

Sinhgad College of Engineering, Pune

Department of E&TC

B.E. E&TC - (Project)

Group No: 79

Landslide Monitoring And Prediction System

Using Machine Learning

(Sponsored By:- TDL TechSphere)

By:

Aditi Sarraf

404A009

Parth Pol

404C047

Swaroop Sawale

404D013

Guide: Dr S.S.Patil(Internal)

2024-25, Sem: VII



Contents

- Introduction
- Aim & Objective
- Literature Survey
- Components Requirements
- Block Diagram
- Methodology
- Algorithm(Flowchart)
- Application & Limitations
- Conclusions , Future Scope & References

Introduction

- ❑ The system is designed to continuously monitor soil moisture, temperature, humidity, and movement using a variety of sensors and provides it for real time monitoring .
- ❑ This data is processed by a microcontroller .To address this, we propose a machine learning algorithm that uses sensor data as input datasets to predict potential landslides and activate early-warning systems.
- ❑ Additionally, the system features a multi-stage alarm to provide timely warnings for potential landslides and floods. Provides an early warning system for landslides and floods, reducing potential damage and enhancing safety.

Aim & Objectives

❖ Aim:

- Develop a system to monitor soil conditions, including moisture, temperature, humidity, and movement, to predict potential landslides and provide early warnings.

❖ Objectives:

1. **Real-time Monitoring:** Continuously monitor soil moisture, temperature, humidity, and vibrations using various sensors.
2. **Multi-stage Alarm System:** Implement an alarm system that triggers at different stages based on the severity of detected conditions, indicating potential landslide risks.
3. **Data Processing and Prediction:** Use machine learning algorithms to process sensor data and predict landslides, providing timely alerts.
4. **Automated Preventive Measures:** Facilitate preventive actions to reduce disaster impacts by providing warnings and potentially activating safety measures.

Literature Survey

1. **"Deep Learning-Based Landslide Susceptibility Mapping"** – Zhu, Q., Xu, X., Pan, B., Chen, F., & Zhao, Q. (2022), *Engineering Geology*, Elsevier.
2. **"Landslide Detection Using Remote Sensing and Machine Learning"** – Youssef, N., Pourghasemi, M., & Demirci, D. (2021), *Remote Sensing*, MDPI.
3. **"A Comparative Study of Machine Learning Algorithms for Landslide Susceptibility Mapping"** – Hong, X., Liu, Y., Wu, J., & Li, T. (2020), *Landslides*, Springer.
4. **"Early Warning of Landslides Using IoT and Edge Computing"** – Tan, J., Wang, C., & Zhang, L. (2021), *IEEE Internet of Things Journal*.
5. **"A Deep Learning Framework for Real-Time Landslide Detection Using Seismic Data"** – Zhao, F., Liu, H., & Chen, K. (2022), *Computers & Geosciences*, Elsevier.
6. **"Multi-Criteria Decision Analysis for Landslide Hazard Assessment Using GIS"** – Kumar, R., Singh, S., & Mehta, P. (2019), *Geocarto International*, Taylor & Francis.

Components Requirements

- ESP32
- Soil Moisture Sensor
- Accelerometer MPU6050
- Temperature sensor DHT11
- Vibration Sensor
- Ultrasonic Sensor
- Buzzer

Hardware Requirements

Hardware Requirements:

- **Sensors:**

- Soil Moisture Sensor: Measures water content in the soil.
- Temperature and Humidity Sensor (DHT11) : Monitors temperature and humidity
- Accelerometer (MPU6050): To get x, y, z acceleration helps detect movements or changes in the angle of the slope, which could indicate potential landslides.
- Vibration Sensor (SW-420) : To detect sudden movements

- **Microcontroller/Processor:**

- ESP32 : For reading sensor data, processing, controlling alarms and sending data to cloud platform ThingSpeak.

- **Output Devices:**

- LEDs: Indicate different levels of alerts.
- Buzzer: Sounds alarm when thresholds are exceeded.
- Notification : ML model processes the data from sensors and makes prediction.

Software Requirements

Software Requirements:

- **Libraries for ESP32 & Cloud :**

- ESP32WiFi.h : Connects ESP32 to Wi-Fi..
- WiFiClient.h: Enables TCP client for cloud communication
- ThingSpeak.h : Sends sensor data to ThingSpeak cloud.

- **Sensor Libraries :**

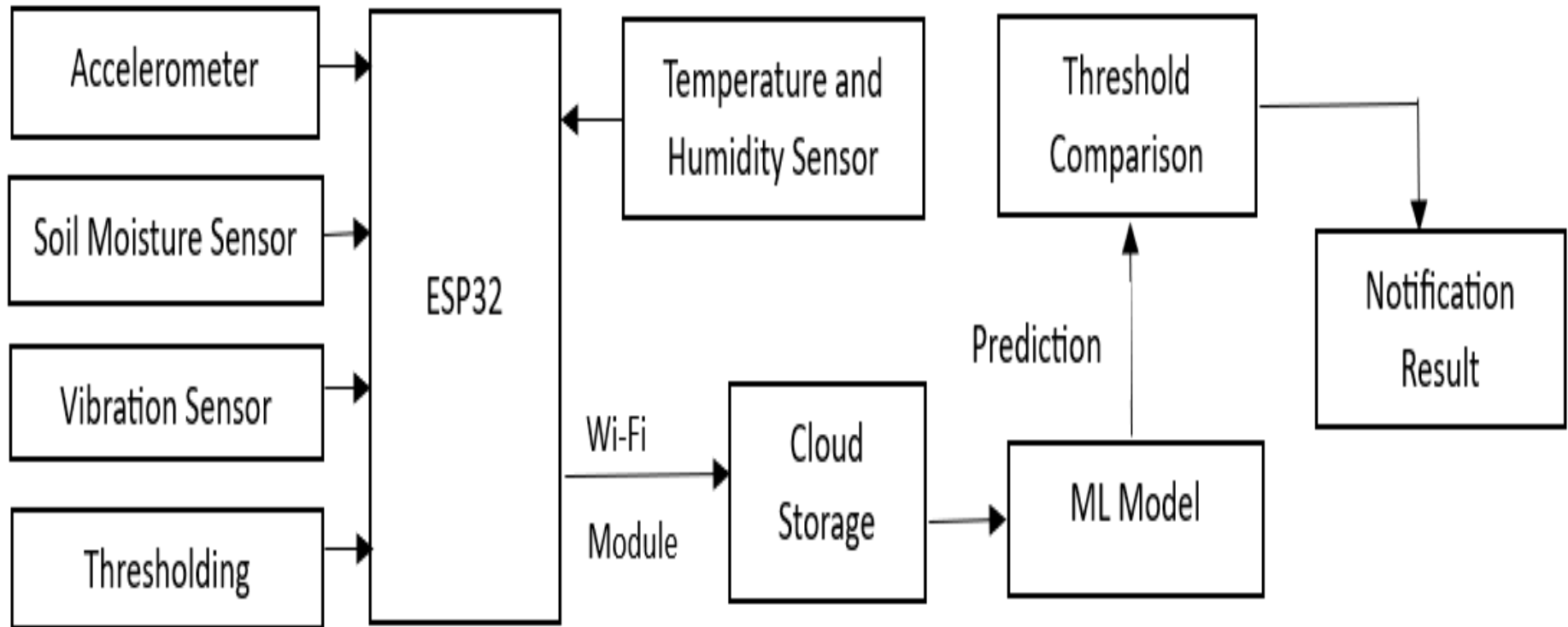
- DHT.h + Adafruit Unified Sensor : For DHT11 (temp & humidity).
- Wire.h : I2C communication for MPU6050.
- Adafruit_MPU6050.h: Reads accelerometer data.

- **Arduino IDE:**

- Used to write, compile & upload code to ESP32.
- Enables sensor interfacing via GPIO/analog pins.
- Sends data every 15 – 20 secs to ThingSpeak using ThingSpeak.writeFields().

- **ML Data Processing**
 - NumPy : For numerical ops.
 - Pandas : For data cleaning & analysis.
 - Matplotlib : For data visualization

Block Diagram



METHODOLOGY

Implementation Steps :-

- **1.Sensor Integration:**
 - Connect all sensors to the microcontroller.
 - Ensure proper calibration of sensors to get accurate readings.
- **2. Microcontroller Programming:**
 - Write code to read data from sensors.
 - Implement logic to check if readings exceed thresholds.
 - Control the buzzer for alarm signaling.
- **3.ML model:** The model is trained on historical data from similar landslide-prone areas. The dataset contains features such as soil moisture, temperature, Rainfall, slope angle and soil type. If values exceed the threshold in the ML model, the buzzer will be activated.
- **4. System Alert:** When the machine learning model detects that the conditions for a landslide are met (based on thresholds of moisture, temperature , soil type), a buzzer will be triggered.

Calculation:- For movements in give direction

Accelerometer: for prone areas ,steep slopes , loose soil , ground movement.

Also detect tilt or inclination:-

$$\text{Accleration in y-axis } a_y = 0.4g$$

$$\text{Accleration in x-axis } a_x = 0.3g$$

$$\text{Accleration in z-axis } a_z = 0.8g$$

$$\text{Total Acceleration } A = \sqrt{(0.3)^2 + (0.4)^2 + (0.8)^2} = 0.943g$$

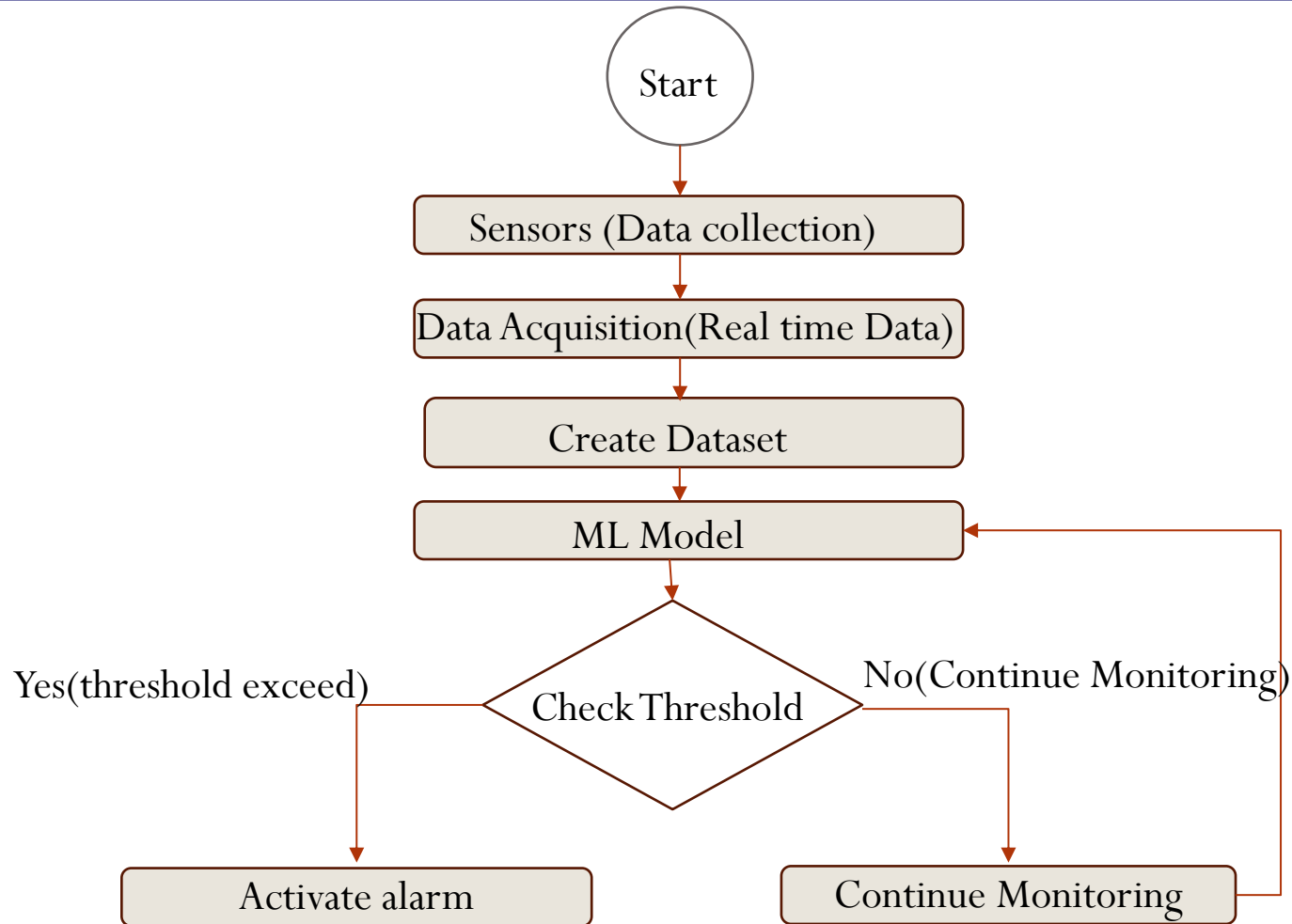
$$1g = 9.8 \text{ m/s}^2$$

$$= 0.943 \times 9.8 = 9.2 \text{ m/s}^2$$

Tilt (using Z-Axis):-

$$\theta = \arctan \left[\frac{a_x}{a_z} \right] = \theta = \arctan \left[\frac{0.3}{0.8} \right] = 20.56^\circ$$

Algorithm(Flowchart)



Results

Simulations and IOT Integration

WOKWI SAVE SHARE Docs SIGN IN

sketch.ino • diagram.json • libraries.txt

Library Manager

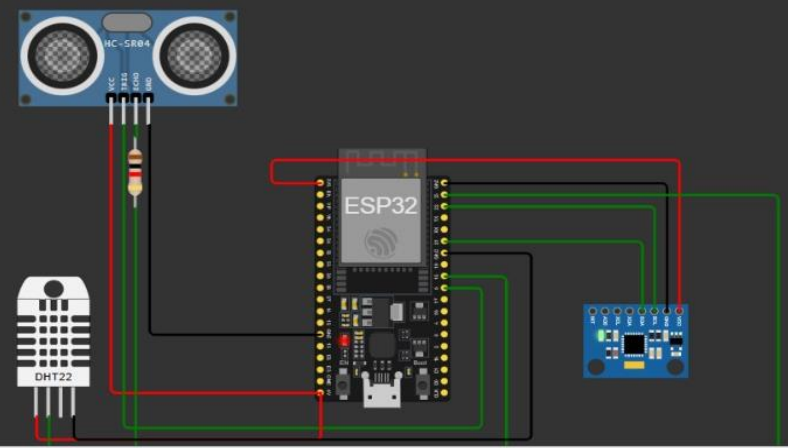
```

26 void loop() {
33   if (isnan(humidity) || isnan(temperatureC)) {
34     // Wait 30 seconds before taking next readings
35   } else {
36     // Display Temperature & Humidity
37     Serial.print("Humidity: ");
38     Serial.print(humidity);
39     Serial.print("% | Temperature: ");
40     Serial.print(temperatureC);
41     Serial.print("°C ~ ");
42     Serial.print(temperatureF);
43     Serial.println("°F");
44   }
45
46   // Measure Distance Using HC-SR04
47   digitalWrite(TRIG_PIN, LOW); // Ensure TRIG is low
48   delayMicroseconds(2); // Small delay
49   digitalWrite(TRIG_PIN, HIGH); // Send pulse
50   delayMicroseconds(10); // Pulse duration
51   digitalWrite(TRIG_PIN, LOW); // End pulse
52
53   // Read the pulse duration from ECHO pin
54   long duration = pulseIn(ECHO_PIN, HIGH);
55   float distanceCm = (duration * SOUND_SPEED) / 2;
56
57   // Display the distance measured by HC-SR04
58   Serial.print("Distance (cm): ");
59   Serial.println(distanceCm);
60
61   // Wait before taking next readings
62   delay(3000); // 3 seconds delay
63 }
64

```

Simulation

00:23.242 80%



Distance (cm): 399.96
Humidity: 40.00% | Temperature: 24.00°C ~ 75.20°F
Distance (cm): 399.96
Humidity: 40.00% | Temperature: 24.00°C ~ 75.20°F
Distance (cm): 399.98
Humidity: 40.00% | Temperature: 24.00°C ~ 75.20°F
Distance (cm): 399.98

Activate Windows
Go to Settings to activate Windows.



WOKWI

SAVE

SHARE

Docs

S

sketch.ino • diagram.json libraries.txt • Library Manager

Simulation

🔄

■

⏸

🔊

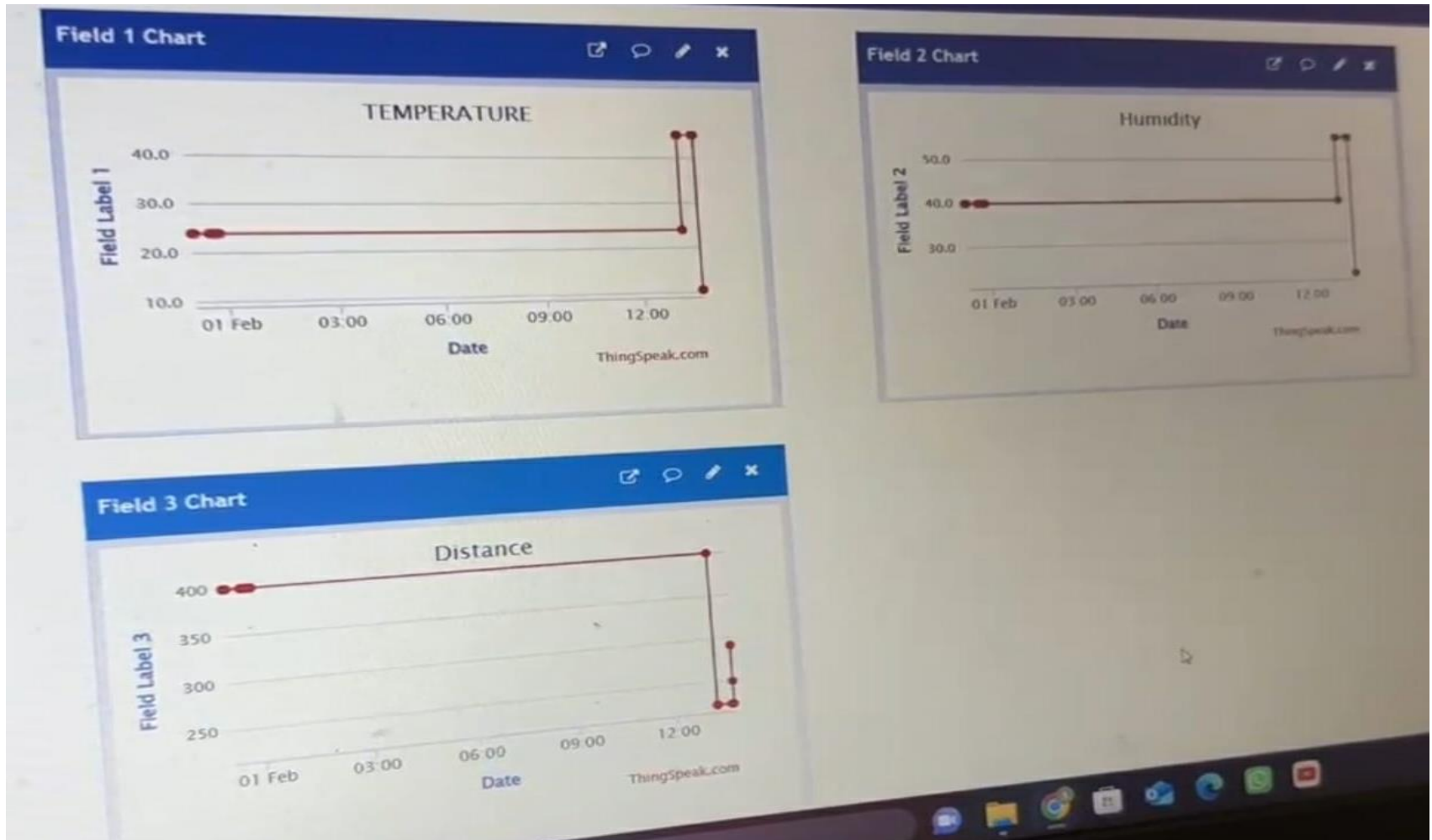
🕒 11:57.858 🔋 99%

```
1 #include <DHT.h>
2 #include <WiFi.h>
3 #include <ThingSpeak.h>
4
5 #define TRIG_PIN 5      // HC-SR04 Trig pin
6 #define ECHO_PIN 18     // HC-SR04 Echo pin (Δ Use Voltage Divi
7 #define SOUND_SPEED 0.034 // Speed of sound in cm/microsecond
8
9 #define DHT_SENSOR_PIN 23 // DHT22 Data pin
10 #define DHT_SENSOR_TYPE DHT22 // DHT sensor type
11
12 // WiFi Credentials
13 #define WIFI_SSID "Wokwi-GUEST" // Δ Change to your WiFi SSID
14 #define WIFI_PASSWORD "" // Δ Change to your WiFi password
15
16 // ThingSpeak Credentials
17 #define THINGSPEAK_API_KEY "1F9ETKWTRR1BQZHE"
18 #define THINGSPEAK_CHANNEL_ID 2826180
19
20 // Initialize the DHT sensor
21 DHT dht(DHT_SENSOR_PIN, DHT_SENSOR_TYPE);
22
23 // Initialize WiFiClient and ThingSpeak client
24 WiFiClient client;
25
26 void setup() {
27   Serial.begin(115200);
28
29   // Set up Trig and Echo for HC-SR04
30   pinMode(TRIG_PIN, OUTPUT);
31   pinMode(ECHO_PIN, INPUT);
32
33   // Initialize DHT sensor
34   dht.begin();
```

```
Temperature: 24.00°C | Humidity: 40.00%
Distance: 399.89 cm
Data sent to ThingSpeak successfully.
Temperature: 24.00°C | Humidity: 40.00%
Distance: 222.89 cm
Data sent to ThingSpeak successfully.
Temperature: 45.10°C | Humidity: 55.50%
```

Activate Windows

Go to Settings to activate Windows.





Landslide Monitoring system

Channel ID: 2826180

Author: mwa0000033775698

Access: Private

Private View

Public View

Channel Settings

Sharing

API Keys

Data Import / Export

+ Add Visualizations

+ Add Widgets

Export recent data

MATLAB Analysis

MATLAB Visualization

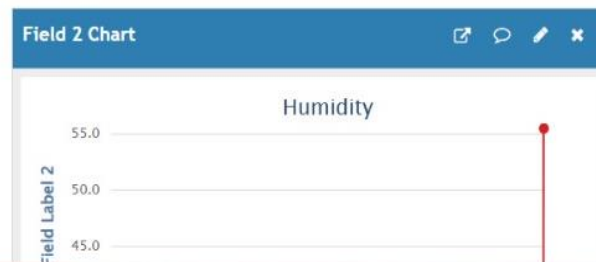
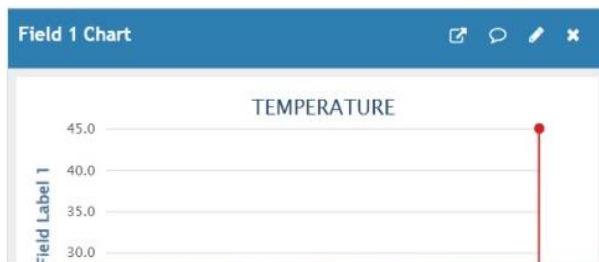
Channel 2 of 2 < >

Channel Stats

Created: about 16 hours ago

Last entry: 21 minutes ago

Entries: 23



Activate Windows
Go to Settings to activate Windows



Private View

Public View

Channel Settings

Sharing

API Keys

Data Import / Export

Import

Upload a CSV file to import data into this channel.

File

Choose File

No file chosen

Time Zone

(GMT+00:00) UTC

Upload

Export

Download all of this Channel's feeds in CSV format.

Time Zone

(GMT+00:00) UTC

Download

Help

The correct format for data import is provided in this [CSV Import Template File](#). Use the field names *field1*, *field2*, and so on, instead of custom field names.

CSV Import Format

```
created_at,field1,field3,field4,field8,elevation  
2019-01-01T10:11:12-05:00,11,33,44,88,10
```

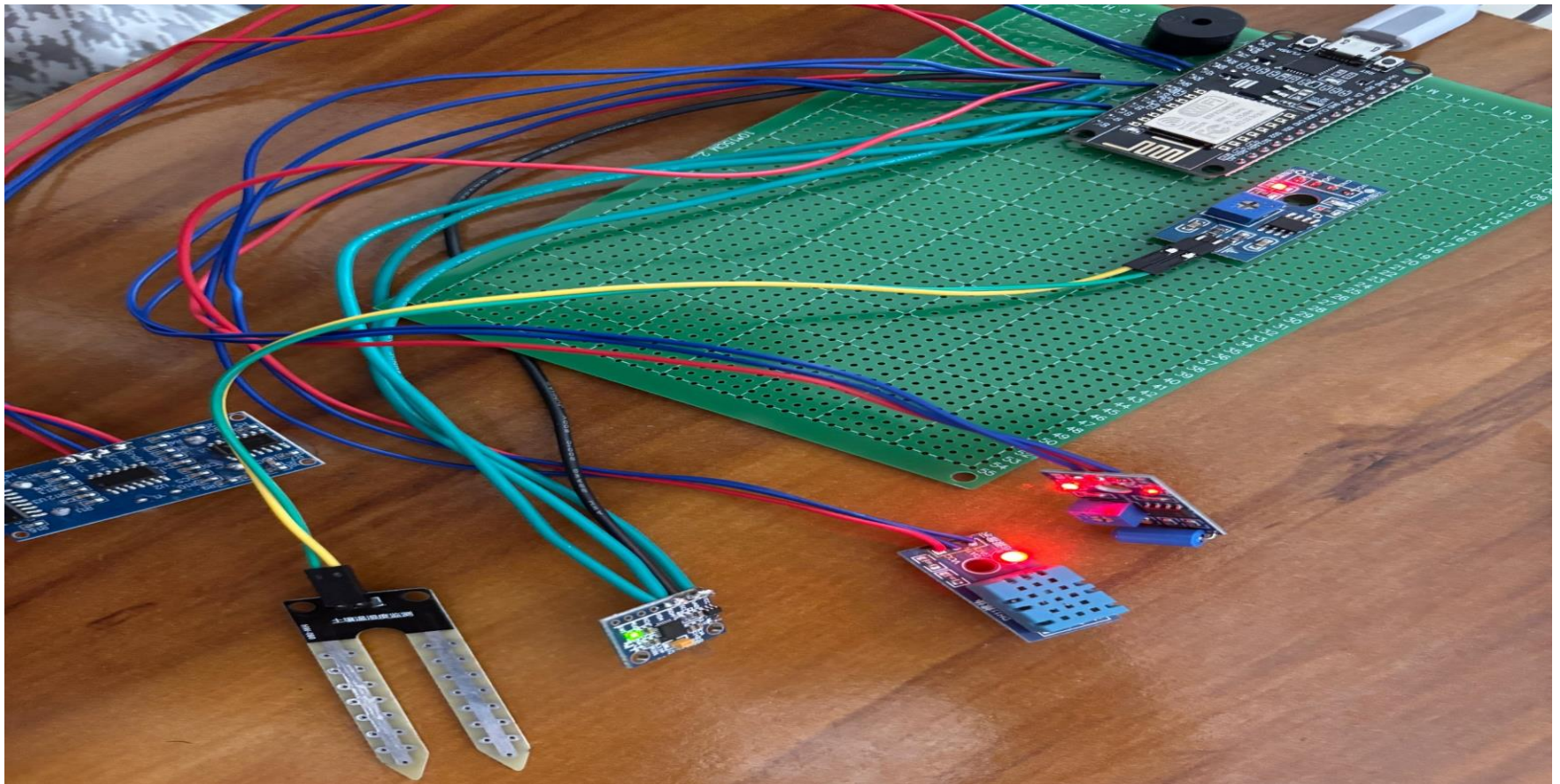
Other Import and Export Options

You can also use MATLAB, the REST API, or the MQTT API to import and export channel data.

[Read Data](#)

[Write Data](#)

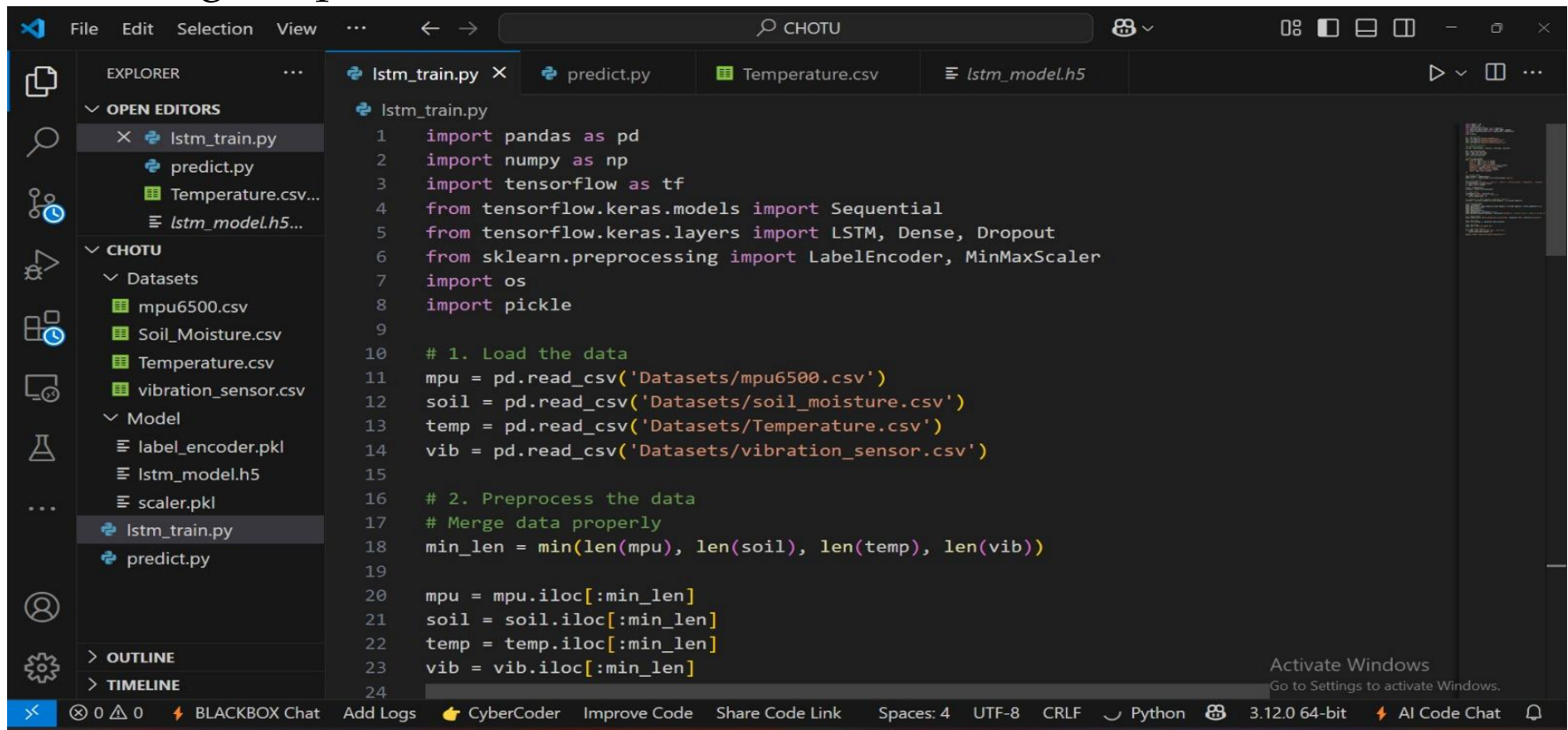
Hardware Integration



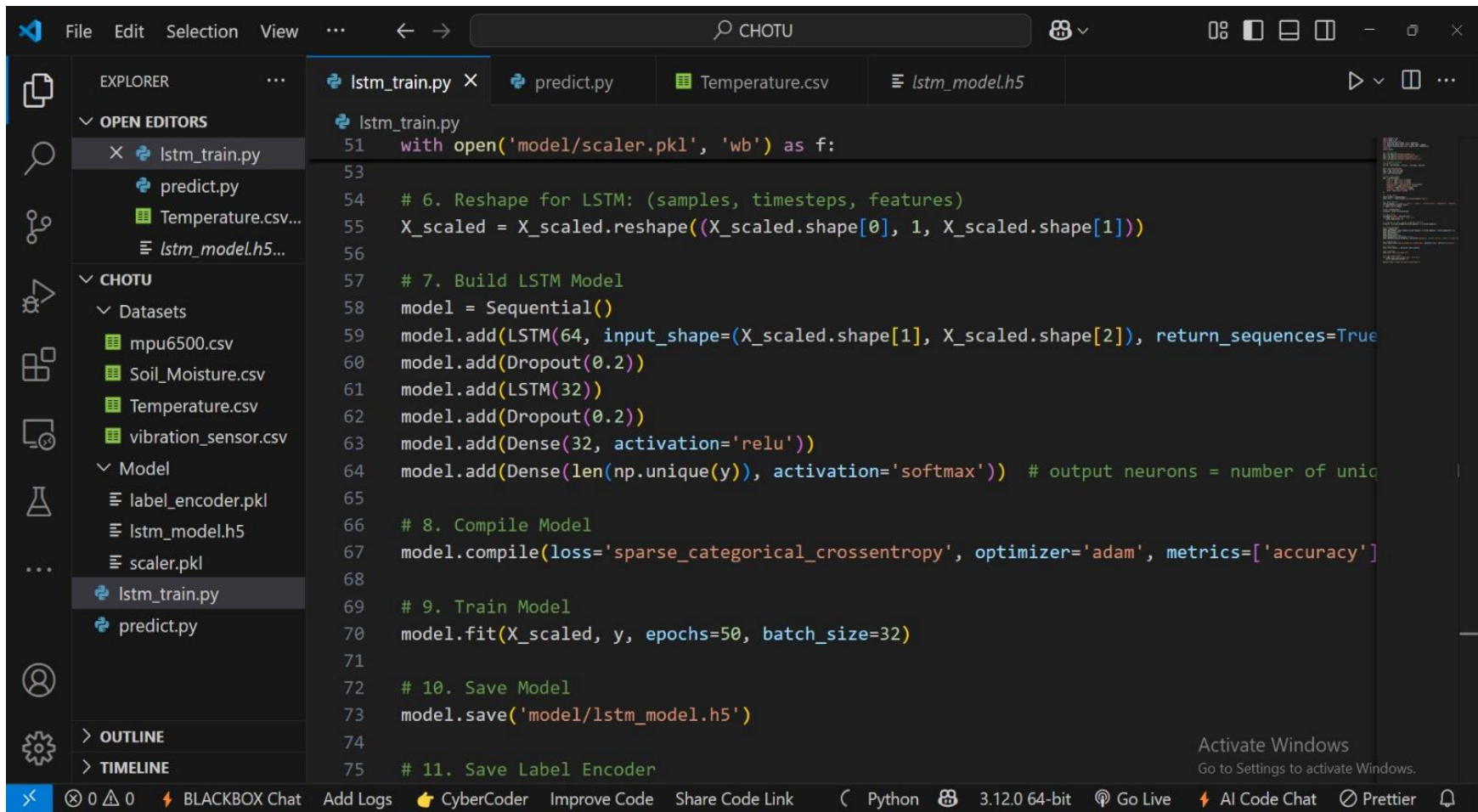


ML Model :

Training Script :

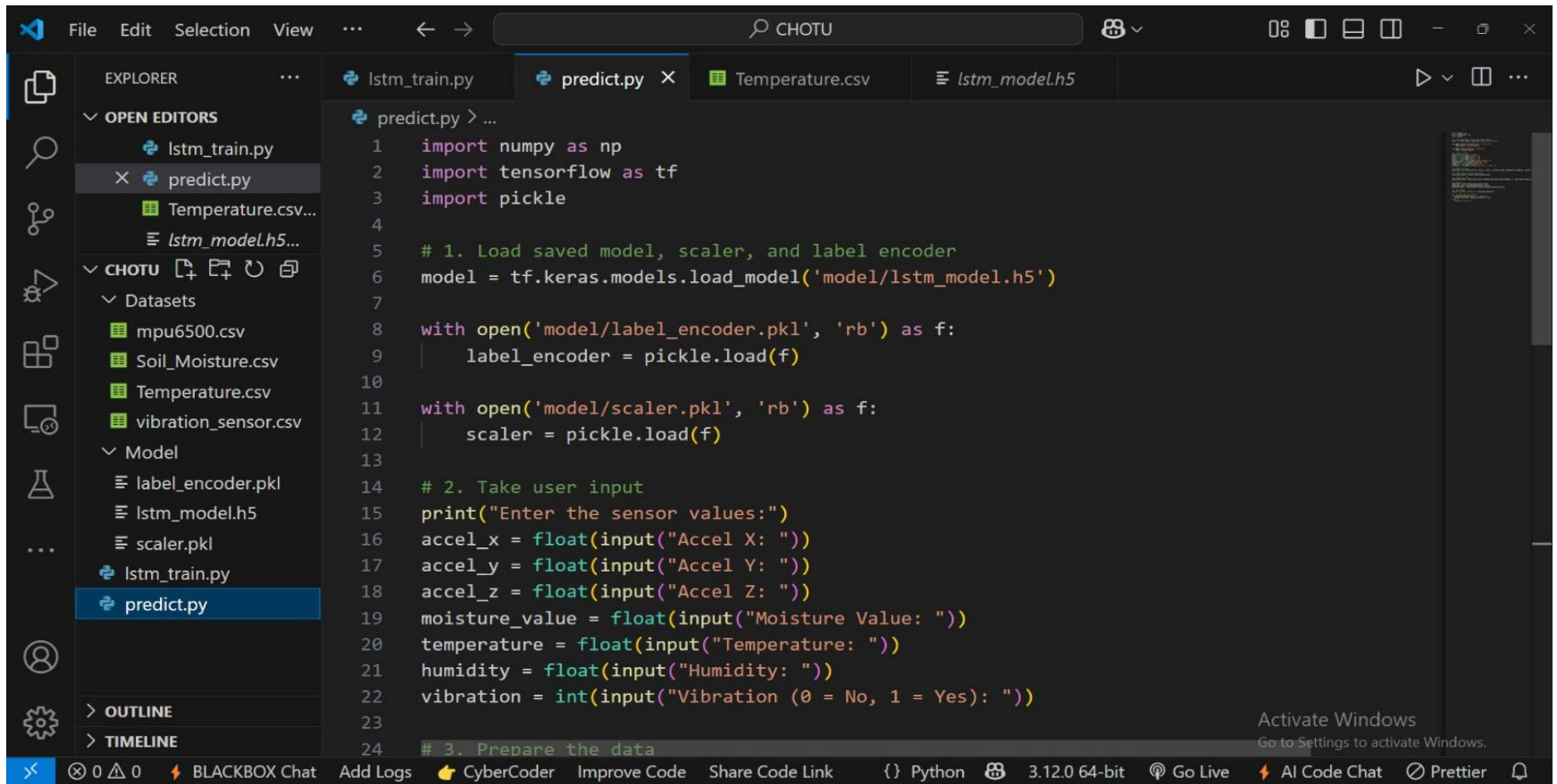


```
1 import pandas as pd
2 import numpy as np
3 import tensorflow as tf
4 from tensorflow.keras.models import Sequential
5 from tensorflow.keras.layers import LSTM, Dense, Dropout
6 from sklearn.preprocessing import LabelEncoder, MinMaxScaler
7 import os
8 import pickle
9
10 # 1. Load the data
11 mpu = pd.read_csv('Datasets/mpu6500.csv')
12 soil = pd.read_csv('Datasets/soil_moisture.csv')
13 temp = pd.read_csv('Datasets/Temperature.csv')
14 vib = pd.read_csv('Datasets/vibration_sensor.csv')
15
16 # 2. Preprocess the data
17 # Merge data properly
18 min_len = min(len(mpu), len(soil), len(temp), len(vib))
19
20 mpu = mpu.iloc[:min_len]
21 soil = soil.iloc[:min_len]
22 temp = temp.iloc[:min_len]
23 vib = vib.iloc[:min_len]
24
```

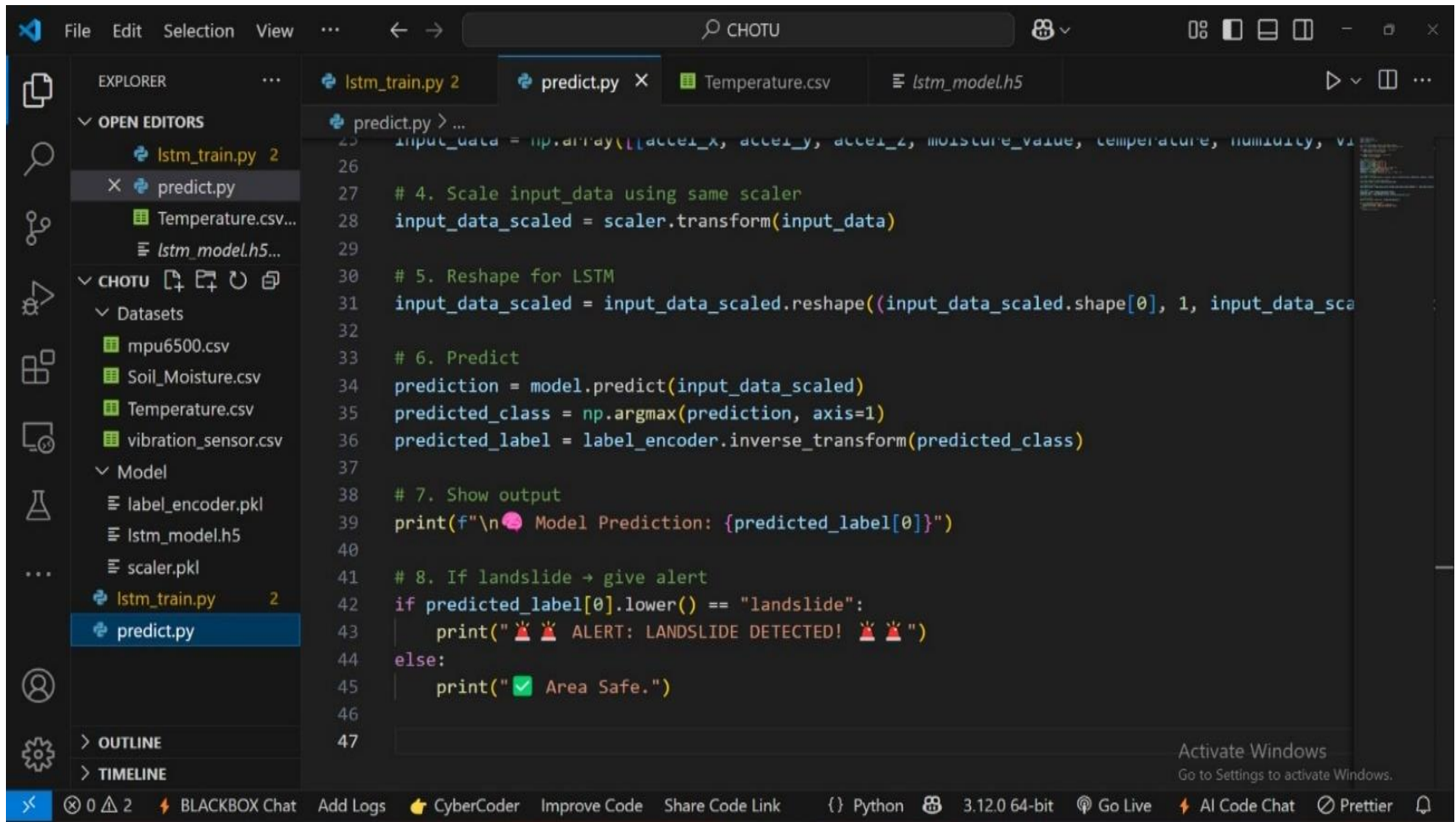


```
51 with open('model/scaler.pkl', 'wb') as f:
52
53
54 # 6. Reshape for LSTM: (samples, timesteps, features)
55 X_scaled = X_scaled.reshape((X_scaled.shape[0], 1, X_scaled.shape[1]))
56
57 # 7. Build LSTM Model
58 model = Sequential()
59 model.add(LSTM(64, input_shape=(X_scaled.shape[1], X_scaled.shape[2]), return_sequences=True))
60 model.add(Dropout(0.2))
61 model.add(LSTM(32))
62 model.add(Dropout(0.2))
63 model.add(Dense(32, activation='relu'))
64 model.add(Dense(len(np.unique(y)), activation='softmax')) # output neurons = number of unique classes
65
66 # 8. Compile Model
67 model.compile(loss='sparse_categorical_crossentropy', optimizer='adam', metrics=['accuracy'])
68
69 # 9. Train Model
70 model.fit(X_scaled, y, epochs=50, batch_size=32)
71
72 # 10. Save Model
73 model.save('model/lstm_model.h5')
74
75 # 11. Save Label Encoder
```


Prediction Script



```
1 import numpy as np
2 import tensorflow as tf
3 import pickle
4
5 # 1. Load saved model, scaler, and label encoder
6 model = tf.keras.models.load_model('model/lstm_model.h5')
7
8 with open('model/label_encoder.pkl', 'rb') as f:
9     label_encoder = pickle.load(f)
10
11 with open('model/scaler.pkl', 'rb') as f:
12     scaler = pickle.load(f)
13
14 # 2. Take user input
15 print("Enter the sensor values:")
16 accel_x = float(input("Accel X: "))
17 accel_y = float(input("Accel Y: "))
18 accel_z = float(input("Accel Z: "))
19 moisture_value = float(input("Moisture Value: "))
20 temperature = float(input("Temperature: "))
21 humidity = float(input("Humidity: "))
22 vibration = int(input("Vibration (0 = No, 1 = Yes): "))
23
24 # 3. Prepare the data
```



```

File Edit Selection View ... < > CHOTU
EXPLORER
OPEN EDITORS
  lstm_train.py 2
  predict.py
  Temperature.csv...
  lstm_model.h5...
CHOTU
  Datasets
    mpu6500.csv
    Soil_Moisture.csv
    Temperature.csv
    vibration_sensor.csv
  Model
    label_encoder.pkl
    lstm_model.h5
    scaler.pkl
  lstm_train.py 2
  predict.py
OUTLINE
TIMELINE

predict.py > ...
25 input_data = np.array([accel_x, accel_y, accel_z, moisture_value, temperature, humidity, vibration])
26
27 # 4. Scale input_data using same scaler
28 input_data_scaled = scaler.transform(input_data)
29
30 # 5. Reshape for LSTM
31 input_data_scaled = input_data_scaled.reshape((input_data_scaled.shape[0], 1, input_data_scaled.shape[2]))
32
33 # 6. Predict
34 prediction = model.predict(input_data_scaled)
35 predicted_class = np.argmax(prediction, axis=1)
36 predicted_label = label_encoder.inverse_transform(predicted_class)
37
38 # 7. Show output
39 print(f"\n 🧠 Model Prediction: {predicted_label[0]}")
40
41 # 8. If landslide → give alert
42 if predicted_label[0].lower() == "landslide":
43     print(" 🚨 🚨 ALERT: LANDSLIDE DETECTED! 🚨 🚨 ")
44 else:
45     print(" ✅ Area Safe.")
46
47
  
```

Activate Windows
Go to Settings to activate Windows.

0 2 BLACKBOX Chat Add Logs CyberCoder Improve Code Share Code Link Python 3.12.0 64-bit Go Live AI Code Chat Prettier

Output :

```
Epoch 47/50
3/3 _____ 0s 24ms/step - accuracy: 0.9895 - loss: 0.0216
Epoch 48/50
3/3 _____ 0s 27ms/step - accuracy: 1.0000 - loss: 0.0089
Epoch 49/50
3/3 _____ 0s 25ms/step - accuracy: 1.0000 - loss: 0.0089
Epoch 50/50
3/3 _____ 0s 25ms/step - accuracy: 0.9817 - loss: 0.0269
3/3 _____ 1s 151ms/step
Prediction: 0.0059, Predicted label: 0, Actual label: 0
Prediction: 0.0077, Predicted label: 0, Actual label: 0
Prediction: 0.0126, Predicted label: 0, Actual label: 0
Prediction: 0.0297, Predicted label: 0, Actual label: 0
Prediction: 0.1141, Predicted label: 0, Actual label: 0
Prediction: 0.5524, Predicted label: 1, Actual label: 0
Prediction: 0.9727, Predicted label: 1, Actual label: 1
Prediction: 0.9982, Predicted label: 1, Actual label: 1
Prediction: 0.9995, Predicted label: 1, Actual label: 1
Prediction: 0.9997, Predicted label: 1, Actual label: 1
```



Sinhgad Institutes

Applications and Future Scope

Applications

- 1. Real-Time Data Analysis:** Continuously monitors and processes sensor data using embedded systems for immediate threat detection..
- 2. Machine Learning for Predictive Analytics:** Uses historical data and machine learning models (e.g., Random Forest, Decision Trees) to predict landslides based on environmental sensor readings.
- 3. Early Warning Systems:** Provides early alerts for potential disasters, helping reduce loss of life and property.
- 4. Disaster Management:** Assists government and agencies in planning evacuation and resource deployment during emergencies.

Future Scope

- 1. AI-Powered Predictive Models:** Future improvements could include more advanced AI models that predict disasters with higher accuracy.
- 2. IoT Integration:** Integration with IoT devices for real-time monitoring and remote alerts via mobile apps.
- 4. Cloud Computing & Big Data:** Leveraging cloud platforms for large-scale data storage and analytics, enabling more scalable, real-time processing of multi-sensor data across larger areas.
- 1. Integration with Image Processing:** Use satellite imagery or drones to perform real-time image analysis for terrain changes and landslide risk mapping.

Conclusions

- By utilizing sensors, a ESP32, and an LSTM model, the system continuously collects and analyzes data, activating alarms if thresholds are exceeded to warn nearby individuals.
- The integration of IoT with machine learning not only enhances early warning accuracy but also enables remote data access and historical trend analysis through cloud platforms like ThingSpeak, laying the groundwork for intelligent, data-driven disaster management systems.
- This scalable, real-time monitoring solution demonstrates significant potential for disaster prevention and mitigation, supporting the safety of communities in landslide-prone areas.

References

1. **Zhu, Q., Xu, X., Pan, B., Chen, F., & Zhao, Q.** (2022). *Deep Learning-Based Landslide Susceptibility Mapping*. Engineering Geology, Elsevier.
2. **Youssef, N., Pourghasemi, M., & Demirci, D.** (2021). *Landslide Detection Using Remote Sensing and Machine Learning*. Remote Sensing, MDPI.
3. **Hong, X., Liu, Y., Wu, J., & Li, T.** (2020). *A Comparative Study of Machine Learning Algorithms for Landslide Susceptibility Mapping*. Landslides, Springer.
4. **Tan, J., Wang, C., & Zhang, L.** (2021). *Early Warning of Landslides Using IoT and Edge Computing*. IEEE Internet of Things Journal.
5. **Zhao, F., Liu, H., & Chen, K.** (2022). *A Deep Learning Framework for Real-Time Landslide Detection Using Seismic Data*. Computers & Geosciences, Elsevier.
6. **Kumar, R., Singh, S., & Mehta, P.** (2019). *Multi-Criteria Decision Analysis for Landslide Hazard Assessment Using GIS*. Geocarto International, Taylor & Francis.
7. **ThingSpeak Documentation** : MathWorks. Available at: <https://thingspeak.com>
8. **Adafruit Documentation** : DHT11 & MPU6050 Libraries and Unified Sensor Library. Available at : <https://learn.adafruit.com>
9. **Arduino IDE**: Arduino Software Platform. Available at: <https://www.arduino.cc/en/software>
10. **Wokwi Simulator** : Online Arduino & ESP8266 Simulator. Available at: <https://wokwi.com>

THANK you