

Intergalactic Riksbanken Chip Authenticator - README

Group 8

Suneela, Sara, and Abhishek

December 14, 2025

Intergalactic Riksbanken Chip Authenticator

> A computer vision system for authenticating and valuing intergalactic credit chips (Gold, Silver, Bronze) with simulator, camera, and interactive testing modes.

![[Python]](<https://www.python.org/>)

![[OpenCV]](<https://opencv.org/>)

■ Quick Start

Launch All Modes (Recommended)

```
# Install dependencies
pip install -r requirements.txt

# Run the launcher
python launcher.py

# Select mode:
# 1 - Simulator Mode (conveyor belt)
# 2 - Camera Mode (real detection)
# 3 - Interactive Game (manual testing)
```

Individual Modes

Option 1: Simulator Mode (No Camera Required)

```
python main.py
```

Option 2: Camera Mode (Real-time Detection)

```
python camera_main.py
```

Option 3: Interactive Game (Manual Chip Testing)

```
python game.py
```

Features

Simulator Mode

- **Green Conveyor Belt:** 50% screen width, centered with moving texture
- **Three Chip Types:**
 - **GOLD** (Yellow): Value = 3 digits × 10 (e.g., 752 → 7520 CR)
 - **SILVER** (Blue): Value = 3 digits (e.g., 756 → 756 CR)
 - **BRONZE** (Orange): Value = 2 digits × × (e.g., 2×4 → 8 CR)
- **Real & Fake Detection:** 80% real chips, 20% fake chips
- **Straight Line Movement:** Chips move perpendicular to belt motion
- **Real-time Statistics:** Track total value, real/fake counts

Camera Mode

Simulator Mode (`main.py`)

| Key | Action |
|-----|-----------------------|
| S | Spawn single chip |
| B | Burst spawn (5 chips) |
| C | Clear all chips |
| P | Pause/Resume |
| R | Reset statistics |
| Q | Quit |

Camera Mode (`camera_main.py`)

| Key | Action |
|-----|--------|
| | |

Controls

| Key | Action |
|-----|-----------------------|
| S | Spawn single chip |
| B | Burst spawn (5 chips) |
| C | Clear all chips |
| P | Pause/Resume |

■■■ camera_main.py # Camera detection system

| | |
|---|------------------|
| R | Reset statistics |
| Q | Quit |

Project Structure

```
chip_system/
■■■ launcher.py           # Main launcher (all modes)
■■■ main.py               # Conveyor simulator
■■■ camera_main.py       # Camera detection
■■■ game.py               # Interactive game
■■■ requirements.txt      # Dependencies
■■■ .gitignore            # Git ignore rules
■■■ README.md             # This file
■■■ QUICKSTART.md         # Quick reference
■■■ CHANGELOG.md          # Version history
■■■ LICENSE               # MIT License
■■■ CONTRIBUTING.md       # Guidelines
■■■ assets/               # Chip images
■   ■■■ gold.png
■   ■■■ silver.png
■   ■■■ bronze.png
■■■ docs/                 # Documentation
■■■ CAMERA_USAGE.md
■■■ MIGRATION.md
```

System Requirements

- Python 3.8+
- OpenCV 4.8+
- NumPy 1.24+
- Webcam (optional, for camera mode)

Value Calculation Rules

Based on STB600 Final Project 2025:

| Chip Type | Pattern | Calculation | Example |
|-----------|----------|---|---------------|
| GOLD | 3 digits | $(d_{100} \times 100 + d_{10} \times 10 + d_1) \times 10$ | 752 → 7520 CR |
| SILVER | 3 digits | $d_{100} \times 100 + d_{10} \times 10 + d_1$ | 756 → 756 CR |
| BRONZE | 2 digits | $d_{10} \times d_1$ | 2×4 → 8 CR |

Fake chips have 0 value and are marked in red.

Usage Example

```
from main import ConveyorSimulator

# Create simulator
sim = ConveyorSimulator(width=1280, height=720, conveyor_speed=3)

# Run
sim.run()
```

Credits

Created by Group 8:

- **Suneela**
- **Sara**
- **Abhishek**

STB600 Final Project 2025

Computer Vision & Image Processing