

Vector CAN Driver

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Document Information

History

Author	Date	Version	Remarks
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) Implementatio	ns Hin	ts			
	! !	!!		!!!	
Confinuention					
Configuration.		!	!		
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Known Issues	/ Limit	ation	ne		4
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1 Introduction

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2 Important References

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Driver Version	Suppor Compile	ted ers	Supported Derivatives	Hardware	Manuf	acturer	Documen	t	Versio	n
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3 Usage of Controller Features

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3.1 [#hw_comObj] - Communication Objects

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[0] RX Buffer Rx FullCAN nRXMBmax receive buffers shared over all channels [max 127] RX Buffer [128] RX FIFO Rx BasicCAN 8 receive FIFOs shared over all channels [135] RX FIFO [160] TX Buffer Tx Normal, LowLevel, FullCAN 16 transmit buffers physical channel CAN0 [175] TX Buffer [176] TX Buffer Tx Normal, LowLevel, FullCAN 16 transmit buffers physical channel CAN1 [191] TX Buffer [272] TX Buffer Tx Normal, LowLevel, FullCAN 16 transmit buffers physical channel CAN7 [287] TX Buffer

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Note ! -! ! !-!! !!! ! !!!!! !! 1 ! ! !! !! ! !! !! !! !! !! ! !!

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Obj number	Hw object type	Log object type	No. of objects	Comment
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-	!		-	
-! !! !-	!	!	- !	! !
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Obj number	Hw object type	Log object type	No. of objects	Comment
-	!! !			
! !	!	!	!	! !! ! !CanTransmit()! ! ! ! !! !! ! !!! !! !! ! !!!!! !! !!
!!	!	!!!	! ! ! !	! !! !! CanMsgTransmit()!!!! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
!! !! ! - !! !! !!	!	!	- ! !!!	! !!!!!!!!! CanTransmit()!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
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3.2 Acceptance Filters

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4 [#hw sleep] - SleepMode and WakeUp 4.1 Sleep CanResetBusSleep() ! !!!!!!!!!he return value kCanOk is always expected. However, if the function returns kCanFailed **call** CanSleep()!!!-!!! 4.2 Internal Wakeup ! !!- !! 4.3 External Wakeup ! ! ! ApplCanPreWakeUp()! ! ! !

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!! ! #define C ENABLE EXTERNAL WAKEUP SUPPRESSION



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5 [#hw_loop] - Hardware Loop Check



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kCanLoopInit ! !! !!!!! !!! ! ! !!!! !!! ! !!!!!! !!!

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kCanLo	oopE	EnterF	Rese	tMode										
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!!		!	!		!	!!	!Car	ıIni	tPowe	erOn()			

kCanLoo	pEn	terOp	erat	ion	Mod	le																
!		!			!	ļ		!		!			!	! Ca	an]	[nit() !	Can	Sta	art()!		!
CanWake	eUp(()!	!	!				!	!	!		!	!		!	!	!	!		!		!
	!	!																				
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!!!	! !	! !		!	!	!		!	Can	Sta	rt	t ()	!			! Ca	anW.	ake	Up()!	!	!

kCanLo	oopR	xFcl	Proc	ess																		
!		!			!	!	!	!			!	! C	anF	ul	lCa	nMs	gRece	ived	()!		!	!
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!Ca	nFu]	LlCa	anM	sgR	ecei	.ve	ed()!			!		!			!	!		!!				

!!!!! !! © !!!!!



6 [#hw_busoff] - Bus off



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7 CAN Driver Features

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7.1 [#hw_feature] - Feature List

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		Standard	HighEnd
	Initiali	zation	
Power-On Initialization	on	-	-
Re-Initialization		-	-
	Transm	nission	
Transmit Request			
Transmit Request Q	ueue		
Internal data copy m	echanism		
Pretransmit functions	S		
Common confirmation	n function		
Confirmation flag			
Confirmation function	n	-	
Offline Mode		-	
Partial Offline Mode		-	
Passive-Mode		-	
Tx Observe mode		-	-
Dynamic TxObjects	ID	-	
	DLC	-	
	Data-Ptr		
Full CAN Tx Objects			
Cancellation in Hard	ware	-	
Low Level Message	Transmit	-	
	Rece	ption	
Receive function			
Search algorithms	Linear		
	Table	-	-
	Index		
	Hash	-	
Range specific preco (min. 2, typ.4)	opy functions	4	4
DLC check			
Internal data copy m	echanism		
Generic precopy fun	ction	-	
Precopy function		-	
Indication flag		-	
Indication function		-	
Message not matche	ed function	-	

!!!!!!



Overrun Notification	=	
Full CAN overrun notification	-	-
Multiple Basic CAN	-	-
Rx Queue ²	-	-
Bus	off	
Notification function	=	
Nested Recovery functions	=	
Sleep	Mode	
Mode Change	=	
Preparation	=	-
Notification function		
Special F	eatures	
Status	=	
Security Level	=	
Assertions	=	-
Hardware loop check	=	-
Stop Mode	=	
Support of OSEK operating system		
Polling Mode Tx		

! ! !! ! ! !! © !!!!!



7.2 Description of Hardware-related Features

7.2.1 [#hw_status] - Status

Status	Support
CanHwIsOk(state)	-
CanHwIsWarning(state)	
CanHwIsPassive(state)	
CanHwIsBusOff(state)	
CanHwIsWakeup(state)	
CanHwIsSleep(state)	
CanHwIsStart(state)	
CanHwIsStop(state)	
CanIsOnline(state)	
CanIsOffline(state)	

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7.2.2 [#hw_stop] - Stop Mode

7.2.3 [#hw int] - Control of CAN Interrupts

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Caution !</

7.2.4 [#hw_cancel] - Cancel in Hardware

							Yes	No
! !CanTxTask()! ! ! !!!	!	!!	!	!!	!!	!		-

! !! !CanCancelTransmit()! CanCancelMessageTransmit()

														Yes	No
ApplCanTxConf	irn	nati	on()!	!		!	ļ.	!		!		!	!		
!	!	!	!		!	!		!	!	!	!!	!!	!	-	
!!	!	!		!		!!	!			!!	!!				

7.2.5	Remote Frames	
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!	!	!	!	!	!	!	!	!		!	!	!	!	
!	!!		!											

7.2.6 CAN RAM Check

!	!	!		!	!		!!	!		!			!		!!			!			!
ļ	!!	!		! (CanIr	nit	!()!	!		!	!		!		!		!	!	!		!
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	! ! !ApplCanCorruptMailbox()! ! ! ! ! ! ! !!!!!
7.2.7 Extended CAN RAM Check	
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !	
! ! ! ! ! ! ! ! CanInit()!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
<pre>! ! ! ! ! ! ! ! !!!!!!!!!!!!!!!!!!!!!!</pre>	bleCommunication!!!!!
ApplCanCorruptRegisters()!!!! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	

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Caution !!!!-!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
Switch Value Description
7.2.8 RSCAN ECC Configuration ! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
Switch Value Description
! ! !ApplCanEccConfiguration()

! ! ! ! !

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7.2.9	RSCAI	N RAN	/I Tes	t											
!	!		!!	!	!	!	!		!	!	!!		!!	!	!!
!	!		!	!	!!	!		!		!	!		!	!	!!
	!	!	!Ca	nIni	tPow	rerOn	()!		!!	!		!	!	!	!
!	!	!!		!		!!		!		!	!	!	!!		!
!		!	!	!		!!	!	!	!		!		!!	!	!
!	!!!	!	-	!		! App	1Ca	nGlol	oal!	MemC	heckFa	aile	d()	!	!
!	!	!!	!		!	!kC	CanE	nabl	eCo	mmur	nicati	on!	!		!!
	!	!	!	!	!	!	!!	!		! kCa	nDisa	bleC	Commu	nica	tion!
!	!!	!	!	!	!	!	!		Can	Init	Power	On ()	!	!	!
	1 1		l Ca	nTni	+ Pow	<i>i</i> erOn	()								



8 [#hw_assert] - Assertions

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9 API

9.1 Category

Single Receive Channels (SRC)									
•	!	!	!	!	!	!	!	!	!
Multiple Receive Channel (MRC)		-	-	-		-			
	1								
		!!	!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	l,	! !	!!		!	!
		!	!!	! !Ca	nOnli	ine()!		!!	!
	Cano	Online(channel	l) ! !	!	!!	!!	!	
		!	!!	!CanTra	ansmi	t(txHan	dle)		

9.2 RSCAN	I ECC	Configuration
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ApplCanEccConfiguration

Prototype		
!!!	void	(void)
!!!	void	(void)
Parameter		
_	_	
Return code		
_	_	
Functional Description		
! !!!!Cai	nInitPowerOn()!!!!!	111 1 1
Particularities and Limit	ations	
!!!C_ENABLE_	ECC_CALLOUT!!	



9.3 (Extended) CAN RAM Check

ApplCanMemCheckFailed

Prototype													
!	!	vuint8	uint8 (void)										
!	!	vuint8	uint8 (CanChannelHandle channel)										
Paramete	r												
CanChannel	Handle channel	!	!	!	!	!	!!	!	!	!	!!	!	
Return co	de												

vuint8



ApplCanCorruptMailbox

Prototype														
!!!	void			((CanOb	jec	tHa	ndle	hwOk	ojHan	dle)		
!!	void CanObjec	tHandle h	wObjHa		CanCh	ann	elH	andl	e cha	annel	,			
Parameter														
CanChannelHandle channel	ļ !	!	!	!!!		!	!	!	!		!	!	!	
CanObjectHandle hwObjHandle	!	!	!	!	!!	!		!						
Return code														
_	_													
Functional Description														
!!!!!!	CanInit()!!!	!	!!	!	!		!						П
Particularities and Limit	ations													
Call context!!!!	!	!!	!	!		!	!		!!	!	!	!	!	!
!!!!!	!!!													
Configuration!!	!!	!!												
!!!!!	! ! !	!!!	!	!		!			!		. 41	!		ļ
	! ! !	!!	!	!		!				Corr	upt		ister	S
Prototype		!!	!	!						Corr	upt		ister	s
Prototype	void	!!!	!	!	(voi	.d)		Арр	lCan				ister	S
Prototype !!!		!!!		•	(voi	.d)		Арр	lCan	Corr			ister	s
Prototype	void	!			(voi	.d)	nne	Арр	l Can			Reg	ister !	s I
Prototype !!! Parameter CanChannelHandle channel	void void				(voi	.d) ıCha	nne	App	l Can		nel)	Reg		s
Prototype	void void !				(voi	.d) ıCha	nne	App	l Can		nel)	Reg		S
Prototype !!! !! Parameter CanChannelHandle channel Return code -	void void				(voi	.d) ıCha	nne	App	l Can		nel)	Reg		s
Prototype !!! Parameter CanChannelHandle channel Return code - Functional Description	void void !	!	!	!	(voi	.d) aCha !	.nne	App	l Can		nel)	Reg		S
Prototype !!!! Parameter CanChannelHandle channel Return code - Functional Description !!!!!!	void void !	!		!	(voi	.d) ıCha	.nne	App	l Can		nel)	Reg		S
Prototype !!! Parameter CanChannelHandle channel Return code - Functional Description !!!!!	void void !	!	!		(voi	.d) Cha	nne !	App 1Han	lCan	chanr	nel)	Reg	!	s
Prototype !!! !Parameter CanChannelHandle channel Return code - Functional Description !!!!! Particularities and Limit Call context!!!! CanResetBusOffEnd()!	void void ! - !!!	! ! ! !!!	!	!	(voi (Car !	d) ! !	nne!!	App IHan ! ! !	lCan	chanr ! !!	! !	Reg		S

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ApplCanGlobalMemCheckFailed

Proto	type		
	!	!	vuint8 (void)
	!	!	vuint8 (void)
Paran	neter		
_			-
Retur	n coc	de	
vuint8			!!!!
Funct	tional	Description	
!	! ! !	! !! !! !!! !!!	
Partic	culari	ties and Limit	tations
Call co			! !!!!!!CanInitPowerOn()
Impor ! !	!	ote: ! ! !! ! !!!	! ! !!kCanEnableCommunication!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!

! ! !! ! ! ! !! © !!!!!



CanEnableChannelCommunication

Prototype	
!!!	void (vuint8 suppressRamCheck)
1 1	void (CanChannelHandle channel, vuint8 suppressRamCheck)
Parameter	
CanChannelHandle channel	! !!!!!!-
vuint8 suppressRamCheck	! !!! !!- !! !!!
	! !!! !!- !! !!!
Return code	
-	-
Functional Description	
! ! - ! ! ! ! ! ! ! ! ! !	! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
Particularities and Limita	ations
Restriction!! Call context!!! Configuration!!	! ! !! ! !CanInit()! ! !!!! ! !!!



CanEnableMailboxCommunication

Prototype	
!!!	vuint8 (CanObjectHandle hwObjHandle)
!!!	vuint8 (CanChannelHandle channel, CanObjectHandle hwObjHandle)
Parameter	
CanChannelHandle channel	-
CanObjectHandle hwObjHandle	! !!!! !!!-
Return code	
vuint8	!! ! !!- !! !!!!!!hwObjHandle!! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
Functional Description	
!!-!!	
Particularities and Limit	ations
Call context!!!! Configuration!!	! !!! ! !!!



! ! -	!!!		!	!!			!								
									Os	Car	nCanl	nterr	upt	Dis	able
Prototype															
!!!	void						(voi	d)							
!!!	void						(Can	Cha	nnel	.Han	dle ch	nanne	el)		
Parameter															
CanChannelHandle channel	!		!	!	!	!		!	!	!	!		!	!	!
Return code															
-	_														
unctional Description															
	nCanInt	errup	tDis	sable	()			_							
	ations				()										
Particularities and Limit !!C_ENABLE Prototype	ations				()				Os	Can	Canlı	nterr	uptl	Res	tore
Particularities and Limit !!C_ENABLE Prototype !!	ations				()		(voic	d)	Os	Can	Canlı	nterr	uptl	Res	tore
Particularities and Limit !!C_ENABLE Prototype !!!	ations _OSEK_CA				()						Canlı			Res	tore
Particularities and Limit !!C_ENABLE Prototype !!!	osek_CA			RL!!			(Can							Res	tore
Particularities and Limit ! ! !C_ENABLE Prototype !!! !!! Parameter	osek_CA	AN_IN		RL!!		!	(Can	Cha		.Hano	dle ch	nanne		Res	
Particularities and Limit !!!C_ENABLE Prototype !!! !! Parameter CanChannelHandle channel	void void	AN_IN	FCTR	RL!!		•	(Can	Cha	nnel	.Hano	dle ch	nanne	:1)		
Particularities and Limit ! ! ! C_ENABLE Prototype !!! !! Parameter CanChannelHandle channel Return code	void void	AN_IN	FCTR	RL!!		•	(Can	Cha	nnel	.Hano	dle ch	nanne	:1)		
Particularities and Limit ! ! ! C_ENABLE Prototype !!! !! Parameter CanChannelHandle channel Return code	void void	AN_IN	FCTR	RL!!		•	(Can	Cha	nnel	.Hano	dle ch	nanne	:1)		
Prototype !!! Parameter CanChannelHandle channel Return code !!!!!Ca	void void !	AN_IN	PCTR	RI! !	!	•	(Can	Cha	nnel	.Hano	dle ch	nanne	:1)		
Particularities and Limit !!C_ENABLE Prototype !!! !! Parameter CanChannelHandle channel Return code	void void !	AN_IN	PCTR	RI! !	!		(Can	Cha	nnel	.Hano	dle ch	nanne	:1)		

9.4 CAN Interrupt Handling by Application

!! © !!!!!



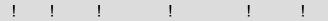
ApplCanWakeupInterruptDisable

Prototype												
1 !	void	(vuint8 channel)										
!!!	void	(vuint8 channel)										
Parameter												
vuint8 channel	!!!											
Return code												
_	_											
Functional Description												
! !!!!Car	nWakeup()! !CanIni	t()										
Particularities and Limit	ations											
! !!C_ENABLE_ !!!	OSEK_CAN_INTCTRL!	!C_ENABLE_SLEEP_WAKEUP! ! !										

ApplCanWakeupInterruptEnable

Prototype				
!!!	void		(vuint8 channel)	
!!!	void		(vuint8 channel)	
Parameter				
vuint8 channel	!!!	!!!!	1 1 1 1	!!!
Return code				
_	_			
Functional Description				
!!!!!Ca:	nSleep()			
Particularities and Limit	ations			
! !!C_ENABLE_ !!!	OSEK_CAN_INTCTRL!	!C_ENABLE_SL	EEP_WAKEUP!!	!!

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10 Implementations Hints

10.1 Important Notes

1. > ! ! !CanTransmit! !

! !CanSetPassive! ! ! !

2. !!!!!

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10.2 Interrupt Configuration

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!	!	!	!			!	!!			!		!	!	!	!Ca	anIn	itE	Powe	ron	()	
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CAN interrupt request name	CAN interrupt request cause	Provided service routine	Remarks
	!!!!	CanlsrRxFifo	Used for BasicCAN reception if ! B ! !!!!!!
	!!!!	CanlsrGlobalStatus	Used for Rx BasicCAN overrun if ! ! !
	!!!!	CanlsrTx_n	Used for transmission on physical channel n if !! is not enabled!!!!
	! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	-	This interrupt is not used.
	!!	CanlsrStatus_n	Used for BusOff detection on physical channel n if Error Polling is not enabled.
	!!!	CanlsrWakeup_n	Used for wakeup detection on physical channel n if the sleep/wakeup functionality is enabled, the external !!!!!

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!!!



```
!!!
       !
                                !!!!!!
                                !!
#pragma ghs interrupt
void CommonIsr Prio x ( void )
/* handling for other interrupts that are assigned to
  this priority and not handled by table reference */
/* CAN interrupts */
if (MK bit of INTRCANGRECC == 0) CanIsrRxFifo();
if (MK bit of INTRCANGERR == 0) CanIsrGlobalStatus();
if (MK bit of INTRCAN1ERR == 0) CanIsrStatus 1();
if (MK bit of INTRCAN1TRX == 0) CanIsrTx 1();
if (MK bit of INTRCAN4ERR == 0) CanIsrStatus 4();
if (MK bit of INTRCAN4TRX == 0) CanIsrTx 4();
/* handling for other interrupts that are assigned to
  this priority and not handled by table reference */
}
      Caution
     !!!!!
10.2.1 Configuration of Interrupt Vectors with IAR compiler
   !!!
   !!!
```

!

© ! ! !



#define	C_CANISRRXFIFO_VECTOR	15
#define	C_CANISRGLOBALSTATUS_VECTOR	14
#define	C_CANISRTX_VECTOR_2	211
#define	C_CANISRSTATUS_VECTOR_2	209
#define	C_CANISRWAKEUP_VECTOR_2	31
#define	C CANISRTX VECTOR 5	281
#define	C CANISRSTATUS VECTOR 5	279
#define	C CANISRWAKEUP VECTOR 5	36

1 1 1 1 1 1



Caution								
!!!	!	!!	!	!	!!	!!	!	!!
!	ļ.	!!	!	!	ļ.	!!!!	!	!!
!!	!							

10.3 CAN Interrupt Handling by Application
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
!
! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
OsCanCanInterruptDisable()!
! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
! ! ! ! ! ! ! ! ! ! C_ENABLE_OSEK_CAN_INTCTRL is defined ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

! ! ! ! ! ! ! !! © !!!!!



!App⊥Ca	anWakeup	Inter	ruptE	Enabl	.e()!	!		!		!!		!	! C	anSl	eep () !
!	!!	!!	!!	!			!		!		!		!	!!	!	!
!	!!!!	!	!		!!			!	!		!	!	!	!		
	!!	!	!!		!	!	!		!		ļ.	!	!	!		!
	!		!	!!	!!			!	!	ļ.		!	!			
!	!!!!		!		!	!	!	!	ļ	!		!	!	!	!	ļ
OsCanC	anInter	ruptD	isabl	e()												
performe	anWakeup ed by into gand in C ! !	errupts	in cor	ntext	of Ca	nWal	keup	(),	resp						_	
\wedge	Caution !C_ENA		SEK_CA	N_INT	「CTRL	!		!!	!	!	,	!!		!	!	

1 1 1 1 1

! ! ! ! ! ! !! © !!!!!

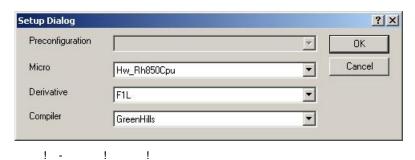


11 Configuration

11.1 Configuration by GENy



11.1.1 Platform Settings



Attribute	Supported Values	Description
		!!- !!!
		!!!!
	!!-	!!!!
	!!-	!!!

1 -1 1 1

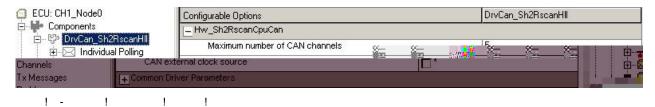
1 1 1 1



11.1.2 Component Settings

!

!!!!



!

!

! !! !-! Enter the maximum number of physical CAN channels that are supported by the actually used derivative. This value is independent from the number of channels in the configuration but used to determine the available hardware resources. Only if this value is correct the tool can ensure valid configurations for the actual derivative. Depending on the selected derivative not all values may be available. ! !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	Attribute	Supported Values	Description
(clk_xincan) as CAN clock !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	!!!	1-1	are supported by the actually used derivative. This value is independent from the number of channels in the configuration but used to determine the available hardware resources. Only if this value is correct the tool can ensure valid configurations for the actual derivative. Depending on the selected derivative
	!!!!	!	(clk_xincan) as CAN clock !!!!!!!!

1 1 1 1

11.1.3 Channel-specific Settings

1 - 1 1

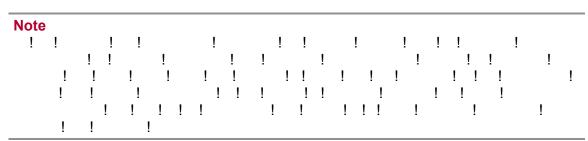
© !!!!!



Attribute	Supported Values	Description
	!	!!!!!!!!
!!	-	
!	-	
!	!!!!!	! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! and configuration ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
!!!	!!	Select the interrupt priority level of this CAN interrupts that are configured if the driver has interrupt control. Depending on the selected derivative not all levels may be available. See section 7.2.3 and chapter 10 for further information.
!!!!	!!	
!!	!!	! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
!!!!	!!	Select the maximum number of pending receive messages that are processed for each Rx BasicCAN object within one polling cycle respectively one interrupt occurrence. By adjusting this value it can be ensured that high FIFO loads will be evenly processed by the driver. Remaining messages are processed within the next polling cycle respectively the interrupt of the next received message on this channel. Select greater values if overruns occur.
!!	!!!!	

1 -1 1 1 1





! ! !! ! ! !! © ! ! !





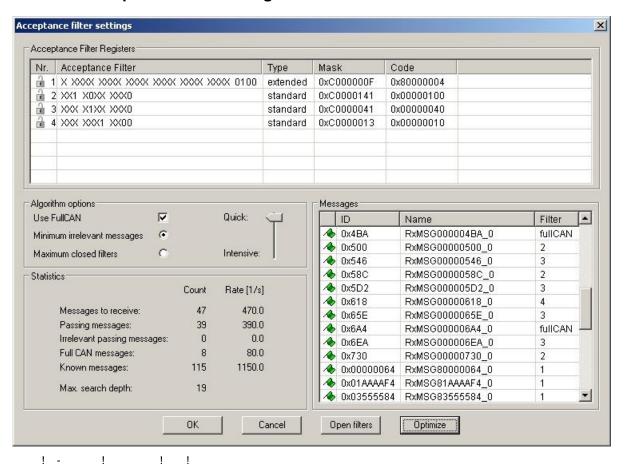
!!

11.1.3.1 Acceptance Filter Configuration

!!!!

1 -1 1 1 1

1 1 1



Attribute	Supported Values	Description
!	1 !!	
	!	
!!	!	
!	-	!!!!!!!!
	-	

!!!!

11.1.3.1.1 Additional information if the feature "Multiple BasicCAN objects" is used

!!!

!!!!!!

Nr.	Acceptance Filter	Туре	Mask	Code	-
1	000 0001 0000	standard	0xE00007FF	0x00000010	BasicCAN 0
2	0 0000 0000 0000 0000 0010 00XX XXX1	extended	0xFFFFFFC1	0x80000201	Dasiconivo
3	0 0000 0000 0011 0000 0XXX XXXX XXXX	extended	0xFFFFF800	0x80030000	BasicCAN 1
4	X10 XXX0 XXXX	standard	0xE0000310	0x00000200	DasicCAN 1
5	XX1 0001 0X01	standard	0xE00001FB	0x00000111	
6	XXX 0001 0011	standard	0xE00000FF	0x00000013	BasicCAN 2



1 - 1 1

1 1 1 1



11.1.3.2 Bustiming Configuration

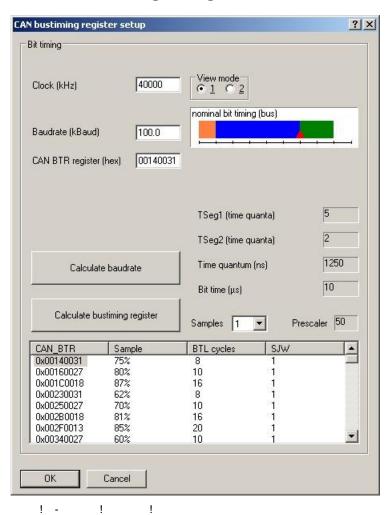
ļ

!

!

! -!

!



!

!

Attribute	Supported Values	Description
Clock	CAN clock	Set the clock frequency that is provided to the CAN cell for baudrate generation Consider the setting of the !!!!!
Baudrate	baudrate	Set the baudrate to be used for this channel.
CAN BTR register	register value	Enter the value for the !!!!
Calculate	-	Calculate possible !!!settings out of the entered baudrate or vice versa.
CAN_BTR, Sample, BTL cycles, SJW	-	

!!!!!



See sections 7.2.6 to 7.2.9 for options that control different RAM test features.

!!!!!!

 See section 10.2.1 for information on how to set up the interrupt vector table when using IAR compiler.



12 Known Issues / Limitations

1 1 1 1 1

13 Contact

1 1 1 1 1

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- > !
- > > !
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