

view_frames Result

Recorded at time: 472.168

map

Broadcaster: /amcl
Average rate: 40.361 Hz
Most recent transform: 5472.141 (-4999.973 sec old)
Buffer length: 2.552 sec

odom

Broadcaster: /gazebo
Average rate: 10.400 Hz
Most recent transform: 472.164 (0.004 sec old)
Buffer length: 2.500 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (472.168 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (472.168 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (472.168 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.400 Hz
Most recent transform: 472.164 (0.004 sec old)
Buffer length: 2.500 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.400 Hz
Most recent transform: 472.164 (0.004 sec old)
Buffer length: 2.500 sec

right_wheel