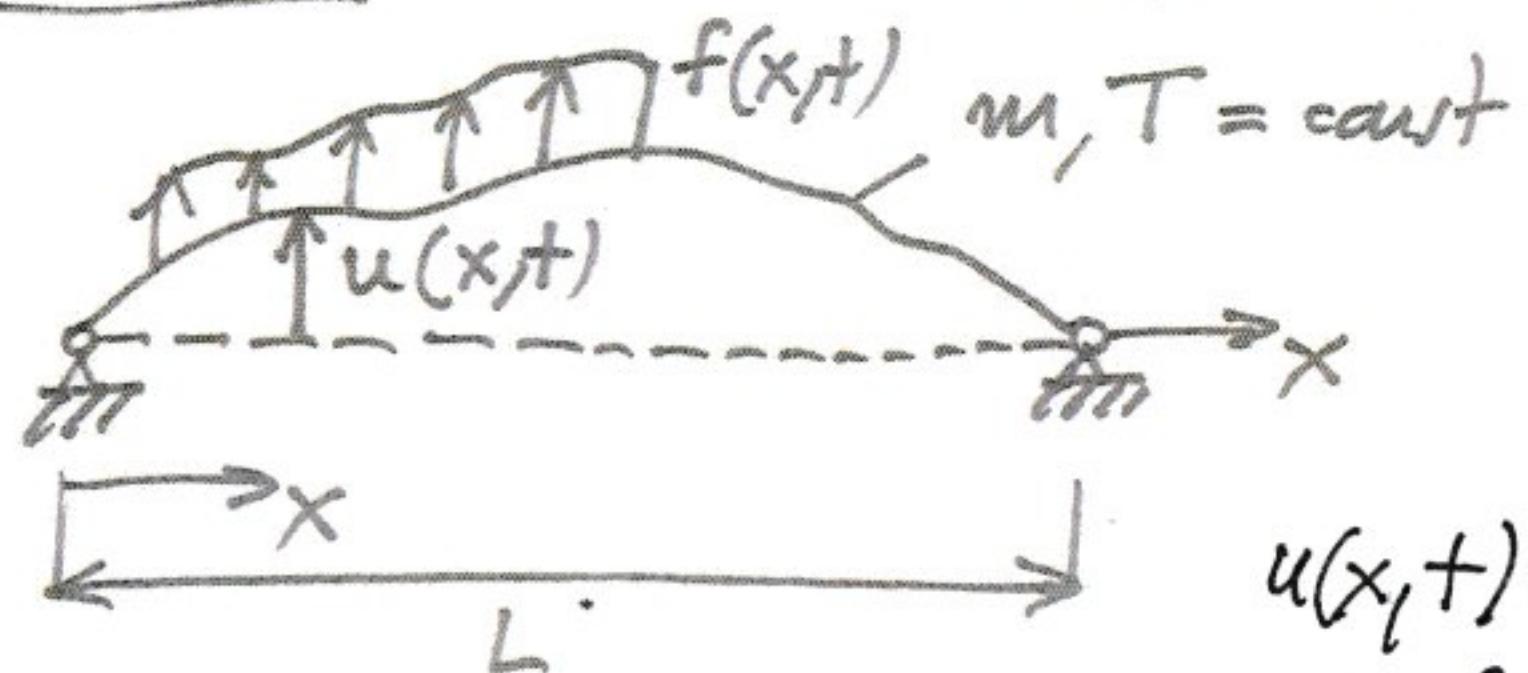


Example 1: Fixed-fixed elastic string



$$\begin{aligned} u(x,t) &= \\ &= \varphi(x)f(t) \end{aligned}$$

The equation of motion is this
case,

$$T \frac{\partial^2 u}{\partial x^2} + F(x,t) = m \frac{\partial^2 u}{\partial t^2}, \quad 0 \leq x \leq L, \quad t \geq 0 \quad (1)$$

$$\text{BCs: } u(0,t) = u(L,t) = 0 \quad (1a)$$

$$\text{ICs: } u(x,0) = g(x), \quad \frac{\partial u}{\partial t}(x_0) = h(x) \quad (1b)$$

First we consider the eigenvalue problem:

$$\frac{d^2 \tilde{\varphi}(x)}{dx^2} + \left(\frac{\omega}{c}\right)^2 \tilde{\varphi}(x) = 0, \quad c = \sqrt{\frac{T}{m}} \Rightarrow$$

$$\tilde{\varphi}(0) = \tilde{\varphi}(L) = 0$$

$$\begin{array}{l} \tilde{\varphi}_1(x,\omega) \\ \downarrow \\ \tilde{\varphi}_2(x,\omega) \end{array}$$

$$\Rightarrow \varphi(x) = C_1 \cos \frac{\omega}{c} x + C_2 \sin \frac{\omega}{c} x$$

$$\varphi(0) = 0 \Rightarrow C_1 = 0$$

$$\varphi(L) = 0 \Rightarrow C_1 \cos \frac{\omega L}{c} + C_2 \sin \frac{\omega L}{c} = 0 \Rightarrow$$

$$\begin{bmatrix} 1 & 0 \\ \cos \frac{\omega L}{c} & \sin \frac{\omega L}{c} \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Setting the determinant of coefficient equal to zero $\Rightarrow \sin \frac{\omega L}{c} = 0 \Rightarrow$

$$\Rightarrow \frac{\omega L}{c} = kn, \quad k = 1, 2, \dots \Rightarrow \left[\omega_k = \frac{k\pi c}{L}, \quad k = 1, 2, \dots \right], \quad \omega_1 = \frac{\pi c}{L} < \omega_2 = \frac{2\pi c}{L} < \omega_3 < \dots$$

Thus, the corresponding eigenfunctions are $\varphi_r(x) = C_r \sin \omega_r x \Rightarrow$

$$\Rightarrow \text{Mass-orthonormalizing} \Rightarrow \int_0^L \tilde{\beta}(x) \varphi_r^2(x) dx = 1 \Rightarrow \int_0^L C_r^2 \sin^2 \omega_r x dx = \frac{1}{m} \Rightarrow$$

$$\Rightarrow C_r = \sqrt{\frac{2}{mL}} \Rightarrow \boxed{\varphi_r(x) = \sqrt{\frac{2}{mL}} \sin \frac{r\pi x}{L}, \quad r=1, 2, \dots} \quad \leftarrow \text{Mass-orthonormalized eigenfunction}$$

Then, we express the solution of problem (i) as,

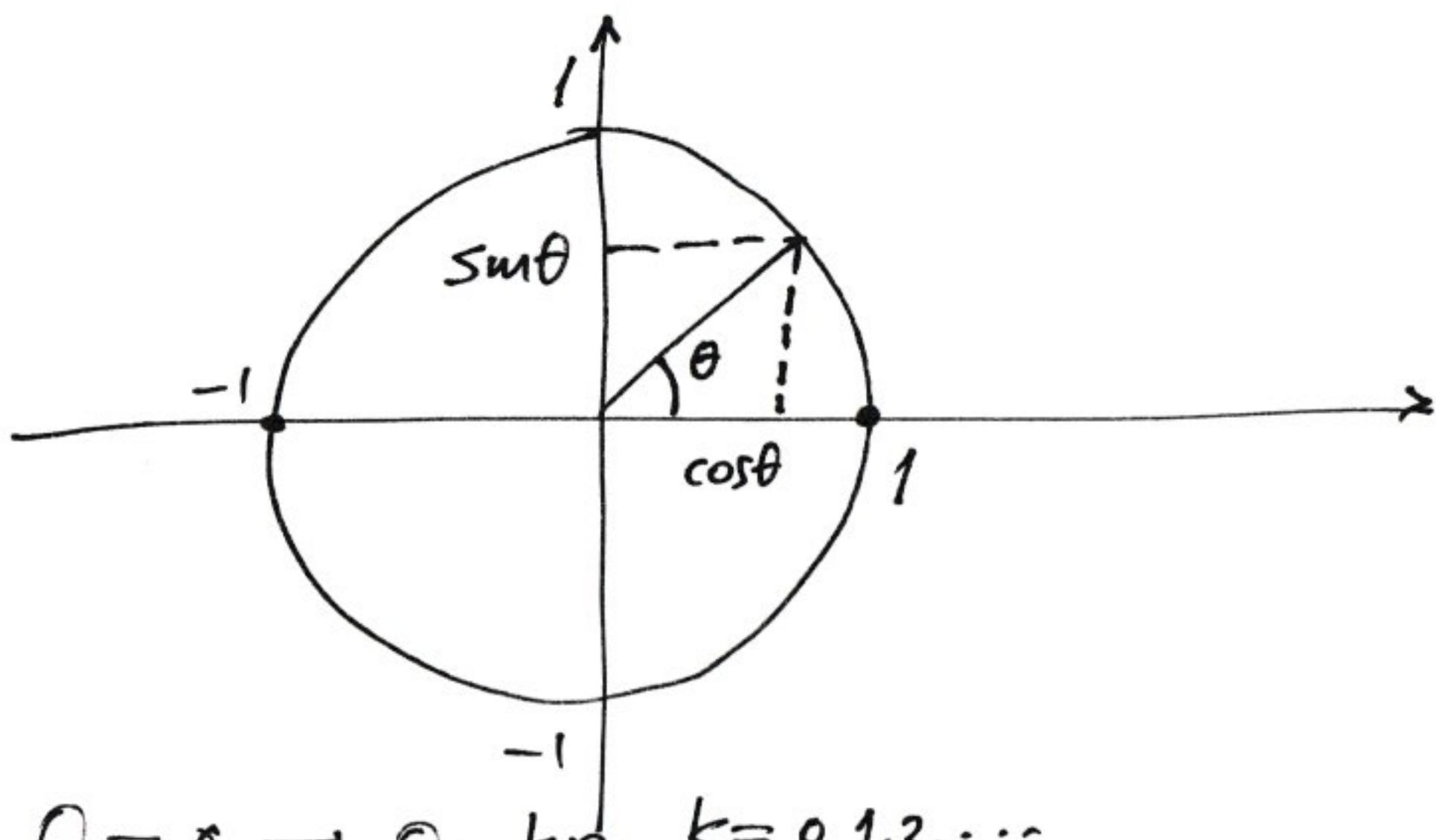
$$u(x,t) = \sum_{i=1}^{\infty} \gamma_i(t) \varphi_i(x) = \sum_{i=1}^{\infty} \gamma_i(t) \sqrt{\frac{2}{mL}} \sin \frac{r\pi x}{L} \quad \leftarrow$$

$$\text{where } \ddot{\gamma}_i(t) + \omega_i^2 \gamma_i(t) = N_i(t) = \int_0^L m F(x,t) \varphi_i(x) dx$$

$$\gamma_i(0) = \sqrt{\frac{2}{mL}} \int_0^L m g(x) \sin \left(\frac{inx}{L} \right) dx$$

$$\dot{\gamma}_i(0) = \sqrt{\frac{2}{mL}} \int_0^L m h(x) \sin \left(\frac{inx}{L} \right) dx$$

$$\Rightarrow \boxed{u(x,t) = \sum_{i=1}^{\infty} \left[\gamma_i(0) \cos \left(\frac{inct}{L} \right) + \frac{\dot{\gamma}_i(0)}{i\pi c} \sin \left(\frac{inct}{L} \right) + \left(\frac{1}{i\pi c} \right) \int_0^L N_i(\tau) \sin \left[\frac{inct}{L} (t-\tau) d\tau \right] \cdot \sqrt{\frac{2}{mL}} \sin \left(\frac{inx}{L} \right) \right]}.$$



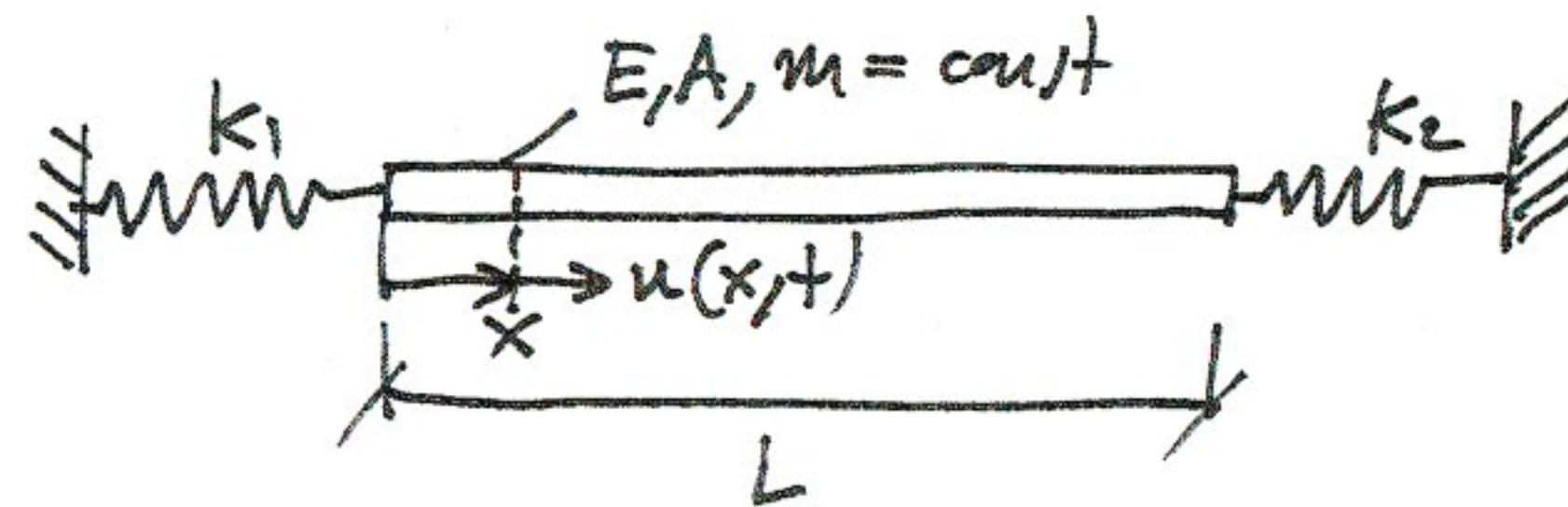
$$\sin \theta = 0 \Rightarrow \theta = kn, \quad k=0, 1, 2, \dots$$

$$\cos \theta = 0 \Rightarrow \theta = \frac{(2k+1)\pi}{2}, \quad k=0, 1, 2, \dots$$

$$\tan \theta = 0 \Rightarrow \dots$$

$$\cot \theta = 0 \Rightarrow \dots$$

Example 2



The governing pde is:

$$EA \frac{\partial^2 u}{\partial x^2} = m \frac{\partial^2 u}{\partial t^2} \quad (1)$$

BCs are:

$$EA \frac{\partial u(0, t)}{\partial x} - k_1 u(0, t) = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\} \quad (1a)$$

$$EA \frac{\partial u(L, t)}{\partial x} + k_2 u(L, t) = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\}$$

$$\text{ICs are: } u(x, 0) = g(x), \frac{\partial u}{\partial t}(x, 0) = h(x) \quad (1c)$$

Working similarly we formulate a linear eigenvalue problem:

$$\varphi''(x) + \left(\frac{\omega}{c}\right)^2 \varphi(x) = 0, \quad c = \sqrt{\frac{E}{\rho}} \quad (2)$$

$$EA \varphi'(0) - k_1 \varphi(0) = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\} \quad (2a)$$

$$EA \varphi'(L) + k_2 \varphi(L) = 0$$

$$(2) \Rightarrow \varphi(x) = C_1 \cos \frac{\omega}{c} x + C_2 \sin \frac{\omega}{c} x \Rightarrow$$

$$\Rightarrow \varphi'(x) = -\frac{\omega}{c} C_1 \sin \frac{\omega}{c} x + \frac{\omega}{c} C_2 \cos \frac{\omega}{c} x$$

$$EA \frac{\omega}{c} C_2 \cos \frac{\omega}{c} L - k_1 C_1 \cdot 1 = 0$$

$$EA \left[-\frac{\omega}{c} C_1 \sin \frac{\omega L}{c} + \frac{\omega}{c} C_2 \cos \frac{\omega L}{c} \right]$$

$$+ k_2 \left[C_1 \cos \frac{\omega L}{c} + C_2 \sin \frac{\omega L}{c} \right] = 0$$

Hence, we get:

$$\begin{bmatrix} -k_1 \\ -EA\frac{\omega}{c} \sin \frac{\omega L}{c} + k_2 \cos \frac{\omega L}{c} \end{bmatrix}$$

$$\frac{EA\omega}{c}$$

$$EA\frac{\omega}{c} \cos \frac{\omega L}{c} + k_2 \sin \frac{\omega L}{c}$$

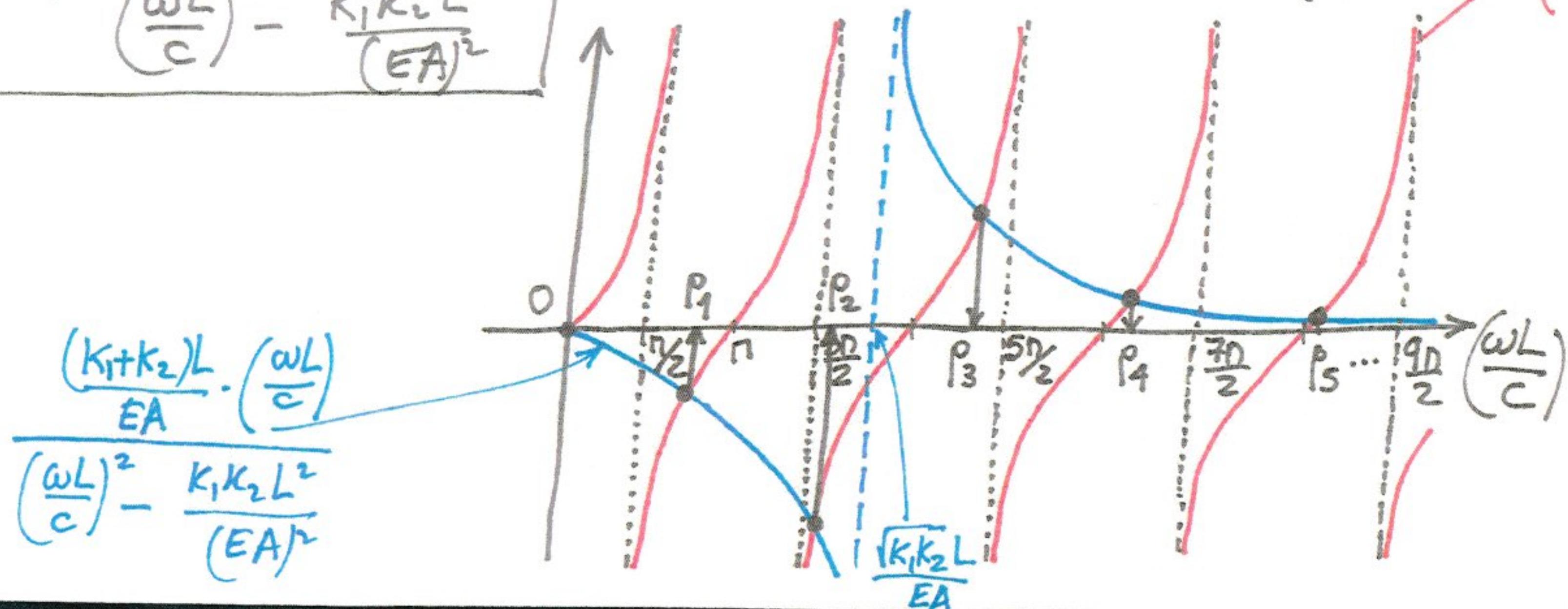
$$\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow$$

\Rightarrow for nontrivial solutions we require that $\det [] = 0 \Rightarrow$

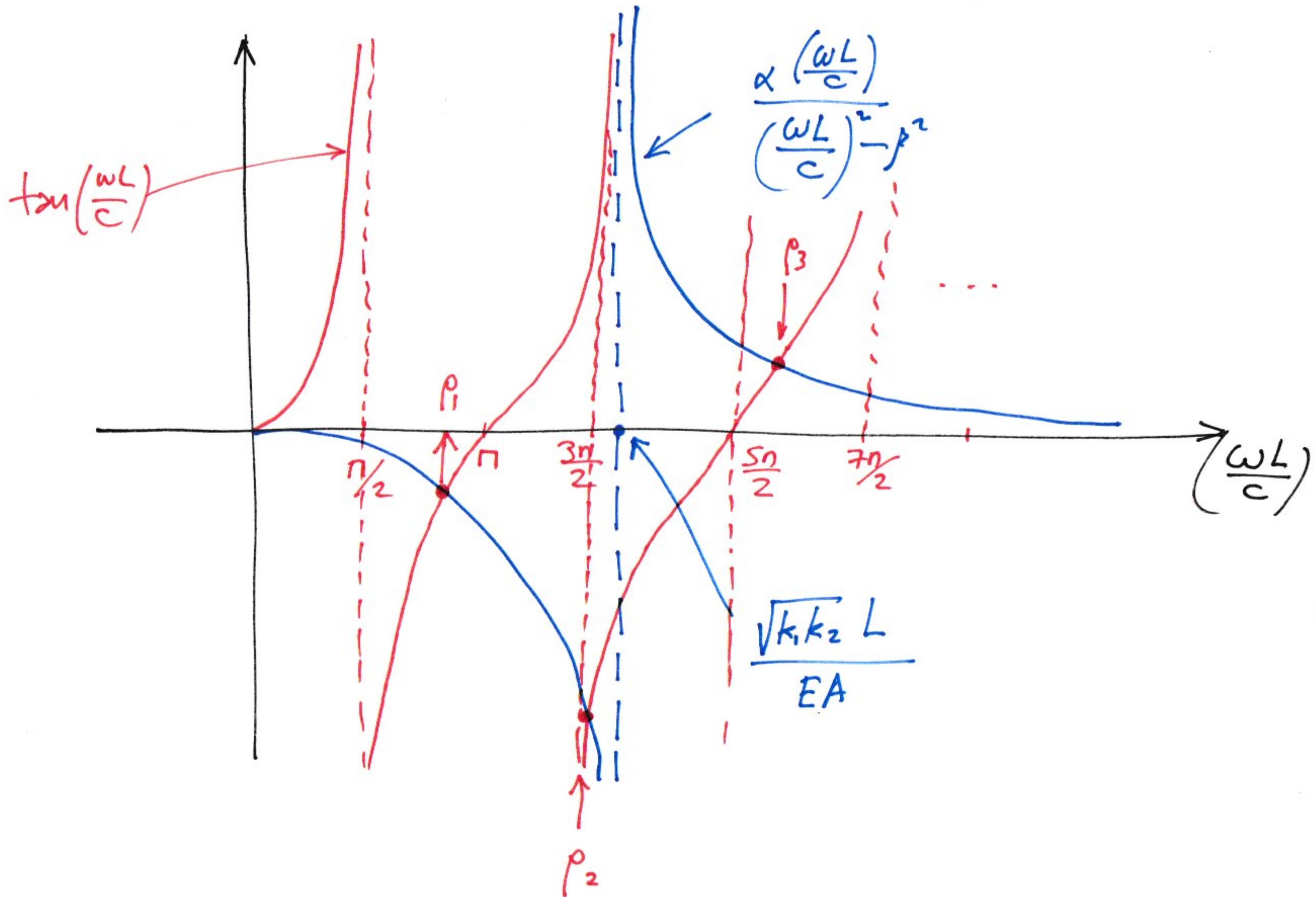
$$\Rightarrow -k_1 EA \frac{\omega}{c} \cos \frac{\omega L}{c} - k_1 k_2 \sin \frac{\omega L}{c} + \left(EA \frac{\omega}{c} \right)^2 \sin \frac{\omega L}{c} - k_2 EA \frac{\omega}{c} \cos \frac{\omega L}{c} = 0 \Rightarrow$$

$$\Rightarrow \tan \left(\frac{\omega L}{c} \right) = \frac{\frac{(k_1+k_2)L}{EA} \cdot \left(\frac{\omega L}{c} \right)}{\left(\frac{\omega L}{c} \right)^2 - \frac{k_1 k_2 L^2}{(EA)^2}}$$

\Rightarrow In the form $\tan x = \frac{\alpha x}{x^2 - \beta}$



$$\tan\left(\frac{\omega L}{c}\right) = \frac{\alpha \left(\frac{\omega L}{c}\right)}{\left(\frac{\omega L}{c}\right)^2 - \beta^2}, \quad \alpha = \frac{(k_1 + k_2)L}{EA}, \quad \beta = \frac{k_1 k_2 L^2}{(EA)^2}$$



Then we see that ρ_i stays within certain limits:

$$\frac{\pi}{2} < \rho_1 < \pi, \quad \frac{3\pi}{2} < \rho_2 < 2\pi, \quad 2\pi < \rho_3 < \frac{5\pi}{2}, \dots$$

Once we have computed $\rho_i \Rightarrow \rho_i = \frac{\omega_i L}{c} \Rightarrow \omega_i = \frac{c \rho_i}{L}, i=1,2,\dots$

Then we can show that the corresponding eigenfunction is

$$\boxed{\varphi_i(x) = C_i \frac{\sin(\rho_i \frac{x}{L} + \psi_i)}{\cos \psi_i}, \quad i=1,2,\dots} \quad \tan \psi_i = \frac{EA \rho_i}{K_1 L} \Rightarrow \\ \Rightarrow 0 < \psi_i < \frac{\pi}{2}, \quad i=1,2,\dots$$

Then we can mass-orthogonalize, $\int_0^L m \varphi_i^2(x) dx = 1 \Rightarrow$

$\Rightarrow m \frac{C_i^2}{\cos^2 \psi_i} \int_0^L \sin^2(\rho_i \frac{x}{L} + \psi_i) dx = 1 \Rightarrow$ from this we may compute the

constant $C_i, i=1,2,\dots \Rightarrow$

$$\boxed{C_i = 2 \cos \psi_i \sqrt{\frac{\rho_i}{m L (2 \rho_i - \sin 2(\rho_i + \psi_i) + 2 \sin 2 \psi_i)}}}$$