

G. H. Rasoni Institute of Engineering & Technology, Pune
(An Autonomous institute affiliated to Savitribai Pune University)

Department: First Year Engineering
Course Name: Matrices and Differential Calculus
AY 2020-21 (Sem-I)
Class: FY B Tech

Question Bank

Unit-1

CO1

1. Reduce the Matrix A to its Echelon form and find its rank, where $A = \begin{bmatrix} 4 & 2 & -1 & 2 \\ 1 & -1 & 2 & 1 \\ 2 & 2 & -2 & 0 \end{bmatrix}$
2. Reduce the following Matrix to its normal form and find its rank,
Where $A = \begin{bmatrix} 3 & 4 & 5 & 6 \\ 1 & 3 & 4 & 5 \\ 4 & 5 & 6 & 7 \\ 9 & 10 & 11 & 12 \end{bmatrix}$
3. Find inverse of matrix by adjoint Method. $A = \begin{bmatrix} 9 & 7 & 3 \\ 5 & -1 & 14 \\ 3 & 5 & 1 \end{bmatrix}$
4. Examine the consistence of following equations, if consistent solve
 $x + y - z = 0, \quad 2x - y + z = 3, \quad 4x + 2y - 2z = 2$
5. Examine for linear dependence or independence of vectors $(1, -1, 1), (2, 1, 1), (3, 0, 2)$. If dependent find the relation between them.
6. Examine for linear dependence or independence of vectors, if dependence find the relation between them $x_1 = (2, 1, -1, 1), x_2 = (1, 2, 1, -1)$ and $x_3 = (1, 1, 2, 1)$
7. Reduce the following Matrix to its normal form and find its rank.

$$\begin{bmatrix} 1 & 1 & -1 & 1 \\ 1 & -1 & 2 & -1 \\ 3 & 1 & 0 & 1 \end{bmatrix}$$

Unit-2

CO 2

1. Determine the eigen values and corresponding eigen vectors of the following matrix

a. $\begin{bmatrix} 4 & 6 & 6 \\ 1 & 3 & 2 \\ -1 & -4 & -3 \end{bmatrix}$

b. $\begin{bmatrix} 2 & 1 & 1 \\ 2 & 3 & 2 \\ 3 & 3 & 4 \end{bmatrix}$

c. $\begin{bmatrix} 2 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 2 & 0 \end{bmatrix}$

d. $\begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix}$

2. Verify Cayley Hamilton theorem for matrix A and use it to find A^{-1} where

$$A = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 3 & -3 \\ -2 & -4 & -4 \end{bmatrix}$$

3. Verify Cayley Hamilton theorem for matrix A and use it to find A^{-1} where $A = \begin{bmatrix} 1 & 3 & 7 \\ 4 & 2 & 3 \\ 1 & 2 & 1 \end{bmatrix}$

4. Using Sylvester Theorem prove that: $\sin^2 A + \cos^2 A = I$, where $A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$

5. Show that the matrix A is diagonalizable where $A = \begin{bmatrix} 1 & -2 \\ -5 & 4 \end{bmatrix}$

6. Show that the following Matrix A is diagonalizable where $A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$

7. Determine the eigen values and eigen vector of the following matrix Where $\begin{bmatrix} 2 & 3 & 4 \\ 4 & 3 & 1 \\ 1 & 2 & 4 \end{bmatrix}$

8. Using Sylvester Theorem, find inverse of matrix A where $A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$

9. Using Sylvester Theorem prove that: $3 \tan A = (\tan 3A)$, where $A = \begin{bmatrix} -1 & 4 \\ 2 & 1 \end{bmatrix}$

Unit-3: Differential Calculus of single variable

CO3

Mean Value Theorems

Q.1 Verify Rolle's Theorem for the following function $f(x) = x^2(1 - x^2)$, $x \in [0, 1]$

Q.2 Verify Lagrange's Mean value theorem for $f(x) = x(x - 1)(x - 2)$, $x \in [0, 1/2]$

Q.3 Verify Cauchy's Mean value theorem for the following function

a) $f(x) = \sin x$ and $g(x) = \cos x$ in $\left[0, \frac{\pi}{2}\right]$

b) $f(x) = x^2 + 2$ and $g(x) = x^3 - 1$ in $[1, 2]$

Successive Differentiation and Leibnitz theorem

Q.4 If $y = \sin[\log(x^2 + 2x + 1)]$ then prove that

$$(x + 1)^2 y_{n+2} + (2n + 1)(x + 1)y_{n+1} + (n^2 + 4)y_n = 0$$

Q.5 Find the n^{th} derivative of 1) $x^2 e^x \cos x$ 2) $x^2 \tan^{-1} x$ 3) $\cos^4 x$

4) $e^{ax} \sin bx \cos cx$ 5) $\frac{2x+3}{5x+7}$

Q.6 If $y = e^{\tan^{-1} x}$ then prove that: $(1 + x^2)y_{n+1} + (2nx - 1)y_n + n(n - 1)y_{n-1} = 0$

Taylor's and Maclaurin's Series

Q.5 Expand $\log[1 + e^x]$ by Maclaurin's theorem as far as the term in x^4

- Q.7. Expand $\sec x$ by Maclaurin's theorem as far as the term in x^4
- Q.6. Using Taylor's theorem express $2x^3 + 7x^2 + x - 6$ in Powers of $(x - 2)$
- Q.7. Using Taylor's theorem express $(x - 2)^4 - 3(x - 2)^3 + 4(x - 2)^2 + 5$ in Powers of x
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Unit-IV: Differential calculus of Functions of Several Variables

CO4

First and higher order Partial derivatives

1. If $u = x^2 \tan^{-1} \frac{y}{x} - y^2 \tan^{-1} \frac{x}{y}$, Find $\frac{\partial^2 u}{\partial x \partial y}$
2. IF $u = x^y$, then verify that $\frac{\partial^2 u}{\partial x \partial y} = \frac{\partial^2 u}{\partial y \partial x}$
3. IF $u = \log(x^2 + y^2)$ Verify that $u_{xy} = u_{yx}$
4. Find the value of n for which $z = t^n e^{-\frac{r^2}{4t}}$ satisfies the partial differential equation
$$\frac{1}{r^2} \left[\frac{\partial}{\partial r} \left(r^2 \frac{\partial z}{\partial r} \right) \right] = \frac{\partial z}{\partial t}$$

Euler's Theorem

5. If $u = \operatorname{cosec}^{-1} \sqrt{\frac{x^{1/2} + y^{1/2}}{x^{1/3} + y^{1/3}}}$, show that
$$x^2 \frac{\partial^2 u}{\partial x^2} + 2xy \frac{\partial^2 u}{\partial x \partial y} + y^2 \frac{\partial^2 u}{\partial y^2} = \frac{\tan u}{12} \left(\frac{13}{12} + \frac{\tan^2 u}{12} \right)$$
6. If $u = \tan^{-1} \left(\frac{x^3 + y^3}{x - y} \right)$ show that
$$x^2 \frac{\partial^2 u}{\partial x^2} + 2xy \frac{\partial^2 u}{\partial x \partial y} + y^2 \frac{\partial^2 u}{\partial y^2} = \frac{\tan u}{12} (1 - 4 \sin^2 u) \sin 2u$$

Jacobians

7. If $x = r \cos \theta$, $y = r \sin \theta$ then evaluate $\frac{\partial(x,y)}{\partial(r,\theta)}$ and $\frac{\partial(r,\theta)}{\partial(x,y)}$
8. If $u = xyz$, $v = x^2 + y^2 + z^2$, $w = x + y + z$ find $\frac{\partial(u, v, w)}{\partial(x, y, z)}$
9. For the transformation $x = e^u \cos v$, $y = e^u \sin v$ prove that $\frac{\partial(x,y)}{\partial(u,v)} \cdot \frac{\partial(u,v)}{\partial(x,y)} = 1$

Maxima and Minima of Function of two Variables

10. Determine the points where the function $x^3 + y^3 - 3axy$ has a maximum or minimum
11. Discuss maxima and minima of $x^3 y^3 (1 - x - y)$
12. Locate the stationary points of $x^4 + y^4 - 2x + 4xy - 2y^2$ and determine their nature.

Lagrange's Method of Undetermined Multipliers

13. Prove that the stationary values of $x^m y^n z^p$ under the condition $x + y + z = a$ is

$$m^m n^n p^p \left(\frac{a}{m+n+p} \right)^{m+n+p}$$

14. As the dimensions of a triangle ABC are varied, show that the maximum value of $\cos A \cdot \cos B \cdot \cos C$ is obtained when the triangle is equilateral.

Unit V: Vector Calculus

CO5

- Find the angle between the tangents to the curve $\vec{r} = (t^2 + 1)\mathbf{i} + (4t - 3)\mathbf{j} + (2t^2 - 6t)\mathbf{k}$ at $t = 0$ and $t = 2$.
 - Find $\nabla\phi$ for a) $\phi = \log(x^2 + y^2 + z^2)$ b) $\phi = 2xz^4 - x^2y$ at $(2, -2, 1)$
- Find $\nabla\phi$ for
 - $\phi = x^2 + y^2 + z^2$ at $(1, 1, 1)$
 - $\phi = r^m$ where $\vec{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$
 - $\phi = e^{-r}r^3$
 - prove that $\nabla f(r) = \frac{f'(r)}{r} \vec{r}$
- Find the directional derivative of the function $\phi = e^{2x} \cos yz$ at a point $(0, 0, 0)$ in the direction of the tangent to the curve $x = a \sin t$, $y = a \cos t$, $z = at$, at $t = \frac{\pi}{4}$.
- Find the directional derivative of the function $\phi = xy^2 + yz^3$ at a point $(1, -1, 1)$ in t
 - Along the vector $2\mathbf{i} - 3\mathbf{j} + 6\mathbf{k}$
 - Towards the point $(2, -1, -1)$
 - Along the direction of the normal to the surface $x^2 + y^2 + z^2 = 9$ at $(1, 2, 2)$.
- Given that $\vec{u} = xyz\mathbf{i} + (2x^2z - y^2x)\mathbf{j} + xz^3\mathbf{k}$, $\vec{v} = x^2\mathbf{i} + 2yz\mathbf{j} + (1 + 2z)\mathbf{k}$ and $\phi = xy + yz + z^2$. Find the following at $(1, 0, -1)$
 - $\nabla \cdot \vec{u}$
 - $\nabla \times \vec{v}$
 - $\nabla \cdot (\phi \vec{u})$
 - $\nabla \times (\phi \vec{v})$
- For the constant vector \vec{a} show that
 - $\nabla(\vec{a} \cdot \vec{r}) = \vec{a}$
 - $\nabla \times (\vec{a} \times \vec{r}) = 2\vec{a}$
 - $\nabla \left(\frac{\vec{a} \cdot \vec{r}}{r^n} \right) = \frac{\vec{a}}{r^n} - \frac{n(\vec{a} \cdot \vec{r})}{r^{n+2}} \vec{r}$
- Show that vectors $\vec{F} = (6xy + z^3)\mathbf{i} + (3x^2 - z)\mathbf{j} + (3xz^2 - y)\mathbf{k}$ is irrotational. Also find the Scalar Potential Function ϕ such that $\vec{F} = \nabla\phi$
- Show that the vector $\left(\frac{\vec{a} \times \vec{r}}{r^n} \right)$ is solenoidal
- Show that $\nabla f(r) = \frac{f'(r)}{r} \vec{r}$ and hence prove that $\nabla^4 e^r = e^r + \frac{4}{r} e^r$
- Show that $\nabla \times \left[\frac{\vec{a} \times \vec{r}}{r^3} \right] = -\frac{\vec{a}}{r^3} + \frac{3(\vec{a} \cdot \vec{r})}{r^5} \vec{r}$
- For the scalar functions ϕ and Ψ , show that:
 - $\nabla \cdot (\phi \nabla \Psi - \Psi \nabla \phi) = \phi \nabla^2 \Psi - \Psi \nabla^2 \phi$
 - $\nabla^2 (\phi \Psi) = \phi \nabla^2 \Psi + 2(\nabla \phi \cdot \nabla \Psi) + \Psi \nabla^2 \phi$
