

SWAROOP. S. JADHAV

Stepper Motor AntiClockwise

1.

#include <stdio.h>

#include <reg51.h>

char xdata port_a = 0x80;

char xdata dt = 0x800;

char xdata au = 0x30;

delay(1);

{

int i;

for (i = 0; i < 800; i++)

{}

}

void main()

{

port_a = 0x80;

while(1)

{

au = 0x11;

port_a = au;

delay(1);

au = 0x22;

port_a = au;

delay(1);

au = 0x44;

port_a = au;

delay(1);

au = 0x88;

port_a = au;

delay(1);

}

}