

Assignment 1. OpenGL Basics

Total of Points of the Assignment: 20

In this first programming assignment you will be asked to write a program to render polygonal meshes. For this, you will need to practice about some important features of a graphics application and their implementation using OpenGL and GLFW/GLUT commands. For example, you will know how to:

- Specify a virtual camera with arbitrary position and orientation;
- Render an object using different kinds of primitives, such as points, wireframe and solid polygons;
- Perform backface culling to reduce the number of primitives actually drawn;
- Change the field of view of the camera to achieve some zooming effects.

Besides supporting all the features listed above, your program should be able to:

- (a) Read and display arbitrary geometric models represented as triangle meshes. These objects are described in .obj suffix whose format will be presented next. Once you read the objects, these should be displayed in the center of the window **(4 points)**;
- (b) Translate the virtual camera along its own axes (u, v, n) (not along the world coordinate system axes) **(3 points)**;
- (c) Rotate the virtual camera along its own axes **(3 points)**;
- (d) Reset the camera to its original position (*i.e.*, object centered inside the window) **(2 points)**;
- (e) Support for rendering objects whose polygon vertices were defined using CW (clockwise) and CCW (counter clockwise) orientation – this will affect the behavior of the backface culling procedure **(2 points)**;
- (f) Support for changing the values of the *near* and *far* clipping planes **(1 point)**;
- (g) Support for interactive change of colors (R, G, B) for the models, making sure that the color change is apparent under all rendering modes (without lighting for this assignment). A single RGB color is assigned to all triangles of the model **(1 point)**;
- (h) Support for rendering the object using different kinds of primitives, such as points, wireframe and solid polygons **(2 points)**;
- (i) Support for reading a new model file through the user interface **(2 points)**.

Submit your source code and a self-contained executable file. You will need to demonstrate your program to the TA during office hours.

Here is the **Layout of the obj file**

Token	Command
v x y z(float)	Vertex position v (position x) (position y) (position z)
vn x y z(float)	Vertex normal vn (normal x) (normal y) (normal z)
vt x y(float)	Texture coordinate vt (tu) (tv)
f v1/vt1/vn1 v2/vt2/vn2 v3/vt3/vn3(int)	f (v)/(vt)/vn (v)/(vt)/(vn) (v)/(vt)/(vn) Faces are stored as a series of three vertices in clockwise order. Vertices are described by their position, optional texture coordinate, and optional normal, encoded as indices into the respective component lists.
Other tokens	We do not use other tokens in the first assignment

Example

cube.obj

v -0.500000 -0.500000 0.500000
v 0.500000 -0.500000 0.500000
v -0.500000 0.500000 0.500000
v 0.500000 0.500000 0.500000
v -0.500000 0.500000 -0.500000
v 0.500000 0.500000 -0.500000
v -0.500000 -0.500000 -0.500000
v 0.500000 -0.500000 -0.500000

vt 0.000000 0.000000
vt 1.000000 0.000000
vt 0.000000 1.000000
vt 1.000000 1.000000

vn 0.000000 0.000000 1.000000
vn 0.000000 1.000000 0.000000
vn 0.000000 0.000000 -1.000000
vn 0.000000 -1.000000 0.000000
vn 1.000000 0.000000 0.000000
vn -1.000000 0.000000 0.000000

f 1/1/1 2/2/1 3/3/1
f 3/3/1 2/2/1 4/4/1
f 3/1/2 4/2/2 5/3/2
f 5/3/2 4/2/2 6/4/2
f 5/4/3 6/3/3 7/2/3
f 7/2/3 6/3/3 8/1/3
f 7/1/4 8/2/4 1/3/4
f 1/3/4 8/2/4 2/4/4
f 2/1/5 8/2/5 4/3/5
f 4/3/5 8/2/5 6/4/5
f 7/1/6 1/2/6 5/3/6
f 5/3/6 1/2/6 3/4/6

Reading Input Files

This code is showed for the purposes of illustration. You can also create your own format of data structure as well.

```
struct Vertex {
    // Position
    glm::vec3 Position;
    // Normal
    glm::vec3 Normal;
    // TexCoords
    glm::vec2 TexCoords;
};

void load_obj(string obj_path, vector<Vertex> &vertices) {
    std::vector<glm::vec3> positions;
    std::vector<glm::vec3> normals;
    std::vector<glm::vec2> tex_coods;
    ifstream ifs;
    try {
        ifs.open(obj_path);
        string one_line;
        while (getline(ifs, one_line)) {
            stringstream ss(one_line);
            string type;
            ss >> type;
            if (type == "v") {
                glm::vec3 vert_pos;
                ss >> vert_pos[0] >> vert_pos[1] >> vert_pos[2];
                positions.push_back(vert_pos);
            }
            else if (type == "vt") {
                glm::vec2 tex_coord;
                ss >> tex_coord[0] >> tex_coord[1];
                tex_coods.push_back(tex_coord);
            }
            else if (type == "vn") {
                glm::vec3 vert_norm;
                ss >> vert_norm[0] >> vert_norm[1] >> vert_norm[2];
                normals.push_back(vert_norm);
            }
            else if (type == "f") {
                string s_vertex_0, s_vertex_1, s_vertex_2;
                ss >> s_vertex_0 >> s_vertex_1 >> s_vertex_2;
                int pos_idx, tex_idx, norm_idx;
                sscanf(s_vertex_0.c_str(), "%d/%d/%d", &pos_idx, &tex_idx, &norm_idx);
                // We have to use index -1 because the obj index starts at 1
                Vertex vertex_0;
                vertex_0.Position = positions[pos_idx-1];
                vertex_0.TexCoords = tex_coods[tex_idx-1];
                vertex_0.Normal = normals[norm_idx-1];
                sscanf(s_vertex_1.c_str(), "%d/%d/%d", &pos_idx, &tex_idx, &norm_idx);
                Vertex vertex_1;
                vertex_1.Position = positions[pos_idx-1];
                vertex_1.TexCoords = tex_coods[tex_idx-1];
                vertex_1.Normal = normals[norm_idx-1];
                sscanf(s_vertex_2.c_str(), "%d/%d/%d", &pos_idx, &tex_idx, &norm_idx);
                Vertex vertex_2;
                vertex_2.Position = positions[pos_idx-1];
                vertex_2.TexCoords = tex_coods[tex_idx-1];
                vertex_2.Normal = normals[norm_idx-1];
                vertices.push_back(vertex_0);
                vertices.push_back(vertex_1);
                vertices.push_back(vertex_2);
            }
        }
    }
    catch (const std::exception&) {
        cout << "Error: Obj file cannot be read\n";
    }
}
```

Tips on How to Complete the Assignment

Don't use fixed rendering pipeline

In this assignment, you need to use the modern OpenGL rendering pipeline instead of fixed pipeline. For example: you should use `glm::perspective()` returning a mat and send mat into vertex shader instead of using `gluPerspective()`. You should also not use `glRotate()`, `glTranslate()`, etc.

Rendering the object in the center of the window

In order to render the object in the center of the window, you will need to do some calculations. For instance, as you read the object description from the file, given the vertices' coordinates in WCS, the object might be behind the camera or outside of its field of view. It could also be too big and be only partially inside the view frustum. You will then need to reposition the camera in order to make sure the object will be completely visible and centered in the window. In order to accomplish this, you will need to identify the range (minimum and maximum coordinates) of the object in both X, Y and Z. With these values at hand, you can then imagine a bounding box (a parallelepiped) for the object. In order for the object to appear centered, the x and y coordinates for the position of the camera can be computed as the average of the corresponding min and max values. Note, however, this might not be enough if the object is too big or if the field of view is too small. In these cases, the object might be partially outside of the view frustum. You should then use your trigonometric skills to figure out what should be the z coordinate of the camera so that the object is completely visible and as close as possible.

Rotating the Camera

In order to perform camera rotation (translation) around (along) the camera's axes, you will need to keep track of the vectors that define the camera coordinate system. As you start your program, let these vectors be: $u = (1, 0, 0)$, $v = (0, 1, 0)$, and $n = (0, 0, -1)$.

As we rotate the camera, we change the vectors that define the CCS (note that this does not happen when we perform just a translation). Thus, we need to recalculate them. Fortunately, this is not difficult and can be accomplished using the same basic ideas used to derive the rotations of points in 2D and 3D.

Changing the values of the near and far clipping planes

This can be accomplished with `glm::perspective()`. Don't forget to select and initialize the projection matrix before you call `glm::perspective()`. and to set the current matrix back to the model view matrix after you are done.

Initialize $Z_{near} = 1.0f$ and $Z_{far} = 3000.0$ and play with these values. What happens when Z_{near} becomes very close to zero?

Selecting the orientation (CW, CCW) for the front facing polygons

Your program should support change of the orientation interactively. For this, use the command `glFrontFace()`.