal (0.99)	Normal	0.60	#s landing gear raising . #/s
Normal	Normal (0.99)	Normal	-0.77	#s home point recorded #/s
Normal	ParamViolation (0.87)	ParamViolation	-1.99	#s live stream video frame rate less than 9hz . #/s
Normal	Normal (0.99)	Normal	-0.40	#s fly with caution #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.81	#s low power . #/s
Normal	Normal (0.99)	Normal	2.07	#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.81	#s low power . #/s
Normal	Normal (0.99)	Normal	-0.35	#s returning home . #/s
SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	1.38	#s magnetic filed interference . #/s
Normal	Normal (0.99)	Normal	2.14	#s exit p - gps mode . #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	0.23	#s yaw error . #/s
SurroundingEnvironment	Normal (0.96)	Normal	-1.69	#s manned aircraft detected

				nearby . #/s
Normal	Normal (0.99)	Normal	-0.40	#s fly with caution #/s
ParamViolation	Normal (0.99)	Normal	0.64	#s max altitude approached . #/s
Normal	Normal (0.99)	Normal	1.98	#s wait for the gps satellite signal recovery before ascend #/s
ParamViolation	ParamViolation (0.87)	ParamViolation	0.01	#s max flight altitude reached . #/s
Normal	Normal (0.99)	Normal	0.72	#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.87)	ParamViolation	1.32	#s max flight distance reached . #/s
Normal	Normal (0.99)	Normal	2.37	#s adjust in main controller settings if necessary . #/s
ParamViolation	ParamViolation (0.87)	ParamViolation	1.60	#s maximum flight distance reached . #/s
Normal	Normal (0.99)	Normal	-2.54	#s adjust the distance in mc settings if required . #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.48	#s mobile device cpu fully loaded . #/s
Normal	Normal (0.99)	Normal	-1.17	#s related performance will be affected . #/s
				#s mobile

				device
				version too
				old to support
				hd image
SoftwareFault	SoftwareFault (0.41)	SoftwareFault	1.45	transmission
				and the
				image
				transmission
				mode has
				been switch
				to normal
				mode . #/s
Normal	Normal (0.99)	Normal	0.51	#s motor is
				blocked . #/s
HardwareFault	HardwareFault (0.95)	HardwareFault	1.07	#s motor
				stuck . #/s
				#s check for
				objects
				blocking
Normal	Normal (0.99)	Normal	-0.83	motor or
				contact dji
				support for
				assistance
				#/s
Normal	Normal (0.99)	Normal	-1.48	#s motors
				started . #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	1.39	#s no gps
				signal . #/s
				#s aircraft
Normal	HardwareFault (0.95)	HardwareFault	-0.58	unable to
				hover . #/s
Normal	Normal (0.99)	Normal	-0.40	#s fly with
				caution #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	1.39	#s no gps
				signal . #/s
Normal	HardwareFault (0.95)	HardwareFault	-0.90	#s unable to
				hover . #/s
Normal	Normal (0.99)	Normal	-0.40	#s fly with
				caution #/s
Normal	Normal (0.99)	Normal	0.90	#s obstacle
				avoidance
				disabled . #/s
Normal	Normal (0.99)	Normal	0.26	#s landing
				gear lowered
				. #/s
Normal	Normal (0.99)	Normal	0.90	#s obstacle
				avoidance
				disabled . #/s

Normal	Normal (0.99)	Normal	0.90	#s obstacle avoidance disabled . #/s
Normal	Normal (0.99)	Normal	0.26	#s landing gear lowered . #/s
Normal	Normal (0.99)	Normal	1.70	#s obstacle avoidance has been disabled . #/s
Normal	Normal (0.99)	Normal	0.07	#s precision landing #/s
Normal	Normal (0.99)	Normal	0.74	#s quickshot has ended #/s
Normal	Normal (0.99)	Normal	1.99	#s recenter gimbal pan #/s
Normal	Normal (0.99)	Normal	2.19	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	-2.09	#s remote controller in high interference environment . #/s
Normal	Normal (0.99)	Normal	1.84	#s manually adjust flight route or return to home #/s
Normal	Normal (0.99)	Normal	2.64	#s return - to - home altitude : 65ft #/s
Normal	Normal (0.99)	Normal	2.29	#s return - to - home altitude : 98ft . #/s
Normal	Normal (0.99)	Normal	2.33	#s rth : ascending to rth altitude . #/s
Normal	Normal (0.99)	Normal	-1.36	#s rth : heading alignment . #/s

Normal	Normal (0.99)	Normal	1.51	#s rth altitude : 65ft . #/s
Normal	Normal (0.99)	Normal	-0.92	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.70)	CommunicationIssue	-0.57	#s signal lost . #/s
Normal	Normal (0.99)	Normal	1.14	#s aircraft returning to home point #/s
Normal	Normal (0.99)	Normal	-0.25	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.88)	SurroundingEnvironment	1.79	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.91)	SoftwareFault	2.11	#s aircraft unable to return to home automatically . #/s
Normal	Normal (0.99)	Normal	0.20	#s lower altitude immediately and return to home manually #/s
Normal	Normal (0.99)	Normal	2.10	#s switched to s ( sport ) - mode . #/s
Normal	Normal (0.99)	Normal	2.51	#s switched to t ( tripod ) - mode . #/s
Normal	Normal (0.99)	Normal	2.23	#s take off in p - mode #/s
SoftwareFault	HardwareFault (0.95)	HardwareFault	2.11	#s vision sensor error . #/s
Normal	Normal (0.99)	Normal	2.39	#s contact dji support for assistance #/s
Normal	Normal (0.99)	Normal	2.05	#s vision systems and obstacle avoidance

Normal	Normal (0.99)	Normal	1.33	disabled #/s
				#s waypoint mission paused #/s
SoftwareFault	SoftwareFault (0.92)	SoftwareFault	-0.25	#s weak gps signal . #/s
Normal	Normal (0.99)	Normal	-2.17	#s aircraft is in attitude mode and hovering may be unstable . #/s
Normal	Normal (0.99)	Normal	-0.88	#s fly with caution . #/s
CommunicationIssue	CommunicationIssue (0.70)	CommunicationIssue	1.57	#s weak signal . #/s
Normal	Normal (0.99)	Normal	0.61	#s adjust antennas #/s
RegulationViolation	RegulationViolation (0.62)	RegulationViolation	3.03	#s your aircraft is flying in an altitude zone ( nnn ) . #/s
Normal	Normal (0.99)	Normal	0.93	#s please fly with caution #/s