

16 – bit, 1024x1280
Max pixel value: 60000
Min pixel value: 4000

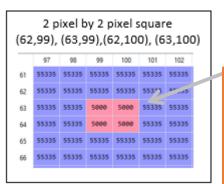
Minimum intensity:

5 by 5 square

18 by 18 square

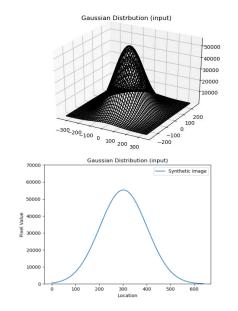
2 by 2 square

What is the minimum difference in pixel value that algorithms can detect?



pixel value: 4002 5 by 5 square 4 by 4 square 20 by 20 square pixel value : 4004 6 by 6 square 5 by 5 square 22 by 22 square pixel value: 4006 5 by 5 square 8 by 8 square 24 by 24 square pixel value: 4008 5 by 5 square 10 by 10 square 26 by 26 square pixel value: 4010 5 by 5 square 12 by 12 square 28 by 28 square pixel value: 4012 5 by 5 square 14 by 14 square 30 by 30 square pixel value: 4014 5 by 5 square 16 by 16 square 32 by 32 square pixel value : 4016

Gaussian distribution



Global contrast enhancement:

Test if it increases global contrast.



Result of global contrast enhancement

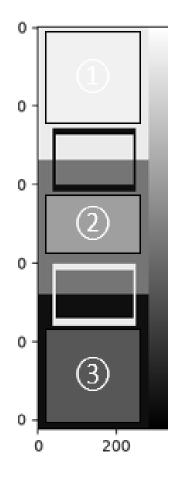
Size of objects:

Test if the size of objects change

Result of Synthetic Targets

	Target 1				Target 2				
	Uniformity	Edge Enhancement	Gradient (brightness)	Frequency limit	Random noise (Entropy)	Size of object	Noticeable pixel value difference	Gaussian distribution	Global contrast enhancement
CLAHE	Good	No	Brighter	Less than 2 pixel/cycle	Increased	Not changed	Less than 2- pixel value	Failed	Yes
Image pyramid	Good	Yes	Brighter	Less than 2pixel/cy	Decreased	Not changed	Less than 2- pixel value	Passed	No
Multiscale Morphology	Good	No	Not changed	Less than 2 pixel	Decreased	Not changed	Less than 2- pixel value	Passed	No

- CLAHE increased global contrast.
- Image pyramid increased local contrast as well as edge enhancement.
- Multiscale Morphology increased contrast based on the size of the object within the filters used in the algorithm. (3 by 3, 5 by 5, 7 by 7, and 9 by 9 in our algorithm.)



Uniformity test

Standard deviation and mean of selected areas

1

Rectangular area under the white background

Mean pixel value: 60000 Standard deviation: 0

2

Rectangular area under the gray background

Mean pixel value: 30000 Standard deviation: 0

3

Rectangular area under the black background

Mean pixel value: 4000 Standard deviation: 0

	Area 1 (white)		Area 2 (gray)		Area 3 (black)	
	Mean	STD	Mean	STD	Mean	STD
Input Target	60000	0	30000	0	4000	0
CLAHE	60000	0	30000	0	4000	0
Image pyramid	65535	0	60000	0	8000	0
Multiscale Morphology	60000	0	30000	0	4000	0

All three algorithms produced a uniform area.

Edge enhancement

Intensity profile from A to B (from white to gray) and C to D (from gray to black)

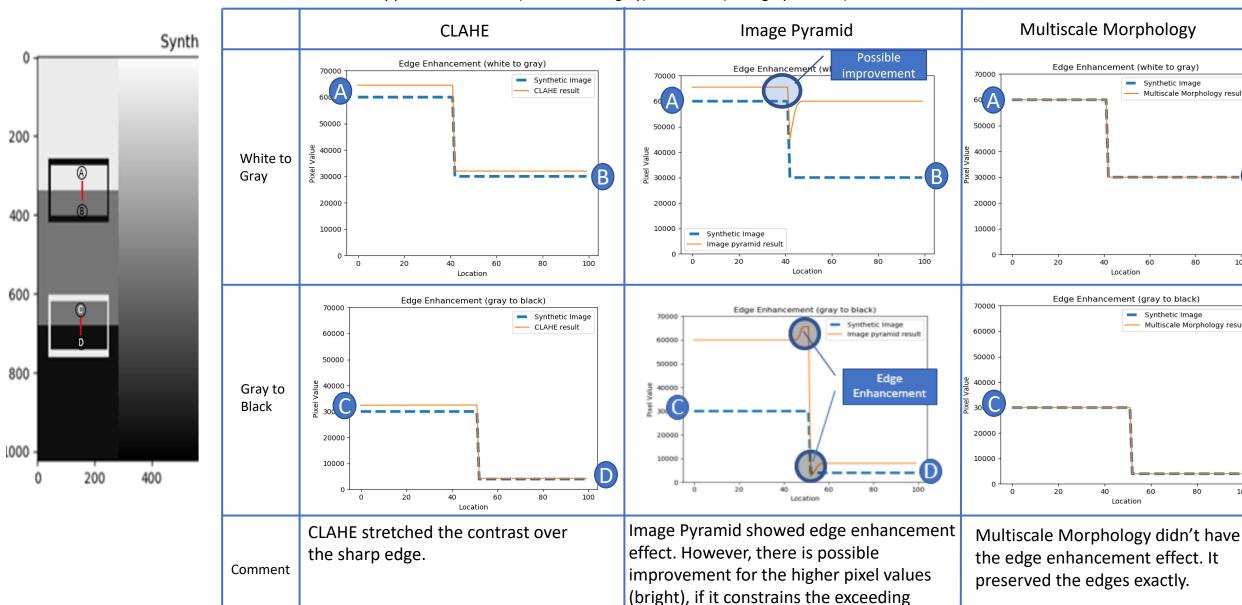
Multiscale Morphology result

Multiscale Morphology result

80

100

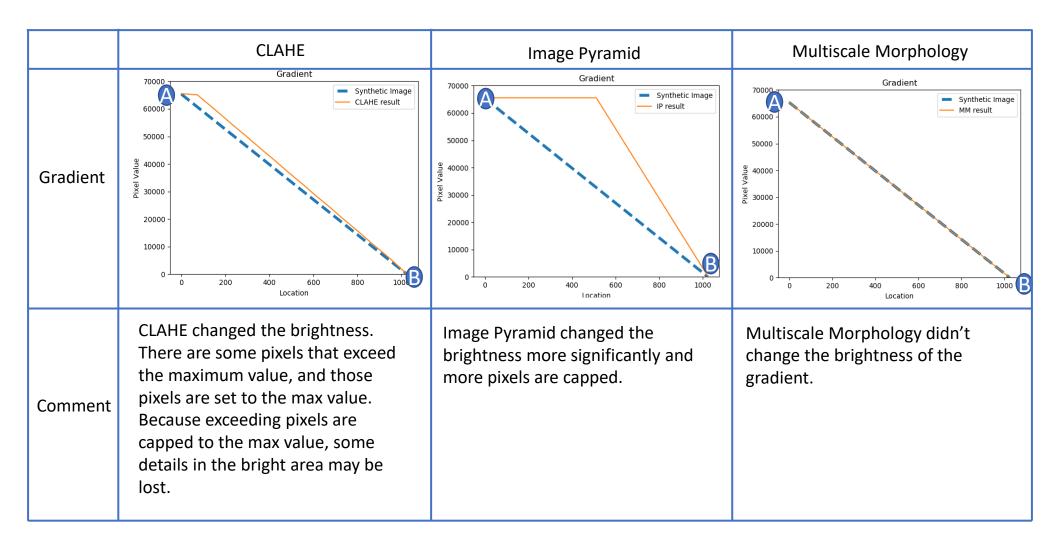
60

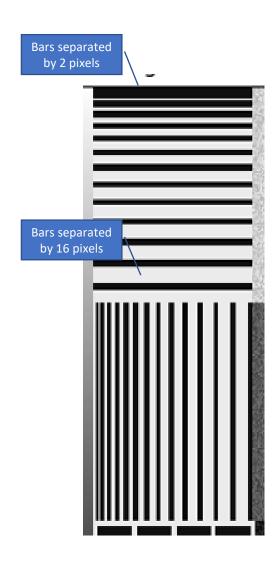


pixels under the maximum pixel value.

600

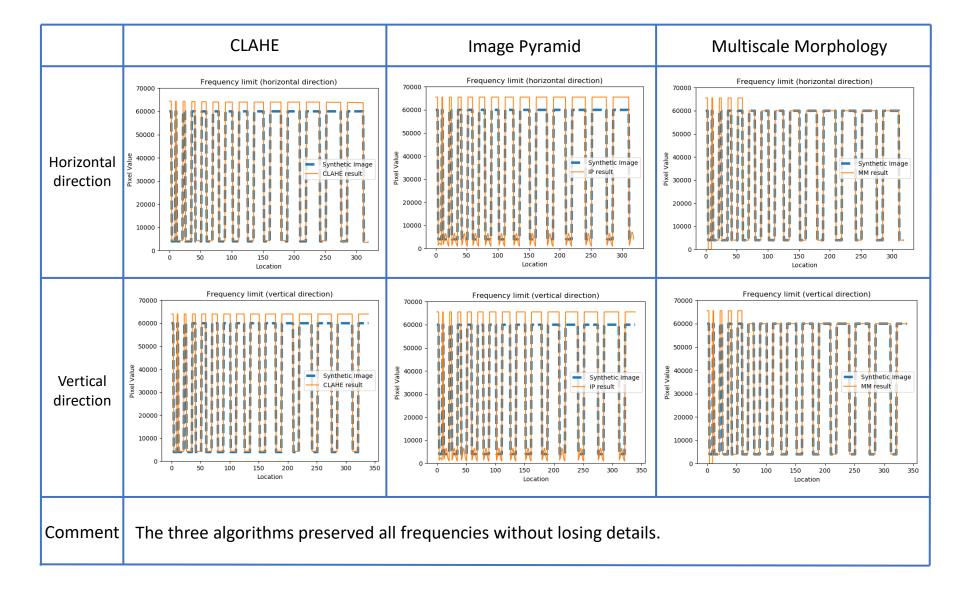
Gradient Intensity profile from A to B (from white to black)





Frequency limit

Each bar is separated by a distance from 2 pixels to 16 pixels.





Random noise test

- Entropy was used to measure the random noise.
- Entropy has the maximum value for the histogram with uniform distribution.

 (Julio César Mello Román, Entropy and Contrast Enhancement of Infrared Thermal Images Using the Multiscale Top-Hat Transform, 2019)

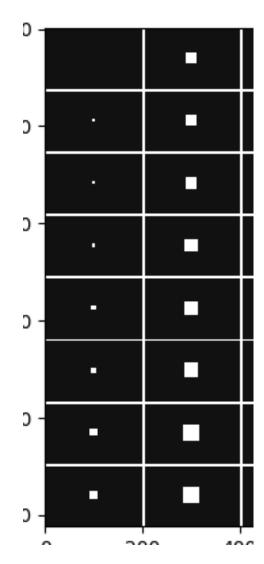
	Area A (Black background)	Area B (White background)
Input Target	0.96	0.96
CLAHE	0.97	0.98
Image pyramid	0.51	0.52
Multiscale Morphology	0.31	0.31

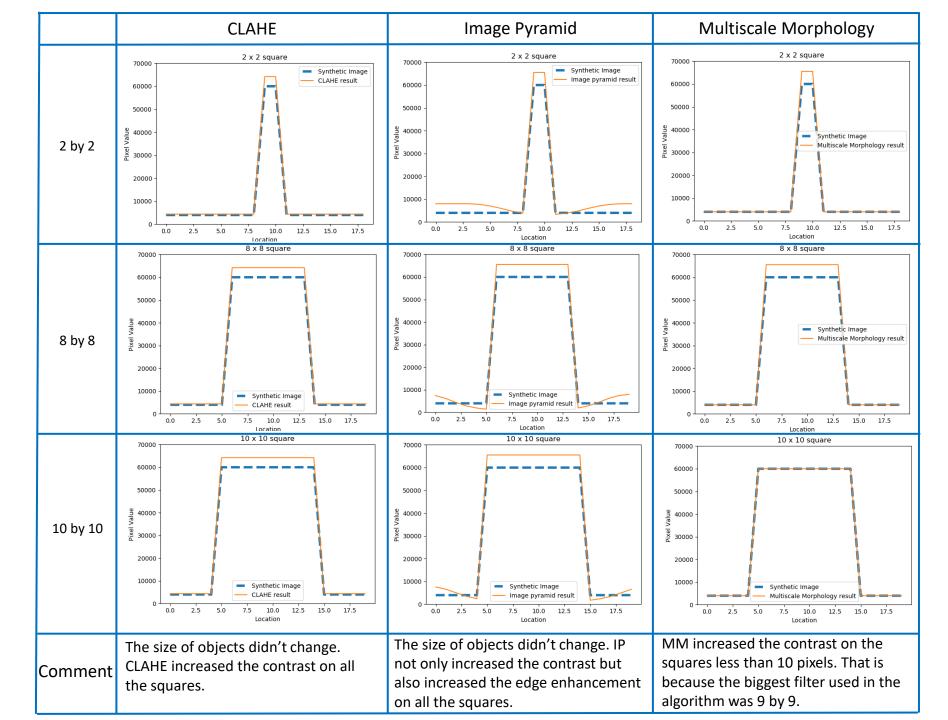
The entropy of the results were lower than entropy of the target (image pyramid and multiscale morphology). The random noise is reduced, and the noise turned into the background.

The entropy of CLAHE is high because it distributed random noise over the image while it expanded the global contrast.

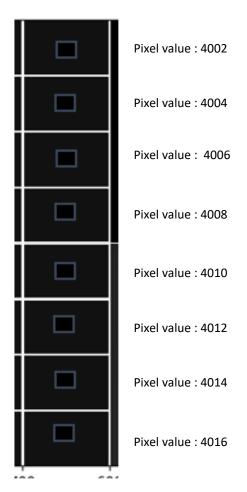
Size of objects:

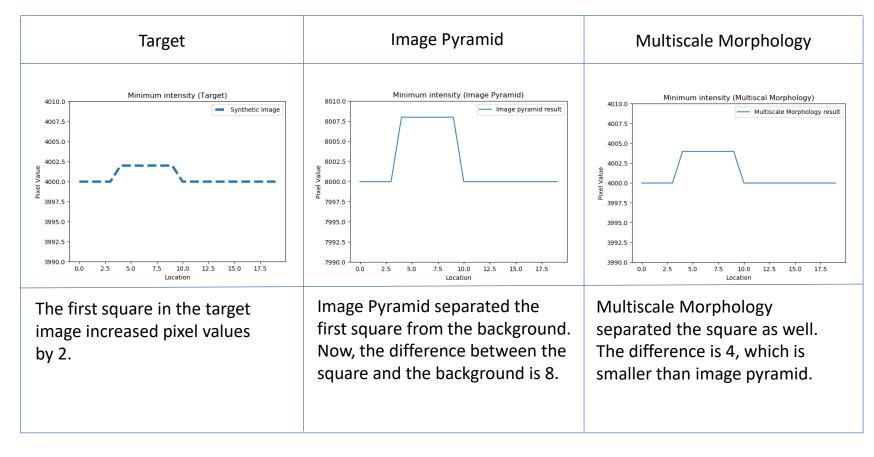
Tested 16 squares (2-pixel square to 16-pixel square)





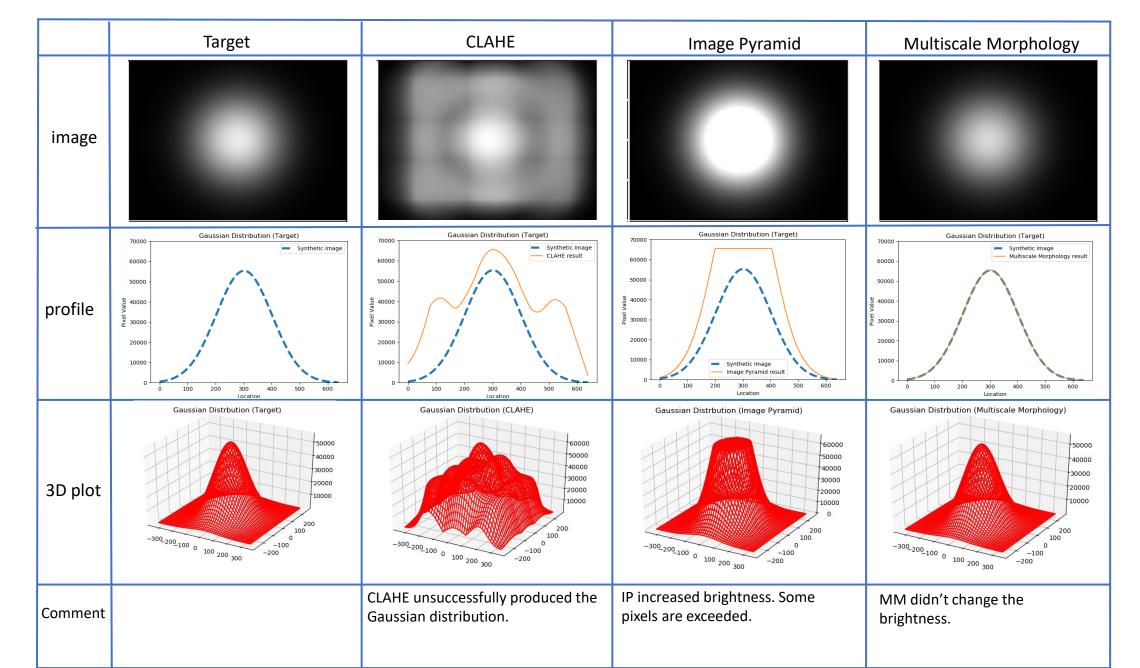
5-pixel squares with pixel value increased by 2. Background pixel value is 4000.





Algorithms successfully identified an object and a background when the object only had a 2-pixel value difference.

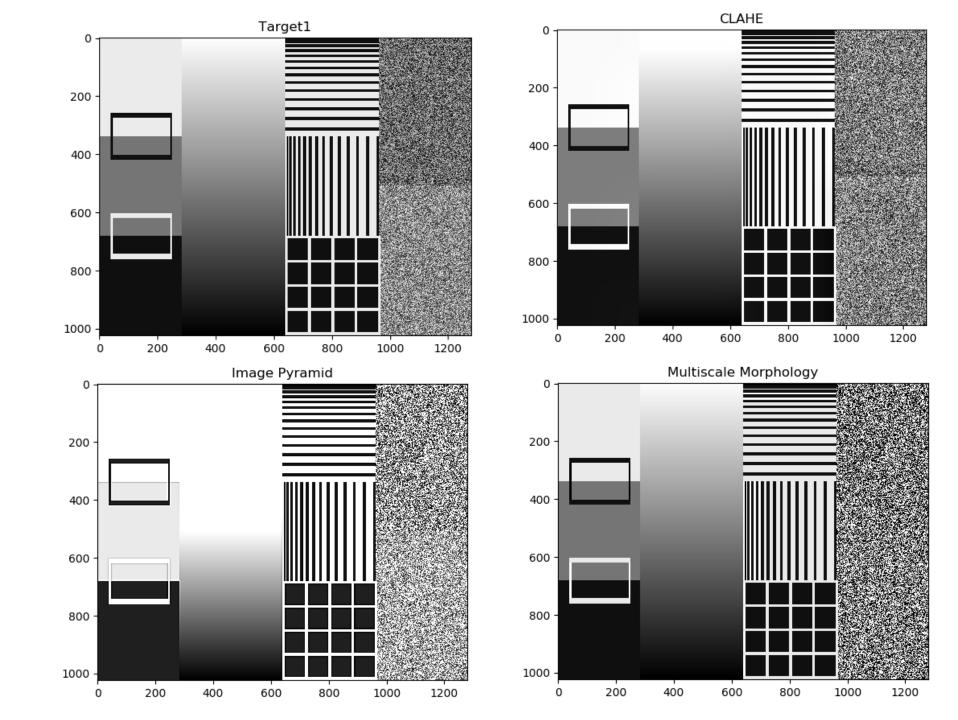
Gaussian distribution



Global contrast enhancement



Result of Synthetic Target1



Result of Synthetic Target2

