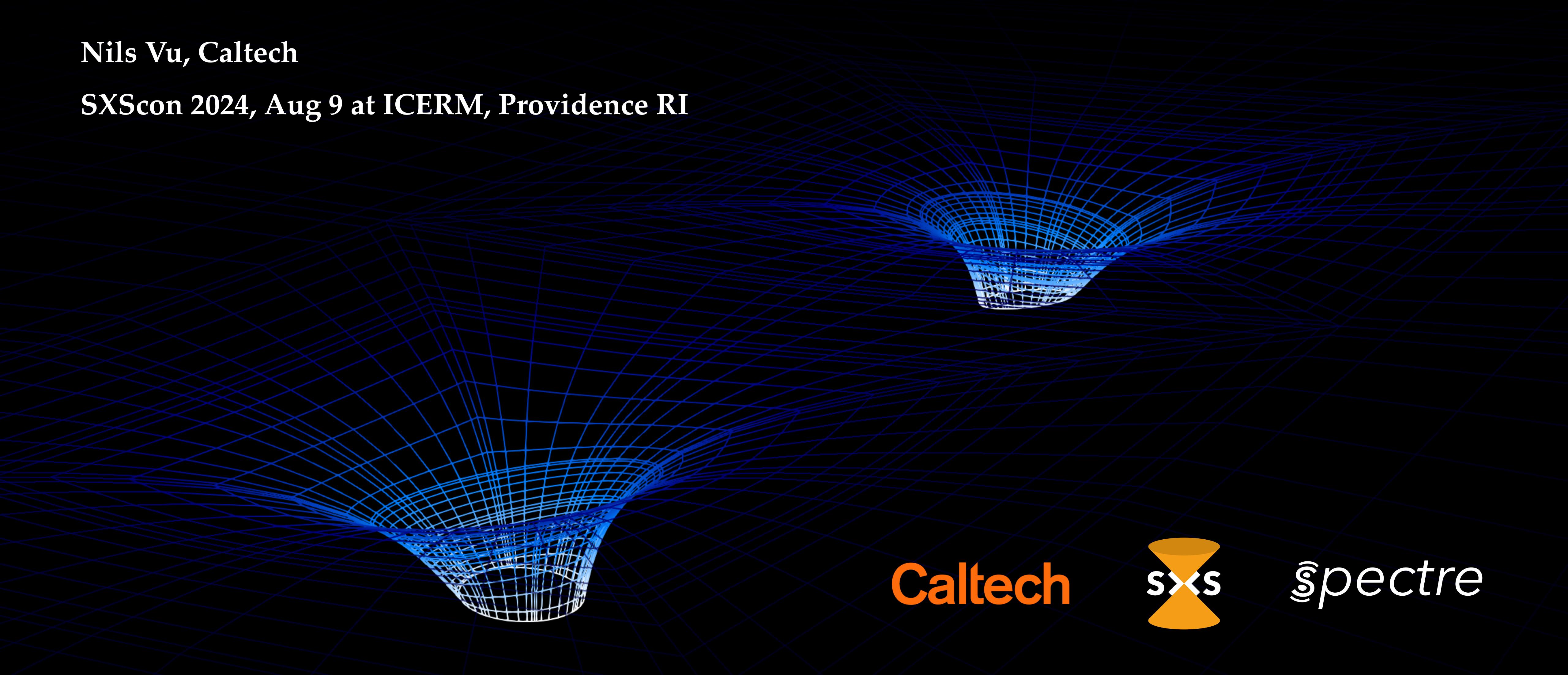


# The *spectre* initial data solver

Nils Vu, Caltech

SXScon 2024, Aug 9 at ICERM, Providence RI



Caltech



*spectre*

# Recap: XCTS initial data

Two black holes in orbit

Einstein constraint equations: 5 coupled, nonlinear, elliptic PDEs

$$\bar{\nabla}^2 \psi = \frac{1}{8} \psi \bar{R} + \frac{1}{12} \psi^5 K^2 - \frac{1}{8} \psi^{-7} \bar{A}_{ij} \bar{A}^{ij} - 2\pi \psi^5 \rho$$

$$\begin{aligned} \bar{\nabla}^2 (\alpha \psi) = \alpha \psi & \left( \frac{7}{8} \psi^{-8} \bar{A}_{ij} \bar{A}^{ij} + \frac{5}{12} \psi^4 K^2 + \frac{1}{8} \bar{R} \right. \\ & \left. + 2\pi \psi^4 (\rho + 2S) \right) - \psi^5 \partial_t K + \psi^5 \beta^i \bar{\nabla}_i K \end{aligned}$$

$$\begin{aligned} \bar{\nabla}_i (\bar{L}\beta)^{ij} = & (\bar{L}\beta)^{ij} \bar{\nabla}_i \ln(\bar{\alpha}) + \bar{\alpha} \bar{\nabla}_i (\bar{\alpha}^{-1} \bar{u}^{ij}) \\ & + \frac{4}{3} \bar{\alpha} \psi^6 \bar{\nabla}^j K + 16\pi \bar{\alpha} \psi^{10} S^j \end{aligned}$$

Excision: nonlinear boundary conditions represent black holes

$$\begin{aligned} n^k \partial_k \psi = & \frac{\psi^3}{8\alpha} n_i n_j (\bar{L}\beta)^{ij} \\ & - \frac{\psi}{4} \bar{m}^{ij} \bar{\nabla}_i n_j - \frac{1}{6} K \psi^3 \\ \beta^i = & -\frac{\alpha}{\psi^2} n^i \end{aligned}$$

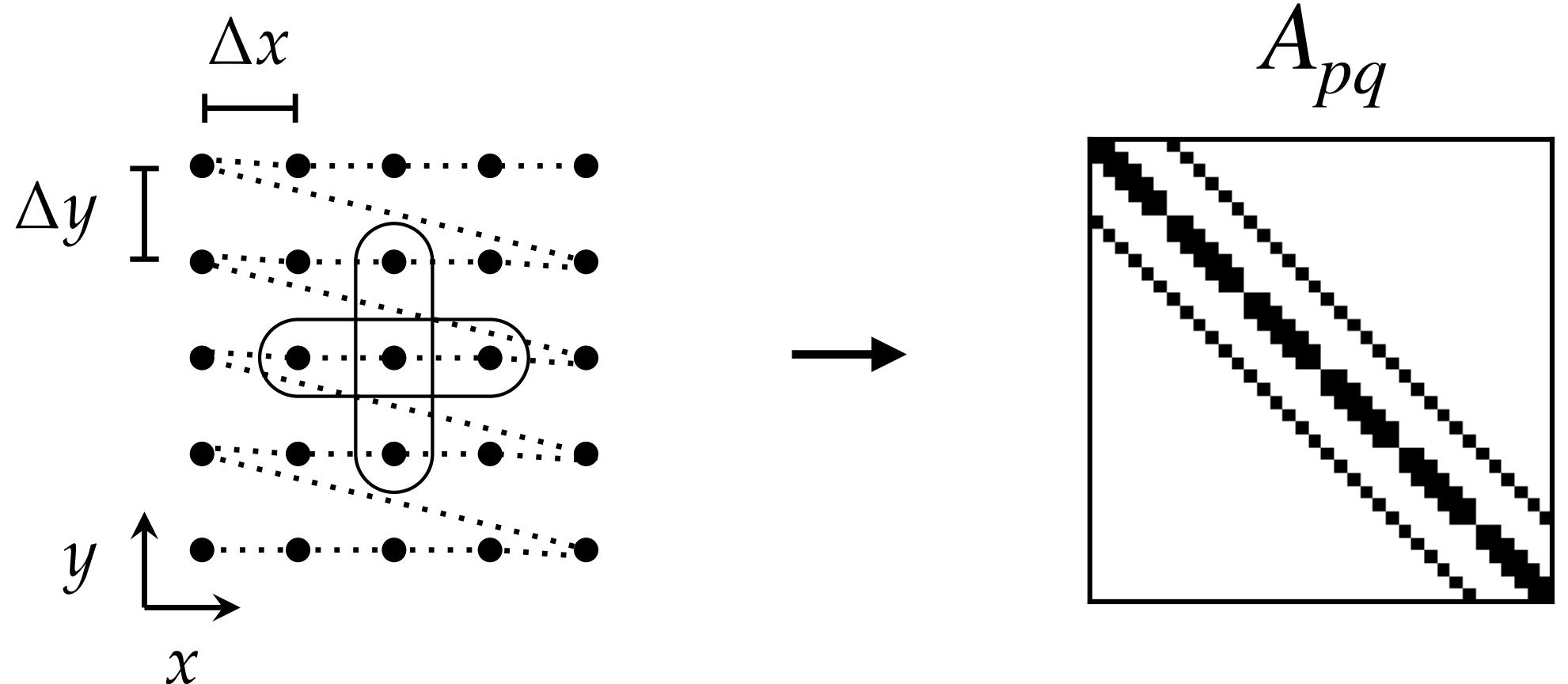
# Solving elliptic equations

Discretize and invert!

1. Discretize:  $-\Delta u = f(x) \rightarrow A_{pq} u_q = b_p$

Example: 2nd order finite difference stencil in 2D

$$-\frac{u_{(p_x+1,p_y)} - 2u_p + u_{(p_x-1,p_y)}}{\Delta x^2} - \frac{u_{(p_x,p_y+1)} - 2u_p + u_{(p_x,p_y-1)}}{\Delta y^2} = f_p$$



2. Invert matrix:  $u_p = A_{pq}^{-1} b_q$

# Solving elliptic equations

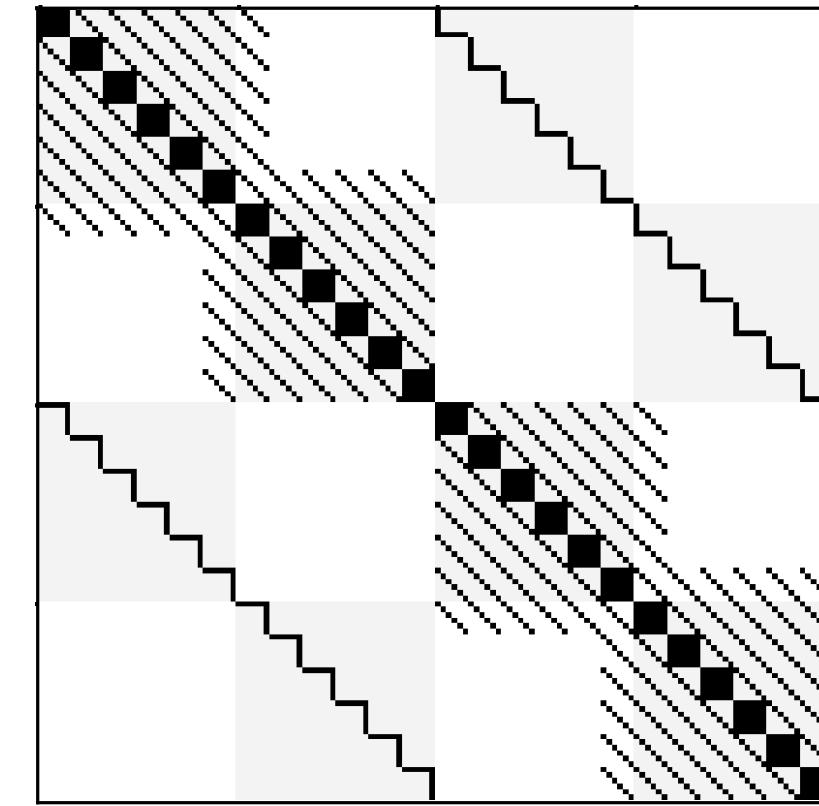
Discretize and invert!

1. Discretize:  $-\Delta u = f(x) \rightarrow A_{pq} u_q = b_p$

*Finite difference, spectral, discontinuous Galerkin, ...*

2. Invert matrix:  $u_p = A_{pq}^{-1} b_q$

*Direct, iterative, hyperbolic relaxation, ...*



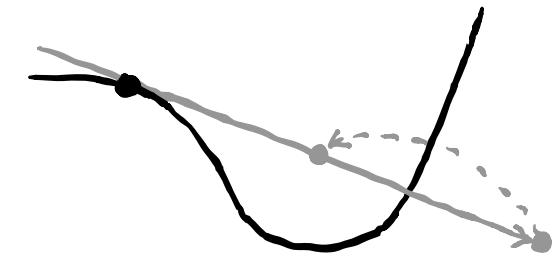
- **In parallel on supercomputers!**

- NV & H. Pfeiffer (2022), *Unified discontinuous Galerkin scheme for a large class of elliptic equations*, Phys. Rev. D **105**, 024034, [arXiv:2108.05826](https://arxiv.org/abs/2108.05826)
- NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D **105**, 084027, [arXiv:2111.06767](https://arxiv.org/abs/2111.06767)

# The spectre elliptic solver

► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D **105**, 084027, [arXiv:2111.06767](https://arxiv.org/abs/2111.06767)

Newton-Raphson  
nonlinear solver

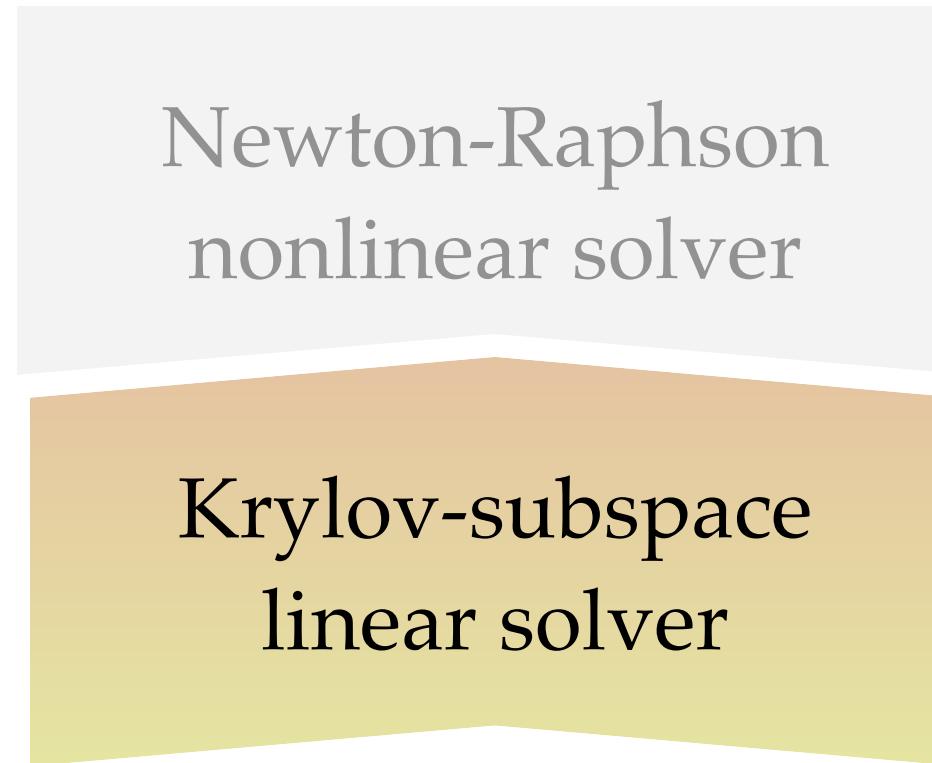


- Repeatedly solve linearization:
- Line-search globalization to avoid overshoots

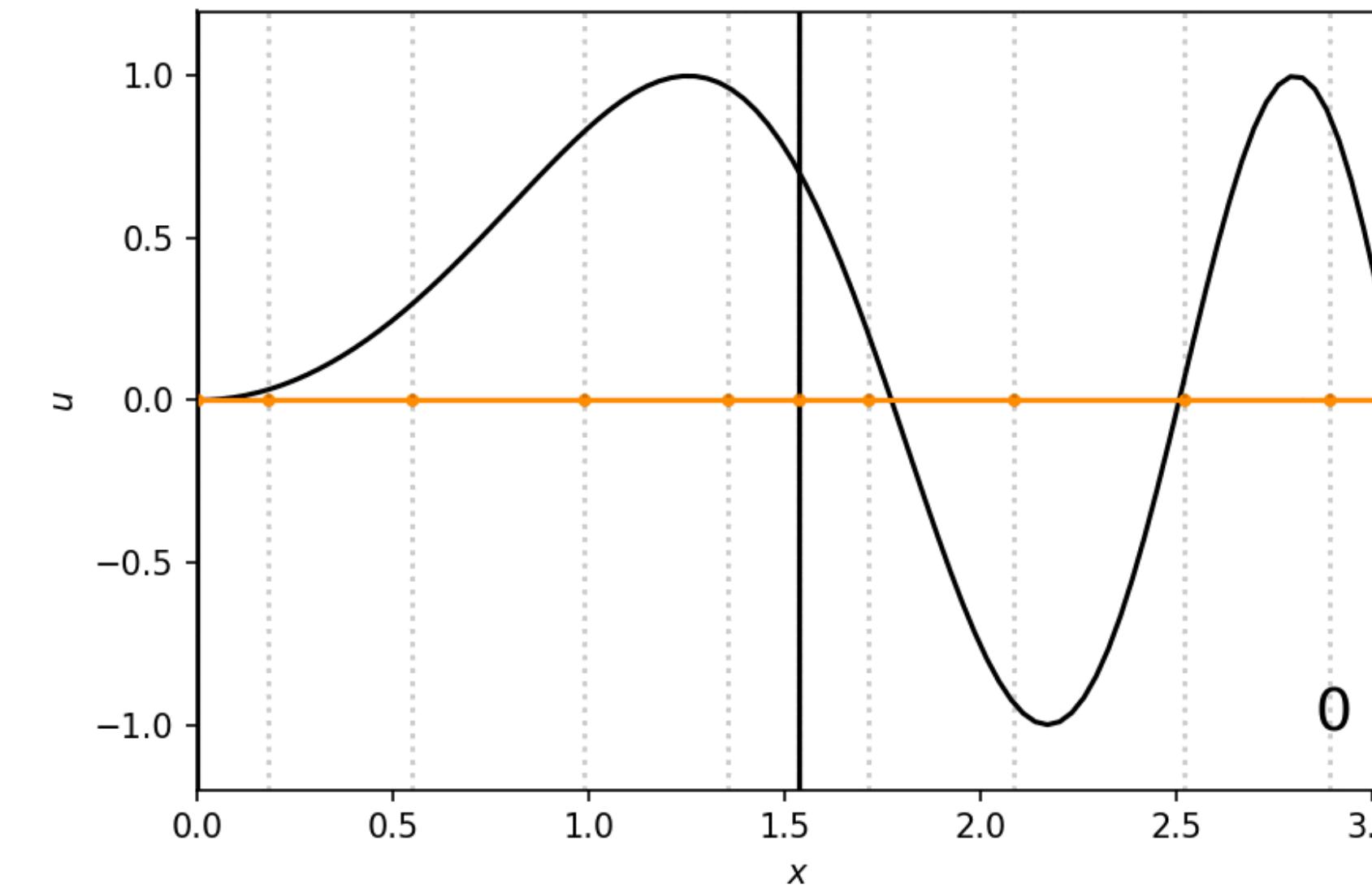
$$\frac{\delta A}{\delta \underline{u}}(\underline{u}) \Delta \underline{u} = \underline{b} - A(\underline{u})$$

# The spectre elliptic solver

► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D 105, 084027, arXiv:2111.06767

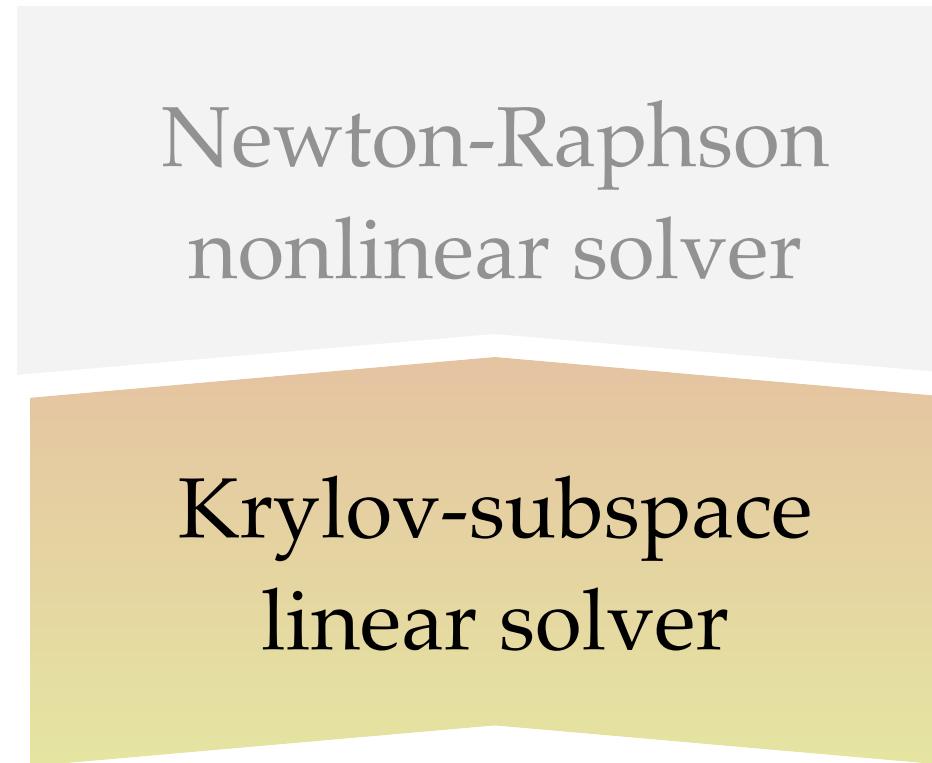


- GMRES or Conjugate Gradients
- Builds up a basis of  $K_n = \text{span}\{b, Ab, \dots, A^{n-1}b\}$
- Struggles with large-scale modes

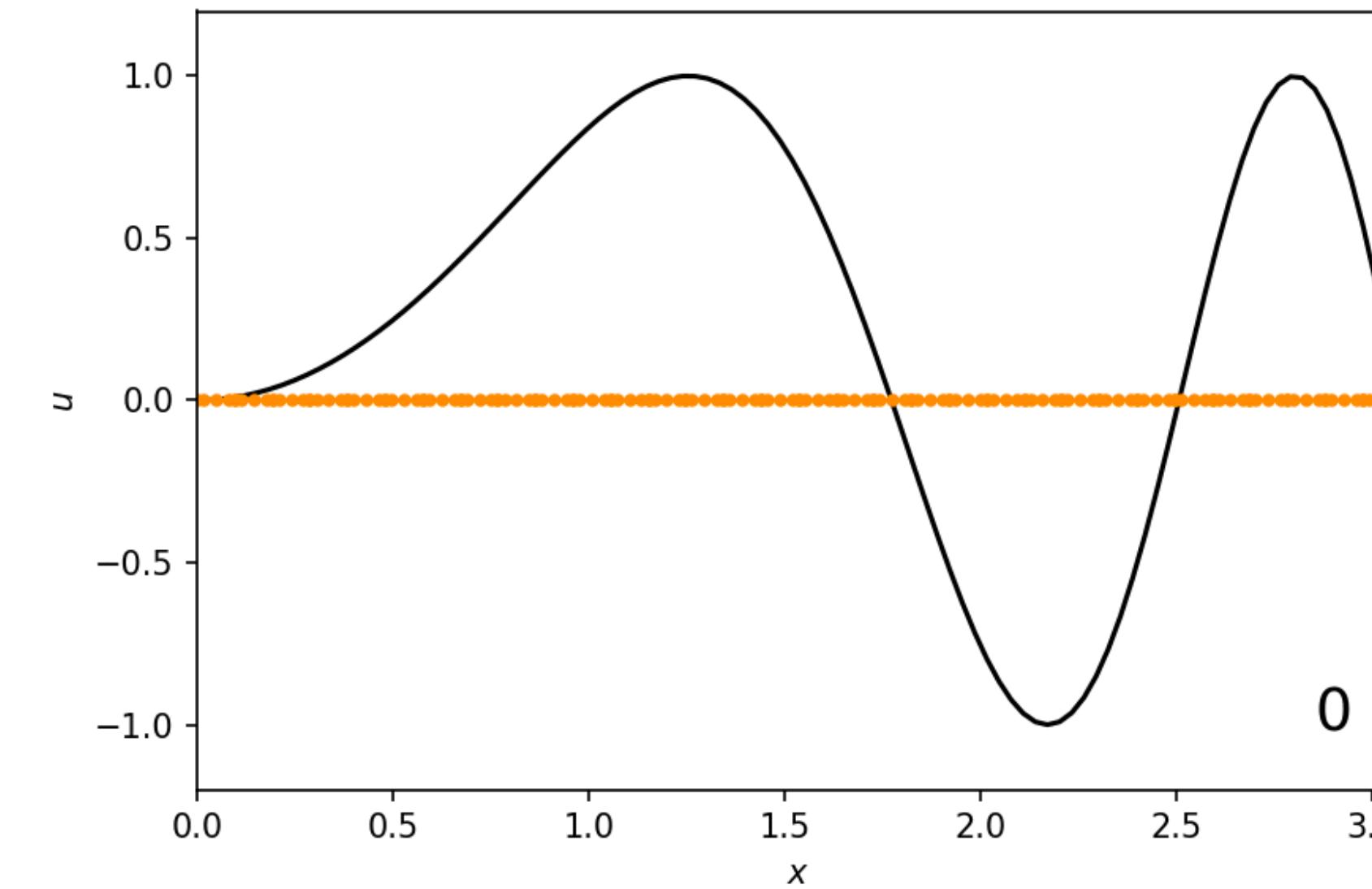


# The spectre elliptic solver

► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D 105, 084027, arXiv:2111.06767

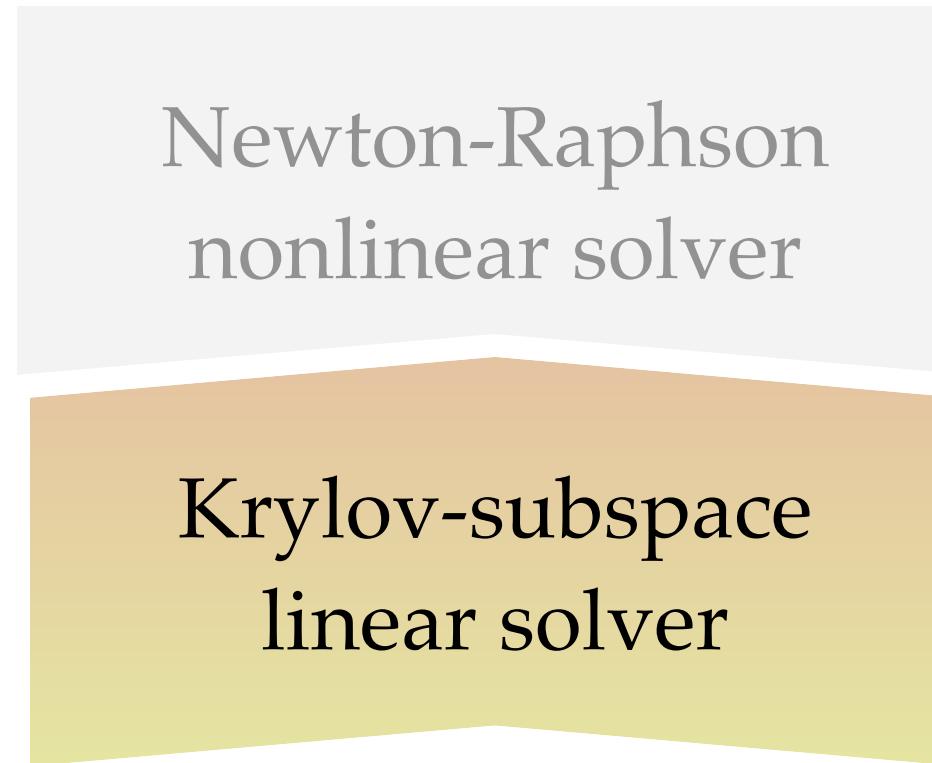


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# The spectre elliptic solver

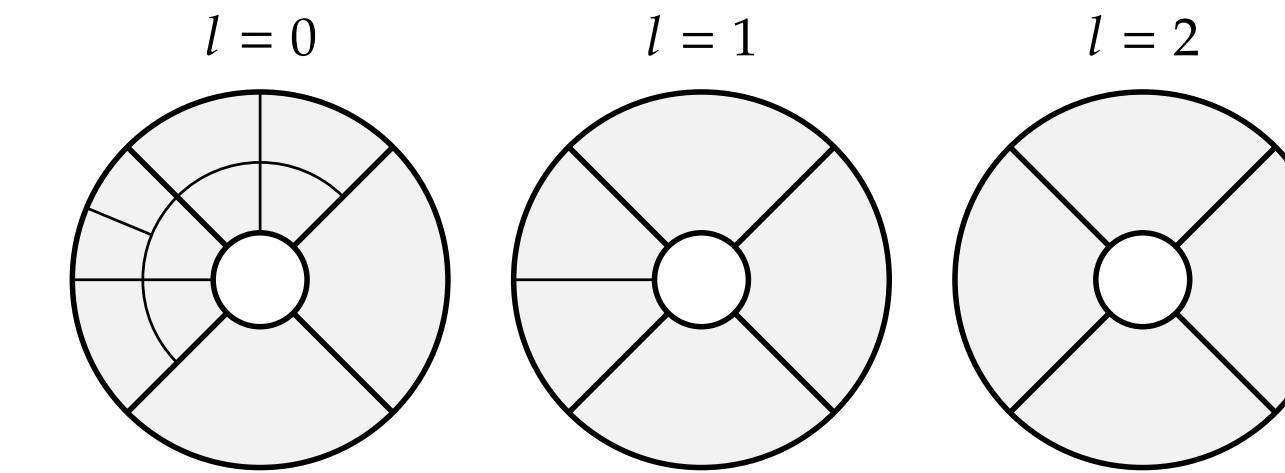
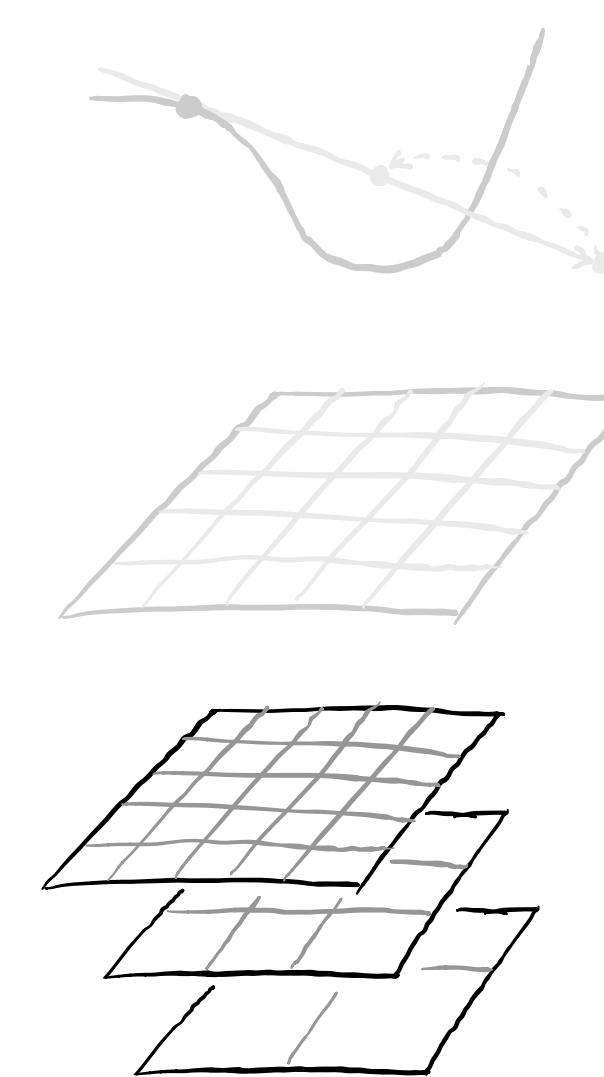
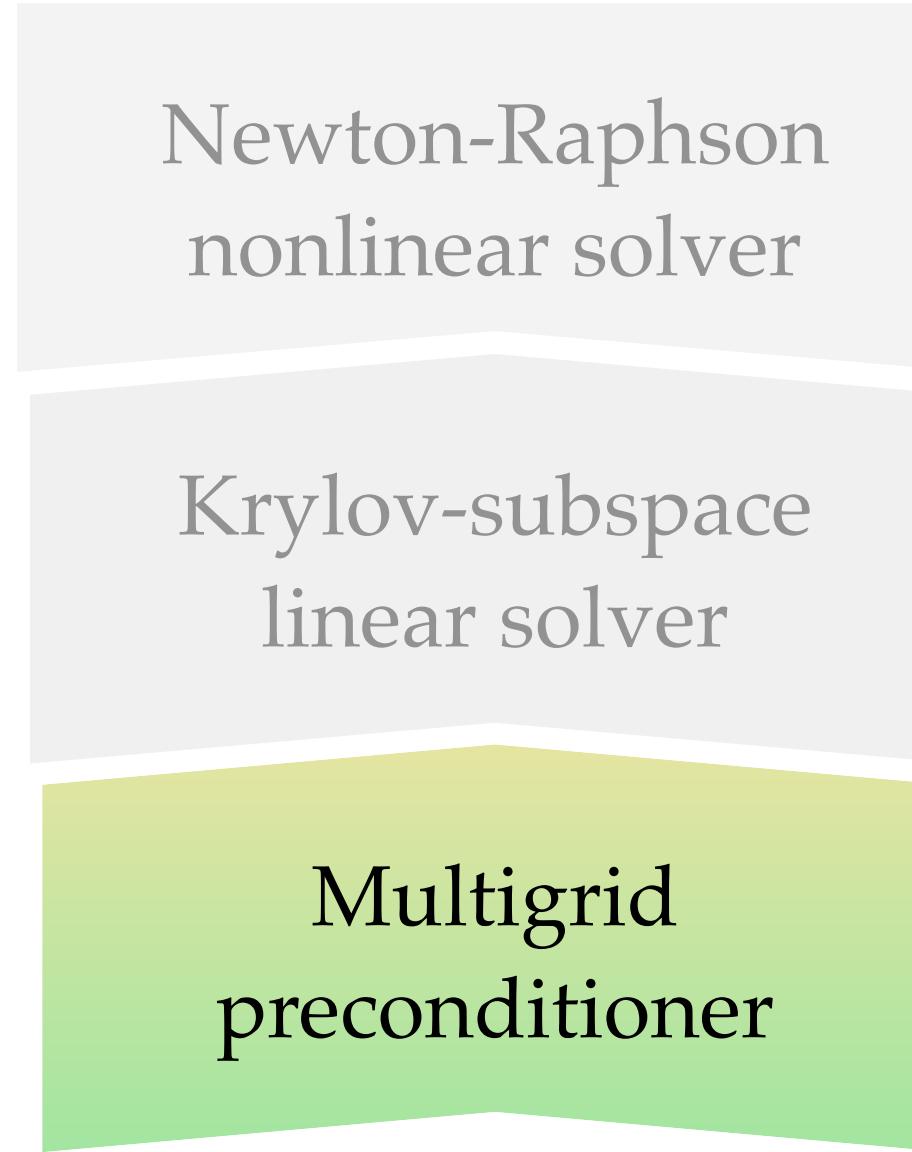
► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D 105, 084027, [arXiv:2111.06767](https://arxiv.org/abs/2111.06767)



- GMRES or Conjugate Gradients
- Builds up a basis of  $K_n = \text{span}\{b, Ab, \dots, A^{n-1}b\}$
- Struggles with large-scale modes
- Poor parallelization

# The spectre elliptic solver

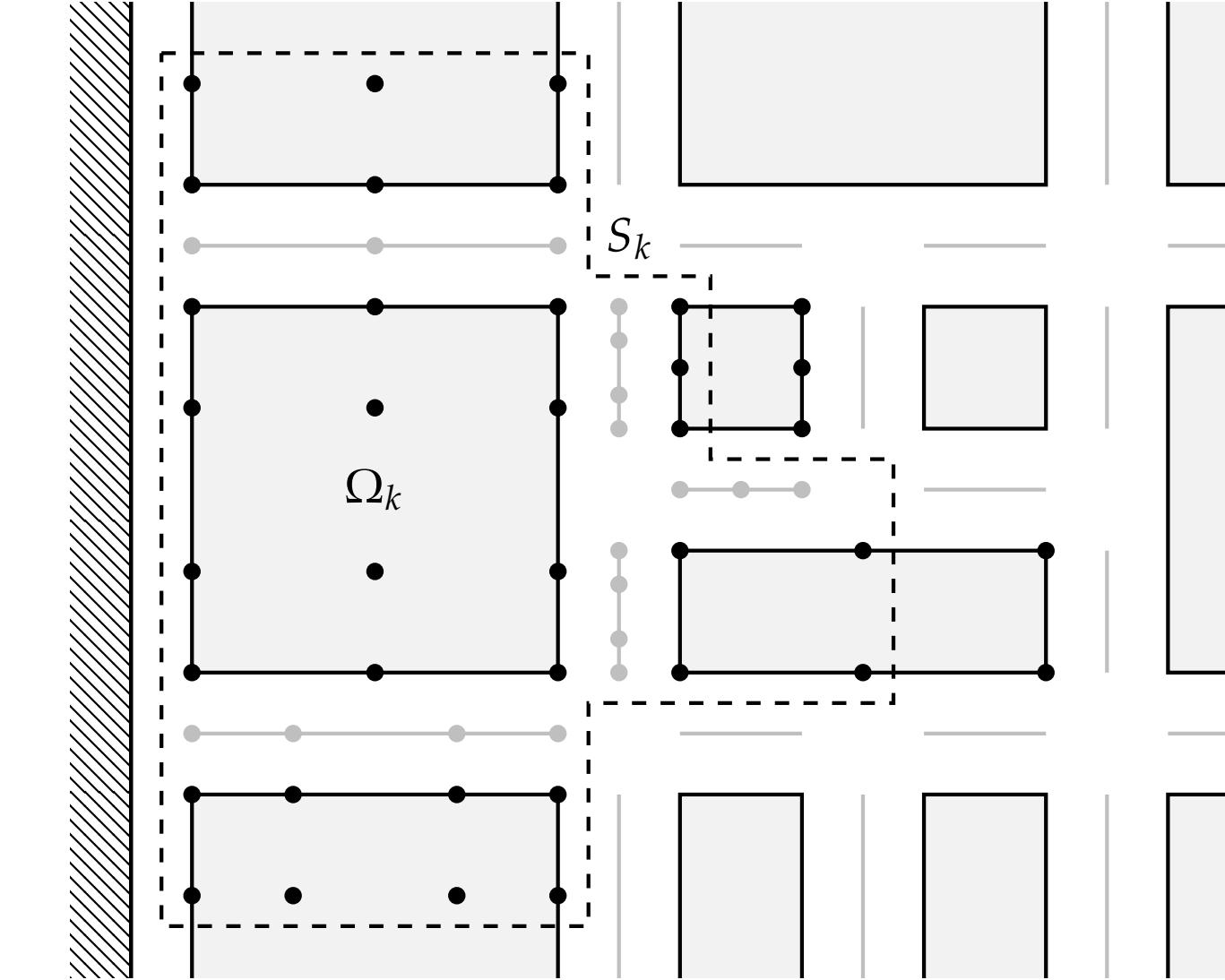
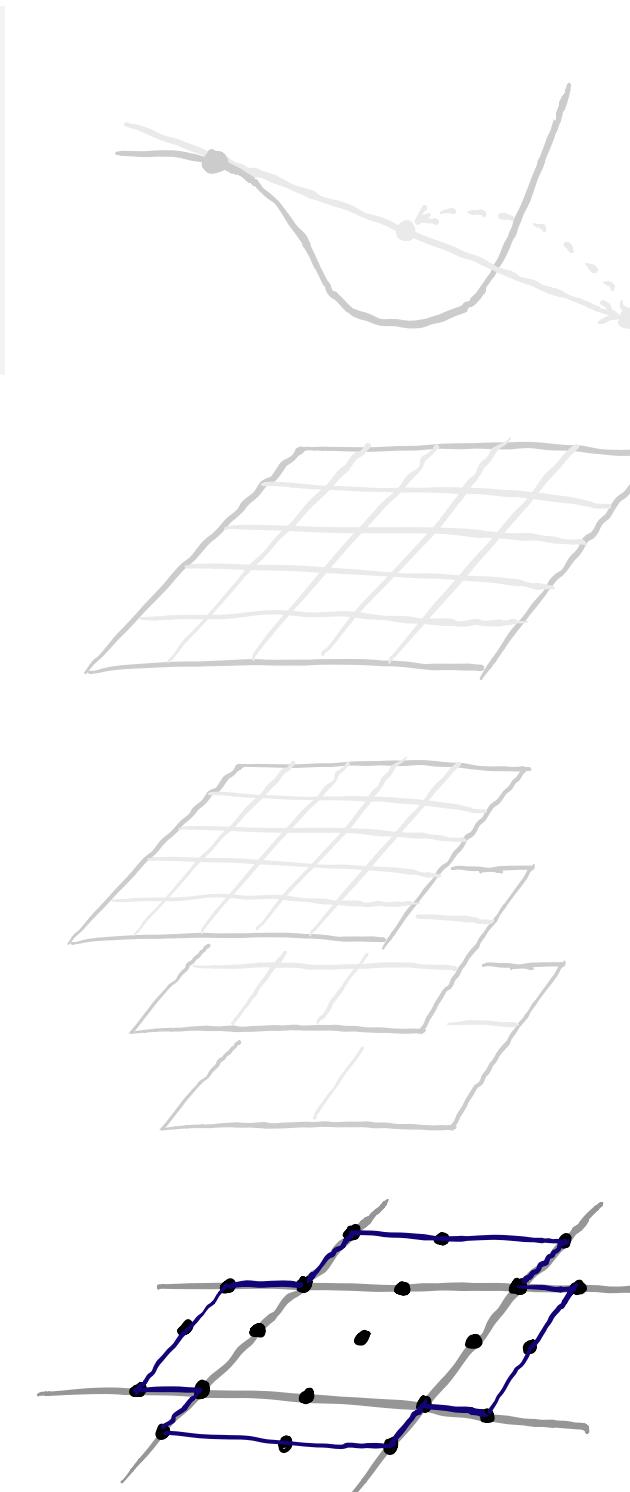
► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D 105, 084027, arXiv:2111.06767



- Interpolates residuals to coarser grids
- Large-scale modes become small-scale
- Coarse-grid solutions correct fine-grid solutions
- A **smoother** runs on every grid

# The spectre elliptic solver

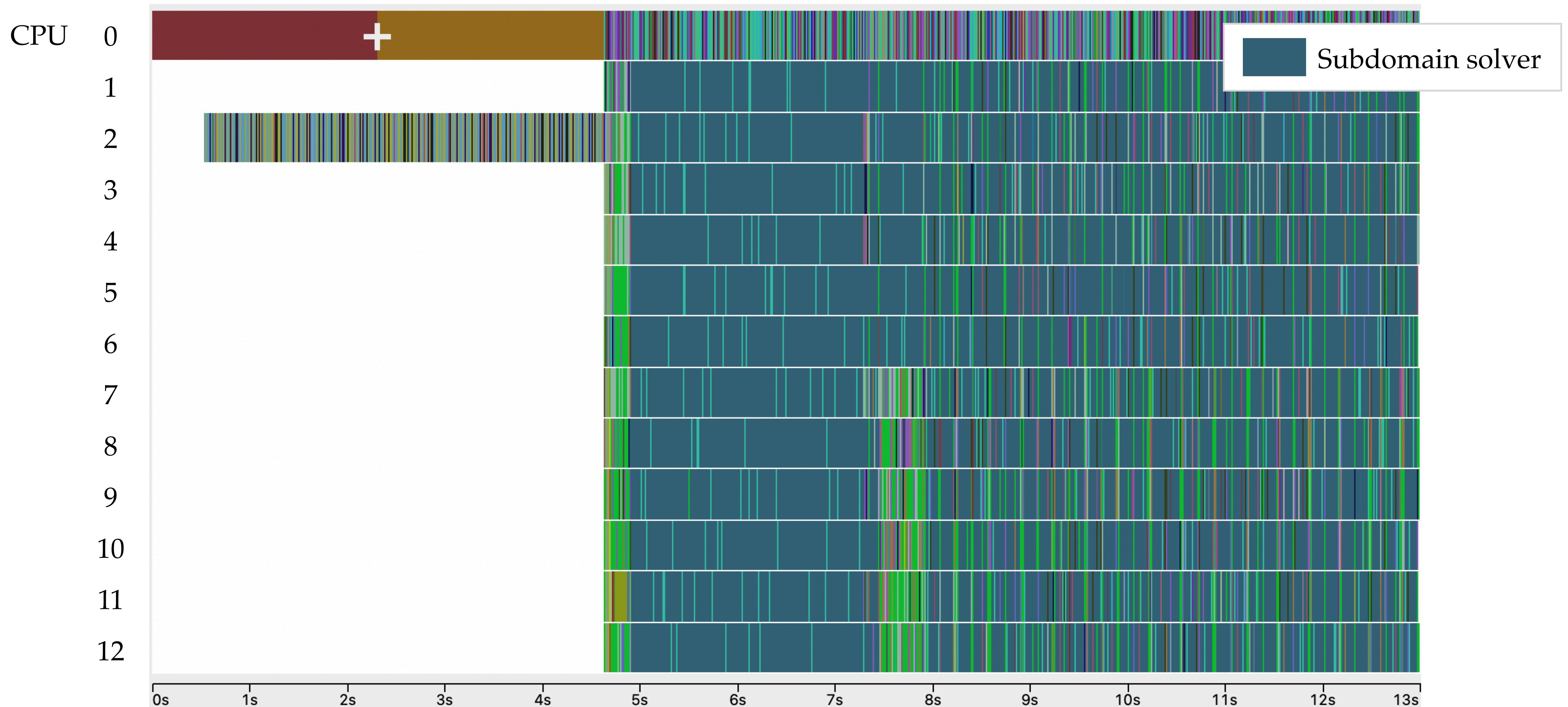
► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D 105, 084027, arXiv:2111.06767



- Restricts problem to overlapping subdomains
- Solves all subdomains in parallel
- Combines subdomain solutions by weighting overlaps

# The spectre elliptic solver

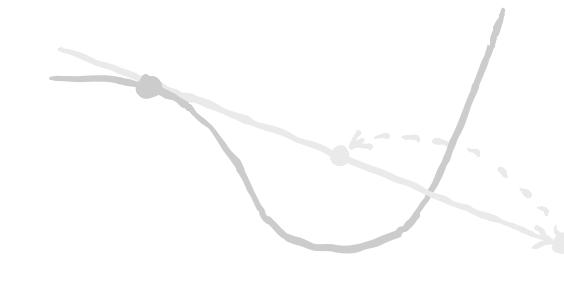
► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D 105, 084027, arXiv:2111.06767



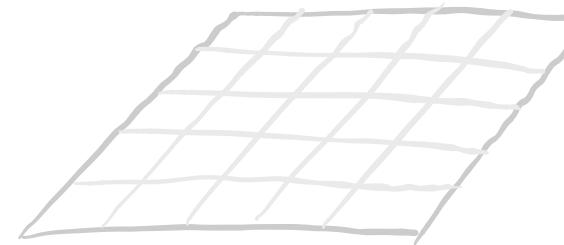
# The spectre elliptic solver

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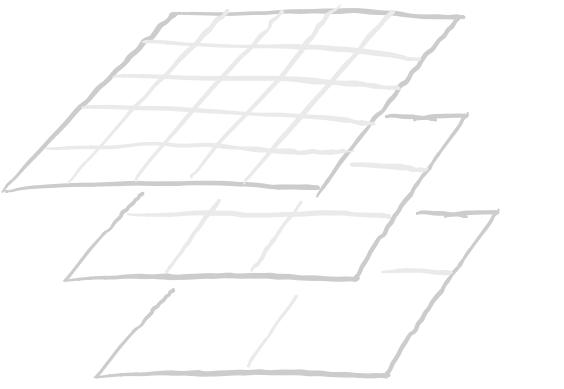
Newton-Raphson  
nonlinear solver



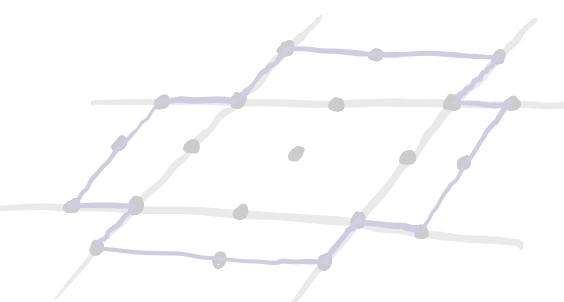
Krylov-subspace  
linear solver



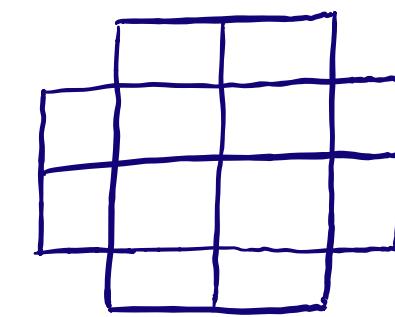
Multigrid  
preconditioner



Schwarz  
smoother



Subdomain  
solver

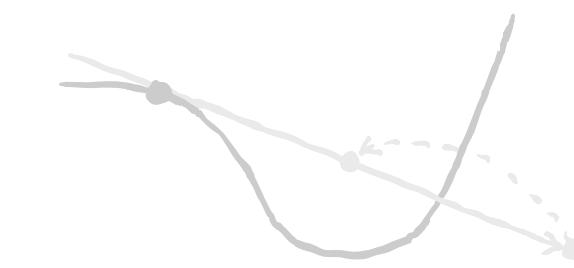


- Solves the subdomain problem in serial
- Another iterative Krylov-subspace algorithm

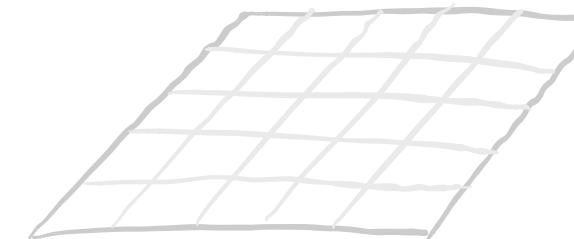
# The spectre elliptic solver

► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D 105, 084027, arXiv:2111.06767

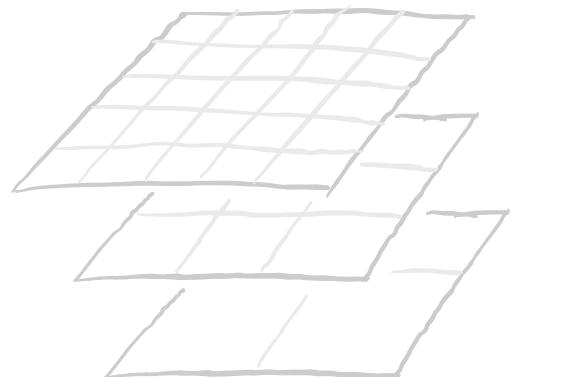
Newton-Raphson  
nonlinear solver



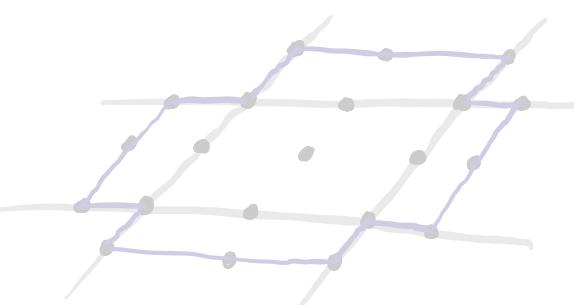
Krylov-subspace  
linear solver



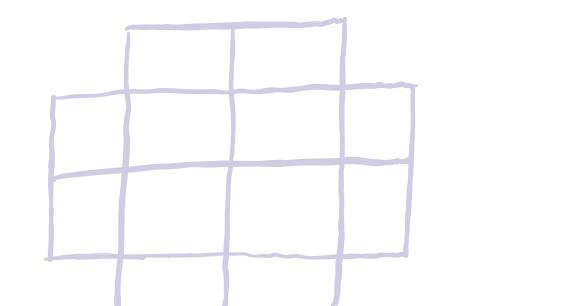
Multigrid  
preconditioner



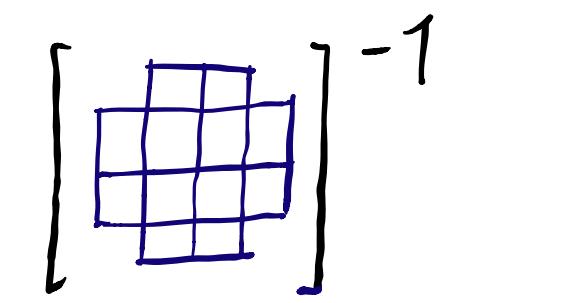
Schwarz  
smoother



Subdomain  
solver



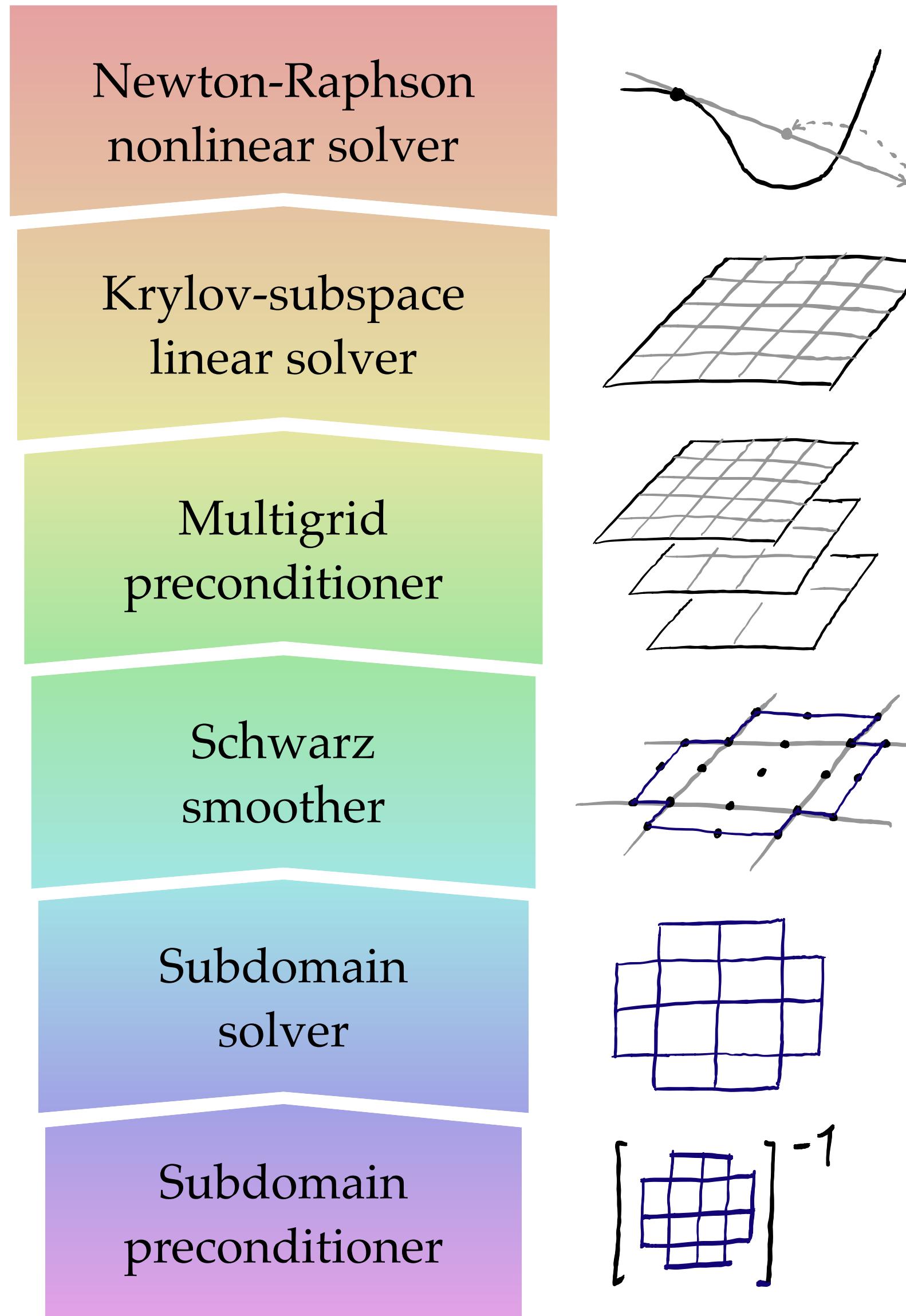
Subdomain  
preconditioner



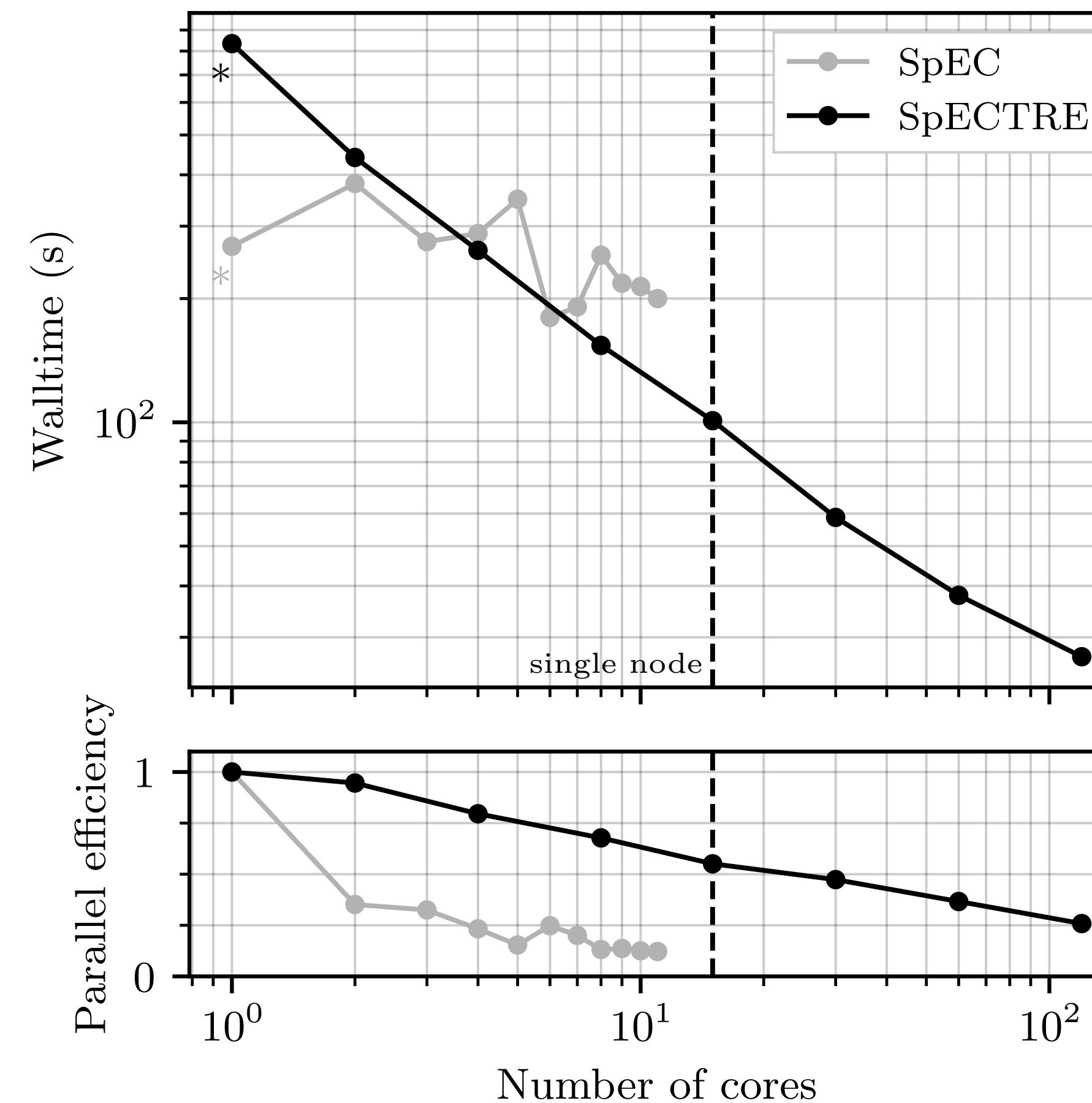
- Laplacian approximation for every equation
- Explicit inverse of Laplacian with ILU

# The spectre elliptic solver

► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D 105, 084027, arXiv:2111.06767



BBH initial data: ~10x faster than SpEC on 120 cores



# The *spectre* initial data solver

- State-of-the-art SXS initial data + *spectre* elliptic solver

➡ ~10x faster than SpEC & open source

➡ Scalable & ready for next-gen numerical relativity

- BBH: public

► NV et al. (2022), *A scalable elliptic solver with task-based parallelism for the SpECTRE code*, Phys. Rev. D **105**, 084027, [arXiv:2111.06767](https://arxiv.org/abs/2111.06767)

- Scalar Gauss-Bonnet: published & will be open source

- BNS+: in development



► I. Legred (Caltech)



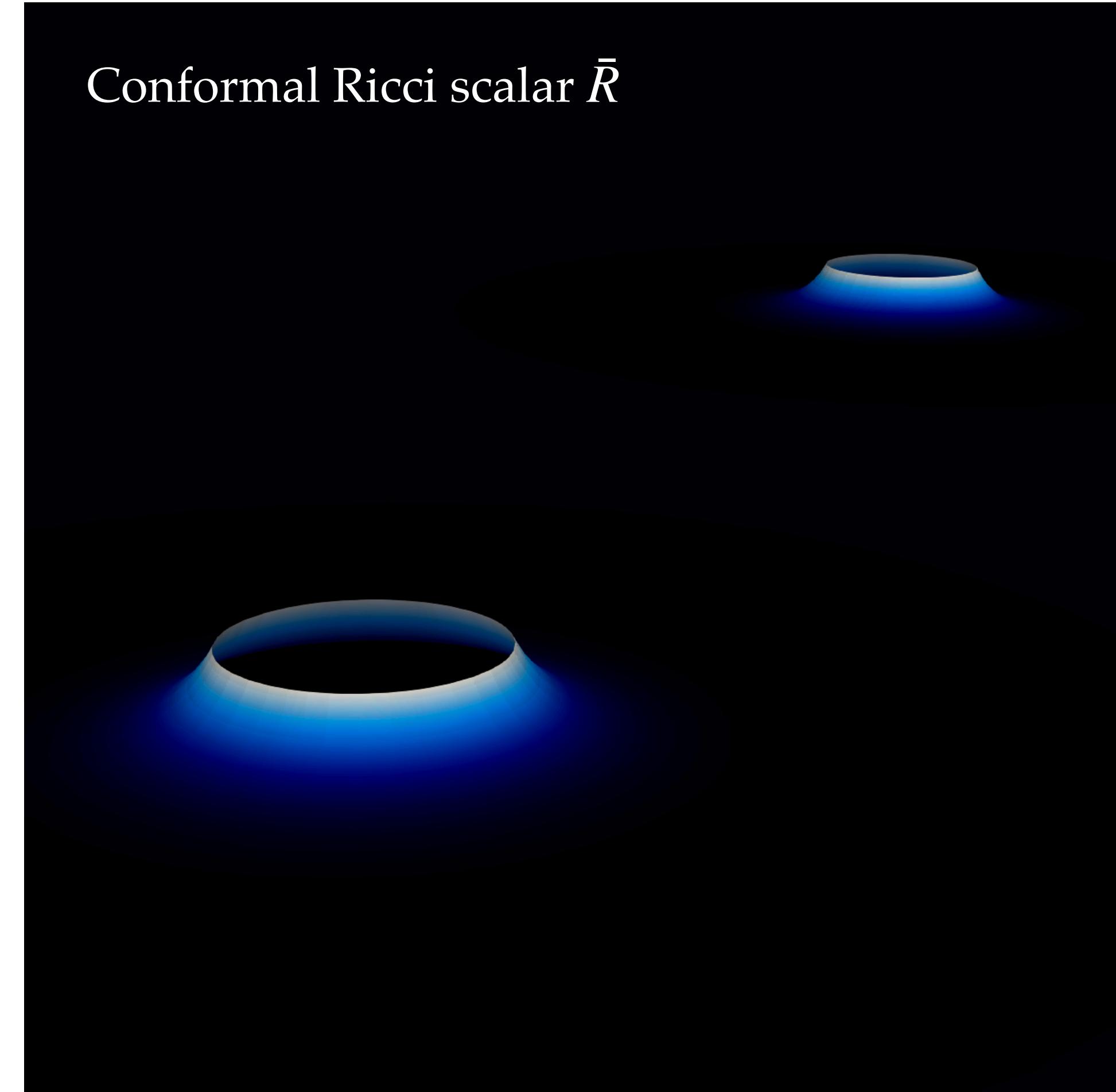
► P.J. Nee (AEI Potsdam),  
[arXiv:2406.08410](https://arxiv.org/abs/2406.08410)

# The *spectre* initial data solver

- Non-conformally-flat: **Superposed Kerr variants**
  - ➡ High spins are possible

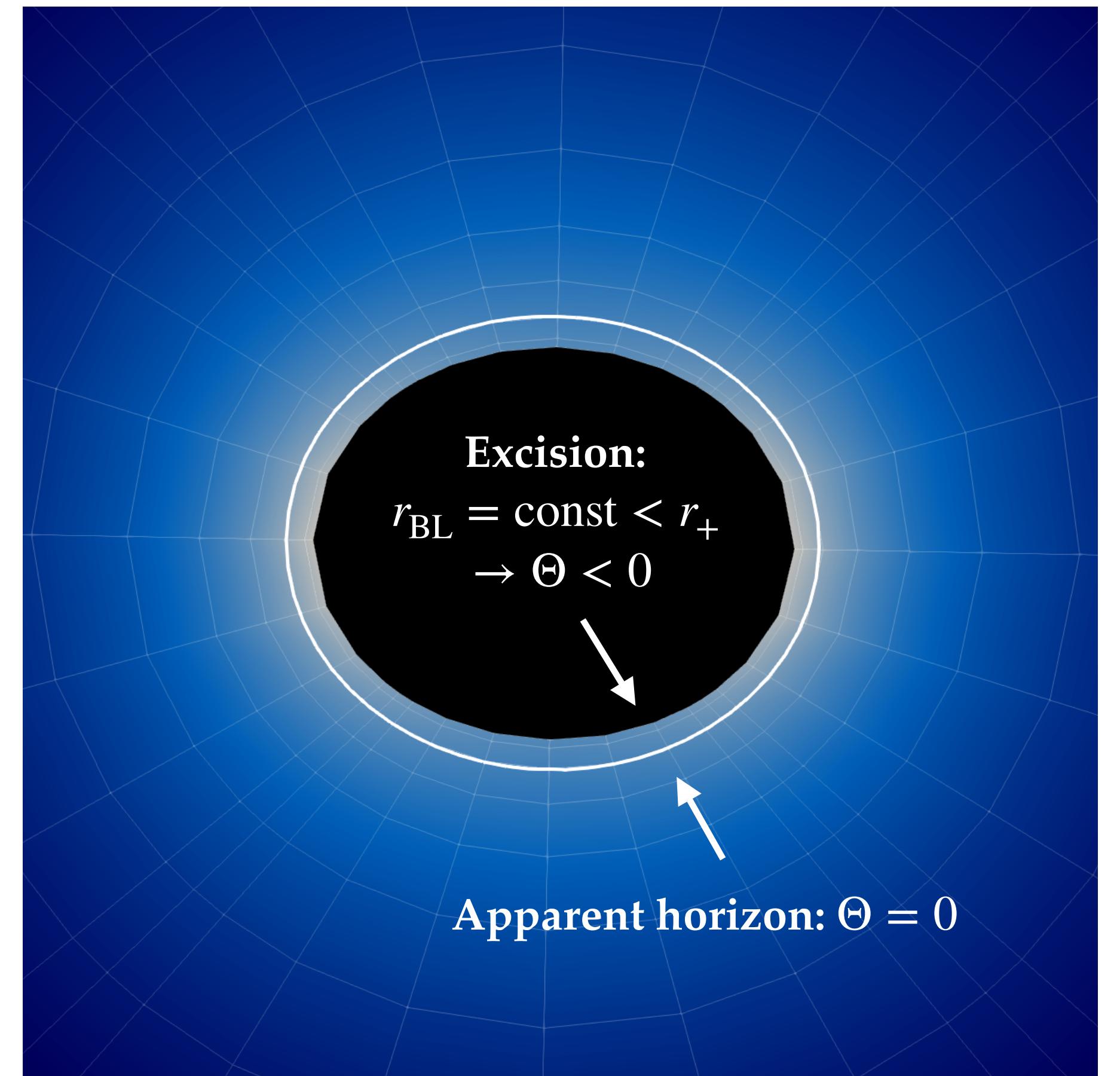
► Lovelace et al. (2008), [arXiv:0805.4192](https://arxiv.org/abs/0805.4192)

Conformal Ricci scalar  $\bar{R}$



# The spectre initial data solver

- Non-conformally-flat: **Superposed Kerr variants**
  - High spins are possible ▶ Lovelace et al. (2008), [arXiv:0805.4192](#)
- **Black hole excisions**
  - Exponential convergence with spectral methods
- **Negative-expansion boundary conditions**
  - Horizon is well resolved
  - Extrapolation into horizon is possible
- No symmetries, parameter control, eccentricity control, ...



# Running the *spectre* initial data solver

## Multiple options:

- Container:



```
$ docker/apptainer run sxscollaboration/spectre bbh generate-id -o ./bbh_id  
-q 1 --chi-A 0 0 0 --chi-B 0 0 0 -D 16 -w 0.015 -a 0
```

- Download static executable from latest release:  
<https://github.com/sxs-collaboration/spectre/releases>
- Install *spectre*:  
<https://spectre-code.org/installation.html>

► Tutorial

# More elliptic problems in spectre

1. Formulate in first-order flux form: 
$$-\partial_i F_\alpha^i + S_\alpha = f_\alpha(x)$$
  $\Delta u = f(x)$   

2. Implement  $F_\alpha^i$ ,  $S_\alpha$ ,  $f_\alpha(x)$   $F^i = \partial_i u$
3. Implement boundary conditions  $S = 0$
4. Use `elliptic::Solver` to compose an executable

# More elliptic problems in spectre

## Thermal noise

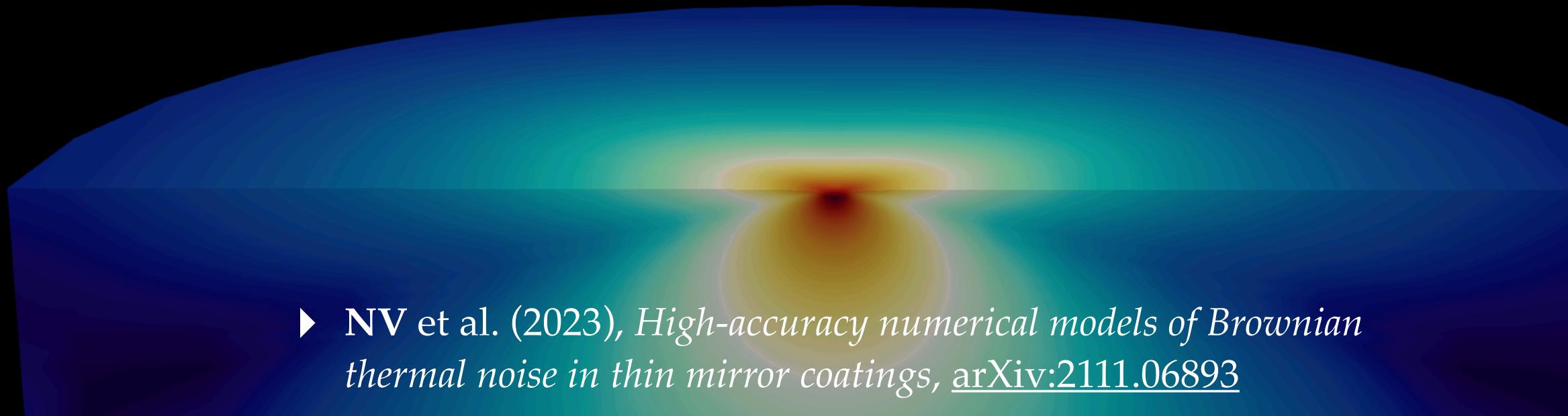
- XCTS momentum constraint is an elasticity equation:

$$\bar{\nabla}_i (\bar{L}\beta)^{ij} = \text{(nonlinear sources)}$$

with  $(\bar{L}\beta)^{ij} = 2\bar{\nabla}^{(i}\beta^{j)} - \frac{2}{3}\bar{\gamma}^{ij}\bar{\nabla}_k\beta^k$

- Fluctuation dissipation theorem connects thermal noise to elasticity.

→ We can simulate thermal noise in LIGO mirrors!



► NV et al. (2023), *High-accuracy numerical models of Brownian thermal noise in thin mirror coatings*, [arXiv:2111.06893](https://arxiv.org/abs/2111.06893)

## M-mode self force

- Second-order Kerr self force

→ EMRI waveforms for LISA

- 1 elliptic PDE per m-mode

► Osburn & Nishimura (2022), *New self-force method via elliptic partial differential equations for Kerr inspiral models*, [arXiv:2206.07031](https://arxiv.org/abs/2206.07031)

