# **ELEN30011 EDM Task**

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### 1.1

 $oldsymbol{
abla}\cdot \mathbf{F}$  (div  $\mathbf{F}$ ) is a scalar,  $oldsymbol{
abla}\times \mathbf{F}$  is a vector field.

Explaination: ↓

#### 1.2

Let  $\mathbf{F}:\mathbb{R}^3 o \mathbb{R}^3$  be a vector field with

$$\mathbf{F}(x,y,z) = F_x(x,y,z)\mathbf{\hat{x}} + F_y(x,y,z)\mathbf{\hat{y}} + F_z(x,y,z)\mathbf{\hat{z}}$$

The divergence of  ${f F}$  (div  ${f F}$ ) is

$$egin{aligned} oldsymbol{
abla} \cdot \mathbf{F} &= (rac{\partial}{\partial x}, rac{\partial}{\partial y}, rac{\partial}{\partial z}) \cdot (F_x, F_y, F_z) \ &= rac{\partial F_x}{\partial x} + rac{\partial F_y}{\partial y} + rac{\partial F_z}{\partial z} \end{aligned}$$

 $\mathbf{\nabla}\cdot\mathbf{F}$  is a scalar.

$$\begin{aligned} \boldsymbol{\nabla} \times \mathbf{F} &= (\frac{\partial}{\partial x} \mathbf{\hat{x}} + \frac{\partial}{\partial y} \mathbf{\hat{y}} + \frac{\partial}{\partial z} \mathbf{\hat{z}}) \times (F_x(x, y, z) \mathbf{\hat{x}} + F_y(x, y, z) \mathbf{\hat{y}} + F_z(x, y, z) \mathbf{\hat{z}}) \\ &= \begin{vmatrix} \mathbf{\hat{x}} & \mathbf{\hat{y}} & \mathbf{\hat{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} \\ &= (\frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z}) \mathbf{\hat{x}} + (\frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x}) \mathbf{\hat{y}} + (\frac{\partial F_x}{\partial y} - \frac{\partial F_y}{\partial x}) \mathbf{\hat{z}} \end{aligned}$$

 $\mathbf{\nabla} \times \mathbf{F}$  is a vector field.

### 1.3

(a)

$$gradf = 
abla f = rac{\partial f}{\partial x}\mathbf{\hat{x}} + rac{\partial f}{\partial y}\mathbf{\hat{y}} + rac{\partial f}{\partial z}\mathbf{\hat{z}} = 0\mathbf{\hat{x}} + 0\mathbf{\hat{y}} + 0\mathbf{\hat{z}}$$

(b)

$$gradf = 
abla f = rac{\partial f}{\partial x}\mathbf{\hat{x}} + rac{\partial f}{\partial y}\mathbf{\hat{y}} + rac{\partial f}{\partial z}\mathbf{\hat{z}} = 1\mathbf{\hat{x}} + z\mathbf{\hat{y}} + y\mathbf{\hat{z}}$$

(c)

$$gradf = 
abla f = rac{\partial f}{\partial x}\mathbf{\hat{x}} + rac{\partial f}{\partial y}\mathbf{\hat{y}} + rac{\partial f}{\partial z}\mathbf{\hat{z}} = x\mathbf{\hat{x}} + (y + rac{1}{2}z^2siny)\mathbf{\hat{y}} - zcosy\mathbf{\hat{z}}$$

(d)

$$gradf = 
abla f = rac{\partial f}{\partial x}\mathbf{\hat{x}} + rac{\partial f}{\partial y}\mathbf{\hat{y}} + rac{\partial f}{\partial z}\mathbf{\hat{z}} = rac{-x}{x^2 + y^2 + z^2}\mathbf{\hat{x}} + rac{-y}{x^2 + y^2 + z^2}\mathbf{\hat{y}} + rac{-z}{x^2 + y^2 + z^2}\mathbf{\hat{z}}$$

### 1.4

(a)

$$div \mathbf{F} = \mathbf{\nabla} \cdot \mathbf{F} = rac{\partial F_x}{\partial x} + rac{\partial F_y}{\partial y} + rac{\partial F_z}{\partial z} = 0$$
 $curl \mathbf{F} = \mathbf{\nabla} imes \mathbf{F} = egin{bmatrix} \mathbf{\hat{x}} & \mathbf{\hat{y}} & \mathbf{\hat{z}} \ rac{\partial}{\partial x} & rac{\partial}{\partial y} & rac{\partial}{\partial z} \ F_x & F_y & F_z \ \end{bmatrix} = egin{bmatrix} \mathbf{\hat{x}} & \mathbf{\hat{y}} & \mathbf{\hat{z}} \ rac{\partial}{\partial x} & rac{\partial}{\partial y} & rac{\partial}{\partial z} \ 0 & 0 & 0 \ \end{bmatrix} = 0\mathbf{\hat{x}} + 0\mathbf{\hat{y}} + 0\mathbf{\hat{z}}$ 

(b)

$$div\mathbf{F} = \mathbf{\nabla} \cdot \mathbf{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z} = -1 + 1 = 0$$

$$curl\mathbf{F} = \mathbf{\nabla} \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -x & 0 & z \end{vmatrix} = 0\hat{\mathbf{x}} + 0\hat{\mathbf{y}} + 0\hat{\mathbf{z}}$$

(c)

$$div \mathbf{F} = \mathbf{
abla} \cdot \mathbf{F} = rac{\partial F_x}{\partial x} + rac{\partial F_y}{\partial y} + rac{\partial F_z}{\partial z} = 0$$
  $curl \mathbf{F} = \mathbf{
abla} imes \mathbf{F} = egin{array}{c|ccc} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ rac{\partial}{\partial x} & rac{\partial}{\partial y} & rac{\partial}{\partial z} \\ F_x & F_y & F_z \end{array} = egin{array}{c|ccc} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ rac{\partial}{\partial x} & rac{\partial}{\partial y} & rac{\partial}{\partial z} \\ z & 0 & -x \end{array} = [1 - (-1)]\hat{\mathbf{y}} = 2\hat{\mathbf{y}}$ 

(d)

$$div\mathbf{F} = \mathbf{\nabla} \cdot \mathbf{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z} = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y} + \frac{\partial^2 f}{\partial z^2}$$

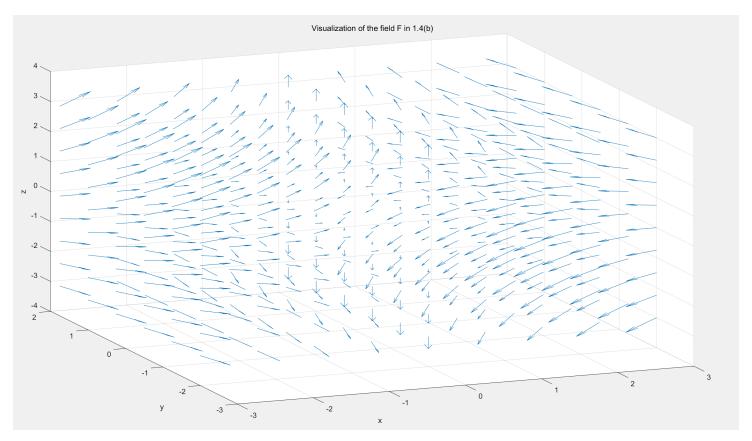
$$curl\mathbf{F} = \mathbf{\nabla} \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix}$$

$$= (\frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y})\hat{\mathbf{x}} + (\frac{\partial^2 f}{\partial z \partial x} - \frac{\partial^2 f}{\partial x \partial z})\hat{\mathbf{y}} + (\frac{\partial^2 f}{\partial y \partial x} - \frac{\partial^2 f}{\partial x \partial y})\hat{\mathbf{z}}$$

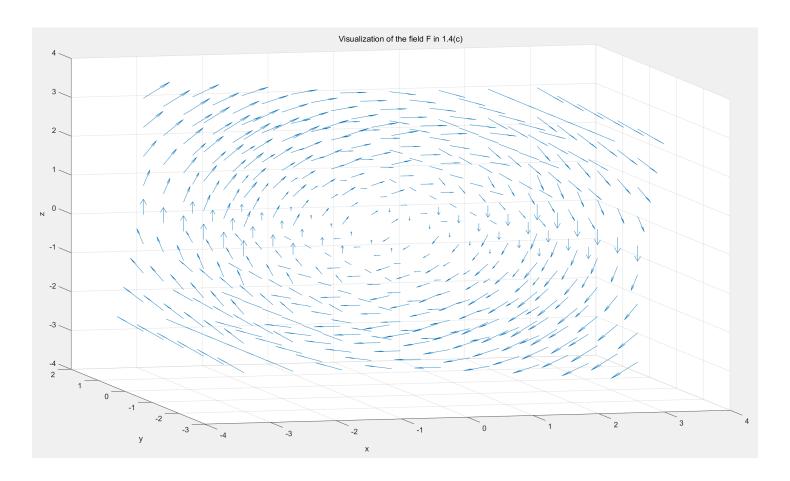
$$= 0\hat{\mathbf{x}} + 0\hat{\mathbf{y}} + 0\hat{\mathbf{z}}$$

#### 1.5

```
close all
clear
clc
x = -3:.75:3;
y = -2:.75:2;
z = -3:.75:3;
[X, Y, Z] = meshgrid(x, y, z);
FX = -X;
FY = 0.*Y:
FZ = Z;
figure(1);
quiver3(X,Y,Z,FX,FY,FZ)
xlabel("x");
ylabel("y");
zlabel("z");
title("Visualization of the field F in 1.4(b)")
```



```
close all
clear
clc
x = -3:.75:3;
y = -2:.75:2;
z = -3:.75:3;
[X, Y, Z] = meshgrid(x, y, z);
FX = Z;
FY = 0.*Y;
FZ = -X;
figure(1);
quiver3(X,Y,Z,FX,FY,FZ)
xlabel("x");
ylabel("y");
zlabel("z");
title("Visualization of the field F in 1.4(c)")
```



# 2.1

## 2.1.1

 $\mathbf{l_1}$  is a straight line.

$$\mathbf{l_1}(s) = (1-s)\mathbf{P_1} + s\mathbf{P_2}$$

 $oldsymbol{l_2}$  is circular arc of radius 1.

Let  $x = cos(\frac{\pi s}{4})$ ,  $y = sin(\frac{\pi s}{4})$ .

$$x^2 + y^2 = cos^2(\frac{\pi s}{4}) + sin^2(\frac{\pi s}{4}) = 1$$

In cartesian coordinates,  $x^2+y^2=1$  is describing a circle with a radius of 1.

Plus, since  $s\in[0,1]$ ,  $x\in[\frac{\sqrt{2}}{2},1]$ ,  $y\in[0,\frac{\sqrt{2}}{2}]$ .

When s increases,  ${f l_2}$  moves from (1,0) to  $(\frac{\sqrt{2}}{2},\frac{\sqrt{2}}{2})$  along this circle, anticlockwise.

#### 2.1.2

Fomular (8) shows that,

$$\mathbf{E}(x,y,z) = -y\mathbf{\hat{x}} - x\mathbf{\hat{y}}$$

For 
$$\mathbf{l_1}$$
,  $x=1-s+rac{s}{\sqrt{2}}$ ,  $y=rac{s}{\sqrt{2}}$ 

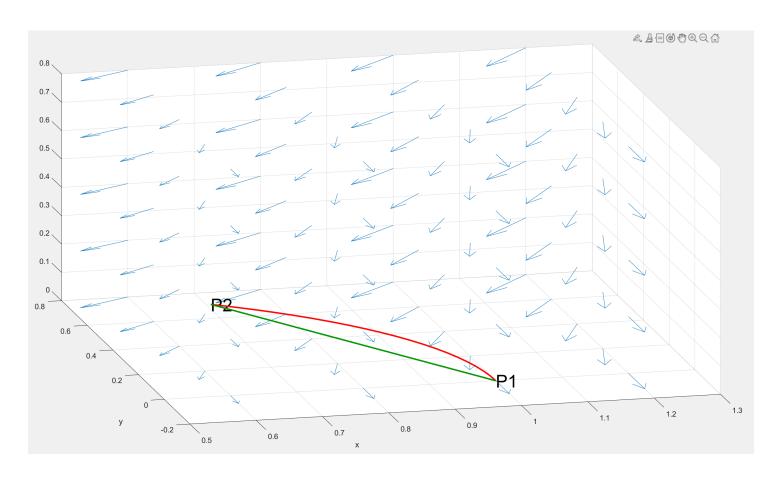
$$\mathbf{E}(\mathbf{l_1}(s)) = -\frac{s}{\sqrt{2}}\mathbf{\hat{x}} - (1 - s + \frac{s}{\sqrt{2}})\mathbf{\hat{y}}$$

For  $\mathbf{l_2}$ ,  $x=cos(rac{\pi s}{4})$ ,  $y=sin(rac{\pi s}{4})$ 

$$\mathbf{E}(\mathbf{l_2}(s)) = -sin(rac{\pi s}{4})\mathbf{\hat{x}} - cos(rac{\pi s}{4})\mathbf{\hat{y}}$$

#### 2.1.3

```
x = 0.6:.2:1.2; y = 0:.2:.8; z = 0:.2:.8;
[xx,yy,zz] = meshgrid(x,y,z);
Exx =-yy; Eyy =-xx; Ezz = 0*xx;
figure(2);
quiver3(xx,yy,zz,Exx,Eyy,Ezz);
grid on; hold on;
xhat = [1;0;0]; yhat = [0;1;0];
s = 0:.05:1;
L1 = (1- s).*xhat + s.*(xhat + yhat)/sqrt(2);
L2 = cos(pi .*s ./4).*xhat + sin(pi .*s ./4).*yhat;
plot3(L1(1,:),L1(2,:),L1(3,:),'Color',[0 .6 0],'LineWidth',2);
plot3(L2(1,:),L2(2,:),L2(3,:),'Color',[1 0 0],'LineWidth',2);
xlabel("x")
ylabel("y")
text(1,0,0,"P1","FontSize",24)
text(1/sqrt(2), 1/sqrt(2), 0, "P2", "FontSize", 24)
```



## 2.1.4

There is no singularity here, the result is not related to the path.

$$egin{aligned} V_{l_1} &= -\int_{l_1} \mathbf{E} \cdot dl_1 \ &= -\int_{l_1} \mathbf{E}(\mathbf{l_1(s)}) \cdot rac{d\mathbf{l_1}}{ds}(s) ds \ &= -\int_{s} (-rac{s}{\sqrt{2}}, -(1-s+rac{s}{\sqrt{2}}))(-1+rac{1}{\sqrt{2}}, rac{1}{\sqrt{2}}) ds \ &= -\int_{0}^{1} \sqrt{2}s - s - rac{\sqrt{2}}{2} ds \ &= rac{1}{2} \end{aligned}$$

$$\begin{split} V_{l_2} &= -\int_{l_2} \mathbf{E} \cdot dl_2 \\ &= -\int_{l_2} \mathbf{E} (\mathbf{l_2}(\mathbf{s})) \cdot \frac{d\mathbf{l_2}}{ds} (s) ds \\ &= -\int_{s} (-sin(\frac{\pi s}{4}), -cos(\frac{\pi s}{4})) (-\frac{\pi}{4} sin(\frac{\pi s}{4}), \frac{\pi}{4} cos(\frac{\pi s}{4})) ds \\ &= \int_{0}^{1} cos^{2} (\frac{\pi s}{4}) - sin^{2} (\frac{\pi s}{4}) ds \\ &= \frac{\pi}{4} \int_{0}^{1} cos(\frac{\pi s}{2}) ds \\ &= \frac{\pi}{4} \times \frac{2}{\pi} sin(\frac{\pi s}{2})|_{s=0}^{s=1} \\ &= \frac{1}{2} \end{split}$$

• Force:

$$\mathbf{F} = q\mathbf{E}$$

• Work:

$$W=-\int_{l}\mathbf{F}dl=-q\int_{l}\mathbf{E}dl$$

Voltage

$$V=rac{W}{q}=-\int_{l}\mathbf{E}dl$$

#### 2.1.5

Since  $\mathbf{E}(x,y,z) = -y\mathbf{\hat{x}} - x\mathbf{\hat{y}}$  (shown in Fomular 8)

This field is static,

$$-\nabla U = E$$
$$\frac{\partial U}{\partial x} = y$$
$$\frac{\partial U}{\partial y} = x$$

Hence,

$$U = xy + c$$

where c is constant.

$$\mathbf{P_1} = (1,0), \mathbf{P_2} = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$$

$$U(\mathbf{P_2}) - U(\mathbf{P_1}) = (1/2 + c) - (0 + c) = \frac{1}{2}$$

# 2.2