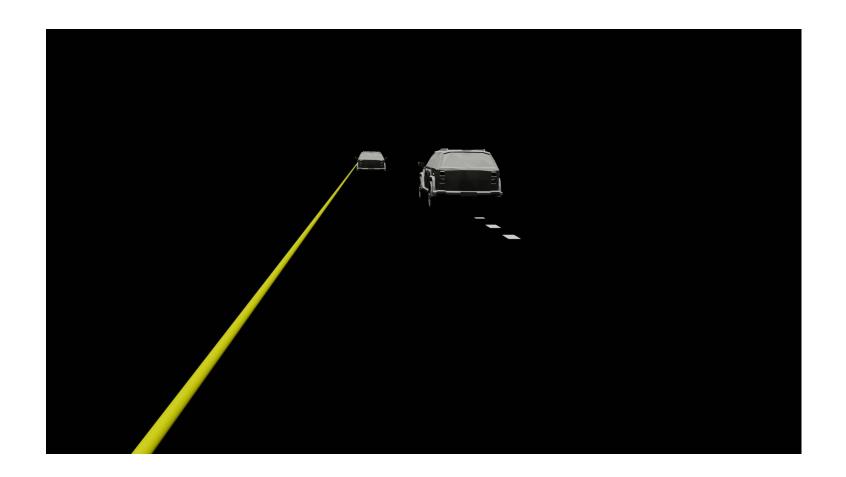


Overview:

- 1. Vehicle detection, classification using YOLOv3, 3-D bounding boxes, classical approaches
- 2. Lane Detection Using YOLOPv2 and classical approaches
- 3. Monocular Depth Estimation using Transformer based MIDAS
- 4. Road Signs using YOLOv3
- 5. Traffic lights using YOLOv5
- 6. Other objects, Blender tricks

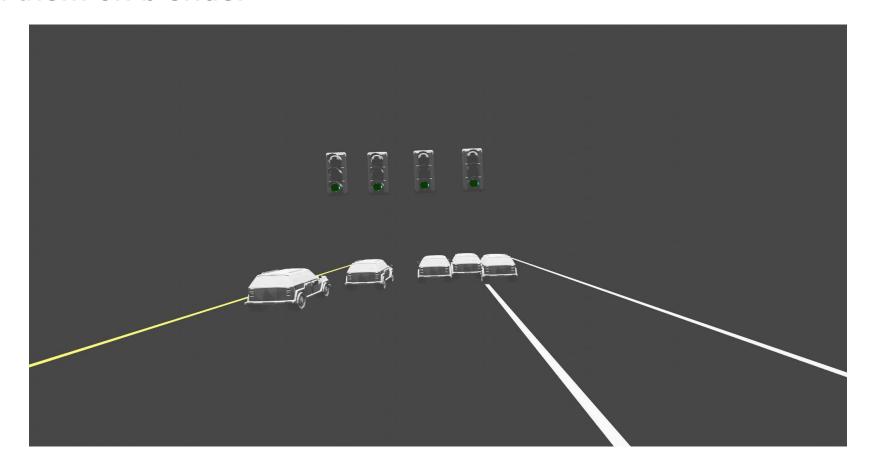
Vehicle detection, classification using YOLOv3

Yolo 3D model was used for Vehicle Detection and classification



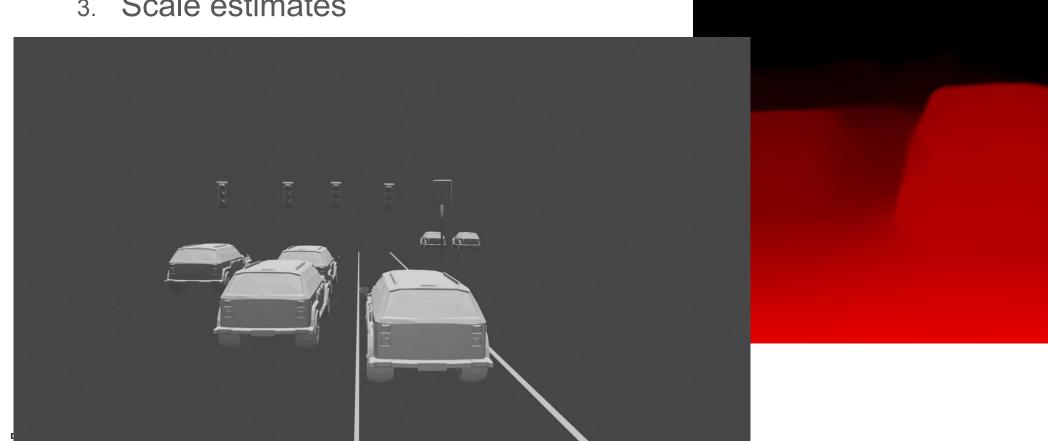
Lanes - YOLOPv2 and classical approaches

- YOLOPv2 and LaneNet were used for lane detection
- We detected the lane points from the images, projected them in 3-D and rendered them on blender



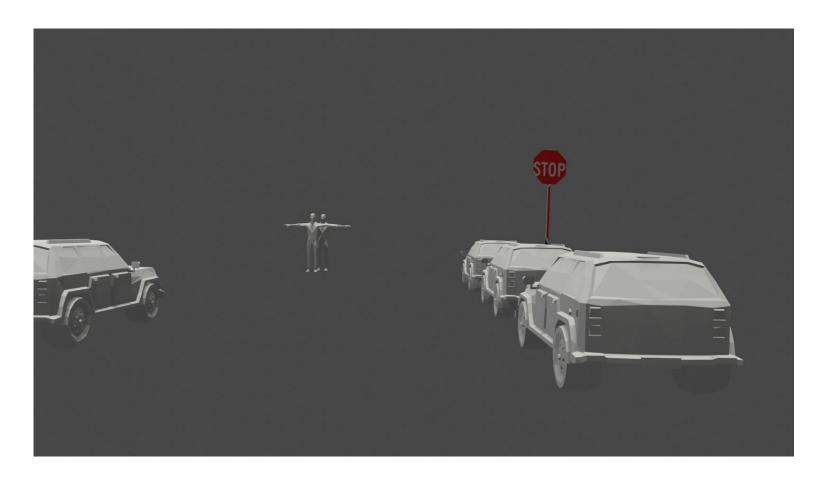
Monocular Depth Estimation using Transformer based MIDAS

- 1. Depth Map
- **Exponential Fitting**
- 3. Scale estimates



Road Signs

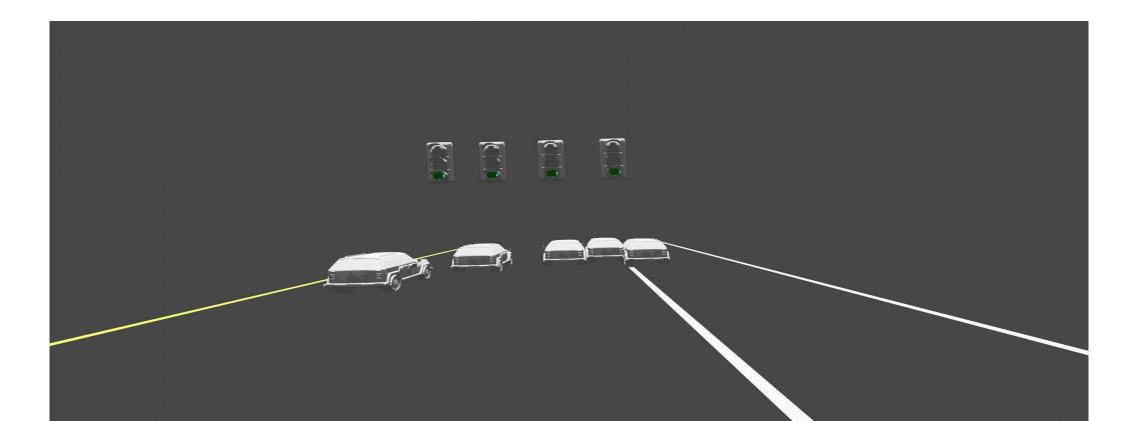
- Detected Road signs using YOLOv3
- Addition of an extra plane for pasting the .png image on blender Road signs



Traffic Light

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- 1. Used MS COCO-based YOLOv3 to detect the traffic lights
- 2. Created different assets for different lights and performed color thresholding



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- 3. Monocular Depth Estimation: https://github.com/isl-org/MiDaS
- 4. Object Detection: Cars, Trucks, Traffic Lights, Road Signs: https://github.com/xiaogangLi/tensorflow-MobilenetV1-SSD
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- 8. YOLO 3-D bounding boxes: https://github.com/ruhyadi/YOLO3D
- 9. Pedestrian keypoint detection: https://github.com/ZheC/Realtime/Multi-Person/Pose/Estimation

