## CN CSL317

#### **ASSIGNMENT-4**

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## > instructions that *clearly* describe how to run codes:

Open the command prompt/power shell in windows. (prerequisite: python installed in it)

Run the BT19CSE098 dvr.py code by adding the input file as a command-line argument.

Ex: suppose input.txt is the input file. Use the following command to run the code.

PS G:\6sem\CN\A2>python BT19CSE098 dvr.py input.txt

Input file format: The first line contains a number of routers, then second-line names of routers and the few lines distances between the routers. And at last, EOF which indicates End of file.

Input.txt example:

3

ABC

**AB** 5

AC2

B C 8

**EOF** 

## > The working of code:

First defined a **common** dictionary,

=>common dictionary having keys: {nodeinfo, counter, lock,finalString} for storing shared information.

nodeinfo: There is a tuple of the queue and its lock for each node name.

counter: to keep a list of nodes that have computed the new table so that the second iteration begins only when all threads are finished

lock: lock for appending each node's updated DVR table to the final string

finalString: string containing the final information printed after each iteration

Then read the input text file (from command line argument) and took lines of it and extracted router information and added it to the router dictionary. The router dictionary has keys as node names for storing router information. node name is a subsequent dictionary with keys: neighbor(to store a list of all neighbors of that node) and DVR( to store the distance vector table of that node). Then printed the initial router information by calling print() function.

Then called task function in threading. Thread target. In task function, taking 4 iterations, in each iteration called update\_queue and bellman\_ford functions.

#### Task performed in brief:

Make a new thread for each node/router and pass it its personal router information (neighbor list and DVR table) as well as the shared data structure. After acquiring queue lock, the routing tables are first shared to all queues of each router's neighbors. Once all of a node's neighbors have shared their DVR information, tables are re-computation using the Bellman-Ford Equation. Each node's updated DVR tables are printed, and the threads wait 2s before the next iteration.

> Testing applied(test cases) and Screenshots of outputs:

#### **Test Case 1:**



## **Output:**

## **Test Case 2:**

```
6
A B C D E F
A B 6
A C 3
B C 2
B D 7
C E 9
D E 1
D F 8
E F 4
EOF
```

# **Output:**

		INITIAL		inf	NA
ROUTER			В	inf	NA
Destination	Cost	Next Router	C D	9.0 1.0	C D
Α		A	E	0	Ē
	6.0		Ē	4.0	
	3.0				
	inf	NA	ROUTE		
	inf	NA	Destination	Cost	Next Router
	inf	NA	A	inf	NA
			B C	inf inf	NA NA
ROUTER	: B		D	8.0	NA D
Destination	Cost	Next Router	Ē	4.0	Ĕ
	6.0	Α	Ē	0	
В	0	В			
C	2.0	C			
D	7.0	D			ITI
Ē	inf	NA	ROUTE	D. A	
F	inf	NA	Destination	Cost	Next Router
			A	0	A
ROUTER			* B	5.0	
Destination	Cost	Next Router	C	3.0	
A	3.0	A	* D	13.0	
В	2.0	B	* E	12.0	
Č	0	C	F	inf	NA
D		NA			
	inf		ROUTE	R: B	
E	9.0	E	Destination	Cost	Next Router
	inf	NA	* A	5.0	
			В		
ROUTER			c	2.0	
Destination	Cost	Next Router	D * E	7.0	D
Α	inf	NA	* E	8.0 15.0	D D
	7.0		* F	15.0	
	inf	NA			
			ROUTE	R: C	
	1.0		Destination	Cost	Next Router
	8.0		А	3.0	
			В	2.0	
ROUTER	: E		C * D	0 9.0	C B

ROUTER	R: C		ROLIT	ER: A	
Destination	Cost	Next Router	Destination	Cost	Next Router
	3.0		A	0	A A
В	2.0	В	В	5.0	c
			С	3.0	
	9.0		* D	12.0	С
	9.0		E	12.0	
	13.0		* F	16.0	
ROUTER	p. n		POLIT	ER: B	
Destination	Cost	Next Router	Destination	Cost	Next Router
* A	13.0	B	A	5.0	C C
В	7.0	В	B	0	В
* C	9.0	В	Č	2.0	Č
D	0	D	D	7.0	D
Ē	1.0	Ē	E	8.0	D
* F	5.0	Ē	* E	12.0	D
				11.0	
ROUTER	R: E		ROUT	ER: C	
Destination	Cost	Next Router	Destination	Cost	Next Router
	12.0		Α	3.0	
	8.0		В	2.0	
	9.0		С		
	1.0		D	9.0	
			E	9.0	
	4.0		F	13.0	
ROUTER	R: F		 ROUT	ER: D	
Destination	Cost	Next Router	Destination		Next Router
	inf	NA	* A	12.0	В
* B	15.0		В	7.0	
	13.0	Ē	 C	9.0	В
	5.0		 D		
	4.0		E	1.0	
			F	5.0	
		ITERATION 2	 ROUT	ER: E	
		TILIMITON Z	Destination	Cost	Next Router
ROUTER	R· A		A	12.0	C
Destination	Cost	Next Router	B	8.0	D
A	0	A	 Č	9.0	č
В	5.0	Ĉ	D	1.0	D
č	3.0		Ē	0	Ĕ

	ROUTER:			
Destina	ation	Cost	Next	Router
		12.0		
		8.0		
		9.0		
		1.0		
		4.0		
	ROUTER:			
Destina	ation	Cost		Router
		16.0		
		12.0		
		13.0		
		5.0		
		4.0		

# Test Case 3:

4				
Α	В	C D		
Α	В	2		
В	С	3		
С	D	11		
Α	D	1		
D	В	7		
EOF				

# Output:

PS G:\6sem\0	N\A4> pyth	on BT19CSE098_dvr.py input2.txt INITIAL	ROUTER		
	TER: A	IN111AL	Descinacion	Cost	Next Router
Destination		Next Router	A	2.0	A
A	0	A A	В	0	В
В	2.0	B	C	3.0	c .
Č	inf	NA	* D	3.0	A
D		D			
U			ROUTER		
ROLL	TER: B		Destination	Cost	Next Router
Destination		Next Router	* A	5.0	B B
A	2.0	A	В	3.0	B
B	0	B	C	0	Č
Č	3.0	Č	* D	10.0	В
	7.0	D		10.0	b
U					
ROLL	TER: C		ROUTER	· n	
Destination		Next Router	Destination	Cost	Next Router
A	inf	NA	A	1.0	A
B	3.0	B	* B	3.0	Â
č	0	Č	* C	10.0	В
	11.0	D	D	0	D
U	11.0				
ROLIT	TER: D				
Destination		Next Router			ITERATION 2
A	1.0	A			
B	7.0	B	ROUTER	: A	
č	11.0		Destination	Cost	Next Router
D	0	D	Α		A
			В	2.0	В
			С	5.0	В
		ITERATION 1	D	1.0	D
		TILIMIZON I			
ROLL	TER: A				
Destination		Next Router	ROUTER	: B	
A			Destination	Cost	Next Router
		Λ			
		A R	A	2.0	Α
В	0 2.0		A B	2.0 0	A B
* C	0 2.0 5.0	B B	A B C	2.0 0 3.0	A B C
В	0 2.0		A B	2.0 0	A B
* C	0 2.0 5.0	B B	A B C	2.0 0 3.0	A B C
B * C D	0 2.0 5.0 1.0	B B	A B C D	2.0 0 3.0 3.0	A B C
B * C D	0 2.0 5.0 1.0	B B D	A B C D	2.0 0 3.0 3.0	A B C A
B * C D ROUT	0 2.0 5.0 1.0 TER: B Cost	B B D Next Router	A B C D ROUTER Destination	2.0 0 3.0 3.0 3.0	A B C A Next Router
B * C D	0 2.0 5.0 1.0	B B D	A B C D	2.0 0 3.0 3.0	A B C A

```
ROUTER: C

Destination Cost Next Router

A 5.0 B

B 3.0 B

C 0 C

* D 6.0 B

ROUTER: D

Destination Cost Next Router

A 1.0 A

B 3.0 A

* C 6.0 A

D 0 D
```