

Vibrating circular plate clamped at its boundary

Consider $\nabla^4 u + \frac{\gamma}{D} u_{tt} = 0$ on $\mathcal{D} = \{0 < r \leq a, 0 \leq \theta < 2\pi\}$

$$u(a, \theta, t) = 0$$

$$u_r(a, \theta, t) = 0$$

$$u, u_r \text{ bounded } \forall 0 \leq r \leq a.$$

Seek solution based on separation of variables, $u(r, \theta, t) = e^{j\omega t} R(r) \Theta(\theta) \Rightarrow$
 \Rightarrow Should require that $\Theta(\theta) = e^{jn\theta}$, $n = 0, 1, 2, \dots$ since otherwise the solution would not be 2π -periodic with respect to $\theta \Rightarrow$

$$\Rightarrow \nabla^4(R\Theta) - \frac{\gamma}{D} \omega^2(R\Theta) = 0 \Rightarrow (\nabla^2 - k^2)(\nabla^2 + k^2)(R\Theta) = 0 \Rightarrow$$

$$\text{Let } \frac{\gamma}{D} \omega^2 \equiv k^4$$

$$\Rightarrow \left\{ \begin{array}{l} (\nabla^2 - k^2)(R\Theta) = 0 \\ (\nabla^2 + k^2)(R\Theta) = 0 \end{array} \right\} \Rightarrow \text{If we satisfy these two equations we have a complete solution.}$$

$$\text{But } \nabla^2 \equiv \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \text{ and } \Theta = e^{jn\theta} \Rightarrow$$

$$\Rightarrow \left\{ \begin{array}{l} \left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} - \frac{n^2}{r^2} - k^2 \right) R = 0 \rightarrow \text{Modified Bessel equation of } n\text{-th order} \\ \left(\frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} + \frac{n^2}{r^2} - k^2 \right) R = 0 \rightarrow \text{Bessel Equation of } n\text{-th order} \end{array} \right.$$

It follows that $R(r)$ should be in the form,

$$R_n(r) = c_1 J_n(kr) + c_2 J_n(jkr)$$

$J_n(jkr) \equiv I_n(kr)$
Modified Bessel function
of the first kind

since only these functions are bounded as $r \rightarrow 0 \Rightarrow$ Let $V(r, \theta) = R(r)\Theta(\theta)$

$$\Rightarrow V_n(r, \theta) = J_n(kr) (a_1 \cos n\theta + b_1 \sin n\theta) + J_n(jkr) (a_2 \cos n\theta + b_2 \sin n\theta)$$

Satisfying the boundary conditions at $r=a \Rightarrow$

$$\Rightarrow u(a, \theta, t) = 0 \Rightarrow \left. \begin{aligned} J_n(ka) a_1 + J_n(jka) a_2 &= 0 & \text{(cosine terms)} \\ J_n(ka) b_1 + J_n(jka) b_2 &= 0 & \text{(sine terms)} \end{aligned} \right\} \Rightarrow$$

$$u_r(a, \theta, t) = 0 \Rightarrow \left. \begin{aligned} J'_n(ka) a_1 + j J'_n(jka) a_2 &= 0 \\ J'_n(ka) b_1 + j J'_n(jka) b_2 &= 0 \end{aligned} \right\}$$

\Rightarrow It should be satisfied that

$$\boxed{\frac{J'_n(ka)}{J_n(ka)} = \frac{j J'_n(jka)}{J_n(jka)}}$$

Frequency equation

\Rightarrow obtain solutions $k_{n1}, k_{n2}, \dots, k_{nm}, \dots$

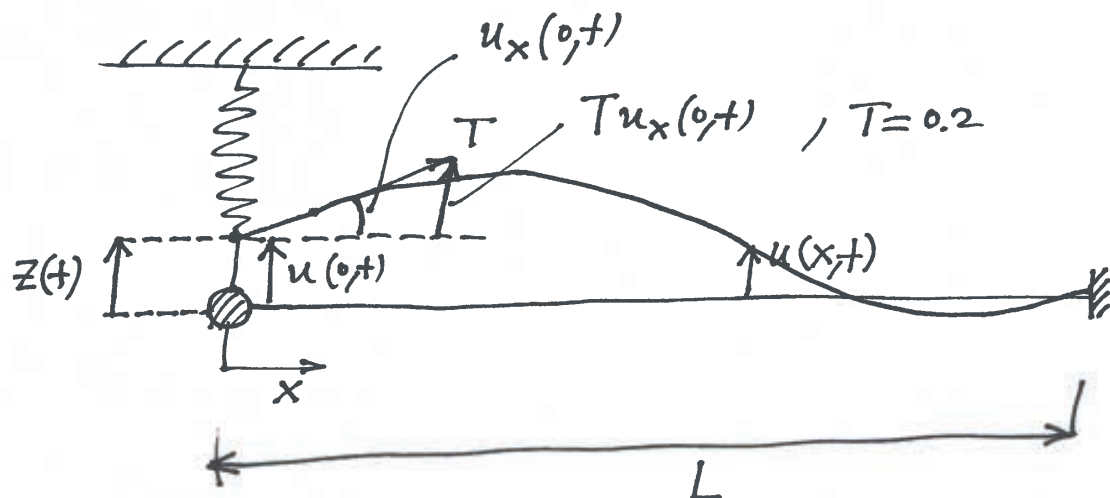
$$\text{So, } \omega_{ni} = \sqrt{\frac{D}{\gamma}} k_{ni}^2, \quad \begin{matrix} n=0, 1, 3, \dots \\ i=1, 2, 3, \dots \end{matrix}$$

$$\text{Hence, } V_{ij}(r, \theta) = \left[J_i\left(\frac{\lambda_{ij} r}{a}\right) - \frac{J_i(\lambda_{ij})}{I_i(\lambda_{ij})} I_i\left(\frac{\lambda_{ij} r}{a}\right) \right] (A_i \cos i\theta + B_i \sin i\theta)$$

Where, $\lambda_{ij} = k_{ij} a$, with corresponding eigenfrequency,

$$\omega_{ij} = \frac{\lambda_{ij}^2}{a^2} \sqrt{\frac{D}{\gamma}}$$

and $i = 0, 1, 2, \dots, j = 1, 2, 3, \dots$



$$\left. \begin{aligned} \frac{d^2 z(t)}{dt^2} + z &= 0.2 u_x(0,t) \\ z(0+) &= 0, \quad \frac{dz}{dt}(0+) = V \end{aligned} \right\} (1)$$



Laplace-transform with respect to time $\Rightarrow \tilde{z}(s) = \mathcal{L}[z(t)] \Rightarrow$

Take (1) $\Rightarrow \mathcal{L} \Rightarrow s^2 \tilde{z}(s) - s z(0+) - \dot{z}(0+) + \tilde{z}(s) = 0.2 \frac{d\tilde{U}(0,s)}{dx},$

where $\tilde{U}(x,s) = \mathcal{L}[u(x,t)] \Rightarrow$

$$\Rightarrow (s^2 + 1) \tilde{z}(s) = 0.2 \frac{d\tilde{U}(0,s)}{dx} + V \quad (3)$$

$$\left. \begin{aligned} u_{xx} - u_{tt} &= 0, \quad 0 < x < L \\ u(x,0) &= u_t(x,0) = 0 \\ u(0,t) &= z(t) \\ u(L,t) &= 0 \end{aligned} \right\} (2)$$

Then \mathcal{L} -transform (2) $\Rightarrow \frac{d^2 \tilde{U}(x,s)}{dx^2} - s^2 \tilde{U}(x,s) + s u(x,0) + u_t(x,0) = 0 \Rightarrow$

$\Rightarrow \frac{d^2 \tilde{U}(x,s)}{dx^2} - s^2 \tilde{U}(x,s) = 0$ (4) \Rightarrow Solving (4) $\Rightarrow \tilde{U}(x,s) = A \cosh[s(L-x)] + B \sinh[s(L-x)]$

$u(L,t) = 0 \xrightarrow{\mathcal{L}} \tilde{U}(L,s) = 0$ (5)

$u(0,t) = Z(t) \xrightarrow{\mathcal{L}} \tilde{U}(0,s) = Z(s)$ (6)

Applying (5) $\Rightarrow \tilde{U}(L,s) = 0 \Rightarrow A = 0$

Applying (6) $\Rightarrow \tilde{U}(0,s) = Z(s) \Rightarrow B \sinh sL = Z(s) \Rightarrow B = \frac{Z(s)}{\sinh sL}$

$\Rightarrow \tilde{U}(x,s) = \frac{Z(s)}{\sinh sL} \sinh[s(L-x)]$ (7a)

Now, substituting (7a) into (3) $\Rightarrow (s^2 + 1) \tilde{Z}(s) = -0.2 s \tilde{Z}(s) \coth(sL) + V \Rightarrow$

$\Rightarrow [s^2 + 0.2 s \coth(sL) + 1] \tilde{Z}(s) = V \Rightarrow \tilde{Z}(s) = \frac{V}{s^2 + 0.2 s \coth(sL) + 1}$ (7b)

Effect of the string interaction!

Unfortunately, no known inverse of (7b) exists...

$$\text{So, } \tilde{Z}(s) = \frac{V}{s^2 + 0.2s \coth sL + 1}$$

$$\begin{aligned} \text{But } \coth(sL) &= \frac{e^{sL} + e^{-sL}}{e^{sL} - e^{-sL}} = \frac{1 + e^{-2sL}}{1 - e^{-2sL}} = \\ &= (1 + e^{-2sL})(1 + e^{-2sL} + e^{-4sL} + e^{-6sL} + \dots) = \\ &= 1 + 2e^{-2sL} + 2e^{-4sL} + 2e^{-6sL} + \dots \end{aligned}$$

$$\text{Hence, } \tilde{Z}(s) = \frac{V}{s^2 + 1 + 0.2s[1 + 2e^{-2sL} + 2e^{-4sL} + 2e^{-6sL} + \dots]} =$$

$$= \frac{V}{(s^2 + 1 + 0.2s) + 0.4s e^{-2sL} [1 + e^{-2sL} + e^{-4sL} + \dots]} =$$

$$= \frac{V}{s^2 + 1 + 0.2s} \left[\frac{1}{1 + \frac{0.4s e^{-2sL}}{s^2 + 0.2s + 1} \{1 + e^{-2sL} + e^{-4sL} + \dots\}} \right] \Rightarrow$$

$$\begin{aligned} \frac{1}{1+x} &= \\ &= 1 - x + x^2 - \dots \end{aligned}$$

$$\Rightarrow \tilde{z}(s) = \frac{V}{s^2 + 0.2s + 1} \left[1 - \frac{0.4s e^{-2sL}}{s^2 + 0.2s + 1} \left\{ 1 + e^{-2sL} + e^{-4sL} + \dots \right\} + \left(\frac{0.4s e^{-2sL}}{s^2 + 0.2s + 1} \right)^2 \left\{ 1 + e^{-2sL} + e^{-4sL} + \dots \right\} + \dots \right] \Rightarrow$$

$$\Rightarrow \tilde{z}(s) = \frac{V}{s^2 + 0.2s + 1} - \frac{0.4Vs e^{-2sL}}{(s^2 + 0.2s + 1)^2} - \frac{0.4Vs e^{-4sL}}{(s^2 + 0.2s + 1)^3} +$$

$$+ \frac{V(0.4)^2 s^2 e^{-4sL}}{(s^2 + 0.2s + 1)^3} + \dots \Rightarrow z(t) = \mathcal{L}^{-1}[\tilde{z}(s)] \Rightarrow$$

$$\Rightarrow z(t) = \mathcal{L}^{-1}\left[\frac{V}{s^2 + 0.2s + 1}\right] - \mathcal{L}^{-1}\left[\frac{0.4Vs e^{-2sL}}{(s^2 + 0.2s + 1)^2}\right] + \mathcal{L}^{-1}\left[\frac{[(0.4s)^2 - 0.4s]V e^{-4sL}}{(s^2 + 0.2s + 1)^3}\right] + \dots$$

Response of a damped SDOF oscillator

This term contributes to the response after time $t = \frac{2L}{c}$, $c=1$, i.e., after the first wave gets reflected from the fixed boundary at $x=L$.

This term contributes to the response after time $t = \frac{4L}{c}$, $c=1$, after it is reflected twice from the boundary at $x=L$.

Note that $\mathcal{Z}^{-1} \left[\frac{V}{s^2 + 0.2s + 1} \right] = \frac{V e^{-0.1t} \sin 0.99t}{0.99}$

$$\mathcal{Z}^{-1} \left[\frac{0.4 V s e^{-2sL}}{(s^2 + 0.2s + 1)^2} \right] = 0.4 V \mathcal{U}(t-2L) \mathcal{Z}^{-1} \left[\frac{s}{(s^2 + 0.2s + 1)^2} \right]$$

$$\mathcal{Z}^{-1} \left[\frac{[(0.4s)^2 - 0.4s] V e^{-4sL}}{(s^2 + 0.2s + 1)^3} \right] = V \mathcal{U}(t-4L) \mathcal{Z}^{-1} \left[\frac{(0.4s)^2 - 0.4s}{(s^2 + 0.2s + 1)^3} \right]$$

Remark 1: What happens as $L \rightarrow \infty$?

Recall that $\tilde{Z}(s) = \frac{V}{s^2 + 0.2s \coth(sL) + 1}$

But $\coth(sL) = \frac{1 + e^{-2sL}}{1 - e^{-2sL}} \Rightarrow \text{As } L \rightarrow \infty \Rightarrow \coth(sL) \rightarrow 1$ } \Rightarrow

$\Rightarrow \lim_{sL \rightarrow \infty} \tilde{Z}(s) = \frac{V}{s^2 + 0.2s + 1} \Rightarrow$ Effect of semi-infinite string (waves radiation) is exactly \propto "viscous damping" term in the oscillator. strength of "damping" is related to internal tension T in string.

But what about the response of the string $\hookrightarrow L \rightarrow \infty$? Recall that,

$$\tilde{V}(x, s) = \frac{Z(s)}{\sinh(sL)} \sinh[s(L-x)]$$

$$\text{But, } \frac{\sinh[s(L-x)]}{\sinh(sL)} = \frac{e^{s(L-x)} - e^{-s(L-x)}}{e^{sL} - e^{-sL}} = \frac{e^{-sx} - e^{-2sL} e^{sx}}{1 - e^{-2sL}} \Rightarrow$$

$$\Rightarrow \text{As } L \rightarrow \infty, \frac{\sinh[s(L-x)]}{\sinh(sL)} \sim e^{-sx} \Rightarrow$$

\Rightarrow Combining with the previous result, $\hookrightarrow L \rightarrow \infty$ we get

$$u(x, t) \sim \mathcal{L}^{-1} \left[\frac{V e^{-sx}}{s^2 + 0.2s + 1} \right] = \frac{V e^{-0.1(t-x)} \sin 0.99(t-x)}{0.99} U(t-x)$$

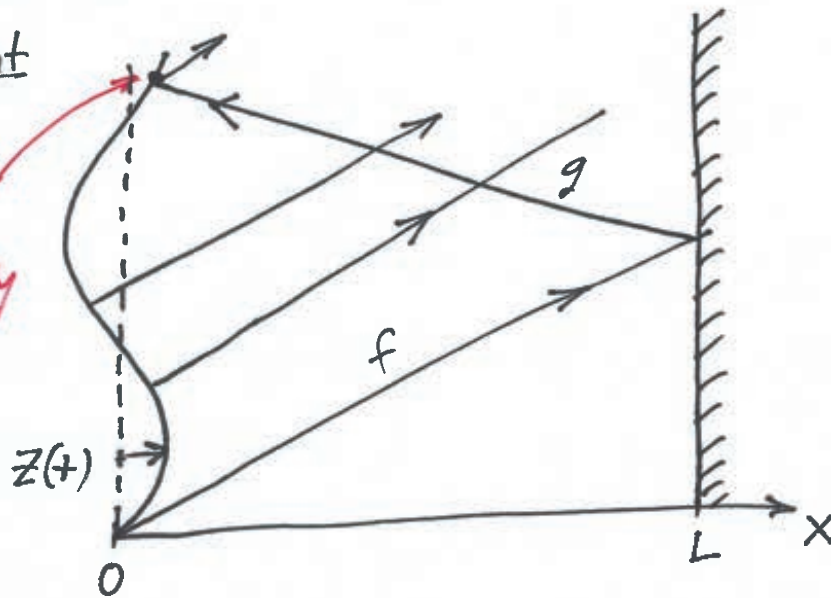
Note that the effect of lack of dispersion in the semi-infinite ~~is~~ string is evident!

Farewell note: Open problems

- 1) What are the effects of viscous damping and/or elastic foundation on the string?
- 2) What happens when you replace the string by a beam?
- 3) Could you solve the previous problem using the method of characteristics?

Hint

Should impose compatibility condition!



- 4) Study condition(s) of resonance when the oscillator is forced by a periodic force.