



Chapter – 5: Magnetic Materials

- 5.1 Ferromagnetism, Ferrimagnetism, Paramagnetism
- 5.2 Domain Structure, Hysteresis loop, Eddy Current losses, Soft magnetic materials
- 5.3 Fe Si alloys, Ni Fe alloys, Ferrites for high frequency transformers
- 5.4 Square loop materials for magnetic memory, Relaxation Oscillators, Hard magnetic materials such as carbon steels alnico and barium ferrites

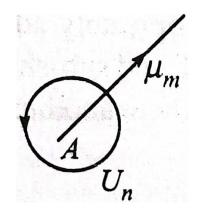


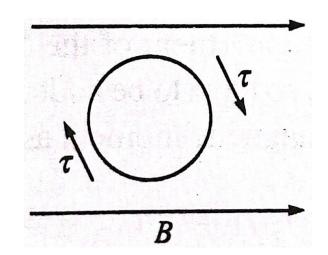
- Many **electrical engineering devices** such as inductors, transformers, rotating machines etc. are based on the **utilization of magnetic properties** of materials.
- To understand magnetic materials and magnetism properly, following must be made clear.
 - Magnetic Dipole Moment
 - Magnetization Vector
 - Magnetizing Field or Magnetic Field Intensity
 - Magnetic Permeability and Susceptibility

Magnetic Dipole Moment & Atomic Magnetic Moments



- In general for a coil, the magnitude of dipole moment is $\mu_m=NIA$; where N is the number of turns, I is the current, A is the cross sectional area
- When a magnetic dipole is placed in a magnetic field, it experiences a torque that tries to rotate the magnetic moment to align its axis with the magnetic field.





Magnetic Dipole Moment & Atomic Magnetic Moments



Magnetic Dipole Moment in atomic form:

• An orbiting electron in an atom behaves much like a current loop and has a magnetic dipole moment associated with it called orbital magnetic moment, μ_{orb}

$$\mu_{orb} = I(\pi r^2) = \frac{-e\omega r^2}{2}$$
 (Since, N = 1 & I = charge flow per unit time = $\frac{-e\omega}{2\pi}$)

- Angular momentum of electron is $L=m_e v r=(m_e \omega r) r=m_e \omega r^2$
 - $\omega r^2 = \frac{L}{m_e}$ Since **L** is quantized $L = l\hbar$ where l is the orbital quantum number.
 - So, orbital magnetic moment is $\mu_{orb} = \frac{-e}{2m_e}L$

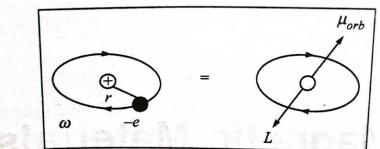
- The intrinsic angular momentum of electron denoted by S gives rise to
 - Since **S** is quantized $S = s\hbar$ spin magnetic moment $\mu_{spin} = \frac{-e}{m_s} S = -s\hbar \frac{e}{2m_s}$ Intrinsic Angular momentum \rightarrow S
- The overall magnetic moment of the electron consists of μ_{orb} and μ_{spin} appropriately added (both are vector quantities).

Magnetization Vector (M)



• The magnetic field inside the solenoid with free space inside is B_0 given by

$$m{B_0} = m{\mu_0} m{n} m{I}$$
 where n is number of turns per unit length, I is current through the solenoid, μ_0 is absolute permeability of free space= $4\pi \times 10^{-7} \, rac{H}{m}$, I' is current per unit length



An orbiting electron is equivalent to a magnetic dipole moment m_{ort}

- If a cylindrical material is placed inside the solenoid, the magnetic field will be changed from B₀
 to B.
- Each atom of the material responds to the applied field and develops a net magnetic moment μ_m along the applied field.
- The medium **gets magnetized**, **Magnetization vector M** describes the **extent of magnetization** of the medium.
- Magnetization vector M is defined as magnetic dipole moment per unit volume.

$$M = \frac{1}{V} \sum_{i=1}^{N} \mu_{mi} = n_{atomic} \mu_{av};$$

where n_{atomic} = number of atoms per unit volume, μ_{av} = average magnetic dipole moment per atom.

Magnetizing Field, Magnetic Field Intensity



- The field inside the magnetized material is the sum of the applied field H and a contribution from the magnetization M at the material.
- Magnetizing field H is the cause and magnetic field B is its effect.
- *H* solely depends upon external conduction currents only whereas the magnetic field *B* depends on the magnetization capability of the material.

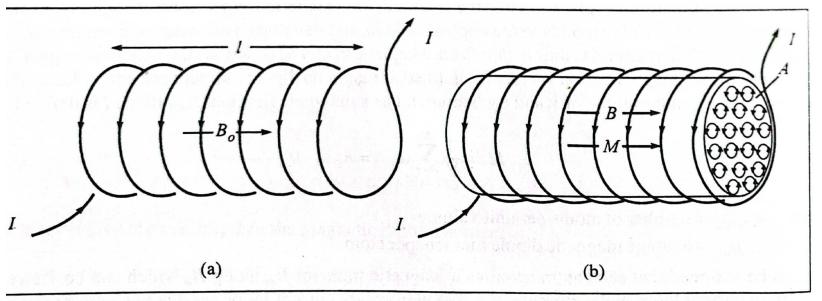


Fig. 5.4 Magnetic field of a solenoid with and without medium.

Magnetic Permeability and Susceptibility



 The magnetic permeability of the medium at any point is defined as the magnetic field per unit magnetizing field

 $\mu = \frac{B}{u}$; μ represents to what extent a medium is permeable by a magnetic field.

• Relative permeability of the medium is defined as the fractional increase in the magnetic field with respect to the magnetic field in free space when a material medium is introduced.

$$\mu_r = \frac{B}{B_0} = \frac{B}{\mu_0 B}$$

$$\mu = \mu_0 \mu_r;$$

 $\mu_r = \frac{B}{B_0} = \frac{B}{\mu_0 H}$ μ is absolute permeability, μ_r is relative permeability, μ_0 is absolute permeability of the free space $=4\pi imes10^{-7} rac{H}{-}$

- The magnetization M produced in the material depends on the net magnetic field B.
- Magnetization M is related to magnetizing field H as $M = \chi_m H$; χ_m is magnetic susceptibility

• Now,
$$B = B_0 + \mu_0 M$$

$$B = \mu_0 H$$
 (due to vacuum) + $\mu_0 M$ (due to material)

$$B = \mu_0 H + \mu_0 \chi_m H$$

$$B = (1 + \chi_m)\mu_0 H$$

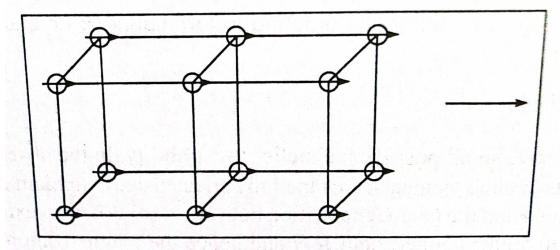
$$B = \mu_r \mu_0 H$$
; where $\mu_r = (1 + \chi_m)$

This expression relates the relative permeability with magnetic susceptibility of the material.

Ferromagnetism



- Ferromagnetic materials can possess large permanent magnetization even in the absence of an applied field.
- The magnetic susceptibility is positive and very large and depends on the applied field intensity.
- The relationship between magnetization M and μ_0H is highly non linear.
- At sufficiently high fields, magnetization saturates.
- The ferromagnetic crystal has **magnetic moments** of all crystal **aligned in an orderly manner** so as to give rise to the **net magnetization vector** *M*.
- Ferromagnetism occurs below a critical temperature T_c called Curie temperature.
- At temperature above this, ferromagnetism is lost.

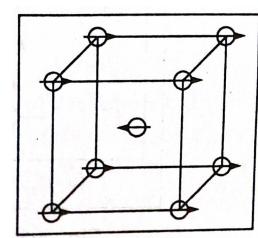


ig. 5.5 Magnetized region of Ferromagnetic material

Anti-ferromagnetism



- Antiferromagnetism materials have small positive susceptibility.
- In the absence of external field, there is not net magnetization of the material.
- They possess magnetic ordering in which the **magnetic moments** on **alternating atoms in the crystals align in opposite directions** \rightarrow due to quantum mechanical exchange interaction.
- Occurs below a critical temperature called Néel temperature. Above this they are paramagnetic.
- These substances are freely magnetized when subjected to a strong magnetic field.
- Example: MnO, FeO, CoO, NiO, Fe Cl_3 Mn O_4 , Cr, Mn, MnS etc

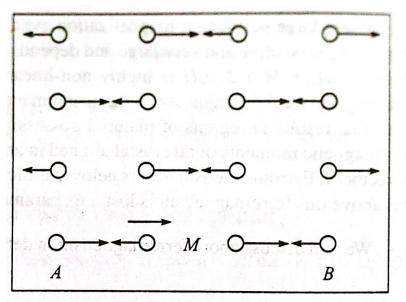


Antiferromagnetic crystal (Cr)

Ferrimagnetism



- Ferrimagnetic materials exhibit magnetic behavior similar to ferromagnetism below a critical temperature called Curie temperature.
- As shown in the figure, all atoms A have their spins aligned in one direction and all atoms B have their spins aligned in opposite direction.
- Magnetic moment of atom A is greater than that of atom B because of which there will be net magnetization in the crystal even in the absence of external applied field.
- These materials are non- conducting, so they do not suffer from eddy current losses.
- This is the reason for these materials being used in high frequency electronic applications.
- These materials are generally known as **ferrites** and represented by XFe_3O_4 , where X=Mg,Cu,Mn,Ni,Zn,Cd etc.



. 5.7 Magnetic ordering in ferrimagnetic crystal

Paramagnetism



- Paramagnetic materials have small positive magnetic susceptibility.
- In the absence of external magnetic field, molecular moments (atomic moments) are randomly oriented due to random collision of molecules.
- So, the average dipole moment and the net magnetization both are zero.
- When an external field is applied, μ_{av} does not equal zero and depends upon the applied field $\mu_0 H$ and hence the magnetization is also non zero and is equal to $\chi_m H$.
- Magnetization increase with $\mu_0 H$ but decreases with increase in temperature.
- At higher temperature, the molecular collisions destroy the alignment of molecular magnetic moments with applied field i.e. Curie law is obeyed.
- When they are placed in a non- uniform magnetic field, the induced magnetization is along the direction of B and there is a net force toward greater field.
- Many gases and metals are paramagnetic. E.g. Pt, Al, Cr, Mn and dilute solutions of ferromagnetic materials.

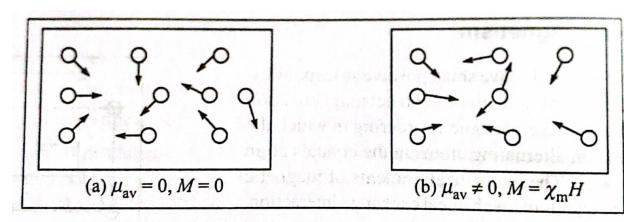


Fig. 5.8 Without external field (a), with external field (b)

[']20/2023 MK/ EEM 11

Diamagnetism



- Materials with negative magnetic susceptibility are termed as diamagnetic substances.
- Relative permeability is slightly less than unity.
- When placed in magnetic field, the magnetization vector M is in opposite direction to the applied field -> causing magnetic field within the material to be less than the applied field.
- Negative susceptibility → these substances trying to expel the applied field from within the material.
- Covalent crystals and many ionic crystals are diamagnetic because the constituent atoms have no unfilled sub-shell.
- Superconductors are perfect diamagnet with $\chi_m=-1$ and totally expel the applied field.
- Other examples are Bi, Sb, Au, Cu, Hg, water, air, alkali halides, organic materials, many polymers, covalent solids like Si, Ge, diamond etc.
- The average value of magnetic susceptibility of diamagnetic materials is in the range of -10^{-6}

Domain Structure / Domain Theory of Ferromagnetism



• A magnetic domain is a region of the crystal in which all the spin magnetic moments are aligned to produce a magnet in one direction only.

Figure alongside shows a single crystal of iron that has a permanent magnetization.

 There is a potential energy stored in a magnetic field called magnetostatic energy which can be reduced in the external field by dividing the crystal into two domains where the

magnetizations are in opposite directions.

 Thus, there is a boundary between the two domains where the magnetization changes from one direction to the opposite direction called as Domain wall or Bloch wall.

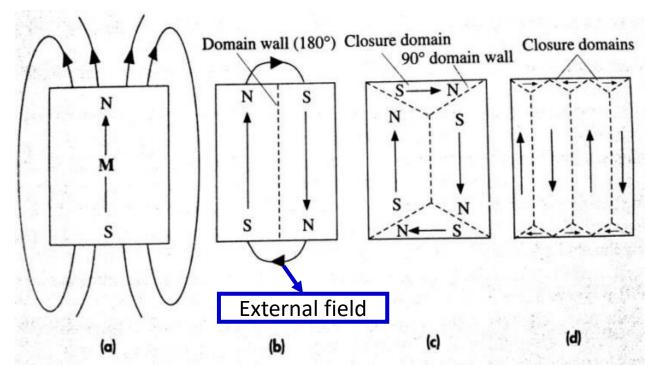


Figure:- creation of magnetic domain

Domain Structure / Domain Theory of Ferromagnetism



- The magnetostatic energy can be further reduced by eliminating these external field lines by closing the ends with sideway domains (Closure domain) with magnetization at 90°.
- Forming domains reduces magnetostatic energy but potential energy in the walls increases due to addition of walls.
- Thus, creation of magnetic domains continues until the magnetostatic energy reduction by addition of domains is balanced by increase in potential energy in the walls due to addition of walls.
- In this condition, there is minimum potential energy with no net magnetization.

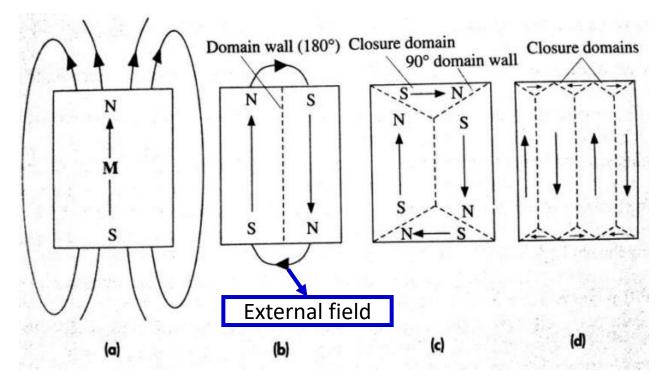


Figure:- creation of magnetic domain

Domain Structure / Domain Theory of Ferromagnetism



- When we apply an external magnetic field to the crystal with domains as in the figure, the magnetization of crystal along the field occurs, in principle, by the growth of domains with magnetization along the field 'H'.
- i.e. the wall between domain A and domain B migrates towards right enlarging domain A and shrinking domain B which is caused by spins in the wall, and also spins in region B adjacent to the wall.

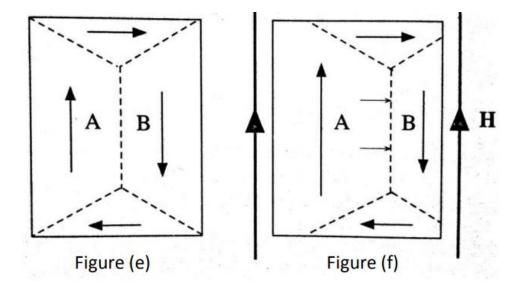
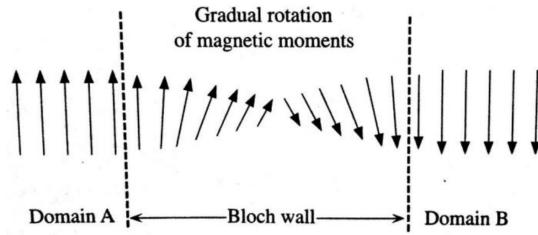


Figure:- Domain Wall Motion

- Gradually rotated by the applied field in the direction of field. The magnetization process involves the motions of wall which is called Domain Wall Motion.
- The Domain Wall is not simply one atomic spacing wide.



Losses in magnetic materials



- When magnetic materials are subjected to changing magnetic field (flux), two types of losses occur which are:
 - Eddy current loss
 - Hysteresis loss

• Eddy Current Loss:

- Eddy currents are loops of electric currents induced within materials by a changing magnetic field because of Faraday's laws of induction.
- Eddy current flow in closed path perpendicular to the applied magnetic field.
- Eddy current creates its own magnetic field that oppose the magnetic field that created it, following Lenz' Law.
- Eddy currents generate resistive losses that transform some form of energy to heat which reduces
 efficiency of iron core of transformers and electric motors and other devices that use changing
 magnetic field.
- Eddy currents are minimized in these devices by selecting magnetic core materials that have low electrical conductivity (e.g. Ferrites) or by using thin sheet of core forming laminations.

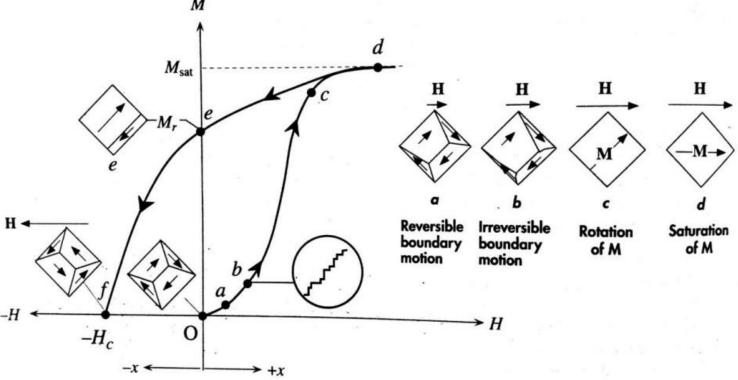
Hysteresis Loop and loss



- The complete M versus H curve obtained by changing magnetizing field (H) from positive x to negative x for corresponding values of magnetization is a closed loop called as hysteresis loop.
- When an external magnetic field 'H' is applied to an unmagnetized iron sample,
 - at start there is very small net magnetization

• as the value of **'H'** is increased, the domain motion extend to larger shapes encountering various obstacles such as crystal imperfections, impurities and so on.

- Sudden changes in magnetization induce eddy currents (circulating current) that dissipate energy via joule heating (I^2R) called eddy current losses.
- As we go on increasing the external magnetic field, eventually a single Hadomain is created and further increase in field, causes M to align in the direction of H and then the sample H reaches saturation magnetization M_{sat}



Hysteresis Loop and loss



- Now, if the magnetizing force is reduced then magnetization of iron sample decreases
- Even when the magnetizing force is reduced to zero, induced magnetization does not reduced to zero

• Some residual remains called as **residual magnetization** (M_r) , also called as **retentivity**. This is useful in a magnetic memory device.

- If magnetizing field is applied in the reverse direction, magnetization of the sample decreases and at a certain value, magnetization 'M' becomes zero.
- The magnetizing field required to totally demagnetize the sample is called coercive field H_c , also called as coercivity.

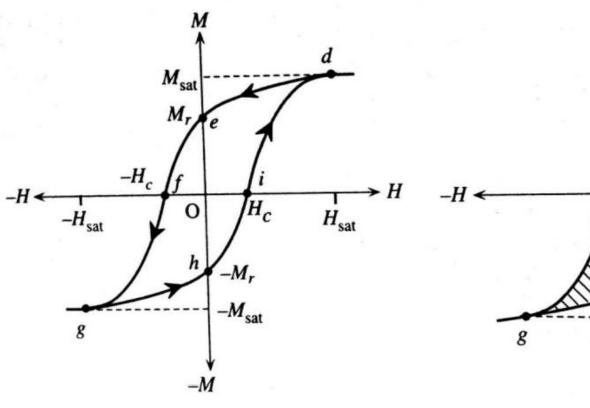


Figure (a): M - H hysteresis curve

Figure (b): corresponding B - H hysteresis curve

 $-B_{\rm sat}$

 $B_{\rm sat}$

Hysteresis Loop and loss



- If the demagnetization is further **increased in reverse direction**, the process from point e will be similar to that when **magnetizing the sample in reverse direction**.
- Point g represents saturation magnetization $-M_{sat}$ in reverse direction.
- Decreasing the magnetizing field from $-H_{sat}$ to zero again leaves residual magnetization.
- To eliminate this we need to apply magnetizing field in reverse direction.
- The energy dissipated during magnetization & demagnetization process is given by the area of hysteresis loop.

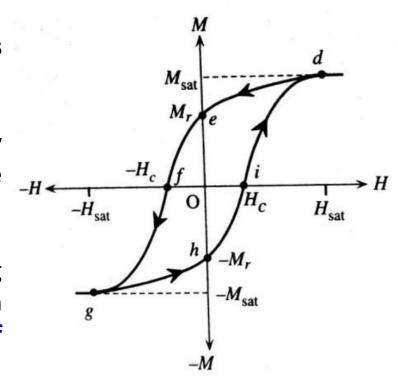


Figure (a): M - H hysteresis curve

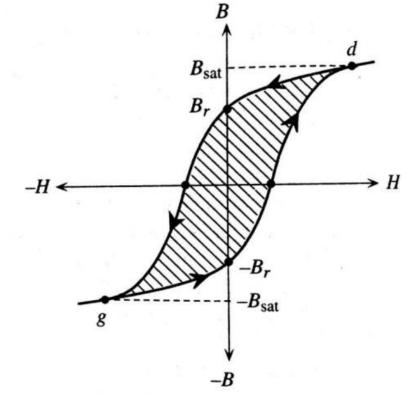


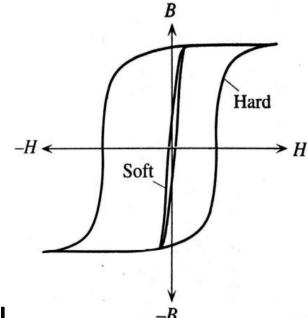
Figure (b): corresponding B - H hysteresis curve

Soft Magnetic material



That magnetic material which can be easily magnetized and demagnetized is called soft magnetic material.

- These materials have
 - very low value of coercivity,
 - very large saturation magnetization (M_{sat})
 - small hysteresis area.
 - Ideally zero coercivity,
 - zero retentivity
 - very large saturation magnetization.
- Their B-H curve has small area, so the power loss per unit cycle is small.
- Thus, suitable for applications where repeated cycles of magnetization and demagnetization are involved.
- Examples: electric motors, transformers, inductor having varying field, electromagnetic relay.

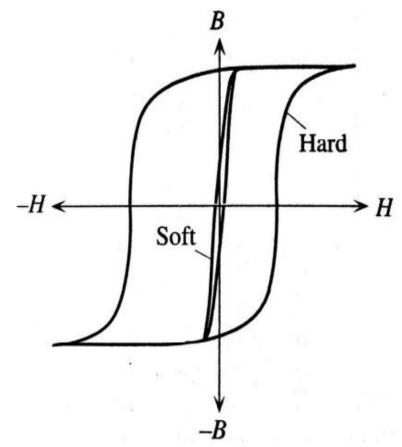


Hard Magnetic materials



 That magnetic material which is difficult to magnetized and demagnetized is called hard magnetic material.

- These materials have
 - very large coercivity,
 - very large saturation magnetization (M_{sat})
 - large hysteresis area.
- The coercive field for hard magnetic materials is millions of times greater than those for soft magnetic materials.
- Their B-H curve is broad and almost rectangular in shape,
 so the power loss per unit cycle is high.
- They are useful for making permanent magnets and in magnetic storage of digital data.



Fe – Si alloys, Ni –Fe alloys



- Pure iron (Fe) despite being soft magnetic material is not normally used as magnetic material because its conductivity allows large eddy currents to be induced under varying fields.
- By adding (2 4%) of Silicon to Iron, Silicon Steel is obtained which is still soft magnetic material with increased resistivity but reduced eddy current loss.
- Mostly **used in manufacture of transformers and other electrical machineries** for alternating current applications.
- Similarly, Nickel Iron alloys with composition around 77% Ni and 23% Fe constitute a soft magnetic material with low coercivity, low hysteresis loss and high initial and maximum relative permeabilities.
 - High initial relative permeability useful in low magnetic field applications that are typically found in high frequency works in electronics like audio and wide band transformers. More applications on: sensitive relays, current transformers, magnetic recording heads, magnetic shielding etc.
- Alloying Iron with Nickel increases resistivity and hence reduces the eddy current losses in the machinery.
- The domain wall motions are easy in Nickel composition resulting smaller hysteresis losses in the material.
- There are number of commercial Ni Fe alloys whose application depends on exact composition (which may also have a few percentages of Mo, Cr, Cu, etc) and method of preparation (e.g. mechanical rolling).

Ferrites for high frequency transformers



- Ferrites are ferromagnetic materials which are typically oxides of mixed transition metals, one of which is iron.
- Ferrites are ferromagnetic materials, normally insulators, so do not suffer from eddy current losses (very high resistance allows only very small current and hence very small or no losses) → thus suitable for high frequency applications
- Ferrites can have **high initial permeabilities and low losses**, but they **do not possess large saturation magnetization** like that in ferromagnets.
- There are many types of ferrites available depending on the application, tolerable losses and required upper frequency of operation.
 - Manganese Zinc Ferrites have high initial relative permeability of 2000 but are only useful up to 1 MHz.
 - Nickel Zinc Ferrites have lower initial relative permeability of 200 but they can be used up to a frequency of 200 MHz.
 - <u>Garnets</u> are ferrimagnetic materials, used at **highest frequencies** covering the microwave range $(1 300 \, \text{GHz})$. Yttrium Iron Garnet YIG $(Y_3 \, Fe_5 \, O_{12})$
 - one of the simplest garnets with very low hysteresis loss at microwave frequencies.
 - Have excellent dielectric properties with high resistivities and consequently low losses.
 - Main disadvantage of garnets is the low saturation magnetization and low Curie temperature.
- The initial relative permeability in the high frequency region decreases with increase in frequency.

Square Loop Magnetic Materials



- Materials having very high coercivities are termed as square loop magnetic materials because
 of the B-H loop imitating the square shape.
- To store any information in the form of digitalized data, these materials are most suited.
- Uses different patterns of magnetization in a magnetizable material to store data and is a form of non –volatile memory
- The magnetic surface is conceptually divided into many small sub-mm sized magnetic regions, referred as magnetic domains. Information is stored on these domains.
- Have high (BH)max values, used in stepper motors, servomotors, gyroscope
- The only drawback of these materials are lower Curie temperature compared to other magnetic materials.



Selected soft magnetic materials (E_h is hysteresis loss i.e. energy dissipated per unit volume per cycle, J/ m^3 at $B_m=1\ T$)

Magnetic Material	μ _ο Η _ο , Τ	B _{sat,} T	B _r , T	μ _{ri}	μ_{rmax}	E _h , Jm ⁻³	Applications
Ideal soft		, and the					
iron	0	Large	0	Large	Large	0	Transformer cores, inductors, magnetic recording heads, re-
				150	4-4		lays, electromagnet cores, machines
Iron (commercial grade, 0.2%	<10 ⁻⁴	2.2	<0.1	150	10 ⁴	250	Due to large eddy current losses used only in some elect-
Silicon Iron (2-4% Si)	<10 ⁻⁴	2	0.5-1	1000	10000 - 400000	30 - 100	magnets and relays Wide range of ac machinery

6/20/2023 MK/ EEM 25



Selected soft magnetic materials (E_h is hysteresis loss i.e. energy dissipated per unit volume per cycle, J/ m^3 at $B_m=1\ T$)

Supermalloy (79%Ni, 15%Fe, 5%Mo, 0.5%Mn)	2 × 10 ⁻⁷	0.7– 0.8	' <0.1	10 ⁵	10 ⁶	<0.5	High permeability low loss electrical devices, e.g. speciality transformers, magnetic amplifier
Permalloy (78.5%Ni, 21.5%Fe)	5 × 10 ⁻⁶	0.86	<0.1	8000	10 ⁵	<0.1	Low loss electrical devices, audio transformers, HF transformers, recording heads, filters
Glassy metals (Fe – Si – B)	2 × 10 ⁻⁶	1.6	<10 ⁻⁶	<u>-</u> -	10 ⁵	20	Low loss transfor- mer cores
Ferrites Mn- Zn territe	10 ⁻⁵	0.4	<0.01	2000	5000	<0.01	HF low loss applications. HF transformers, recording heads, inductors (E and U cores)

6/20/2023 MK/ EEM 26



Néel temperature (T_N) and paramagnetic Curie temperature (θ_c) for some antiferrimagnetic materials

Material	T _N ,K	θ _c , K
MnF ₂	72	113
MnO_2	84	316
MnO	122	610
MnS	165	528
FeO	198	570
NiF ₂	73	116
CoO	292	280

Table 5.5 Susceptibility of some diamagnetic materials

Material	$\chi = \mu_r - 1, x 10^{-5}$	Material	$\chi = \mu_r - 1, x 10^{-5}$
Al ₂ O ₃	-0.5	Cu	-0.9
BaCl,	-2.0	Au Au	-3.6
NaCl	-1.2	Ge Ge	
Diamond	-2.1	Si	-0.3
Graphite	-12	Se	-1.7



Occurrence of permanent atomic magnetic dipoles and interaction between neighboring dipoles

Type of material	Permanent dipoles	Interaction between neighboring dipoles
Paramagnetic	Yes	Negligible
Ferromagnetic	Yes	Parallel orientation
Antiferrimagnetic	Yes	Antiparallel orientation of equal moments
Ferrimagnetic	Yes	Antiparallel orientation of unequal moments

Table 5.3 Susceptibilities of some paramagnetic materials at 300K

Substance	$\chi = \mu_r - 1, x 10^{-3}$	Substance	$\chi = \mu_r - 1, x 10^{-3}$	
CrCl ₂	1.5	Fe ₂ O ₃	1.4	
Cr ₂ O ₃	computered the 11.7 of Martin the	Fe ₂ (SO ₄) ₃	2.2	
CoO	5.8	FeCl ₂	3.7 had at 3.7	
CoSO ₄	2.0	FeSO ₄	2.8	
MnSO ₄	3.6	NiSO ₄	1.2	