

Legend: ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
SurroundingEnvironment	Normal (0.44)	Normal	-0.16	#s <span style="background-color: #d9ead3;">a</span>
				passenger
				aircraft is <span style="background-color: #f4cccc;">nearby</span> . #/s
Normal	Normal (0.43)	Normal	1.69	#s <span style="background-color: #d9ead3;">fly</span> with <span style="background-color: #d9ead3;">caution</span> #/s
Normal	Normal (0.44)	Normal	1.64	#s <span style="background-color: #d9ead3;">account</span> not <span style="background-color: #d9ead3;">logged</span> in . #/s
ParamViolation	ParamViolation (0.83)	ParamViolation	1.48	#s flight altitude and distance <span style="background-color: #d9ead3;">restricted</span> to nnn and nnn . #/s
				#s <span style="background-color: #d9ead3;">check</span> and <span style="background-color: #d9ead3;">log</span> in #/s
				#s <span style="background-color: #d9ead3;">activetrack</span>
Normal	Normal (0.44)	Normal	1.37	flight paused #/s
Normal	Normal (0.44)	Normal	2.21	#s aircraft <span style="background-color: #d9ead3;">activetrack</span> <span style="background-color: #d9ead3;">available</span> at <span style="background-color: #d9ead3;">max</span> speed . #/s
				#s <span style="background-color: #f4cccc;">obstacle</span> <span style="background-color: #d9ead3;">avoidance</span> is <span style="background-color: #d9ead3;">not</span> available #/s
				#s aircraft <span style="background-color: #d9ead3;">activetrack</span> <span style="background-color: #d9ead3;">available</span> at <span style="background-color: #d9ead3;">max</span> speed . #/s
Normal	ParamViolation (0.83)	ParamViolation	-0.05	#s when <span style="background-color: #f4cccc;">exceeding</span> nnn , <span style="background-color: #d9ead3;">obstacle</span> <span style="background-color: #f4cccc;">avoidance</span> is <span style="background-color: #f4cccc;">not</span> available #/s
Normal	Normal (0.44)	Normal	1.99	#s <span style="background-color: #f4cccc;">aircraft</span> <span style="background-color: #d9ead3;">activetrack</span> <span style="background-color: #d9ead3;">max</span> speed of <span style="background-color: #d9ead3;">nnn</span> and

HardwareFault	HardwareFault (0.74)	HardwareFault	1.64	obstacle avoidance functions normally #/s #s aircraft core board overheated #/s
				#s aircraft entered fixed wing mode . #/s
				#s current flight speed is nnn . #/s
				#s press c2 to exit #/s
				#s aircraft flight control unlocked #/s
RegulationViolation	RegulationViolation (0.72)	RegulationViolation	1.18	#s aircraft in restricted zones . #/s
Normal	Normal (0.44)	Normal	1.67	#s check map to find recommended zones #/s
Normal	Normal (0.44)	Normal	2.89	#s aircraft is in attitude mode , so that it will not hover . #/s
Normal	Normal (0.43)	Normal	0.91	#s please fly with caution . #/s
Normal	Normal (0.44)	Normal	1.55	#s aircraft is in tripod mode . #/s
Normal	Normal (0.44)	Normal	1.99	#s exit this mode and try again #/s
Normal	Normal (0.44)	Normal	1.68	#s aircraft is returning to the starting point #/s
ParamViolation	ParamViolation (0.83)	ParamViolation	2.10	#s aircraft out of range #/s

RegulationViolation	RegulationViolation (0.72)	RegulationViolation	2.18	#s approaching a no - fly zone . #/s
Normal	Normal (0.44)	Normal	1.31	#s rth may be affected . #/s
Normal	Normal (0.43)	Normal	1.69	#s fly with caution #/s
Normal	Normal (0.44)	Normal	1.86	#s arrived at start point . #/s
Normal	Normal (0.44)	Normal	1.57	#s starting waypoint mission #/s
Normal	Normal (0.43)	Normal	-0.34	#s auto landing initiated #/s
Normal	Normal (0.44)	Normal	1.65	#s auxiliary bottom light turned off #/s
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.66	#s backward obstacle sensing is not functioning . #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	0.27	#s battery cell broken , please replace the battery #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.17	#s battery error . #/s
Normal	Normal (0.44)	Normal	1.64	#s aircraft returning to home automatically #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.62	#s battery power low . #/s
Normal	Normal (0.44)	Normal	2.38	#s check battery status and charge or warm up battery #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.64	#s cache space full #/s

SurroundingEnvironment	SoftwareFault (0.76)	SoftwareFault	2.02	#s calibration subject is too close . #/s
Normal	Normal (0.44)	Normal	1.96	#s recalibrate using a subject that is farther away #/s
HardwareFault	HardwareFault (0.75)	HardwareFault	1.72	#s camera busy , cannot enter playback #/s
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.85	#s cannot enable intelligent flight mode #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.46	#s low battery #/s
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.19	#s cannot start return to home due to weak gps signal #/s
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.51	#s cannot start self - timer . #/s
SoftwareFault	ParamViolation (0.83)	ParamViolation	-0.15	#s exposure time is too long #/s
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.21	#s cannot switch flight mode . #/s
Normal	Normal (0.44)	Normal	1.60	#s turn on " multiple flight modes " to enable atti and sport modes . #/s
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.41	#s cannot track subject #/s
SurroundingEnvironment	SoftwareFault (0.76)	SoftwareFault	1.13	#s no image #/s
Normal	Normal (0.44)	Normal	1.39	#s please retry #/s
				#s cannot

SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.41	track subject #/s
SurroundingEnvironment	SoftwareFault (0.76)	SoftwareFault	0.72	#s subject too large #/s
Normal	Normal (0.44)	Normal	1.97	#s move away and retry #/s
Normal	Normal (0.44)	Normal	2.42	#s color display in the liveview has been enhanced . #/s
Normal	Normal (0.44)	Normal	2.49	#s videos and photos will still be shot in d - log mode #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.51	#s compass abnormal . #/s
Normal	Normal (0.44)	Normal	3.58	#s solution : 1 . ensure there are no magnets or metal objects near the aircraft . #/s
Normal	Normal (0.44)	Normal	0.28	#s the ground or walls may contain metal . #/s
Normal	Normal (0.44)	Normal	1.66	#s move away from sources of interference before attempting flight . #/s
Normal	Normal (0.44)	Normal	-0.14	#s 2 calibrate compass before takeoff #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.50	#s compass error #/s #s compass

HardwareFault	HardwareFault (0.74)	HardwareFault	0.68	error , calibration required #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.49	#s compass error . #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.49	#s compass error . #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.49	#s compass disconnected #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.49	#s compass error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.78)	SurroundingEnvironment	1.31	#s magnetic filed interference . #/s
Normal	Normal (0.44)	Normal	1.70	#s exit p - gps mode #/s
SoftwareFault	HardwareFault (0.74)	HardwareFault	-0.16	#s compass initialization failed . #/s
Normal	Normal (0.43)	Normal	1.25	#s restart aircraft #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.22	#s critical low battery . #/s
Normal	Normal (0.44)	Normal	1.49	#s aircraft in auto power off protection . #/s
Normal	Normal (0.44)	Normal	1.62	#s forced landing in progress #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.22	#s critical low battery . #/s
Normal	Normal (0.44)	Normal	1.55	#s aircraft landing automatically #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.22	#s critical low battery . #/s
Normal	Normal (0.44)	Normal	1.69	#s return to home or land promptly #/s
				#s critically

HardwareFault	HardwareFault (0.74)	HardwareFault	1.47	low power. #/s
Normal	Normal (0.43)	Normal	1.49	#s aircraft is landing #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.47	#s critically low power. #/s
Normal	Normal (0.43)	Normal	1.25	#s aircraft landing. #/s
Normal	Normal (0.43)	Normal	1.25	#s aircraft landing. #/s
Normal	Normal (0.44)	Normal	1.79	#s throttle up to reduce the speed of descent and use sticks to avoid obstacles #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	2.09	#s critically low voltage warning. #/s
Normal	Normal (0.44)	Normal	1.47	#s aircraft will be forced to land #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.81	#s critically low voltage. #/s
Normal	Normal (0.43)	Normal	1.50	#s aircraft will land #/s
Normal	Normal (0.44)	Normal	2.19	#s data recorder file index is 15. #/s
Normal	Normal (0.44)	Normal	1.76	#s data recorder file index is 17. #/s
Normal	Normal (0.44)	Normal	1.86	#s data recorder file index is 30. #/s
Normal	Normal (0.44)	Normal	1.69	#s data recorder file index is 45. #/s
Normal	Normal (0.44)	Normal	1.77	#s data recorder file index is 46. #/s

				#/s
				#s data recorder file index is 65 .
Normal	Normal (0.44)	Normal	2.01	#/s
				#s disable sd card read and write protection or change card
Normal	Normal (0.44)	Normal	2.15	#/s
CommunicationIssue	CommunicationIssue (0.81)	CommunicationIssue	0.99	#s downlink lost . #/s
				#s downlink restored ( after 0m 2 9s ) . #/s
Normal	Normal (0.44)	Normal	0.49	#s drone is vibrating #/s
Normal	Normal (0.43)	Normal	1.42	#s entered cruise control mode . #/s
Normal	Normal (0.44)	Normal	1.86	#s press c1 or c2 to exit #/s
ParamViolation	ParamViolation (0.83)	ParamViolation	-0.64	#s excessive attitude angle detected #/s
				#s forward obstacle avoidance has stopped working #/s
SoftwareFault	SoftwareFault (0.73)	SoftwareFault	1.29	#s exit backward sensing system #/s
Normal	Normal (0.44)	Normal	1.57	#s ambient light is too weak #/s
SurroundingEnvironment	SurroundingEnvironment (0.78)	SurroundingEnvironment	1.35	#s exited visual avoidance system . #/s
Normal	Normal (0.43)	Normal	1.19	#s exiting gps mode : unknown
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	0.99	



ParamViolation	ParamViolation (0.83)	ParamViolation	-1.57	error #/s
				#s extra
				payload detected . #/s
Normal	Normal (0.44)	Normal	1.55	#s flight
				performance
				will be affected . #/s
Normal	Normal (0.43)	Normal	1.69	#s fly with
				caution #/s
				#s forward
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	2.05	obstacle
				sensing is not functioning .
				#/s
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.82	#s forward
				obstacle
				sensing not responding
HardwareFault	HardwareFault (0.74)	HardwareFault	1.98	#/s
				#s gimbal
				motor overloaded .
Normal	Normal (0.44)	Normal	2.12	#/s
				#s check
				whether
HardwareFault	HardwareFault (0.74)	HardwareFault	1.38	gimbal can
				rotate freely
				#/s
Normal	Normal (0.43)	Normal	1.39	#s gimbal
				pitch limit
				reached . #/s
Normal	Normal (0.43)	Normal	1.70	#s ground
				plain . #/s
				#s safe to
ParamViolation	SurroundingEnvironment (0.77)	SurroundingEnvironment	1.23	land . #/s
				#s high
				altitude . #/s
Normal	Normal (0.44)	Normal	1.63	#s aircraft
				braking
				distance
Normal	Normal (0.43)	Normal	1.69	increased and
				flight time
				decreased .
SurroundingEnvironment	SurroundingEnvironment	SurroundingEnvironment		#/s
				#s fly with
				caution #/s
SurroundingEnvironment	SurroundingEnvironment	SurroundingEnvironment		#s high
				wind

SurroundingEnvironment	(0.77)	SurroundingEnvironment	-0.72	velocity . #/s
Normal	Normal (0.44)	Normal	2.23	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.77)	SurroundingEnvironment	-0.72	#s high wind velocity . #/s
Normal	Normal (0.44)	Normal	2.23	#s ensure the aircraft remains within your line of sight and fly with caution . #/s
SurroundingEnvironment	SurroundingEnvironment (0.77)	SurroundingEnvironment	-0.72	#s high wind velocity . #/s
Normal	Normal (0.44)	Normal	2.79	#s fly with caution and land in a safe place asap . #/s
Normal	Normal (0.44)	Normal	-0.70	#s high - altitude flight #/s
Normal	Normal (0.43)	Normal	1.69	#s fly with caution #/s
Normal	Normal (0.44)	Normal	1.46	#s aircraft braking distance is extended #/s
Normal	Normal (0.44)	Normal	1.96	#s flight time is shortened . #/s
Normal	Normal (0.43)	Normal	1.57	#s home point updated . #/s
ParamViolation	ParamViolation (0.35)	ParamViolation	0.02	#s imu attitude restricted . #/s
Normal	Normal (0.44)	Normal	0.81	#s ensure aircraft is level #/s
SoftwareFault	Normal (0.44)	Normal	0.31	#s imu not

				calibrated . #/s
Normal	Normal (0.44)	Normal	1.70	#s calibrate imu #/s
Normal	Normal (0.43)	Normal	1.25	#s landing canceled . #/s
Normal	Normal (0.44)	Normal	1.73	#s landing gear function restored #/s
Normal	Normal (0.43)	Normal	1.80	#s landing gear paused . #/s
Normal	Normal (0.43)	Normal	1.33	#s landing gear raising . #/s
Normal	Normal (0.43)	Normal	1.41	#s home point recorded #/s
Normal	ParamViolation (0.64)	ParamViolation	-0.78	#s live stream video frame rate less than 9hz . #/s
Normal	Normal (0.43)	Normal	1.69	#s fly with caution #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.51	#s low power . #/s
Normal	Normal (0.44)	Normal	1.99	#s aircraft is returning to the home point . #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.51	#s low power . #/s
Normal	Normal (0.43)	Normal	1.44	#s returning home . #/s
SurroundingEnvironment	SurroundingEnvironment (0.78)	SurroundingEnvironment	1.31	#s magnetic field interference . #/s
Normal	Normal (0.43)	Normal	2.32	#s exit p - gps mode . #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.78	#s yaw error . #/s
SurroundingEnvironment	SurroundingEnvironment (0.78)	SurroundingEnvironment	0.64	#s manned aircraft detected

				nearby . #/s
Normal	Normal (0.43)	Normal	1.69	#s fly with caution #/s
ParamViolation	ParamViolation (0.83)	ParamViolation	1.21	#s max altitude approached . #/s
Normal	Normal (0.44)	Normal	2.18	#s wait for the gps satellite signal recovery before ascend #/s
ParamViolation	ParamViolation (0.83)	ParamViolation	1.38	#s max flight altitude reached . #/s
Normal	Normal (0.44)	Normal	2.50	#s adjust in main controller settings if necessary #/s
ParamViolation	ParamViolation (0.83)	ParamViolation	2.05	#s max flight distance reached . #/s
Normal	Normal (0.44)	Normal	1.09	#s adjust in main controller settings if necessary . #/s
ParamViolation	ParamViolation (0.83)	ParamViolation	1.58	#s maximum flight distance reached . #/s
Normal	Normal (0.44)	Normal	2.26	#s adjust the distance in mc settings if required . #/s
HardwareFault	HardwareFault (0.74)	HardwareFault	1.93	#s mobile device cpu fully loaded . #/s
Normal	Normal (0.44)	Normal	1.65	#s related performance will be affected . #/s
				#s mobile

SoftwareFault	Normal (0.42)	Normal	-2.49	device
				version too
				old to support
				hd image
				transmission
Normal	Normal (0.43)	Normal	0.64	and the
				image
				transmission
				mode has
				been switch
HardwareFault	HardwareFault (0.74)	HardwareFault	1.39	to normal
				mode . #/s
				#s motor is
				blocked . #/s
				#s motor
Normal	Normal (0.44)	Normal	-0.68	stuck . #/s
				#s check for
				objects
				blocking
				motor or
Normal	Normal (0.43)	Normal	1.48	contact dji
				support for
				assistance
				#/s
				#s motors
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.82	started . #/s
				#s no gps
				signal . #/s
				#s aircraft
				unable to
Normal	HardwareFault (0.74)	HardwareFault	-0.64	hover . #/s
				#s fly with
				caution #/s
				#s no gps
				signal . #/s
Normal	Normal (0.43)	Normal	1.69	#s obstacle
				avoidance
				disabled . #/s
				#s landing
				gear lowered
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	1.82	. #/s
				#s obstacle
				avoidance
				disabled . #/s
Normal	Normal (0.43)	Normal	1.70	
Normal	Normal (0.43)	Normal	1.84	
Normal	Normal (0.43)	Normal	1.70	

Normal	Normal (0.43)	Normal	1.70	#s obstacle avoidance disabled . #/s
Normal	Normal (0.43)	Normal	1.84	#s landing gear lowered . #/s
Normal	Normal (0.44)	Normal	1.75	#s obstacle avoidance has been disabled . #/s
Normal	Normal (0.43)	Normal	1.26	#s precision landing #/s
Normal	Normal (0.44)	Normal	1.56	#s quickshot has ended #/s
Normal	Normal (0.44)	Normal	2.06	#s recenter gimbal pan #/s
Normal	Normal (0.44)	Normal	1.36	#s rectifying aircraft position #/s
SurroundingEnvironment	SurroundingEnvironment (0.78)	SurroundingEnvironment	2.09	#s remote controller in high interference environment . #/s
Normal	Normal (0.44)	Normal	2.53	#s manually adjust flight route or return to home #/s
Normal	Normal (0.44)	Normal	1.83	#s return - to - home altitude : 65ft #/s
Normal	Normal (0.44)	Normal	1.65	#s return - to - home altitude : 98ft . #/s
Normal	Normal (0.44)	Normal	2.19	#s rth : ascending to rth altitude . #/s
Normal	Normal (0.44)	Normal	2.04	#s rth : heading alignment . #/s

Normal	Normal (0.44)	Normal	0.57	#s rth altitude : 65ft . #/s
Normal	Normal (0.44)	Normal	1.35	#s rth altitude : 98ft . #/s
CommunicationIssue	CommunicationIssue (0.81)	CommunicationIssue	1.06	#s signal lost . #/s
Normal	Normal (0.44)	Normal	-1.28	#s aircraft returning to home point #/s
Normal	Normal (0.44)	Normal	1.76	#s sprayer turned on #/s
SurroundingEnvironment	SurroundingEnvironment (0.77)	SurroundingEnvironment	1.26	#s strong wind warning . #/s
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	2.11	#s aircraft unable to return to home automatically . #/s
Normal	Normal (0.44)	Normal	1.42	#s lower altitude immediately and return to home manually #/s
Normal	Normal (0.44)	Normal	2.42	#s switched to s ( sport ) - mode . #/s
Normal	Normal (0.44)	Normal	2.13	#s switched to t ( tripod ) - mode . #/s
Normal	Normal (0.44)	Normal	1.89	#s take off in p - mode #/s
SoftwareFault	HardwareFault (0.74)	HardwareFault	0.02	#s vision sensor error . #/s
Normal	Normal (0.44)	Normal	1.76	#s contact dji support for assistance #/s
Normal	Normal (0.44)	Normal	2.12	#s vision systems and obstacle avoidance

Normal	Normal (0.44)	Normal	1.46	disabled #/s
				#s waypoint
				mission
SoftwareFault	SoftwareFault (0.76)	SoftwareFault	0.33	paused #/s
				#s weak gps
				signal . #/s
Normal	Normal (0.44)	Normal	0.85	#s aircraft is
				in attitude
				mode and
Normal	Normal (0.43)	Normal	0.98	hovering may
				be unstable .
				#/s
CommunicationIssue	CommunicationIssue (0.81)	CommunicationIssue	1.17	#s fly with
				caution . #/s
				#s weak
Normal	Normal (0.43)	Normal	1.49	signal . #/s
				#s adjust
				antennas #/s
RegulationViolation	RegulationViolation (0.72)	RegulationViolation	2.18	#s your
				aircraft is
				flying in an
Normal	Normal (0.44)	Normal	1.40	altitude zone
				( nnn ) . #/s
				#s please fly
Normal	Normal (0.44)	Normal	1.40	with caution
				#/s