

SEMINAR NOTES: BASIC DE RHAM THEORY

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These notes is based on author's presentation on the first meeting of sminar on GTM 82, at USTC. The first meeting covers section 1- section 3 in chapter 1.

1. INTRODUCTION

Cohomology, homology and homotopy groups are three fundamental tools deveoloped in algebraic topology. The can be considered as the following functors:

$$\begin{aligned} H^*(-; A): \mathbf{Top} &\longrightarrow \mathbf{Ring}, \\ H_*(-; A): \mathbf{Top} &\longrightarrow \mathbf{Mod}_R, \\ \pi_n(-): \mathbf{Top}_* &\longrightarrow \mathbf{Grp}, \end{aligned}$$

where A is an R -module. These tools are effective in studying and distinguishes spaces, but in reture they are usually difficult to describe and compute.

The fundamental idea in GTM 82 is roughly the following: Invariants in algebraic topology can be defined and represented in an easier way on manifolds with the help of specific tools for manifolds.

We will focus on the subcategory \mathbf{Man}^∞ , the category of smooth manifolds, whose morphisms are smooth maps. Note that functors above actually factor through \mathbf{hTop} and \mathbf{hTop}_* , but considering \mathbf{Man}^∞ is safe, due to the Whitney approximation which claims that every continuous map of smooth manifolds is homotopic to a smooth one.

2. REVIEW OF DIFFERENTIAL FORMS

The main ingredients for de Rham theory are differential forms on smooth manifolds.

Let M be a smooth manifold. A k -form on M is a smooth section

$$\omega: M \longrightarrow \bigwedge^k T^*M.$$

Collection of k -forms is denoted by $\Omega^k(M)$. In local coordinates (x^1, \dots, x^m) , a k -form can be written as

$$\omega = \omega_I dx^I,$$

where I runs over ordered indices with length k .

3. ORIENTATION AND INTEGRAL ON MANIFOLDS

Manifolds are generalized objects of Euclidean spaces, on which we can still perform differential and integral.

4. DE RHAM THEORY

Let M be a smooth manifold. We can consider chains of exterior derivatives

$$\Omega^0(M) \xrightarrow{d} \Omega^1(M) \xrightarrow{d} \dots \xrightarrow{d} \Omega^m(M) \xrightarrow{d} 0.$$

Let $Z_k = \text{Ker}(d: \Omega^k(M) \rightarrow \Omega^{k+1}(M))$ and $B_k = \text{Im}(d: \Omega^{k-1}(M) \rightarrow \Omega^k(M))$. Then $d^2 = 0$ implies $B_k \leq Z_k$. The k -th de Rham cohomology of M is

$$H_{\text{dR}}^k(M) = B_k / Z_k.$$

$(\Omega^*(M), d)$ is actually an example for cochain complexes.

Definition 4.1. A cochain complex is a pair (C^*, d) which consists of a chain of morphisms $d: C^q \rightarrow C^{q+1}$ such that $d^2 = 0$. Here C^q are modules or vector spaces over fields.

For every cochain complex (C^*, d) , we can all define its cohomology

$$H^k(C^q, d) = \frac{\text{Ker}(d: C^q \rightarrow C^{q+1})}{\text{Im}(d: C^{q-1} \rightarrow C^q)}.$$

Definition 4.2. Let $(A^*, d_A), (B^*, d_B)$ be cochain complexes. A cochain map $f: A^* \rightarrow B^*$ is a sequence of morphisms $f_q: A^q \rightarrow B^q$ such that the following diagram is commutative

$$\begin{array}{ccc} A^q & \xrightarrow{d_A} & A^{q+1} \\ \downarrow f_q & & \downarrow f_{q+1} \\ B^q & \xrightarrow{d'_B} & B^{q+1} \end{array}$$

This can be simply expressed as $f \circ d_A = d_B \circ f$.

By definition, a cochain map $f: A^* \rightarrow B^*$ naturally induces maps of cohomology $f: H^q(A^*, d_A) \rightarrow H^q(B^*, d_B), [\alpha] \mapsto [f(\alpha)]$. This is well-defined because $f(d_A(\alpha)) = d_B(f(\alpha))$.

Definition 4.3. Cochain maps

$$0 \longrightarrow A^* \xrightarrow{f} B^* \xrightarrow{g} C^* \longrightarrow 0$$

is called a short exact sequence if for each q ,

$$0 \longrightarrow A^q \xrightarrow{f} B^q \xrightarrow{g} C^q \longrightarrow 0$$

is exact.

Theorem 4.4. A short exact sequence

$$0 \longrightarrow A^* \xrightarrow{f} B^* \xrightarrow{g} C^* \longrightarrow 0$$

induces a long exact sequence

$$\begin{array}{ccccccc} \cdots & \longrightarrow & H^n(A^*) & \xrightarrow{f} & H^n(B^*) & \xrightarrow{g} & H^n(C^*) \\ & & & & \searrow \delta & & \\ & & H^{n+1}(A^*) & \xleftarrow{f} & H^{n+1}(B^*) & \xrightarrow{g} & H^{n+1}(C^*) \longrightarrow \cdots \end{array}$$

δ is called the connecting map.

Proof. We simply construct the connecting map, while the rest is easy to check directly. Given a class $[\alpha] \in H^n(C^*)$. Since $g: B^n \rightarrow C^n$ is surjective, $\alpha = g(\beta)$ for some $\beta \in B^n$. Consider $d\beta$. Since $g(d\beta) = d(g(\beta)) = d\alpha = 0$, there exists a unique element $\gamma \in A^{n+1}$ such that $f(\gamma) = d\beta$. Since $f(d\gamma) = d(f(\gamma)) = d^2\beta = 0$, we have $d\gamma = 0$, which implies $\gamma \in H^{n+1}(A^*)$. This can be illustrated by the following diagram

$$\begin{array}{ccccc} & & \beta & \longrightarrow & \alpha \\ & & \downarrow & & \downarrow \\ \gamma & \longrightarrow & d\beta & \longrightarrow & 0 \\ \downarrow & & \downarrow & & \\ d\gamma & \longrightarrow & 0 & & \end{array}$$

□

Let $f: M \rightarrow N$ be a smooth map of manifolds. Then f induces the pullback of differential forms $f^*: \Omega^*(N) \rightarrow \Omega^*(M)$. Moreover, this is indeed a cochain map because d commutes with the pullback. If f is a diffeomorphism, then $(f \circ f^{-1})^* = (f^{-1})^* \circ f^* = \mathbb{1}$ and $(f^{-1} \circ f)^* = f^* \circ (f^{-1})^* = \mathbb{1}$. In particular, diffeomorphism manifolds have isomorphism de Rham cohomologies.

Example 4.5. Let's consider the de Rham cohomology of $X = \mathbb{R}^2 \setminus \{P, Q\}$, where P, Q are distinct points. Without loss of generality, assume $P = (-1, 0)$ and $Q = (1, 0)$. The cochain complex writes

$$C^\infty(X) \xrightarrow{d} \{f dx + g dy \mid f, g \in C^\infty(X)\} \xrightarrow{d} \{\varphi dx \wedge dy \mid \varphi \in C^\infty\}.$$

$H_{\text{dR}}^0(X) = \text{Ker}(d: C^\infty \rightarrow \Omega^1(X))$. $df = 0$ implies that f is constant, so $H_{\text{dR}}^0(X) = \mathbb{R}$.

Next consider $H_{\text{dR}}^1(X)$. Let $\omega = f dx + g dy$ and we want to see that how far it is from an exact form. First

$$d\omega = \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y}\right) dx \wedge dy = 0,$$

so $\frac{\partial g}{\partial x} = \frac{\partial f}{\partial y}$. If $\omega = d\varphi$, then

$$\varphi(x) = \varphi(x_0) + \int_{x_0}^x \omega,$$

where the integral is taken along an arbitrary smooth path joining x_0, x in X . Conversely, if the integral of ω is indeed independent of the path, by multivariable calculus, φ is a well-defined smooth function such that $d\varphi = \omega$. As $d\omega = 0$, by Stokes' formula the integral is invariant up to free homotopy, so the problem lies in the two integrals

$$\lambda_1 \int_{C_1} \omega, \lambda_2 = \int_{C_2} \omega,$$

where C_1, C_2 are small circle around P, Q respectively. To get rid to this, we can consider forms

$$\eta_1 = \frac{1}{2\pi} \frac{(x+1)dy - ydx}{(x+1)^2 + y^2}, \eta_2 = \frac{1}{2\pi} \frac{(x-1)dy - ydx}{(x-1)^2 + y^2}.$$

These are all closed forms with

$$\int_{C_i} \eta_j = \delta_{ij}.$$

Thus we can modify ω by considering

$$\omega - \lambda_1 \eta_1 - \lambda_2 \eta_2.$$

This time the integral of $\omega - \lambda_1 \eta_1 - \lambda_2 \eta_2$ along arbitrary paths is well-defined, so it is exact. In other words,

$$[\omega] = \lambda_1 [\eta_1] + \lambda_2 [\eta_2].$$

It follows that $H_{\text{dR}}^1(X) = \mathbb{R}[\eta_1] \oplus \mathbb{R}[\eta_2] \simeq \mathbb{R}^2$.

It is discouraging that we found difficulty computing the last cohomology $H_{\text{dR}}^3(X)$.

5. MAYER-VIETORIS SEQUENCES

Computation for de Rham cohomology of plane punctured two points suggest we need to develop more techniques.

6. COMPACT SUPPORTED DE RHAM COHOMOLOGY