

```

; @file: project1.asm
; @authors: Vincent Allen, Sam Itchner, Dakota Ewigman
; @date: 3/31/2014
;
; @registers:
; R0 - Bits 0 through 4 track previous button states each iteration.
;   - Bit 5 tracks state of Vince's button (toggles functionality)
;   - Bit 6 determines which set of LEDs will change with input.
;   - Bit 7 tracks whether or not the 4 bit value R3 turned over.
; R3 - Count stored here (4 bit)
; R1 - Least significant counter for delay
; R2 - Most significant counter for delay
; R4 - Oscillator counter
; R5,R6,R7 - Delay for Sam's button.

;=====
;                                     MAIN LOOP
;=====

        ORG 0

        MOV 0xA4, #0      ; Set Port 2 to bi-directional
        MOV 0x91, #0      ; Set Port 1 to bi-directional
        MOV 0x84, #0      ; Set Port 0 to bi-directional

        MOV R0, #0        ; R0.7: no turn over, R0.6: use corner LEDs, R0.5:
        ; start with 1's comp, R0.0-R0.4: not pressed
        MOV R1, #0
        MOV R2, #0
        MOV R3, #0        ; Count set to 0
        MOV R4, #0

        CLR P1.7          ; Default alarm off

MainLoop:    LCALL CheckIncBtn
            LCALL CheckDecBtn
            LCALL CheckVincesBtn
            LCALL CheckSamsBtn
            LCALL CheckDakotasBtn
            LCALL PostProcessing
            SJMP MainLoop

;=====
;                                     POST, and BTN CHECKS
;=====

;-----
; @name: CheckIncBtn
; @brief: If button is being held down, set the
;         state to 1. Else check if was set to 1
;         last iteration. If so, it was just
;         released and we need to increment,
;         update LEDs, the duration of the alarm

```

 Vince  
 Dakotn  
 Sam



```

;         and set the state to 0 (for this btn).
;-----
CheckIncBtn:      MOV A, R0
                  JB  P0.1, IncNotPressed      ; If pressed:
                  SETB ACC.0                    ;   Change state to pressed
                  MOV R0, A
                  SJMP CheckIncBtnRET

IncNotPressed:    NOP                          ; Delay - consistent alarm frequency
                  NOP
                  JNB ACC.0, CheckIncBtnRET      ; Else, if pressed last check:
                  CLR ACC.0                      ;   Change state to released
                  MOV R0, A
                  LCALL IncMethod                ;   Increment counter
                  LCALL CheckForTurnOver         ;   If turned over, R0.7 set, else clr
                  LCALL SetLEDs                  ;   Update LEDs
                  LCALL SetAlarm                 ;   If turned over, set R1, R2, R4 -
                  sound alarm

CheckIncBtnRET:    RET

;-----
; @name: CheckDecBtn
;-----
CheckDecBtn:      MOV A, R0
                  JB  P0.3, DecNotPressed
                  SETB ACC.1
                  MOV R0, A
                  SJMP CheckDecBtnRET

DecNotPressed:    NOP
                  NOP
                  JNB ACC.1, CheckDecBtnRET
                  CLR ACC.1
                  MOV R0, A
                  LCALL DecMethod
                  LCALL CheckForTurnOver
                  LCALL SetLEDs
                  LCALL SetAlarm

CheckDecBtnRET:    RET

;-----
; @name: CheckVincesBtn
;-----
CheckVincesBtn:   MOV A, R0
                  JB  P0.2, VincesNotPressed
                  SETB ACC.2
                  MOV R0, A
                  SJMP CheckVincesBtnRET

VincesNotPressed: NOP
                  NOP
                  JNB ACC.2, CheckVincesBtnRET
                  CLR ACC.2
                  MOV R0, A
                  LCALL VincesMethod

```



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        LCALL CheckForTurnOver
        LCALL SetLEDs
        LCALL SetAlarm

```

```
CheckVincesBtnRET:  RET
```

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;-----
; @name: CheckSamsBtn
;-----

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CheckSamsBtn:      MOV A, R0
                   JB  P1.4, SamsNotPressed
                   SETB ACC.3
                   MOV R0, A
                   SJMP CheckSamsBtnRET

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SamsNotPressed:   NOP
                   NOP
                   JNB ACC.3, CheckSamsBtnRET
                   CLR ACC.3
                   MOV R0, A
                   LCALL SamsMethod
                   LCALL CheckForTurnOver
                   LCALL SetLEDs
                   LCALL SetAlarm

```

```
CheckSamsBtnRET:  RET
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;-----
; @name: CheckDakotasBtn
;-----

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CheckDakotasBtn:  MOV A, R0
                   JB  P0.0, DakotasNotPressed
                   SETB ACC.4
                   MOV R0, A
                   SJMP CheckDakotasBtnRET

```

```

DakotasNotPressed: NOP
                   NOP
                   JNB ACC.4, CheckDakotasBtnRET
                   CLR ACC.4
                   MOV R0, A
                   LCALL DakotasMethod
                   LCALL CheckForTurnOver
                   LCALL SetLEDs
                   LCALL SetAlarm

```

```
CheckDakotasBtnRET: RET
```

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;-----
; @name: PostProcessing
;-----

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PostProcessing:   LCALL Delay
                   RET

```

```

;=====
;
;                                     OTHER METHODS
;=====

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```
;-----  
; @name: SetLEDs  
; @brief: Sets the LEDs to represent Register 3  
;-----
```

SetLEDs:

```
MOV A,R0  
JB ACC.6, Sides ; Jump to side lights if 1  
  
MOV A,R3 ; Turn on corner LEDs  
CPL A ; Account for active low  
  
MOV C,ACC.3  
MOV P2.7,C  
MOV C,ACC.2  
MOV P2.4,C  
MOV C,ACC.1  
MOV P2.5,C  
MOV C,ACC.0  
MOV P2.6,C  
SJMP SetLEDsRET
```

Sides:

```
MOV A,R3 ; Turn on Side LEDs  
CPL A ; Account for active low  
  
MOV C,ACC.3  
MOV P0.4,C  
MOV C,ACC.2  
MOV P0.5,C  
MOV C,ACC.1  
MOV P0.6,C  
MOV C,ACC.0  
MOV P0.7,C
```

SetLEDsRET: RET

```
;-----  
; @name: IncMethod  
; @brief: Increments Register 3  
;-----
```

IncMethod: INC R3  
RET

```
;-----  
; @name: DecMethod  
; @brief: Decrements Register 3  
;-----
```

DecMethod: DEC R3  
RET



```

; @name: VincesMethod
; @brief: Toggle what this button does after
;         each time it is pressed:
;         1)Flip the bits of the current counter
;         value (R3)
;         2)Rotate the counter bits (left).
;-----
VincesMethod:      MOV A, R0
                   JB ACC.5, RotateR3Bits

                   MOV A, R3           ; Flip the bits
                   CPL ACC.0
                   CPL ACC.1
                   CPL ACC.2
                   CPL ACC.3
                   MOV R3, A
                   SJMP ToggleBtnFunct

RotateR3Bits:      MOV A, R3           ; Rotate the bits
                   MOV B, #2
                   MUL AB              ; First double to shift bits (left)
                   MOV C, ACC.4        ; Take 4th bit and rotate back to front
                   MOV ACC.0, C
                   CLR ACC.4
                   MOV R3, A

ToggleBtnFunct:   MOV A, R0
                   CPL ACC.5           ; Toggle flip/rotate
                   MOV R0, A
                   RET

;-----
; @name: DakotasMethod
; @brief: 'Rotate' which LED's are used
;-----
DakotasMethod:
                   MOV A,R0
                   CPL ACC.6           ; change LED outputs
                   MOV R0,A

                   SETB P2.4           ; clear corner lights
                   SETB P2.7
                   SETB P2.5
                   SETB P2.6

                   SETB P0.5           ; clear side lights
                   SETB P0.4
                   SETB P0.7
                   SETB P0.6

                   RET                 ; Return

```



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;-----
; @name: CheckForTurnOver
; @brief: If operation caused turn over, set
;         R0.7 to 1. Clear R3.4 thru R3.7
;-----

```

CheckForTurnOver:

```

    MOV A,R3
    MOV B,R0
    JNB ACC.4,Over ; if R3.4 is 0, jump to Over
    SETB B.7
    CLR ACC.4      ; clear excess bits
    CLR ACC.5
    CLR ACC.6
    CLR ACC.7
    MOV R3,A

```

Over:

```

    JNB ACC.7,Under ; if R3.7 is 0, jump to Under
    SETB B.7
    CLR ACC.4
    CLR ACC.5
    CLR ACC.6
    CLR ACC.7
    MOV R3,A

```

Under:

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    MOV R0,B
    RET

```

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;-----
; @name: SetAlarm
; @brief: Sound the alarm for .1 sec with a
;         frequency of 1kHz.
;-----

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SetAlarm:

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    MOV A, R0
    JNB ACC.7, SetAlarmRET ; Skipping this if didn't turn over
    MOV R4, #25             ; Iterations per half-period
    MOV R2, #50             ; Most significant duration count
    MOV R1, #40             ; Least significant duration count
    CLR ACC.7
    MOV R0,A

```

SetAlarmRET:

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    RET

```

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;-----
; @name: Delay
; @brief: Oscillate the speaker between on and
;         off for a brief period of time
;-----

```

Delay:

```

    MOV A,R1
    JZ ChkR2

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```

MOV A,R4
JNZ OscDec

DEC R1      ; Dec R1 (R1 is not 0, R4 is 0)
CPL P1.7    ; Toggle sound
MOV R4, #26  ; R4 = 25+1 to account for dec
DEC R4      ; Dec R4 (R1 is not 0)
SJMP DelayRet ; Finished

```

```

OscDec:      NOP
             NOP
             NOP
DEC R4      ; Dec R4 (R1 is not 0)
SJMP DelayRet ; Finished

```

```

ChkR2:      NOP
MOV A,R2
JZ DelayEnd

DEC R4      ; Dec R4 (R1 is 0, R2 is not 0)
DEC R2      ; Dec R2
MOV R1, #40  ; R1 = 40
SJMP DelayRet ; Finished

```

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DelayEnd:    CLR P1.7    ; Sound off (R1 is 0, R2 is 0)
MOV R1, #0   ; Clear registers
MOV R2, #0
MOV R4, #0

```

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DelayRet:    RET

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;-----
; @name: SamsDelay
; @brief: Time Delay used by Sam
;-----

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SamsDelay:

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```

MOV R5,#10

```

```

ACH:

```

```

MOV R6,#250

```

```

HERE:

```

```

MOV R7,#250

```

```

AGAIN:

```

```

DJNZ R7,AGAIN

```

```

DJNZ R6,HERE

```

```

DJNZ R5,ACH

```

```

RET

```

```

;-----
; @name: SamsMethod
; @brief: Clears Register R3 (the count)
; Also flashes all LEDs twice for input feedback
;-----

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```

SamsMethod:

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MOV R3,#0

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```
    lcall TurnOffLEDS
    lcall SamsDelay
    lcall TurnOnLEDS
    lcall SamsDelay
    lcall TurnOffLEDS
    lcall SamsDelay
    lcall TurnOnLEDS
    lcall SamsDelay
    lcall TurnOffLEDS
    RET
```

```
;-----
; @name: TurnOnLEDS
; @brief: Turns on all LEDs
;-----
```

```
TurnOnLEDS:    CLR P2.4
               CLR P0.5
               CLR P2.7
               CLR P0.6
               CLR P1.6
               CLR P0.4
               CLR P2.5
               CLR P0.7
               CLR P2.6
               RET
```

```
;-----
; @name: TurnOffLEDS
; @brief: Turns off all LEDs
;-----
```

```
TurnOffLEDS:   SETB P2.4
               SETB P0.5
               SETB P2.7
               SETB P0.6
               SETB P1.6
               SETB P0.4
               SETB P2.5
               SETB P0.7
               SETB P2.6
               RET
```

end