

# Vibrations due to motions of the supports

Consider again  $EA \frac{\partial^2 u}{\partial x^2} = m \frac{\partial^2 u}{\partial t^2}$ ,  $0 \leq x \leq L$ ,  $t \geq 0$  (1)

Now, let's consider nonhomogeneous boundary conditions, i.e., conditions where time enters explicitly in the expressions,

$$\left. \begin{aligned} u(0, t) &= u_{g1}(t) \\ u(L, t) &= u_{g2}(t) \end{aligned} \right\} (1a)$$

subject to the initial conditions,

$$\left. \begin{aligned} u(x, 0) &= g(x) \\ u_t(x, 0) &= h(x) \end{aligned} \right\} (1b)$$

Because of compatibility we require,

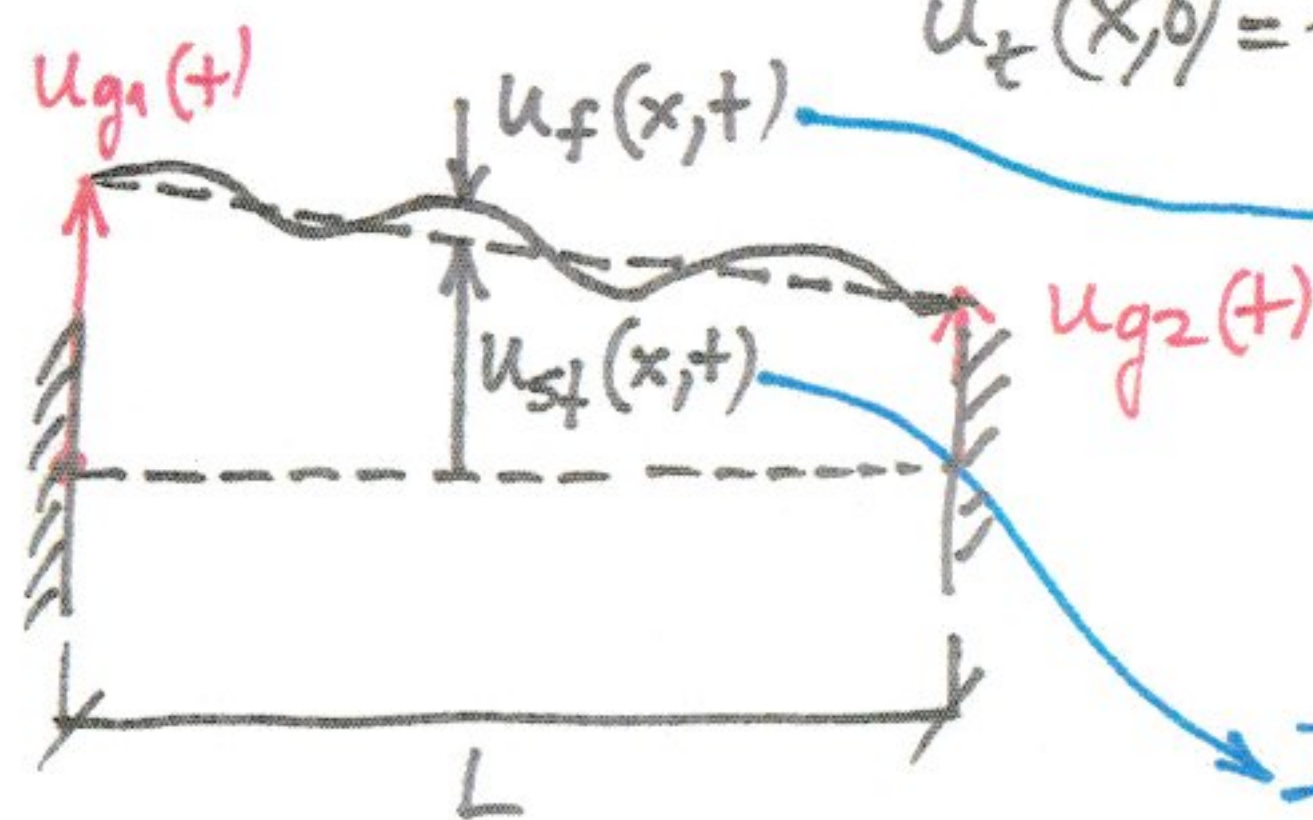
$$u(0, 0) = g(0) = u_{g1}(0)$$

$$u(L, 0) = g(L) = u_{g2}(0)$$

$$u_t(0, 0) = h(0) = u'_{g1}(0)$$

$$u_t(L, 0) = h(L) = u'_{g2}(0)$$

$$( )' \equiv \frac{d}{dt}, \quad ( )_t \equiv \frac{\partial}{\partial t}$$



Now we take into account the inertia forces and compute the flexible deformation from the pseudostatic displacement  $\Rightarrow$  'flexible' response  $u_f(x, t)$

Is only due to the motion of the supports without taking into account the inertia forces of the string  $\Rightarrow$  'pseudo-static' response  $u_{st}(x, t)$



Summarizing, we express the total response  $u(x,t)$  as,

$$u(x,t) = u_{st}(x,t) + u_f(x,t) \quad (2)$$

where,  $u_{st}(0,t) = u_{g1}(t)$  and  $u_{st}(L,t) = u_{g2}(t)$   
 $u_f(0,t) = 0$  and  $u_f(L,t) = 0$

Solving for  $u_{st}(x,t)$

Reconsider the wave equation,  $EA \frac{\partial^2 u}{\partial x^2} = m \frac{\partial^2 u}{\partial t^2} \Rightarrow$  Neglecting the inertia forces (i.e., treating the string as non-flexible),  $EA \frac{\partial^2 u_{st}}{\partial x^2} = 0 \Rightarrow$

$$\Rightarrow u_{st}(x,t) = C_1(t)x + C_2(t) \quad \Rightarrow u_{g1}(t) = C_2(t)$$

But  $u_{st}(0,t) = u_{g1}(t)$

Also,  $u_{st}(L,t) = u_{g2}(t) \Rightarrow u_{g2}(t) = C_1(t)L + u_{g1}(t) \Rightarrow$

$$\Rightarrow C_1(t) = \frac{u_{g2}(t) - u_{g1}(t)}{L}$$

$$\Rightarrow \boxed{u_{st}(x,t) = u_{g1}(t) \left(1 - \frac{x}{L}\right) + u_{g2}(t) \frac{x}{L}}, \quad 0 \leq x \leq L$$

Nonhomogeneous BCs are fully accounted for in  $u_{st}(x,t)$



# Solving for $u_f(x,t)$

Substitute (2) into the governing equation (1)  $\Rightarrow$

$$EA \frac{\partial^2 u_{st}}{\partial x^2} + EA \frac{\partial^2 u_f}{\partial x^2} = m \frac{\partial^2 u_{st}}{\partial t^2} + m \frac{\partial^2 u_f}{\partial t^2} \Rightarrow$$

$$\Rightarrow \underbrace{EA \frac{\partial^2 u_f}{\partial x^2} - m \frac{\partial^2 u_f}{\partial t^2}}_{\text{known function of } x \text{ and } t} = m \frac{\partial^2 u_{st}}{\partial t^2} \equiv f(x,t) \quad (3)$$

$\Rightarrow$  We have transformed the problem for  $u_f(x,t)$  to a <sup>forced</sup> standard problem with simple BCs.

$$u_f(0,t)=0, u_f(L,t)=0 \Rightarrow \quad (3a)$$

$\Rightarrow$  we get 'simple' boundary conditions!

Note on the initial conditions:  $u(x,0)=g(x) \Rightarrow u_{st}(x,0)+u_f(x,0)=g(x) \Rightarrow$

$$\Rightarrow u_f(x,0)=g(x)-u_{st}(x,0) \quad (3b)$$

Similarly we compute the other initial condition,  $u_{f,t}(x,0)=h(x)-u_{st,t}(x,0)$

Hence, (3), (3a) and (3b) form a standard problem that we can solve.