

Chapter 2. Electrostatics

Coulomb's Law: $\vec{F} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2} \hat{r}$, $\vec{r} = \vec{r}_2 - \vec{r}_1$

Electric Field: $\vec{F} = Q\vec{E}$, $\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^n \frac{q_i}{r_i^2} \hat{r}_i$

Continuous: $\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\hat{r}}{r^2} dq$, $dq = \lambda dl \sim 6da$, $\sim \rho d\tau$

Gauss' Law: $\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$, $\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

Curl of \vec{E} : $\nabla \times \vec{E} = 0 \Leftrightarrow \oint \vec{E} \cdot d\vec{l} = 0$

Electric potential: $V(\vec{r}) = -\int \vec{E} \cdot d\vec{l}$

$V(b) - V(a) = -\int_a^b \vec{E} \cdot d\vec{l}$, $\vec{E} = -\nabla V$

Poisson's equation: $\nabla^2 V = -\frac{\rho}{\epsilon_0}$, $\rho = 0 \Rightarrow \nabla^2 V = 0$

With $0 = \infty$: $V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum \frac{q_i}{r_i}$, $V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho}{r} d\tau$

Boundary Conditions:

$E_{\perp}^{(1)} - E_{\perp}^{(2)} = \frac{\sigma}{\epsilon_0}$, $E_{\parallel}^{(1)} = E_{\parallel}^{(2)} \Rightarrow \vec{E}^{(2)} - \vec{E}^{(1)} = \frac{\sigma}{\epsilon_0} \hat{n}$

$V^{(2)} = V^{(1)}$, $\frac{\partial V^{(2)}}{\partial n} - \frac{\partial V^{(1)}}{\partial n} = -\frac{\sigma}{\epsilon_0}$, $\frac{\partial V}{\partial n} = \nabla V \cdot \hat{n}$

Point on a surface charge: $\vec{E}_{\text{other}} = \frac{1}{2}(\vec{E}_{\text{above}} + \vec{E}_{\text{below}})$

Work to move a charge $a \rightarrow b$: $V(b) - V(a) = \frac{W}{Q}$

Bring charge from ∞ : $W = QV(\vec{r})$

Energy: $W = \frac{1}{2} \sum q_i V(\vec{r}_i)$, $W = \frac{\epsilon_0}{2} \int E^2 d\tau$ (all space)

Conductors: 1. $\vec{E} = 0$ inside 2. $\rho = 0$ inside 3. Net charge resides on the surface. 4. Conductor is equipotential

4. \vec{E} is \perp to the surface.

Capacitors: $C = \frac{Q}{V}$, $V = V_+ - V_- = -\int \vec{E} \cdot d\vec{l}$

Energy in capacitors: $W = \frac{Q^2}{2C} = \frac{1}{2} CV^2$

$\vec{E} = 0$

Chapter 3. Potentials

Laplace: $\nabla^2 V = 0$. Solution: 1. $V(\vec{r}) = \frac{1}{4\pi R^2} \oint V dS$

2. Extreme values occur at boundary.

Uniqueness Theorems: 1. if V is specified on boundary

2. (a) ρ (b) V at boundaries are satisfied 3. Total charge on each conductors is given.

Method of image: All the same except for the energy

$V = 0$

$R = a$, $b = \frac{R^2}{a}$, $q' = -\frac{R}{a}q$

$V(R) = 0$

Separation of variables

1. Cartesian: $\frac{d^2 X}{dx^2} = C_1 X$, $\frac{d^2 Y}{dy^2} = C_2 Y$, $\frac{d^2 Z}{dz^2} = C_3 Z$

$\int_0^a \sin\left(\frac{n\pi x}{a}\right) \sin\left(\frac{n'\pi x}{a}\right) dx = \frac{a}{2} \delta_{nn'}$

2. Spherical with azimuthal symmetry.

$V(r, \theta) = \sum_{l=0}^{\infty} (A_l r^l + \frac{B_l}{r^{l+1}}) P_l(\cos\theta)$

$\int_0^\pi P_l(\cos\theta) P_{l'}(\cos\theta) \sin\theta d\theta = \frac{2}{2l+1} \delta_{ll'}$

$P_0(x) = 1$, $P_1(x) = x$, $P_2(x) = (3x^2 - 1)/2$

Multiple expansion:

$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{n=0}^{\infty} \frac{1}{r^{n+1}} \int (r')^n P_n(\cos\alpha) \rho(\vec{r}') d\tau'$

$V_{\text{mon}} = \frac{1}{4\pi\epsilon_0} \frac{Q}{r}$, $Q = \int \rho d\tau$

$V_{\text{dip}} = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \hat{r}}{r^2}$, $\vec{p} = \int \vec{r} \rho(\vec{r}') d\tau'$ dipole moment

Change origin: $\vec{p}_{\text{new}} = \vec{p} - Q\vec{a}$ - displacement of 0.

For a perfect dipole: $V_{\text{dip}}(r, \theta) = \frac{p \cos\theta}{4\pi\epsilon_0 r^2}$

$\vec{p} \uparrow \vec{E}_{\text{dip}} = \frac{p}{4\pi\epsilon_0 r^3} (2\cos\theta \hat{r} + \sin\theta \hat{\theta})$

Chapter 4. Electric Fields in Matter

Alignment of polar molecules: $\vec{P} = (\vec{p} \cdot \nabla) \vec{E}$, $\vec{N} = \vec{p} \times \vec{E}$

\vec{P} = dipole moment per volume.

Bound charges: $\epsilon_b = \vec{P} \cdot \hat{n}$, $\rho_b = -\nabla \cdot \vec{P}$

$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \oint \frac{\epsilon_b}{r} da + \frac{1}{4\pi\epsilon_0} \int \frac{\rho_b}{r} d\tau'$

Electric displacement: $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$

Gauss' Law: $\nabla \cdot \vec{D} = \rho_f \Leftrightarrow \oint \vec{D} \cdot d\vec{a} = Q_{\text{fenc}}$

Boundary conditions:

$D_{\text{above}} - D_{\text{below}} = \epsilon_f$, $D_{\text{above}} - D_{\text{below}} = \vec{P}_{\text{above}} - \vec{P}_{\text{below}}$

Energy: $W = \frac{1}{2} \int \vec{D} \cdot \vec{E} d\tau$

Linear dielectrics: $\vec{P} = \epsilon_0 \chi_e \vec{E}$, $\vec{D} = \epsilon \vec{E}$, $\epsilon = \epsilon_0(1 + \chi_e)$

Boundary conditions for linear dielectric $\epsilon_r = \frac{\epsilon}{\epsilon_0} = 1 + \chi_e$

$\nabla \cdot \vec{D} = \rho_f$, $\nabla \times \vec{D} = 0$, $\rho_b = -\nabla \cdot \vec{P} = -\frac{\chi_e}{1 + \chi_e} \rho_f$

$\epsilon_{\text{above}} \frac{E_{\text{above}}}{\partial V_{\text{above}} / \partial n} - \epsilon_{\text{below}} \frac{E_{\text{below}}}{\partial V_{\text{below}} / \partial n} = \epsilon_f$, $V_{\text{above}} = V_{\text{below}}$

Forces on dielectric:

$F = \frac{1}{2} V^2 \frac{d^2 C}{d\alpha^2}$

Chapter 5. Magnetostatics

Lorentz force: $\vec{F}_{\text{mag}} = Q(\vec{v} \times \vec{B})$, $\vec{F} = Q[\vec{E} + \vec{v} \times \vec{B}]$

Current: $\vec{I} = \lambda \vec{v}$, $\vec{K} = \frac{d\vec{I}}{dl} = 6\vec{v}$, $\vec{J} = \frac{d\vec{I}}{dA} = 6\vec{v}$

$\vec{F}_{\text{mag}} = \int I(d\vec{l} \times \vec{B}) = \int \vec{K} \times \vec{B} da = \int \vec{J} \times \vec{B} d\tau$

Continuity: $\nabla \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$. Steady currents: $\frac{\partial \rho}{\partial t} = 0$, $\frac{\partial J}{\partial t} = 0$

Biot-Savart law:

$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{(\vec{I}(\vec{r}') \times \hat{r})}{r^2} d\tau'$, $\frac{\mu_0}{4\pi} \int \frac{(\vec{K}(\vec{r}') \times \hat{r})}{r^2} da'$, $\frac{\mu_0}{4\pi} \int \frac{(\vec{J}(\vec{r}') \times \hat{r})}{r^2} d\tau'$

Divergence: $\nabla \cdot \vec{B} = 0$

Ampère's law: $\nabla \times \vec{B} = \mu_0 \vec{J} \Leftrightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}}$

$\vec{B} = \frac{\mu_0 I}{2\pi s} \hat{\phi}$, $\vec{B} = \mu_0 n \vec{I}$

Vector potential: $\vec{B} = \nabla \times \vec{A}$. Let $\nabla \cdot \vec{A} = 0$, $\nabla^2 \vec{A} = -\mu_0 \vec{J}$

$\vec{J} \rightarrow 0$ at ∞ : $\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}')}{r} d\tau' = \frac{\mu_0}{4\pi} \int \frac{\vec{I}}{r} dl' = \frac{\mu_0}{4\pi} \int \frac{\vec{K}}{r} da'$

Boundary conditions:

$B_{\text{above}} = B_{\text{below}}$, $B_{\text{above}} - B_{\text{below}} = \mu_0 K$, $B_{\text{above}} - B_{\text{below}} = \mu_0 K$

$A_{\text{above}} = A_{\text{below}}$, $\frac{\partial A_{\text{above}}}{\partial n} - \frac{\partial A_{\text{below}}}{\partial n} = -\mu_0 K$

Multipole expansion: $\vec{A}(\vec{r}) = \frac{\mu_0 I}{4\pi} \sum_{n=0}^{\infty} \frac{1}{r^{n+1}} \oint (\vec{r}')^n P_n(\cos\alpha) d\tau'$

$\vec{A}_{\text{dip}}(\vec{r}) = \frac{\mu_0 I}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2}$, $\vec{m} = I \int d\vec{a}$

magnetic dipole moment

Chapter 6. Magnetic Fields Matter

Magnetic dipoles in field: $\vec{N} = \vec{m} \times \vec{B}$, $\vec{F} = \nabla(\vec{m} \cdot \vec{B})$

\vec{m} = magnetic dipole moment per unit volume.

Bound currents: $\vec{J}_b = \nabla \times \vec{M}$, $\vec{K}_b = \vec{M} \times \hat{n}$

In magnetized medium: $\vec{J} = \vec{J}_b + \vec{J}_f$, $\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}$, $\nabla \cdot \vec{H} = -\nabla \cdot \vec{M}$

Ampère's law: $\nabla \times \vec{H} = \vec{J}_f \Leftrightarrow \oint \vec{H} \cdot d\vec{l} = I_{\text{fenc}}$

Boundary conditions: $H_{\text{above}} - H_{\text{below}} = -(M_{\text{above}} - M_{\text{below}})$

$H_{\text{above}} - H_{\text{below}} = K_f \times \hat{n}$

Linear media: $\vec{M} = \chi_m \vec{H}$, $\vec{B} = \mu_0(1 + \chi_m) \vec{H} = \mu \vec{H}$, $\mu = \mu_0(1 + \chi_m)$

$\vec{J}_b = \chi_m \vec{J}_f$

Chapter 7. Electrodynamics

Ohm's law: $\vec{J} = \sigma \vec{E} = 6\vec{E}$, $V = IR$

Joule heating law: $P = VI = I^2 R$

Current around circuit: $\vec{J} = \vec{J}_s + \vec{E}$, $\vec{J}_s = 0$ outside source

emf: $\mathcal{E} = \oint \vec{f} \cdot d\vec{l} = \oint \vec{f}_s \cdot d\vec{l}$

Faraday's law: changing \vec{B} induces \vec{E} : $\oint \vec{E} \cdot d\vec{a} = -\frac{d\Phi}{dt}$, $\mathcal{E} = -\frac{d\Phi}{dt}$

$\rho = 0$: $\nabla \cdot \vec{E} = 0$, $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow \oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi}{dt}$

Mutual inductance: $\Phi_2 = M_{21} I_1$, $M = M_{12} = M_{21} = \frac{\mu_0}{4\pi} \oint \oint \frac{d\vec{l}_1 \times d\vec{l}_2}{r}$

Self inductance: $\Phi = LI$, $\mathcal{E} = -L \frac{dI}{dt}$ back emf.

Energy in \vec{B} field: $W = \frac{1}{2} LI^2$, $W = \frac{1}{2\mu_0} \int B^2 d\tau$ (all space).

Ampère's law: $\nabla \times \vec{B} = \mu_0(\vec{J} + \vec{J}_d)$, $\vec{J}_d = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

Maxwell's equations

$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$, $\nabla \cdot \vec{B} = 0$, $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$, $\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

$\nabla \cdot \vec{D} = \rho_f$, $\nabla \cdot \vec{B} = 0$, $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$, $\nabla \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$

Integral forms:

$\oint \vec{D} \cdot d\vec{a} = Q_{\text{fenc}}$, $\oint \vec{B} \cdot d\vec{a} = 0$, $\oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int \vec{B} \cdot d\vec{a}$, $\oint \vec{H} \cdot d\vec{l} = I_{\text{fenc}} + \frac{d}{dt} \int \vec{D} \cdot d\vec{a}$

Boundary conditions

$D_{\text{above}} - D_{\text{below}} = \epsilon_f$, $B_{\text{above}} - B_{\text{below}} = 0$, $E_{\text{above}} - E_{\text{below}} = 0$, $H_{\text{above}} - H_{\text{below}} = K_f \times \hat{n}$

Linear media:

$\epsilon_{\text{above}} E_{\text{above}} - \epsilon_{\text{below}} E_{\text{below}} = 0$, $\frac{1}{\mu_1} B_{\text{above}} - \frac{1}{\mu_2} B_{\text{below}} = K_f \times \hat{n}$

Chapter 8. Conservation Laws

Continuity equation: $\frac{\partial \rho}{\partial t} = -\nabla \cdot \vec{J}$

Energy density: $u = \frac{1}{2} (\epsilon_0 E^2 + \frac{1}{\mu_0} B^2)$

Poynting's theorem

$\frac{dW}{dt} = -\frac{d}{dt} \int_V u d\tau - \oint \vec{S} \cdot d\vec{a}$, $\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B})$

work done on charges, energy remain in fields, flow out surface

Poynting vector.

Maxwell stress tensor $(\vec{a} \cdot \vec{T})_j = \sum_i a_i T_{ij}$, $(\vec{T} \cdot \vec{a})_j = \sum_i T_{ji} a_i$

$T_{ij} = \epsilon_0 (E_i E_j - \frac{1}{2} \delta_{ij} E^2) + \frac{1}{\mu_0} (B_i B_j - \frac{1}{2} \delta_{ij} B^2)$

EM force on charges in V :

$\vec{F} = \oint_S \vec{T} \cdot d\vec{a} - \epsilon_0 \mu_0 \frac{d}{dt} \int_V \vec{S} d\tau$ static case $\vec{F} = \oint_S \vec{T} \cdot d\vec{a}$

Conservation of momentum: $\frac{d\vec{P}_{\text{mech}}}{dt} = -\epsilon_0 \mu_0 \frac{d}{dt} \int_V \vec{S} d\tau + \oint_S \vec{T} \cdot d\vec{a}$

Momentum stored in fields: $\vec{P} = \epsilon_0 \mu_0 \int_V \vec{S} d\tau$

Momentum density: $\vec{g} = \epsilon_0 \mu_0 \vec{S} = \epsilon_0 (\vec{E} \times \vec{B})$

If $dP_{\text{mech}}/dt = 0 \Rightarrow \frac{\partial \vec{g}}{\partial t} = \nabla \cdot \vec{T}$

Angular momentum: $\vec{L} = \vec{r} \times \vec{g} = \epsilon_0 (\vec{r} \times (\vec{E} \times \vec{B}))$

Chapter 9. Electromagnetic Waves

The wave equation: $\frac{\partial^2 f}{\partial z^2} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2}$

Sinusoidal waves: $f(z, t) = A \cos[k(z - vt) + \delta]$

k : wavenumber, λ : wavelength: $\lambda = \frac{2\pi}{k}$

T : period $T = \frac{2\pi}{\omega}$, $\nu = \frac{1}{T} = \frac{\omega}{2\pi}$ frequency

$\omega = 2\pi\nu = kv$: angular frequency.

$f(z, t) = A \cos(kz - \omega t + \delta)$ travel to right

$f(z, t) = A \cos(-kz - \omega t + \delta)$ left.

Complex notation: $f(z, t) = \hat{A} e^{i(kz - \omega t)}$, $\hat{A} = A e^{i\delta}$

$f(z, t) = \text{Re}[f(z, t)]$

Reflection & Transmission

$f(z, t) = \begin{cases} \hat{A}_{\text{I}} e^{i(k_1 z - \omega t)} + \hat{A}_{\text{R}} e^{i(-k_1 z - \omega t)} & z < 0 \\ \hat{A}_{\text{T}} e^{i(k_2 z - \omega t)} & z > 0 \end{cases}$

At knot

$f(0^-, t) = f(0^+, t)$, $\frac{\partial f}{\partial z} \Big|_{0^-} = \frac{\partial f}{\partial z} \Big|_{0^+}$

$\Rightarrow A_{\text{R}} = \frac{v_2 - v_1}{v_2 + v_1} A_{\text{I}}$, $A_{\text{T}} = \frac{2v_2}{v_2 + v_1} A_{\text{I}}$

Polarization

$\hat{n} \uparrow \hat{y}$, \hat{z}

$f(z, t) = \hat{A} e^{i(kz - \omega t)}$, $\hat{n} = \cos\theta \hat{x} + \sin\theta \hat{y}$

Monochromatic Plane waves:

$\vec{E}(z, t) = \vec{E}_0 e^{i(kz - \omega t)}$, $\vec{B} = \vec{B}_0 e^{i(kz - \omega t)}$, $\omega = ck$

$\vec{B}_0 = \frac{k}{\omega} (\hat{z} \times \vec{E}_0)$, $B_0 = \frac{1}{c} E_0$

\vec{k} : propagation vector

\hat{n} : polarization vector

General case: $\vec{E}(\vec{r}, t) = \vec{E}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$

$\vec{B}(\vec{r}, t) = \frac{1}{c} \vec{E}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)} (\hat{k} \times \hat{n})$

$= \frac{1}{c} \hat{k} \times \vec{E}$

Real form: $\vec{E}(\vec{r}, t) = E_0 \cos(\vec{k} \cdot \vec{r} - \omega t + \delta) (\hat{k} \times \hat{n})$

$\vec{B}(\vec{r}, t) = \frac{1}{c} E_0 \cos(\vec{k} \cdot \vec{r} - \omega t + \delta) (\hat{k} \times \hat{n})$

$u = \epsilon_0 E_0^2 \cos^2(kz - \omega t + \delta)$, $\vec{S} = c u \hat{z}$, $\vec{g} = \frac{1}{c} u \hat{z}$

$\langle u \rangle = \frac{1}{2} \epsilon_0 E_0^2$, $\langle \vec{S} \rangle = \frac{1}{2} c \epsilon_0 E_0^2 \hat{z}$, $\langle \vec{g} \rangle = \frac{1}{2c} \epsilon_0 E_0^2 \hat{z}$

Intensity: $I = \langle S \rangle = \frac{1}{2} c \epsilon_0 E_0^2$ average power per unit area

Radiation pressure on perfect absorber

$\Delta p = \langle \vec{g} \rangle A \Delta t \Rightarrow P = \frac{1}{A} \frac{\Delta p}{\Delta t} = \frac{I}{c}$

EM waves in matter: $v = \frac{1}{\sqrt{\epsilon \mu}} = \frac{c}{n}$, $n = \sqrt{\frac{\epsilon \mu}{\epsilon_0 \mu_0}}$

$\epsilon_0 \rightarrow \epsilon$, $\mu_0 \rightarrow \mu$, $c \rightarrow v$

index of refraction, $\sqrt{\epsilon_r}$

Reflection and Transmission at Normal Incidence

$\vec{E}_{\text{I}} \uparrow \vec{E}_{\text{T}}$, $\vec{B}_{\text{I}} \uparrow \vec{B}_{\text{T}}$, $\vec{E}_{\text{R}} \uparrow \vec{E}_{\text{T}}$

$\vec{E}_{\text{OR}} = \frac{1 - \beta}{1 + \beta} \vec{E}_{\text{OI}}$, $\beta = \frac{\mu_1 v_2}{\mu_2 v_1}$

$\vec{E}_{\text{OT}} = \frac{2}{1 + \beta} \vec{E}_{\text{OI}} = \frac{\mu_2 n_1}{\mu_1 n_2} \vec{E}_{\text{OI}}$

$\vec{E}_{\text{OR}} = \frac{v_2 - v_1}{v_2 + v_1} \vec{E}_{\text{OI}}$

$\vec{E}_{\text{OT}} = \frac{2v_2}{v_2 + v_1} \vec{E}_{\text{OI}}$

Reflection & transmission coefficients:

$R = \frac{I_{\text{R}}}{I_{\text{I}}} = \left(\frac{n_2 - n_1}{n_2 + n_1}\right)^2$, $T = \frac{I_{\text{T}}}{I_{\text{I}}} = \frac{4n_1 n_2}{(n_2 + n_1)^2}$, $R + T = 1$

Reflection & Transmission at Oblique Incidence.

First law: $K_{\text{I}} \sin \theta_{\text{I}} = K_{\text{R}} \sin \theta_{\text{R}} = K_{\text{T}} \sin \theta_{\text{T}}$

Second law: $\theta_{\text{I}} = \theta_{\text{R}}$

Third law: $\frac{\sin \theta_{\text{T}}}{\sin \theta_{\text{I}}} = \frac{n_1}{n_2}$ (Snell's law)

Fresnel's equations.

$\vec{E}_{\text{OR}} = \left(\frac{\alpha - \beta}{\alpha + \beta}\right) \vec{E}_{\text{OI}}$, $\vec{E}_{\text{OT}} = \left(\frac{2}{\alpha + \beta}\right) \vec{E}_{\text{OI}}$

$\alpha = \frac{\cos \theta_{\text{T}}}{\cos \theta_{\text{I}}}$, $\beta = \frac{\mu_1 v_1}{\mu_2 v_2} = \frac{\mu_1 n_2}{\mu_2 n_1}$

$R = \left(\frac{\alpha - \beta}{\alpha + \beta}\right)^2$, $T = \alpha \beta \left(\frac{2}{\alpha + \beta}\right)^2$

$$\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{C} \times \vec{A}) = \vec{C} \cdot (\vec{A} \times \vec{B}) = \begin{vmatrix} A_x & A_y & A_z \\ B_x & B_y & B_z \\ C_x & C_y & C_z \end{vmatrix}$$

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B})$$

$$\nabla = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \quad \nabla T = \frac{\partial T}{\partial x} \hat{x} + \frac{\partial T}{\partial y} \hat{y} + \frac{\partial T}{\partial z} \hat{z}$$

$$dT = (\nabla T) \cdot d\vec{l} \quad \nabla \cdot \vec{U} = \frac{\partial U_x}{\partial x} + \frac{\partial U_y}{\partial y} + \frac{\partial U_z}{\partial z}$$

$$\nabla \times \vec{U} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ U_x & U_y & U_z \end{vmatrix} = \hat{x}(\frac{\partial U_z}{\partial y} - \frac{\partial U_y}{\partial z}) + \hat{y}(\frac{\partial U_x}{\partial z} - \frac{\partial U_z}{\partial x}) + \hat{z}(\frac{\partial U_y}{\partial x} - \frac{\partial U_x}{\partial y})$$

Product rules:

$$\nabla(fg) = f \nabla g + g \nabla f$$

$$\nabla(\vec{A} \cdot \vec{B}) = \vec{A} \times (\nabla \times \vec{B}) + \vec{B} \times (\nabla \times \vec{A}) + (\vec{A} \cdot \nabla) \vec{B} + (\vec{B} \cdot \nabla) \vec{A}$$

$$\nabla(f\vec{A}) = f(\nabla \times \vec{A}) + \vec{A} \times \nabla f$$

$$\nabla \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B})$$

$$\nabla \times (f\vec{A}) = f(\nabla \times \vec{A}) - \vec{A} \times \nabla f$$

$$\nabla \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} - (\vec{A} \cdot \nabla) \vec{B} + \vec{A}(\nabla \cdot \vec{B}) - \vec{B}(\nabla \cdot \vec{A})$$

$$\nabla^2 T = \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2}$$

$$\nabla^2 \vec{U} = \nabla^2 U_x \hat{x} + \nabla^2 U_y \hat{y} + \nabla^2 U_z \hat{z}$$

$$\nabla \times (\nabla T) = \vec{0}, \quad \nabla \cdot (\nabla \times \vec{U}) = 0$$

$$\nabla \times (\nabla \times \vec{U}) = \nabla(\nabla \cdot \vec{U}) - \nabla^2 \vec{U}$$

$$\int_C \vec{U} \cdot d\vec{l} = \int_a^b \vec{U}(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

$$\int_S \vec{U} \cdot d\vec{S} = \int \vec{U}(\vec{r}(s,t)) \cdot \left(\frac{\partial \vec{r}}{\partial s} \times \frac{\partial \vec{r}}{\partial t} \right) ds dt$$

$$\int_{\vec{a}}^{\vec{b}} (\nabla T) \cdot d\vec{l} = T(\vec{b}) - T(\vec{a})$$

$$\text{Divergence theorem: } \int_V (\nabla \cdot \vec{U}) dV = \oint_S \vec{U} \cdot d\vec{A}$$

$$\text{Stokes' theorem: } \int_S (\nabla \times \vec{U}) \cdot d\vec{A} = \oint_P \vec{U} \cdot d\vec{l}$$

$$\int_V f(\nabla A) dV = - \int \vec{A} \cdot (\nabla f) dV + \oint f \vec{A} \cdot d\vec{a}$$

Spherical coordinates.

$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases} \quad \begin{cases} \hat{r} = \sin \theta \cos \phi \hat{x} + \sin \theta \sin \phi \hat{y} + \cos \theta \hat{z} \\ \hat{\theta} = \cos \theta \cos \phi \hat{x} + \cos \theta \sin \phi \hat{y} - \sin \theta \hat{z} \\ \hat{\phi} = -\sin \phi \hat{x} + \cos \phi \hat{y} \end{cases} \quad \begin{cases} d\vec{l} = dr \hat{r} + r d\theta \hat{\theta} + r \sin \theta d\phi \hat{\phi} \\ d\vec{a} = r^2 \sin \theta d\theta d\phi \\ d\tau = r^2 \sin \theta dr d\theta d\phi \end{cases}$$

$$\nabla T = \frac{\partial T}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial T}{\partial \theta} \hat{\theta} + \frac{1}{r \sin \theta} \frac{\partial T}{\partial \phi} \hat{\phi}$$

$$\nabla \cdot \vec{U} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta U_\theta) + \frac{1}{r \sin \theta} \frac{\partial U_\phi}{\partial \phi}$$

$$\nabla \times \vec{U} = \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (\sin \theta U_\phi) - \frac{\partial U_\theta}{\partial \phi} \right] \hat{r} + \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial U_r}{\partial \phi} - \frac{\partial}{\partial r} (r U_\phi) \right] \hat{\theta} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r U_\theta) - \frac{\partial U_r}{\partial \theta} \right] \hat{\phi}$$

$$\nabla^2 T = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 T}{\partial \phi^2}$$

$$\frac{d\hat{r}}{dr} = 0, \quad \frac{d\hat{r}}{d\theta} = \hat{\theta}, \quad \frac{d\hat{r}}{d\phi} = \sin \theta \hat{\phi}$$

$$\frac{d\hat{\theta}}{dr} = 0, \quad \frac{d\hat{\theta}}{d\theta} = -\hat{r}, \quad \frac{d\hat{\theta}}{d\phi} = \cos \theta \hat{\phi}$$

$$\frac{d\hat{\phi}}{dr} = 0, \quad \frac{d\hat{\phi}}{d\theta} = 0, \quad \frac{d\hat{\phi}}{d\phi} = -\sin \theta \hat{r} - \cos \theta \hat{\theta}$$

Cylindrical Coordinates

$$\begin{cases} x = r \cos \phi \\ y = r \sin \phi \\ z = z \end{cases} \quad \begin{cases} \hat{r} = \cos \phi \hat{x} + \sin \phi \hat{y} \\ \hat{\phi} = -\sin \phi \hat{x} + \cos \phi \hat{y} \\ \hat{z} = \hat{z} \end{cases} \quad \begin{cases} d\vec{l} = dr \hat{r} + r d\phi \hat{\phi} + dz \hat{z} \\ d\vec{a} = r dr d\phi \hat{z} \end{cases}$$

$$\nabla T = \frac{\partial T}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial T}{\partial \phi} \hat{\phi} + \frac{\partial T}{\partial z} \hat{z}$$

$$\nabla \cdot \vec{U} = \frac{1}{r} \frac{\partial}{\partial r} (r U_r) + \frac{1}{r} \frac{\partial U_\phi}{\partial \phi} + \frac{\partial U_z}{\partial z}$$

$$\nabla \times \vec{U} = \left(\frac{1}{r} \frac{\partial U_z}{\partial \phi} - \frac{\partial U_\phi}{\partial z} \right) \hat{r} + \left(\frac{\partial U_r}{\partial z} - \frac{\partial U_z}{\partial r} \right) \hat{\phi} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r U_\phi) - \frac{\partial U_r}{\partial \phi} \right] \hat{z}$$

$$\nabla^2 T = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \phi^2} + \frac{\partial^2 T}{\partial z^2}$$

$$\text{Derivatives for } \hat{r}, \hat{\phi}, \hat{z} \text{ are all 0 except for } \frac{d\hat{r}}{d\phi} = \hat{\phi}, \quad \frac{d\hat{\phi}}{d\phi} = -\hat{r}$$

$$\int \tan x dx = -\ln |\cos x| + C$$

$$\int \frac{dx}{a^2 - x^2} = \frac{1}{a} \arcsin \frac{x}{a} + C, \quad a > 0 \quad \int \frac{dx}{x^2 - a^2} = \frac{1}{2a} \log \left| \frac{x-a}{x+a} \right| + C$$

$$\int \cot x dx = \ln |\sin x| + C$$

$$\int \frac{1}{\cos^2 x} dx = \tan x + C \quad \int \frac{dx}{x^2 + a^2} = \log |x + \sqrt{x^2 + a^2}| + C \quad \int \frac{dx}{x^2 + a^2} = \frac{1}{a} \arctan \frac{x}{a} + C$$

Surface area elements

$$dS = R d\theta d\phi$$

$$dS = R^2 \sin \theta d\theta d\phi$$

$$d\vec{S} = r \sin \alpha dr d\phi d\theta$$

$$\vec{r}(s,t) \Rightarrow dS = \left\| \frac{\partial \vec{r}}{\partial s} \times \frac{\partial \vec{r}}{\partial t} \right\| ds dt$$

$$d\vec{S} = \left(\frac{\partial \vec{r}}{\partial s} \times \frac{\partial \vec{r}}{\partial t} \right) ds dt$$