Overview of my work in Jul and Aug

- Classification of *Braking* and *Normal* Windows using PCA eigen vectors
- Classification of *Braking* and *Normal* Windows using AutoRegressive Model
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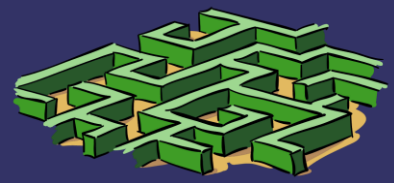
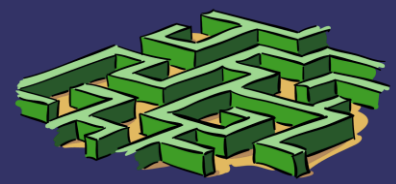


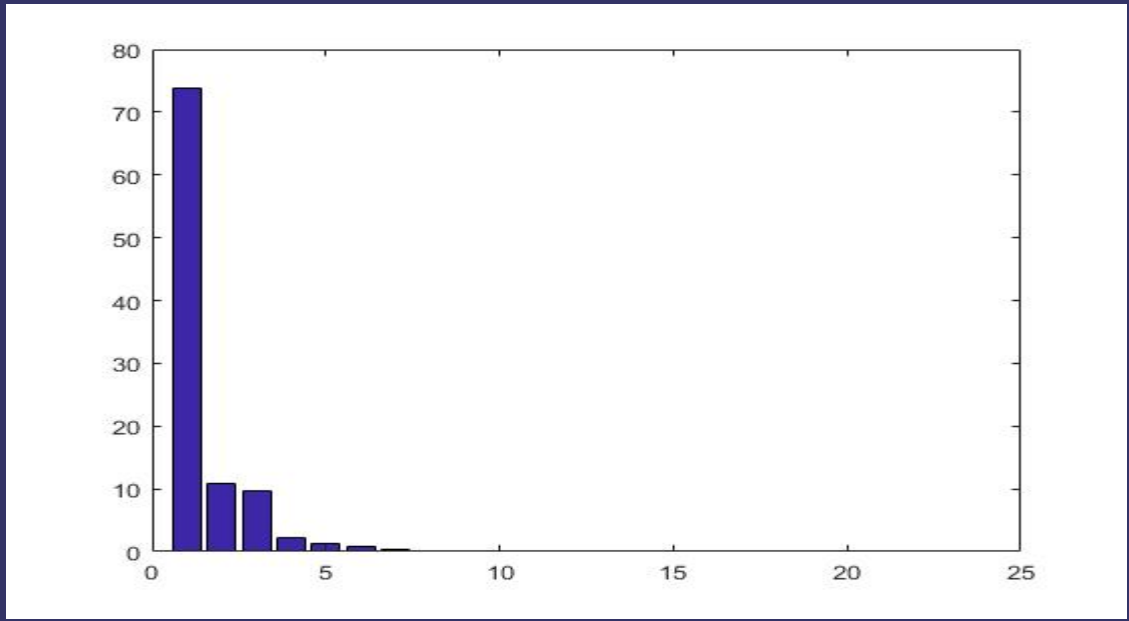
Classification using PCA

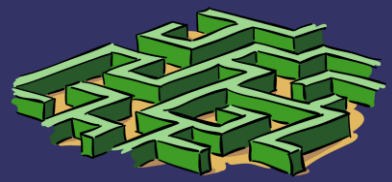
- PCA data matrix consists of *variables* and *observations*
- I am considering channels as variables
- I am considering windows data samples as observations
- I consider 24 channels and 1.5sec window (300 samples) across these channels
- I reduce each window signal to Zero Mean and Unit Variance
- So the data matrix fed to PCA is of size 300 * 24



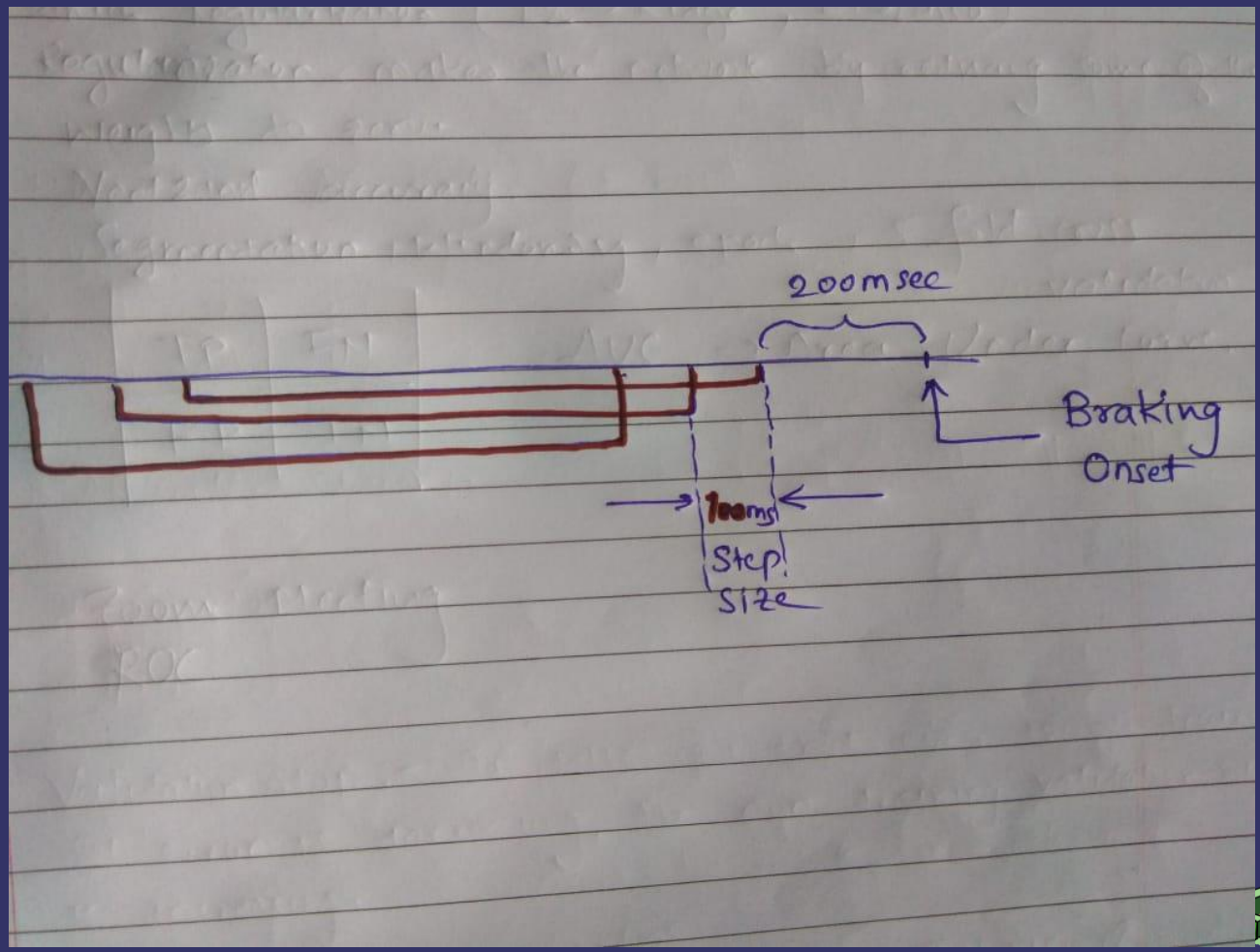
Classification using PCA (contd ...)

- PCA generates a 24*24 matrix with eigen vectors
- I am considering first 4 eigen vectors based on maximum information for each *point* (little 1.500 sec window)



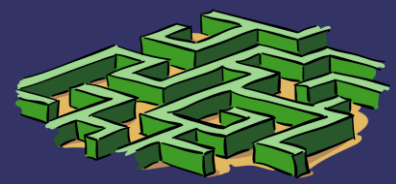


Overlapping Windows



Classification using PCA (contd ...)

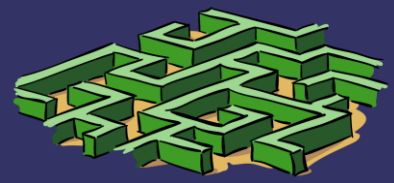
- There are totally such 30 braking and 70 normal points for each of 14 training subjects
- This gives me 14*30*6 + 14*70*6=8400 points (6 is number of overlapping windows)
- I shuffle the above points and their corresponding labels
- I feed the points to the neural network



Over-Fitting issue

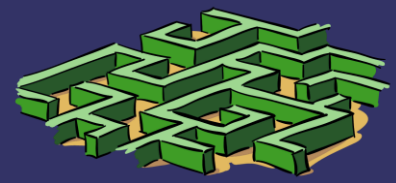
- I faced an over-fitting issue where the training accuracy is much higher than unseen data testing accuracy

- Solutions for Over-fitting issue
  - Regularization
  - Early Stopping
  - More training data
  - Less features



Regularization of Neural Network to avoid Over-Fitting

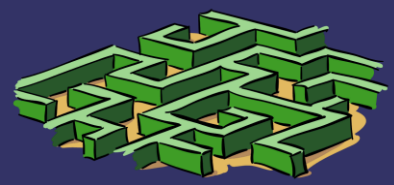
- I implemented Regularization in two ways
- Introducing a ReLU (Poslin) layer
- Make Mean Square Error (MSE) to be a function of weights



Training NN Multiple Times and Pick The Best Network

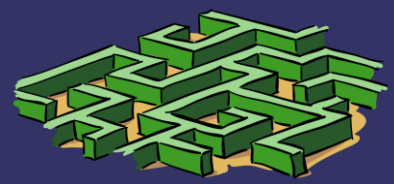
- I trained the neural network multiple times with Randomness in input data division and finite number of epochs

- I picked up the best network, based on the unseen data accuracy it provides

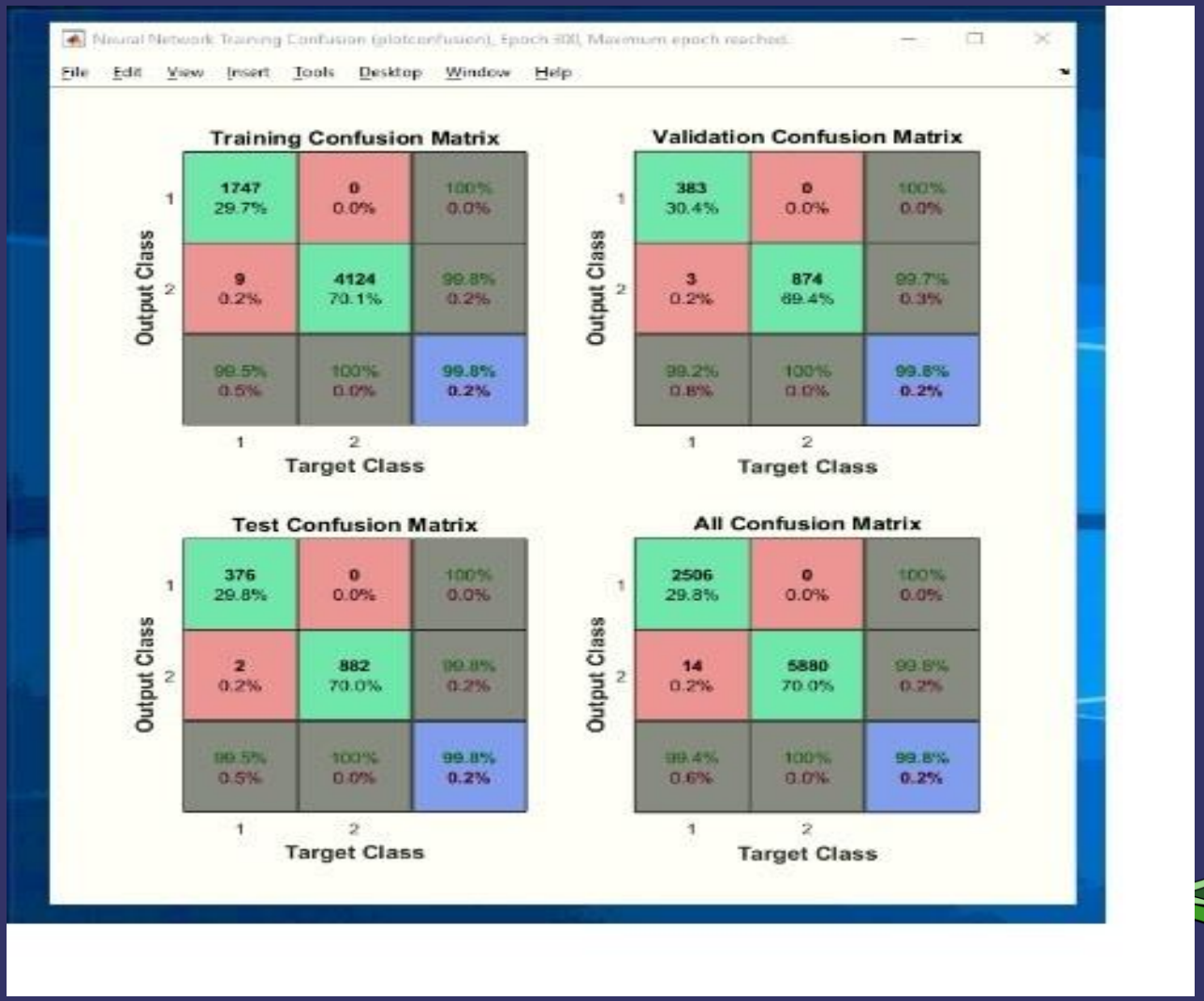


Add More Hidden Layers

- I added more hidden layers to represent a more complex non-linear function

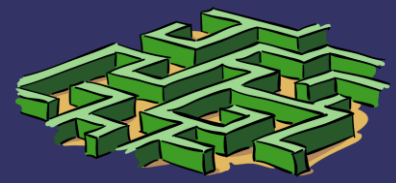


Confusion Matrix for Training with PCA classification



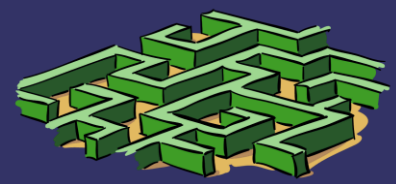
Unseen data accuracy

- My unseen data accuracy is 70+ percent
- This accuracy is calculated as follows:
  - Calculate the difference between the "target" and "predicted" labels.
  - Error Percentage = ((Incorrect labels)/(Total number of labels)) * 100.
  - Accuracy = 100 - Error Percentage



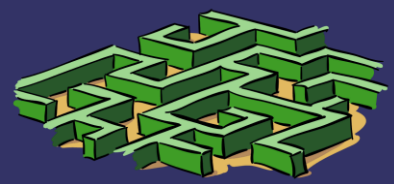
Results so far

- Early Detection:
  - So far I am able to detect the braking signal 200ms early, which is less than mentioned in the paper which is 600ms
- Braking Signal Detection Accuracy:
  - I am able to detect the braking signal with 99% training accuracy and 70% testing accuracy with unseen data
- Real Time Testing: Pending

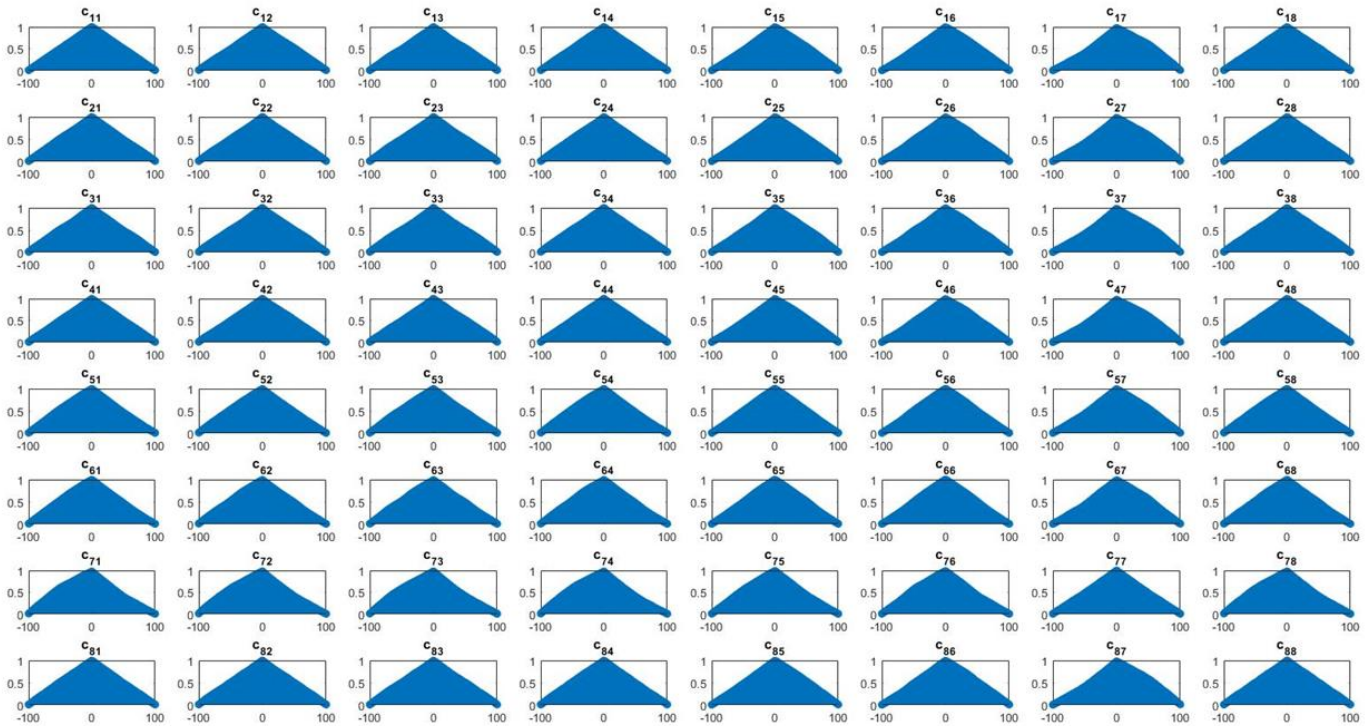


Auto-Correlation and Cross Correlation of Braking and Normal Windows

- I analyzed eight consecutive non-overlapping windows before the normal and braking points.
- I get the output as shown in the figures on the next slides
- My hypothesis is, whenever there is normal driving I get triangular auto/cross correlation without any abnormality.
- However, when there is braking action, I get some abnormality in the auto/cross correlation



Auto and Cross Correlations before Normal



Auto and Cross Correlations before Braking