FANUC

Robotics

Project Software Configuration

PaintTool Project Software Configuration

Project Name: GM Tech Center		Date: 4/18/2012		
Project Number: 122695 PCS 305776		Software PaintTool Version: 7.50/Pxx (xx=Latest Release)		
Zones: 1 Lab Zone		Number of PCMCIA Cards: 1		
Number of Controllers: 1 R30ia w/1-WB P700 and 1		Custom Yes No		
p25 opener		Custom 🖂 Tes	5	
Change History:			Software Engineer: Matt White	
			Bottware Engineer, Watt White	
110te. Clear path required				
Note: Clear path required ☐ J726 : 2D Vision ☐ J783 : 3D Vision Bin Picking ☐ J908 : 3DL Disconnection ☐ R576 : AB-RIO Int (pc104) ☐ J781 : APDT for Robot Link ☐ J780 : APDT for multi group ☐ J673 : Accu Cur Pos Out ☐ R501 : AccuAir Control ☐ R635 : AccuCal2 ☐ R502 : AccuFlow ☐ J550 : Adjust Point ☐ R665 : Alarm Cause/Remedy ☐ J614 : Angle Shift ☐ R507 : Ascii Upload ☐ J698 : AutoMode TP operation ☐ R513 : Auto SingularityAvoidance ☐ JNN6 : BOOTP Server ☐ R689 : Basic Process Axes ☐ R657 : Basic Remote TCP ☐ J951 : Brake check function ☐ J786 : CC-Link Interface ☐ R700 : CD Dynamic UFrame ☐ J618 : CE Mark ☐ J956 : CLSM for KMTS ☐ J858 : CPRUT ☐ J535 : CRT/Keyboard Manager ☐ R517 : CalMate ☐ R519 : Cell Finder ☐ R520 : Center Finder ☐ J795 : Clock Simulaneous	R522 : Cycle J567 : DCS J568 : DCS R526 : DHC R588 : DQ R631 : Data J675 : Data J501 : Data J753 : Devic J754 : Devic J754 : Devic J754 : Devic J755 : Doma J836 : Dual J679 : Dumn J646 : Duty R683 : Dyna R535 : EGD J553 : Easy J985 : Enhar J560 : Enhar R698 : Enhar J692 : Enhar J692 : Enhar J527 : Error J664 : Error	m Setting 2 Time Priority e Time Tracking Pos./Speed check Safe I/O connect P Acquistion Monitor Transfer eNet Interface eNet Safety eNet(Slave) Resource Center nostic Video Mon in Name Serv. Drive ny order for FRN. Diagnosis mic Space Check D Ethernet IO Normal Utility nced Dry Run nced Edit nced I/O nced Mirror Imag nced Stopping Code Output Recovery	☐ J967 : FSW programming ☐ R544 : Fault & Incident Rep ☐ R545 : Filtered Memory Dev. ☐ J558 : Finishing func PKG ☐ J758 : Fipio Interface ☐ J876 : Force Control Basic ☐ J877 : Force Control Fitting ☐ J835 : Force Ctl. Contouring ☐ R548 : Frequency Interface ☐ R550 : Function Instruction ☐ J649 : Gravity Compensation ☐ J831 : HDI for Line Tracking ☐ R553 : HMI Device (SNPX) ☐ J898 : High perf. softfloat ☐ R554 : Initial Setting Load ☐ R554 : Integral Pump Control ☐ J804 : Interbus PxC ☐ J896 : Interbus PxC ☐ J896 : Interference Check ☐ R699 : Interference Check ☐ R699 : Interference Avoidance ☐ R558 : Internet Conn/Custo ☐ J966 : Jnt Position output ☐ R632 : KAREL ☐ R566 : KAREL Diagnostic ☐ R567 : KAREL Trans/Comp ☐ J971 : KAREL develop support ☐ J512 : Line Tracking ☐ R569 : Line/Rail Tracking ☐ J806 : Local Stop ☐ J959 : M-10iA,M-20iA TUI	
		rnet Sniffer rnet/IP Adapter rnetIP I/O RTR	☐ J798 : M-2000-iA 1350kg Opt ☐ J798 : M-900iA 700kg option ☐ J897 : M-TP Interface	
R724 : Config. Presets R663 : Constant Path J613 : Continuous turn J756 : ControlNet Interface J757 : ControlNet(Slave)	\[rnetIP I/O scan bean special functi ath Optimization ded Axis Control anded User Frames	R572 : Manual Jog Panel R577 : Menu Utility	
☐ J686 : Coord Motion Package ☐ R669 : Coord-Motion Plus ☐ J619 : Coordinated Motion	J759 : FL-ne	t – Waterborne	R710 : Motion Data Viewer R711 : Motion Diagnostics R583 : Motion Optimization	

☐ J998 : Custom Log Output 1	R651 : FRL Params	☐ J605 : Multi Robot Control
☐ J964 : Multi UOP Interface	☐ J544 : Robot Isolation	R673 : Triple/Quad Arm Pkg
R670 : Multi-Arm Calibration	☐ J776 : Robot Simulator FCTN	J958 : Trouble Diag. & Prev.
R671 : Multi-Arm Pkg	R672 : RobotLink Plus Pkg	☐ J957 : USB port on iPendant
☐ J601 : Multi-Group Motion	R715 : S/W Reg Base	RVAT: Uneven Auto Tuning
	R611 : S/W Reg Cmn	J893 : Unified UserInterface
R585 : Off-line Singularity	R717 : S/W Reg Prem	R648 : User Socket Msg
R664 : Online Help	R677 : SMB Client	R690 : User TP Prog. Device
■ R586 : Opening Devices	R610 : SNTP Client	☐ J729 : V-500i/V-510i 3D
☐ J695 : Operation logbook	☐ J667 : Safety space	☐ J788 : V-500i VisTrack Basic
☐ J695 : Option size list	R712 : Sencoder Feedback	☐ J832 : V-500i VisTrack M-Arms
R641 : PC Interface	J502 : Sensor Interface	☐ J884 : V-500i VisTrack M-Robs
R652 : PMC Change Mode	☐ J671 : Servo Gun WT Compens	R625 : VersaBell
J760 : PMC(FAPT Ladder)	☐ J671 : Servo Tool Change	☐ J873 : Vision support tools
☐ J713 : PROFIBUS	☐ J979 : Servo gun setup pack	R702 : Vision Diagnostics
☐ J752 : PROFIBUS-DP(Master)	J833 : ServoGun Dual CPU	☐ J635 : Vision Tracking
☐ J751 : PROFIBUS-DP(Slave)	J777 : Simultaneous R. Link	R682 : Wait/Release Comm
☐ J930 : PROFINET I/O	☐ J854 : Slave motion I/F	☐ J724 : Wash teaching
R549 : Paint 2 Gun	☐ J644 : Small Circle Accuracy	R629 : Xrail Manager
R543 : Paint Cancel Recovery	☐ J892 : Smpl grp chg	☐ J775 : YELLOW BOX
R693 : PaintPRO Repairs	R636 : Socket Messaging	R726 : iRCalib. Signature
R589 : PaintTool Diagnostics	☐ J612 : Soft Float	R518 : iRCalibration Frame
☐ J500 : Palletizing	☐ J609 : Space Check	R601 : iRCalibration Master
R594 : Panel Wizard	☐ J820 : Special Control Stop	R617 : iRCalibration TCP
R643 : Parameter Control	☐ J538 : Special FWD/BWD	☐ J991 : iRCalibration VFrame
☐ J541 : Password Protection	☐ J559 : Special Jog Sequence	☐ J993 : iRCalibration VMCal
☐ J693 : PathSwitch	R614 : Standard Color Change	☐ J992 : iRCalibration VMaster
☐ J669 : Payload Ident.	☐ J629 : Stick Detection	☐ J994 : iRCalibration VShift
☐ J878 : Payload confirm	☐ J683 : Stitch function	☐ J990 : iRCalibration VTCP
☐ J975 : Pos.Rep.Conversion	R638 : TCP Mate	R575: iRVision 2D DEMO
☐ J932 : Positional record	☐ J694 : TCP SPEED OUTPUT	R685 : iRVision 2D Pkg
R597 : Process Champion	☐ J524 : TP Speed Prediction	☐ J901 : iRVision 2DV
R649 : Procsync function	R709 : TP DRAM/FILE Storage	J906 : iRVision 2DV Plus
☐ J697 : Program Viewer	R642 : TP Error Recovery	R714 : iRVision 3-D Multi VP
☐ J801 : Pump Only Motion	R620 : TP Shim (FlexTool)	J904 : iRVision 3D Tri-View
☐ J789 : QUEUE EXPAND	☐ J943 : TUI FANUC pos. disp.	☐ J902 : iRVision 3DL
☐ J968 : R2000iB200R,170CF TUI	☐ J940 : TUI Unified spec	J907 : iRVision 3DL Plus
☐ J547 : RIA	☐ J942 : TUI register transfer	J910 : iRVision AntiDefect
☐ J803 : ROBOMachine JOG	☐ J969 : Torlim Multi Setup	☐ J909 : iRVision Bin Picking
R603 : ROS Ethernet Packets	☐ J611 : Torque Limit	☐ J900 : iRVision Core
S178: RVAT for Developpers	☐ J882 : Torque Simulator I/F	☐ J920 : iRVision Core VCPU
☐ J624 : Remote TCP	R722 : Track Optimize tool	R730 : iRVision ErrP Adv Pkg
☐ J941 : Remote jog for TUI	R624 : Tracking Jog	R688 : iRVision ErrProof Pkg

☐ J905 : iRVision Error Proof
R697 : iRVision GiGe Camera
R728 : iRVision Img. File CS
☐ J870 : iRVision KAREL I/F
☐ J872 : iRVision Online Help
☐ J874 : iRVision Part Queue
☐ J868 : iRVision Standard
☐ J869 : iRVision TPP I/F
☐ J871 : iRVision UIF Controls
☐ J903 : iRVision VisTrack
R687 : iRVision VisTrack Pkg
☐ J921 : pl.Collision Skip
☐ NGIP : soft float recovery
☐ J999 : software for debug

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Change History:	Software Engineer: Matt White		
	Software Engineer. Wate Write		
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J726 : 2D Vision	m Setting 1		
□ R520 : Center Finder □ J527 : Error O □ J795 : Clock Simulaneous □ J664 : Error O □ R534 : Collision Guard □ R569 : Ether □ J684 : Collision Guard Pack □ R538 : Ether □ J666 : Collision Skip □ R539 : Ether □ R724 : Config. Presets □ R540 : Ether □ R663 : Constant Path □ J537 : Europ □ J613 : Continuous turn □ J829 : Ext Pa □ J756 : ControlNet Interface □ J518 : Extend □ J757 : ControlNet(Slave) □ R696 : Extend □ J686 : Coord Motion Package □ J759 : FL-net	Recovery The the Sniffer The the Sniff		

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