

# Vector CAN Driver

!

!

	!

## History

Author	Date	Version	Remarks
!	- -		! ! ! ! ! ! !
!	- -		! ! ! ! ! !
!	- -		! ! !
!	- -		! ! ! ! ! ! ! ! !
!	- -		! ! ! ! ! ! ! ! ! ! ! ! ! ! !
!	- -		! ! ! ! ! ! ! ! ! ! ! ! ! ! !
!	- -		! ! ! ! ! ! ! ! !
!	- -		! ! ! ! ! ! ! ! !

! - !                      ! ! !



**Please note**

[illegible]

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[illegible]

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2 Important References

Driver Version	Supported Compilers	Supported Derivatives	Hardware Manufacturer Document	Version

Driver Version:   
Supported Compilers:   
Supported Derivatives:   
Hardware Manufacturer Document:   
Version:

<sup>1</sup>   
©

! ! ! ! ! ! ! ! ! !

! ! ! ! ! ! ! ! ! !



© ! ! ! ! ! ! ! ! ! !



! - ! ! !

© ! ! ! ! !

! ! ! !

[illegible][illegible]

```
!      !      !      !      !      !      !      !      !      !CanSleep()!    !
!          !      !      !      !      !      !!      !      !      !CanWakeUp()!   !
!        !      !      !      !      !      !      !      !      !      !      !      !
```

```

!      !      !      !      !      !      !      !      !      !      !      !      !      !      !      !
!      !      !      !      !      !      !      !      !      !      !      !      !      !      !      !
!CanWakeUp()!      !      !      !      !kCanNotSupported
!CanSleep()!

```

```

!           ! CanSleep()!           !   !           !           !           !           !           !
!   !           !           !           !           !           !           !           !           !
!           !           !           !           !           !           !           !           !
!           !           !           !           !           !           !           !           !

```

! ! ! ! ! ! ! ! ! ! ! ! he  
n value kCanOk is always expected. However, if the function returns kCanFailed  
anSleep()! ! ! - ! !

```

!          ! CanWakeUp()!          ! !          !          !          !          !          !
!          !
!          ! kCanOk! !          !          !          !          !          !          !          !
!          !          !          !          !          !          !          !          !          !
!          ! kCanLoopEnterOperationMode! !          !          !          !          !          !
!          ! kCanFailed!          !          !          !          !          ! CanWakeup()!
! ! -          ! !

```

```
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
!  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
```



```
#define C_ENABLE_EXTERNAL_WAKEUP_SUPPRESSION
```





! ! ! ! ! ! ! ! ! !

| | |

[illegible]

```
! ! ! ! ! ! CanInitPowerOn() ! ! ! ! !  
    ! ! ! ! ! !  
    ! ! ! ! ! !  
• ! ! ! ! ! ! ! ! ! ! ! ! ! !  
    ! ! !  
• ! ! ! ! ! !  
• ! ! ! ! ! ! ! ! ! ! ! ! ! !  
    ! ! ! !  
• ! ! ! ! ! ! ! ! !  
• ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
    ! ! ! ! ! ! ! ! ! CanInitPowerOn() !  
    ! !
```

```
!      !      !      !      !      !      !CanInit()!!      !      !!      !!
!      !      !      !      !      !      !      !      !      !      !
!      !      !      !      !      !      !      !      !      !      !
!
!      !      !      !      !      !      !      !      !      !      !
!      !      !      -      !      !      !      !      !      !      !      !
!      !      !      !      !      !      !      !      !      !      !
!
```

```
!          !           !   !       ! CanInit()!    !         ! !      ! !  
!        !     !     !   !       !       !       !  
!          !           !       ! ! !       !       ! !      !  
!!              ! !      ! ! !       !       ! !      !
```

```
!      !          !      !    !           !       ! CanInit() CanStart() !  
CanWakeUp(!        !         !   !     !     !     !     !     !     !  
            !      !  
!      !          !          !      !    !    !    !    !     !     !  
!      !      !      !      !    !    ! CanStart()             ! CanWakeUp(!     !!  
            !      !
```

```

!      !      !      !!      !      ! CanFullCanMsgReceived()!      !
      !      !      !      !      !      !      !      !      !      !
    !!      !      !      !      !      !      !      !      !      !
      !      !      !      !      !      !      !      !      !      !
    !      !      !      !      !      !      !      !      !      !
!      !      !      !      !      !      !      !      !      !
      !      !      !      !      !      !      !      !      !      !
    !      !      !      !      !      !      !      !      !      !
      !      !      !      !      !      !      !      !      !      !
!      !      !      !      !      !      !      !      !      !
      !      !      !      !      !      !      !      !      !      !
    !      !      !      !      !      !      !      !      !      !
      !      !      !      !      !      !      !      !      !      !
! CanFullCanMsgReceived()!      !      !      !      !      !      !

```

```
!      !    !          !           !              !    !    !          !    !    !
        !            !       !     !             !         !    !    -   !    !
        !      !    !          !               !         !    !    !    !    !
        !      !          !    !           !CanResetBusOffStart/-End()!      !    !    !
!    !CanInit()!          !      !    !! CanResetBusOffEnd()!    !      !    !
        !            !    !          !      !    !kCanLoopBusOffRecovery!!
!      !CanInit()!      !      !
```

## 7 CAN Driver Features

### 7.1 [#hw\_feature] - Feature List

	Standard	HighEnd
<b>Initialization</b>		
Power-On Initialization	■	■
Re-Initialization	■	■
<b>Transmission</b>		
Transmit Request	■	■
Transmit Request Queue	■	■
Internal data copy mechanism	■	■
Pretransmit functions	■	■
Common confirmation function	■	■
Confirmation flag	■	■
Confirmation function	■	■
Offline Mode	■	■
Partial Offline Mode	■	■
Passive-Mode	■	■
Tx Observe mode	■	■
Dynamic TxObjects	ID	■
	DLC	■
	Data-Ptr	■
Full CAN Tx Objects	■	■
Cancellation in Hardware	■	■
Low Level Message Transmit	-	■
<b>Reception</b>		
Receive function	■	■
Search algorithms	Linear	■
	Table	-
	Index	■
	Hash	■
Range specific precopy functions (min. 2, typ.4)	4	4
DLC check	■	■
Internal data copy mechanism	■	■
Generic precopy function	■	■
Precopy function	■	■
Indication flag	■	■
Indication function	■	■
Message not matched function	■	■



Overrun Notification	■	■
Full CAN overrun notification	-	-
Multiple Basic CAN	-	■
Rx Queue <sup>2</sup>	-	■
<b>Bus off</b>		
Notification function	■	■
Nested Recovery functions	■	■
<b>Sleep Mode</b>		
Mode Change	■	■
Preparation	■	■
Notification function	■	■
<b>Special Features</b>		
Status	■	■
Security Level	■	■
Assertions	■	■
Hardware loop check	■	■
Stop Mode	■	■
Support of OSEK operating system	■	■
Polling Mode      Tx		

! ! ! ! ! ! ! ! ! !

! - ! !



---

## **[#hw\_cancel] - Cancel in Hardware**

	Yes	No
! CanTxTask() ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !		■

```

!          ! !          ! !CanCancelTransmit()!
CanCancelMessageTransmit()

```

	Yes	No
ApplCanTxConfirmation() ! ! ! ! ! ! ! ! ! !		
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !	■	
!! !! ! !! ! ! ! ! ! ! ! ! ! !		

### 7.2.5 Remote Frames

! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! !

### 7.2.6 CAN RAM Check

```

! ! ! ! ! ! ! ! ! !
! ! ! CanInit() ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! !
!! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! !
AppCanCorruptMailbox()! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! !
AppCanMemCheckFailed()! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! - ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! !CanInitPowerOn()
```



Switch	Value	Description
		! ! !App1CanCorruptMailbox() ! ! ! ! ! ! ! ! ! !

```

! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
CanInitPowerOn() ! ! ! ! ! ! ! ! ! ! - ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

```

```

!      !      !!      !      !      !      !      !      !      !
•  !      !      !      !      !      !      !      !      !      !      !
      !      !      !      !      !      !      !      !      !      !
ApplCanGlobalMemCheckFailed()!      !      !CanInitPowerOn()!      !
      !      !kCanEnableCommunication!      !      !      !      !
      !      !      !      !      !      !kCanDisableCommunication!      !      !
      !      !      !      !      !      CanInitPowerOn()!      !      !
      !      !      !      !      !      !      !      !      !      !
CanInitPowerOn()!      !      !      !      !      !      !      !      !
      !      !      !      !      !      !      !      !      !CanInitPowerOn()!
      !      !      !      !      !      !      !      !      !

```

[illegible]

```

•      ! ! ! ! ! ! ! ! ! ! - ! !
  ApplCanCorruptMailbox()      !      ! ! ! ! ! ! ! ! ! !
                                ! ! ! ! ! ! ! ! ! !
      !      !      ! ! ! ! !      !      !      !      !      !      !
      !      ! ! ! ! !      !      !      !      !      !      ! ! !
      !ApplCanMemCheckFailed(),!      !      !      !      !
•      ! !      ! ! !      !      !      ! ! ! ! ! -      !      !
      !      !CanEnableChannelCommunication()
•      !      !      !      ! !      !      !      ! ! ! -      ! ! !      !
  CanEnableMailboxCommunication(!      !      ! ! !      !      !      !
      ! !
•      !      ! !      !      !      ! !      !      !      !      !      ! -      !      !
      ! !CanInit()!      !      !CanResetBusOffEnd()!      !      !      !
      !      ! !      !      !

```



## Caution

```

! ! ! ! - ! ! ! ! ! ! !
CanEnableChannelCommunication() !CanEnableMailboxCommunication()!
!CanInitPowerOn()

```

[illegible]

Switch	Value	Description
		! ! ! ! ! !

### 7.2.8 RSCAN ECC Configuration

[illegible]

Switch	Value	Description
		! ! !ApplCanEccConfiguration()

### 7.2.9 RSCAN RAM Test

```

!      !      !!      !      !      !      !      !      !      !!      !!      !      !      !
!      !      !      !      !!      !      !      !      !      !      !      !      !      !
!      !      !      !CanInitPowerOn()!      !!      !      !      !      !      !      !
!      !      !!      !      !!      !      !      !      !      !      !      !
!      !      !      !      !      !      !      !      !      !      !      !      !
!      !      !      !      -      !      !ApplCanGlobalMemCheckFailed()      !      !
!      !      !!      !      !      !kCanEnableCommunication!      !      !!
!      !      !      !      !      !      !      !      !kCanDisableCommunication!
!      !!      !      !      !      !      !      !      CanInitPowerOn()!      !      !
!      !      !CanInitPowerOn()

```

! ! ! ! ! ! ! !

9 API

9.1 Category

Single Receive Channels (SRC)	
■	! ! ! ! ! ! ! ! !
Multiple Receive Channel (MRC)	
■	! !CanOnline()! ! ! CanOnline(channel)! ! ! ! ! ! ! ! ! ! ! !CanTransmit(txHandle)

! - ! !

9.2 RSCAN ECC Configuration

! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! !

ApplCanEccConfiguration

Prototype	
! !	void (void)
! !	void (void)
Parameter	
-	-
Return code	
-	-
Functional Description	
! ! ! !CanInitPowerOn()! ! ! ! ! ! ! !	
Particularities and Limitations	
! !C_ENABLE_ECC_CALLOUT! !	



! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! !

Prototype													
!	!	vuint8 (void)											
!	!	vuint8 (CanChannelHandle channel)											
Parameter													
CanChannelHandle channel	!	!	!	!	!	!	!	!	!	!	!	!	!
Return code													

© ! ! ! ! ! ! ! !

! ! ! ! ! ! ! !

ApplCanCorruptMailbox

Prototype	
! !	void (CanObjectHandle hwObjHandle)
! !	void (CanChannelHandle channel, CanObjectHandle hwObjHandle)
Parameter	
CanChannelHandle channel	! ! ! ! ! ! ! ! ! !
CanObjectHandle hwObjHandle	! ! ! ! ! ! !
Return code	
-	-
Functional Description	
! ! ! !CanInit()! ! ! ! ! ! ! !	
Particularities and Limitations	
<b>Call context</b> !	
<b>Configuration</b> ! ! ! ! ! ! !	

! !

ApplCanCorruptRegisters

Prototype	
! !	void (void)
! !	void (CanChannelHandle channel)
Parameter	
CanChannelHandle channel	! ! ! ! ! ! ! ! ! !
Return code	
-	-
Functional Description	
! ! ! ! ! ! ! ! ! ! ! !	
Particularities and Limitations	
<b>Call context</b> ! ! ! ! ! ! ! ! !CanInit()! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !	
CanResetBusOffEnd() ! ! ! ! !CanInit() ! ! ! ! ! ! ! ! ! !	
<b>Configuration</b> ! ! ! ! ! ! ! ! !CanEnableChannelCommunication()	

## Prototype

### Parameter

## Return code

## Functional Description

## Particularities and Limitations

```
Important note:  !      ! !      !      !      ! !kCanEnableCommunication! !      ! !
!      !      ! !      !      !      !      !      !      !      !      !      !
!      !      ! !      !      !      !      !      !      !      !      !      !
```

## CanEnableChannelCommunication

[illegible]

## Prototype

```
uint8_t (CanObjectHandle)
hwObjHandle)
```

```
uint8_t CanChannelHandle channel,
CanObjectHandle hwObjHandle)
```

## CanChannelHandle channel

- ! ! ! ! ! ! ! ! ! ! !

! ! ! ! ! ! ! -

## vuint8

```

      ! !      !      !      ! -
      ! !      ! !      !      !      !hwObjHandle! !
! !      ! !      !      !      !      !
      ! !      !      !      !

```

[illegible]

**Call context!**      !      ! !      ! ! !

<b>Call context!</b>	!	!	!	!	!
<b>Configuration!</b>	!	!	!	!	!

[illegible]

## OsCanCanInterruptRestore

Prototype	
<pre> ! ! </pre>	<pre> void (void) </pre>
<pre> ! ! </pre>	<pre> void (CanChannelHandle channel) </pre>
Parameter	
CanChannelHandle channel	<pre> ! ! ! ! ! ! ! ! ! ! ! ! </pre>
Return code	
-	-
Functional Description	
<pre> ! !! ! !CanCanInterruptRestore() </pre>	
Particularities and Limitations	
<pre> ! !!C ENABLE OSEK CAN INTCTRL! </pre>	

## AppCanWakeupInterruptDisable

Prototype	
uint8_t	CanWakeup() (uint8_t channel)
uint8_t	CanInit() (uint8_t channel)
Parameter	
uint8_t channel	Channel number (0-15)
Return code	
uint8_t	0: Success 1: Channel not initialized 2: Channel not awake 3: Channel not in sleep mode 4: Channel not in wakeup mode 5: Channel not in init mode 6: Channel not in sleep mode 7: Channel not in wakeup mode 8: Channel not in init mode 9: Channel not in sleep mode 10: Channel not in wakeup mode 11: Channel not in init mode 12: Channel not in sleep mode 13: Channel not in wakeup mode 14: Channel not in init mode 15: Channel not in sleep mode
Functional Description	
uint8_t	CanWakeup() CanInit()
Particularities and Limitations	
uint8_t	CanWakeup() CanInit()

## AppCanWakeupInterruptEnable

Prototype	
<pre>void CanSleep(     uint8 channel );</pre>	<pre>void CanSleep(     uint8 channel );</pre>
Parameter	
uint8 channel	Channel number (0-15)
Return code	
-	-
Functional Description	
<p>CanSleep() returns true if the CAN module is in sleep mode and false otherwise.</p>	
Particularities and Limitations	
<p>CanSleep() returns true if the CAN module is in sleep mode and false otherwise. The CAN module is in sleep mode if the CAN_INTCTRL register is set to 0x00000000 and the CAN_SLEEP_WAKEUP register is set to 0x00000000.</p>	





```
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! !CanInitPoweron()  
  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
- ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! !
```

! - ! ! !

[illegible]

```
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! - ! ! ! ! ! !  
! ! ! ! ! C_ENABLE_ISRVOID! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !
```



## Caution

```

!      !           !         !       !          !             !    !     !        !
!      !           !         !       !          !             !    !     !        !
!C_ENABLE_DIRECT_INTERRUPT_BRANCH!   !            !           !         !       !
!      !           !         !       !          !             !    !     !        !
!      !           !         !       !          !             !    !     !        !

```

### 10.2.1 Configuration of Interrupt Vectors with IAR compiler

[illegible]

[illegible]

```

!C_ENABLE_OSEK_CAN_INTCTRL has to be defined via the user configuration file!

!CanInitPowerOn()

-

!CanCanInterruptDisable()
CanCanInterruptRestore()!
!OsCanCanInterruptDisable()!
!OsCanCanInterruptRestore()!

!OsCanCanInterruptDisable() and be available not until the last nested call of
!OsCanCanInterruptRestore().

!C_ENABLE_OSEK_CAN_INTCTRL
s defined
!
! Iso there are two additional
application call-back functions!

```

```
OsCanCanInterruptDisable()
```

! ! ! ! ! ! ! ! ! !

! ! ! ! ! ! ! ! ! !



## Caution

© ! ! ! ! ! ! ! ! ! !

11 Configuration

11.1 Configuration by GENy



Note

11.1.1 Platform Settings

Setup Dialog

Preconfiguration

Micro

Derivative

Compiler

OK

Cancel

Attribute	Supported Values	Description



Attribute	Supported Values	Description
! ! ! !	!-!	Enter the maximum number of physical CAN channels that are supported by the actually used derivative. This value is independent from the number of channels in the configuration but used to determine the available hardware resources. Only if this value is correct the tool can ensure valid configurations for the actual derivative. Depending on the selected derivative not all values may be available.
! ! !	!	Enable this attribute to use the external clock input (clk_xincan) as CAN clock ! ! ! ! ! ! ! !-! ! ! ! ! (This setting directly affects the DCS bit in the global configuration register.)

[illegible]

Attribute	Supported Values	Description
	!	!
!	-	!
!	-	!
!	!!!!	! Depending on the selected derivative and configuration !11.1.2) n !
!	!!	Select the interrupt priority level of this CAN interrupts that are configured if the driver has interrupt control. Depending on the selected derivative not all levels may be available. See section 7.2.3 and chapter 10 for further information.
!	!!	!
!	!!	Depending on the selected derivative n !
!	!!	Select the maximum number of pending receive messages that are processed for each Rx BasicCAN object within one polling cycle respectively one interrupt occurrence. By adjusting this value it can be ensured that high FIFO loads will be evenly processed by the driver. Remaining messages are processed within the next polling cycle respectively the interrupt of the next received message on this channel. Select greater values if overruns occur.
!	!!!!	!



### Note

!



Acceptance filter settings

Acceptance Filter Registers

Nr.	Acceptance Filter	Type	Mask	Code
1	X XXXX XXXX XXXX XXXX XXXX 0100	extended	0xC000000F	0x80000004
2	XX1 X0XX XXX0	standard	0xC0000141	0x00000100
3	XXX X1XX XXX0	standard	0xC0000041	0x00000040
4	XXX XXX1 XX00	standard	0xC0000013	0x00000010

Algorithm options

Use FullCAN

☒

Quick:

☐

Minimum irrelevant messages

☐

Maximum closed filters

☐

Intensive:

☐

Statistics

	Count	Rate [1/s]
Messages to receive:	47	470.0
Passing messages:	39	390.0
Irrelevant passing messages:	0	0.0
Full CAN messages:	8	80.0
Known messages:	115	1150.0
Max. search depth:	19	

Messages

ID	Name	Filter
0x4BA	RxMSG000004BA_0	fullCAN
0x500	RxMSG00000500_0	2
0x546	RxMSG00000546_0	3
0x58C	RxMSG0000058C_0	2
0x5D2	RxMSG000005D2_0	3
0x618	RxMSG00000618_0	4
0x65E	RxMSG0000065E_0	3
0x6A4	RxMSG000006A4_0	fullCAN
0x6EA	RxMSG000006EA_0	3
0x730	RxMSG00000730_0	2
0x00000064	RxMSG80000064_0	1
0x01AAAF4	RxMSG81AAAF4_0	1
0x03555584	RxMSG83555584_0	1

OK

Cancel

Open filters

Optimize

[illegible]

### 11.1.3.1.1 Additional information if the feature “Multiple BasicCAN objects” is used

Nr.	Acceptance Filter	Type	Mask	Code	
1	000 0001 0000	standard	0xE00007FF	0x00000010	BasicCAN 0
2	0 0000 0000 0000 0010 00XX XXX1	extended	0xFFFFFC1	0x80000201	
3	0 0000 0000 0011 0000 00XX XXXX XXXX	extended	0xFFFF800	0x80030000	BasicCAN 1
4	X10 XXX0 XXXX	standard	0xE0000310	0x00000200	
5	XX1 0001 0X01	standard	0xE00001FB	0x00000111	BasicCAN 2
6	XXX 0001 0011	standard	0xE00000FF	0x00000013	



#### Note

Attribute	Supported Values	Description
Clock	CAN clock	Set the clock frequency that is provided to the CAN cell for baudrate generation. Consider the setting of the $f_{CAN}$ .
Baudrate	baudrate	Set the baudrate to be used for this channel.
CAN BTR register	register value	Enter the value for the BTR register.
Calculate	-	Calculate possible baudrate settings out of the entered baudrate or vice versa.
CAN_BTR, Sample, BTL cycles, SJW	-	Enter the value for the CAN_BTR register, the sample period in cycles, the number of bit times for the bit length error judgment, and the synchronous jump width in bit times.

## 11.2 Manual Configuration

- ! ! ! ! ! !
- ! ! ! ! !
- !C\_DISABLE\_NESTED\_INTERRUPTS! !C\_ENABLE\_NESTED\_INTERRUPTS! !  
! ! ! ! ! See section 10.1 for further information.
- Define C\_ENABLE\_DIRECT\_INTERRUPT\_BRANCH! ! ! ! !  
C\_ENABLE\_ISRVOID! ! ! ! ! ! ! ! ! ! !  
! ! ! ! ! !
- !C\_ENABLE\_OSEK\_CAN\_INTCTRL to prohibit write accesses by the driver within the interrupt controller address space. See section 10.3 for further information.
- Define C\_ENABLE\_EXTERNAL\_WAKEUP\_SUPPRESSION! ! ! ! !  
! ! ! ! !
- See sections 7.2.6 to 7.2.9 for options that control different RAM test features.
- See section 10.2.1 for information on how to set up the interrupt vector table when using IAR compiler.

1. ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

2. ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

3. ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

4. ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

5. ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

6. ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

7. ! ! ! ! ! ! ! ! ! ! ! ! ! ! !

! ! ! ! ! ! ! ! ! ! ! ! ! ! !

