True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
None	Normal (1.00)	Normal	0.17	[CLS] motors starting [SEP]
None	Normal (1.00)	Normal	0.64	[CLS] flight mode changed to starting motors [SEP]
None	Normal (1.00)	Normal	0.02	[CLS] data recorder file index is 88 . [SEP]
None	Normal (1.00)	Normal	0.40	[CLS] set return to home (rth) altitude to 100 m (328 ft) [SEP]
None	Normal (1.00)	Normal	-1.61	[CLS] set maximum flight altitude to 500 m (1640 ft) [SEP]
None	Normal (1.00)	Normal	0.17	[CLS] motors starting [SEP]
None	Normal (1.00)	Normal	0.87	[CLS] flight mode changed to manual takeoff [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p - gps [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] home point updated [SEP]
None	Normal (1.00)	Normal	-0.31	[CLS] rth altitude adjusted to 100m [SEP]
None	Normal (1.00)	Normal	0.55	[CLS] home point updated [SEP]
None	Normal (1.00)	Normal	-0.31	[CLS] rth altitude adjusted to 100m [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]

	(0.97)			
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	HardwareFault (0.99)	HardwareFault	1.78	[CLS] gimbal pitch axis endpoint reached [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]

None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.86	[CLS] flight mode changed to go home [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]

None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p - gps [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]

None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.07	[CLS] flight mode changed to confirm landing [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] auto landing in progress [SEP]
None	Normal (1.00)	Normal	0.16	[CLS] auto landing in progress [SEP]