

Mining Massive Datasets Dimensionality Reduction SVD&CUR

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Dimensionality Reduction

Compress / reduce dimensionality:

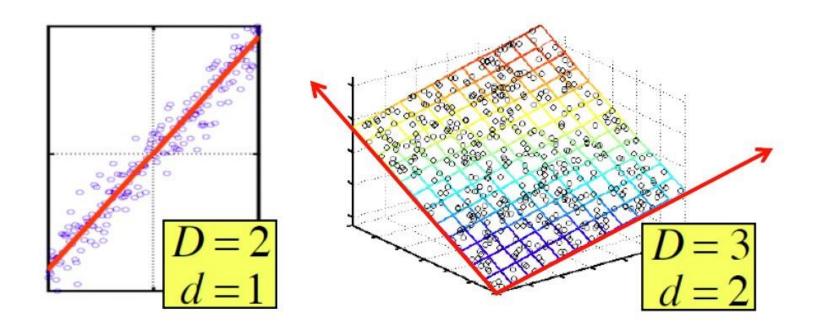
- 10⁶ rows; 10³ columns; no updates
- Random access to any cell(s); small error: OK

\mathbf{day}	We	${f Th}$	\mathbf{F} r	\mathbf{Sa}	Su
customer	7/10/96	7/11/96	7/12/96	7/13/96	7/14/96
ABC Inc.	1	1	1	0	0
DEF Ltd.	2	2	2	0	0
GHI Inc.	1	1	1	0	0
KLM Co.	5	5	5	0	0
\mathbf{Smith}	0	0	0	2	2
$_{ m Johnson}$	0	0	0	3	3
Thompson	0	0	0	1	1

The above matrix is really "2-dimensional." All rows can be reconstructed by scaling [1 1 1 0 0] or [0 0 0 1 1]



Dimensionality Reduction



- Assumption: Data lies on or near a low d-dimensional subspace
- Axes of this subspace are effective representation of the data



Why Reduce Dimensions?

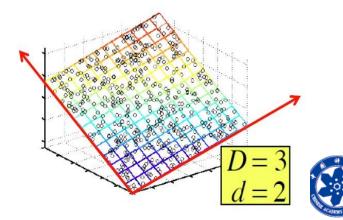
- Some features may be irrelevant
- We want to visualize high dimensional data
- "Intrinsic" dimensionality may be smaller than the number of features
- ■In particular, choose projection that minimizes the squared error in reconstructing original data



Why Reduce Dimensions?

Why reduce dimensions?

- Discover hidden correlations/topics
 - Words that occur commonly together
- Remove redundant and noisy features
 - Not all words are useful
- Interpretation and visualization
- Easier storage and processing of the data



SVD-Definition

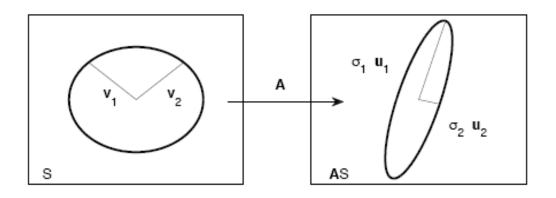
$$A_{[m \times n]} = U_{[m \times r]} \Sigma_{[r \times r]} (V_{[n \times r]})^T$$

- A: Input data matrix
 - \blacksquare $m \times n$ matrix (e.g., m documents, n terms)
- U: Left singular vectors
 - $m \times r$ matrix (m documents, r concepts)
- Σ: Singular values
 - $r \times r$ diagonal matrix (strength of each 'concept') (r: rank of the matrix A)
- V: Right singular vectors
 - \blacksquare $n \times r$ matrix (n terms, r concepts)



SVD-decomposition

 The SVD, much as illustrated in the following figure, is essentially a transformation that stretches/compresses and rotates a given set of vectors



the transformation from the unit sphere to the hyperellipse

$$\mathbf{A}\mathbf{v}_j = \sigma_j \mathbf{u}_j,$$
$$\mathbf{A}^T \mathbf{u}_i = \sigma_j \mathbf{v}_j.$$

$$\mathbf{A}^T \mathbf{u}_i = \sigma_j \mathbf{v}_j.$$



SVD-Eigenvalue & Eigenvector

Given a n x n matrix A^TA , for any σ and v, if

$$A^T A v_j = \sigma_j v_j$$

Then σ is called eigenvalue, and w is called eigenvector.

To gain insight into the SVD, treat the rows of an m×n matrix A as n points in a n-dimensional space and consider the problem of finding the best r-dimensional subspace with respect to the set of points. Here best means minimize the sum of the squares of the perpendicular distances of the points to the subspace.



SVD-decomposition

 The objective of the rotation transformation is to find the maximal variance. We Projection of data along v is Av. Variance:

$$\sigma^2 = (Av)^T (Av) = v^T A^T A v$$

where A^TA is the covariance matrix of the data

Objective: maximize variance subject to constraint $v^Tv=1$.

Maximize
$$f = v^T A^T A v - \lambda (v^T v - 1)$$

 λ is the Lagrange multiplier, Differentiating with respect to vyields Eigenvalue equation:

$$A^T A v = \lambda v$$



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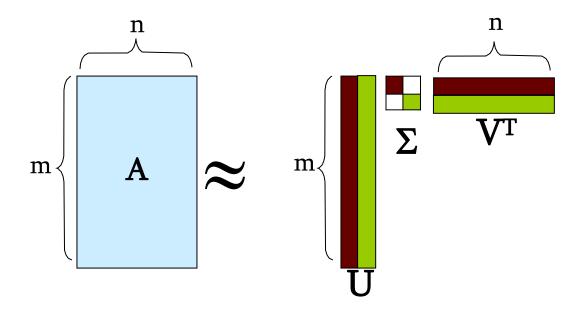
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SVD

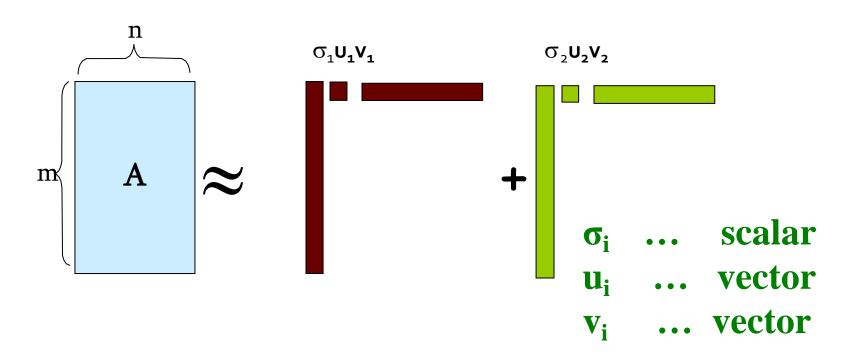
$$\mathbf{A} pprox \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i^\mathsf{T}$$





SVD

$$\mathbf{A} pprox \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i^{\mathsf{T}}$$





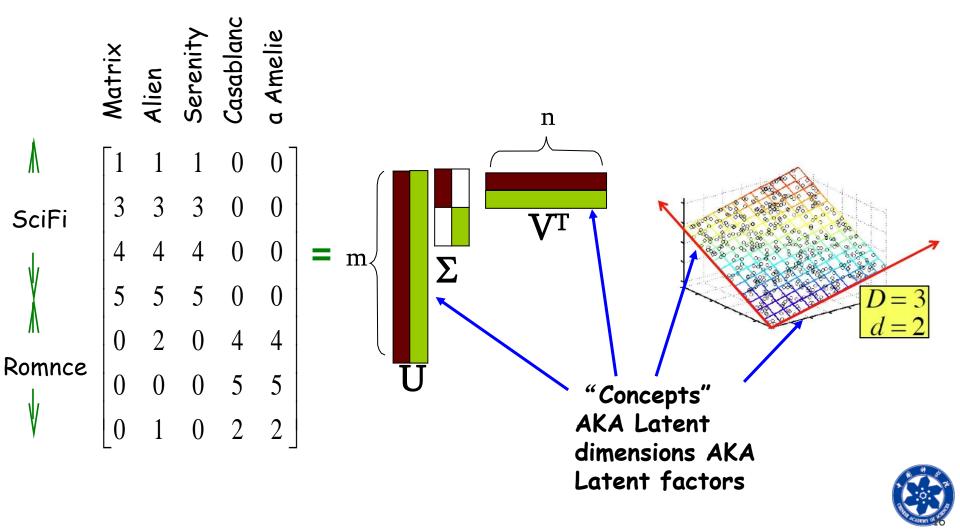
SVD

It is always possible to decompose a real matrix A into $A = U \sum V^{T}$, where

- \blacksquare U, Σ , V: unique
- U, V: column orthonormal
 - $U^T U = I^T V^T V = I (I^T identity matrix)$
 - (Columns are orthogonal unit vectors)
- Σ: diagonal
 - Entries (singular values) are positive, and sorted in decreasing order ($\sigma_1 \geq \sigma_2 \geq ... \geq 0$)



• $A = U\Sigma V^T$ - example: Users to Movies



■ $A = U\Sigma V^T$ – example: Users to Movies

$$\uparrow \text{ SciFi}$$
SciFi
$$\downarrow \text{ Romnce}$$

$$\downarrow \text{ Romnce}$$

$$\downarrow \text{ 0 1 0 2 2}$$

$$\downarrow \text{ 0 1 0 2 2}$$

$$\downarrow \text{ 0 1 0 2 2}$$
SciFi
$$\downarrow \text{ 0 0 0 0 5 5 5}$$

$$0 1 0 2 0 4 4 4$$

$$0 0 0 0 0 5 5$$

$$0 0 0 0 0 5 5$$

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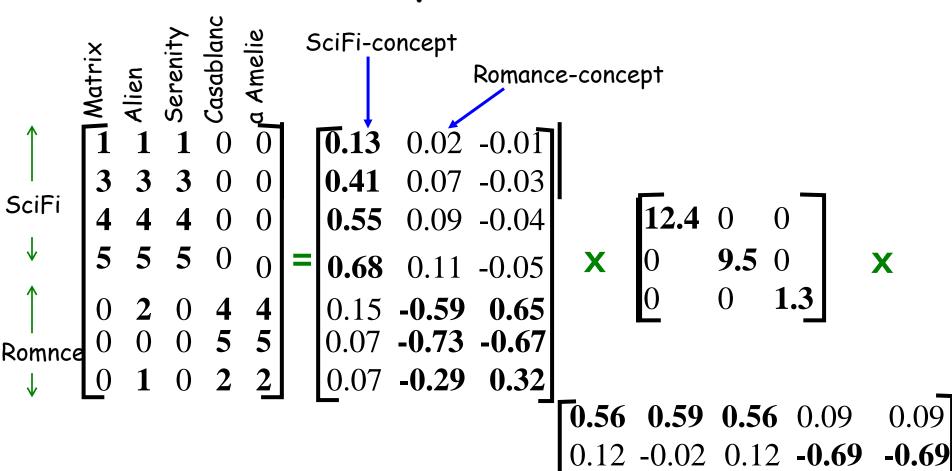
$$0 0 0 0 0 0$$

$$0 0 0 0 0 0$$

$$0 0 0$$



■ $A = U\Sigma V^T$ - example: Users to Movies



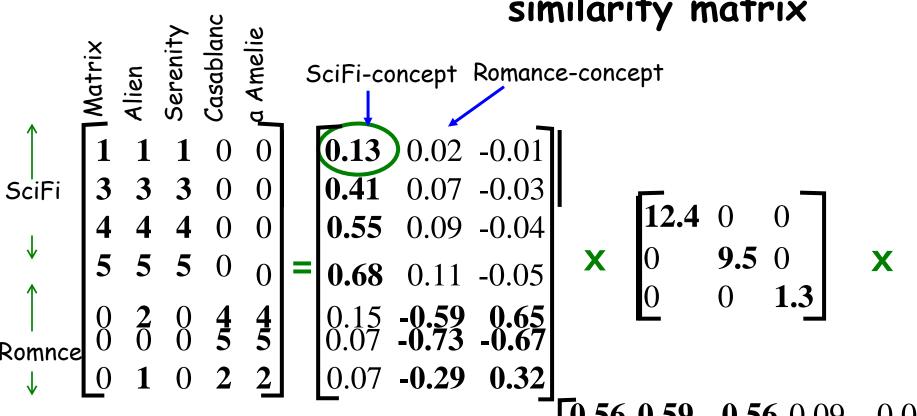


0.09

0.09

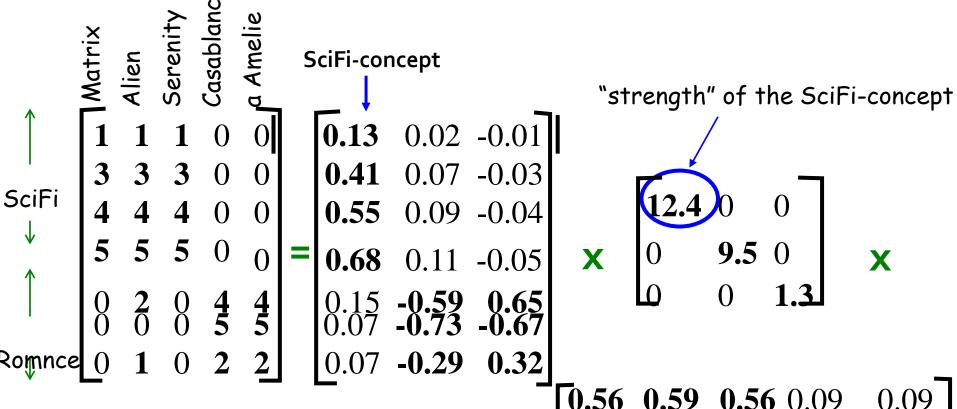
0.40 **-0.80** 0.40

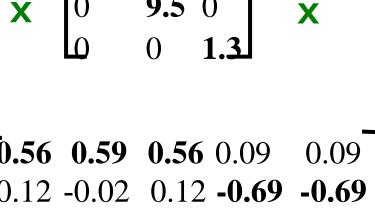
■ $A = U\Sigma V^T$ - example: U is "user-to-concept" similarity matrix





example:



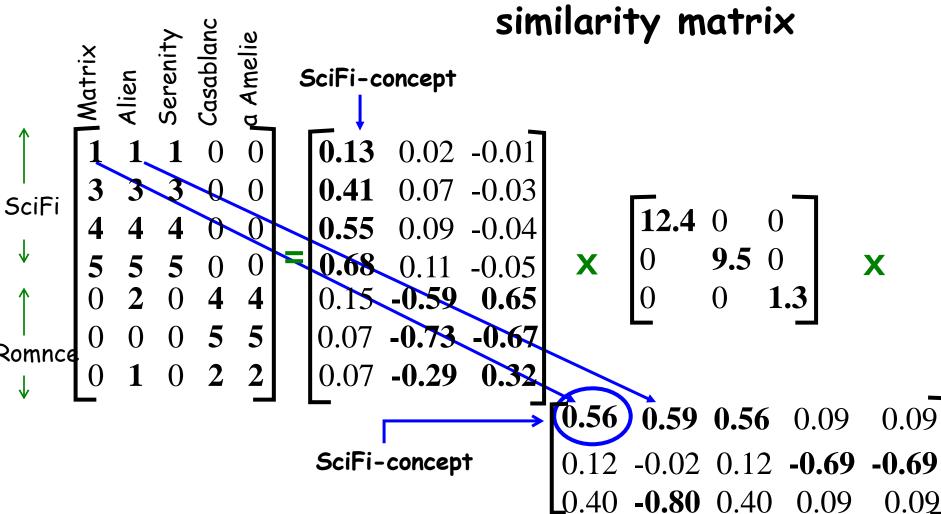


0.40 0.09

0.40 -0.80



■ $A = U\Sigma V^T$ - example: V is "movie-to-concept" similarity matrix





'movies', 'users' and 'concepts':

- U: user-to-concept similarity matrix
- V: movie-to-concept similarity matrix
- $\bullet \Sigma$: its diagonal elements: 'strength' of each concept

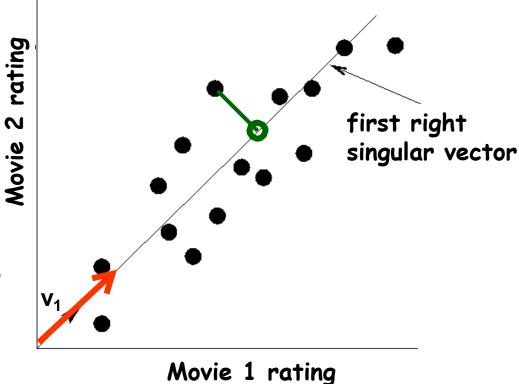


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 SVD gives 'best' axis to project on:

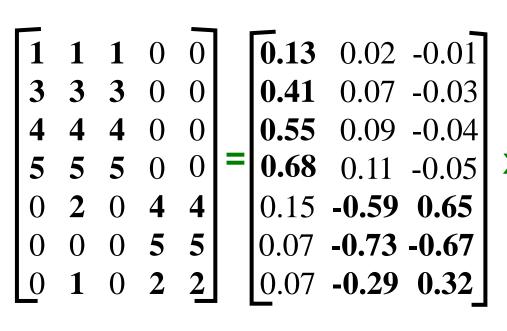
'best' = min sum of squares of projection errors

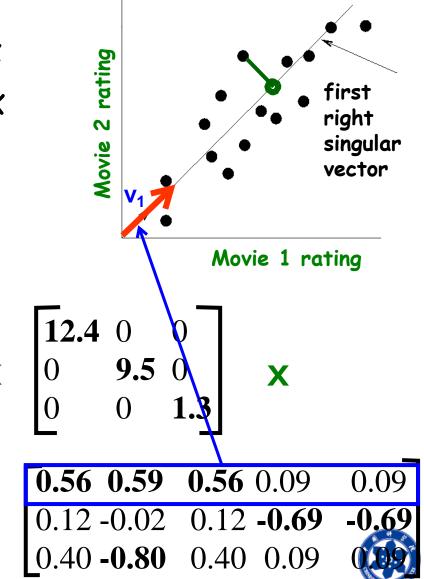
In other words, minimum reconstruction error



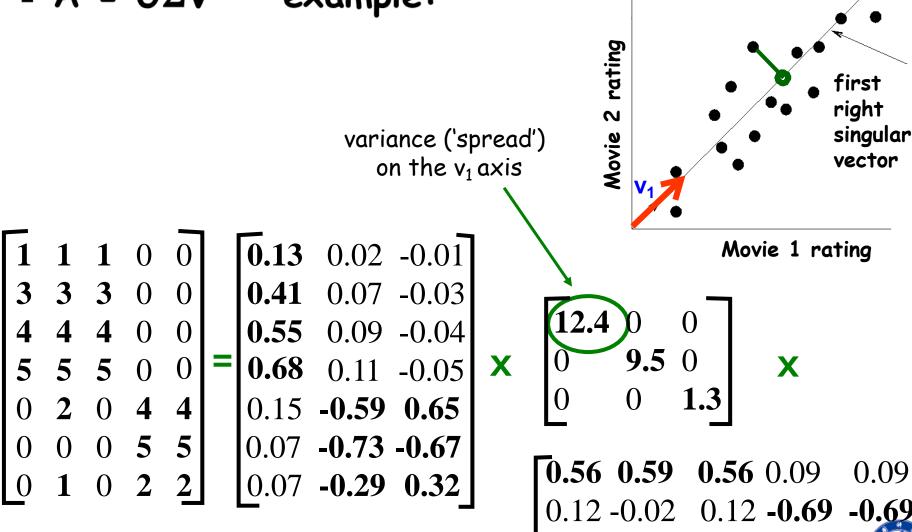


- $A = U\Sigma V^T$ example:
 - V: "movie-to-concept" matrix
 - U: "user-to-concept" matrix



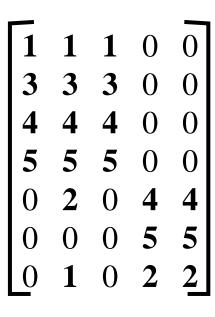




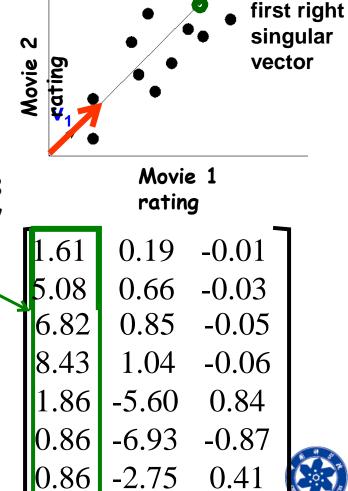


0.40

- $A = U\Sigma V^T$ example:
 - UΣ: Gives the coordinates of the points in the projection axis



Projection of users on the "Sci-Fi" axis $(U\Sigma)^T$



More details

Q: How exactly is dim. reduction done?



- Q: How exactly is dim. reduction done?
- A: Set smallest singular values to zero



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$$\begin{bmatrix}
1 & 1 & 1 & 0 & 0 \\
3 & 3 & 3 & 0 & 0 \\
4 & 4 & 4 & 0 & 0 \\
5 & 5 & 5 & 0 & 0
\end{bmatrix}$$

$$\begin{bmatrix}
0.13 & 0.0 \\
0.41 & 0.0 \\
0.55 & 0.0 \\
0.68 & 0.1 \\
0.15 & -0.5 \\
0.07 & -0.7 \\
0.07 & -0.7 \\
0.07 & -0.7$$

```
0.13 0.02 -0.01
     0.07 -0.03
0.09 -0.04
0.68 0.11 -0.05
      -0.59
      -0.73 -0.67
0.07 -0.29 0.32
```



- Q: How exactly is dim. reduction done?
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$$\begin{bmatrix} \mathbf{1} & \mathbf{1} & \mathbf{1} & 0 & 0 \\ \mathbf{3} & \mathbf{3} & \mathbf{3} & 0 & 0 \\ \mathbf{4} & \mathbf{4} & \mathbf{4} & 0 & 0 \\ \mathbf{5} & \mathbf{5} & \mathbf{5} & 0 & 0 \\ 0 & \mathbf{2} & 0 & \mathbf{4} & \mathbf{4} \\ 0 & 0 & 0 & \mathbf{5} & \mathbf{5} \\ 0 & \mathbf{1} & 0 & \mathbf{2} & \mathbf{2} \end{bmatrix} \approx \begin{bmatrix} \mathbf{0.13} & 0.02 \\ \mathbf{0.41} & 0.07 \\ \mathbf{0.55} & 0.09 \\ \mathbf{0.68} & 0.11 \\ 0.15 & \mathbf{-0.59} \\ 0.07 & \mathbf{-0.73} \\ 0.07 & \mathbf{-0.73} \\ 0.07 & \mathbf{-0.29} \end{bmatrix} \times \begin{bmatrix} \mathbf{12.4} & 0 \\ 0 & \mathbf{9.5} \end{bmatrix} \times \begin{bmatrix} \mathbf{12.4} & 0 \\ 0 & \mathbf{9.5} \end{bmatrix} \times \begin{bmatrix} \mathbf{0.56} & \mathbf{0.59} & \mathbf{0.56} & 0.09 & 0.09 \\ 0.12 & \mathbf{-0.02} & 0.12 & \mathbf{-0.69} & \mathbf{-0.69} \end{bmatrix}$$



More details

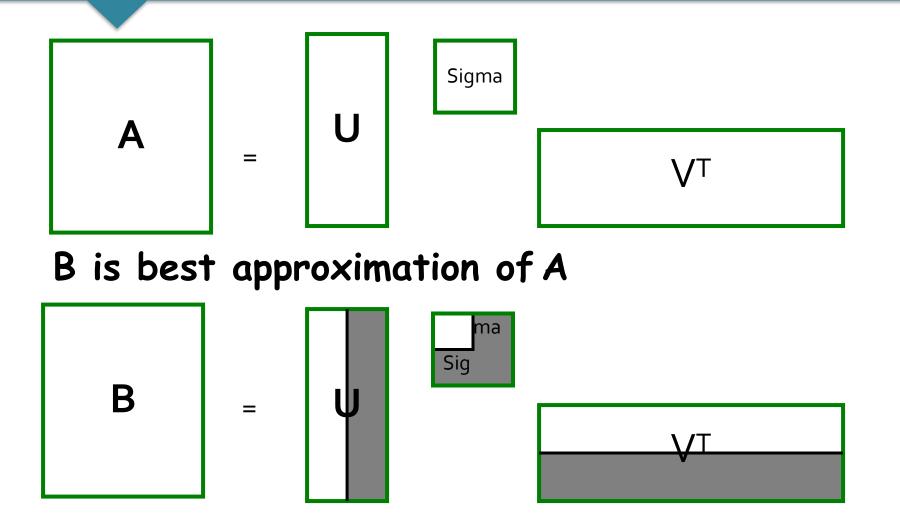
- Q: How exactly is dim. reduction done?
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Frobenius norm:

$$\|\mathbf{M}\|_{\mathrm{F}} = \sqrt{\sum_{ij} \mathbf{M}_{ij}^2}$$

$$\|\mathbf{A} - \mathbf{B}\|_F = \sqrt{\Sigma_{ij}} \; (\mathbf{A}_{ij} - \mathbf{B}_{ij})^2$$
 is "small"







- Theorem: Let $A = U \Sigma V^T$ $(\sigma_1 \ge \sigma_2 \ge ..., rank(A) = r)$ then $B = U S V^T$
- S = diagonal nxn matrix where $s_i = \sigma_i$ (i=1...k) else $s_i = 0$ is a best rank-k approximation to A:
- B is a solution to $min_B \|A-B\|_F$ where rank(B)=k

$$\begin{pmatrix} x_{11} & x_{12} & \dots & x_{1n} \\ x_{21} & x_{22} & \dots & & \\ \vdots & \vdots & \ddots & & \\ x_{m1} & & & x_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & \dots & & \\ \vdots & \ddots & & \\ u_{m1} & & & \\ & & & & \\ & & & & \\ \end{pmatrix} \begin{pmatrix} \mathbf{\Sigma} & & & \mathbf{V}^\mathsf{T} \\ \boldsymbol{\sigma}_1 & 0 & \dots \\ 0 & \ddots & & \\ \vdots & \ddots & & \\ \vdots & \ddots & & \\ r \times r \end{pmatrix} \begin{pmatrix} v_{11} & \dots & v_{1n} \\ \vdots & \ddots & & \\ \vdots & \ddots & & \\ r \times r \end{pmatrix}$$

We will need 2 facts:

- $||\mathbf{M}||_F = \sum_i (q_{ii})^2$ where $\mathbf{M} = \mathbf{P} \mathbf{Q} \mathbf{R}$ is SVD of \mathbf{M}
- $\mathbf{U} \Sigma \mathbf{V}^{\mathsf{T}} \mathbf{U} \mathbf{S} \mathbf{V}^{\mathsf{T}} = \mathbf{U} (\Sigma \mathbf{S}) \mathbf{V}^{\mathsf{T}}$



We will need 2 facts:

 $\blacksquare |M|_F = \sum_k (q_{kk})^2$ where M = PQR is SVD of M

$$||M|| = \sum_{i} \sum_{j} (m_{ij})^{2} = \sum_{i} \sum_{j} \left(\sum_{k} \sum_{\ell} p_{ik} q_{k\ell} r_{\ell j}\right)^{2}$$

$$||M|| = \sum_{i} \sum_{j} \sum_{k} \sum_{\ell} \sum_{n} \sum_{m} p_{ik} q_{k\ell} r_{\ell j} p_{in} q_{nm} r_{mj}$$

 $\sum_{i} p_{ik} p_{in}$ is 1 if k = n and 0 otherwise

■ U ΣV^{T} - U S V^{T} = U (Σ - S) V^{T}

We apply:

- -- P column orthonormal
- -- R row orthonormal
- -- Q is diagonal

- \blacksquare $A = U \Sigma V^T$, $B = U S V^T (\sigma_1 \ge \sigma_2 \ge ... \ge 0, rank(A) = r)$
- S = diagonal $n \times n$ matrix where $s_i = \sigma_i$ (i = 1...k) else $s_i = 0$ then B is solution to $\min_B \|A B\|_F$, $\operatorname{rank}(B) = k$
- Why?

$$\min_{B, rank(B) = k} \|A - B\|_F = \min \|\Sigma - S\|_F = \min_s \sum_{i=1}^{\infty} (\sigma_i^2 - s_i^2)$$
We used: U Σ VT - U Σ VT = U $(\Sigma$ - Σ) VT

- We want to choose \mathbf{s}_i to minimize $\sum (\sigma_i s_i)^2$
 - We set $s_i = \sigma_i$ (i=1...k) and other $s_i = 0$

$$= \min_{s_i} \sum_{i=1}^{\infty} (\sigma_i - s_i)^2 + \sum_{i=k+1}^{\infty} \sigma_i^2 = \sum_{i=k+1}^{\infty} \sigma_i^2$$



Equivalent:

'spectral decomposition' of the matrix:

$$\begin{bmatrix} \mathbf{1} & \mathbf{1} & \mathbf{1} & 0 & 0 \\ \mathbf{3} & \mathbf{3} & \mathbf{3} & 0 & 0 \\ \mathbf{4} & \mathbf{4} & \mathbf{4} & 0 & 0 \\ \mathbf{5} & \mathbf{5} & \mathbf{5} & 0 & 0 \\ 0 & \mathbf{2} & 0 & \mathbf{4} & \mathbf{4} \\ 0 & 0 & 0 & \mathbf{5} & \mathbf{5} \\ 0 & \mathbf{1} & 0 & \mathbf{2} & \mathbf{2} \end{bmatrix} = \begin{bmatrix} \begin{vmatrix} & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ \end{bmatrix} \times \begin{bmatrix} \sigma_1 & \swarrow & & & \\ & \swarrow & \sigma_2 \end{bmatrix} \times \begin{bmatrix} \sigma_1 & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ \end{bmatrix}$$



Equivalent:

'spectral decomposition' of the matrix:

thing to do?

Vectors \mathbf{u}_i and \mathbf{v}_i are unit length, so $\mathbf{\sigma}_i$ scales them.

So, zeroing small σ_i introduces less error

SVD-Interpretation #2

Q: How many σ_s to keep? A: Rule-of-a thumb:

keep 80-90% of 'energy' $(=\sum \sigma_i^2)$

$$\begin{vmatrix}
1 & 1 & 1 & 0 & 0 \\
3 & 3 & 3 & 0 & 0 \\
4 & 4 & 4 & 0 & 0 \\
5 & 5 & 5 & 0 & 0 \\
0 & 2 & 0 & 4 & 4 \\
0 & 0 & 0 & 5 & 5 \\
0 & 1 & 0 & 2 & 2
\end{vmatrix} = \sigma_{1} \quad U_{1} \quad V^{T}_{1} + \sigma_{2} \quad U_{2} \quad V^{T}_{2} + \dots$$

$$Assume: \sigma_{1} \geq \sigma_{2} \geq \sigma_{3} \geq \dots$$



SVD-Complexity

- To compute SVD:
 - $O(nm^2)$ or $O(n^2m)$ (whichever is less)
 - But:
 - Less work, if we just want singular values
 - or if we want first k singular vectors
 - or if the matrix is sparse
 - Implemented in linear algebra packages like
 - LINPACK, Matlab, SPlus, Mathematica ...



SVD-Conclusions so far

- SVD: $A = U \Sigma V^{T}$: unique
 - U: user-to-concept similarities
 - V: movie-to-concept similarities
 - Σ : strength of each concept
 - Dimensionality reduction:
 - keep the few largest singular values (80-90% of 'energy')
 - SVD: picks up linear correlations



Relation to Eigen-decompositon

SVD gives us:

- $\blacksquare A = U \Sigma V^T$
- Eigen-decomposition:
 - $\blacksquare A = X \Lambda X^T$
 - A is symmetric
 - U, V, X are orthonormal (**U**^T**U**=**I**),
 - Λ, Σare diagonal
- What is:
 - $AA^{\top} = U\Sigma V^{\top}(U\Sigma V^{\top})^{\top} = U\Sigma V^{\top}(V\Sigma^{T}\Sigma U^{\top}) = U^{\top}\Sigma\Sigma^{T}U^{\top}$



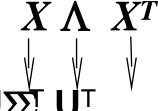
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- What is:
 - $\mathbf{A}\mathbf{A}^{\mathsf{T}} = \mathbf{U}\Sigma\mathbf{V}^{\mathsf{T}}(\mathbf{U}\Sigma\mathbf{V}^{\mathsf{T}})^{\mathsf{T}} = \mathbf{U}\Sigma\mathbf{V}^{\mathsf{T}}(\mathbf{V}\Sigma\mathbf{U}^{\mathsf{T}}) = \mathbf{U}\Sigma\Sigma^{\mathsf{T}}\mathbf{U}^{\mathsf{T}}$

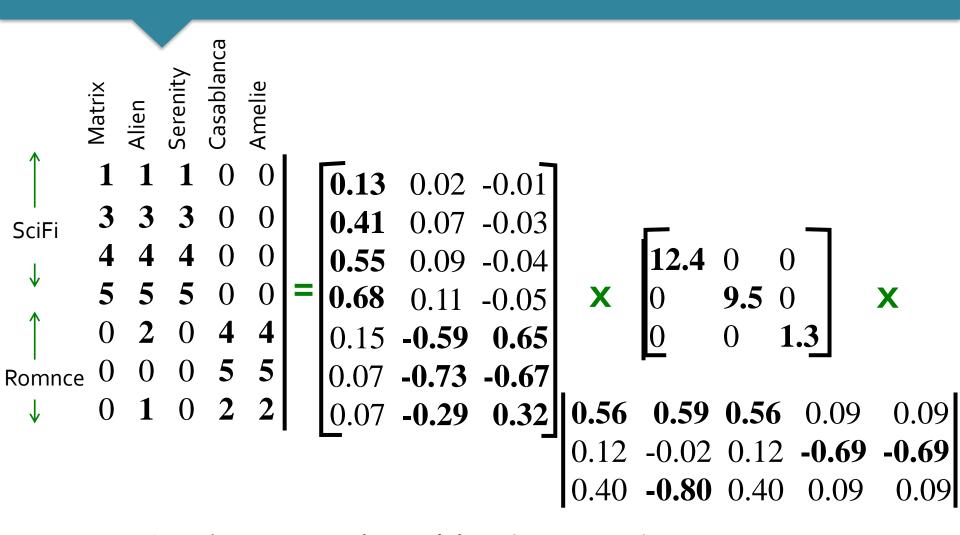
Shows how to compute SVD using eigenvalue decomposition!





So,
$$\lambda_i = \sigma_i^2$$



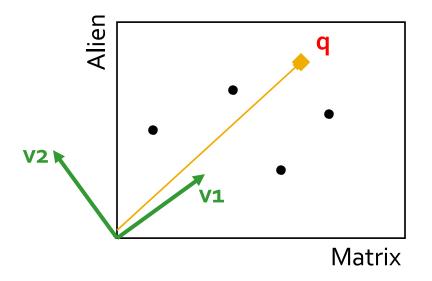


- Q: Find users that like 'Matrix'
- A: Map query into a 'concept space' how?



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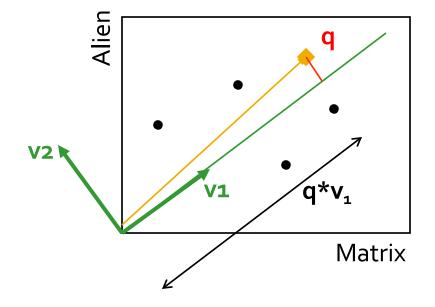
Project into concept space: Inner product with each 'concept' vector **v**_i





- Q: Find users that like 'Matrix'
- A: Map query into a 'concept space' how?

Project into concept space: Inner product with each 'concept' vector **v**_i





Compactly, we have: 9concept = 9 V

E.g.:

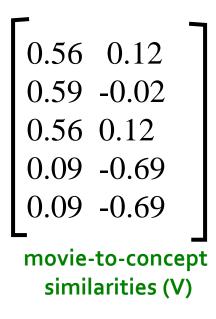
q =
$$\begin{bmatrix} 5 & 0 & 0 & 0 & 0 \end{bmatrix}$$
 X $\begin{bmatrix} 0.56 & 0.12 \\ 0.59 & -0.02 \\ 0.56 & 0.12 \\ 0.09 & -0.69 \\ 0.09 & -0.69 \end{bmatrix}$ = $\begin{bmatrix} 2.8 & 0.6 \end{bmatrix}$ movie-to-concept similarities (V)

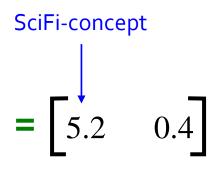


 How would the user d that rated ('Alien', 'Serenity') be handled?

$$\mathbf{q} = \begin{bmatrix} 0 & 4 & 5 & 0 & 0 \end{bmatrix} \mathbf{X}$$

$$\begin{bmatrix} 0.56 & 0.12 \\ 0.59 & -0.02 \\ 0.56 & 0.12 \\ 0.09 & -0.69 \\ 0.09 & -0.69 \\ 0.09 & -0.69 \end{bmatrix}$$







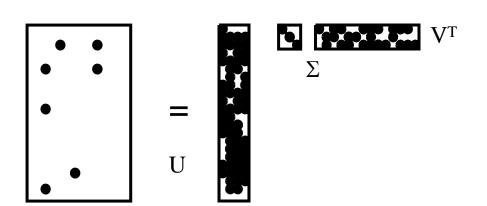
Observation: User d that rated ('Alien', 'Serenity') will be similar to user q that rated ('Matrix'), although d and q have zero ratings in common!



SVD: Drawbacks

Optimal low-rank approximation in terms of Frobenius norm

- Interpretability problem:
 - A singular vector specifies a linear combination of all input columns or rows
- Lack of sparsity:
 - Singular vectors are dense!



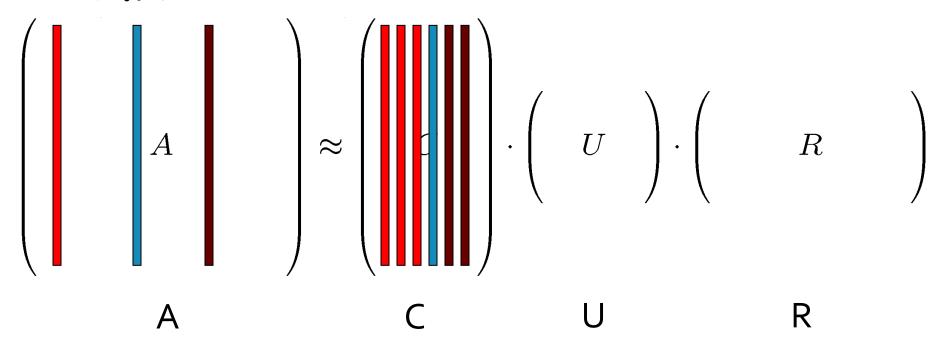


CUR Decomposition



$$\|\mathbf{X}\|_{\mathbf{F}} = \sum_{ij} \mathbf{X}_{ij}^{2}$$

 Goal: Express A as a product of matrices C,U,R Make ||A-C·U·R||_F small



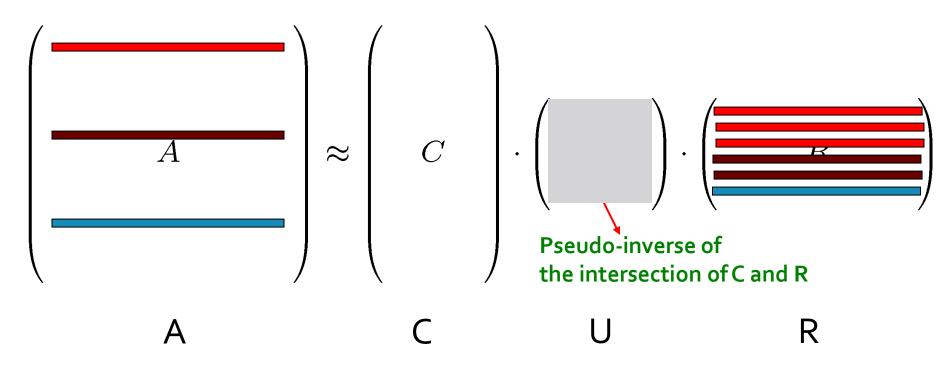


CUR Decomposition

Frobenius norm:

$$\|\mathbf{X}\|_{\mathbf{F}} = \sum_{ij} \mathbf{X}_{ij} \quad ^{2}$$

- Goal: Express A as a product of matrices
 C,U,R Make ||A-C·U·R||_F small
- "Constraints" on C and R:





CUR: Provably good approx.to SVD

Let:

 A_k be the "best" rank k approximation to A (that is, A_k is SVD of A)

Theorem [Drineas et al.]

CUR in $O(\mathbf{m} \cdot \mathbf{n})$ time achieves

- $\|\mathbf{A}\text{-}\mathbf{C}\mathbf{U}\mathbf{R}\|_{\mathbf{F}} \leq \|\mathbf{A}\|_{\mathbf{F}} + \varepsilon \|\mathbf{A}\|_{\mathbf{F}}$ with probability at least $\mathbf{1}$ - δ by picking
- O(k log(1/ δ) / ϵ^2) columns, and
 - $O(k^2 \log^3(1/\delta)/\epsilon^6)$ rows

In practice:
Pick 4k
cols/rows



CUR: How it Works

Sampling columns (similarly for rows):

Input: matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$, sample size c

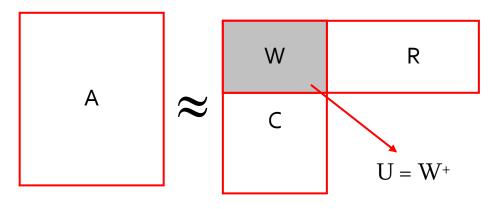
Output: $\mathbf{C}_d \in \mathbb{R}^{m \times c}$

- 1. for x = 1 : n [column distribution]
- 2. $P(x) = \sum_{i} \mathbf{A}(i, x)^{2} / \sum_{i,j} \mathbf{A}(i, j)^{2}$
- 3. for i = 1 : c [sample columns]
- 4. Pick $j \in 1 : n$ based on distribution P(x)
- 5. Compute $\mathbf{C}_d(:,i) = \mathbf{A}(:,j)/\sqrt{cP(j)}$



Computing U

- Let W be the "intersection" of sampled columns C and rows R
 - Let SVD of W = X Z Y^T
- Then: U = W⁺ = Y Z⁺ X^T
 - $Z_{:}$: reciprocals of non-zero singular values: $Z_{::}^{t} = 1/Z_{::}$
 - W⁺ is the "pseudoinverse"



Why pseudoinverse works?

W = X Z Y then $W^{-1} = X^{-1} Z^{-1} Y^{-1}$ Due to orthonomality $X^{-1} = X^T$ and $Y^{-1} = Y^T$

Since Z is diagonal $Z = 1/Z_{ii}$ **Thus**, if **W** is nonsingular, pseudoinverse is the true inverse



CUR: Pros&Cons

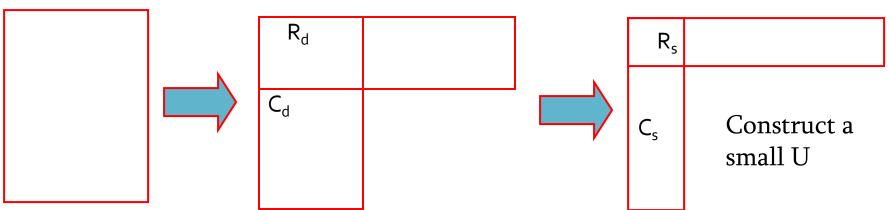
- + Easy interpretation
- Since the basis vectors are actual columns and rows
- + Sparse basis
- Since the basis vectors are actual Singular vectors columns and rows
- Duplicate columns and rows
 - Columns of large norms will be sampled many times



Solution

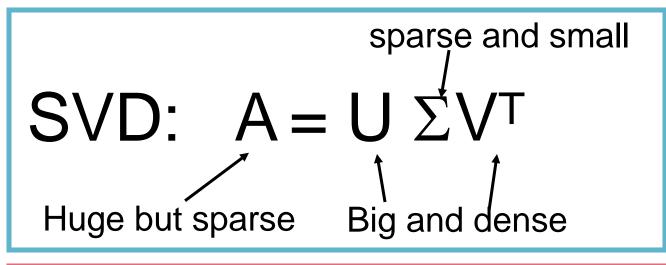
If we want to get rid of the duplicates:

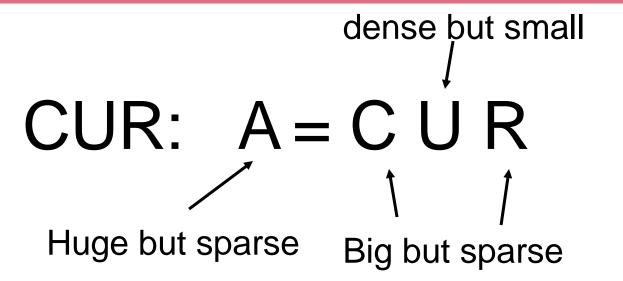
- Throw them away
- Scale (multiply) the columns/rows by the square root of the number of duplicates





SVD VS. CUR







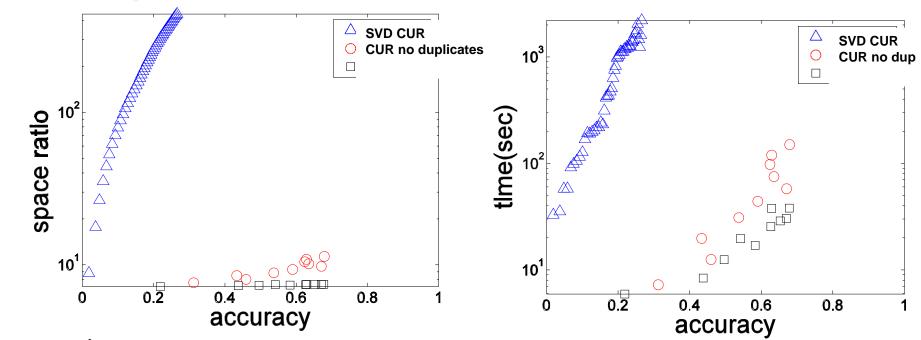
Simple Experiment

DBLP bibliographic data

- Author-to-conference big sparse matrix
- A_{ij} : Number of papers published by author i at conference j
- 428K authors (rows), 3659 conferences (columns)
 - Very sparse
- Want to reduce dimensionality
 - How much time does it take?
 - What is the reconstruction error?
 - How much space do we need?



Results: DBLP-big sparse matrix



Accuracy:

1 - relative sum squared errors

Space ratio:

#output matrix entries / #input matrix entries

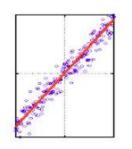
CPU time

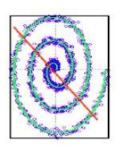


What about linearity assumption?

SVD is limited to linear projections:

 Lower-dimensional linear projection that preserves Euclidean distances

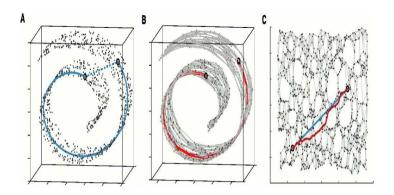




- Non-linear methods: Isomap
- Data lies on a nonlinear low-dim curve aka manifold
 - Use the distance as measured along the manifold

How?

- Build adjacency graph
- Geodesic distance is graph distance
- SVD/PCA the graph pairwise distance matrix





Further Reading: CUR

- Drineas et al., Fast Monte Carlo Algorithms for Matrices III: Computing a Compressed Approximate Matrix Decomposition, SIAM Journal on Computing, 2006.
- J. Sun, Y. Xie, H. Zhang, C. Faloutsos: Less is More: Compact Matrix Decomposition for Large Sparse Graphs, SDM 2007
- Intra- and interpopulation genotype reconstruction from tagging SNPs, P. Paschou, M. W. Mahoney, A. Javed, J. R. Kidd, A. J. Pakstis, S. Gu, K. K. Kidd, and P. Drineas, Genome Research, 17(1), 96-107 (2007)
- Tensor-CUR Decompositions For Tensor-Based Data,
 M. W. Mahoney, M. Maggioni, and P. Drineas, Proc. 12-th Annual SIGKDD, 327-336 (2006)



Tell me and I forget.

Show me and I remember.

Involve me and I understand.

 \bullet \bullet \bullet \bullet \bullet \bullet \bullet

Thank you! Q&A



