

A brief introduction to our PDG construction on LLVM

Input and Output

- Input: an LLVM module file (e.g. test.bc)
- Output: a .dot file which can be transformed into a .png file for visualization.
- For some large programs, it's difficult to generate a visualizable .png file but the PDG does exist in our in-memory data structures.

It's good to use a simple example to show our basic workflow first...

Example: original C

Assume we have a C program in file test.c as follows...

```
#include <stdio.h>

int CalcSum (int s, int i){
    return s + i;
}

int main(){
    int sum = 0 ;
    int i = 0;
    while(i < 10){
        sum = CalcSum(sum , i) ;
        i = i + 1;
    }
    return 0;
}
```

Example: C \rightarrow IR

We first compile it into an IR file – test.bc

```
; Function Attrs: nounwind uwtable
define i32 @CalcSum(i32 %s, i32 %i) #0
{
entry:
    %s.addr = alloca i32, align 4
    %i.addr = alloca i32, align 4
    store i32 %s, i32* %s.addr, align 4
    store i32 %i, i32* %i.addr, align 4
    %0 = load i32* %s.addr, align 4
    %1 = load i32* %i.addr, align 4
    %add = add nsw i32 %0, %1
    ret i32 %add
}

; Function Attrs: nounwind uwtable
define i32 @main() #0 {
entry:
    %retval = alloca i32, align 4
    %sum = alloca i32, align 4
    %i = alloca i32, align 4
    store i32 0, i32* %retval
    store i32 0, i32* %sum, align 4
    store i32 0, i32* %i, align 4
    br label %while.cond

while.cond:    ; preds = %while.body, %entry
    %0 = load i32* %i, align 4
    %cmp = icmp slt i32 %0, 10
    br i1 %cmp, label %while.body, label
    %while.end

while.body:    ; preds = %while.cond
    %1 = load i32* %sum, align 4
    %2 = load i32* %i, align 4
    %call = call i32 @CalcSum(i32 %1, i32 %2)
    store i32 %call, i32* %sum, align 4
    %3 = load i32* %i, align 4
    %add = add nsw i32 %3, 1
    store i32 %add, i32* %i, align 4
    br label %while.cond

while.end:    ; preds = %while.cond
    ret i32 0
}
```

Example: IR processing

- Our program will process the input LLVM module (test.bc) function by function, instruction by instruction, and create a “node” for each instruction, and insert this node into our PDG.
- we also create some dummy nodes for connecting the callers and callees, such as the “Entry” nodes for entering a callee function, and the nodes for parameter passing(parameter trees)
- When the module processing done, the PDG is already constructed in memory.

Example: .dot

We can also dump the in-memory PDG into a .dot file, which looks like this:

```
digraph "Program Dependency Graph for 'main' function" {
    label="Program Dependency Graph for 'main' function";

    Node0x2e3b590 [shape=record,label="{  %s.addr = alloca i32, align 4}"];
    Node0x2e3b590 -> Node0x2e3b600[style=dotted,label = "{DEF_USE}" ];
    Node0x2e3b590 -> Node0x2e3b670[style=dotted,label = "{DEF_USE}" ];
    Node0x2e3b600 [shape=record,label="{  store i32 %s, i32* %s.addr, align 4}"];
    Node0x2e3b600 -> Node0x2e3b670[style=dotted,label = "{RAW} s.addr"];
    Node0x2e3b670 [shape=record,label="{  %0 = load i32* %s.addr, align 4}"];
    Node0x2e3b670 -> Node0x2e3b890[style=dotted,label = "{DEF_USE}" ];

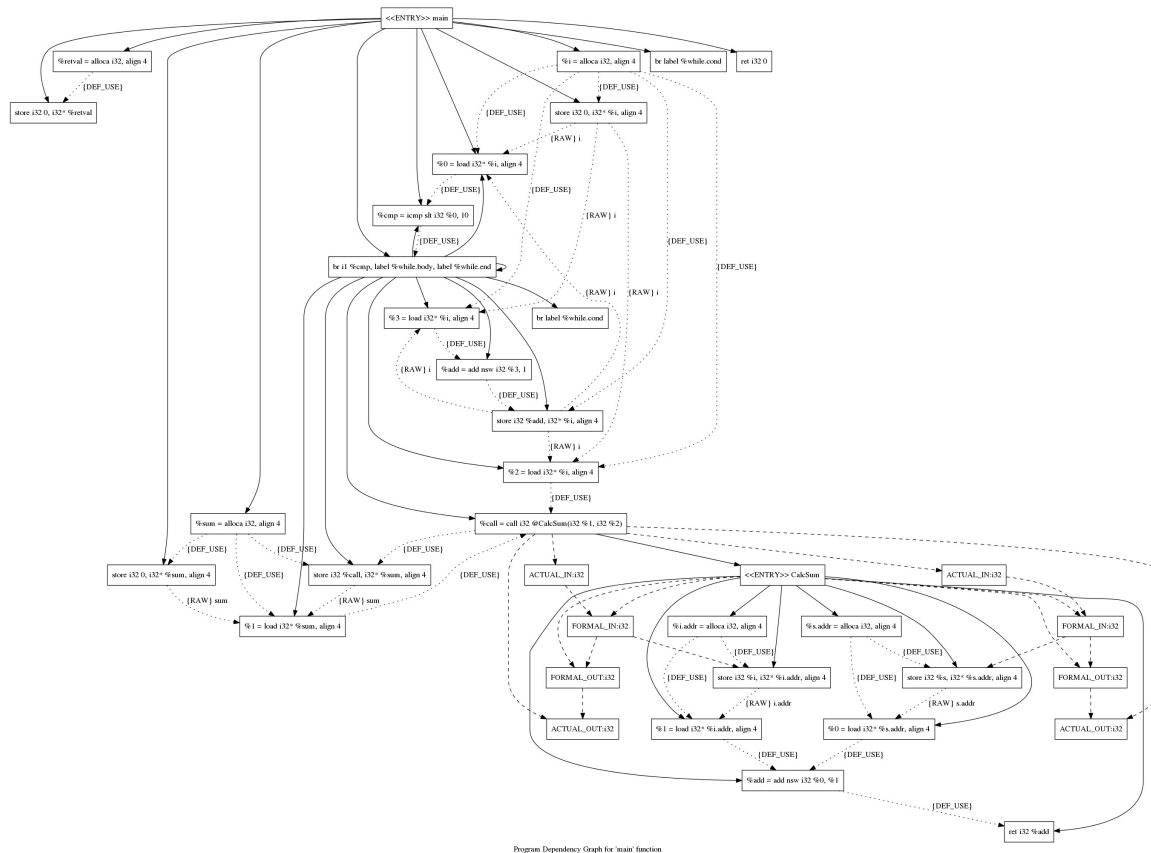
    ...

    Node0x2e40b00 -> Node0x2e3f580;
    Node0x2e40b00 -> Node0x2e40bf0;
    Node0x2e40b70 [shape=record,label="{  br label %while.cond}"];
    Node0x2e40bf0 [shape=record,label="{  ret i32 0}"];
}
```

pdgraph.dot

Example: visualizable PDG

Then use dot command to transform the .dot file into a .png file as follows for visualization



pdg.png

Control Dependency: Algorithm

From Ferrante[1] et al. the algorithm for obtaining control dependency information is as follows:

- **Step 1:** Let edge set S consists of all edges (A,B) in the CFG $(A \rightarrow B)$ such that B does not post-dominate A .
- **Step 2:** Examine each pair (A,B) in S . Let L denote the least common ancestor of A and B in the post-dominator tree. L can be two things (see the paper for proofs)
 - Case 1. $L = \text{parent of } A$. All nodes in the post-dominator tree on the path from L to B , including B but not L , should be made control dependent on A .
 - Case 2. $L = A$. All nodes in the post-dominator tree on the path from A to B , including A and B , should be made control dependent on A . (This case captures loop dependence.)

Control Dependency: Implementation

- Constructing CDG is easy since LLVM already has a built-in pass to compute the PostDominatorTree
- The Dependencies established by using PostDominatorTree pass are among basicblocks, but it's quite easy to convert the CDG from the basicblock-level to instruction-level (see function `addDependency()` in `ControlDependencies.cpp`).
- In our code, the ultimate control dependence graph for each llvm function is stored in pointer `ControlDepGraph *CDG`

Data Dependency: Intra-procedural

- There are two kinds of intra-procedural data dependences in our code.
 - Definition-use dependence – this represents the data dependency between temporaries(**register** values).
 - Flow dependence – this represents the read-after-write (RAW) **memory** dependency between StoreInst and LoadInst.
- One thing needs to be stated clearly is **we only compute the flow dependence (true data dependence)**. The other two kinds of data dependences(anti-, output-) are not in our consideration.
- It's easy to detect a DD between register values because LLVM uses the SSA form. So, in order to detect a DD, it suffices to find all operands in an instruction and add a dependency between it and the instruction that defines the operand.

Data Dependency: Intra-procedural

- For **flow dependencies**, since they only exist between Store and Load instructions, our algorithm for computing all of intra-procedural flow dependencies is as follows:
 - Step 1: Check each instruction in F, if it is a LoadInst, do Step 2; otherwise, continue to check the next.
 - Step 2: For LoadInst LI, check each StoreInst SI in F, if LI and SI **must or may** access the same memory location, SI->LI is a flow dependence. The AliasAnalysis pass is required here, now we are using DSA analysis to do this, see <https://github.com/jtcriswell/llvm-dsa>
- Both def-use and flow dependences will be stored in one DDG in the end (DataDepGraph *DDG).

Data Dependency: Inter-procedural

- The inter-procedural data flow fully depends on the parameter passing. So, the hardest part is how to represent function parameters. In our framework, each parameter is represented by a set of **parameter trees**, which includes 4 tree types: actual-in tree, actual-out tree, formal-in tree and formal-out tree.
- The actual-in and actual-out trees represent the flow of the actual parameters (arguments) to call temporaries and from return temporaries respectively. The formal-in and formal-out trees are the callee analogs of actual-in/out trees.
- A parameter tree for atomic data types (e.g. int, float, char...) will shrink to a single parameter node.

Data Dependency: parameter trees

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- We greatly benefit from the work by Susan Horwitz et al [1]. and Jürgen Graf [2], you can read the papers below for more details.

[1]<https://courses.cs.washington.edu/courses/cse590md/01sp/w2l1.pdf> 13

[2]<http://pp.info.uni-karlsruhe.de/uploads/publikationen/graf10scam.pdf>

Parameter Trees: example

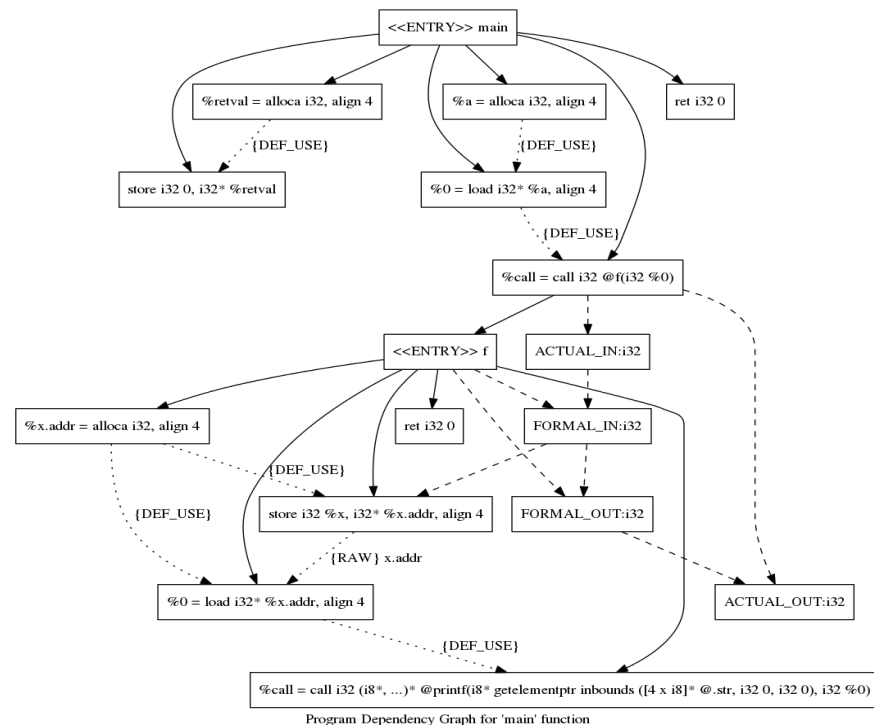
Still, let's start with the simplest example to show how parameter trees look like. In the following example, the only parameter is an integer.

For all atomic (built-in) C data types (e.g int, float, char...), a parameter tree will shrink to a single node. The dependence from Formal-in node to the StoreInst inside callee f represents the inter-procedural DD.

```
#include <stdio.h>

int f(int x){
    printf("%d\n",x);
    return 0;
}

int main(){
    int a;
    f(a);
    return 0;
}
```



Parameter Trees: example

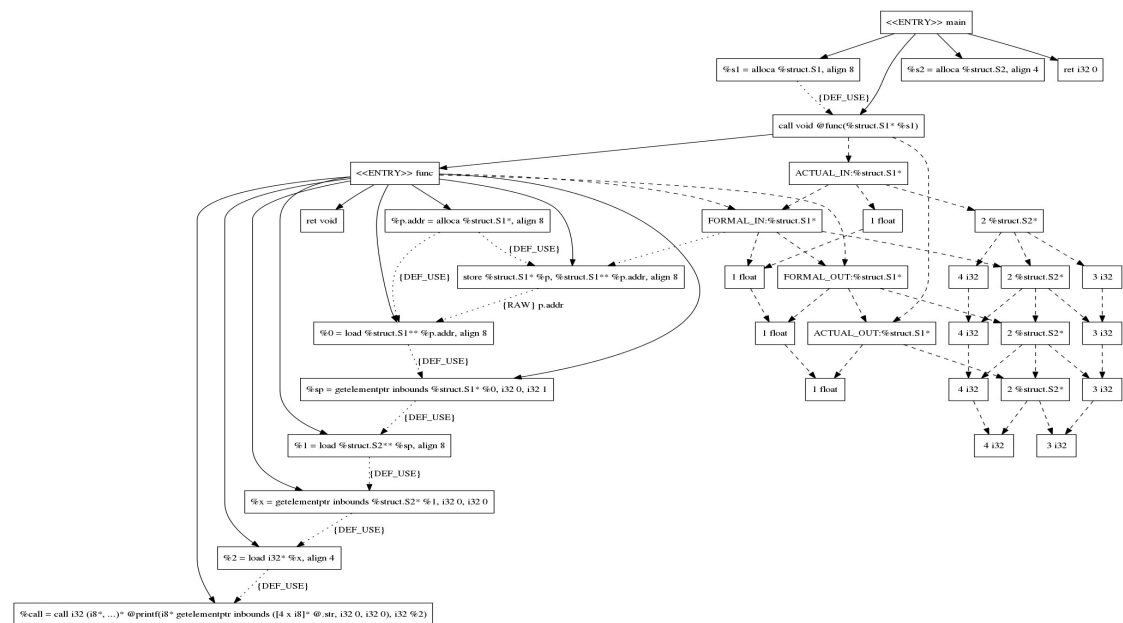
Now, look at an example with struct pointer parameter. As you can see, parameter &si is represented as four parameter trees. The root of each tree is [%struct *S1], each root has two leafs: [float] and [%Struct *S2](by static analysis we can just use types instead of value names to label), leaf [%Struct *S2] has two leafs [i32][i32]. The default data flow for each parameter field among parameter trees is [actual-in → formal-in → formal-out → actual-out] (see Susan Horwitz's paper for more detailed explanation).

```
#include<stdio.h>
typedef struct{
    int x;
    int y;
}S2;

typedef struct{
    float f;
    S2 *sp;
}S1;

void func(S1 *p){
    printf("%d\n",p->sp->x);
}

int main(){
    S1 s1;
    S2 s2;
    func(&s1);
}
```



The main modules in our code

- **DependencyNode**
 - this template defines all low level common things about dependence graph such as node representations and operations (e.g. add dependence from node A to node B, check whether node A depends on B or not).
- For example, the low level interaction between dependence nodes are implemented by the following data structures:

```
typedef std::pair<DependencyNode<NodeT>*, Type> DependencyLink;  
typedef std::vector<DependencyLink> DependencyLinkList;
```

(see Dependencies.h/.cpp)

The main modules in our code

- **ControlDependenceGraph**

this function pass defines ControlDependenceGraph class and generates control dependence graph. Pass PostDominatorTree will be called inside.

- **DataDependenceGraph**

this function pass defines DataDependenceGraph class and generates data dependence graph.

- **ProgramDependenceGraph**

this pass calls ControlDependenceGraph and DataDependenceGraph to generate an ultimate program dependence graph.

The main modules in our code

- DepPrinter

This module generates the .dot files, write the in-memory data into .dot files based on the `llvm::DOTGraphTraits<Ty> Struct` template.

(see DepPrinter.cpp)

- FlowDependenceAnalysis

This pass is called by DataDependenceGraph module to process the Load/Store instructions. The **DSA** analysis will be called inside.

(see FlowDependenceAnalysis.cpp)

- Now it's another good time to show how these modules work, for example, a data dependence graph(DDG) can be constructed in 3 steps...

An workflow example

- **Step 1:** Initialization, use `DataDependenceGraph` to analyze the input IR file and put all instructions into a static data structure called `instMap`.

```
static std::map<const llvm::Instruction*,  
InstructionWrapper*> instMap;
```

- **Step 2:** For each instruction, check whether it is a load instruction or not. If yes, call `FlowDependenceAnalysis` to find the related flow dependences, otherwise reiterate the whole function to detect all def-use data dependences.

An workflow example

- **Step 3:** A `DataDependenceGraph*` pointer will be transferred into the `DepPrinter` module and generate a `ddg.dot` file(ddg graph description).
- The workflow for CDG generation is quite similar. If we want to generate PDG instead of CDG and DDG separately, just call `ProgramDependenceGraph` pass to generate PDG at the same time.