

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	Normal (0.16)	Normal	-0.72	#s <span style="background-color: #d9ead3;">a</span>
				passenger
				aircraft is
Normal	Normal (0.16)	Normal	-0.72	<span style="background-color: #f4cccc;">nearby</span> . #/s
				#s fly <span style="background-color: #d9ead3;">with</span>
				<span style="background-color: #d9ead3;">caution</span> #/s
Normal	Normal (0.16)	Normal	-0.83	#s <span style="background-color: #f4cccc;">account</span>
				<span style="background-color: #d9ead3;">not</span> logged in
				. #/s
ParamViolation	ParamViolation (0.16)	ParamViolation	-1.52	#s flight
				altitude and
				<span style="background-color: #f4cccc;">distance</span>
Normal	Normal (0.16)	Normal	-1.52	<span style="background-color: #d9ead3;">restricted</span> to
				<span style="background-color: #f4cccc;">nnn</span> and <span style="background-color: #f4cccc;">nnn</span> .
				#/s
Normal	Normal (0.16)	Normal	0.41	#s <span style="background-color: #f4cccc;">check</span> <span style="background-color: #d9ead3;">and</span>
				<span style="background-color: #d9ead3;">log in</span> #/s
				#s
Normal	Normal (0.16)	Normal	1.82	<span style="background-color: #d9ead3;">activetrack</span>
				flight <span style="background-color: #d9ead3;">paused</span>
				#/s
Normal	Normal (0.16)	Normal	0.10	#s aircraft
				<span style="background-color: #d9ead3;">activetrack</span>
				<span style="background-color: #f4cccc;">available</span> at
Normal	Normal (0.16)	Normal	0.10	<span style="background-color: #f4cccc;">max</span> speed .
				#/s
				#s obstacle
Normal	Normal (0.16)	Normal	0.75	<span style="background-color: #f4cccc;">avoidance</span> is
				<span style="background-color: #d9ead3;">not</span> <span style="background-color: #d9ead3;">available</span>
				#/s
Normal	Normal (0.16)	Normal	0.10	#s aircraft
				<span style="background-color: #d9ead3;">activetrack</span>
				<span style="background-color: #f4cccc;">available</span> at
Normal	Normal (0.16)	Normal	0.10	<span style="background-color: #f4cccc;">max</span> speed .
				#/s
				#s when
Normal	ParamViolation (0.16)	ParamViolation	-1.48	<span style="background-color: #f4cccc;">exceeding</span>
				<span style="background-color: #f4cccc;">nnn</span> , obstacle
				<span style="background-color: #f4cccc;">avoidance</span> is
Normal	Normal (0.16)	Normal	-1.48	<span style="background-color: #d9ead3;">not</span> available
				#/s
				#s aircraft
Normal	Normal (0.16)	Normal	-0.33	<span style="background-color: #f4cccc;">activetrack</span>
				<span style="background-color: #f4cccc;">max</span> speed <span style="background-color: #d9ead3;">of</span>
				<span style="background-color: #d9ead3;">nnn</span> and

HardwareFault	HardwareFault (0.18)	HardwareFault	1.37	obstacle avoidance functions normally #/s #s aircraft core board overheated #/s
				#s aircraft entered fixed - wing mode . #/s
				#s current flight speed is nnn . #/s
				#s press c2 to exit #/s
				#s aircraft flight control unlocked #/s
RegulationViolation	RegulationViolation (0.17)	RegulationViolation	0.65	#s aircraft in restricted zones . #/s
Normal	Normal (0.16)	Normal	0.80	#s check map to find recommended zones #/s
Normal	Normal (0.16)	Normal	1.48	#s aircraft is in attitude mode , so that it will not hover . #/s
Normal	Normal (0.16)	Normal	-1.13	#s please fly with caution . #/s
Normal	Normal (0.16)	Normal	1.10	#s aircraft is in tripod mode . #/s
Normal	Normal (0.16)	Normal	-1.96	#s exit this mode and try again #/s
Normal	Normal (0.16)	Normal	-1.15	#s aircraft is returning to the starting point #/s
ParamViolation	ParamViolation (0.16)	ParamViolation	1.38	#s aircraft out of range #/s

RegulationViolation	RegulationViolation (0.17)	RegulationViolation	1.71	#s approaching a no-fly zone . #/s
Normal	Normal (0.16)	Normal	0.69	#s rth may be affected . #/s
Normal	Normal (0.16)	Normal	1.54	#s fly with caution #/s
Normal	Normal (0.16)	Normal	1.52	#s arrived at start point . #/s
Normal	Normal (0.16)	Normal	0.98	#s starting waypoint mission #/s
Normal	Normal (0.16)	Normal	-1.55	#s auto landing initiated #/s
Normal	Normal (0.16)	Normal	-2.02	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.77	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.05	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.42	#s battery error . #/s
Normal	Normal (0.16)	Normal	-1.48	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.33	#s battery power low . #/s
Normal	Normal (0.16)	Normal	-1.56	#s check battery status and charge or warm up battery #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.49	#s cache space full #/s

SurroundingEnvironment	SoftwareFault (0.19)	SoftwareFault	-0.74	#s calibration subject is too close . #/s
Normal	Normal (0.16)	Normal	-1.12	#s recalibrate using a subject that is farther away #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.33	#s camera busy , cannot enter playback #/s
SoftwareFault	SoftwareFault (0.19)	SoftwareFault	1.48	#s cannot enable intelligent flight mode #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.36	#s low battery #/s
SoftwareFault	SoftwareFault (0.19)	SoftwareFault	0.37	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.10	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.16)	ParamViolation	-0.55	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	0.82	#s cannot switch flight mode . #/s
Normal	Normal (0.16)	Normal	0.79	#s turn on " multiple flight modes " to enable atti and sport modes . #/s
SoftwareFault	SoftwareFault (0.19)	SoftwareFault	1.14	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.18)	SoftwareFault	0.01	#s no image #/s
Normal	Normal (0.16)	Normal	-1.39	#s please retry #/s #s cannot

SoftwareFault	SoftwareFault (0.19)	SoftwareFault	1.14	track subject #/s
SurroundingEnvironment	SoftwareFault (0.19)	SoftwareFault	1.29	#s subject too large #/s
Normal	Normal (0.16)	Normal	-1.09	#s move away and retry #/s
Normal	Normal (0.16)	Normal	-2.04	#s color display in the liveview has been enhanced . #/s
Normal	Normal (0.16)	Normal	-1.72	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.50	#s compass abnormal . #/s
Normal	Normal (0.16)	Normal	1.26	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	Normal (0.16)	Normal	1.73	#s the ground or walls may contain metal . #/s
Normal	Normal (0.16)	Normal	1.98	#s move away from sources of interference before attempting flight . #/s
Normal	Normal (0.16)	Normal	1.92	#s 2 . calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	0.34	#s compass error #/s #s compass

HardwareFault	SoftwareFault (0.16)	SoftwareFault	1.76	error , calibration required #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.43	#s compass error . #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.43	#s compass error . #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.37	#s compass disconnected #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.43	#s compass error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.17)	SurroundingEnvironment	0.89	#s magnetic filed interference . #/s
Normal	Normal (0.16)	Normal	1.70	#s exit p - gps mode #/s
SoftwareFault	HardwareFault (0.18)	HardwareFault	0.58	#s compass initialization failed . #/s
Normal	Normal (0.16)	Normal	1.48	#s restart aircraft #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.38	#s critical low battery . #/s
Normal	Normal (0.16)	Normal	-2.06	#s aircraft in auto power off protection . #/s
Normal	Normal (0.16)	Normal	1.50	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.38	#s critical low battery . #/s
Normal	Normal (0.16)	Normal	-0.86	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.38	#s critical low battery . #/s
Normal	Normal (0.16)	Normal	-1.15	#s return to home or land promptly #/s
				#s critically

HardwareFault	HardwareFault (0.18)	HardwareFault	1.73	low power . #/s
Normal	Normal (0.16)	Normal	-1.07	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.73	#s critically low power . #/s
Normal	Normal (0.15)	Normal	1.07	#s aircraft landing . #/s
Normal	Normal (0.15)	Normal	1.07	#s aircraft landing . #/s
Normal	Normal (0.16)	Normal	-0.73	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.50	#s critically low voltage warning . #/s
Normal	Normal (0.16)	Normal	-0.40	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.75	#s critically low voltage . #/s
Normal	Normal (0.16)	Normal	0.02	#s aircraft will land #/s
Normal	Normal (0.16)	Normal	-1.28	#s data recorder file index is 15 . #/s
Normal	Normal (0.16)	Normal	0.31	#s data recorder file index is 17 . #/s
Normal	Normal (0.16)	Normal	-1.53	#s data recorder file index is 30 . #/s
Normal	Normal (0.16)	Normal	-1.71	#s data recorder file index is 45 . #/s
Normal	Normal (0.16)	Normal	1.35	#s data recorder file index is 46 .

				#/s
Normal	Normal (0.16)	Normal	0.82	#s data recorder file index is 65 . #/s
Normal	Normal (0.16)	Normal	0.67	#s disable sd card read and write protection or change card #/s
CommunicationIssue	CommunicationIssue (0.16)	CommunicationIssue	1.63	#s downlink lost . #/s
Normal	Normal (0.16)	Normal	0.93	#s downlink restored ( after 0m 2 . 9s ) . #/s
Normal	Normal (0.16)	Normal	1.30	#s drone is vibrating #/s
Normal	Normal (0.16)	Normal	1.59	#s entered cruise control mode . #/s
Normal	Normal (0.16)	Normal	-0.18	#s press c1 or c2 to exit #/s
ParamViolation	ParamViolation (0.16)	ParamViolation	1.81	#s excessive attitude angle detected #/s
SoftwareFault	SoftwareFault (0.19)	SoftwareFault	1.98	#s forward obstacle avoidance has stopped working #/s
Normal	Normal (0.16)	Normal	-0.27	#s exit backward sensing system #/s
SurroundingEnvironment	SurroundingEnvironment (0.17)	SurroundingEnvironment	0.88	#s ambient light is too weak #/s
Normal	Normal (0.16)	Normal	1.13	#s exited visual avoidance system . #/s
SoftwareFault	SoftwareFault (0.19)	SoftwareFault	1.27	#s exiting gps mode : unknown



ParamViolation	ParamViolation (0.16)	ParamViolation	1.71	error #/s
				#s extra payload detected . #/s
Normal	Normal (0.16)	Normal	1.23	#s flight performance will be affected . #/s
Normal	Normal (0.16)	Normal	1.54	#s fly with caution #/s
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	-0.64	#s forward obstacle sensing is not functioning . #/s
				#s forward obstacle sensing not responding #/s
SoftwareFault	SoftwareFault (0.19)	SoftwareFault	1.99	#s gimbal motor overloaded . #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	2.23	#s check whether gimbal can rotate freely #/s
Normal	Normal (0.16)	Normal	-1.44	#s gimbal pitch limit reached . #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	-0.87	#s ground plain . #/s
Normal	Normal (0.15)	Normal	1.31	#s safe to land . #/s
Normal	Normal (0.15)	Normal	-0.65	#s high altitude . #/s
ParamViolation	SurroundingEnvironment (0.17)	SurroundingEnvironment	-0.18	#s aircraft braking distance increased and flight time decreased . #/s
Normal	Normal (0.16)	Normal	-1.86	#s fly with caution #/s
Normal	Normal (0.16)	Normal	1.54	#s high wind
	SurroundingEnvironment			

SurroundingEnvironment	(0.17)	SurroundingEnvironment	1.45	velocity . #/s
Normal	Normal (0.16)	Normal	0.37	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.17)	SurroundingEnvironment	1.45	#s high wind velocity . #/s
Normal	Normal (0.16)	Normal	0.37	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.17)	SurroundingEnvironment	1.45	#s high wind velocity . #/s
Normal	Normal (0.16)	Normal	1.72	#s fly with caution and land in a safe place asap . #/s
Normal	Normal (0.15)	Normal	-1.32	#s high - altitude flight #/s
Normal	Normal (0.16)	Normal	1.54	#s fly with caution #/s
Normal	Normal (0.16)	Normal	0.84	#s aircraft braking distance is extended #/s
Normal	Normal (0.16)	Normal	1.70	#s flight time is shortened . #/s
Normal	Normal (0.15)	Normal	1.24	#s home point updated . #/s
ParamViolation	SoftwareFault (0.18)	SoftwareFault	0.60	#s imu attitude restricted . #/s
Normal	Normal (0.16)	Normal	-1.31	#s ensure aircraft is level #/s
SoftwareFault	Normal (0.16)	Normal	0.50	#s imu not

				calibrated . #/s
Normal	Normal (0.16)	Normal	-0.42	#s calibrate imu #/s
Normal	Normal (0.15)	Normal	1.35	#s landing canceled . #/s
Normal	Normal (0.16)	Normal	1.30	#s landing gear function restored #/s
Normal	Normal (0.15)	Normal	-0.82	#s landing gear paused . #/s
Normal	Normal (0.15)	Normal	-1.51	#s landing gear raising . #/s
Normal	Normal (0.16)	Normal	1.61	#s home point recorded #/s
Normal	ParamViolation (0.15)	ParamViolation	-1.07	#s live stream video frame rate less than 9hz . #/s
Normal	Normal (0.16)	Normal	1.54	#s fly with caution #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.51	#s low power . #/s
Normal	Normal (0.16)	Normal	-2.18	#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.51	#s low power . #/s
Normal	Normal (0.15)	Normal	1.23	#s returning home . #/s
SurroundingEnvironment	SurroundingEnvironment (0.17)	SurroundingEnvironment	0.89	#s magnetic field interference . #/s
Normal	Normal (0.16)	Normal	1.49	#s exit p - gps mode . #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	0.04	#s yaw error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.17)	SurroundingEnvironment	1.13	#s manned aircraft detected

				nearby. #/s
Normal	Normal (0.16)	Normal	1.54	#s fly with caution #/s
ParamViolation	ParamViolation (0.16)	ParamViolation	1.12	#s max altitude approached. #/s
Normal	Normal (0.16)	Normal	-0.20	#s wait for the gps satellite signal recovery before ascend #/s
ParamViolation	ParamViolation (0.16)	ParamViolation	1.43	#s max flight altitude reached. #/s
Normal	Normal (0.16)	Normal	-0.77	#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.16)	ParamViolation	-1.45	#s max flight distance reached. #/s
Normal	Normal (0.16)	Normal	-1.26	#s adjust in main controller settings if necessary . #/s
ParamViolation	ParamViolation (0.16)	ParamViolation	-1.82	#s maximum flight distance reached. #/s
Normal	Normal (0.16)	Normal	-2.13	#s adjust the distance in mc settings if required . #/s
HardwareFault	HardwareFault (0.18)	HardwareFault	1.97	#s mobile device cpu fully loaded. #/s
Normal	Normal (0.16)	Normal	-1.63	#s related performance will be affected . #/s
				#s mobile

SoftwareFault	Normal (0.15)	Normal	-1.12	device
				version too
				old to support
				hd image
				transmission
Normal	Normal (0.15)	Normal	1.15	and the
				image
				transmission
				mode has
				been switch
HardwareFault	HardwareFault (0.18)	HardwareFault	-1.28	to normal
				mode . #/s
				#s motor is
				blocked . #/s
				#s motor
Normal	Normal (0.16)	Normal	0.61	stuck . #/s
				#s check for
				objects
				blocking
				motor or
Normal	Normal (0.15)	Normal	0.80	contact dji
				support for
				assistance
				#/s
				#s motors
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.80	started . #/s
				#s no gps
				signal . #/s
				#s aircraft
				unable to
Normal	Normal (0.16)	Normal	1.54	hover . #/s
				#s fly with
				caution #/s
				#s no gps
				signal . #/s
Normal	Normal (0.16)	Normal	1.54	#s unable to
				hover . #/s
				#s fly with
				caution #/s
				#s obstacle
Normal	Normal (0.15)	Normal	1.40	avoidance
				disabled . #/s
				#s landing
				gear lowered
				. #/s
Normal	Normal (0.15)	Normal	1.40	#s obstacle
				avoidance
				disabled . #/s

Normal	Normal (0.15)	Normal	1.40	#s obstacle avoidance disabled . #/s
Normal	Normal (0.15)	Normal	-1.14	#s landing gear lowered . #/s
Normal	Normal (0.16)	Normal	-1.00	#s obstacle avoidance has been disabled . #/s
Normal	Normal (0.16)	Normal	-1.37	#s precision landing #/s
Normal	Normal (0.16)	Normal	1.93	#s quickshot has ended #/s
Normal	Normal (0.16)	Normal	1.17	#s recenter gimbal pan #/s
Normal	Normal (0.16)	Normal	0.84	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.17)	SurroundingEnvironment	1.28	#s remote controller in high interference environment . #/s
Normal	Normal (0.16)	Normal	0.66	#s manually adjust flight route or return to home #/s
Normal	Normal (0.16)	Normal	1.49	#s return - to - home altitude : 65ft #/s
Normal	Normal (0.16)	Normal	1.85	#s return - to - home altitude : 98ft . #/s
Normal	Normal (0.16)	Normal	-1.17	#s rth : ascending to rth altitude . #/s
Normal	Normal (0.16)	Normal	2.10	#s rth : heading alignment . #/s

Normal	Normal (0.16)	Normal	-2.19	#s rth altitude : 65ft . #/s
Normal	Normal (0.16)	Normal	0.70	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.16)	CommunicationIssue	0.95	#s signal lost . #/s
Normal	Normal (0.16)	Normal	-0.81	#s aircraft returning to home point #/s
Normal	Normal (0.16)	Normal	0.95	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.17)	SurroundingEnvironment	1.63	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.19)	SoftwareFault	2.08	#s aircraft unable to return to home automatically . #/s
Normal	Normal (0.16)	Normal	1.73	#s lower altitude immediately and return to home manually #/s
Normal	Normal (0.16)	Normal	1.36	#s switched to s ( sport ) - mode . #/s
Normal	Normal (0.16)	Normal	-0.21	#s switched to t ( tripod ) - mode . #/s
Normal	Normal (0.16)	Normal	0.96	#s take off in p - mode #/s
SoftwareFault	HardwareFault (0.18)	HardwareFault	0.16	#s vision sensor error . #/s
Normal	Normal (0.16)	Normal	-1.17	#s contact dji support for assistance #/s
Normal	Normal (0.16)	Normal	-2.02	#s vision systems and obstacle avoidance

Normal	Normal (0.16)	Normal	-0.62	disabled #/s
				#s waypoint
				mission
SoftwareFault	SoftwareFault (0.18)	SoftwareFault	1.40	paused #/s
				#s weak gps
				signal . #/s
Normal	Normal (0.16)	Normal	-2.10	#s aircraft is
				in attitude
				mode and
Normal	Normal (0.15)	Normal	1.18	hovering may
				be unstable .
				#/s
CommunicationIssue	CommunicationIssue (0.16)	CommunicationIssue	1.46	#s fly with
				caution . #/s
				#s weak
Normal	Normal (0.16)	Normal	1.18	signal . #/s
				#s adjust
				antennas #/s
RegulationViolation	RegulationViolation (0.17)	RegulationViolation	2.88	#s your
				aircraft is
				flying in an
Normal	Normal (0.16)	Normal	-1.31	altitude zone
				( nnn ) . #/s
				#s please fly
Normal	Normal (0.16)	Normal	-1.31	with caution
				#/s