Example 5 EIZ, mz = court We want to study the free vibrations of NZ(xxx) this statically indeterminate system. $EJ_1, W_1 = caust$ Sechul 2 Section 1 $EI_{1}\frac{9v_{1}}{9x_{1}^{4}}+m_{1}\frac{9v_{1}}{9t^{2}}=0, \quad 0\leq x_{1}\leq L_{1}, t>0$ $EI_2 \frac{\partial^4 v_2}{\partial x_1^2} + m_2 \frac{\partial v_1}{\partial x_2} = 0 \quad 0 < x_2 < L_2$ $V_{2}(0,t)=0$, $V_{2}(L_{2},t)=0$, $EL_{1}\frac{\partial V_{2}(L_{2})}{\partial X_{1}}$ $V_1(0,t)=0$ $V_1(L_0,t)=0$ Note that, we deside identa mue dependencies since we we seeking named wholes We proceed by separation of space and time => v, (x,+) = (x,) f(+) Then it is every to prove that for should be a houmanic Anchon of to inbration.

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Two segments of the hearm. which we

/www.entag $\varphi_i(0)=0, \quad \varphi_i(L_i)=0$ elel Minchal $G_1''(0)=0$ $EI_1 \circ (I_1) = EI_2 \circ (0)$ G(XI)=Arcor G-XI+BISM G-XI+ +Grosh Exit-Diswh Exx $G_{1}(0)=0 \Rightarrow A_{1}+G=0$ V=) (Ai= G=0) 6//(0)=0=> -A1+G=0 G(4)=0=> 3,5m=4+D,5mh=6-4=0

(2(x2)=A2cos @ x2+ B2sm @ x2+ ナでないとなったがというといんと大き = A2 cos (2-X2)+B2 sun (4-X4)+ + Cz cochie (Lz-Xz)+Dzsmh Ex (Lz-Xz)

Sechon 2

$$\begin{aligned} & \zeta_{1}(L_{1}) = \zeta_{2}(0) \stackrel{>}{\Rightarrow} B_{1} \stackrel{\text{Tw}}{\text{cos}} \cos \frac{\Omega}{C_{1}} L_{1} + D_{1} \frac{\delta \omega}{C_{1}} \cos k \frac{\delta \omega}{C_{1}} L_{1} = \\ & = -B_{2} \stackrel{\text{Tw}}{\text{cos}} \cos \frac{\delta \omega}{C_{2}} L_{2} - D_{2} \stackrel{\text{Tw}}{\text{cos}} \cos k \frac{\delta \omega}{C_{2}} L_{2} \\ & = -B_{2} \stackrel{\text{Tw}}{\text{cos}} \cos \frac{\delta \omega}{C_{2}} L_{2} - D_{2} \stackrel{\text{Tw}}{\text{cos}} \cos k \frac{\delta \omega}{C_{2}} L_{2} \\ & = EI_{2} \left(-B_{1} \left(\stackrel{\text{Tw}}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} + D_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sinh \frac{\delta \omega}{C_{2}} L_{1} \right) \\ & = EI_{2} \left(-B_{1} \left(\stackrel{\text{Tw}}{C_{2}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{2} + D_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sinh \frac{\delta \omega}{C_{2}} L_{1} \right) \\ & = EI_{2} \left(-B_{1} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \right) \\ & = EI_{2} \left(-B_{1} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \right) \\ & = EI_{2} \left(-B_{1} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \right) \\ & = EI_{2} \left(-B_{1} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \right) \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{2} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{2} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{2} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{2} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{2} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{2} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \sin \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \cos \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \cos \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \cos \frac{\delta \omega}{C_{2}} L_{1} \\ & = EI_{2} \left(\frac{\delta \omega}{C_{1}} \right)^{2} \cos \frac{\delta \omega}{C_{2$$

