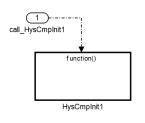
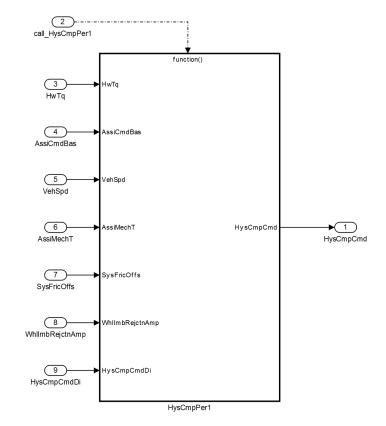


SF012A Hysterisis Compensation Version: 1.0.0

Date: Jul 8, 2015

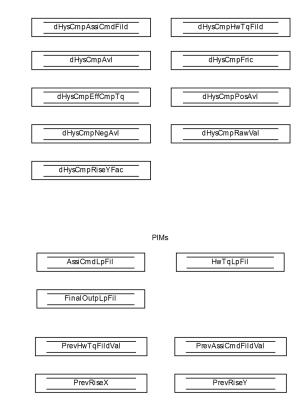
This function improves steering precision and feel by compensating for physical friction and efficiency losses. Due to the vibratory nature of a vehicle, the calibrations associated with these physical attributes are allowed to vary according to vehicle speed and the magnitude of Wheel Imbalance Rejection function command. The function includes a feature to deal with changing physical system properties over temperature operating range. It also incorporates calibration tables used to modify how the compensation is applied during transitions between operating quadrants and during periods of near-zero handwheel torque. Finally the function may be disabled for purposes of bench testing





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Display Variables



SF012A_HysCmp/HysCmp

f() function

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FilLpInit

Ic: 0

Ts: ARCHGLBPRM_2MILLISEC_SEC_F32

Freq: HysCmpAssiCmdLpFilFrq

StVar: AssiCmdLpFil

HysCmpAssiCmdLpFillnit

FilLpInit

Ic: 0

Ts: ARCHGLBPRM_2MILLISEC_SEC_F32

Freq: HysCmpFinalOutpLpFilFrq

StVar: FinalOutpLpFil

HysCmpFinalOutpLpFil

FilLpInit

Ic: 0

Ts: ARCHGLBPRM_2MILLISEC_SEC_F32

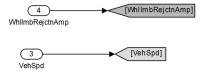
Freq: HysCmpHwTqLpFilFrq

StVar. HwTqLpFil

HysCmpHwTqLpFillnit

SF012A_HysCmp/HysCmp/HysCmpPer1/CalcAvlCmp

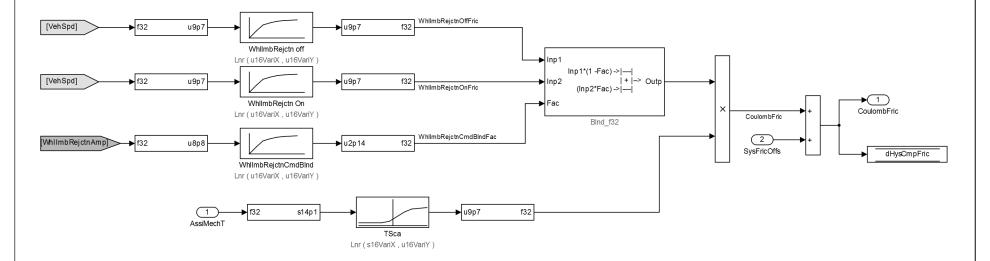
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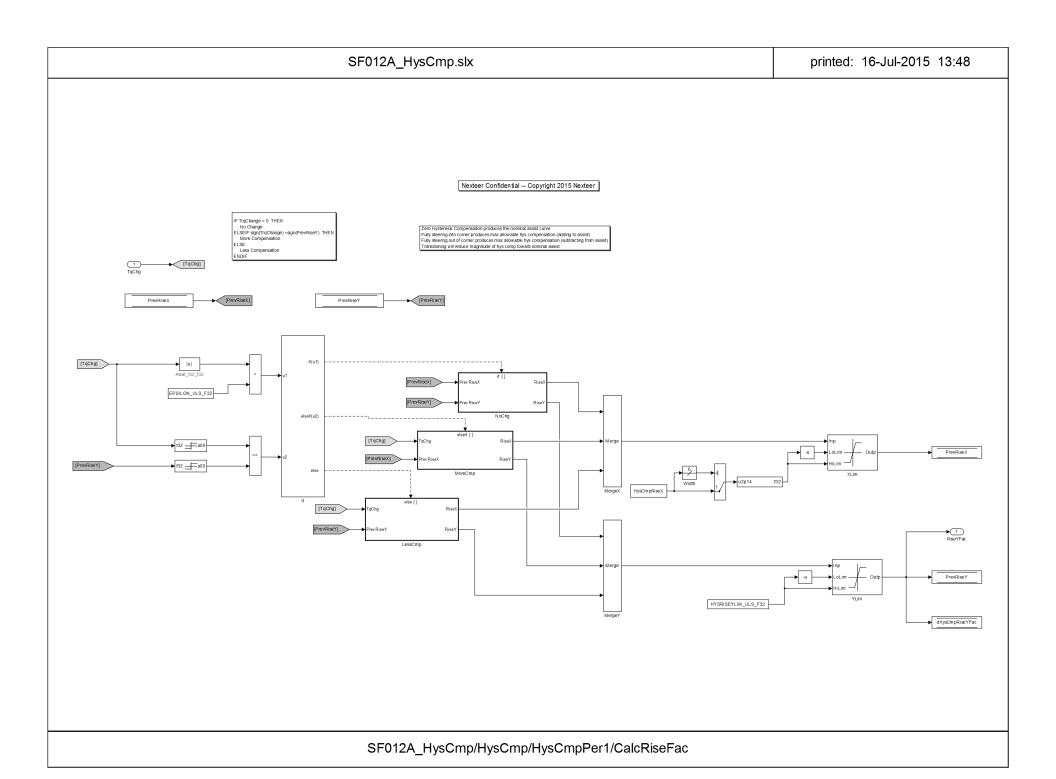


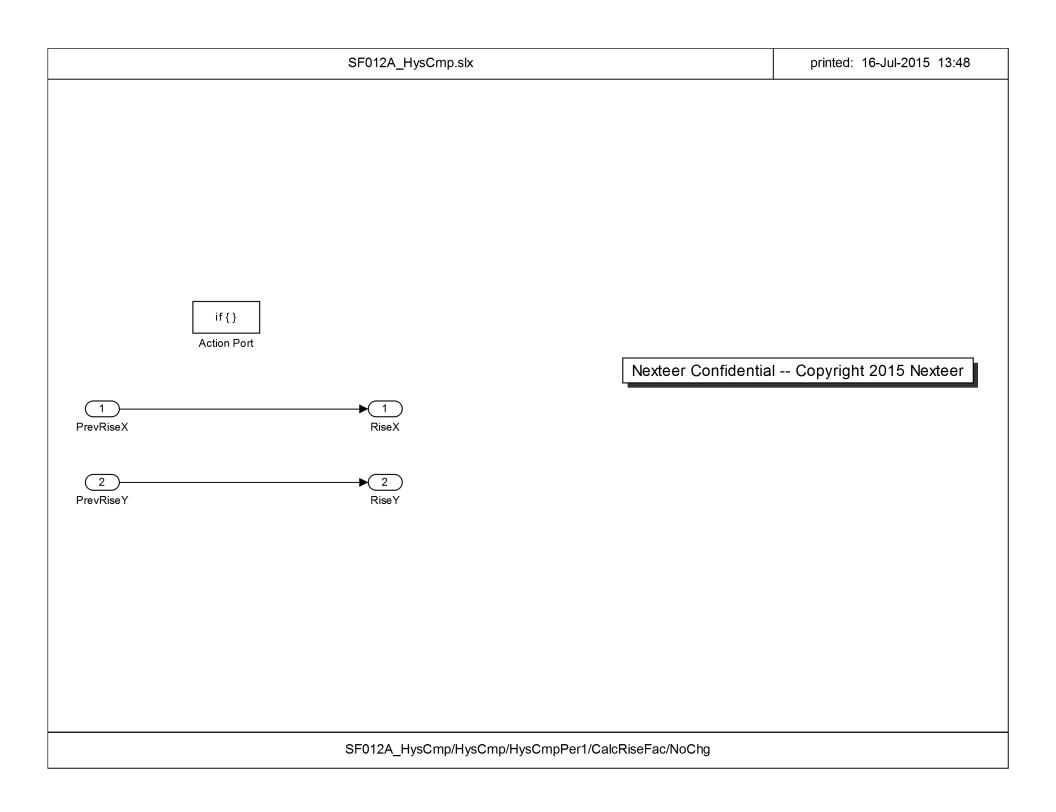
For a given vehicle speed, find the constant friction value, then blend between them according to "CoulFricWIRBInd" table".

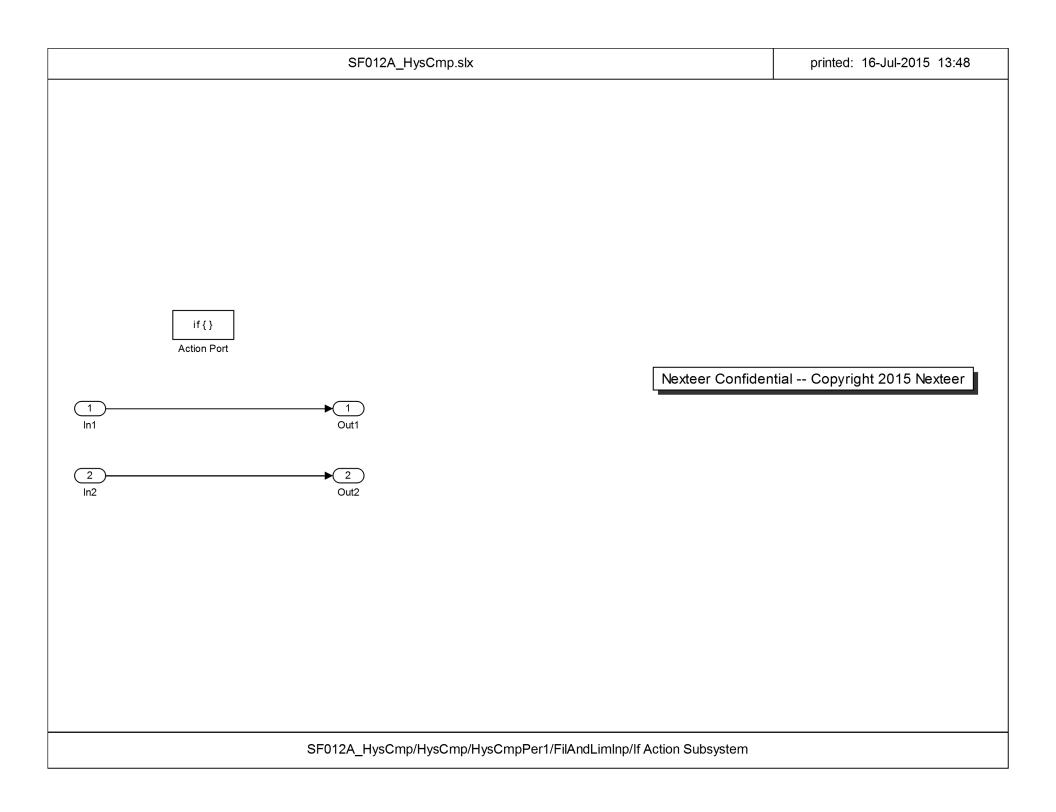
Then scale the whole thing up or down according to the ball nut temperature signal.

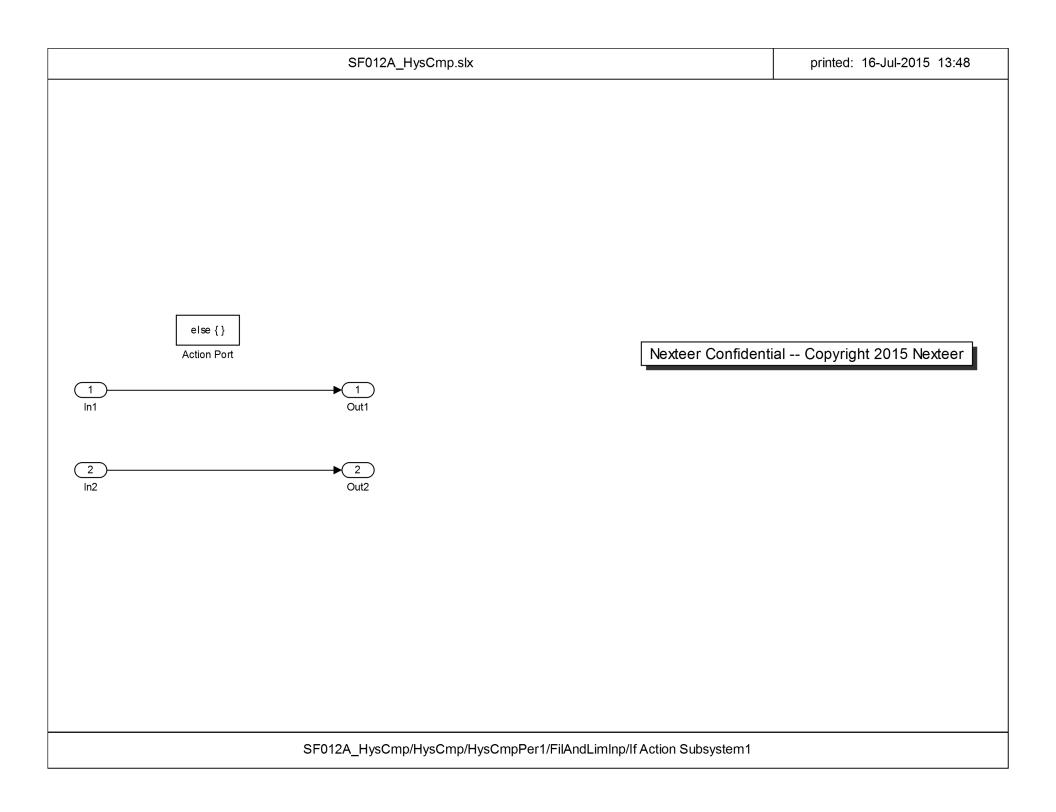
Finally, adjust by the offset value recevied from SF-07 Average Learned Friction.

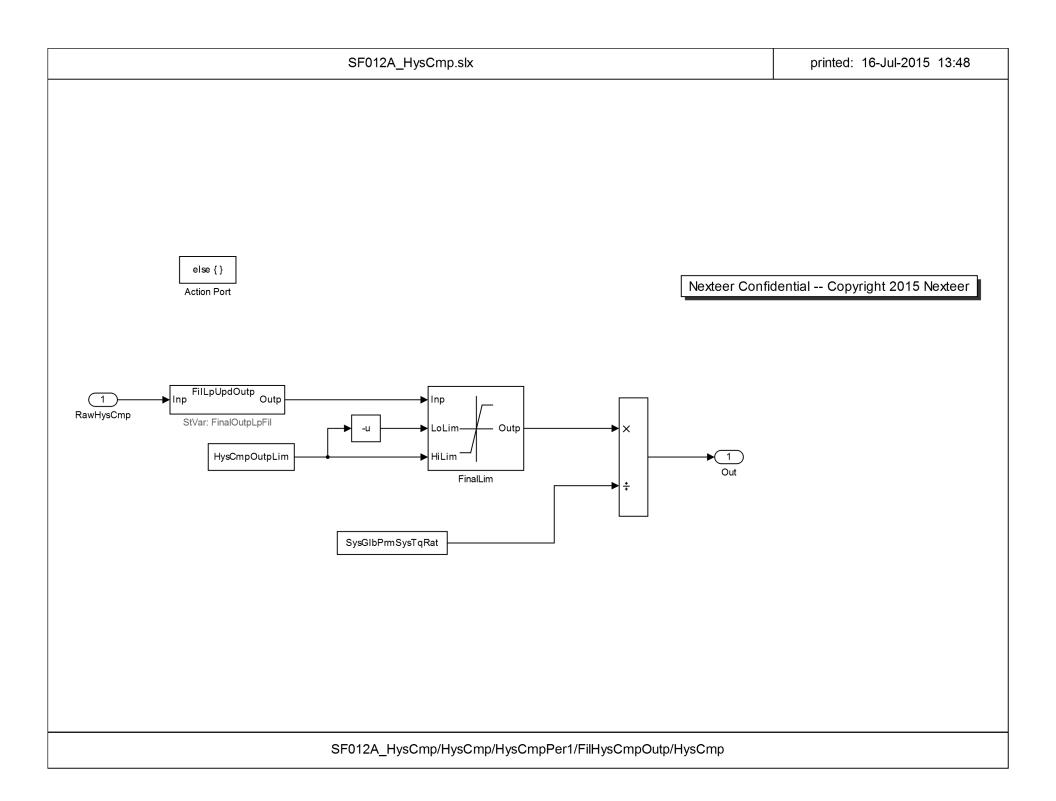












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if {}		
Action Port		
		Nexteer Confidential Copyright 2015 Nexteer
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Enable			
f() 1 Function-Call Out1			
Generator			
SF012A_HysCmp/call_HysCmplnit1			