

最近时间比较多，把去年Real World总决赛的路由器重新调了一遍

router

Score: 500

Demo

There are many ways to manage a router, and I choose SNMP.

NOTE: The target device is inside the cabinet beside your table. The login information is root:rwctf. This weak credential is for debugging only.

Demonstration Requirements:

Building Environment

因为我最后没有拿路由器，所以需要先搭建好整个模拟路由环境启动snmp服务
路由器版本:

Netgear R6300 v2

```
#https://openwrt.org/toh/netgear/netgear_r6300_v2
```

首先下载openwrt的源码(18.06.1和18.06.2皆可，只是最后EXP中偏移可能不同)

配置config：

Target System: BCM47XX/53XX

Target Profile: Netgear R6300 v2

Target Images: squashfs //■■■■■■■■■■

Development: gdb&&gdbserver //■■■■■■■■■■

而后保存配置并编译

在编译好的文件中找到编译好的文件系统：

```
# ls
bin  etc  mnt      proc  root  sys  usr  www
dev  lib  overlay  rom   sbin  tmp  var
```

有两个思路：

```
■■■■■■■■■■■gemu■■ #■■■■  
■gemu■■arm■■■■■■■■■■arm■■■chroot■■■■■■
```

我选择直接在树莓派中搭建环境

(也可以在qemu system mode下的arm虚拟机中启动，后面有说明)

将文件系统整个放入树莓派中(包括比赛的两个ipk包):

而后配置chroot环境：

```
sudo mount proc chroot_dir/proc -t proc
sudo mount sysfs chroot_dir/sys -t sysfs
cp /etc/hosts chroot_dir/etc/hosts #■■■■■■■■
■■ chroot_dir/etc/resolv.conf: #■■DNS■■
nameserver 8.8.8.8
```

开启chroot环境：

而后安装比赛的snmp环境：

确认snmp服务启动：

```
/ # netstat -anp|grep snmpd
udp        0      0 0.0.0.0:161          0.0.0.0:*          1922/snmpd
udp        0      0 :::161              :::*                1922/snmpd
unix  2      [ ACC ]     STREAM     LISTENING     18493 1922/snmpd      /var/run/agentx.sock
```

```
kirin@kirin-virtual-machine:~$ snmpwalk -v 1 -c public 192.168.137.33 .1
iso.3.6.1.4.1.2021.13.32.1.0 = INTEGER: 0
iso.3.6.1.4.1.2021.13.32.2.0 = INTEGER: 1996043560
End of MIB
```

□□□□&&□□

■■qemu■■■■■■■■

■■gemu■■■■

```
■■■■■■■■■■chroot■■■■■■■■
```

在搭建的路由器环境下gdbserver运行snmpd，IDA下动态调试追踪程序流可以看到snmp服务会先初始化mib，agent等环境：

在init_mib_modules中可以看到：

```
int init_mib_modules()
{
    int result; // r0
    int v1; // r3

    result = should_init();
    if ( result )
        result = j_init_greatSensors();
    v1 = dword_1102C;
    dword_11028 = 1;
    if ( !dword_1102C )
    {
        dword_1102C = 1;
        result = snmp_register_callback(v1, 2, (int)sub_9D4);
        if ( result )
            result = snmp_log(3, "error registering for SHUTDOWN callback for mib modules\n");
    }
    return result;
}
```

```

LOAD:000008E0 init_greatSensors          ; CODE XREF: j_init_greatSensors+8↑j
LOAD:000008E0                          ; DATA XREF: LOAD:000002D8↑o ...
LOAD:000008E0
LOAD:000008E0 var_70                    = -0x70

```

```

LOAD:000008E0 var_64          = -0x64
LOAD:000008E0 var_60          = -0x60
LOAD:000008E0 var_38          = -0x38
LOAD:000008E0
LOAD:000008E0                LDR            R12, =(dword_A88 - 0x8FC)
LOAD:000008E4                STMFD         SP!, {R4,R5,LR}
LOAD:000008E8                SUB            SP, SP, #0x64
LOAD:000008EC                ADD            LR, SP, #0x70+var_60
LOAD:000008F0                LDR            R5, =(_GLOBAL_OFFSET_TABLE_ - 0x90C)
LOAD:000008F4                ADD            R12, PC, R12 ; dword_A88
LOAD:000008F8                MOV            R4, R12
LOAD:000008FC                ADD            R12, R12, #0x28
LOAD:00000900                LDMIA         R4!, {R0-R3}
LOAD:00000904                ADD            R5, PC, R5 ; _GLOBAL_OFFSET_TABLE_
LOAD:00000908                STMIA         LR!, {R0-R3}
LOAD:0000090C                LDMIA         R4!, {R0-R3}
LOAD:00000910                STMIA         LR!, {R0-R3}
LOAD:00000914                LDMIA         R4, {R0,R1}
LOAD:00000918                MOV            R4, #3
LOAD:0000091C                STMIA         LR, {R0,R1}
LOAD:00000920                ADD            LR, SP, #0x70+var_38
LOAD:00000924                LDMIA         R12!, {R0-R3}
LOAD:00000928                STMIA         LR!, {R0-R3}
LOAD:0000092C                LDMIA         R12!, {R0-R3}
LOAD:00000930                STMIA         LR!, {R0-R3}
LOAD:00000934                ADD            R2, SP, #0x70+var_60
LOAD:00000938                LDMIA         R12, {R0,R1}
LOAD:0000093C                LDR            R3, =(off_10FFC - 0x10FAC)
LOAD:00000940                STMIA         LR, {R0,R1}
LOAD:00000944                LDR            R0, =(aGreatmiscsenso - 0x958)
LOAD:00000948                LDR            R3, [R5,R3] ; handle_greatMiscSensorsDevice
LOAD:0000094C                STR            R4, [SP,#0x70+var_70]
LOAD:00000950                ADD            R0, PC, R0 ; "greatMiscSensorsDevice"
LOAD:00000954                STR            R3, [SP,#0x70+var_64]
LOAD:00000958                MOV            R3, #0xA
LOAD:0000095C                LDR            R1, [SP,#0x70+var_64]
LOAD:00000960                BL            netsnmp_create_handler_registration
LOAD:00000964                BL            netsnmp_register_scalar
LOAD:00000968                LDR            R3, =(off_10FF0 - 0x10FAC)
LOAD:0000096C                ADD            R2, SP, #0x70+var_38
LOAD:00000970                LDR            R0, =(aGreatmiscsenso_0 - 0x980)
LOAD:00000974                LDR            R3, [R5,R3] ; handle_greatMiscSensorsIndex
LOAD:00000978                ADD            R0, PC, R0 ; "greatMiscSensorsIndex"
LOAD:0000097C                STR            R4, [SP,#0x70+var_70]
LOAD:00000980                STR            R3, [SP,#0x70+var_64]
LOAD:00000984                MOV            R3, #0xA
LOAD:00000988                LDR            R1, [SP,#0x70+var_64]
LOAD:0000098C                BL            netsnmp_create_handler_registration
LOAD:00000990                BL            netsnmp_register_scalar
LOAD:00000994                MOV            R0, #0x78 ; 'x' ; size_t
LOAD:00000998                BL            malloc
LOAD:0000099C                LDR            R3, =(vla_str - 0x9AC)
LOAD:000009A0                MOV            R2, #0
LOAD:000009A4                ADD            R3, PC, R3 ; vla_str
LOAD:000009A8                STR            R0, [R3,#(mib_address - 0x11020)]
LOAD:000009AC                STR            R2, [R3]
LOAD:000009B0                ADD            SP, SP, #0x64
LOAD:000009B4                LDMFD         SP!, {R4,R5,PC}
LOAD:000009B4 ; End of function init_greatSensors

```

可以看到其注册了两个回调函数，动态调试下看到注册过程：

```

int __fastcall sub_76F59344(int a1, int a2, int a3, int a4)
{
    int v4; // r5@1
    int v5; // r6@1
    int v6; // r7@1
    int v7; // r4@1
    int v8; // r5@2

```

```

v4 = a1;
v5 = a3;
v6 = a4;
v7 = ((int (__cdecl *)(int, int, int))unk_76F4D74C)(a1, a2, a3);
if ( v7 )
{
    v8 = ((int (__fastcall *)(int, int, int, int))unk_76F4C0D8)(v4, v7, v5, v6);
    if ( !v8 )
        ((void (__fastcall *)(int))unk_76F4C228)(v7);
}
else
{
    v8 = 0;
}
return v8;
}

```

首先是写入函数地址：

```

00024D80 00 00 00 00 00 00 00 00 41 00 00 00 31 00 00 00 .....A...1...
00024D90 C0 4D 02 00 00 00 00 00 00 00 00 00 0C D7 F2 76 .M.....v

```

而后函数名称：

```

00024D80 00 00 00 00 00 00 00 00 31 00 00 00 21 00 00 00 .....1...!...
00024DC0 67 72 65 61 74 4D 69 73 63 53 65 6E 73 6F 72 73 greatMiscSensors
00024DD0 44 65 76 69 63 65 00 00 21 00 00 00 41 00 00 00 Device..!...A...

```

而后mib对象对应的OID：

```

00024E30 44 65 76 69 63 65 00 00 21 00 00 00 31 00 00 00 Device..!...1...
00024E40 01 00 00 00 03 00 00 00 06 00 00 00 01 00 00 00 .....
00024E50 04 00 00 00 01 00 00 00 E5 07 00 00 0D 00 00 00 .....
00024E60 20 00 00 00 02 00 00 00 31 00 00 00 90 01 00 00 .....1.....

```

可以看到此OID：1.3.6.1.4.1.2021.13.32.2.0

当利用snmpset/snmpget对此对象进行读写操作时，会利用netsnmp_call_handler函数处理对象，最终调用对应此OID的回调函数：handle_greatMiscSensorsDevice函数，netsnmp_call_handler关键部分：

```

v10 = (int (__fastcall *)(int *, int, int *, int))v8[3];
if ( !v10 )
    break;
se_find_label_in_slist((int)"agent_mode", *v6);
result = v10(v8, v9, v6, v7);
v12 = v8[2];

```

同样另一个回调函数handle_greatMiscSensorsIndex对应OID：

```

76FFF5B0 49 6E 64 65 78 00 00 00 21 00 00 00 41 00 00 00 Index...!...A...
76FFF5C0 01 00 00 00 03 00 00 00 06 00 00 00 01 00 00 00 .....
76FFF5D0 04 00 00 00 01 00 00 00 E5 07 00 00 0D 00 00 00 .....
76FFF5E0 20 00 00 00 01 00 00 00 00 00 00 00 11 0A 00 00 .....

```

即：1.3.6.1.4.1.2021.13.32.1.0

这时候关注两个回调函数，发现了任意地址读写：

handle_greatMiscSensorsDevice：

```

int __fastcall handle_greatMiscSensorsDevice(int a1, int a2, signed int *a3, _DWORD *a4)
{
    signed int v4; // r4
    int result; // r0
    int v6; // r0
    int v7; // r3
    const char *v8; // r2
    int v9; // r1

    v4 = *a3;
    if ( *a3 == 2 )
    {
        if ( vla_str <= 29 )
        {
            *(_DWORD *)(mib_address + 4 * vla_str) = **(_DWORD **)(*a4 + 16);
            return 0;
        }
    }
LABEL_15:
    netsnmp_set_request_error();
}

```

```

    return 0;
}
if ( *a3 > 2 )
{
    if ( v4 > 5 )
    {
        if ( v4 != 160 )
            goto LABEL_5;
        v6 = *a4;
        if ( vla_str > 29 )
        {
            v7 = 7;
            v9 = 4;
            v8 = "Go Back";
        }
        else
        {
            v7 = 4;
            v8 = (const char *) (mib_address + 4 * vla_str);
            v9 = 2;
        }
        snmp_set_var_typed_value(v6, v9, (int)v8, v7);
    }
    return 0;
}
if ( v4 )
{
    if ( v4 != 1 )
    {
LABEL_5:
        snmp_log(3, "unknown mode (%d) in handle_greatMiscSensorsDevice\n", *a3);
        return 5;
    }
    return 0;
}
result = netsnmp_check_vb_type(*a4, 2);
if ( result )
    goto LABEL_15;
return result;
}

```

handle_greatMiscSensorsIndex:

```

int __fastcall handle_greatMiscSensorsIndex(int a1, int a2, signed int *a3, _DWORD *a4)
{
    signed int v4; // r4
    int result; // r0

    v4 = *a3;
    if ( *a3 == 2 )
    {
        vla_str = **(_DWORD **)(a4 + 16);
        return 0;
    }
    if ( *a3 > 2 )
    {
        if ( v4 > 5 )
        {
            if ( v4 != 0xA0 )
                goto LABEL_5;
            snmp_set_var_typed_value(a4, 2, (int)&vla_str, 4); // (netsnmp_variable_list *newvar, u_char type, const void *val_str, s
        }
        return 0;
    }
    if ( v4 )
    {
        if ( v4 != 1 )
        {
LABEL_5:

```

```

        snmp_log(3, "unknown mode (%d) in handle_greatMiscSensorsDevice\n", *a3);
        return 5;
    }
    return 0;
}
result = netsnmp_check_vb_type(*a4, 2);
if ( result )
{
    netsnmp_set_request_error();
    return 0;
}
return result;
}

```

可以看到handle_greatMiscSensorsDevice中：
当使用snmpset写对象时，

```

#*a30000->0 1 2 3 0 1 2 3.....
if ( *a3 == 2 )
{
    if ( vla_str <= 29 )
    {
        *(_DWORD *) (mib_address + 4 * vla_str) = **(_DWORD **)(*a4 + 16);
        return 0;
    }
}

```

mid_address是在snmp服务启动mib初始化时在init_greatSensors中：

```

result = malloc(0x78u);
mib_address = (int)result;
vla_str = 0;

```

而val_str在handle_greatMiscSensorsIndex中可以进行设置：

```

vla_str = **(_DWORD **)(*a4 + 16);

```

即我们对OID对象1.3.6.1.4.1.2021.13.32.1.0设置的值

所以当我们依次调用handle_greatMiscSensorsIndex进行设置vla_str，此值只需小于29(在这里设置为负数即可)，而后调用handle_greatMiscSensorsDevice即可实现任意地址读相同原理，当snmpget读取对象时，会调用：

```

#v8 = (const char *) (mib_address + 4 * vla_str);
#00000000vla_str0000290000000000
snmp_set_var_typed_value(v6, v9, (int)v8, v7)

```

即会将对象的值设置我们构造地址处的值

而后取出对象value返回给snmpget完成任意地址读

POC

首先需要leak libc

想到注册回调函数位置

利用任意地址读找到注册函数保存地址来leak libc

```

hex(0x76F5F9F0-0x76F5F40c)=0x5e4

```

而后再次利用handle来劫持程序流，即netsnmp_call_handler中：

```

v10 = (int (__fastcall *) (int *, int, int *, int))v8[3];
if ( !v10 )
    break;
se_find_label_in_slist((int)"agent_mode", *v6);
result = v10(v8, v9, v6, v7);
v12 = v8[2];

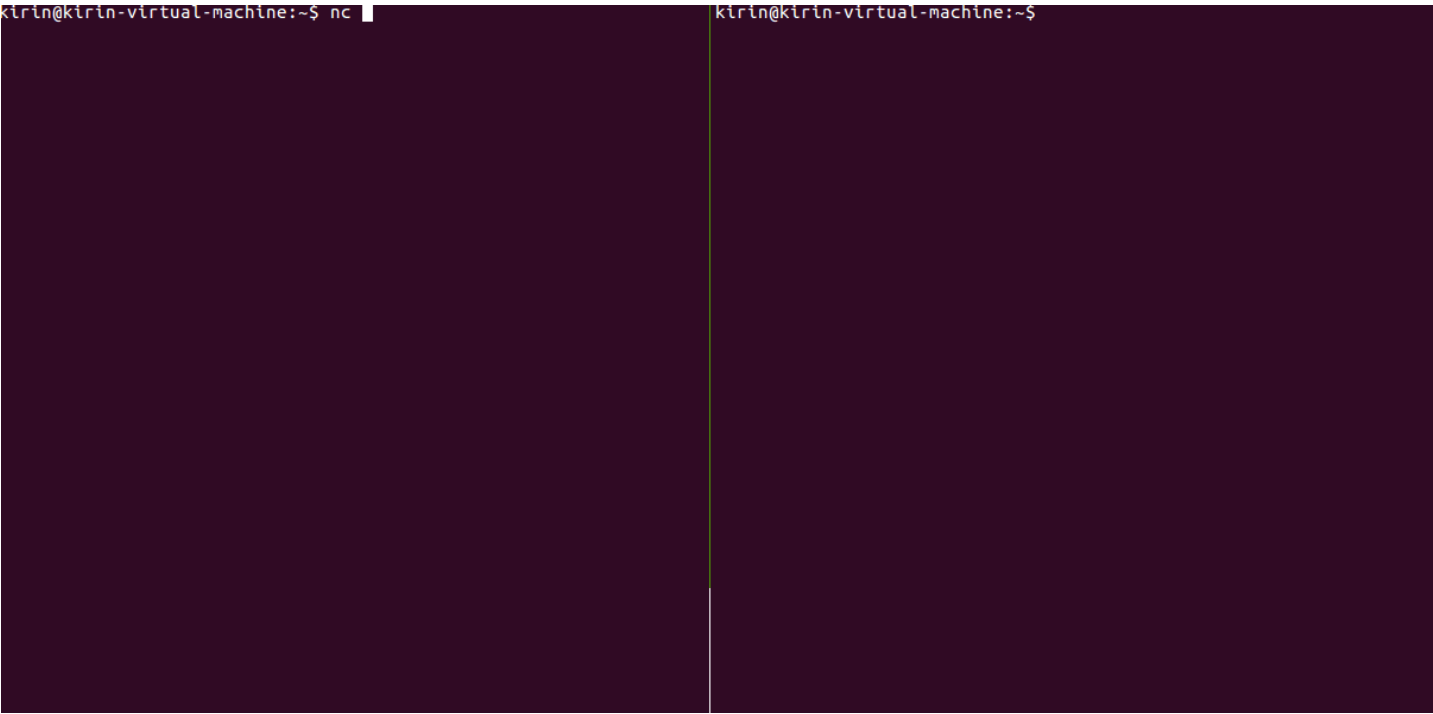
```

这时候只需要事先布置好一条ROP链，最后将handle改为我们的rop chain地址即可劫持程序流，最终达到RCE：

```

ROPgadget --binary ./libc.so
.....
0x000596bc : ldr r3, [pc, #0x3c] ; ldr r2, [pc, #0x3c] ; add r3, pc, r3 ; ldr r0, [pc, r2] ; ldr r3, [r3] ; blx r3
.....
00000000r3r200000000&system function,&shell

```

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