

**Legend:** ■ Negative □ Neutral ■ Positive

True Label	Predicted Label	Attribution Label	Attribution Score	Word Importance
None	<b>Normal (1.00)</b>	Normal	<b>0.17</b>	[CLS] motors starting [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.64</b>	[CLS] flight mode changed to starting motors [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] data recorder file index is 89 . [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.40</b>	[CLS] set return to home ( rth ) altitude to 100 m ( 328 ft ) [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>-1.61</b>	[CLS] set maximum flight altitude to 500 m ( 1640 ft ) [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.87</b>	[CLS] flight mode changed to manual takeoff [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>1.50</b>	[CLS] flight mode changed to p - gps [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.55</b>	[CLS] home point updated [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>-0.31</b>	[CLS] rth altitude adjusted to 100m [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.55</b>	[CLS] home point updated [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>-0.31</b>	[CLS] rth altitude adjusted to 100m [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.55</b>	[CLS] home point updated [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>-0.31</b>	[CLS] rth altitude adjusted to 100m [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	Normal	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	SurroundingEnvironment	<b>1.75</b>	[CLS] ambient light too low [SEP]

None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.55</b>	[CLS] home point updated [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.31</b>	[CLS] rth altitude adjusted to 100m [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]

<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] aircraft braking [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.43</b>	[CLS] aircraft will follow preset action for lost signal [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.73</b>	[CLS] image transmission signal weak [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.01</b>	[CLS] adjust antennas and make sure they are perpendicular to flight direction of aircraft [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.75</b>	[CLS] image transmission signal lost [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.21</b>	[CLS] downlink restored ( after 0m

				22 . 8s ) [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.86</b>	[CLS] flight mode changed to go home [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.61</b>	[CLS] failsafe rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.22</b>	[CLS] press brake button to cancel rth [SEP]
None	<b>SoftwareFault (0.79)</b>	<b>SoftwareFault</b>	<b>0.88</b>	[CLS] no image transmission [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.05</b>	[CLS] aircraft returning to home [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.05</b>	[CLS] returning to home [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.99</b>	[CLS] aircraft and remote controller disconnected [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.61</b>	[CLS] failsafe rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.22</b>	[CLS] press brake button to cancel rth [SEP]
None	<b>SoftwareFault (0.79)</b>	<b>SoftwareFault</b>	<b>0.88</b>	[CLS] no image transmission [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.05</b>	[CLS] aircraft returning to home [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.05</b>	[CLS] returning to home [SEP]
None	<b>HardwareFault (0.99)</b>	<b>HardwareFault</b>	<b>1.99</b>	[CLS] aircraft and remote controller disconnected [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] rth ascending [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.61</b>	[CLS] failsafe rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.22</b>	[CLS] press brake button to cancel rth [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.05</b>	[CLS] returning to home [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]

None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p - gps [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	1.75	[CLS] ambient light too low [SEP]

<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] aircraft braking [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.43</b>	[CLS] aircraft will follow preset action for lost signal [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.32</b>	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] aircraft braking [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.43</b>	[CLS] aircraft will follow preset action for lost signal [SEP]
<b>None</b>	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.32</b>	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]

None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] aircraft braking [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.43</b>	[CLS] aircraft will follow preset action for lost signal [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.32</b>	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] aircraft braking [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.43</b>	[CLS] aircraft will follow preset action for lost signal [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.13</b>	[CLS] downward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>2.01</b>	[CLS] forward ambient light too low [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.23</b>	[CLS] fly with caution [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.61</b>	[CLS] failsafe rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.86</b>	[CLS] flight mode changed to go home [SEP]

None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	Normal (1.00)	Normal	-1.34	[CLS] original route rth [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	-1.34	[CLS] original route rth [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance unavailable [SEP]
None	Normal (1.00)	Normal	0.23	[CLS] fly with caution [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	SurroundingEnvironment (0.99)	SurroundingEnvironment	2.13	[CLS] downward ambient light too low [SEP]
None	Normal (1.00)	Normal	0.13	[CLS] obstacle avoidance

None	Normal (1.00)	Normal	0.23	unavailable [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] fly with caution [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] failsafe rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] press brake button to cancel rth [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p-gps [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]

None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.86	[CLS] flight mode changed to go home [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	-1.34	[CLS] original route rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	-1.34	[CLS] original route rth [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]

None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.32</b>	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.21</b>	[CLS] rth in progress [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.61</b>	[CLS] failsafe rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.22</b>	[CLS] press brake button to cancel rth [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.05</b>	[CLS] returning to home [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.32</b>	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.21</b>	[CLS] rth in progress [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.27</b>	[CLS] rth ascending [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.01</b>	[CLS] controller triggered aircraft to descend [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.32</b>	[CLS] auto rth canceled [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.50</b>	[CLS] flight mode changed to gps [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.61</b>	[CLS] failsafe rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.01</b>	[CLS] controller triggered aircraft to descend [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.32</b>	[CLS] auto rth canceled [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.05</b>	[CLS] returning to home [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.32</b>	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.61</b>	[CLS] failsafe rth [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>-0.01</b>	[CLS] controller triggered aircraft to descend [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.32</b>	[CLS] auto rth canceled [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
None	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.32</b>	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.53</b>	[CLS] rc signal lost [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]
None	<b>CommunicationIssue (0.97)</b>	<b>CommunicationIssue</b>	<b>1.52</b>	[CLS] rc signal weak [SEP]

None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.86	[CLS] flight mode changed to go home [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	-1.34	[CLS] original route rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]

None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to gps [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.73	[CLS] image transmission signal weak [SEP]
None	Normal (1.00)	Normal	-0.07	[CLS] downlink restored ( after 0m 16s ) [SEP]
None	Normal (1.00)	Normal	0.86	[CLS] flight mode changed to go

None	Normal (1.00)	Normal	-0.61	home [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] failsafe rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] press brake button to cancel rth [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	-1.34	[CLS] original route rth [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.61	

None	Normal (1.00)	Normal	-0.01	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] controller triggered aircraft to descend [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] auto rth canceled [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] rc signal lost [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p-gps [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	0.27	

None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] aircraft braking [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] rc signal weak [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] rc signal lost [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] aircraft will follow preset action for lost signal [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rc signal lost [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] aircraft braking [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] rc signal lost [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] aircraft will follow preset action for lost signal [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	0.86	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] flight mode changed to go home [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	Normal (1.00)	Normal	-1.34	[CLS] original route rth [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	0.22	[CLS] press brake button to cancel rth [SEP]
None	CommunicationIssue	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]

	(0.97)			
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.21	[CLS] rth in progress [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	Normal (1.00)	Normal	1.50	[CLS] flight mode changed to p - gps [SEP]
None	Normal (1.00)	Normal	-0.61	[CLS] failsafe rth [SEP]
None	Normal (1.00)	Normal	-0.01	[CLS] controller triggered aircraft to descend [SEP]
None	Normal (1.00)	Normal	0.32	[CLS] auto rth canceled [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.05	[CLS] returning to home [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] rth ascending [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	0.27	[CLS] aircraft braking [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.53	[CLS] rc signal lost [SEP]
None	Normal (1.00)	Normal	-0.43	[CLS] aircraft will follow preset action for lost signal [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	Normal (1.00)	Normal	1.32	[CLS] avoid blocking antennas and adjust antenna orientation [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]
None	CommunicationIssue (0.97)	CommunicationIssue	1.52	[CLS] rc signal weak [SEP]



<b>None</b>	<b>(0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.07</b>	[CLS] flight mode changed to confirm landing [SEP]
<b>None</b>	<b>SurroundingEnvironment (0.99)</b>	<b>SurroundingEnvironment</b>	<b>1.75</b>	[CLS] ambient light too low [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.13</b>	[CLS] obstacle avoidance unavailable [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.16</b>	[CLS] auto landing in progress [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>0.16</b>	[CLS] auto landing in progress [SEP]
<b>None</b>	<b>Normal (1.00)</b>	<b>Normal</b>	<b>1.50</b>	[CLS] flight mode changed to p - gps [SEP]