

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	SurroundingEnvironment (0.42)	SurroundingEnvironment	1.13	#s a <span style="background-color: #d9ead3;"></span>
				passenger <span style="background-color: #d9ead3;"></span>
				aircraft is <span style="background-color: #d9ead3;"></span>
				nearby . #/s <span style="background-color: #f4cccc;"></span>
				#s fly with <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.64)	Normal	1.51	caution #/s <span style="background-color: #d9ead3;"></span>
				#s account <span style="background-color: #f4cccc;"></span>
				not logged in <span style="background-color: #f4cccc;"></span>
				. #/s <span style="background-color: #f4cccc;"></span>
				#s flight <span style="background-color: #d9ead3;"></span>
ParamViolation	ParamViolation (0.59)	ParamViolation	1.93	altitude and <span style="background-color: #d9ead3;"></span>
				distance <span style="background-color: #d9ead3;"></span>
				restricted to <span style="background-color: #d9ead3;"></span>
				nnn and nnn . <span style="background-color: #d9ead3;"></span>
				#/s <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.64)	Normal	1.79	#s check and <span style="background-color: #d9ead3;"></span>
				log in #/s <span style="background-color: #d9ead3;"></span>
				#s <span style="background-color: #d9ead3;"></span>
				activetrack <span style="background-color: #d9ead3;"></span>
				flight paused <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.64)	Normal	1.97	#/s <span style="background-color: #d9ead3;"></span>
				#s aircraft <span style="background-color: #d9ead3;"></span>
				activetrack <span style="background-color: #d9ead3;"></span>
				available at <span style="background-color: #d9ead3;"></span>
				max speed . <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.64)	Normal	2.42	#/s <span style="background-color: #d9ead3;"></span>
				#s obstacle <span style="background-color: #f4cccc;"></span>
				avoidance is <span style="background-color: #f4cccc;"></span>
				not available <span style="background-color: #f4cccc;"></span>
				#/s <span style="background-color: #f4cccc;"></span>
Normal	SoftwareFault (0.53)	SoftwareFault	-1.66	#s aircraft <span style="background-color: #d9ead3;"></span>
				activetrack <span style="background-color: #d9ead3;"></span>
				available at <span style="background-color: #d9ead3;"></span>
				max speed . <span style="background-color: #d9ead3;"></span>
				#/s <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.64)	Normal	2.42	#s <span style="background-color: #d9ead3;"></span>
				when <span style="background-color: #d9ead3;"></span>
				exceeding <span style="background-color: #f4cccc;"></span>
				nnn , obstacle <span style="background-color: #f4cccc;"></span>
				avoidance is <span style="background-color: #d9ead3;"></span>
Normal	Normal (0.53)	Normal	0.06	not available <span style="background-color: #f4cccc;"></span>
				#/s <span style="background-color: #f4cccc;"></span>
				#s aircraft <span style="background-color: #d9ead3;"></span>
				activetrack <span style="background-color: #d9ead3;"></span>
				max speed of <span style="background-color: #f4cccc;"></span>
Normal	Normal (0.64)	Normal	1.55	nnn and <span style="background-color: #d9ead3;"></span>
				#s <span style="background-color: #d9ead3;"></span>
				aircraft <span style="background-color: #d9ead3;"></span>
				activetrack <span style="background-color: #d9ead3;"></span>
				max speed of <span style="background-color: #f4cccc;"></span>

HardwareFault	HardwareFault (0.60)	HardwareFault	1.38	obstacle avoidance functions normally #/s #s aircraft core board overheated #/s
				#s aircraft entered fixed wing mode . #/s
				#s current flight speed is nnn . #/s
				#s press c2 to exit #/s
				#s aircraft flight control unlocked #/s
RegulationViolation	RegulationViolation (0.36)	RegulationViolation	1.84	#s aircraft in restricted zones . #/s
Normal	Normal (0.64)	Normal	1.98	#s check map to find recommended zones #/s
Normal	Normal (0.64)	Normal	3.03	#s aircraft is in attitude mode , so that it will not hover . #/s
Normal	Normal (0.64)	Normal	1.71	#s please fly with caution . #/s
Normal	Normal (0.64)	Normal	1.95	#s aircraft is in tripod mode . #/s
Normal	Normal (0.64)	Normal	1.91	#s exit this mode and try again #/s
Normal	Normal (0.64)	Normal	1.03	#s aircraft is returning to the starting point #/s
ParamViolation	ParamViolation (0.58)	ParamViolation	1.49	#s aircraft out of range #/s

RegulationViolation	RegulationViolation (0.37)	RegulationViolation	2.22	#s approaching a no - fly zone . #/s
Normal	Normal (0.64)	Normal	1.85	#s rth may be affected . #/s
Normal	Normal (0.64)	Normal	1.51	#s fly with caution #/s
Normal	Normal (0.64)	Normal	1.20	#s arrived at start point . #/s
Normal	Normal (0.64)	Normal	0.77	#s starting waypoint mission #/s
Normal	Normal (0.64)	Normal	1.58	#s auto landing initiated #/s
Normal	Normal (0.64)	Normal	1.65	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	1.53	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.59)	HardwareFault	-0.90	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.36	#s battery error . #/s
Normal	Normal (0.64)	Normal	1.75	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.26	#s battery power low . #/s
Normal	Normal (0.64)	Normal	1.22	#s check battery status and charge or warm up battery #/s
HardwareFault	HardwareFault (0.59)	HardwareFault	1.21	#s cache space full #/s

SurroundingEnvironment	Normal (0.31)	Normal	-1.41	#s calibration subject is too close . #/s
Normal	Normal (0.64)	Normal	2.33	#s recalibrate using a subject that is farther away #/s
HardwareFault	HardwareFault (0.57)	HardwareFault	1.68	#s camera busy , cannot enter playback #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	1.28	#s cannot enable intelligent flight mode #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.56	#s low battery #/s
SoftwareFault	SoftwareFault (0.56)	SoftwareFault	0.53	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	1.09	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.58)	ParamViolation	-2.05	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	1.08	#s cannot switch flight mode . #/s
Normal	Normal (0.64)	Normal	3.43	#s turn on " multiple flight modes " to enable atti and sport modes . #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	0.69	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.56)	SoftwareFault	-0.85	#s no image #/s
Normal	Normal (0.64)	Normal	1.31	#s please retry #/s
				#s cannot

SoftwareFault	SoftwareFault (0.57)	SoftwareFault	0.69	track subject #/s
SurroundingEnvironment	SoftwareFault (0.55)	SoftwareFault	-1.41	#s subject too large #/s
Normal	Normal (0.64)	Normal	1.71	#s move away and retry #/s
Normal	Normal (0.64)	Normal	2.66	#s color display in the liveview has been enhanced . #/s
Normal	Normal (0.64)	Normal	1.80	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.51	#s compass abnormal . #/s
Normal	Normal (0.64)	Normal	3.11	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	Normal (0.63)	Normal	1.94	#s the ground or walls may contain metal . #/s
Normal	Normal (0.64)	Normal	1.92	#s move away from sources of interference before attempting flight . #/s
Normal	Normal (0.64)	Normal	1.60	#s 2 . calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.34	#s compass error #/s #s compass

HardwareFault	HardwareFault (0.47)	HardwareFault	1.76	error , calibration required #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.53	#s compass error . #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.53	#s compass error . #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.43	#s compass disconnected #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.53	#s compass error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.47)	SurroundingEnvironment	1.43	#s magnetic filed interference . #/s
Normal	Normal (0.64)	Normal	1.96	#s exit p - gps mode #/s
SoftwareFault	HardwareFault (0.59)	HardwareFault	0.61	#s compass initialization failed . #/s
Normal	Normal (0.64)	Normal	1.51	#s restart aircraft #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.46	#s critical low battery . #/s
Normal	Normal (0.64)	Normal	2.09	#s aircraft in auto power off protection . #/s
Normal	Normal (0.59)	Normal	1.03	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.46	#s critical low battery . #/s
Normal	Normal (0.64)	Normal	1.32	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.46	#s critical low battery . #/s
Normal	Normal (0.64)	Normal	1.33	#s return to home or land promptly #/s
				#s critically

HardwareFault	HardwareFault (0.60)	HardwareFault	1.68	low power . #/s
Normal	Normal (0.64)	Normal	1.30	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.68	#s critically low power . #/s
Normal	Normal (0.64)	Normal	1.61	#s aircraft landing . #/s
Normal	Normal (0.64)	Normal	1.61	#s aircraft landing . #/s
Normal	Normal (0.64)	Normal	3.17	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.54	#s critically low voltage warning . #/s
Normal	Normal (0.63)	Normal	1.49	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.78	#s critically low voltage . #/s
Normal	Normal (0.64)	Normal	1.61	#s aircraft will land #/s
Normal	Normal (0.64)	Normal	1.97	#s data recorder file index is 15 . #/s
Normal	Normal (0.64)	Normal	2.24	#s data recorder file index is 17 . #/s
Normal	Normal (0.64)	Normal	2.02	#s data recorder file index is 30 . #/s
Normal	Normal (0.64)	Normal	2.43	#s data recorder file index is 45 . #/s
Normal	Normal (0.64)	Normal	2.05	#s data recorder file index is 46 .

				#/s
Normal	Normal (0.64)	Normal	2.29	#s data recorder file index is 65 . #/s
Normal	Normal (0.64)	Normal	2.64	#s disable sd card read and write protection or change card #/s
CommunicationIssue	CommunicationIssue (0.44)	CommunicationIssue	0.91	#s downlink lost . #/s
Normal	Normal (0.64)	Normal	3.02	#s downlink restored ( after 0m 2 . 9s ) . #/s
Normal	HardwareFault (0.57)	HardwareFault	-1.53	#s drone is vibrating #/s
Normal	Normal (0.64)	Normal	1.86	#s entered cruise control mode . #/s
Normal	Normal (0.64)	Normal	2.10	#s press c1 or c2 to exit #/s
ParamViolation	ParamViolation (0.59)	ParamViolation	1.59	#s excessive attitude angle detected #/s
SoftwareFault	SoftwareFault (0.52)	SoftwareFault	2.15	#s forward obstacle avoidance has stopped working #/s
Normal	Normal (0.64)	Normal	1.89	#s exit backward sensing system #/s
SurroundingEnvironment	SurroundingEnvironment (0.48)	SurroundingEnvironment	1.26	#s ambient light is too weak #/s
Normal	Normal (0.64)	Normal	1.81	#s exited visual avoidance system . #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	-0.68	#s exiting gps mode : unknown

				error #/s
ParamViolation	ParamViolation (0.59)	ParamViolation	1.70	#s extra payload detected . #/s
Normal	Normal (0.64)	Normal	1.98	#s flight performance will be affected . #/s
Normal	Normal (0.64)	Normal	1.51	#s fly with caution #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	1.63	#s forward obstacle sensing is not functioning . #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	-0.59	#s forward obstacle sensing not responding #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	0.40	#s gimbal motor overloaded . #/s
Normal	Normal (0.64)	Normal	2.45	#s check whether gimbal can rotate freely #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.64	#s gimbal pitch limit reached . #/s
Normal	Normal (0.54)	Normal	1.36	#s ground plain . #/s
Normal	Normal (0.64)	Normal	1.80	#s safe to land . #/s
ParamViolation	SurroundingEnvironment (0.44)	SurroundingEnvironment	1.84	#s high altitude . #/s
Normal	Normal (0.64)	Normal	2.12	#s aircraft braking distance increased and flight time decreased . #/s
Normal	Normal (0.64)	Normal	1.51	#s fly with caution #/s
	SurroundingEnvironment			#s high wind

SurroundingEnvironment	(0.47)	SurroundingEnvironment	1.67	velocity . #/s
Normal	Normal (0.64)	Normal	2.71	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.47)	SurroundingEnvironment	1.67	#s high wind velocity . #/s
Normal	Normal (0.64)	Normal	2.71	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.47)	SurroundingEnvironment	1.67	#s high wind velocity . #/s
Normal	Normal (0.64)	Normal	2.03	#s fly with caution and land in a safe place asap . #/s
Normal	SurroundingEnvironment (0.36)	SurroundingEnvironment	0.13	#s high - altitude flight #/s
Normal	Normal (0.64)	Normal	1.51	#s fly with caution #/s
Normal	Normal (0.64)	Normal	0.45	#s aircraft braking distance is extended #/s
Normal	Normal (0.60)	Normal	1.86	#s flight time is shortened . #/s
Normal	Normal (0.64)	Normal	1.26	#s home point updated . #/s
ParamViolation	Normal (0.64)	Normal	1.34	#s imu attitude restricted . #/s
Normal	Normal (0.64)	Normal	1.35	#s ensure aircraft is level #/s
SoftwareFault	Normal (0.64)	Normal	-1.84	#s imu not

				calibrated . #/s
Normal	Normal (0.64)	Normal	2.10	#s calibrate imu #/s
Normal	Normal (0.37)	Normal	0.69	#s landing canceled . #/s
Normal	Normal (0.64)	Normal	1.71	#s landing gear function restored #/s
Normal	Normal (0.64)	Normal	1.59	#s landing gear paused . #/s
Normal	Normal (0.64)	Normal	1.80	#s landing gear raising . #/s
Normal	Normal (0.64)	Normal	1.69	#s home point recorded #/s
Normal	Normal (0.33)	Normal	-0.37	#s live stream video frame rate less than 9hz . #/s
Normal	Normal (0.64)	Normal	1.51	#s fly with caution #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.31	#s low power . #/s
Normal	Normal (0.64)	Normal	2.17	#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.31	#s low power . #/s
Normal	Normal (0.64)	Normal	1.44	#s returning home . #/s
SurroundingEnvironment	SurroundingEnvironment (0.47)	SurroundingEnvironment	1.43	#s magnetic field interference . #/s
Normal	Normal (0.64)	Normal	2.02	#s exit p - gps mode . #/s
HardwareFault	HardwareFault (0.60)	HardwareFault	1.27	#s yaw error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.46)	SurroundingEnvironment	1.78	#s manned aircraft detected

				nearby . #/s
Normal	Normal (0.64)	Normal	1.51	#s fly with caution #/s
ParamViolation	Normal (0.34)	Normal	1.93	#s max altitude approached . #/s
Normal	Normal (0.64)	Normal	2.12	#s wait for the gps satellite signal recovery before ascend #/s
ParamViolation	ParamViolation (0.59)	ParamViolation	1.86	#s max flight altitude reached . #/s
Normal	Normal (0.64)	Normal	1.23	#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.59)	ParamViolation	1.79	#s max flight distance reached . #/s
Normal	Normal (0.64)	Normal	1.76	#s adjust in main controller settings if necessary . #/s
ParamViolation	ParamViolation (0.59)	ParamViolation	1.75	#s maximum flight distance reached . #/s
Normal	Normal (0.64)	Normal	1.90	#s adjust the distance in mc settings if required . #/s
HardwareFault	Normal (0.60)	Normal	0.78	#s mobile device cpu fully loaded . #/s
Normal	Normal (0.64)	Normal	1.85	#s related performance will be affected . #/s
				#s mobile

SoftwareFault	Normal (0.64)	Normal	0.73	device
				version too
				old to support
				hd image
				transmission
Normal	HardwareFault (0.60)	HardwareFault	-1.41	and the
				image
				transmission
				mode has
				been switch
HardwareFault	HardwareFault (0.60)	HardwareFault	1.15	to normal
				mode . #/s
				#s motor is
				blocked . #/s
				#s motor
Normal	Normal (0.64)	Normal	2.92	stuck . #/s
				#s check for
				objects
				blocking
				motor or
Normal	Normal (0.63)	Normal	1.44	contact dji
				support for
				assistance
				#/s
				#s motors
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	1.49	started . #/s
				#s no gps
				signal . #/s
				#s aircraft
				unable to
Normal	HardwareFault (0.58)	HardwareFault	-1.08	hover . #/s
				#s fly with
				caution #/s
				#s no gps
				signal . #/s
Normal	Normal (0.64)	Normal	1.51	#s fly with
				caution #/s
				#s obstacle
				avoidance
				disabled . #/s
Normal	Normal (0.64)	Normal	1.83	#s landing
				gear lowered
				. #/s
				#s obstacle
				avoidance
Normal	Normal (0.64)	Normal	1.77	disabled . #/s
				#s obstacle
				avoidance
				disabled . #/s
				#s obstacle
Normal	Normal (0.64)	Normal	1.83	avoidance
				disabled . #/s
				#s obstacle
				avoidance
				disabled . #/s

Normal	Normal (0.64)	Normal	1.83	#s obstacle avoidance disabled . #/s
Normal	Normal (0.64)	Normal	1.77	#s landing gear lowered . #/s
Normal	Normal (0.64)	Normal	1.83	#s obstacle avoidance has been disabled . #/s
Normal	Normal (0.63)	Normal	1.29	#s precision landing #/s
Normal	Normal (0.64)	Normal	1.30	#s quickshot has ended #/s
Normal	Normal (0.64)	Normal	2.31	#s recenter gimbal pan #/s
Normal	Normal (0.64)	Normal	1.62	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.48)	SurroundingEnvironment	1.53	#s remote controller in high interference environment . #/s
Normal	Normal (0.64)	Normal	1.16	#s manually adjust flight route or return to home #/s
Normal	Normal (0.64)	Normal	2.50	#s return - to - home altitude : 65ft #/s
Normal	Normal (0.64)	Normal	2.63	#s return - to - home altitude : 98ft . #/s
Normal	Normal (0.64)	Normal	1.58	#s rth : ascending to rth altitude . #/s
Normal	Normal (0.64)	Normal	1.63	#s rth : heading alignment . #/s

Normal	Normal (0.64)	Normal	1.04	#s rth altitude : 65ft . #/s
Normal	Normal (0.64)	Normal	2.18	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.39)	CommunicationIssue	1.33	#s signal lost . #/s
Normal	Normal (0.64)	Normal	1.89	#s aircraft returning to home point #/s
Normal	Normal (0.64)	Normal	1.89	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.47)	SurroundingEnvironment	1.69	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	1.34	#s aircraft unable to return to home automatically . #/s
Normal	Normal (0.64)	Normal	1.53	#s lower altitude immediately and return to home manually #/s
Normal	Normal (0.64)	Normal	1.63	#s switched to s ( sport ) - mode . #/s
Normal	Normal (0.64)	Normal	1.00	#s switched to t ( tripod ) - mode . #/s
Normal	Normal (0.64)	Normal	2.21	#s take off in p - mode #/s
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	0.95	#s vision sensor error . #/s
Normal	Normal (0.64)	Normal	1.93	#s contact dji support for assistance #/s
Normal	Normal (0.64)	Normal	1.91	#s vision systems and obstacle avoidance

Normal	Normal (0.64)	Normal	1.55	disabled #/s
				#s waypoint
				mission
SoftwareFault	SoftwareFault (0.57)	SoftwareFault	1.59	paused #/s
				#s weak gps
				signal . #/s
Normal	Normal (0.64)	Normal	2.49	#s aircraft is
				in attitude
				mode and
Normal	Normal (0.64)	Normal	1.56	hovering may
				be unstable .
				#/s
CommunicationIssue	CommunicationIssue (0.44)	CommunicationIssue	1.47	#s fly with
				caution . #/s
				#s weak
Normal	Normal (0.64)	Normal	0.86	signal . #/s
				#s adjust
				antennas #/s
RegulationViolation	RegulationViolation (0.37)	RegulationViolation	2.67	#s your
				aircraft is
				flying in an
Normal	Normal (0.64)	Normal	1.66	altitude zone
				( nnn ) . #/s
				#s please fly
Normal	Normal (0.64)	Normal	1.66	with caution
				#/s