Lagrange Points: Equilibrium Points in Restricted 3-Body

Ross book, section 2.5

Murray & Dermott section 3.6

Les the rotating brane, we seek equilibrium points (points where there is no motion) In general, x=f(x), x & IR" equil points are those points & where = 0 news we look for \$ s.t. f(x) = 0 For the CRBBP, theops in first order form: $\dot{x} = v_x \qquad \dot{v}_x = 2\overline{v}_y - \overline{U}_x \qquad \frac{1}{2} \frac{\partial \overline{U}}{\partial y_i} = \frac{\partial \overline{U}}{\partial y_i}$ $\dot{y} = v_y \qquad \dot{v}_y = -2\overline{v}_y - \overline{U}_y \qquad \frac{1}{2} \frac{\partial \overline{U}}{\partial y_i}$ 2 = V2 = - 172 Equil, will have $\dot{x} = \dot{y} = \dot{z} = \dot{v}_x = \dot{v}_y = \dot{v}_z = 0$ => Vx = Vy = Vz = 0 | Ux = Uy = Uz = 0 | In other words, a critical point " of U(x,y,z) when 2 \$0, there are no critical points consider Z=0, Ux = Uy =0 in the place Restrict der now to y to

We'll use 1, 12

(-4,0)

(-4,0) $\overline{U(x,y)} = -\frac{(1-u)}{r_1} - \frac{u}{r_2} - \frac{1}{2}(x^2+y^2) - \frac{1}{2}u(1-u)$ $\overline{U(x,y)} = -\frac{(1-u)}{r_1} - \frac{u}{r_2}$ $\overline{U(x,y)} = -\frac{1}{2}(x^2+y^2) - \frac{1}{2}u(1-u)$ $0 \leq r_1 \text{ and } r_2$ ~= (x+μ)2+y3, ~2=(x-(1-μ))2+y2 Claim: x2+y2 = (1-12) 1,2 + 111,2-11 (1-12) (1-m) ~2 + m ~2 = (1-u) (x+u) 2+y2] + u (x-(1-u)) 2+y27

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(x+n)2+y2- m(x2+2ux+u2+x2) + u(x3-2(1-u)x+(1-u)2 + x2) = x2+2/xx+118+y2-2/2x(-113)-2/xx+2/12x + 4(1-4)2 x2 + x2 + 12 + 11 (1-211+112) - 113 = x2+ y2 + m2 + m - 2 m2 + p3 - p3 $= x^{2} + y^{2} + \mu - \mu^{2} = x^{3} + y^{2} + \mu(1-\mu)$ $= x^{2} + y^{2} + \mu - \mu^{3} = x^{3} + y^{2} + \mu(1-\mu)$ $\frac{1}{\sqrt{(r_{13}r_{2})}} = -\frac{(1-n)}{r_{1}} - \frac{1}{r_{2}} - \frac{1}{2}(1-n)r_{1}^{2} - \frac{1}{2}nr_{2}^{2} = -\frac{1}{2}$ $\frac{1}{\sqrt{(r_{13}r_{2})}} = -\frac{(1-n)}{r_{1}} - \frac{1}{r_{2}} - \frac{1}{2}(1-n)r_{1}^{2} - \frac{1}{2}nr_{2}^{2} = -\frac{1}{2}$ $\overline{\mathcal{U}}_{x} = \overline{\mathcal{U}}_{r_{1}} \frac{\partial r_{1}}{\partial x} + \overline{\mathcal{U}}_{r_{2}} \frac{\partial r_{2}}{\partial x} = \overline{\mathcal{U}}_{r_{1}} \left(\frac{x+x}{r_{1}} \right) + \overline{\mathcal{U}}_{r_{2}} \left(\frac{x-(1-x)}{r_{2}} \right) = 0$ $\overline{\mathcal{U}}_{\gamma} = \overline{\mathcal{U}}_{r_1} \frac{\partial r_1}{\partial \nu} + \overline{\mathcal{U}}_{r_2} \frac{\partial r_2}{\partial \nu} = \overline{\mathcal{U}}_{r_1} \left(\frac{\gamma}{r_1}\right) + \overline{\mathcal{U}}_{r_2} \left(\frac{\gamma}{r_2}\right) = 0$ Ux = Uy =0 is equis. to Un = Ura =0 So, we want to solve the Sofforers sys. of egs $0 = \overline{U}_{r_1} = \overline{U}_{r_2} + \overline{U}_{r_3}$ $0 = \overline{U}_{r_2} = -u_{r_2} + \frac{u}{r_2^2}$ $0 = \overline{U}_{r_3} = -u_{r_2} + \frac{u}{r_2^2}$ Similarly $r_3 = 1$ So there is a critical point of n=1=1 There are 2 locations satsisying n=1 and n=1 These are the "equilateral points"

They form an equilateral triangle

(a.k.a., "triangular points")

These are the Ly and Ly hagrange points

0.5

 m_1x

1

Ma

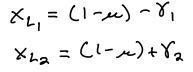
1.5

-2 -1.5 -1 -0.5 0

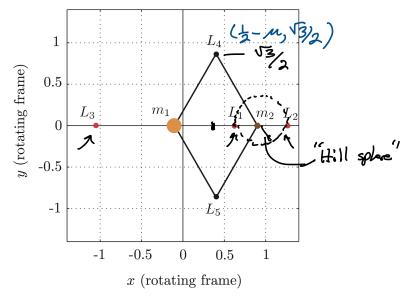
Consider the equil. between m_1 and m_2 (L_1)

The clistance of L_1 from m_2 Ly L_3 is δ_1 which is the real not δ_2 the sollowing polynomial δ_3 $\delta_1 = (3-a)\delta_1^4 + (3-2a)\delta_1^3 - a\delta_1^2 + 2a\delta_1 - n = 0$ Sor a=0.1, $\delta_1 = 0.29096$ An approximation is $\delta_1 = \delta_1 \left(1 - \frac{1}{3} \delta_1 - \frac{1}{9} \delta_1^2 + \cdots\right)$ $\delta_1 = \delta_2 \left(1 + \frac{1}{3} \delta_1 - \frac{1}{9} \delta_1^2 + \cdots\right)$ $\delta_2 = \delta_1 \left(1 + \frac{1}{3} \delta_1 - \frac{1}{9} \delta_1^2 + \cdots\right)$ "Hill radius" i for a=0.1, $\delta_3 = 0.322$









read "sphere of instrume"

