ELEN30011 EDM Task

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1.1

For rectangular coordinates and cylindrical coodinates,

 $x = rcos\phi$

 $y = rsin\phi$

z = z

(a)

(1, 0, 0)

(b)

(-1, 0, 0)

(c)

(0, -1, 3)

(d)

(0, 0, -2)

(e)

(-1, 0, 0)

1.2

For spherical coordinates and rectangular coordinates,

 $x=rcos\phi sin\theta$

$$y = r sin \phi sin heta$$
 $z = r cos heta$

It can be noted that, r is the modulus of a vector $r=\sqrt{x^2+y^2+z^2}$; ϕ is the angle with the x-axis in x-y plane $\phi=\arctan(y/x)$; θ is the angle with the z-axis $\theta=\arctan(\sqrt{x^2+y^2}/z)$. In order to make the answer unique, we assume $r\geq 0, \phi\in[0,2\pi), \theta\in[0,\pi]$

(a)

 $(1,0,\pi/2)$

(b)

 $(1,\pi/2,\pi/2)$

(c)

(1,0,0)

• ϕ can be any real number here.

(d)

 $(\sqrt{2},\pi/2,\pi/4)$

(e)

(0,0,0)

• $r=0,\,\phi$ and θ can be any real number here.

2.1

(a) Let

$$x=rcos\phi, y=rsin\phi, z=z$$

Jacobin Matrix:

$$J(r,\phi,z) = egin{pmatrix} cos\phi & -rsin\phi & 0 \ sin\phi & rcos\phi & 0 \ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} dx \\ dy \\ dz \end{pmatrix} = J \begin{pmatrix} dr \\ d\phi \\ dz \end{pmatrix}$$

Hence find expressions for \hat{r} and $\hat{\phi}$ in terms of \hat{x} and $\hat{y}.$ Since \hat{r} and $\hat{\phi}$ are unit vectors, let r=1

$$T(\phi) = egin{pmatrix} cos\phi & -sin\phi & 0 \ sin\phi & cos\phi & 0 \ 0 & 0 & 1 \end{pmatrix}$$

Or, considering

$$egin{aligned} \hat{r} &= cos\phi\hat{x} + sin\phi\hat{y} \ \hat{\phi} &= -sin\phi\hat{x} + cos\phi\hat{y} \ v &= v_r\hat{r} + v_\phi\hat{\phi} + v_z\hat{z} \end{aligned} \ v_x &= v\cdot\hat{x} = v_rcos\phi - v_\phi sin\phi \ v_y &= v\cdot\hat{y} = v_rsin\phi + v_\phi cos\phi \ v_z &= v\cdot\hat{z} = v_z \end{aligned}$$

In order to make

$$egin{pmatrix} v_x \ v_y \ v_z \end{pmatrix} = T(\phi) egin{pmatrix} v_r \ v_\phi \ v_z \end{pmatrix}$$
 $T(\phi) = egin{pmatrix} cos\phi & -sin\phi & 0 \ sin\phi & cos\phi & 0 \ 0 & 0 & 1 \end{pmatrix}$

(b)

We've got that

$$T(\phi) = egin{pmatrix} cos \phi & -sin \phi & 0 \ sin \phi & cos \phi & 0 \ 0 & 0 & 1 \end{pmatrix}$$

The (i, j)-cofactor is $C_{i,j}=(-1)^{i+j}M_{i,j}$, where $M_{i,j}$ is the (i, j)-minor.

$$C_{11}=(-1)^{1+1}M_{11}=egin{bmatrix} cos\phi & 0\ 0 & 1 \end{bmatrix}=cos\phi$$

Similarly,

$$C_{12} = -sin\phi \quad C_{13} = 0 \ C_{21} = sin\phi \quad C_{22} = cos\phi \quad C_{23} = 0 \ C_{31} = 0 \quad C_{32} = 0 \quad C_{33} = 1$$

Hence,

$$(T^*(\phi))^T = egin{pmatrix} cos\phi & -sin\phi & 0 \ sin\phi & cos\phi & 0 \ 0 & 0 & 1 \end{pmatrix}$$

The adjugate matrix of T is:

$$T^*(\phi) = egin{pmatrix} cos\phi & sin\phi & 0 \ -sin\phi & cos\phi & 0 \ 0 & 0 & 1 \end{pmatrix} \ det[T(\phi)] = 1$$

Based on Cramer's rule,

$$T^{-1}(\phi) = rac{1}{det}T^*(\phi)$$

Hence,

$$T^{-1}(\phi) = egin{pmatrix} cos\phi & sin\phi & 0 \ -sin\phi & cos\phi & 0 \ 0 & 0 & 1 \end{pmatrix}$$

(c)

$$r=\sqrt{x^2+y^2\over x} \ cos(\phi)=rac{x}{\sqrt{x^2+y^2}} \ sin(\phi)=rac{y}{\sqrt{x^2+y^2}}$$

(d)

According to the result of part c, substitute $cos\phi$ and $sin\phi$:

$$T^{-1}(\phi) = egin{pmatrix} cos\phi & sin\phi & 0 \ -sin\phi & cos\phi & 0 \ 0 & 0 & 1 \end{pmatrix}$$

$$S(P) = egin{pmatrix} rac{x}{\sqrt{x^2 + y^2}} & rac{y}{\sqrt{x^2 + y^2}} & 0 \ -rac{y}{\sqrt{x^2 + y^2}} & rac{x}{\sqrt{x^2 + y^2}} & 0 \ 0 & 0 & 1 \end{pmatrix}$$

2.2

In Question 2.1(d), we've got

$$S(P) = egin{pmatrix} rac{x}{\sqrt{x^2 + y^2}} & rac{y}{\sqrt{x^2 + y^2}} & 0 \ -rac{y}{\sqrt{x^2 + y^2}} & rac{x}{\sqrt{x^2 + y^2}} & 0 \ 0 & 0 & 1 \end{pmatrix}$$

(a) P = (0, -1, 0)

$$S(P) = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} S^{-1}(P) = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
$$S^{-1}(P)P = (-1, 0, 0)^{T}$$

(b) P = (1, 0, 0)

$$S^{-1}(P) = S(P) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

 $S^{-1}(P)P = (1, 0, 0)^T$

(c) P = (-1, 0, 0)

$$S^{-1}(P) = S(P) = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
$$S^{-1}(P)P = (1, 0, 0)^{T}$$

(d) P = (1, -1, 0)

$$S(P) = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & 0\\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0\\ 0 & 0 & 1 \end{pmatrix} S^{-1}(P) = \begin{pmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0\\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0\\ 0 & 0 & 1 \end{pmatrix}$$

$$S^{-1}(P)P = (0, -\sqrt{2}, 0)^T$$

(e)
$$P = (0, 0, 0)$$

Since,

$$\lim_{x o 0, y = 0} rac{x}{\sqrt{x^2 + y^2}} = 1 \ \lim_{x = 0, y o 0} rac{y}{\sqrt{x^2 + y^2}} = 1$$

We get S(P) and $S^{-1}(P)$:

$$S(P) = egin{pmatrix} 1 & 1 & 0 \ -1 & 1 & 0 \ 0 & 0 & 1 \end{pmatrix} S^{-1}(P) = egin{pmatrix} 1/2 & -1/2 & 0 \ 1/2 & 1/2 & 0 \ 0 & 0 & 1 \end{pmatrix} \ S^{-1}(P)P = (0,0,0)^T$$

3.1

(a)

```
x = -2:.1:2;
y = -2:.1:2;
[xx, yy] = meshgrid(x, y);
size(xx)
size(yy)
```

Which output is:

```
ans =

41 41

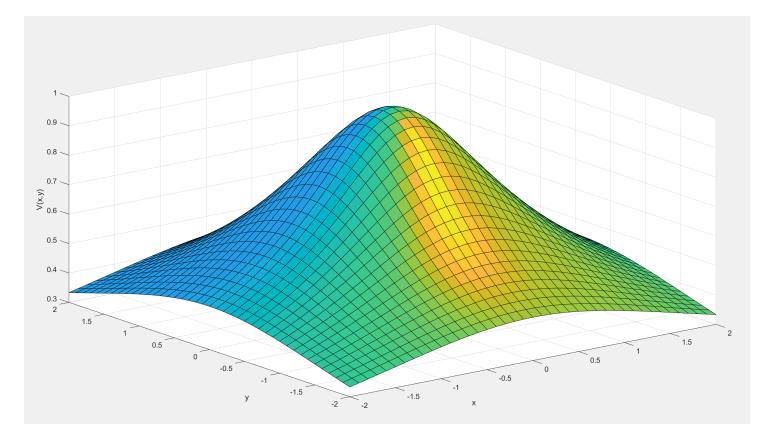
ans =

41 41
```

```
x = -2:.1:2;
y = -2:.1:2;
[xx, yy] = meshgrid(x, y);

size(xx)
size(yy)

zz = 1./sqrt(1 + xx.^2 + yy.^2);
figure(1);
surfl(xx, yy, zz);
xlabel('x');
ylabel('y');
zlabel('V(x,y)');
grid on;
```



Based on the picture above, it has been shown that the surface exhibit a maximum.

After checked the value "zz" in workspace, we get the maximum point is (0,0,1).

For certain plane, origin can always be the point with the highest electrostatic potential. If a charge moves in any direction on its x-y plane, the electric field does positive work on it.

(c)

A circle.

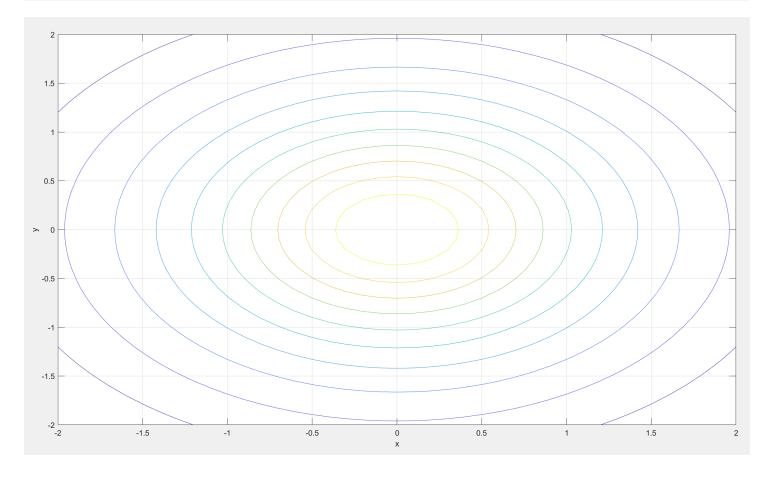
$$V = rac{1}{\sqrt{1+x^2+y^2}} \ \sqrt{1+x^2+y^2} = rac{1}{V} \ x^2+y^2 = rac{1}{V^2} - 1$$

Its radius is $\sqrt{rac{1}{V^2}-1}$

If V=c>1, radius will be an imaginary number, which is impossible here. Hence, c will never be greater than 1.

(d)

```
figure(2);
contour(xx, yy,zz, 10);
xlabel('x');
ylabel('y');
grid on;
```



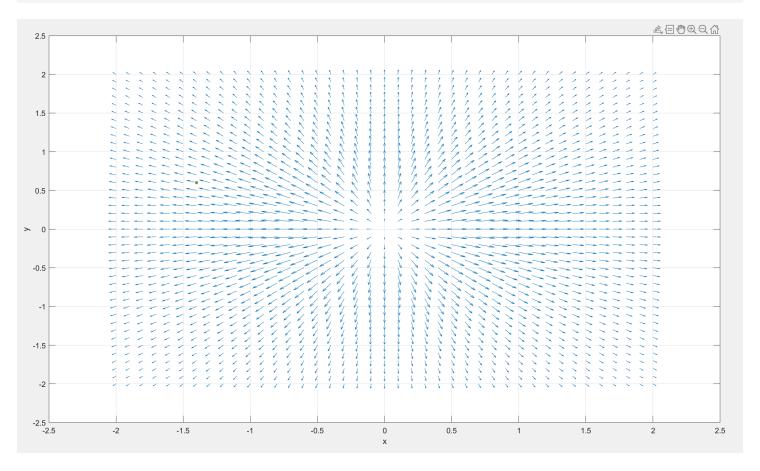
[&]quot;10" means: Display 10 contour lines at automatically chosen levels (heights).

3.2

(a)

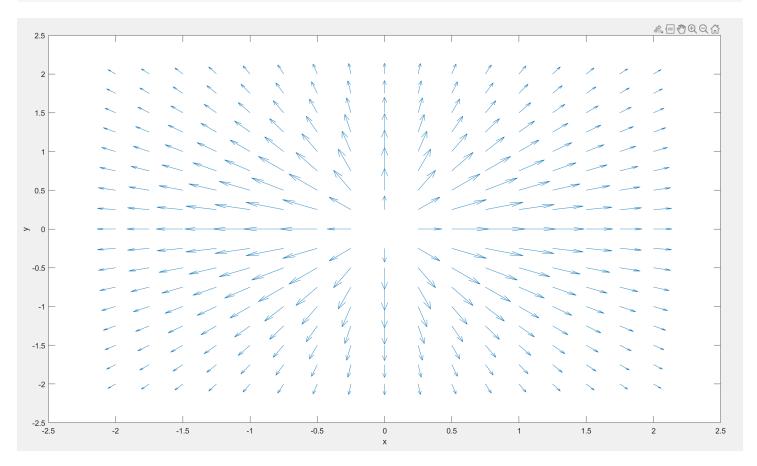
```
exx = xx./(1 + xx.^2 + yy.^2).^(3/2);
eyy = yy./(1 + xx.^2 + yy.^2).^(3/2);

figure(3);
quiver(xx,yy,exx,eyy);
xlabel('x');
ylabel('y');
grid on;
```



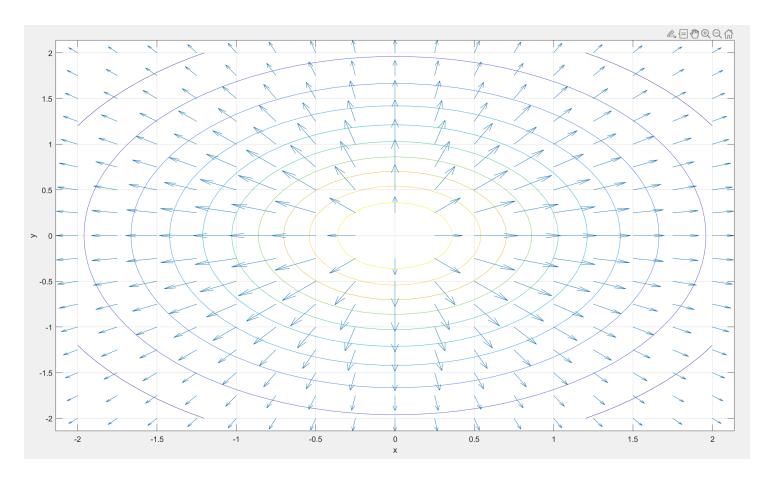
(b)

```
xnew = -2:.25:2;
ynew = xnew;
[xxnew, yynew] = meshgrid(xnew, ynew);
exxnew = xxnew./(1 + xxnew.^2 + yynew.^2).^(3/2);
eyynew = yynew./(1 + xxnew.^2 + yynew.^2).^(3/2);
figure(4);
quiver(xxnew, yynew, exxnew, eyynew);
hold on;
```



(c)

```
figure(2);
hold on;
quiver(xxnew, yynew, exxnew, eyynew);
```



Perpendicular to each other.

3.3

(a)