

# PAWS Root Systems: PROBLEM SET 2

Devjani Basu, Marcella Manivel, Mishty Ray, Ajmain Yamin

September 30, 2024

**Question 1:** This question asks us to use the definition of  $B_2$  to determine the characterization of  $B_3$  and then  $B_\ell$ .

- (1) Recall the definition of  $B_2$  and compute the Euclidean lengths of the roots as vectors. Notice that there are roots of length 1 and roots of length  $\sqrt{2}$ . Check that these are all the vectors in  $\mathbb{R}^2$  with integer coordinates and with Euclidean length 1 or  $\sqrt{2}$ .
- (2) List all the vectors in  $\mathbb{R}^3$  with integer coordinates and with Euclidean length 1. *Hint: there should be 6.* List all the vectors in  $\mathbb{R}^3$  with integer coordinates and with Euclidean length  $\sqrt{2}$ . *Hint: there should be 12.*
- (3) Prove that the set of vectors in  $\mathbb{R}^3$  with integer coordinates and Euclidean length 1 or  $\sqrt{2}$  is a root system. This is the  $B_3$  root system.
- (3) Make a guess for a definition of  $B_\ell$ . List all the vectors in  $B_\ell$ .
- (4) Check your guess with section 8.10.3 of Hall's *Lie Groups, Lie Algebras, and Representations*. The book is available at Springer's website or on ResearchGate (link to download).

**Question 2:** With the  $A_1 \times A_1$  root system as given in the notes, draw the integral span of  $\Phi$ . That is, draw

$$m_1(e_1 - e_2) + m_2(-e_1 + e_2) + m_3(e_1 + e_2) + m_4(-e_1 - e_2) \quad \text{with } m_i \in \mathbb{Z}.$$

**Question 3:** The **dual** of a root system  $\Phi$  in the finite dimensional real vector space  $V$  is the set

$$\Phi^\vee = \{\alpha^\vee = \frac{2\alpha}{(\alpha, \alpha)} \mid \alpha \in \Phi\}.$$

- (1) Prove that  $\Phi^\vee$  is a root system in  $V$ .
- (2) Prove that the Weyl group of  $\Phi^\vee$  is isomorphic to the Weyl group of  $\Phi$ .
- (3) Show that  $\langle \alpha^\vee, \beta^\vee \rangle = \langle \beta, \alpha \rangle$ .
- <sup>\*</sup>(4) Draw a picture of  $\Phi^\vee$  in the cases of  $A_1$ ,  $A_2$ ,  $B_2$ ,  $G_2$ .

**Definition.** Let  $\Delta$  be a base for a root system  $\Phi$ . For  $\beta \in \Phi$ , there is a unique way to write

$$\beta = \sum_{\alpha \in \Delta} c_{\alpha} \alpha.$$

The **height** of  $\beta$  (relative to  $\Delta$ ), denoted  $ht(\beta)$ , is  $ht(\beta) := \sum_{\alpha \in \Delta} c_{\alpha}$ .

**Question 4:** In your own words, what is the height measuring?

**Question 5:** Consider the  $B_2$  root system with

$$\Phi = \{\pm e_1, \pm e_2, \pm(e_1 + e_2), \pm(e_1 - e_2)\}.$$

One example of a base is  $\Delta = \{e_1, -e_1 + e_2\}$ .

(1) Express the remaining roots in  $\Phi$  in terms of the simple roots in  $\Delta$ .

(2) Find the height of the following roots with respect to  $\Delta$ :

- (a)  $e_1$
- (b)  $e_2$
- (c)  $e_1 + e_2$
- (d)  $-e_1 - e_2$

**\*Question 6:** If  $\beta$  is a positive root but not a simple root, prove that  $ht(\beta) > 1$ .

**\*Question 7:** Any root  $\beta \in \Phi$  can be expressed uniquely as

$$\beta = \sum_{\alpha \in \Delta} c_{\alpha} \alpha$$

where all  $c_{\alpha} \geq 0$  or all  $c_{\alpha} \leq 0$ . Prove that if  $\beta$  is not a multiple of a root, then there exists Weyl group element  $w \in W$  such that

$$w(\beta) = \sum_{\alpha \in \Delta} c'_{\alpha} \alpha \text{ with some } c'_{\alpha} > 0 \text{ and some } c'_{\alpha} < 0.$$

**\*Question 8:** Show that the Weyl group of  $B_{\ell}$  is the group of transformations expressible as a composition of a permutation of the entries and an arbitrary number of sign changes.

**Question 9:**

(1) Prove that Weyl groups of  $A_1 \times A_1$ ,  $A_2$ ,  $B_2$ ,  $G_2$  are dihedral groups of order 4, 6, 8 and 12, respectively.

**\*(2)** Prove that if  $\Phi$  is any root system of rank 2, its Weyl group must be isomorphic to one of these.

**Question 10:** Prove that the Weyl group  $W$  of a root system  $\Phi$  is a normal subgroup of  $\text{Aut}(\Phi)$ , the group of linear automorphisms of  $V$  preserving  $\Phi$  set-wise.

**Question 11:** Determine the Weyl group of  $A_l$ .

**Question 12:** At the end of the lecture, Dr. Emory mentions the Lie algebras that our root systems correspond to. This question is meant to familiarize us with Lie algebras. A *Lie algebra* is a vector space  $V$  with a binary operation, called the Lie bracket, denoted  $[\cdot, \cdot] : V \times V \rightarrow V$  that is bilinear, anti-symmetric, and satisfies the Jacobi identity.<sup>1</sup>

In this problem, we consider the example

$$\mathfrak{sl}(3, \mathbb{C}) := \{A \in M_{3,2}(\mathbb{C}) \mid \text{tr}(A) = 0\}$$

which is an 8-dimensional vector space (there's 9 entries in each matrix and the trace zero condition removes one degree of freedom). The Lie bracket in  $\mathfrak{sl}(3, \mathbb{C})$  is defined as

$$[A, B] := AB - BA$$

(1) Compute  $\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$ .

(2) Witness an example of anti-symmetry by computing

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

and comparing with part (1).

(3) Verify that the Jacobi identity holds for

$$X = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, Y = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, Z = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}.$$

(4) Lie algebras matter because they are the tangent space at the identity of a Lie group. To recover the Lie group  $SL(3, \mathbb{C})$ , we can apply the matrix exponential map to elements in  $\mathfrak{sl}(3, \mathbb{C})$ . For any square matrix  $X$ , the matrix exponential is defined as

$$\exp(X) := Id + X + \frac{1}{2!}X^2 + \frac{1}{3!}X^3 + \frac{1}{4!}X^4 + \dots \quad (1)$$

Compute  $\exp\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}\right)$  and find  $\det(\exp\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}\right))$ .

---

<sup>1</sup>Bilinear means that for  $X, Y, Z \in \mathfrak{sl}(3, \mathbb{C})$  and  $a, b$  scalars  $[aX + bY, Z] = a[X, Z] + b[Y, Z]$  and  $[Z, aX + bY] = a[Z, X] + b[Z, Y]$ .

Anti-symmetry means that  $[X, Y] = -[Y, X]$ .

The Jacobi identity means that  $[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$ .