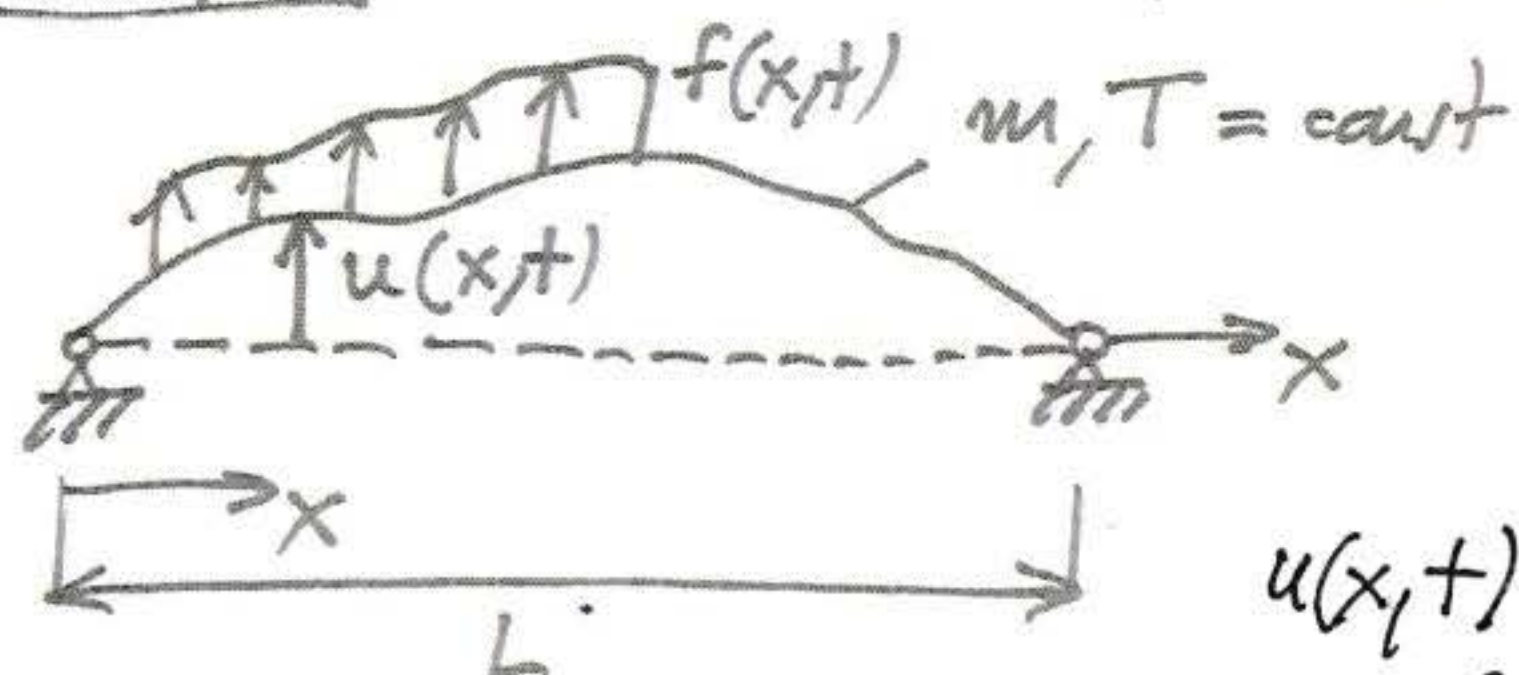


Example 1: fixed-fixed elastic string



$$u(x,t) = \varphi(x)f(t)$$

The equation of motion is then

$$T \frac{\partial^2 u}{\partial x^2} + F(x,t) = m \frac{\partial^2 u}{\partial t^2} \quad 0 \leq x \leq L, \quad t \geq 0$$

(1)

$$\text{BCs: } u(0,t) = u(L,t) = 0$$

(1a)

$$\text{ICs: } u(x,0) = g(x), \quad \frac{\partial u}{\partial t}(x,0) = h(x) \quad (1b)$$

First we consider the eigenvalue problem: $\left. \begin{aligned} \frac{d^2 \varphi(x)}{dx^2} + \left(\frac{\omega}{c}\right)^2 \varphi(x) &= 0, \quad c = \sqrt{\frac{T}{m}} \\ \varphi(0) &= \varphi(L) = 0 \end{aligned} \right\} \Rightarrow$

$$\Rightarrow \varphi(x) = C_1 \overset{\varphi_1(x,\omega)}{\cos \frac{\omega}{c} x} + C_2 \overset{\varphi_2(x,\omega)}{\sin \frac{\omega}{c} x}$$

$$\varphi(0) = 0 \Rightarrow C_1 = 0$$

$$\varphi(L) = 0 \Rightarrow C_1 \cos \frac{\omega L}{c} + C_2 \sin \frac{\omega L}{c} = 0 \Rightarrow \begin{bmatrix} 1 & 0 \\ \cos \frac{\omega L}{c} & \sin \frac{\omega L}{c} \end{bmatrix} \begin{Bmatrix} C_1 \\ C_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

\Rightarrow Setting the determinant of coefficient equal to zero $\Rightarrow \sin \frac{\omega L}{c} = 0 \Rightarrow$

$$\Rightarrow \frac{\omega L}{c} = k\pi, \quad k = 1, 2, \dots \Rightarrow \boxed{\omega_k = \frac{k\pi c}{L}, \quad k = 1, 2, \dots}, \quad \omega_1 = \frac{\pi c}{L} < \omega_2 = \frac{2\pi c}{L} < \omega_3 < \dots$$

Then, the corresponding eigenfunctions are $\varphi_r(x) = C_r \sin \omega_r x \Rightarrow$

$$\Rightarrow \text{Mass-normalizing} \Rightarrow \int_0^L \underbrace{B(x)}_m \varphi_r^2(x) dx = 1 \Rightarrow \int_0^L C_r^2 \sin^2 \omega_r x dx = \frac{1}{m} \Rightarrow$$

$$\Rightarrow C_r = \sqrt{\frac{2}{mL}} \Rightarrow \boxed{\varphi_r(x) = \sqrt{\frac{2}{mL}} \sin \frac{r\pi x}{L}, \quad r=1, 2, \dots} \leftarrow \text{Mass-normalized eigenfunction}$$

Then, we express the solution of problem (1) as,

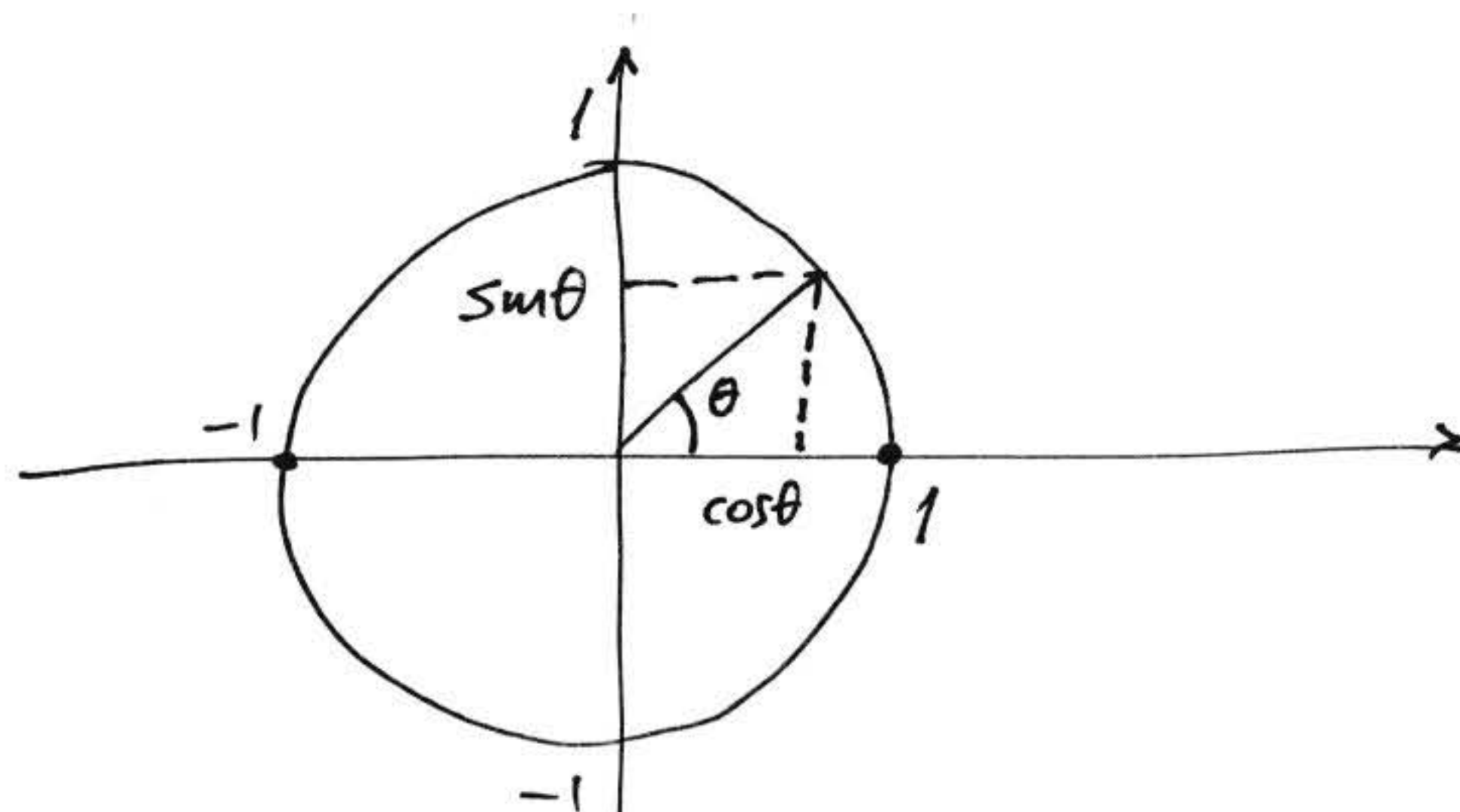
$$u(x,t) = \sum_{i=1}^{\infty} \gamma_i(t) \varphi_i(x) = \sum_{i=1}^{\infty} \gamma_i(t) \sqrt{\frac{2}{mL}} \sin \frac{r\pi x}{L} \quad \left. \vphantom{\sum_{i=1}^{\infty}} \right\} \Rightarrow$$

$$\text{where } \ddot{\gamma}_i(t) + \omega_i^2 \gamma_i(t) = N_i(t) = \int_0^L m F(x,t) \varphi_i(x) dx$$

$$\gamma_i(0) = \sqrt{\frac{2}{mL}} \int_0^L m g(x) \sin\left(\frac{i\pi x}{L}\right) dx$$

$$\dot{\gamma}_i(0) = \sqrt{\frac{2}{mL}} \int_0^L m h(x) \sin\left(\frac{i\pi x}{L}\right) dx$$

$$\Rightarrow \boxed{u(x,t) = \sum_{i=1}^{\infty} \left[\gamma_i(0) \cos\left(\frac{i\pi c t}{L}\right) + \frac{\dot{\gamma}_i(0)}{i\frac{\pi c}{L}} \sin\left(\frac{i\pi c t}{L}\right) + \frac{1}{\left(i\frac{\pi c}{L}\right)} \int_0^t N_i(\tau) \sin\left[\frac{i\pi c}{L}(t-\tau)\right] d\tau \right] \cdot \sqrt{\frac{2}{mL}} \sin\left(\frac{i\pi x}{L}\right)}$$



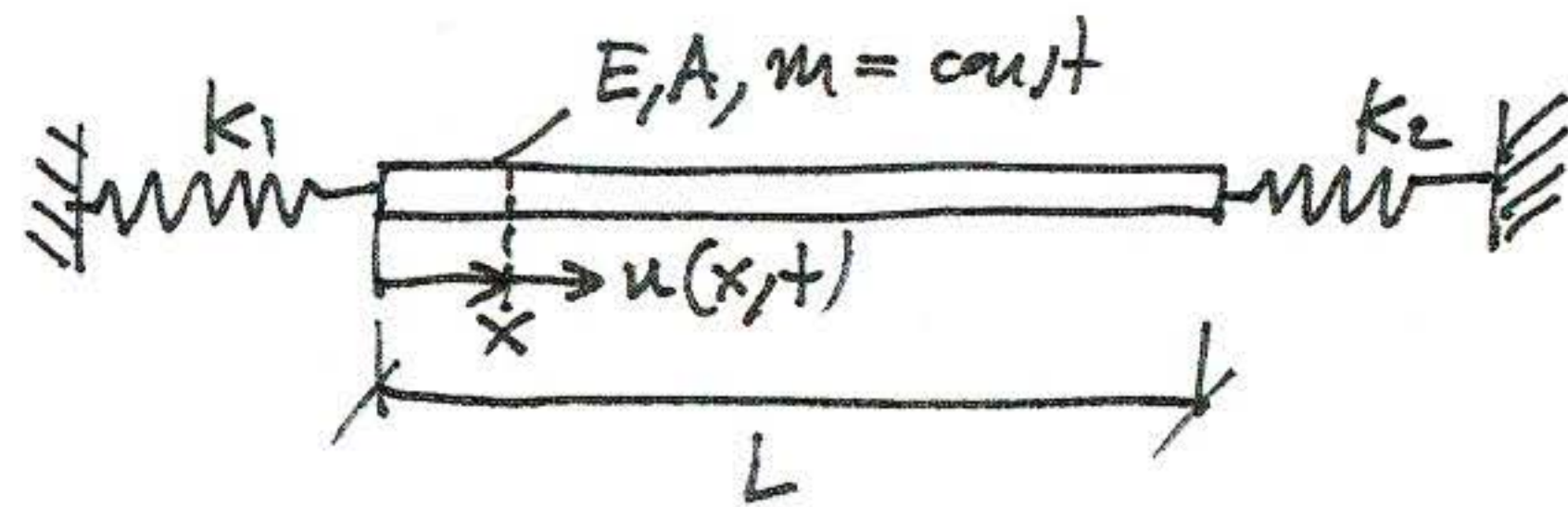
$$\sin \theta = 0 \Rightarrow \theta = k\pi, \quad k = 0, 1, 2, \dots$$

$$\cos \theta = 0 \Rightarrow \theta = \frac{(2k+1)\pi}{2}, \quad k = 0, 1, 2, \dots$$

$$\tan \theta = 0 \Rightarrow \dots$$

$$\cot \theta = 0 \Rightarrow \dots$$

Example 2



the governing pde is,

$$EA \frac{\partial^2 u}{\partial x^2} = m \frac{\partial^2 u}{\partial t^2} \quad (1)$$

BCs are:

$$EA \frac{\partial u(0, t)}{\partial x} - k_1 u(0, t) = 0 \quad (1a)$$

$$EA \frac{\partial u(L, t)}{\partial x} + k_2 u(L, t) = 0$$

$$\text{ICs are: } u(x, 0) = g(x), \quad \frac{\partial u(x, 0)}{\partial t} = h(x) \quad (1c)$$

Working similarly we formulate a linear eigenvalue problem:

$$\varphi''(x) + \left(\frac{\omega}{c}\right)^2 \varphi(x) = 0, \quad c = \sqrt{\frac{E}{\rho}} \quad (2)$$

$$EA \varphi'(0) - k_1 \varphi(0) = 0 \quad (2a)$$

$$EA \varphi'(L) + k_2 \varphi(L) = 0$$

$$(2) \Rightarrow \varphi(x) = C_1 \cos \frac{\omega}{c} x + C_2 \sin \frac{\omega}{c} x \Rightarrow$$

$$\Rightarrow \varphi'(x) = -\frac{\omega}{c} C_1 \sin \frac{\omega}{c} x + \frac{\omega}{c} C_2 \cos \frac{\omega}{c} x$$

$$EA \frac{\omega}{c} C_2 \cos \frac{\omega 0}{c} - k_1 C_1 \cdot 1 = 0$$

$$EA \left[-\frac{\omega}{c} C_1 \sin \frac{\omega L}{c} + \frac{\omega}{c} C_2 \cos \frac{\omega L}{c} \right]$$

$$+ k_2 \left[C_1 \cos \frac{\omega L}{c} + C_2 \sin \frac{\omega L}{c} \right] = 0$$

Hence, we get:

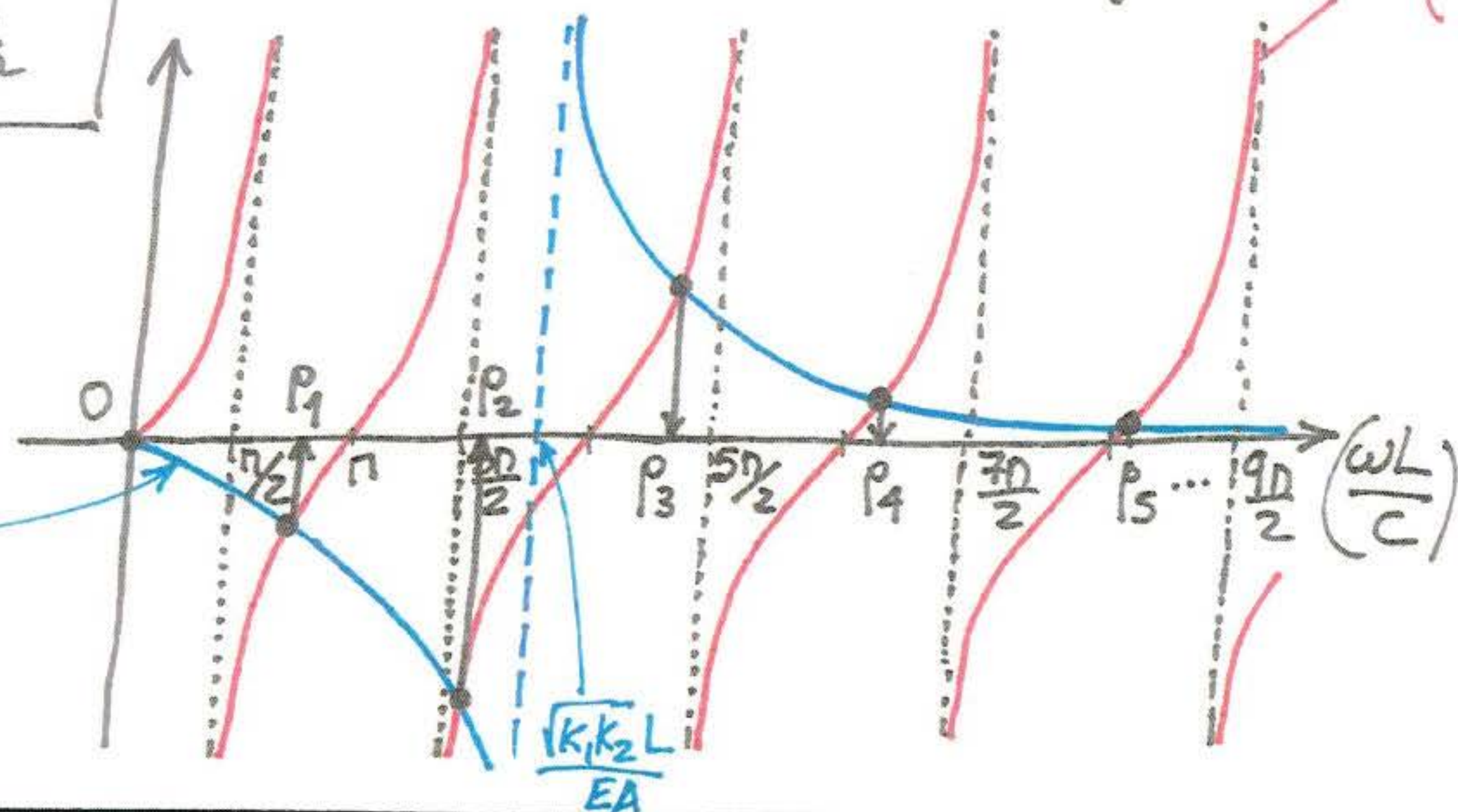
$$\begin{bmatrix} -k_1 & \frac{EA\omega}{C} \\ -EA\frac{\omega}{C}\sin\frac{\omega L}{C} + k_2 \cos\frac{\omega L}{C} & EA\frac{\omega}{C}\cos\frac{\omega L}{C} + k_2 \sin\frac{\omega L}{C} \end{bmatrix} \begin{Bmatrix} C_1 \\ C_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \Rightarrow$$

\Rightarrow For nontrivial solutions we require that $\det[\] = 0 \Rightarrow$

$$\Rightarrow -k_1 EA \frac{\omega}{C} \cos\frac{\omega L}{C} - k_1 k_2 \sin\frac{\omega L}{C} + \left(EA \frac{\omega}{C}\right)^2 \sin\frac{\omega L}{C} - k_2 EA \frac{\omega}{C} \cos\frac{\omega L}{C} = 0 \Rightarrow$$

$$\Rightarrow \tan\left(\frac{\omega L}{C}\right) = \frac{\frac{(k_1+k_2)L}{EA} \cdot \left(\frac{\omega L}{C}\right)}{\left(\frac{\omega L}{C}\right)^2 - \frac{k_1 k_2 L^2}{(EA)^2}} \Rightarrow \text{In the form } \tan X = \frac{\alpha X}{X^2 - \beta}$$

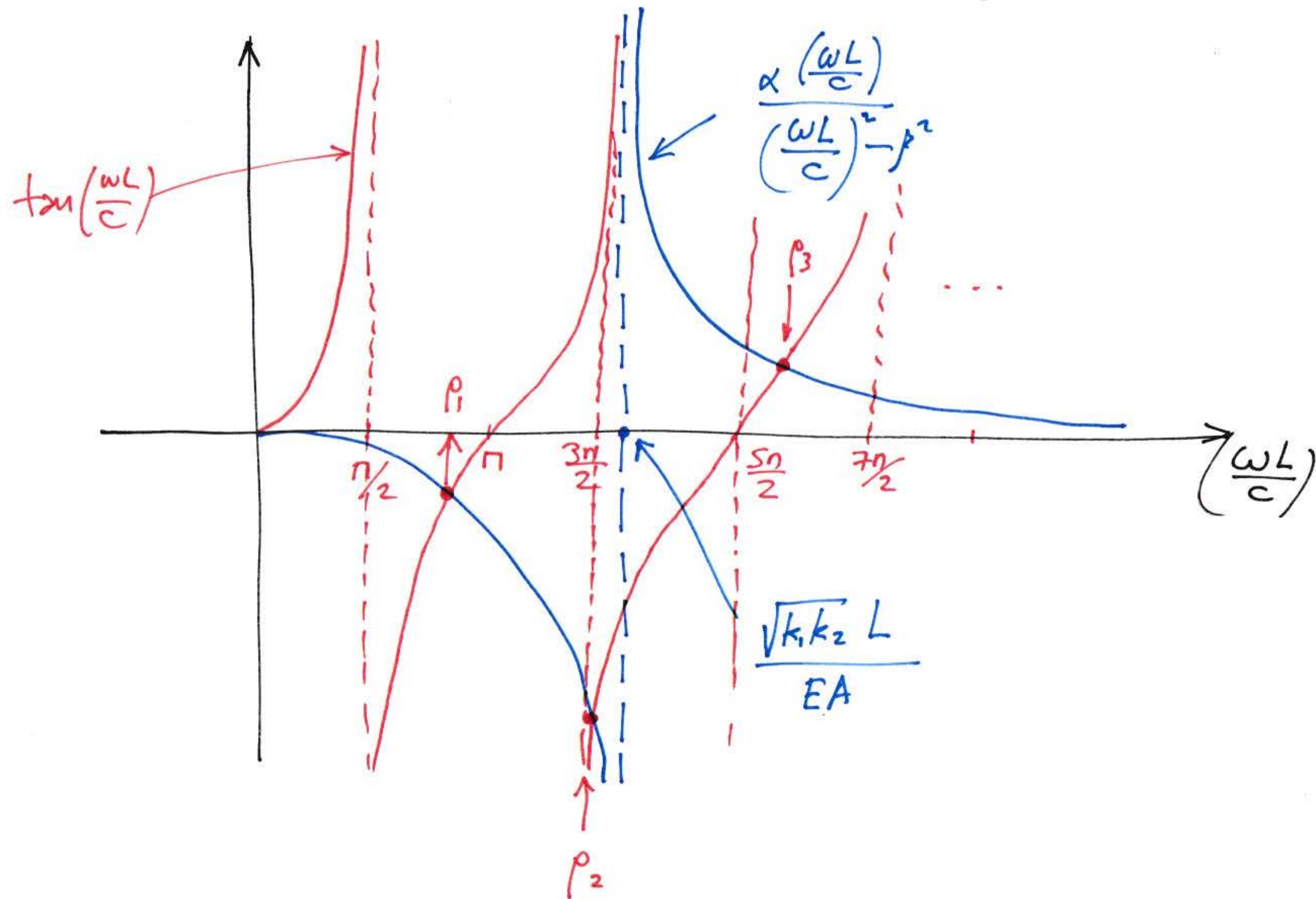
$$\frac{\frac{(k_1+k_2)L}{EA} \cdot \left(\frac{\omega L}{C}\right)}{\left(\frac{\omega L}{C}\right)^2 - \frac{k_1 k_2 L^2}{(EA)^2}}$$



$$\tan\left(\frac{\omega L}{c}\right) = \frac{\alpha \left(\frac{\omega L}{c}\right)}{\left(\frac{\omega L}{c}\right)^2 - \beta^2}$$

$$\alpha = \frac{(k_1 + k_2)L}{EA}$$

$$\beta = \frac{k_1 k_2 L^2}{(EA)^2}$$



Then we see that p_i stays within certain limits:

$$\frac{n}{2} < p_1 < n, \quad \frac{3n}{2} < p_2 < 2n, \quad \cancel{2n} < p_3 < \frac{5n}{2}, \dots$$

Once we have computed $p_i \Rightarrow p_i = \frac{\omega_i L}{c} \Rightarrow \omega_i = \frac{c p_i}{L}, i=1,2,\dots$

Then we can show that the corresponding eigenfunction is

$$\boxed{\varphi_i(x) = C_i \frac{\sin(p_i \frac{x}{L} + \psi_i)}{\cos \psi_i}, \quad i=1,2,\dots}, \quad \tan \psi_i = \frac{EA p_i}{K_1 L} \Rightarrow 0 < \psi_i < \frac{\pi}{2}, i=1,2,\dots$$

Then we can mass-orthonormalize, $\int_0^L m \varphi_i^2(x) dx = 1 \Rightarrow$

$$\Rightarrow m \frac{C_i^2}{\cos^2 \psi_i} \int_0^L \sin^2(p_i \frac{x}{L} + \psi_i) dx = 1 \Rightarrow \text{from this we may compute the}$$

constant $C_i, i=1,2,\dots \Rightarrow$

$$\boxed{C_i = 2 \cos \psi_i \sqrt{\frac{p_i}{mL(2p_i - \sin 2(p_i + \psi_i)) + 2 \sin 2\psi_i}}}$$