

Legend: ■ Negative □ Neutral ■ Positive

| True Label | Predicted Label | Attribution Label | Attribution Score | Word Importance |
|------------------------|-----------------------|-------------------|-------------------|---|
| SurroundingEnvironment | Normal (0.64) | Normal | -0.69 | #s a passenger aircraft is nearby . #/s |
| Normal | Normal (0.64) | Normal | 1.11 | #s fly with caution #/s |
| Normal | Normal (0.62) | Normal | 1.46 | #s account not logged in . #/s |
| ParamViolation | ParamViolation (0.34) | ParamViolation | 1.64 | #s flight altitude and distance restricted to nnn and nnn . #/s |
| Normal | Normal (0.64) | Normal | 1.67 | #s check and log in #/s |
| Normal | Normal (0.64) | Normal | 2.00 | #s activetrack flight paused #/s |
| Normal | Normal (0.64) | Normal | 2.15 | #s aircraft activetrack available at max speed . #/s |
| Normal | Normal (0.64) | Normal | 1.72 | #s obstacle avoidance is not available #/s |
| Normal | Normal (0.64) | Normal | 2.15 | #s aircraft activetrack available at max speed . #/s |
| Normal | ParamViolation (0.32) | ParamViolation | -1.57 | #s when exceeding nnn , obstacle avoidance is not available #/s |
| Normal | Normal (0.64) | Normal | 2.67 | #s aircraft activetrack max speed of nnn and #/s |

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|---------------------|-----------------------------------|----------------------------|-------------|---|
| | | | | obstacle avoidance functions normally #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.31 | #s aircraft core board overheated #/s |
| Normal | Normal (0.64) | Normal | 2.21 | #s aircraft entered fixed - wing mode . #/s |
| Normal | Normal (0.64) | Normal | 2.06 | #s current flight speed is mnn . #/s |
| Normal | Normal (0.64) | Normal | 1.91 | #s press c2 to exit #/s |
| Normal | Normal (0.64) | Normal | 1.48 | #s aircraft flight control unlocked #/s |
| RegulationViolation | RegulationViolation (0.26) | RegulationViolation | 1.08 | #s aircraft in restricted zones . #/s |
| Normal | Normal (0.64) | Normal | 2.31 | #s check map to find recommended zones #/s |
| Normal | Normal (0.64) | Normal | 3.26 | #s aircraft is in attitude mode , so that it will not hover . #/s |
| Normal | Normal (0.64) | Normal | 1.11 | #s please fly with caution . #/s |
| Normal | Normal (0.64) | Normal | 1.94 | #s aircraft is in tripod mode . #/s |
| Normal | Normal (0.64) | Normal | 2.17 | #s exit this mode and try again #/s |
| Normal | Normal (0.64) | Normal | 2.01 | #s aircraft is returning to the starting point #/s |
| ParamViolation | ParamViolation (0.34) | ParamViolation | 0.13 | #s aircraft out of range #/s |

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| RegulationViolation | RegulationViolation (0.27) | RegulationViolation | 2.40 | #s approaching a no - fly zone . #/s |
| Normal | Normal (0.64) | Normal | 1.80 | #s rth may be affected . #/s |
| Normal | Normal (0.64) | Normal | 1.11 | #s fly with caution #/s |
| Normal | Normal (0.64) | Normal | 1.56 | #s arrived at start point . #/s |
| Normal | Normal (0.64) | Normal | 1.80 | #s starting waypoint mission #/s |
| Normal | Normal (0.64) | Normal | 1.48 | #s auto landing initiated #/s |
| Normal | Normal (0.64) | Normal | 0.81 | #s auxiliary bottom light turned off #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.87 | #s backward obstacle sensing is not functioning . #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.80 | #s battery cell broken , please replace the battery #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.33 | #s battery error . #/s |
| Normal | Normal (0.64) | Normal | 1.86 | #s aircraft returning to home automatically #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | -0.28 | #s battery power low . #/s |
| Normal | Normal (0.64) | Normal | 2.73 | #s check battery status and charge or warm up battery #/s |
| HardwareFault | HardwareFault (0.42) | HardwareFault | 1.19 | #s cache space full #/s |

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| SurroundingEnvironment | SoftwareFault (0.42) | SoftwareFault | 0.31 | #s calibration subject is too close . #/s |
| Normal | Normal (0.64) | Normal | 2.32 | #s recalibrate using a subject that is farther away #/s |
| HardwareFault | HardwareFault (0.43) | HardwareFault | 0.92 | #s camera busy , cannot enter playback #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.31 | #s cannot enable intelligent flight mode #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.44 | #s low battery #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | -0.93 | #s cannot start return to home due to weak gps signal #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 0.97 | #s cannot start self - timer . #/s |
| SoftwareFault | ParamViolation (0.34) | ParamViolation | 0.07 | #s exposure time is too long #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | -0.95 | #s cannot switch flight mode . #/s |
| Normal | Normal (0.64) | Normal | 2.56 | #s turn on " multiple flight modes " to enable atti and sport modes . #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.00 | #s cannot track subject #/s |
| SurroundingEnvironment | SoftwareFault (0.42) | SoftwareFault | 1.00 | #s no image #/s |
| Normal | Normal (0.64) | Normal | 0.97 | #s please retry #/s |
| | | | | #s cannot |

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|-------------------------------|-----------------------------|----------------------|-------------|--|
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.00 | track subject #/s |
| SurroundingEnvironment | SoftwareFault (0.42) | SoftwareFault | 1.56 | #s subject too large #/s |
| Normal | Normal (0.64) | Normal | 1.60 | #s move away and retry #/s |
| Normal | Normal (0.64) | Normal | 2.55 | #s color display in the liveview has been enhanced . #/s |
| Normal | Normal (0.64) | Normal | 1.74 | #s videos and photos will still be shot in d - log mode #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.40 | #s compass abnormal . #/s |
| Normal | Normal (0.64) | Normal | 2.98 | #s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s |
| Normal | Normal (0.64) | Normal | 2.31 | #s the ground or walls may contain metal . #/s |
| Normal | Normal (0.64) | Normal | 2.82 | #s move away from sources of interference before attempting flight . #/s |
| Normal | Normal (0.64) | Normal | 2.55 | #s 2 . calibrate compass before takeoff #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.63 | #s compass error #/s |
| | | | | #s compass |

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| HardwareFault | SoftwareFault (0.36) | SoftwareFault | 1.07 | error , calibration required #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.11 | #s compass error . #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.11 | #s compass error . #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.01 | #s compass disconnected #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.11 | #s compass error . #/s |
| | | | | #s magnetic |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 0.72 | filed interference . #/s |
| Normal | Normal (0.64) | Normal | 1.67 | #s exit p - gps mode #/s |
| SoftwareFault | HardwareFault (0.44) | HardwareFault | -0.52 | #s compass initialization failed . #/s |
| Normal | Normal (0.64) | Normal | 1.32 | #s restart aircraft #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.20 | #s critical low battery . #/s |
| | | | | #s aircraft in |
| Normal | Normal (0.64) | Normal | 2.10 | auto power off protection . #/s |
| Normal | Normal (0.64) | Normal | 1.58 | #s forced landing in progress #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.20 | #s critical low battery . #/s |
| | | | | #s aircraft landing automatically #/s |
| Normal | Normal (0.64) | Normal | 1.30 | #s critical low battery . #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.20 | #s return to home or land promptly #/s |
| Normal | Normal (0.64) | Normal | 1.91 | #s critically |

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| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.18 | low power . #/s |
| Normal | Normal (0.64) | Normal | 1.05 | #s aircraft is landing #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.18 | #s critically low power . #/s |
| Normal | Normal (0.64) | Normal | 0.60 | #s aircraft landing .#/s |
| Normal | Normal (0.64) | Normal | 0.60 | #s aircraft landing .#/s |
| | | | | #s throttle up to reduce the speed of |
| Normal | Normal (0.64) | Normal | 3.39 | descent and use sticks to avoid obstacles #/s |
| | | | | #s critically |
| HardwareFault | HardwareFault (0.44) | HardwareFault | -0.46 | low voltage warning .#/s |
| | | | | #s aircraft |
| Normal | Normal (0.64) | Normal | 2.13 | will be forced to land #/s |
| | | | | #s critically |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.81 | low voltage .#/s |
| | | | | #s aircraft |
| Normal | Normal (0.64) | Normal | 1.41 | will land #/s |
| | | | | #s data |
| Normal | Normal (0.64) | Normal | 1.58 | recorder file index is 15 .#/s |
| | | | | #s data |
| Normal | Normal (0.64) | Normal | 1.87 | recorder file index is 17 .#/s |
| | | | | #s data |
| Normal | Normal (0.64) | Normal | 1.26 | recorder file index is 30 .#/s |
| | | | | #s data |
| Normal | Normal (0.64) | Normal | 1.47 | recorder file index is 45 .#/s |
| | | | | #s data |
| Normal | Normal (0.64) | Normal | 1.12 | recorder file index is 46 . |

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| | | | | #/s |
| Normal | Normal (0.64) | Normal | 2.10 | #s data recorder file index is 65 . #/s |
| Normal | Normal (0.64) | Normal | 2.45 | #s disable sd card read and write protection or change card #/s |
| CommunicationIssue | CommunicationIssue (0.28) | CommunicationIssue | 1.68 | #s downlink lost . #/s |
| Normal | Normal (0.64) | Normal | 2.94 | #s downlink restored (after 0m 2 . 9s) . #/s |
| Normal | Normal (0.64) | Normal | 1.53 | #s drone is vibrating #/s |
| Normal | Normal (0.64) | Normal | 1.79 | #s entered cruise control mode . #/s |
| Normal | Normal (0.64) | Normal | 2.08 | #s press c1 or c2 to exit #/s |
| ParamViolation | ParamViolation (0.33) | ParamViolation | 1.72 | #s excessive attitude angle detected #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 2.00 | #s forward obstacle avoidance has stopped working #/s |
| Normal | Normal (0.64) | Normal | 0.16 | #s exit backward sensing system #/s |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.45 | #s ambient light is too weak #/s |
| Normal | Normal (0.64) | Normal | 1.78 | #s exited visual avoidance system . #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | -0.68 | #s exiting gps mode : unknown |

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| ParamViolation | ParamViolation (0.34) | ParamViolation | 1.82 | error #/s |
| Normal | Normal (0.64) | Normal | 1.72 | #s extra payload detected . #/s |
| Normal | Normal (0.64) | Normal | 1.11 | #s flight performance will be affected . #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.84 | #s fly with caution #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.49 | #s forward obstacle sensing is not functioning . #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 2.45 | #s forward obstacle sensing not responding #/s |
| Normal | Normal (0.64) | Normal | 2.29 | #s gimbal motor overloaded . #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.57 | #s check whether gimbal can rotate freely #/s |
| Normal | Normal (0.64) | Normal | 1.07 | #s gimbal pitch limit reached . #/s |
| Normal | Normal (0.64) | Normal | 1.68 | #s ground plain . #/s |
| ParamViolation | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.80 | #s safe to land . #/s |
| Normal | Normal (0.64) | Normal | 2.62 | #s high altitude . #/s |
| Normal | Normal (0.64) | Normal | 1.11 | #s aircraft braking distance increased and flight time decreased . #/s |
| | | SurroundingEnvironment | | #s fly with caution #/s |
| | | | | #s high wind |

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| SurroundingEnvironment | (0.36) | SurroundingEnvironment | 1.69 | velocity . #/s |
| Normal | Normal (0.64) | Normal | 3.26 | #s ensure the aircraft remains within your line of sight and fly with caution . #/s |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.69 | #s high wind velocity . #/s |
| Normal | Normal (0.64) | Normal | 3.26 | #s ensure the aircraft remains within your line of sight and fly with caution . #/s |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.69 | #s high wind velocity . #/s |
| Normal | Normal (0.64) | Normal | 1.97 | #s fly with caution and land in a safe place asap . #/s |
| Normal | Normal (0.64) | Normal | 1.77 | #s high - altitude flight #/s |
| Normal | Normal (0.64) | Normal | 1.11 | #s fly with caution #/s |
| Normal | Normal (0.63) | Normal | 1.18 | #s aircraft braking distance is extended #/s |
| Normal | Normal (0.64) | Normal | 1.02 | #s flight time is shortened . #/s |
| Normal | Normal (0.64) | Normal | 1.51 | #s home point updated . #/s |
| ParamViolation | SoftwareFault (0.42) | SoftwareFault | -1.58 | #s imu attitude restricted . #/s |
| Normal | Normal (0.64) | Normal | 1.20 | #s ensure aircraft is level #/s |
| SoftwareFault | Normal (0.64) | Normal | -1.37 | #s imu not |

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| | | | | | calibrated . |
| | | | | | #/s |
| Normal | Normal (0.64) | Normal | 1.74 | #s | calibrate |
| | | | | imu | #/s |
| Normal | Normal (0.64) | Normal | 0.33 | #s | landing |
| | | | | canceled | . #/s |
| Normal | Normal (0.64) | Normal | 1.83 | #s | landing |
| | | | | gear function | |
| Normal | Normal (0.64) | Normal | 1.46 | restored | #/s |
| | | | | #s | landing |
| Normal | Normal (0.64) | Normal | 1.72 | gear | paused . |
| | | | | #/s | |
| Normal | Normal (0.64) | Normal | 0.84 | #s | landing |
| | | | | gear | raising . |
| Normal | Normal (0.64) | Normal | 0.84 | #/s | |
| | | | | #s | home |
| Normal | Normal (0.64) | Normal | 0.84 | point | |
| | | | | recorded | #/s |
| Normal | ParamViolation (0.24) | ParamViolation | -1.50 | #s | live |
| | | | | stream | video |
| Normal | Normal (0.64) | Normal | 1.11 | frame rate | |
| | | | | less than | 9hz |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.42 | . #/s | |
| | | | | #s | fly with |
| Normal | Normal (0.64) | Normal | 1.70 | caution | #/s |
| | | | | #s | low power |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.42 | . #/s | |
| | | | | #s | aircraft is |
| Normal | Normal (0.64) | Normal | -0.42 | returning to | |
| | | | | the home | |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 0.72 | point | . #/s |
| | | | | #s | magnetic |
| Normal | Normal (0.64) | Normal | -0.15 | filed | |
| | | | | interference | . |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.65 | #/s | |
| | | | | #s | exit p - |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.30 | gps mode | . |
| | | | | #/s | |
| Normal | Normal (0.64) | Normal | -0.15 | #s | yaw error |
| | | | | . #/s | |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.30 | #s | manned |
| | | | | aircraft | |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.30 | detected | |

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|----------------|------------------------------|----------------|--------------|---|
| Normal | Normal (0.64) | Normal | 1.11 | nearby . #/s #s fly with caution #/s |
| ParamViolation | ParamViolation (0.31) | ParamViolation | 1.12 | #s max altitude approached . #/s #s wait for the gps satellite |
| Normal | Normal (0.64) | Normal | 1.74 | #s signal recovery before ascend #/s |
| ParamViolation | ParamViolation (0.34) | ParamViolation | 1.46 | #s max flight altitude reached . #/s #s adjust in main |
| Normal | Normal (0.64) | Normal | -0.09 | controller settings if necessary #/s #s max flight distance reached . #/s |
| ParamViolation | ParamViolation (0.34) | ParamViolation | 0.42 | #s adjust in main controller settings if necessary . #/s #s maximum flight distance reached . #/s |
| Normal | Normal (0.64) | Normal | 1.34 | #s mc settings if required . #/s #s mobile device cpu fully loaded . #/s #s related performance will be affected . #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | 1.92 | #s mobile |
| Normal | Normal (0.64) | Normal | 1.58 | |

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| SoftwareFault | Normal (0.47) | Normal | -0.40 | device version too old to support hd image transmission and the image transmission mode has been switch to normal mode . #/s |
| Normal | Normal (0.64) | Normal | 1.12 | #s motor is blocked . #/s |
| HardwareFault | HardwareFault (0.44) | HardwareFault | -0.12 | #s motor stuck . #/s |
| Normal | Normal (0.64) | Normal | 1.39 | #s check for objects blocking motor or contact dji support for assistance #/s |
| Normal | Normal (0.64) | Normal | 0.70 | #s motors started . #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.57 | #s no gps signal . #/s |
| Normal | HardwareFault (0.44) | HardwareFault | 0.53 | #s aircraft unable to hover . #/s |
| Normal | Normal (0.64) | Normal | 1.11 | #s fly with caution #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.57 | #s no gps signal . #/s |
| Normal | HardwareFault (0.44) | HardwareFault | -1.30 | #s unable to hover . #/s |
| Normal | Normal (0.64) | Normal | 1.11 | #s fly with caution #/s |
| Normal | Normal (0.64) | Normal | 1.40 | #s obstacle avoidance disabled . #/s |
| Normal | Normal (0.64) | Normal | 1.52 | #s landing gear lowered . #/s |
| Normal | Normal (0.64) | Normal | 1.40 | #s obstacle avoidance disabled . #/s |

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|------------------------|--------------------------------------|------------------------|-------------|---|
| Normal | Normal (0.64) | Normal | 1.40 | #s obstacle avoidance disabled . #/s |
| Normal | Normal (0.64) | Normal | 1.52 | #s landing gear lowered . #/s |
| Normal | Normal (0.64) | Normal | 1.57 | #s obstacle avoidance has been disabled . #/s |
| Normal | Normal (0.64) | Normal | 1.04 | #s precision landing #/s |
| Normal | Normal (0.64) | Normal | 0.96 | #s quickshot has ended #/s |
| Normal | Normal (0.64) | Normal | 2.13 | #s recenter gimbal pan #/s |
| Normal | Normal (0.64) | Normal | 2.15 | #s rectifying aircraft position #/s |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.90 | #s remote controller in high interference environment . #/s |
| Normal | Normal (0.64) | Normal | 2.46 | #s manually adjust flight route or return to home #/s |
| Normal | Normal (0.64) | Normal | 2.16 | #s return - to - home altitude : 65ft #/s |
| Normal | Normal (0.64) | Normal | 2.30 | #s return - to - home altitude : 98ft . #/s |
| Normal | Normal (0.64) | Normal | 1.48 | #s rth : ascending to rth altitude . #/s |
| Normal | Normal (0.64) | Normal | 1.82 | #s rth : heading alignment . #/s |

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|------------------------|--------------------------------------|------------------------|--------------|--|
| Normal | Normal (0.64) | Normal | 2.08 | #s rth altitude : 65ft . #/s |
| Normal | Normal (0.64) | Normal | 2.19 | #s rth altitude : 98ft . #/s |
| CommunicationIssue | CommunicationIssue (0.28) | CommunicationIssue | 1.27 | #s signal lost . #/s |
| Normal | Normal (0.64) | Normal | 1.89 | #s aircraft returning to home point . #/s |
| Normal | Normal (0.64) | Normal | 1.35 | #s sprayer turned on #/s |
| SurroundingEnvironment | SurroundingEnvironment (0.36) | SurroundingEnvironment | 1.93 | #s strong wind warning . #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | -1.91 | #s aircraft unable to return to home automatically . #/s |
| Normal | Normal (0.64) | Normal | 1.64 | #s lower altitude immediately and return to home manually #/s |
| Normal | Normal (0.64) | Normal | 1.49 | #s switched to s (sport) - mode . #/s |
| Normal | Normal (0.64) | Normal | 2.46 | #s switched to t (tripod) - mode . #/s |
| Normal | Normal (0.64) | Normal | -2.07 | #s take off in p - mode #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.16 | #s vision sensor error . . #/s |
| Normal | Normal (0.64) | Normal | 2.27 | #s contact dji support for assistance . #/s |
| Normal | Normal (0.64) | Normal | 2.21 | #s vision systems and obstacle avoidance |

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| Normal | Normal (0.64) | Normal | 1.41 | disabled #/s #s waypoint mission paused #/s |
| SoftwareFault | SoftwareFault (0.42) | SoftwareFault | 1.30 | #s weak gps signal . #/s #s aircraft is in attitude mode and hovering may be unstable . #/s |
| Normal | Normal (0.64) | Normal | -1.00 | #s aircraft is in attitude mode and hovering may be unstable . #/s |
| Normal | Normal (0.64) | Normal | 0.38 | #s fly with caution . #/s |
| CommunicationIssue | CommunicationIssue (0.28) | CommunicationIssue | -1.42 | #s weak signal . #/s |
| Normal | Normal (0.64) | Normal | 1.15 | #s adjust antennas #/s #s your aircraft is |
| RegulationViolation | RegulationViolation (0.26) | RegulationViolation | 2.86 | flying in an altitude zone (nnn) . #/s #s please fly |
| Normal | Normal (0.64) | Normal | -1.11 | with caution #/s |