Type Encoding/Decoding rules: from C to Protocol Buffer

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Abstract

Type conversion between C and protocol buffer is an important issue in our project. When the separation is done and the RPC tool begins working, we must automatically restore all the arguments for each RPC function in the receiver process, which means the function parameter types need to be transmitted between two processes fully and exactly. Unfortunately, the type system that protocol buffer supports is quite weak. To make our project automatically run in the end, we have to design a type conversion protocol to let protocol buffer automatically convert some advanced C types(e.g. pointer) into protocol buffer types.

1 Background

We use gRPC, which is fully based on google protocol buffer, to deal with RPC issues in our project. In gRPC, a C type must be packed to protocol buffer "message" type in a .proto file(IDL file) for further transmission. For example, if you have a C function int foo(int x) which needs to be called remotely, then in your .proto file, the argument type int can be packed in protocol buffer as follows:

Next, protocol buffer will automatically generate a group of read/write APIs for each message. Here is an API for x's value assignment:

```
void set_x(::google::protobuf::int32 value);
and an API for getting the value of x:
   inline ::google::protobuf::int32 M::x() const {
     return x_;
}
```

Here is a more complex C-protobuf type conversion sample:

```
typedef struct{
  int x;
  int y;
}Point;

typedef struct{
  Point center;
  double radius;
}Circle;

message Circle{
  message Point{
    int64 x=1;
    int64 y=2;
  }
  double radius=1;
}
```

Our project can automatically finish this conversion for all scalar types and simple composite types as "Circle". However, when parameter types become more and more complex, especially for those structures with multi-level pointers, generating a correct .proto file automatically as before will be a real challenge. To achieve this goal, a possible way is designing a type-conversion protocol to make our project work more intelligently. Simply speaking, for any C type input, first we use such a protocol to convert it into an integer array(encoding), and then construct the "message" type in .proto. On the receiver side, we do array parsing to restore the original C types(decoding) instead of parsing the complex .proto file.

2 Type system and encoding/decoding rules

In this draft we only use a small subset of C type system to show how the encoding/decoding idea works. Here is how our toy type system looks like:

To encode/decode such a type system, first of all, we can set up a basic buffer block of 6 elements, and the meaning of each element is as follows:

Index	Name	Value	Description
0	bufferLength	$n \in \mathbb{N}$	The buffer length used for representing the current
			type
1	isPointerTy	1/0	If this is a pointer type, assign 1; otherwise assign 0.
2	isStructTy	1/0	If this is a struct type, assign 1; otherwise assign 0.
3	isFloatTy	1/0	If this is a float type, assign 1; otherwise assign 0.
4	isIntTy	1/0	If this is a int type, assign 1; otherwise assign 0.
5	fieldNum	$n \in \mathbb{N}$	If the current type is a struct, fieldNum = number
			of fields in this struct; otherwise, leave it to zero

Once we have such a basic block, we can easily construct the encoding/decoding rules as follows:

```
Definition encode: type t -> int[]
  match t with
  | int -> [6][0][0][0][1][0]
  | float -> [6][0][0][1][0][0]
  | t* -> [6 + len(encode(t))][1][0][0][0][0]::encode(t)
  | struct(t1;...;tn) ->
    [6 + len(encode(t1) + ... +len(encode(tn))))][0][1][0][n]
    ::encode(t1)::encode(t2)::..::encode(tn)
  end.
Definition decode: int[] list[0,1,...,n] -> type
 match list [0,1,\ldots,n] with
  | [6][0][0][1][0] -> int
  | [6][0][0][1][0][0] -> float
  | [len][1][0][0][0]::list[6,...,n] -> {decode(list[6,...,n])}*
  | [len][0][1][0][0][n]::list[6,...,n] ->
      decode(list[6,...,6+list[6]-1]);
      decode(list[6+list[6],...,6+list[6+list[6]]-1]));
      decode(list[6+list[6+...]],...,n);
   }
  end.
```