

1) Problem Statement

→ Modelling corona virus (COVID-19) outbreak for various countries.

→ Train a model to fit statistics for India.

→ The SIR (Susceptible, Infected, Removed/Recovered) model is used as a reference from [lewuathe.com/covid-19-dynamics-with-sir-model.html](http://lewuathe.com/covid-19-dynamics-with-sir-model.html).

Data: The dataset provided for this assignment had the fields:

- new daily cases
- new daily deaths
- total recoveries
- total infected
- total deaths

for a span of 94 days. Using this raw data we can calculate current active cases as (total infected -

total deaths - total recoveries) and

susceptible population =  $N - \text{total cases}$  for each particular day.  $N$  is the population. Now, susceptible present,

infected present and total recoveries serve as the gold standard SIR

values. All the relevant plots were

generated to get a proper feel of

the data set. SIR is a good

choice of a model for modelling

such pandemics. Though  $N$  is supposed to be population size, putting  $N$  as 1.5 billion was not feasible as it makes everything else insignificant. Therefore, we set  $N \sim 10^5$  and used the intuition of exposed population <sup>to infection</sup> as a subset of original population.

By SIR Model,

$$\frac{dS}{dt} = -\frac{\beta SI}{N}, \quad \frac{dI}{dt} = \frac{\beta SI}{N} - \gamma I, \quad \frac{dR}{dt} = \gamma I$$

We train our models to learn  $\beta$  and  $\gamma$ .

Now, let  $\bar{S}, \bar{I}, \bar{R}$  be the computed SIR values using the model for time = 1 to  $d$ .  $d$  is the number of days i.e 94 in this case. We define a loss:

$d(\beta, \gamma) = L2$  norm of (infected present -  $\bar{I}$ ). Denoting infected present as  $I$ .

$$d(\beta, \gamma) = [\bar{I} - I]^T [\bar{I} - I]$$

$$\therefore \frac{\partial d}{\partial \beta} = 2 [\bar{I} - I] \frac{\partial \bar{I}}{\partial \beta} = 2 [\bar{I} - I] \cdot \frac{\bar{I} (\beta + \Delta\beta) - \bar{I}(\beta)}{\Delta\beta}$$

$$\frac{\partial d}{\partial \gamma} = 2 [\bar{I} - I] \frac{\partial \bar{I}}{\partial \gamma} = 2 [\bar{I} - I] \frac{\bar{I} (\gamma + \Delta\gamma) - \bar{I}(\gamma)}{\Delta\gamma}$$

-  $\Delta\beta, \Delta\gamma$  are very small.

• We integrate over the range of  $t = 0$  to 94 on the given differentials to generate all  $\bar{I}$  values.

• Note,  $\frac{\partial \bar{I}}{\partial \beta}$  cannot be computed analytically.

Following procedure gives a fairly decent

approximation.

We have  $w = [\beta, \gamma]^T$ . Update for GD:

$$w^{(k+1)} \leftarrow w^{(k)} - \eta \begin{bmatrix} 2 \frac{(I - \bar{I}) \bar{I}(\beta + \Delta\beta) - \bar{I}(\beta)}{\Delta\beta}}{(I - \bar{I}) \frac{\bar{I}(\gamma + \Delta\gamma) - \bar{I}(\gamma)}{\Delta\gamma}} \end{bmatrix}$$

And for Newton's updates Hessian computation:

$$H = \begin{bmatrix} \frac{\partial^2 L}{\partial \beta^2} & \frac{\partial^2 L}{\partial \beta \partial \gamma} \\ \frac{\partial^2 L}{\partial \gamma \partial \beta} & \frac{\partial^2 L}{\partial \gamma^2} \end{bmatrix}$$

$$\text{And } \frac{\partial^2 L}{\partial \beta^2} = 2 \left[ (\bar{I} - I) \frac{\partial^2 \bar{I}}{\partial \beta^2} + \left( \frac{\partial I}{\partial \beta} \right)^2 \right]$$

$$\text{where } \frac{\partial^2 \bar{I}}{\partial \beta^2} = \frac{I(\beta + 2\Delta\beta) + I(\beta) - 2I(\beta + \Delta\beta)}{(\Delta\beta)^2}$$

$$\frac{\partial^2 L}{\partial \beta \partial \gamma} = \frac{\partial^2 L}{\partial \gamma \partial \beta} = 2 \left[ (\bar{I} - I) \frac{\partial^2 I}{\partial \beta \partial \gamma} + \left( \frac{\partial I}{\partial \beta} \right) \left( \frac{\partial I}{\partial \gamma} \right) \right]$$

$$\text{where } \frac{\partial^2 I}{\partial \beta \partial \gamma} = \frac{I(\beta + \Delta\beta, \gamma + \Delta\gamma) - I(\beta, \gamma + \Delta\gamma) - I(\beta + \Delta\beta, \gamma) + I(\beta, \gamma)}{(\Delta\beta)(\Delta\gamma)}$$

$$\frac{\partial^2 L}{\partial \gamma^2} = 2 \left[ (\bar{I} - I) \frac{\partial^2 \bar{I}}{\partial \gamma^2} + \left( \frac{\partial I}{\partial \gamma} \right)^2 \right]$$

$$\text{where } \frac{\partial^2 \bar{I}}{\partial \gamma^2} = \frac{I(\gamma + 2\Delta\gamma) + I(\gamma) - 2I(\gamma + \Delta\gamma)}{(\Delta\gamma)^2}$$

Newton's Update:

$$w^{(k+1)} \leftarrow w^{(k)} - H^{-1} \begin{bmatrix} (\bar{I} - I) [\bar{I}(\beta + \Delta\beta) - \bar{I}(\beta)] / \Delta\beta \\ (\bar{I} - I) [\bar{I}(\gamma + \Delta\gamma) - \bar{I}(\gamma)] / \Delta\gamma \end{bmatrix}$$