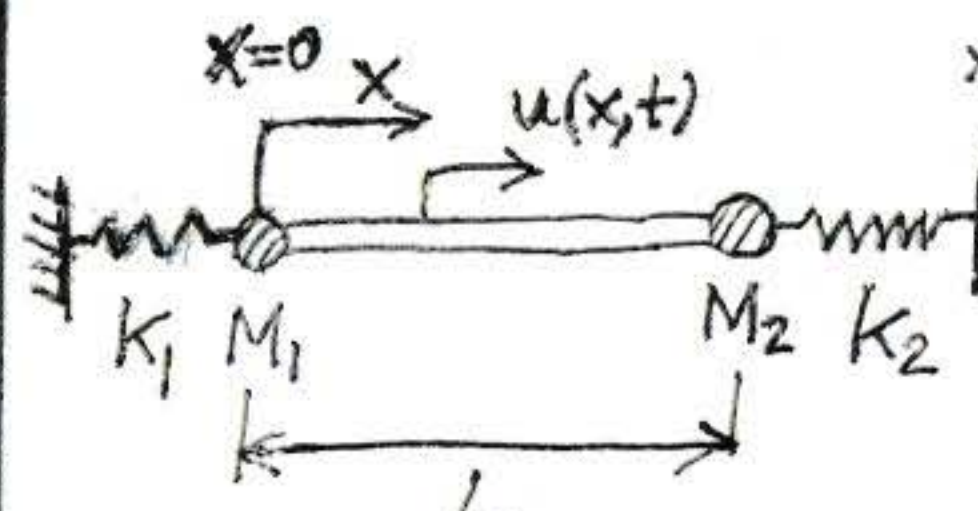


From last time...



$$\frac{\partial}{\partial x} \left[ A(x) \frac{\partial u}{\partial x} \right] = B(x) \frac{\partial^2 u}{\partial t^2}, \quad 0 \leq x \leq L, \quad t \geq 0$$

$$\left. \begin{aligned} A(0) \frac{\partial u(0,t)}{\partial x} - k_1 u(0,t) - M_1 \frac{\partial^2 u(0,t)}{\partial t^2} &= 0 \\ A(L) \frac{\partial u(L,t)}{\partial x} + k_2 u(L,t) + M_2 \frac{\partial^2 u(L,t)}{\partial t^2} &= 0 \end{aligned} \right\} (*)$$

We found that any two eigenfunctions of this problem satisfied the mass-orthogonality conditions

$$\int_0^L B(x) \varphi_r(x) \varphi_s(x) dx + M_1 \varphi_r(0) \varphi_s(0) + M_2 \varphi_r(L) \varphi_s(L) = \delta_{rs}, \quad (4)$$

$r, s = 1, 2, \dots$

To derive the additional stiffness-orthogonality condition we consider

$$\frac{d}{dx} [A(x) \varphi_r'(x)] = -\omega_r^2 \frac{B(x)}{\varphi_r(x)} \quad \text{for same } r \Rightarrow \text{Multiply by } \varphi_s(x), s \neq r \text{ and integrate } \int_0^L dx \Rightarrow$$

$$\Rightarrow \int_0^L \frac{d}{dx} [A(x) \varphi_r'(x)] \varphi_s(x) dx = -\omega_r^2 \int_0^L B(x) \varphi_r(x) \varphi_s(x) dx \Rightarrow$$

$$\Rightarrow \left[ \int_0^L \frac{d}{dx} [A(x) \varphi_r'(x)] \varphi_s(x) dx - \omega_r^2 M_1 \varphi_r(0) \varphi_s(0) - \omega_r^2 M_2 \varphi_r(L) \varphi_s(L) \right] = -\omega_r^2 \delta_{rs} \quad (5a)$$



But we want to formulate the second orthogonality condition only in terms of stiffness term  $\Rightarrow$  Recall the boundary conditions satisfied by the eigenfunctions  $\Rightarrow$

$$\left. \begin{aligned} \omega_r^2 M_1 \varphi_r(0) &= K_1 \varphi_r(0) - A(0) \varphi_r'(0) \Rightarrow (\cdot) \text{ by } \varphi_s(0) \\ \omega_r^2 M_2 \varphi_r(L) &= K_2 \varphi_r(L) + A(L) \varphi_r'(L) \Rightarrow (\cdot) \text{ by } \varphi_s(L) \end{aligned} \right\} \Rightarrow$$

$\Rightarrow$  Then, substituting into (5a) we derive the alternative expression for the orthogonality condition:

$$\int_0^L \frac{d}{dx} \left[ A(x) \frac{d\varphi_r}{dx} \right] \varphi_s(x) dx - K_1 \varphi_r(0) \varphi_s(0) + A(0) \varphi_r'(0) \varphi_s(0) - K_2 \varphi_r(L) \varphi_s(L) - A(L) \varphi_r'(L) \varphi_s(L) = -\omega_r^2 \delta_{rs} \quad (5b)$$

But, we can simplify even more by performing integration by parts of the first integral  $\Rightarrow$

$$\Rightarrow \underbrace{A(x) \varphi_r'(x) \varphi_s(x)}_{\text{blue circle}} \Big|_0^L - \int_0^L A(x) \varphi_r'(x) \varphi_s'(x) dx \underbrace{- \omega_r^2 M_1 \varphi_r(0) \varphi_s(0)}_{\text{red box}} - \underbrace{\omega_r^2 M_2 \varphi_r(L) \varphi_s(L)}_{\text{blue circle}} + \omega_r^2 \delta_{rs} = 0$$

Here I used (5a)

$\rightarrow -K_1 \varphi_r(0) \varphi_s(0)$        $\rightarrow -K_2 \varphi_r(L) \varphi_s(L)$

$\underbrace{A(L) \varphi_r'(L) \varphi_s(L) - A(0) \varphi_r'(0) \varphi_s(0)}_{\text{red box}}$



It follows that the stiffness-orthogonality condition can be expressed in simplest form as:

$$\int_0^L A(x) \phi_r'(x) \phi_s'(x) dx + K_1 \phi_r(0) \phi_s(0) + K_2 \phi_r(L) \phi_s(L) = \omega_r^2 \delta_{rs} \\ r, s = 1, 2, \dots$$

Note that this relation holds for the mass-orthonormalized eigenfunctions<sup>(6)</sup>

### Modal Analysis

Now consider the forced generalized wave equation with non-simple BCs,

$$\frac{\partial}{\partial x} \left[ A(x) \frac{\partial u}{\partial x} \right] + F(x, t) = B(x) \frac{\partial^2 u}{\partial t^2}, \quad 0 \leq x \leq L, \quad t \geq 0$$

$$\text{Initial conditions } u(x, 0) = g(x), \quad \frac{\partial u}{\partial t}(x, 0) = h(x)$$

Boundary conditions (\*)

First we solve the eigenvalue problem and mass-orthonormalize the eigenfunctions, so that  $\phi_r(x)$  satisfy (4), (6),  $r = 1, 2, \dots$

Then, use modal superposition,

$$u(x, t) = \sum_{i=1}^{\infty} \eta_i(t) \phi_i(x)$$



Substituting into the governing pde and the boundary conditions,

$$\sum_{i=1}^{\infty} \ddot{\eta}_i(t) \int_0^L B(x) \varphi_i(x) \varphi_j(x) dx = \sum_{i=1}^{\infty} \eta_i(t) \int_0^L \frac{d}{dx} \left[ A(x) \frac{d\varphi_i}{dx} \right] \varphi_j(x) dx + \underbrace{\int_0^L F(x,t) \varphi_j(x) dx}_{N_j(t)}, \quad j \text{ arbitrary but fixed}$$

Doing the same for the BCs,

$$\sum_{i=1}^{\infty} \ddot{\eta}_i(t) M_1 \varphi_i(0) = \sum_{i=1}^{\infty} \eta_i(t) [-k_1 \varphi_i(0) + A(0) \varphi_i'(0)] \Rightarrow (\cdot) \varphi_j(0)$$

$$\sum_{i=1}^{\infty} \ddot{\eta}_i(t) M_2 \varphi_i(L) = \sum_{i=1}^{\infty} \eta_i(t) [-k_2 \varphi_i(L) - A(L) \varphi_i'(L)] \Rightarrow (\cdot) \varphi_j(L)$$

$\Rightarrow$  Then add the resulting expressions  $\Rightarrow$

$$\begin{aligned} \Rightarrow \sum_{i=1}^{\infty} \ddot{\eta}_i(t) \left[ \int_0^L B(x) \varphi_i(x) \varphi_j(x) dx + M_1 \varphi_i(0) \varphi_j(0) + M_2 \varphi_i(L) \varphi_j(L) \right] &= \delta_{ij} \\ = \sum_{i=1}^{\infty} \eta_i(t) \left[ \int_0^L \frac{d}{dx} [A(x) \varphi_i'(x)] \varphi_j(x) dx - k_1 \varphi_i(0) \varphi_j(0) + A(0) \varphi_i'(0) \varphi_j(0) - \right. & - \omega_j^2 \delta_{ij} \\ \left. - k_2 \varphi_i(L) \varphi_j(L) - A(L) \varphi_i'(L) \varphi_j(L) \right] + N_j(t) &\Rightarrow \end{aligned}$$



$$\Rightarrow \boxed{\ddot{\gamma}_j(t) + \omega_j^2 \gamma_j(t) = N_j(t), j = 1, 2, \dots} \quad \text{Modal oscillators in (7) simple form!}$$

finally we need to compute the initial conditions for these modal oscillators.

$$u(x, 0) = g(x) \Rightarrow \sum_{i=1}^{\infty} \gamma_i(0) \varphi_i(x) = g(x) \Rightarrow$$

$$\Rightarrow \sum_{i=1}^{\infty} \gamma_i(0) \int_0^L B(x) \varphi_i(x) \varphi_j(x) dx = \int_0^L B(x) g(x) \varphi_j(x) dx$$

But also, it holds that  $\sum_{i=1}^{\infty} \gamma_i(0) \varphi_i(0) = g(0) \Rightarrow$

$$\Rightarrow \sum_{i=1}^{\infty} \gamma_i(0) M_1 \varphi_i(0) \varphi_j(0) = g(0) M_1 \varphi_j(0)$$

Also,  $\sum_{i=1}^{\infty} \gamma_i(0) \varphi_i(L) = g(L) \Rightarrow \sum_{i=1}^{\infty} \gamma_i(0) \varphi_i(L) M_2 \varphi_j(L) = g(L) M_2 \varphi_j(L)$

$$\Rightarrow \sum_{i=1}^{\infty} \gamma_i(0) \left[ \int_0^L B(x) \varphi_i(x) \varphi_j(x) dx + M_1 \varphi_i(0) \varphi_j(0) + M_2 \varphi_i(L) \varphi_j(L) \right] =$$

$$= \int_0^L B(x) g(x) \varphi_j(x) dx + M_1 g(0) \varphi_j(0) + M_2 g(L) \varphi_j(L) \Rightarrow$$



$$\Rightarrow \eta_j(0) = \int_0^L B(x) g(x) \varphi_j(x) dx + M_1 g(0) \varphi_j(0) + M_2 g(L) \varphi_j(L), \quad j=1,2,\dots \quad (8)$$

Similarly we find the initial velocities for the modal oscillators,

$$\dot{\eta}_j(0) = \int_0^L B(x) h(x) \varphi_j(x) dx + M_1 h(0) \varphi_j(0) + M_2 h(L) \varphi_j(L), \quad j=1,2,\dots \quad (9)$$

Then, the solution of the forced problem is given by,

$$u(x,t) = \sum_{i=1}^{\infty} \eta_i(t) \varphi_i(x)$$

where the modal amplitudes  $\eta_i(t)$  are solved by the modal solutions of (7) subject to the initial conditions (8) and (9).