

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	Normal (0.16)	Normal	1.17	#s a passenger aircraft is nearby . #/s
				#s fly with caution #/s
				#s account not logged in . #/s
Normal	Normal (0.16)	Normal	1.55	#s flight altitude and distance restricted to nnn and nnn . #/s
				#s check and log in #/s
				#s activetrack flight paused #/s
ParamViolation	ParamViolation (0.18)	ParamViolation	2.17	#s aircraft activetrack available at max speed . #/s
				#s obstacle avoidance is not available #/s
				#s aircraft activetrack available at max speed . #/s
Normal	Normal (0.16)	Normal	-1.19	#s when exceeding nnn , obstacle avoidance is not available #/s
				#s aircraft activetrack max speed of nnn and
Normal	Normal (0.16)	Normal	1.55	

HardwareFault	HardwareFault (0.17)	HardwareFault	1.42	obstacle avoidance functions normally #/s
				#s aircraft core board overheated #/s
				#s aircraft entered fixed - wing mode . #/s
				#s current flight speed is nnn . #/s
				#s press c2 to exit #/s
Normal	Normal (0.16)	Normal	2.38	#s aircraft flight control unlocked #/s
Normal	Normal (0.16)	Normal	1.53	#s aircraft in restricted zones . #/s
Normal	Normal (0.16)	Normal	1.64	#s check map to find recommended zones #/s
Normal	Normal (0.16)	Normal	1.60	#s aircraft is in attitude mode , so that it will not hover . #/s
RegulationViolation	RegulationViolation (0.16)	RegulationViolation	0.67	#s please fly with caution . #/s
Normal	Normal (0.16)	Normal	0.86	#s aircraft is in tripod mode . #/s
Normal	Normal (0.16)	Normal	1.88	#s exit this mode and try again #/s
Normal	Normal (0.16)	Normal	1.01	#s aircraft is returning to the starting point #/s
Normal	Normal (0.16)	Normal	1.11	#s aircraft out of range #/s
ParamViolation	ParamViolation (0.18)	ParamViolation	1.42	

RegulationViolation	RegulationViolation (0.16)	RegulationViolation	1.75	#s approaching a no-fly zone . #/s
Normal	Normal (0.16)	Normal	1.64	#s rth may be affected . #/s
Normal	Normal (0.16)	Normal	1.55	#s fly with caution #/s
Normal	Normal (0.16)	Normal	-1.67	#s arrived at start point . #/s
Normal	Normal (0.16)	Normal	-0.56	#s starting waypoint mission #/s
Normal	Normal (0.16)	Normal	1.55	#s auto landing initiated #/s
Normal	Normal (0.16)	Normal	0.18	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	1.82	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	0.82	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.39	#s battery error . #/s
Normal	Normal (0.16)	Normal	0.98	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.32	#s battery power low . #/s
Normal	Normal (0.16)	Normal	2.11	#s check battery status and charge or warm up battery #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.51	#s cache space full #/s

SurroundingEnvironment	SoftwareFault (0.17)	SoftwareFault	-0.68	#s calibration subject is too close . #/s
Normal	Normal (0.16)	Normal	-0.92	#s recalibrate using a subject that is farther away #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.27	#s camera busy , cannot enter playback #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	1.38	#s cannot enable intelligent flight mode #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.45	#s low battery #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	0.98	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	0.65	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.18)	ParamViolation	-0.67	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.16)	SoftwareFault	-1.79	#s cannot switch flight mode . #/s
Normal	Normal (0.16)	Normal	1.06	#s turn on " multiple flight modes " to enable atti and sport modes . #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	1.15	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.17)	SoftwareFault	1.21	#s no image #/s
Normal	Normal (0.16)	Normal	-0.12	#s please retry #/s
				#s cannot

SoftwareFault	SoftwareFault (0.17)	SoftwareFault	1.15	track subject #/s
SurroundingEnvironment	SoftwareFault (0.17)	SoftwareFault	-1.76	#s subject too large #/s
Normal	Normal (0.16)	Normal	1.02	#s move away and retry #/s
Normal	Normal (0.16)	Normal	1.00	#s color display in the liveview has been enhanced . #/s
Normal	Normal (0.16)	Normal	-0.30	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.36	#s compass abnormal . #/s
Normal	Normal (0.16)	Normal	3.05	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	Normal (0.16)	Normal	1.75	#s the ground or walls may contain metal . #/s
Normal	Normal (0.16)	Normal	1.93	#s move away from sources of interference before attempting flight . #/s
Normal	Normal (0.16)	Normal	1.92	#s 2 . calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	0.96	#s compass error #/s #s compass

HardwareFault	HardwareFault (0.16)	HardwareFault	1.60	error , calibration required #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.49	#s compass error . #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.49	#s compass error . #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.44	#s compass disconnected #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.49	#s compass error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.18)	SurroundingEnvironment	0.92	#s magnetic filed interference . #/s
Normal	Normal (0.16)	Normal	1.49	#s exit p - gps mode #/s
SoftwareFault	HardwareFault (0.17)	HardwareFault	0.51	#s compass initialization failed . #/s
Normal	Normal (0.16)	Normal	1.41	#s restart aircraft #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	-0.56	#s critical low battery . #/s
Normal	Normal (0.16)	Normal	-0.79	#s aircraft in auto power off protection . #/s
Normal	Normal (0.16)	Normal	1.74	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	-0.56	#s critical low battery . #/s
Normal	Normal (0.16)	Normal	0.38	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	-0.56	#s critical low battery . #/s
Normal	Normal (0.16)	Normal	2.02	#s return to home or land promptly #/s
				#s critically

HardwareFault	HardwareFault (0.17)	HardwareFault	1.75	low power . #/s
Normal	Normal (0.16)	Normal	1.40	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.75	#s critically low power . #/s
Normal	Normal (0.16)	Normal	1.09	#s aircraft landing . #/s
Normal	Normal (0.16)	Normal	1.09	#s aircraft landing . #/s
Normal	Normal (0.16)	Normal	2.12	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.32	#s critically low voltage warning . #/s
Normal	Normal (0.16)	Normal	-0.03	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.77	#s critically low voltage . #/s
Normal	Normal (0.16)	Normal	1.60	#s aircraft will land #/s
Normal	Normal (0.16)	Normal	1.22	#s data recorder file index is 15 . #/s
Normal	Normal (0.16)	Normal	1.61	#s data recorder file index is 17 . #/s
Normal	Normal (0.16)	Normal	-1.68	#s data recorder file index is 30 . #/s
Normal	Normal (0.16)	Normal	0.01	#s data recorder file index is 45 . #/s
Normal	Normal (0.16)	Normal	1.35	#s data recorder file index is 46 .

				#/s
Normal	Normal (0.16)	Normal	-0.40	#s data recorder file index is 65 . #/s
Normal	Normal (0.16)	Normal	0.83	#s disable sd card read and write protection or change card #/s
CommunicationIssue	CommunicationIssue (0.16)	CommunicationIssue	1.80	#s downlink lost . #/s
Normal	Normal (0.16)	Normal	1.90	#s downlink restored (after 0m 2 . 9s) . #/s
Normal	Normal (0.16)	Normal	1.53	#s drone is vibrating #/s
Normal	Normal (0.16)	Normal	1.82	#s entered cruise control mode . #/s
Normal	Normal (0.16)	Normal	-0.91	#s press c1 or c2 to exit #/s
ParamViolation	ParamViolation (0.18)	ParamViolation	1.62	#s excessive attitude angle detected #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	2.05	#s forward obstacle avoidance has stopped working #/s
Normal	Normal (0.16)	Normal	1.06	#s exit backward sensing system #/s
SurroundingEnvironment	SurroundingEnvironment (0.18)	SurroundingEnvironment	0.84	#s ambient light is too weak #/s
Normal	Normal (0.16)	Normal	-1.27	#s exited visual avoidance system . #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	1.23	#s exiting gps mode : unknown

ParamViolation	ParamViolation (0.18)	ParamViolation	1.84	error #/s
				#s extra payload detected . #/s
Normal	Normal (0.16)	Normal	1.23	#s flight performance will be affected . #/s
Normal	Normal (0.16)	Normal	1.55	#s fly with caution #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	-0.70	#s forward obstacle sensing is not functioning . #/s
				#s forward obstacle sensing not responding #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	0.70	#s gimbal motor overloaded . #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.98	#s check whether gimbal can rotate freely #/s
Normal	Normal (0.16)	Normal	0.52	#s gimbal pitch limit reached . #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	-0.90	#s ground plain . #/s
Normal	Normal (0.16)	Normal	1.32	#s safe to land . #/s
Normal	Normal (0.16)	Normal	0.79	#s high altitude . #/s
ParamViolation	SurroundingEnvironment (0.18)	SurroundingEnvironment	-0.63	#s aircraft braking distance increased and flight time decreased . #/s
Normal	Normal (0.16)	Normal	0.08	#s fly with caution #/s
Normal	SurroundingEnvironment			#s high wind

SurroundingEnvironment	(0.18)	SurroundingEnvironment	1.34	velocity . #/s
Normal	Normal (0.16)	Normal	0.60	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.18)	SurroundingEnvironment	1.34	#s high wind velocity . #/s
Normal	Normal (0.16)	Normal	0.60	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.18)	SurroundingEnvironment	1.34	#s high wind velocity . #/s
Normal	Normal (0.16)	Normal	1.80	#s fly with caution and land in a safe place asap . #/s
Normal	Normal (0.16)	Normal	1.55	#s high altitude flight #/s
Normal	Normal (0.16)	Normal	1.55	#s fly with caution #/s
Normal	Normal (0.16)	Normal	1.95	#s aircraft braking distance is extended #/s
Normal	Normal (0.16)	Normal	1.71	#s flight time is shortened . #/s
Normal	Normal (0.16)	Normal	1.28	#s home point updated . #/s
ParamViolation	SoftwareFault (0.16)	SoftwareFault	0.41	#s imu attitude restricted . #/s
Normal	Normal (0.16)	Normal	1.90	#s ensure aircraft is level #/s
SoftwareFault	Normal (0.16)	Normal	-1.32	#s imu not

Normal	Normal (0.16)	Normal	0.87	calibrated . #/s
				#s calibrate imu #/s
				#s landing canceled . #/s
Normal	Normal (0.16)	Normal	1.35	#s landing gear function
				restored #/s
				#s landing gear paused . #/s
Normal	Normal (0.16)	Normal	0.25	#s landing gear raising . #/s
				#s home point recorded #/s
				#s live stream video frame rate less than 9hz . #/s
Normal	ParamViolation (0.18)	ParamViolation	-1.13	#s fly with caution #/s
				#s low power . #/s
				#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.50	#s low power . #/s
				#s returning home . #/s
				#s magnetic field interference . #/s
SurroundingEnvironment	SurroundingEnvironment (0.18)	SurroundingEnvironment	0.92	#s exit p - gps mode . #/s
				#s yaw error . #/s
				#s manned aircraft detected
Normal	Normal (0.16)	Normal	1.51	
HardwareFault	HardwareFault (0.17)	HardwareFault	-0.10	
SurroundingEnvironment	SurroundingEnvironment (0.18)	SurroundingEnvironment	1.22	

				nearby . #/s
Normal	Normal (0.16)	Normal	1.55	#s fly with caution #/s
ParamViolation	ParamViolation (0.18)	ParamViolation	1.45	#s max altitude approached . #/s
Normal	Normal (0.16)	Normal	-1.72	#s wait for the gps satellite signal recovery before ascend #/s
ParamViolation	ParamViolation (0.18)	ParamViolation	1.29	#s max flight altitude reached . #/s
Normal	Normal (0.16)	Normal	0.45	#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.18)	ParamViolation	-1.43	#s max flight distance reached . #/s
Normal	Normal (0.16)	Normal	0.31	#s adjust in main controller settings if necessary . #/s
ParamViolation	ParamViolation (0.18)	ParamViolation	-1.79	#s maximum flight distance reached . #/s
Normal	Normal (0.16)	Normal	0.74	#s adjust the distance in mc settings if required . #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.94	#s mobile device cpu fully loaded . #/s
Normal	Normal (0.16)	Normal	-0.58	#s related performance will be affected . #/s
				#s mobile

				device
				version too
				old to support
				hd image
SoftwareFault	Normal (0.15)	Normal	0.17	transmission
				and the
				image
				transmission
				mode has
				been switch
				to normal
				mode . #/s
Normal	Normal (0.16)	Normal	1.18	#s motor is
				blocked . #/s
HardwareFault	HardwareFault (0.17)	HardwareFault	1.46	#s motor
				stuck . #/s
				#s check for
				objects
				blocking
Normal	Normal (0.16)	Normal	0.80	motor or
				contact dji
				support for
				assistance
				#/s
Normal	Normal (0.16)	Normal	0.83	#s motors
				started . #/s
SoftwareFault	SoftwareFault (0.16)	SoftwareFault	1.84	#s no gps
				signal . #/s
				#s aircraft
Normal	HardwareFault (0.17)	HardwareFault	-1.65	unable to
				hover . #/s
Normal	Normal (0.16)	Normal	1.55	#s fly with
				caution #/s
SoftwareFault	SoftwareFault (0.16)	SoftwareFault	1.84	#s no gps
				signal . #/s
Normal	HardwareFault (0.17)	HardwareFault	-1.58	#s unable to
				hover . #/s
Normal	Normal (0.16)	Normal	1.55	#s fly with
				caution #/s
Normal	Normal (0.16)	Normal	1.40	#s obstacle
				avoidance
				disabled . #/s
Normal	Normal (0.16)	Normal	1.28	#s landing
				gear lowered
				. #/s
Normal	Normal (0.16)	Normal	1.40	#s obstacle
				avoidance
				disabled . #/s

Normal	Normal (0.16)	Normal	1.40	#s obstacle avoidance disabled . #/s
Normal	Normal (0.16)	Normal	1.28	#s landing gear lowered . #/s
Normal	Normal (0.16)	Normal	1.81	#s obstacle avoidance has been disabled . #/s
Normal	Normal (0.16)	Normal	0.91	#s precision landing #/s
Normal	Normal (0.16)	Normal	1.93	#s quickshot has ended #/s
Normal	Normal (0.16)	Normal	1.20	#s recenter gimbal pan #/s
Normal	Normal (0.16)	Normal	1.47	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.18)	SurroundingEnvironment	1.38	#s remote controller in high interference environment . #/s
Normal	Normal (0.16)	Normal	1.72	#s manually adjust flight route or return to home #/s
Normal	Normal (0.16)	Normal	-1.41	#s return - to - home altitude : 65ft #/s
Normal	Normal (0.16)	Normal	2.12	#s return - to - home altitude : 98ft . #/s
Normal	Normal (0.16)	Normal	-1.52	#s rth : ascending to rth altitude . #/s
Normal	Normal (0.16)	Normal	-0.64	#s rth : heading alignment . #/s

Normal	Normal (0.16)	Normal	1.94	#s rth altitude : 65ft . #/s
Normal	Normal (0.16)	Normal	1.37	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.16)	CommunicationIssue	1.03	#s signal lost . #/s
Normal	Normal (0.16)	Normal	2.08	#s aircraft returning to home point #/s
Normal	Normal (0.16)	Normal	1.44	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.18)	SurroundingEnvironment	1.66	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.17)	SoftwareFault	2.08	#s aircraft unable to return to home automatically . #/s
Normal	Normal (0.16)	Normal	1.87	#s lower altitude immediately and return to home manually #/s
Normal	Normal (0.16)	Normal	1.47	#s switched to s (sport) - mode . #/s
Normal	Normal (0.16)	Normal	-1.02	#s switched to t (tripod) - mode . #/s
Normal	Normal (0.16)	Normal	-0.88	#s take off in p - mode #/s
SoftwareFault	HardwareFault (0.17)	HardwareFault	0.19	#s vision sensor error . #/s
Normal	Normal (0.16)	Normal	1.60	#s contact dji support for assistance #/s
Normal	Normal (0.16)	Normal	0.10	#s vision systems and obstacle avoidance

Normal	Normal (0.16)	Normal	1.09	disabled #/s
				#s waypoint mission paused #/s
SoftwareFault	SoftwareFault (0.16)	SoftwareFault	1.45	#s weak gps signal . #/s
Normal	Normal (0.16)	Normal	1.47	#s aircraft is in attitude mode and hovering may be unstable . #/s
Normal	Normal (0.16)	Normal	-1.32	#s fly with caution . #/s
CommunicationIssue	CommunicationIssue (0.16)	CommunicationIssue	1.16	#s weak signal . #/s
Normal	Normal (0.16)	Normal	1.18	#s adjust antennas #/s
RegulationViolation	RegulationViolation (0.16)	RegulationViolation	2.87	#s your aircraft is flying in an altitude zone (nnn) . #/s
Normal	Normal (0.16)	Normal	-0.84	#s please fly with caution #/s