

Line Spectrum Estimation - Methods

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Pisarenko Harmonic Decomposition (PHD)

- $x(n)$ is assumed to be a sum of p complex exponentials (uniformly distributed phase) in white noise and p is known

$$x(n) = \sum_{i=1}^p A_i e^{jn\omega_i} + w(n).$$

- Corresponding autocorrelation coefficients are

$$r_x(k) = \sum_{i=1}^p P_i e^{jk\omega_i} + \sigma_w^2 \delta(k), \quad k = 0, \dots, M-1,$$

where $P_i = |A_i|^2$ is the power in the i -th component

- Corresponding autocorrelation matrix \mathbf{R}_x $((p+1) \times (p+1))$ is either known or can be estimated

$$\mathbf{R}_x = \mathbf{R}_{\text{sig}} + \mathbf{R}_{\text{noise}} = \sum_{i=1}^p P_i \mathbf{e}_i \mathbf{e}_i^H + \sigma_w^2 \mathbf{I},$$

Pisarenko Harmonic Decomposition (PHD)

- Dimension of noise subspace is one and is spanned by the eigenvector \mathbf{v}_{min} corresponding to λ_{min}
- From orthogonality of signal subspace and noise eigenvector space

$$\mathbf{e}_i^H \mathbf{v}_{min} = \sum_{k=0}^p v_{min}(k) e^{-jk\omega} = 0; \quad i = 1, \dots, p.$$

where

$$\mathbf{e}_i = \left[1, e^{j\omega_i}, e^{j2\omega_i}, \dots, e^{jp\omega_i} \right]^T$$

Pisarenko Harmonic Decomposition (PHD)

- DTFT of the noise vector

$$V_{min}(e^{j\omega}) = \sum_{k=0}^p v_{min}(k) e^{-jk\omega}$$

- This being zero at each of the complex exponential frequencies $\omega_i, i = 1, \dots, p$.
- Can be considered as an **eigenfilter** that has p zeros on the unit circle

$$V_{min}(z) = \sum_{k=0}^p v_{min}(k) z^{-k} = \prod_{k=1}^p \left(1 - e^{j\omega_k} z^{-1}\right).$$

and the roots of this provide the frequencies of the complex exponentials

Pisarenko Harmonic Decomposition (PHD)

- An alternative approach is to search for peak locations of the frequency estimation function (“pseudospectrum”)

$$\hat{P}_{PHD}(e^{j\omega}) = \frac{1}{|\mathbf{e}^H \mathbf{v}_{min}|^2}.$$

Pisarenko Harmonic Decomposition (PHD)

- Having ω_i need to estimate corresponding power P_i
- Eigenvectors of \mathbf{R}_x are normalized, i.e., $\mathbf{v}_i^H \mathbf{v}_i = 1$
- For $i = 1, \dots, p$, we have

$$\begin{aligned}\mathbf{R}_x \mathbf{v}_i &= \lambda_i \mathbf{v}_i \\ \mathbf{v}_i^H \mathbf{R}_x \mathbf{v}_i &= \lambda_i \mathbf{v}_i^H \mathbf{v}_i = \lambda_i.\end{aligned}$$

- Using the signal and noise decomposition of \mathbf{R}_x , we have

$$\mathbf{v}_i^H \mathbf{R}_x \mathbf{v}_i = \mathbf{v}_i^H \left\{ \sum_{k=1}^p P_k \mathbf{e}_k \mathbf{e}_k^H + \sigma_w^2 \mathbf{I} \right\} \mathbf{v}_i,$$

which

$$\Rightarrow \sum_{k=1}^p P_k \left| \mathbf{e}_k^H \mathbf{v}_i \right|^2 = \lambda_i - \sigma_w^2, \quad i = 1, \dots, p.$$

Pisarenko Harmonic Decomposition (PHD)

- We have $|\mathbf{e}_k^H \mathbf{v}_i|^2$ corresponding to the squared magnitude of the DTFT of the signal subspace eigenvector \mathbf{v}_i evaluated at frequency ω_k ,

$$|\mathbf{e}_k^H \mathbf{v}_i|^2 = |V_i(e^{j\omega_k})|^2.$$

- Using this we have

$$\sum_{k=1}^p P_k |V_i(e^{j\omega_k})|^2 = \lambda_i - \sigma_w^2, \quad i = 1, \dots, p.$$

- Which can be solved for powers P_k using p linear equations, as shown in matrix form

$$\begin{bmatrix} |V_1(e^{j\omega_1})|^2 & |V_1(e^{j\omega_2})|^2 & \dots & |V_1(e^{j\omega_p})|^2 \\ \vdots & \vdots & \vdots & \vdots \\ |V_p(e^{j\omega_1})|^2 & |V_p(e^{j\omega_2})|^2 & \dots & |V_p(e^{j\omega_p})|^2 \end{bmatrix} \begin{bmatrix} P_1 \\ \vdots \\ P_p \end{bmatrix} = \begin{bmatrix} \lambda_1 - \sigma_w^2 \\ \vdots \\ \lambda_p - \sigma_w^2 \end{bmatrix}.$$

MUSIC - Multiple Signal Classification

- Improvement over PHD for frequency estimation
- In PHD - projection of signal vectors onto a single noise eigenvector
- MUSIC - projection of signal vectors onto the entire noise subspace
- Signal $x(n)$ is a mixture of p complex exponentials in white noise with variance σ_w^2 and has a $M \times M$ autocorrelation matrix \mathbf{R}_x with $M > p + 1$
 - in contrast to PHD where $M = p + 1$

MUSIC - Multiple Signal Classification

- We can divide the eigenvectors of \mathbf{R}_x into two groups;
 - p signal EVecs corresponding to p largest EVals
 - $M - p$ noise EVecs that have an EVals of σ_w^2
- $M - p$ smallest EVals are approximately equal to σ_w^2

$$\hat{\sigma}_w^2 = \frac{1}{M - p} \sum_{k=p+1}^M \lambda_k.$$

MUSIC - Multiple Signal Classification

- Taking the DTFT of the noise subspace eigenvectors, the eigenfilters can be obtained as

$$V_i(z) = \sum_{k=0}^{M-1} v_i(k)z^{-k}, \quad i = p + 1, \dots, M.$$

- Has $M - 1$ roots with p of them lying on the unit circle
- The location of those on the unit circle correspond to the frequencies of the complex exponentials.
- The pseudospectrum (eigen spectrum) of the signal

$$\left| V_i(e^{j\omega}) \right|^2 = \frac{1}{\left| \sum_i^{M-1} v_i(k)e^{-jk\omega} \right|^2}, \quad (1)$$

has peaks at the ω_j corresponding to the complex exponentials.

- Uses only one of the noise eigenvectors \mathbf{v}_j .

MUSIC - Multiple Signal Classification

- Issues with using single noise eigenvector
 - $M - p - 1$ zeros corresponding to noise might lie close to unit circle
 - p zeros corresponding to signal might not lie exactly on unit circle
- This leads to spurious peaks
- Spurious peaks can be reduced by averaging

$$\hat{P}_{MU}(e^{j\omega}) = \frac{1}{\sum_{i=p+1}^M |\mathbf{e}^H \mathbf{v}_i|^2}.$$

- Location of the p largest peaks in $\hat{P}_{MU}(e^{j\omega})$ correspond to the frequencies of the complex exponentials
- Corresponding power P_i can be estimated as in PHD method

MUSIC - Multiple Signal Classification

Alternate view

- Consider the projection matrix on to the noise space

$$\mathbf{P}_{\text{noise}} = \mathbf{V}_{\text{noise}} \mathbf{V}_{\text{noise}}^H$$

- The denominator term can be considered as

$$\mathbf{e}^H \mathbf{P}_{\text{noise}} \mathbf{e} = \mathbf{e}^H \mathbf{V}_{\text{noise}} \mathbf{V}_{\text{noise}}^H \mathbf{e}$$

- This goes to zero for \mathbf{e}_i that are orthogonal to the noise subspace
- The MUSIC pseudospectrum can be represented as

$$\hat{P}_{MU}(e^{j\omega}) = \frac{1}{\mathbf{e}^H \mathbf{V}_{\text{noise}} \mathbf{V}_{\text{noise}}^H \mathbf{e}}.$$

Root MUSIC

- Obtain the roots of an equivalent polynomial (corresponding to the MUSIC method)

$$D(z) = \sum_{i=p+1}^M V_i(z) V_i^*(1/z^*),$$

- p roots that are closest to the unit circle correspond to the complex exponentials

Eigenvector Method

- Similar to MUSIC, differs only by a constant

$$\hat{P}_{EV}(e^{j\omega}) = \frac{\sigma_w^2}{\sum_{i=p+1}^M |\mathbf{e}^H \mathbf{v}_i|^2} = \frac{1}{\frac{1}{\lambda_i} \sum_{i=p+1}^M |\mathbf{e}^H \mathbf{v}_i|^2},$$

where $\lambda_i = \sigma_w^2$ are the eigenvalues corresponding to the eigenvectors $\mathbf{v}_i, i = p + 1, \dots, M$

- Differs from MUSIC: in practise the estimated small λ_i s all need not be equal

Minimum-norm Algorithm

- Choose a **single noise vector** \mathbf{a} with minimum norm to define the pseduospectrum
- Compare to PHD or MUSIC
 - PHD uses single noise eigenvector
 - MUSIC uses all noise eigenvectors

Motivation for choice of \mathbf{a}

- \mathbf{a} lies in the noise subspace - ensures p roots of $A(z)$ lie on the unit circle
- \mathbf{a} has minimum norm - ensures that spurious roots of $A(z)$ lie inside the unit circle, i.e., $|z_k| < 1$. i.e., $A(z)$ is a minimum-phase polynomial. Further these roots are approximately uniformly distributed around the unit-circle in sectors where the signal roots are not present
- the first element of \mathbf{a} is unity - to ensure that the minimum norm solution is not the zero vector

Minimum-norm Algorithm

- The pseudospectrum is defined as

$$\hat{P}_{MN}(e^{j\omega}) = \frac{1}{|\mathbf{e}^H \mathbf{a}|^2}.$$

where \mathbf{a} is constrained to lie in the noise subspace and \mathbf{e} is a complex exponential

- The peak locations of this function correspond to the frequencies of the complex exponentials
- Considering the z-domain polynomial corresponding to \mathbf{a}

$$A(z) = \sum_{k=0}^{M-1} a(k)z^{-k} = \underbrace{\prod_{k=1}^p (1 - e^{j\omega_k} z^{-1})}_{\text{roots on unit-circle}} \underbrace{\prod_{k=p+1}^{M-1} (1 - z_k z^{-1})}_{\text{roots not on unit-circle}}$$

- Goal: determine the noise subspace vector \mathbf{a} that minimizes the effect of the spurious zeros

Minimum-norm Algorithm

- The noise subspace vector **a** can be obtained by imposing three constraints
 - C1 **a** lies in the noise subspace
 - C2 **a** has minimum norm
 - C3 First element of **a** is unity
- C1 can be expressed using the noise projection matrix, $\mathbf{P}_n = \mathbf{V}_{\text{noise}} \mathbf{V}_{\text{noise}}^H$, which projects an arbitrary vector **y** onto the noise subspace

$$\mathbf{a} = \mathbf{P}_n \mathbf{y}.$$

- C3 can be represented using

$$\mathbf{a}^H \mathbf{u}_1 = 1$$

where $\mathbf{u}_1 = [1, 0, \dots, 0]^T$.

Minimum-norm Algorithm

- Combining C1 and C3, we have

$$\mathbf{y}^H(\mathbf{P}_n^H \mathbf{u}_1) = 1.$$

- Objective is to minimize norm of \mathbf{a}

$$\begin{aligned}\|\mathbf{a}\|^2 &= \|\mathbf{P}_n \mathbf{y}\|^2 \\ &= \mathbf{y}^H \left(\mathbf{P}_n^H \mathbf{P}_n \right) \mathbf{y} \\ &= \mathbf{y}^H \mathbf{P}_n \mathbf{y} \quad (\because \mathbf{P}_n \text{ is Hermitian, idempotent, } \mathbf{P}_n^2 = \mathbf{P}_n).\end{aligned}$$

- Minimizing the norm of \mathbf{a} can be formulated as a constrained optimization problem

$$\min \mathbf{y}^H \mathbf{P}_n \mathbf{y} \quad \text{subject to} \quad \mathbf{y}^H \left(\mathbf{P}_n^H \mathbf{u}_1 \right) = 1.$$

and the solution \mathbf{y} can be used to obtain \mathbf{a}

Gradient of a Scalar Quantity

- Let Q be a scalar quantity depending on the real vector \mathbf{a} . The gradient is defined as

$$\nabla_{\mathbf{a}} Q \stackrel{\text{def}}{=} \begin{bmatrix} \frac{\partial Q}{\partial a_1} \\ \frac{\partial Q}{\partial a_2} \\ \vdots \\ \frac{\partial Q}{\partial a_N} \end{bmatrix}$$

Table : Gradient relation for real vectors and symmetric \mathbf{B}

Quantity Q	$\mathbf{a}^T \mathbf{b}$	$\mathbf{b}^T \mathbf{a}$	$\mathbf{a}^T \mathbf{B} \mathbf{a}$
Gradient $\nabla_{\mathbf{a}} Q$	\mathbf{b}	\mathbf{b}	$2\mathbf{B}\mathbf{a}$

Gradient of a Scalar Quantity

- Let \mathcal{Q} be a scalar quantity depending on the complex vector $\mathbf{a} = \mathbf{a}_r + j\mathbf{a}_i$. The gradient is defined as

$$\nabla_{\mathbf{a}} \mathcal{Q} \stackrel{\text{def}}{=} \frac{1}{2}(\nabla_{\mathbf{a}_r} \mathcal{Q} - j\nabla_{\mathbf{a}_i} \mathcal{Q})$$

and

$$\nabla_{\mathbf{a}^*} \mathcal{Q} \stackrel{\text{def}}{=} \frac{1}{2}(\nabla_{\mathbf{a}_r} \mathcal{Q} + j\nabla_{\mathbf{a}_i} \mathcal{Q})$$

Table : Gradient relation for complex vectors and Hermitian \mathbf{B}

Quantity \mathcal{Q}	$\mathbf{a}^H \mathbf{b}$	$\mathbf{b}^H \mathbf{a}$	$\mathbf{a}^H \mathbf{B} \mathbf{a}$
Gradient $\nabla_{\mathbf{a}} \mathcal{Q}$	0	\mathbf{b}^*	$(\mathbf{B} \mathbf{a})^*$
Gradient $\nabla_{\mathbf{a}^*} \mathcal{Q}$	\mathbf{b}	0	$\mathbf{B} \mathbf{a}$

Minimum-norm Algorithm

- Solution to the constrained optimization problem can be obtained using a Lagrange multiplier λ and minimizing

$$Q(\mathbf{y}, \lambda) = \mathbf{y}^H \mathbf{P}_n \mathbf{y} + \lambda(1 - \mathbf{y}^H (\mathbf{P}_n^H \mathbf{u}_1)).$$

- Setting the gradient of $Q(\mathbf{y}, \lambda)$ w.r.t \mathbf{y}^* equal to zero

$$\begin{aligned}\nabla_{\mathbf{y}^*} Q(\mathbf{y}, \lambda) &= \mathbf{P}_n \mathbf{y} - \lambda (\mathbf{P}_n^H \mathbf{u}_1) = 0 \\ \implies \mathbf{y} &= \lambda \mathbf{P}_n^{-1} (\mathbf{P}_n^H \mathbf{u}_1) = \lambda \mathbf{u}_1.\end{aligned}$$

- λ can be obtained by setting $\nabla_{\lambda} Q(\mathbf{y}, \lambda)$ equal to zero

$$1 - \mathbf{y}^H (\mathbf{P}_n^H \mathbf{u}_1) = 0 \implies \lambda = \frac{1}{\mathbf{u}_1^H \mathbf{P}_n \mathbf{u}_1}.$$

- Hence the minimum-norm solution is

$$\mathbf{a} = \mathbf{P}_n \mathbf{y} = \lambda \mathbf{P}_n \mathbf{u}_1 = \frac{\mathbf{P}_n \mathbf{u}_1}{\mathbf{u}_1^H \mathbf{P}_n \mathbf{u}_1} = \frac{(\mathbf{V}_n \mathbf{V}_n^H) \mathbf{u}_1}{\mathbf{u}_1^H (\mathbf{V}_n \mathbf{V}_n^H) \mathbf{u}_1}.$$

ESPRIT Method

ES_timation of S_ignal P_arameters by R_otational I_nvariance T_echnique

- Exploits invariance principle that exists for discrete sequences
- Consider the multiple complex signal model

$$x(n) = \sum_{i=1}^p A_i e^{jn\omega_i} + w(n)$$

and considering $n = 0, \dots, M-1$, we have

$$\mathbf{x} = \sum_{i=1}^p A_i \mathbf{e}_i + \mathbf{w},$$

where $\mathbf{e}_i = [1 \quad e^{j\omega_i} \quad \dots \quad e^{j(M-1)\omega_i}]^T$.

ESPRIT Method

- Consider \mathbf{x}' a translated version of \mathbf{x} i.e.,

$$\begin{aligned}\mathbf{x} &= [x(0) \quad x(1) \quad \cdots \quad x(M-1)] \\ \mathbf{x}' &= [x(1) \quad x(2) \quad \cdots \quad x(M)] \\ \Rightarrow \mathbf{x}' &= \sum_{i=1}^p A_i \mathbf{e}'_i + \mathbf{w}',\end{aligned}$$

where

$$\mathbf{e}'_i = \begin{bmatrix} e^{j\omega_i} \\ e^{j2\omega_i} \\ \vdots \\ e^{j(N)\omega_i} \end{bmatrix} = e^{j\omega_i} \mathbf{e}.$$

- Translational invariance between the two data sets leads to a rotational invariance between the two corresponding signal subspaces

ESPRIT Method

- The cross-correlation matrix for the vectors \mathbf{x} and \mathbf{x}' is

$$\mathbf{R}_{\mathbf{x}\mathbf{x}'} = \sum_{i=1}^p P_i e^{-j\omega_i} \mathbf{e}_i \mathbf{e}_i^H + \sigma_w^2 \mathbf{D}_{-1}$$

or

$$\mathbf{R}_{\mathbf{x}\mathbf{x}'} = \mathbf{E} \mathbf{P} \mathbf{\Phi}^H \mathbf{E}^H + \sigma_w^2 \mathbf{D}_{-1}$$

where

$$\mathbf{\Phi} = \begin{bmatrix} e^{j\omega_1} & 0 & \dots & 0 \\ 0 & e^{j\omega_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e^{j\omega_p} \end{bmatrix}, \mathbf{D}_{-1} = \begin{bmatrix} 0 & 0 & \dots & 0 \\ -1 & 0 & \dots & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

- Obtaining $\mathbf{\Phi}$ will give us the required frequencies

ESPRIT Method

- ESPRIT begins by forming the matrices

$$\mathbf{R}_S \stackrel{\text{def}}{=} \mathbf{R}_X - \sigma_w^2 \mathbf{I} = \mathbf{E} \mathbf{P} \mathbf{E}^H$$

and

$$\mathbf{R}_{SS'} \stackrel{\text{def}}{=} \mathbf{R}_{XX'} - \sigma_w^2 \mathbf{D}_{-1} = \mathbf{E} \mathbf{P} \Phi^H \mathbf{E}^H$$

- As in MUSIC σ_w^2 the smallest eigenvalue of \mathbf{R}_X can be computed and used in the subtraction
- The values $e^{j\omega_k}$ are the eigenvalues of the generalized eigenvalue problem

$$\mathbf{R}_S \dot{\mathbf{e}} = \dot{\lambda} \mathbf{R}_{SS'} \dot{\mathbf{e}}$$

ESPRIT Method

- To show $e^{j\omega_k}$ are eigenvalues of $\mathbf{R}_s \dot{\mathbf{e}} = \dot{\lambda} \mathbf{R}_{ss'} \dot{\mathbf{e}}$

$$\mathbf{R}_s \dot{\mathbf{e}} - \dot{\lambda} \mathbf{R}_{ss'} \dot{\mathbf{e}} = \mathbf{E} \mathbf{P} (\mathbf{I} - \dot{\lambda} \Phi) \mathbf{E}^H \dot{\mathbf{e}}$$

$$= \mathbf{E} \mathbf{P} \begin{bmatrix} 1 - \dot{\lambda} e^{-j\omega_1} & 0 & \dots & 0 \\ 0 & 1 - \dot{\lambda} e^{-j\omega_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 - \dot{\lambda} e^{-j\omega_p} \end{bmatrix} \mathbf{E}^H \dot{\mathbf{e}}$$

- Since $\dot{\lambda} = e^{j\omega_k}$ reduces the rank of the matrix, they are the generalized eigenvalues

ESPRIT Method

- Let us consider the p complex exponential signal matrix \mathbf{E}
- We can form two matrices \mathbf{E}_1 and \mathbf{E}_2 that are related by a rotation

$$\mathbf{E}_1 = [\mathbf{I}_{M-1} \quad \mathbf{0}] \mathbf{E} \quad (M-1 \times p)$$

$$\mathbf{E}_2 = [\mathbf{0} \quad \mathbf{I}_{M-1}] \mathbf{E} \quad (M-1 \times p)$$

where \mathbf{I}_{M-1} is $(M-1) \times (M-1)$ identity matrix

- We have $\mathbf{E}_2 = \mathbf{E}_1 \mathbf{D}$ where

$$\mathbf{D} = \begin{bmatrix} e^{j\omega_1} & 0 & \dots & 0 \\ 0 & e^{j\omega_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e^{j\omega_p} \end{bmatrix}$$

is a unitary matrix and causes a rotation

ESPRIT Method

- Now let's consider the signal eigenvectors \mathbf{V}_S and

$$\mathbf{V}_{S1} = [\mathbf{I}_{M-1} \quad \mathbf{0}] \mathbf{V}_S \quad \text{and} \quad \mathbf{V}_{S2} = [\mathbf{I}_{M-1} \quad \mathbf{0}] \mathbf{V}_S$$

- Using the autocorrelation matrix \mathbf{R}_x ,

$$\mathbf{R}_x \mathbf{V}_S = \mathbf{V}_S \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_p \end{bmatrix} = \mathbf{E} \mathbf{P} \mathbf{E}^H \mathbf{V}_S + \sigma_w^2 \mathbf{V}_S$$

- Accordingly we have, $\mathbf{V}_S = \mathbf{E}(\mathbf{P} \mathbf{E}^H \mathbf{V}_S \mathbf{\Lambda}^{-1})$ where $\mathbf{\Lambda} = \text{diag}(\lambda_1 - \sigma_w^2, \dots, \lambda_p - \sigma_w^2)$
- We have $\mathbf{V}_S = \mathbf{E} \mathbf{C}$, where $\mathbf{C} = \mathbf{P} \mathbf{E}^H \mathbf{V}_S \mathbf{\Lambda}^{-1}$ is non-singular

ESPRIT Method

- The term $\mathbf{V}_S = \mathbf{E}\mathbf{C}$ indicates the relation between the signal space \mathbf{E} and signal eigenvectors \mathbf{V}_S
- From the earlier partitioning, and using the above relation we have

$$\mathbf{V}_{S2} = \mathbf{E}_2\mathbf{C}$$

- Using the rotational relation

$$\mathbf{V}_{S2} = \mathbf{E}_2\mathbf{C} = \mathbf{E}_1\mathbf{D}\mathbf{C} = \mathbf{V}_{S1}\mathbf{C}^{-1}\mathbf{D}\mathbf{C} = \mathbf{V}_{S1}\boldsymbol{\Phi}.$$

- Since \mathbf{V}_{S1} and \mathbf{V}_{S2} are known, we can solve for $\boldsymbol{\Phi}$ using least squares

$$\boldsymbol{\Phi} = (\mathbf{V}_{S1}^H \mathbf{V}_{S1})^{-1} \mathbf{V}_{S1}^H \mathbf{V}_{S2}$$

- From $\mathbf{C}^{-1}\mathbf{D}\mathbf{C} = \boldsymbol{\Phi}$, it can be seen that \mathbf{D} and $\boldsymbol{\Phi}$ have the same eigen values

ESPRIT Method

- After estimating Φ , its eigenvalues can be obtained
- These are also the eigenvalues of \mathbf{D} , and hence $\{\omega_k\}_{k=1}^p$ can be found from

$$\arg(\gamma_k)$$

where $\{\gamma_k\}_{k=1}^p$ are eigenvalues of the estimated Φ

- Here Φ is obtained using least squares (LS) approach
- LS solves for \mathbf{X} from $\mathbf{AX} \approx \mathbf{B}$ or

$$\min \|\mathbf{AX} - \mathbf{B}\|^2$$

or

$$\min \|\Delta \mathbf{B}\|^2 \text{ subject to } \mathbf{AX} = \mathbf{B} + \Delta \mathbf{B}$$

- LS solution $\mathbf{X} = (\mathbf{A}^H \mathbf{A})^{-1} \mathbf{A}^H \mathbf{B} = \mathbf{A}^\dagger \mathbf{B}$

ESPRIT Method using Total Least Squares (TLS)

- Total least squares (TLS) error both in **A** and **B**
- TLS solves for **X** from

$$\min \| \mathbf{AX} - \mathbf{B} \|^2$$

or

$$\min \| \Delta \mathbf{A} \Delta \mathbf{B} \|^2 \text{ subject to } (\mathbf{A} + \Delta \mathbf{A})\mathbf{X} = \mathbf{B} + \Delta \mathbf{B}$$

- This can be solved using Singular Value Decomposition (SVD)

Singular Value Decomposition (SVD)

- SVD provides better numerical precision while computing eigenvalues and eigenvectors
- Uses the data \mathbf{X} instead of the autocorrelation matrix \mathbf{R}_x

Singular Value Decomposition (SVD)

- SVD theorem states that any $K \times N$ matrix \mathbf{X} can be decomposed as

$$\mathbf{X} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^H$$

where \mathbf{U} is the $K \times K$ unitary matrix of *left singular vectors*

$$\mathbf{U} = [\mathbf{u}_1 \quad \mathbf{u}_2 \quad \cdots \mathbf{u}_K],$$

where \mathbf{V} is the $N \times N$ unitary matrix of *right singular vectors*

$$\mathbf{V} = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \cdots \mathbf{v}_N],$$

$\mathbf{\Sigma}$ is the $K \times N$ nonnegative real singular values ($K > N$)

$$\mathbf{\Sigma} = \begin{bmatrix} \mathbf{S}_1 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \text{ with } \mathbf{S}_1 = \begin{bmatrix} \sigma_1 & 0 & \cdots & 0 \\ 0 & \sigma_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & \cdots & \sigma_N. \end{bmatrix}$$

Singular Value Decomposition (SVD)

- Left singular vectors \mathbf{u}_k are the eigenvectors of $\mathbf{X}\mathbf{X}^H$
- Right singular vectors \mathbf{v}_k are the eigenvectors of $\mathbf{X}^H\mathbf{X}$
- The singular values of $\mathbf{X}^H\mathbf{X}$ are σ_k^2 the squared singular values of \mathbf{X}
- If $K > N$, then there are at most N singular values, i.e., $K - N$ singular values are zero
- The pseudoinverse (used in LS) can be defined as

$$\mathbf{X}^\dagger \stackrel{\text{def}}{=} \mathbf{V}\mathbf{\Sigma}^\dagger\mathbf{U}^H$$

where

$$\mathbf{\Sigma}^\dagger = \begin{bmatrix} \mathbf{S}_1^{-1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$

ESPRIT Method using Total Least Squares (TLS)

- SVD of matrix in ESPRIT method

$$\underbrace{\begin{bmatrix} \mathbf{V}_{S1} & \mathbf{V}_{S2} \end{bmatrix}}_{M-1 \times 2p} = \underbrace{\begin{bmatrix} \mathbf{U}_1 & \mathbf{U}_2 \end{bmatrix}}_{M-1 \times M-1} \underbrace{\begin{bmatrix} \boldsymbol{\Sigma}_1 & \mathbf{0} \\ \mathbf{0} & \boldsymbol{\Sigma}_2 \end{bmatrix}}_{M-1 \times 2p} \underbrace{\begin{bmatrix} \mathbf{V}_1^H \\ \mathbf{V}_2^H \end{bmatrix}}_{2p \times 2p}$$

- Partitioning \mathbf{V}_2 as

$$\mathbf{V}_2^H = \begin{bmatrix} \underbrace{\mathbf{V}_{21}^H}_p & \underbrace{\mathbf{V}_{22}^H}_p \end{bmatrix}$$

- The TLS solution can be obtained as

$$\boldsymbol{\Phi}_{\text{TLS}} = -\mathbf{V}_{21} \mathbf{V}_{22}^{-1}$$

Principal Components Spectrum Estimation

- Earlier methods made use of the **noise subspace vectors** to estimate the complex exponential frequencies
- Here we use the **signal subspace vectors** to estimate the power spectrum
- From eigendecomposition of \mathbf{R}_x we have

$$\mathbf{R}_x = \sum_{i=1}^M \lambda_i \mathbf{v}_i \mathbf{v}_i^H = \sum_{i=1}^p \lambda_i \mathbf{v}_i \mathbf{v}_i^H + \sum_{i=p+1}^M \lambda_i \mathbf{v}_i \mathbf{v}_i^H,$$

where the eigenvalues of \mathbf{R}_x have been arranged in decreasing order, $\lambda_1 \geq \lambda_2 \geq \cdots \lambda_M$.

- We can obtain a **reduced rank** approximation to the signal autocorrelation matrix \mathbf{R}_s , by retaining the **principal eigenvectors** of \mathbf{R}_x ,

$$\hat{\mathbf{R}}_s = \sum_{i=1}^p \lambda_i \mathbf{v}_i \mathbf{v}_i^H.$$

Principal Components Spectrum Estimation

- We use the reduced rank approximation instead of \mathbf{R}_x in other spectral estimators
- Effect of using principal components is to filter out noise components and hence better spectral estimation of signal components
- Using this in Blackman-Tukey estimate

$$\hat{P}_{\text{BT}}(e^{j\omega}) = \sum_{k=-M}^M \hat{r}_x(k) w(k) e^{-jk\omega}$$

- With Bartlett window, we have

$$\hat{P}_{\text{BT}}(e^{j\omega}) = \frac{1}{M} \sum_{k=-M}^M (M - |k|) \hat{r}_x(k) e^{-jk\omega} = \frac{1}{M} \mathbf{e}^H \mathbf{R}_x \mathbf{e}.$$

Principal Components Spectrum Estimation

- Using Eigendecomposition

$$\hat{P}_{\text{BT}}(e^{j\omega}) = \frac{1}{M} \sum_{i=1}^M \left| \mathbf{e}^H \mathbf{v}_i \right|^2.$$

- With principal component approximation for \mathbf{R}_x , we have

$$\hat{P}_{\text{PC-BT}}(e^{j\omega}) = \frac{1}{M} \mathbf{e}^H \hat{\mathbf{R}}_s \mathbf{e} = \frac{1}{M} \sum_{i=1}^p \left| \mathbf{e}^H \mathbf{v}_i \right|^2.$$

- Similar approximations can be used in other techniques that use the autocorrelation matrix \mathbf{R}_x