

Mathematical Models of Gene Regulation

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Today

Abstract

This paper explores the dynamics of gene regulation and degradation. We examine the self regulation of a single gene before moving to multi-gene systems and finally to discuss more complex regulatory system and the option available to more accurately model these. We examine how WOR1 and WOR 2 regulate each other in *Candida albicans* modelling the system using state of the art numerical packages and investigative techniques.

Introduction

Modelling the feedback system of genes has a few approaches, this paper will cover the use of differential equations to determine the concentration of these genes, specifically WOR1 and WOR2 in *Candida albicans*. At first a single gene positive feedback system with mRNA is explored, and later a multi-gene system containing both WOR1 and WOR2. Throughout this paper, assumptions will be made and discussed with regards to how CO₂, temperature and time delay affects the expression of the genes.

The results of both of these models yield a bistable system occurring, one where white cells dominate and another where opaque cells dominate. The positive feedback self regulating system is the simplest system possible which still has this bistable state, and as more feedback regulations get added, the complexity and dimension increases. This bistability is important in determining the interactions that *Candida albicans* has with its host, and as such will be a driving factor for how our models were derived.

Candida albicans is used as a model organism for fungal growth and infections effectively and enough research has gone into it that its entire genome sequence has been identified [?]. This can then be extrapolated to how other similar fungal infections can affect the human body and so similar treatments can be implemented. Another important model organism are rats (*Rattus norvegicus*) which are commonly used to study toxicology [?]. *Rattus norvegicus* have larger organs than a lot of other commonly used model organisms, and so are much better suited to compare to humans than others.

Using a series of differential equations is not the only way to model this sort of system, another technique to use would be that of a Stochastic process. Gene reactions are discrete and so differential equations may not be suited to solving these sort of problems, instead Stochastic processes or a Boolean network may yield more accurate results. These methods will be compared and contrasted with our chosen method.

1 Method

1.1 Introduction

All numerical calculations were carried out with *R* [?]. The third party packages *deSolve* [?], *phaseR* [?] and *ggplot2* [?] were used for modelling the equations, finding nullclines, constructing phase portraits and plotting the behaviour for each system. The diagrams have been constructed in order to adhere to the graphical notation for biological networks as proposed by Kitano in [?].

1.2 A Single Gene System

The simplest case to consider when modelling the interactions of genes and protein is the interaction of a single gene with its protein. There are three possible scenarios to consider in this case. The protein can feed back positively into its transcription (Figure ??), it can feed back negatively or it can have no affect its transcription at all. The last case is of no real interest to us and won't be looked at further. The first two cases, do however give rise to interesting dynamical systems and will be the focus of this section.

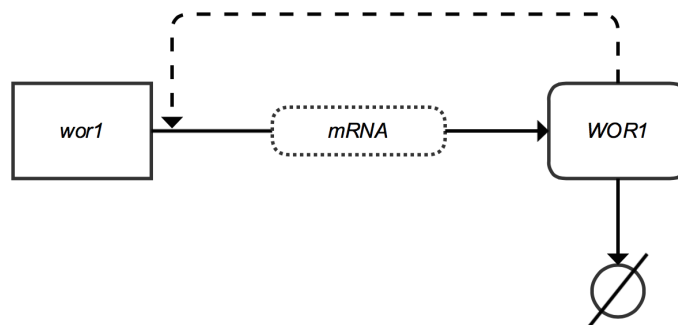


Figure 1: Positive feedback system of the *wor1* gene's feedback with the WOR1 protein, including mRNA and degradation of the protein.

The approach taken to constructing a system of equations for a positive and negative feedback dynamical system was inspired by the approach of de Jong in [?], it includes mRNA, protein and degradation. Hills equation is used to model the fraction of possible binding sites on the receptor that are occupied by a ligand.

1.2.1 Positive Feedback

Using this approach the positive feedback system depicted in Figure ?? can be mathematically described by the following equations.

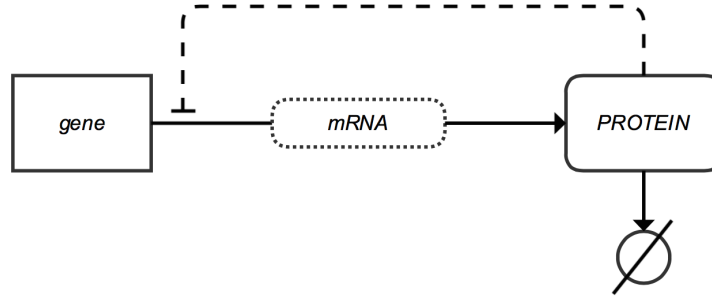


Figure 2: Negative feedback system of a gene with a protein including mRNA and degradation of the protein.

$$\begin{aligned}\frac{dx_1}{dt} &= \kappa_1 h(x_2) - \gamma_1 x_1 \\ \frac{dx_2}{dt} &= \kappa_2 x_1 - \gamma_2 x_2\end{aligned}$$

The variables are denoted as:

x_1 = Concentration of mRNA

x_2 = Concentration of Protein

κ_1, κ_2 = Production Rate of mRNA and Protein respectively

γ_1, γ_2 = Degredation Rate of mRNA and Protein respectively

$h(x) = \frac{x^n}{k^n + x^n}$ where k describes a threshold concentration and n a strength

One of these single gene positive feedback system as described above exists in *Candida Albicans*, for the sake of relevance we'll be discussing the above system as it pertains to this specific system where the gene is *wor1* and the protein is WOR1.

In order to investigate the system further the nullclines and phase portrait are plotted in Figure ???. We can see from these that there are three stationary points in this system. The middle stationary point around (1, 1) is not stable and of not much practical interest as even infinitesimally small perturbations will cause it to tend towards one of the other stationary points of which are both stable. It can be concluded from this that the system is bi-stable as there are exactly two stability points. Taking this one step further the behaviour of the protein around these stability points can be investigated to get a sense of the difference in physical state of the system being at either of the stability points.

The fraction of available binding sites on the receptor was modelled against the concentration of protein

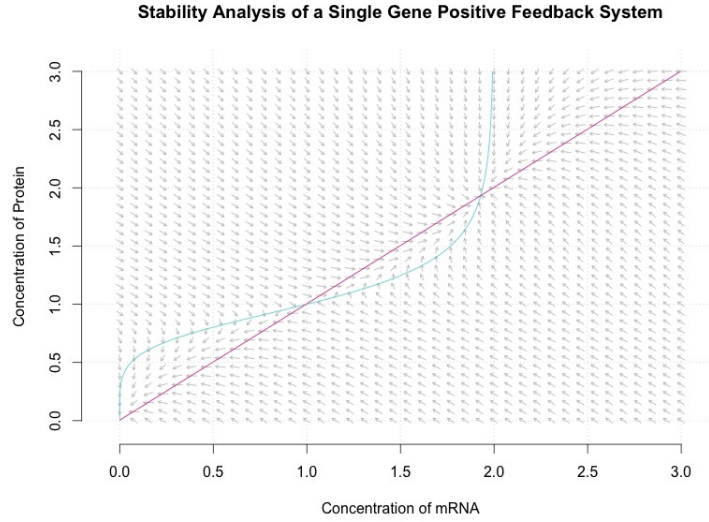


Figure 3: The stability of stationary point present in a single gene positive feedback system. The red line represents the nullcline for the protein and blue the nullcline of mRNA. The arrows represent the direction of change for the system at a given state.

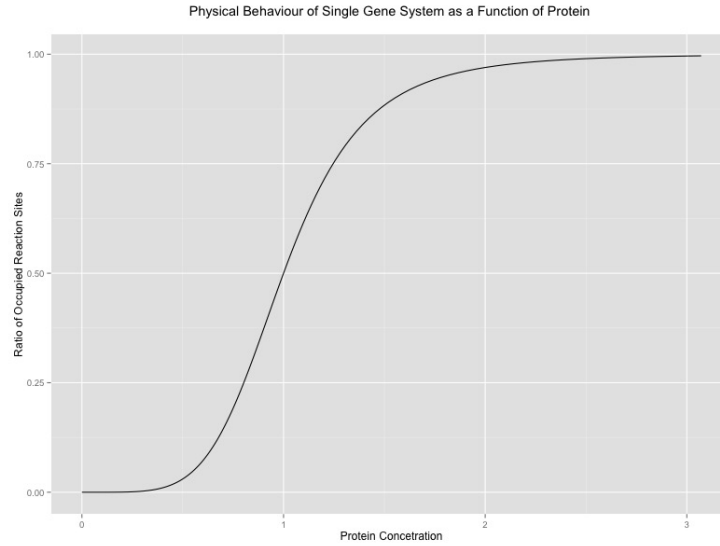


Figure 4: Compares the fraction of occupiable receptor sites on the protein that are currently occupied against the concentration of protein.

in Figure ???. This shows that as the concentration of protein increases the ratio of occupied receptor sites increases until all sites are occupied. We can think of this as a state where White is dominant and Opaque is subdued

1.2.2 Negative Feedback

The same approach as used in analysing the positive feedback system was applied to modelling the negative feedback system. The only difference in the set of equations that describe the system is a modification

to the Hill equation. Instead of the hill equation being $h(x) = \frac{x^n}{k^n + x^n}$ we use $h(x) = \frac{k^n}{k^n + x^n}$. This is a small modification with quite a drastic impact. Modelling the nullclines and phase portrait to investigate the behaviour of the system around its stability points in Figure ?? we can see that the negative feedback system has only one stationary point which is in turn its only stability point. It appears that the negative feedback system of a single gene is incapable of producing a bistable or multi stable state.

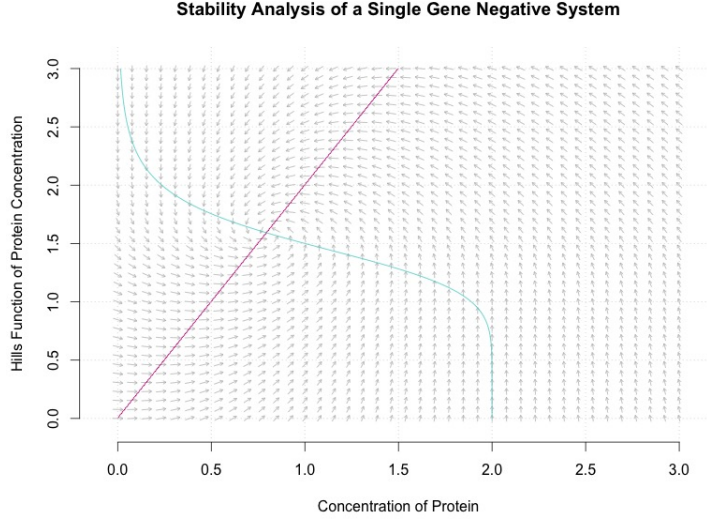


Figure 5: The stability of stationary point present in a single gene negative feedback system. The red line represents the nullcline for the protein and blue the nullcline of mRNA. The arrows represent the direction of change for the system at a given state.

1.3 Multiple Gene Systems

A vast number of multiple gene feedback loops are possible, sadly most of these systems are out of the scope of this paper. The two that will be investigated are mutual positive feedback between two genes and mutual negative feedback between two genes. A different approach to modelling these will be adopted as compared to the single gene cases. In order to keep things relatively manageable the impact of mRNA will be neglected and only the concentration of protein in each system will be looked at, this is the simplified approach to this problem adopted by de Jong in [?].

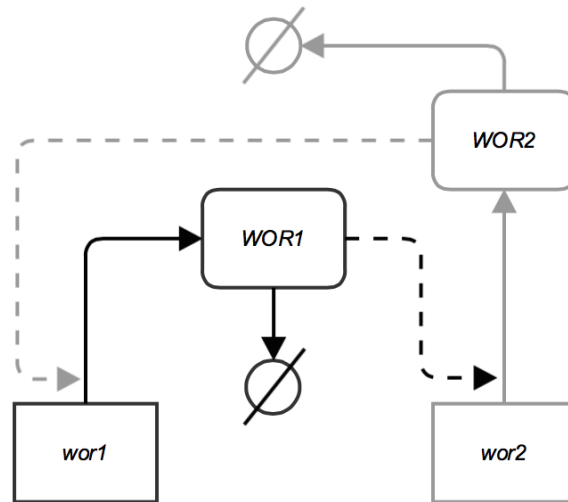


Figure 6: Positive feedback system of the *wor1* gene and the *wor2* gene whereby *WOR1* promotes *WOR2* and *WOR2* promotes *WOR1*

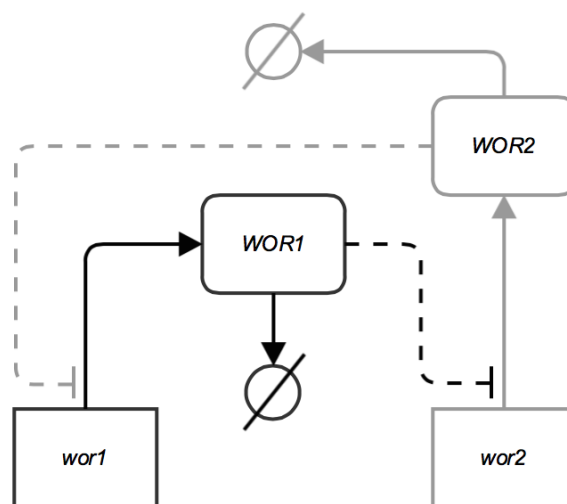


Figure 7: Negative feedback system of two genes where the protein mutually inhibit each other.

1.3.1 Positive Feedback

A network of 2 genes with mutual positive feedback also exists in the *Candida Albicans* cell between the *wor1* & *wor2* genes, this is the system as depicted in Figure ?? . The equations describing this system are given below.

$$\begin{aligned}\frac{dx_1}{dt} &= \kappa_1 h(x_2) - \gamma_1 x_1 \\ \frac{dx_2}{dt} &= \kappa_2 h(x_1) - \gamma_2 x_2\end{aligned}$$

The variables are denoted as:

x_1 = Concentration of WOR1

x_2 = Concentration of WOR2

κ_1, κ_2 = Production Rate of WOR1 and WOR2 respectively

γ_1, γ_2 = Degredation Rate of WOR1 and WOR2 respectively

$h(x) = \frac{x^n}{k^n + x^n}$ where k describes a threshold concentration and n a strength

Again, the nullclines and phase portrait are plotted to investigate the behaviour around the stability points. This can be seen in Figure ?? . This system behaves somewhat similar to the single gene positive feedbacks system, similarly it has three stationary points, two of which are stable and one of which is unstable. This makes sense when considering the behaviour of the general system

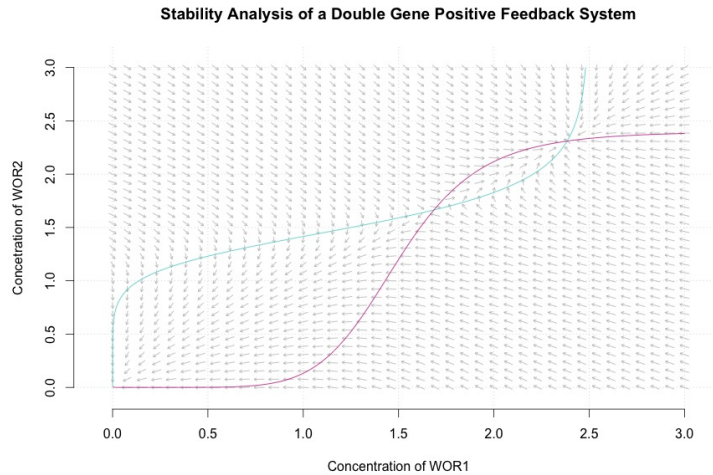


Figure 8: The stability of stationary point present in a double gene positive feedback system. The red line represents the nullcline for the protein and blue the nullcline of mRNA. The arrows represent the direction of change for the system at a given state.

1.3.2 Negative Feedback

Although, a known double feedback does not directly exist between two genes in *Candida Albicans* it is perhaps the most interesting situation to look at. The system is depicted in Figure ??, and the equation describing it are identical to those describing the positive apart from the negative half equation being used as described in the negative single gene model. Again, applying our standard analysis for stability of the system Figure ?? we see something completely different to the single gene case. Whereas the single gene with negative feedback only produce a single stationary and stability point the double gene with mutual negative feedback generates three stationary point with two of them being stable. This demonstrates that you can generate a bistable system out of solely negative feedback. An indirect double negative feedback system exists in *Candida Albicans* but requires the modelling of an additional gene which is beyond the scope of this paper.

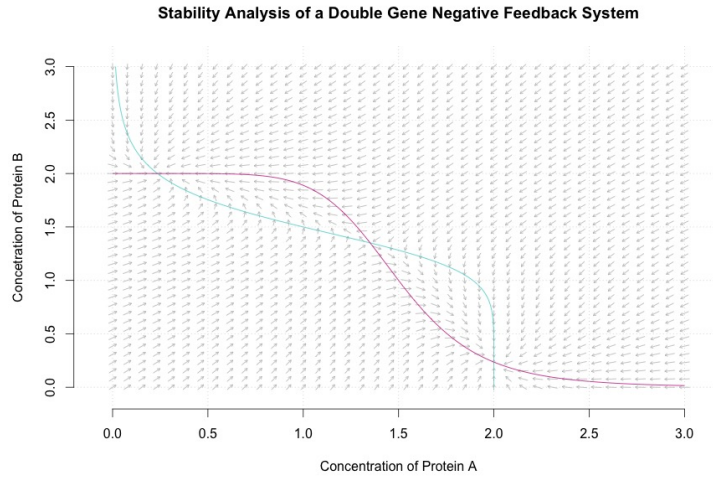


Figure 9: The stability of stationary point present in a double gene negative feedback system. The red line represents the nullcline for the protein and blue the nullcline of mRNA. Thewidth=0.6e arrows represent the direction of change for the system at a given state.

2 Discussion

2.1 Findings

Single Gene

Positive Feedback

Negative Feedback

Multiple Gene System

Mutual Positive Feedback

Mutual Negative Feedback

2.2 Comparison of Methods

There are other many possible ways of mathematically modelling gene regulation using differing methods. Here we will compare and contrast our method to evaluate its value.

Our chosen method was solving differential equations. Differential equations are a power method of simulating gene regulation due to the many known methods for solving and computing them. Matlab come with packages that solve differential equations for the user, instead of having to specifically code these yourself. There also exist many well known methods of analysing differential equations and understanding their results. This was particularly beneficial, allowing us to understand how the system was behaving based on which set of genes, proteins and feedbacks that were being modelled.

Some downsides of using our method was that we did not know appropriate values of parameters to accurately simulate the real system. An assumption of differential equations is that you are working with continuous variables. On the molecular level this is not true, you can't have half a protein or a gene. For this reason it would be far more realistic to use a stochastic model.

Stochastic models are used to describe systems of random variables and their time evolution. Stochastic processes are the counterpart to a deterministic system. As previously mentioned before, a stochastic method is a better reflection of the discrete nature of gene regulation than continuous variables. By using a continuous model we have made an assumption about the nature of the system that may inaccurately represent its time evolution.

Using a stochastic method also has its own issues and raises many questions. For example, the WOR1 auto regulatory feedback loop is known to cause a stochastic W/O transition. However, this contradicts the experimental fact that the WOR2⁺ produces a stable white form. This indicates that there exists an unknown negative regulation that generates a positive feedback loop between WOR1 and EFG1. This may only be possible if the unknown protein competes with the regulation of wor1 gene that keeps the system in the default state. (<https://lifeware.inria.fr/soliman/publi/KSF09jtb.pdf> page 6)

This tells us that modelling using stochastic methods is not some kind of magic bullet. Using stochastic methods still leads to major differences between experimental observation and reality.

2.3 Expanding the Model

Many environmental factors are known to effect the regulation of *Candida Albicans*. It is know that white-opaque and opaque-white switching rates can be strongly influenced by environmental factors such as temperature and CO2 concentration.

(Huang, Guanghai et al. "CO2 Regulates White-Opaque Switching in *Candida Albicans*.) demonstrated that a temperature shift from 25-37 degrees caused an increase in the O/W switching rate. This temperature increase also lead to a total increase in production of both opaque and white states. Studies of the effect of CO2 concentration on the the switching states (Huang, Guanghai et al.) showed that W/O was stimulated and O/W was blocked. They analysed the induction of switching by CO2 in *wor1* discovering that it suppressed switching of white cells.

Our model has not taken temperature or CO2 concentration into account which, as described above, would impact the production and degradation rates significantly. The model is a theoretical mathematical model of the regulation of *Candida Albicans*. It does not represent realistic values for concentrations of proteins, instead modelling the generalised behaviour of its feedbacks. To accurately apply our model to reality we need to introduce many dependancies on environmental conditions to our constants. To model this dependancy far outside the scope of this assignment and would require significant research and data.

MircoRNA - there are genes that code for expressed proteins and genes that code to silence proteins after they are translated by mRNA - microRNA repress the translation of mRNA - so they silence genes that express, and silence genes that silence

3 Model evaluation and conclusion

Our model does provide insight into the way a system of genes may regulate itself. However it uses a large number of assumptions in order to reach its result. Due to this it is very difficult to judge whether our model accurately represents the regulation of *wor1* and *wor2* in a real biological system.

We have demonstrated possible behaviours of the system under certain condition, but also explored how other variables or methods of modelling may cause the real system to differ from our results. We have explored and discussed a number of methods used in modern mathematical modelling.

It is clear that mathematical models are a powerful technique for analysing biological systems. In future years it is likely that collaboration between scientists and mathematicians will lead to deep and accurate insights into the way these systems behave.

<http://www-sop.inria.fr/comore/arcgdyn/28fev/arc03-intro.pdf>

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