

WHAT GREEK LETTERS MEAN IN EQUATIONS

π THIS MATH IS EITHER VERY SIMPLE OR IMPOSSIBLE.

Δ SOMETHING HAS CHANGED.

δ SOMETHING HAS CHANGED AND IT'S A MATHEMATICIAN'S FAULT.

θ CIRCLES!

ϕ ORBS

ϵ NOT IMPORTANT, DON'T WORRY ABOUT IT.

U, V IS THAT A V OR A U? OR...OH NO, IT'S ONE OF THOSE.

μ THIS MATH IS COOL BUT IT'S NOT ABOUT ANYTHING THAT YOU WILL EVER SEE OR TOUCH, SO WHATEVER.

Σ THANK YOU FOR PURCHASING ADDITION PRO®!

Π ...AND THE MULTIPLICATION® EXPANSION PACK!

ζ THIS MATH WILL ONLY LEAD TO MORE MATH.

β THERE ARE JUST TOO MANY COEFFICIENTS.

α OH BOY, NOW *THIS* IS MATH ABOUT SOMETHING REAL. THIS IS MATH THAT COULD KILL SOMEONE.

Ω OOOH, *SOME* MATHEMATICIAN THINKS THEIR FUNCTION IS COOL AND IMPORTANT.

ω A LOT OF WORK WENT INTO THESE EQUATIONS AND YOU ARE GOING TO DIE HERE AMONG THEM.

σ SOME POOR SOUL IS TRYING TO APPLY THIS MATH TO REAL LIFE AND IT'S NOT WORKING.

ξ EITHER THIS IS TERRIFYING MATHEMATICS OR THERE WAS A HAIR ON THE SCANNED PAGE.

Υ ZOOM PEW PEW PEW [SPACE NOISES] ZOOOOM!

ρ UNFORTUNATELY, THE TEST VEHICLE SUFFERED AN UNEXPECTED WING SEPARATION EVENT.

Ξ GREETINGS! WE HOPE TO LEARN A GREAT DEAL BY EXCHANGING KNOWLEDGE WITH YOUR EARTH MATHEMATICIANS.

Ψ YOU HAVE ENTERED THE DOMAIN OF KING TRITON, RULER OF THE WAVES.

Source: xkcd.com/2586

EXPONENTIAL SMOOTHING MODELS

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INTRODUCTION

Time Dependencies

- Time series data relies on the assumption that the observations at a certain time point depend on previous observations in time.

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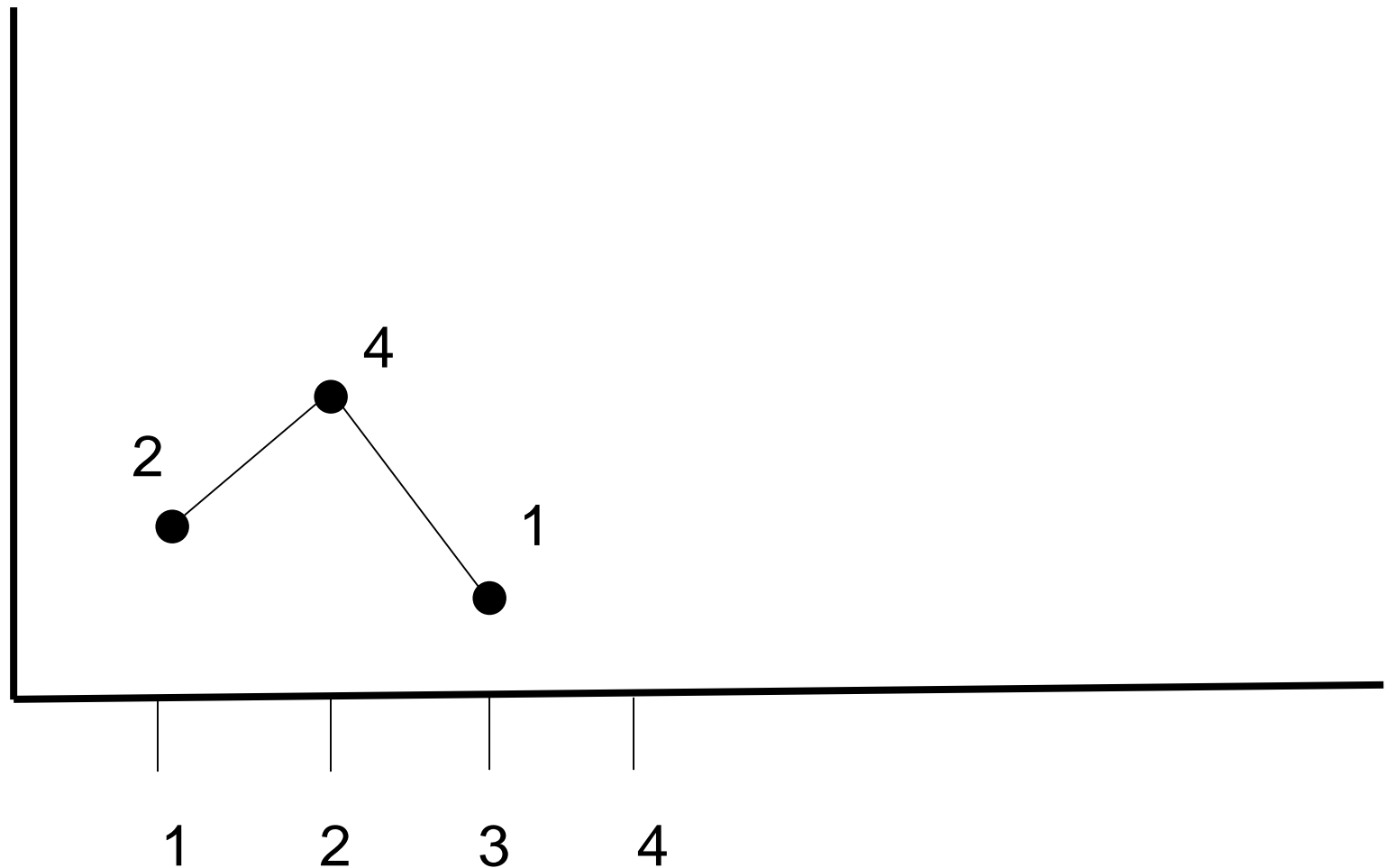
Naïve Model:

$$\hat{Y}_{t+h} = Y_t$$

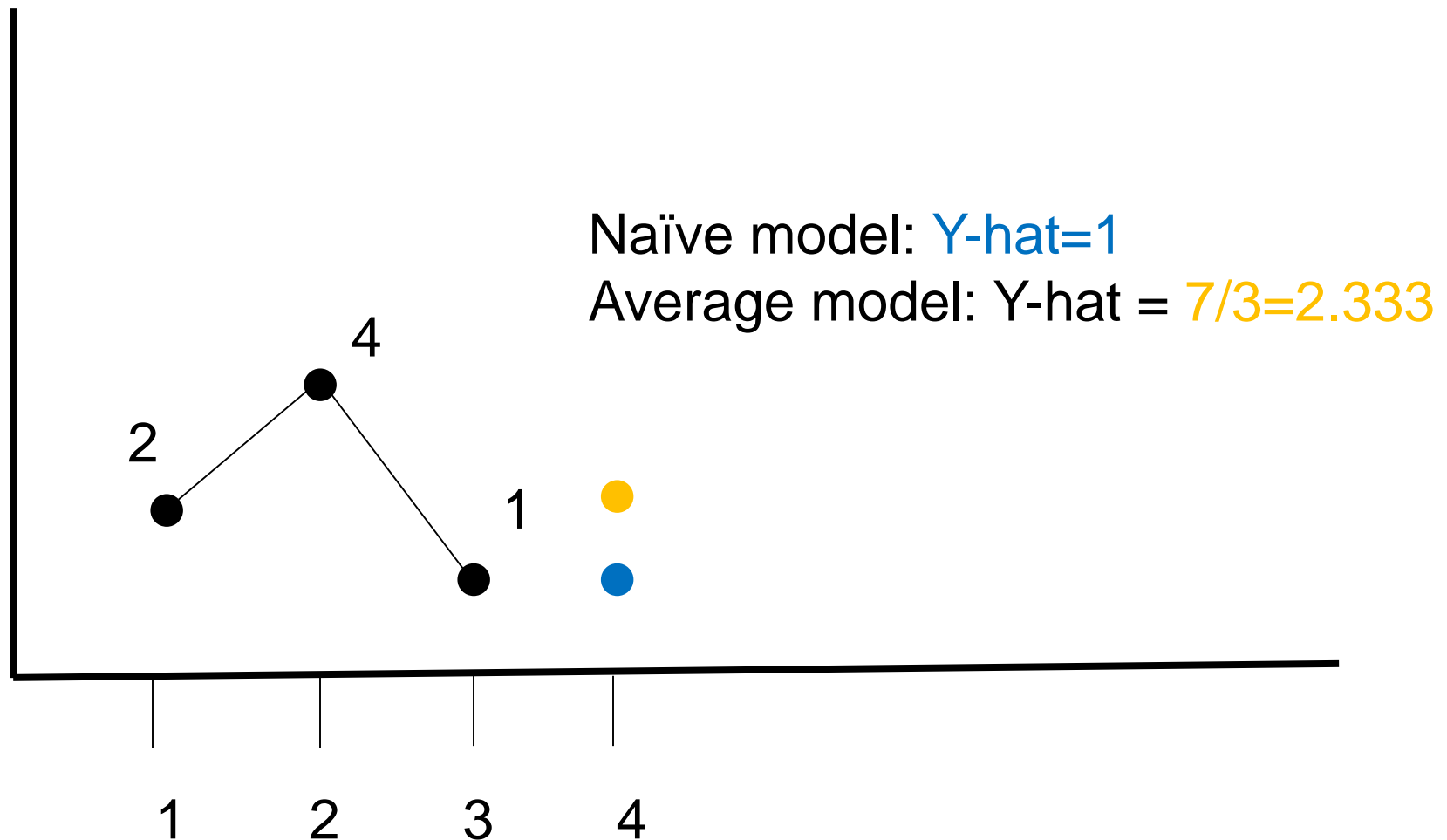
Average Model:

$$\hat{Y}_{t+h} = \frac{1}{T} \sum_{t=1}^T Y_t$$

Naïve model versus Average model



Naïve model versus Average model



Exponential Smoothing

- This is what exponential smoothing does (however, it is a WEIGHTED average, not a simple average)
- Models only require a few parameters.
- Equations are simple and easy to implement.

Exponential Smoothing

- There are many different types of exponential smoothing models.
- We will discuss the four common types of Exponential Smoothing:
 - Single
 - Linear / Holt (incorporates trend)
 - Holt-Winters (incorporates trend and seasonality)
- ESM are great for “one-step ahead” forecasting

SINGLE EXPONENTIAL SMOOTHING

Single Exponential Smoothing

- The Single Exponential Smoothing model equates the predictions at time t equal to the weighted values of the previous time period along with the previous time period's prediction:

$$\hat{Y}_{t+1} = \theta Y_t + (1 - \theta)\hat{Y}_t$$

Where \hat{Y}_t is the estimate of Y_t (weighted average of previous observations)

Single Exponential Smoothing

- We can apply a weighting scheme that decreases exponentially the further back in time we go.

$$\hat{Y}_{t+1} = \theta Y_t + (1 - \theta) \hat{Y}_t$$

$$\hat{Y}_{t+1} = \theta Y_t + (1 - \theta) [\theta Y_{t-1} + (1 - \theta) \hat{Y}_{t-1}]$$

$$\hat{Y}_{t+1} = \theta Y_t + \theta(1 - \theta) Y_{t-1} + (1 - \theta)^2 \hat{Y}_{t-1}$$

$$\hat{Y}_{t+1} = \theta Y_t + \theta(1 - \theta) Y_{t-1} + \theta(1 - \theta)^2 Y_{t-2} \\ + (1 - \theta)^3 \hat{Y}_{t-2}$$

⋮

$$\hat{Y}_{t+1} = \theta Y_t + \theta(1 - \theta) Y_{t-1} + \theta(1 - \theta)^2 Y_{t-2} + \cdots$$

Single Exponential Smoothing

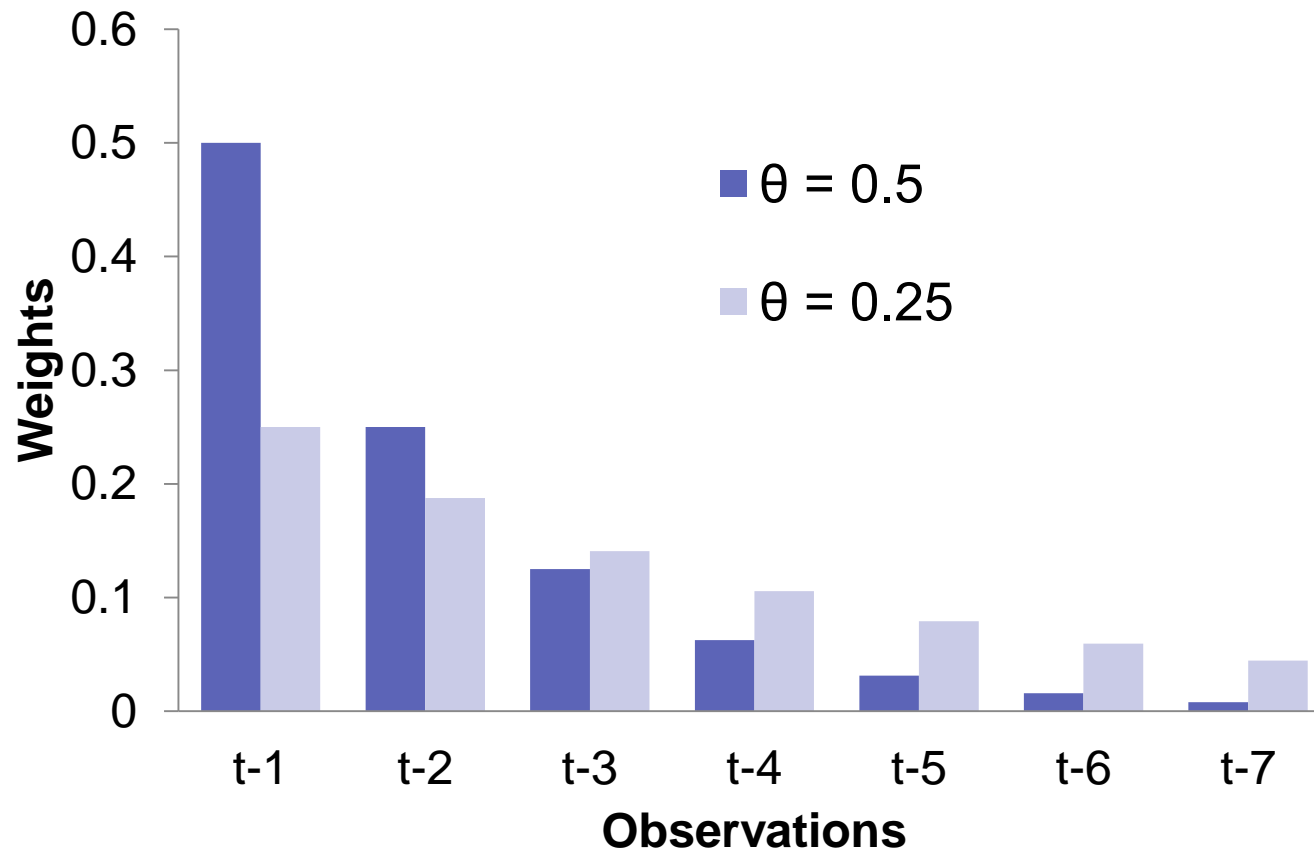
- As you can see, as we go further back in time, the weights decrease exponentially (more weight is put on the most recent observations).

$$\hat{Y}_{t+1} = \theta Y_t + \theta(1 - \theta)Y_{t-1} + \theta(1 - \theta)^2 Y_{t-2} + \theta(1 - \theta)^3 Y_{t-3} + \theta(1 - \theta)^4 Y_{t-4} + \dots$$

$$0 \leq \theta \leq 1$$

Single Exponential Smoothing

- The larger the value of the θ , the more that the most recent observation is emphasized.



Component Form

- The Single ESM can also be written in **component form**:

Forecast Equation: $\hat{Y}_{t+1} = L_t$

Level Equation: $L_t = \theta Y_t + (1 - \theta)L_{t-1}$

Parameter Estimation

$$\hat{Y}_t = \theta Y_{t-1} + (1 - \theta) \hat{Y}_{t-1}$$

- The typical method for calculating the optimal value of θ in the Exponential Smoothing model is through one-step ahead forecasts.
- The value of θ that minimizes the one-step ahead forecast errors is considered the optimal value.

$$SSE = \sum_{t=1}^T (Y_t - \hat{Y}_t)^2$$

Parameter Estimation

$$\hat{Y}_t = \theta Y_{t-1} + (1 - \theta) \hat{Y}_{t-1}$$

- Estimates that are not statistically significant should not be disqualified (in fact, significance test usually test if $\theta = 0$which simplifies down to the average model).
- Models were originally derived without statistical distribution consideration (estimates are fine even without normality!).
- HOWEVER, normality is needed if trying to construct a confidence interval.

SES Function

```
ES.Steel <- ses(SteelShp, initial="simple",  
               h=24)  
summary(ES.Steel)
```

Output from R (edited)

Smoothing parameters:

alpha = 0.4549

Initial states:

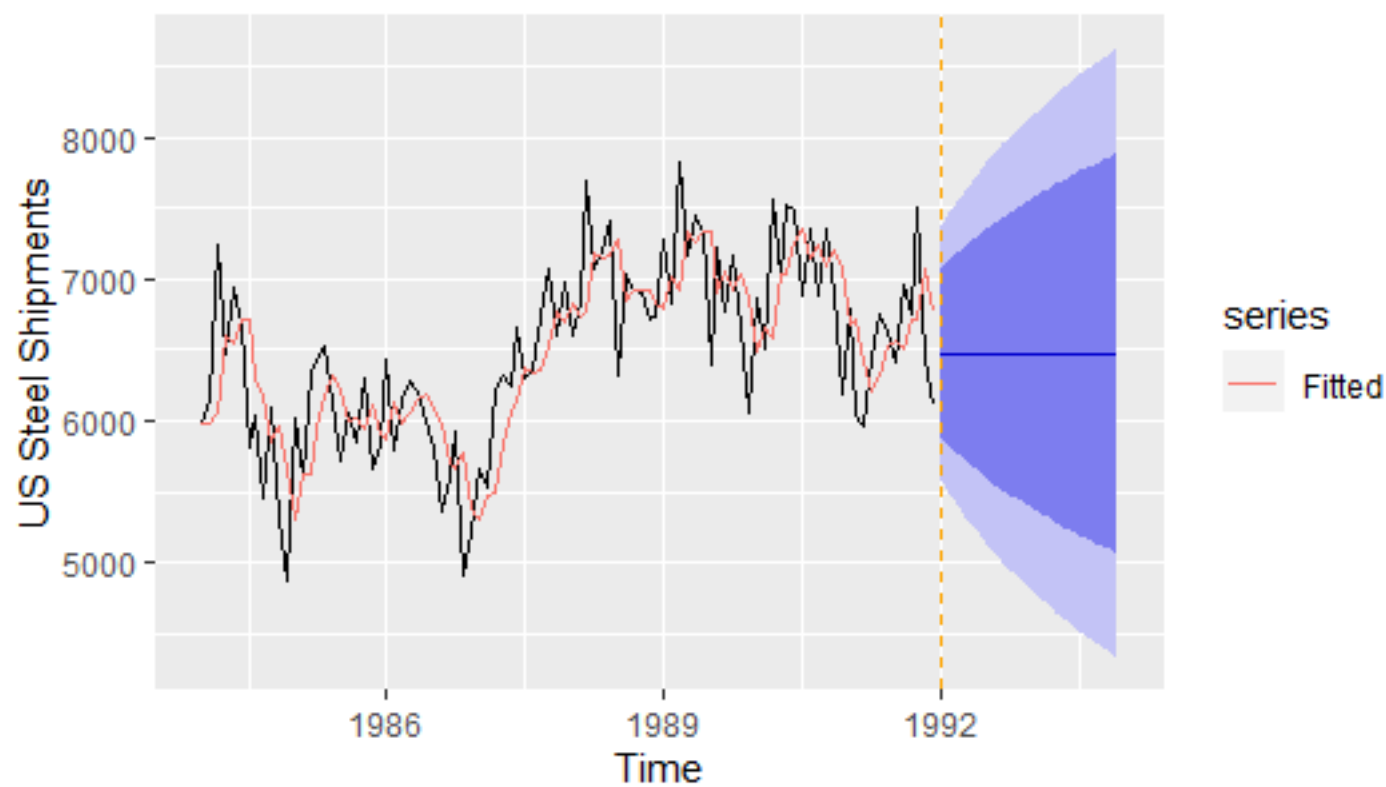
l = 5980

sigma: 460.4357

Error measures:

	ME	RMSE	MAE	MPE	MAPE
Training set	11.43866	460.4357	363.9341	-0.2204828	5.708307

Forecasts from Simple exponential smoothing



LINEAR TREND FOR EXPONENTIAL SMOOTHING

Trending Exponential Smoothing

- The Single Exponential Smoothing model are better used for short-term forecasts.
- The SES model **cannot** adequately handle data that is trending up or down.
- There are multiple ways to incorporate a trend in the Exponential Smoothing Model.
 - Linear / Holt Exponential Smoothing
 - Damped Trend Exponential Smoothing

Linear / Holt Exponential Smoothing

- The Linear Exponential Smoothing model has two components.
- The second component incorporates trending into the model.

$$\hat{Y}_{t+h} = L_t + hT_t$$

$$L_t = \theta Y_t + (1 - \theta)(L_{t-1} + T_{t-1})$$

$$T_t = \gamma(L_t - L_{t-1}) + (1 - \gamma)T_{t-1}$$

Linear / Holt Exponential Smoothing

- The Linear Exponential Smoothing model has two components.
- The second component incorporates trending into the model.

$$\hat{Y}_{t+h} = L_t + hT_t$$

$$L_t = \theta Y_t + (1 - \theta)(L_{t-1} + T_{t-1})$$

$$T_t = \gamma(L_t - L_{t-1}) + (1 - \gamma)T_{t-1}$$

There are only two parameters to estimate here (both smoothing or “weight” parameters)

Damped Trend Exponential Smoothing

- The Linear Exponential Smoothing model has two components.
- The second component incorporates trending into the model.

$$\hat{Y}_{t+h} = L_t + \sum_{i=1} \phi^i T_t$$

$$L_t = \theta Y_t + (1 - \theta)(L_{t-1} + \phi T_{t-1})$$

$$T_t = \gamma(L_t - L_{t-1}) + (1 - \gamma)\phi T_{t-1}$$

Damped Trend Exponential Smoothing

- The Linear Exponential Smoothing model has two components.
- The second component incorporates trending into the model.

$$\hat{Y}_{t+h} = L_t + \sum_{i=1}^h \phi^i T_t$$

Between 0 and 1

$$L_t = \theta Y_t + (1 - \theta)(L_{t-1} + \phi T_{t-1})$$

$$T_t = \gamma(L_t - L_{t-1}) + (1 - \gamma)\phi T_{t-1}$$

HOLT Function – R

```
LES.Steel <- holt(SteelShp, initial="optimal",  
                  h=24)
```

```
summary(LES.Steel)
```

```
LDES.Steel <- holt(SteelShp, initial="optimal",  
                   h=24, damped=TRUE)
```

```
summary(LDES.Steel)
```

Holt output from R (edited)

Smoothing parameters:

alpha = 0.4329

beta = 1e-04

AIC	AICc	BIC
-----	------	-----

1626.001	1626.667	1638.822
----------	----------	----------

Error measures:

	ME	RMSE	MAE	MPE	MAPE
--	----	------	-----	-----	------

Training set	-4.167318	461.5062	369.9177	-0.4760441	
	5.818476				

Damped Holt output from R (edited)

Smoothing parameters:

alpha = 0.5721

beta = 1e-04

phi = 0.8057

AIC	AICc	BIC
-----	------	-----

4906.527	4906.924	4926.862
----------	----------	----------

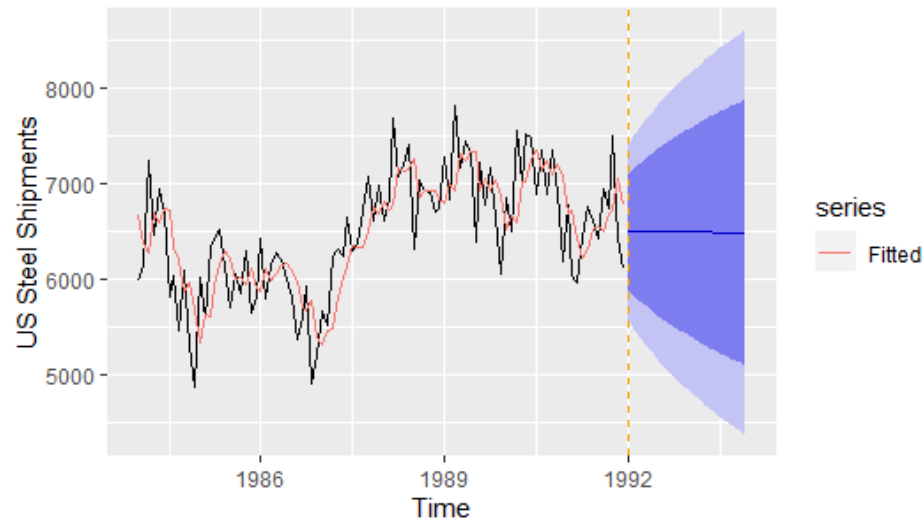
Error measures:

	ME	RMSE	MAE	MPE	MAPE
--	----	------	-----	-----	------

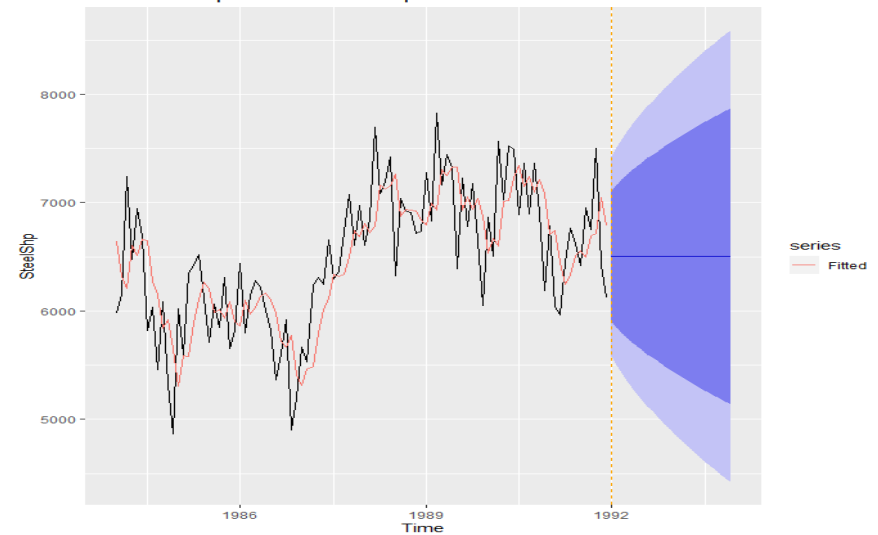
Training set	196.2283	4818.336	3529.079	-0.2896149	7.191284
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Linear ESM

US Steel Shipment with Holt forecasts



US Steel Shipment Linear Damped ESM Forecast



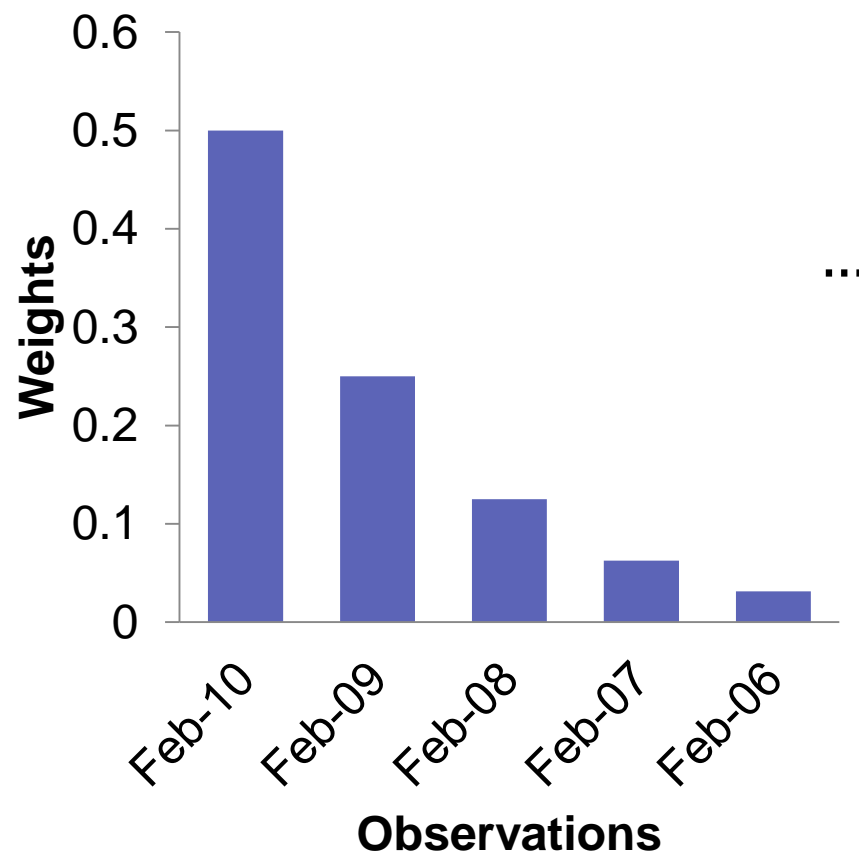
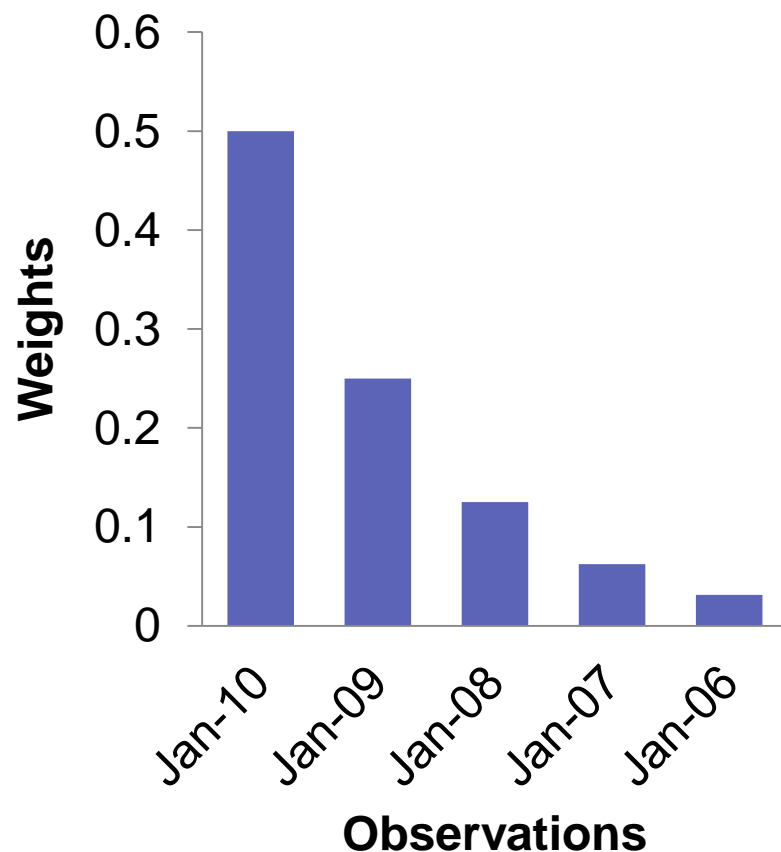
SEASONAL EXPONENTIAL SMOOTHING

Seasonal Exponential Smoothing

- Exponential Smoothing models can also be adapted to account for seasonal factors.
- Seasonal models can be additive or multiplicative in the seasonal effect in the Exponential Smoothing Model.
 - Holt Winters Additive Exponential Smoothing (includes trend)
 - Holt Winters Multiplicative Exponential Smoothing (includes trend)

Seasonal Exponential Smoothing

- In seasonal exponential smoothing, weights decay with respect to the seasonal factor.



Winters / Triple Exponential Smoothing (Additive)

- The Linear Exponential Smoothing model has three components.
 - Level, Trend and Seasonal

$$\hat{Y}_{t+h} = L_t + hT_t + S_{t-p+h}$$

$$L_t = \theta(Y_t - S_{t-p}) + (1 - \theta)(L_{t-1} + T_{t-1})$$

$$T_t = \gamma(L_t - L_{t-1}) + (1 - \gamma)T_{t-1}$$

$$S_t = \delta(Y_t - L_{t-1} - T_{t-1}) + (1 - \delta)S_{t-p}$$

Winters / Triple Exponential Smoothing (Multiplicative)

- The Linear Exponential Smoothing model has three components.

$$\hat{Y}_{t+h} = (L_t + hT_t)S_{t-p+h}$$

$$L_t = \theta(Y_t/S_{t-p}) + (1 - \theta)(L_{t-1} + T_{t-1})$$

$$T_t = \gamma(L_t - L_{t-1}) + (1 - \gamma)T_{t-1}$$

$$S_t = \delta(Y_t/(L_{t-1} + T_{t-1})) + (1 - \delta)S_{t-p}$$

HW Function

```
HWES.USAir <- hw(Passenger, seasonal="additive")  
summary(HWES.USAir)
```

```
HWES.USAir <- hw(Passenger, seasonal="multiplicative")  
summary(HWES.USAir)
```

Call:

hw(y = Passenger, seasonal = "additive")

Smoothing parameters:

alpha = 0.5967

beta = 1e-04

gamma = 1e-04

ADDITIVE

sigma: 1949.79

AIC	AICc	BIC
4515.651	4518.696	4573.265

Error measures:

	ME	RMSE	MAE	MPE	MAPE	MASE
Training set	-84.80235	1877.214	1168.093	-0.2917412	2.495749	0.4389788

Call:

```
hw(y = Passenger, seasonal = "multiplicative")
```

Smoothing parameters:

alpha = 0.4372

beta = 1e-04

gamma = 0.2075

MULTIPLICATIVE

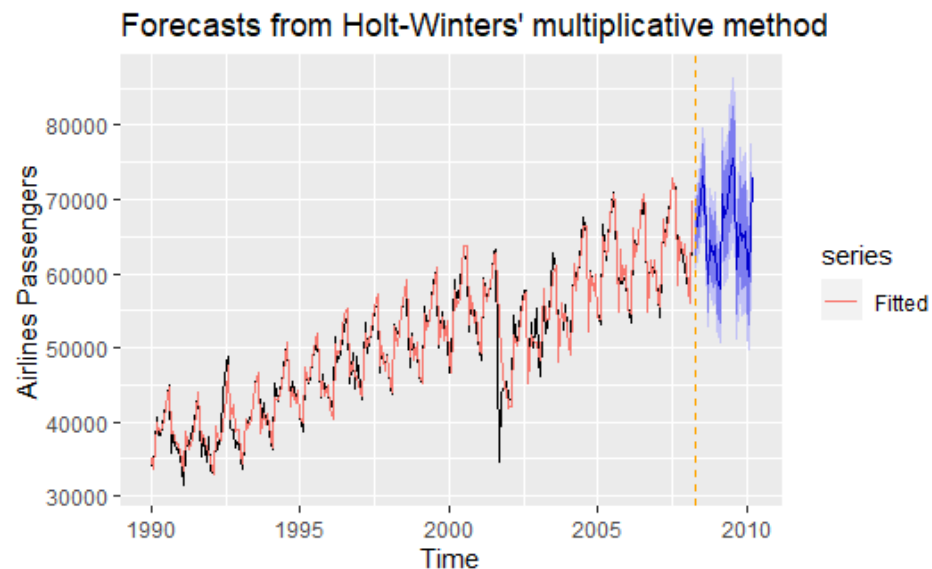
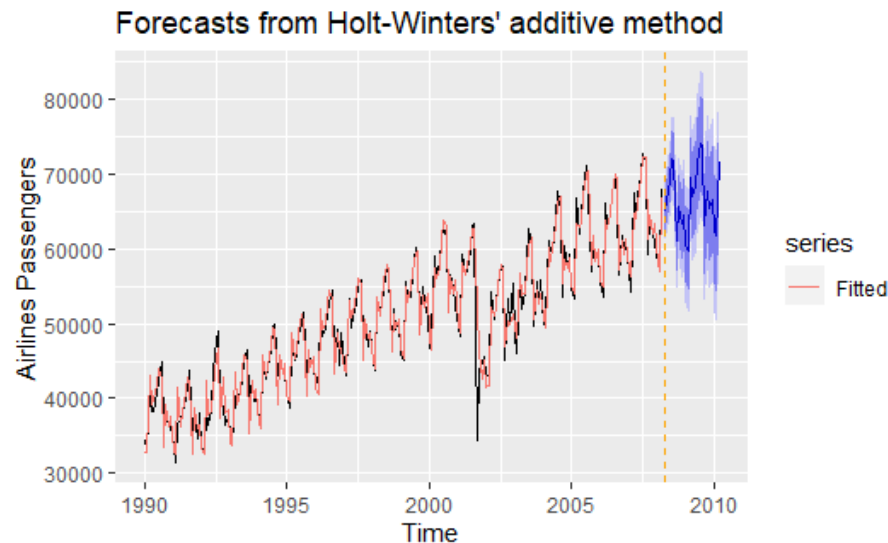
sigma: 0.0381

AIC	AICc	BIC
4504.228	4507.272	4561.842

Error measures:

	ME	RMSE	MAE	MPE	MAPE	MASE
Training set	-113.1889	1848.797	1090.105	-0.383246	2.303162	0.4096702

Additive Model versus Multiplicative Model



EVALUATING FORECASTS

Forecasting Strategy

- Accuracy of forecasts depends on your definition of accuracy.
 - Different across different fields of industry.
- Good forecasts should have the following characteristics:
 - Be highly correlated with actual series values
 - Exhibit small forecast errors
 - Capture the important features of the original time series.

Judgment Forecasting

- When using data, forecasts are found using quantitative (or modeling) approaches. However, there are instances where models are not available (or potentially past data is not available) and a qualitative or judgement forecast is used.
- Occasionally a qualitative and quantitative approach are merged together.

Accuracy vs. Goodness-of-Fit

- A diagnostic statistic calculated using the same sample that was used to build the model is a ***goodness-of-fit*** statistic.
- A diagnostic statistic calculated using a hold out sample that was not used in the building of the model is an ***accuracy*** statistic.

Hold-out Sample

- A hold out sample in time series analysis is different than cross-sectional analysis.
- The hold-out sample is always at the end of the time series, and doesn't typically go beyond 25% of the data.
- IF YOU HAVE A SEASONAL TIME SERIES (Fall 2)
Ideally, an entire season should be captured in a hold-out sample.

Hold-out Sample

1. Divide the time series into two or three segments – training and validation (hold-out) and/or test.
2. Derive a set of candidate models.
3. Calculate the chosen *accuracy* statistic by forecasting the validation data set.
4. Pick the model with the best accuracy statistic.
5. Provide the accuracy of the model on the *test* data set.

Model Diagnostic Statistics

1. Mean Absolute Percent Error:

$$\text{MAPE} = \frac{1}{n} \sum_{t=1}^n \left| \frac{Y_t - \hat{Y}_t}{Y_t} \right|$$

2. Mean Absolute Error:

$$\text{MAE} = \frac{1}{n} \sum_{t=1}^n |Y_t - \hat{Y}_t|$$

Model Diagnostic Statistics

1. Mean Absolute Percent Error:

$$\text{MAPE} = \frac{1}{n} \sum_{t=1}^n \left| \frac{Y_t - \hat{Y}_t}{Y_t} \right| \longrightarrow \text{Problems:}$$

- Overweight of Over-predictions
- Actual of 0

2. Mean Absolute Error:

$$\text{MAE} = \frac{1}{n} \sum_{t=1}^n |Y_t - \hat{Y}_t| \longrightarrow \text{Problems:}$$

- Not scale invariant

Model Diagnostic Statistics

3. Square Root of Mean Square Error:

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_{t=1}^n (Y_t - \hat{Y}_t)^2}$$

4. Symmetric Mean Absolute Percent Error:

$$\text{sMAPE} = \frac{1}{n} \sum_{t=1}^n \frac{|Y_t - \hat{Y}_t|}{(|Y_t| + |\hat{Y}_t|)}$$

Model Diagnostic Statistics

3. Square Root of Mean Square Error:

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_{t=1}^n (Y_t - \hat{Y}_t)^2} \longrightarrow \text{Problems:}$$

- Overweight of larger errors
- Not scale invariant

4. Symmetric Mean Absolute Percent Error: invariant

$$\text{sMAPE} = \frac{1}{n} \sum_{t=1}^n \frac{|Y_t - \hat{Y}_t|}{(|Y_t| + |\hat{Y}_t|)} \longrightarrow \text{Problems:}$$

- Divide by 0
- Still asymmetric

Comparison Across Diagnostics

	$Y_t = 1,$ $\hat{Y}_t = 3$	$Y_t = 2,$ $\hat{Y}_t = 3$	$Y_t = 3,$ $\hat{Y}_t = 3$	$Y_t = 4,$ $\hat{Y}_t = 3$	$Y_t = 15,$ $\hat{Y}_t = 3$	MEAN
APE	200%	50%	0%	25%	80%	71%
AE	2	1	0	1	12	3.2
SE	4	1	0	1	144	30
Sym. APE	50%	20%	0%	14.3%	66.7%	30.2%

Comparison Across Diagnostics

	$Y_t = 0,$ $\hat{Y}_t = 3$	$Y_t = 2,$ $\hat{Y}_t = 3$	$Y_t = 3,$ $\hat{Y}_t = 3$	$Y_t = 4,$ $\hat{Y}_t = 3$	$Y_t = 15,$ $\hat{Y}_t = 3$	MEAN
APE	∞	50%	0%	25%	80%	...?
AE	3	1	0	1	12	3.4
SE	9	1	0	1	144	31
Sym. APE	100%	20%	0%	14.3%	66.7%	40.2%

Model Diagnostic Statistics

5. Akaike's Information Criterion

$$\text{AIC} = -2 \log(L) + 2k$$

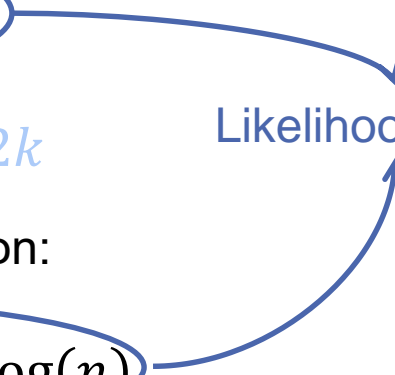
$$\text{AIC} = n \log \left(\frac{\text{SSE}}{n} \right) + 2k$$

6. Schwarz's Bayesian Information Criterion:

$$\text{SBC} = -2 \log(L) + k \log(n)$$

$$\text{SBC} = n \log \left(\frac{\text{SSE}}{n} \right) + k \log(n)$$


Likelihood Based



Model Diagnostic Statistics

5. Akaike's Information Criterion

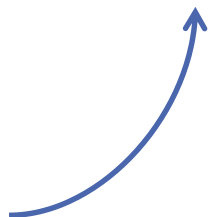
$$AIC = -2 \log(L) + 2k$$

$$AIC = n \log \left(\frac{SSE}{n} \right) + 2k$$


Error Based

6. Schwarz's Bayesian Information Criterion:

$$SBC = -2 \log(L) + k \log(n)$$

$$SBC = n \log \left(\frac{SSE}{n} \right) + k \log(n)$$


Error Based

R output

```
training=subset(Passenger,end=length(Passenger)-12)
test=subset(Passenger,start=length(Passenger)-11)
HWES.USAir.train <- hw(training, seasonal =
"multiplicative",initial='optimal')
test.results=forecast(HWES.USAir.train,h=12)
```

```
error=test-test.results$mean
MAE=mean(abs(error))
MAPE=mean(abs(error)/abs(test))
MAE
[1] 1134.58
MAPE
[1] 0.01763593
```

ETS

ETS (Error, Trend, Season)

- ETS is an automated search procedure that will try to identify the “best” model based on treating the data as a state space problem (think back to the “components” of ESM’s)
 - For “Error”, the choices are Additive (A) or Multiplicative (M)
 - For “Trend”, the choices are None (N), Additive (A), Multiplicative (M)...if you wanted “Damped”, you can specify that `damped=TRUE`, which indicates the trend
 - For “Seasonal”, the choices are None (N), Additive (A), Multiplicative (M)
- You can choose which one you want, OR you can let the computer choose (either specify “Z” for each EST feature or leave them blank)

ETS function

```
ets.passenger<-ets(training)
summary(ets.passenger)
ets.forecast.passenger<-forecast(ets.passenger,h=12)
error=mean(abs(test-test.results$mean))
error
```

R output (edited)

ETS(M,Ad,M)

Call:

ets(y = training)

Smoothing parameters:

alpha = 0.6485

beta = 1e-04

gamma = 1e-04

phi = 0.9755

AIC	AICc	BIC
4225.929	4229.567	4285.918

Training set error measures:

	ME	RMSE	MAE	MPE	MAPE
Training set	157.1888	1747.817	1043.596	0.1980283	2.19083