

Yoonchang Sung

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Education

Virginia Tech, Blacksburg, USA

Ph.D. in Electrical & Computer Engineering, September 2014–Present

Advisor: Pratap Tokekar

Korea University, Seoul, Korea

M.S. in Mechanical Engineering, August 2013

Advisor: Woojin Chung

Korea University, Seoul, Korea

B.S. in Mechanical Engineering, February 2011

Employment

Research Assistant, September 2016–Present

Dept. of Electrical & Computer Engineering, Virginia Tech, Blacksburg, USA

Advisor: Pratap Tokekar

Research Assistant, September 2014–August 2016

Dept. of Mechanical Engineering, Virginia Tech, Blacksburg, USA

Advisor: Brian Lattimer & Tomonari Furukawa

Research Intern, August 2013–June 2014

Center for Bionics, Korea Institute of Science and Technology, Seoul, Korea

Supervisor: JongSuk Choi

Research Assistant, March 2011–August 2013

Dept. of Mechanical Engineering, Korea University, Seoul, Korea

Advisor: Woojin Chung

Teaching

Teaching Assistant

Dept. of Mechanical Engineering, Korea University, Seoul, Korea

MECH 210: Computer Aided Mechanical Drawing, Spring 2012

MECH 328: Machine Component Design, Fall 2011

Dept. of Electrical & Computer Engineering, Virginia Tech, Blacksburg, USA

ECE 4984: SS:Robot Motion Planning, Guest Lecturer: Introduction to ROS, August 2018

Publications

Journal Articles

In Preparation

[J7] **Y. Sung**, and P. Tokekar, “A competitive algorithm for online multi-robot exploration of a translating plume,” *IEEE Transactions on Robotics (T-RO)*, Note: In Preparation.

[J6] **Y. Sung**, J. Das, and P. Tokekar, “An introduction to decision making for robotic environmental monitoring,” *IEEE Robotics and Automation Magazine (RAM)*, Note:

In Preparation.

Under Review

[J5] Z. Zhang, J. Lee, JM Smereka, **Y. Sung**, L. Zhou, and P. Tokekar, “Tree search techniques for minimizing detectability and maximizing visibility,” *IEEE Robotics and Automation Letters (RA-L)*, Note: Revision Under Review.

[J4] **Y. Sung**, AK Budhiraja, RK Williams, and P. Tokekar, “Distributed assignment with limited communication for multi-robot multi-target tracking,” *Autonomous Robots (AURO)*, *Special Issue on Robot Communication Challenges*, Note: Conditionally Accepted.

[J3] **Y. Sung**, and P. Tokekar, “GM-PHD filter for searching and tracking an unknown number of targets with a mobile sensor with limited FoV,” *IEEE Transactions on Automation Science and Engineering (T-ASE)*, Note: Revision Under Review.

Published

[J2] C. Knabe, R. Griffin, J. Burton, G. Cantor-Cooke, L. Dantanarayana, G. Day, O. Ebeling-Koning, E. Hahn, M. Hopkins, J. Neal, J. Newton, C. Nogales, V. Orekhov, J. Peterson, M. Rouleau, J. Seminatore, **Y. Sung**, J. Webb, N. Wittenstein, J. Ziglar, A. Leonessa, B. Lattimer, and T. Furukawa, “Team VALOR’s ESCHER: A novel electromechanical biped for the DARPA Robotics Challenge,” *Journal of Field Robotics (JFR)*, 34(5): pp. 912-939, 2017.

[J1] **Y. Sung**, and W. Chung, “Hierarchical sample-based joint probabilistic data association filter for following human legs using a mobile robot in a cluttered environment,” *IEEE Transactions on Human-Machine Systems (T-HMS)*, 46(3): pp. 340-349, 2016.

Refereed Conference Publications

Under Review

[C10] Z. Zhang, J. Lee, JM Smereka, **Y. Sung**, L. Zhou, and P. Tokekar, “Tree search techniques for minimizing detectability and maximizing visibility,” *IEEE International Conference on Robotics and Automation (ICRA 2019)*, Note: Under Review.

[C9] **Y. Sung**, and P. Tokekar, “A competitive algorithm for online multi-robot exploration of a translating plume,” *IEEE International Conference on Robotics and Automation (ICRA 2019)*, Note: Under Review.

Published

[C8] **Y. Sung**, AK Budhiraja, RK Williams, and P. Tokekar, “Distributed simultaneous action and target assignment for multi-robot multi-target tracking,” *IEEE International Conference on Robotics and Automation (ICRA 2018)*, 2018.

[C7] **Y. Sung**, and P. Tokekar, “Hierarchical GM-PHD filter for false alarm reduction in search and tracking task,” *US-KOREA Conference on Science, Technology and Entrepreneurship (UKC 2017)*, 2017.

[C6] **Y. Sung**, and P. Tokekar, “Algorithms for searching and tracking an unknown and varying number of mobile targets using a limited FoV sensor,” *IEEE International Conference on Robotics and Automation (ICRA 2017)*, 2017.

[C5] JH Kim, **Y. Sung**, and B. Lattimer, “Bayesian estimation based real-time fire-heading in smoke-filled indoor environments using thermal imagery,” *IEEE International Conference on Robotics and Automation (ICRA 2017)*, 2017.

[C4] **Y. Sung**, and T. Furukawa, “Information measure for the optimal control of target searching via the grid-based method,” *International Conference on Information Fusion (Fusion 2016)*, 2016.

- [C3] B. Lattimer, J. Starr, J. McNeil, C. Nogales, J. Peterson, J. Ziglar, J. Burton, C. Knabe, **Y. Sung**, J. Seminatore, R. Griffin, J. Newton, V. Orekhov, M. Rouleau, M. Hopkins, D. Hong, and D. Lee, “Humanoid firefighting robot for structure fires,” *International Conference and Exhibition on Fire Science and Engineering (Interflam 2016)*, 2016.
- [C2] D. Cha, H. Cho, J. Jin, H. Kwon, J. Kim, H. Lee, J. Seong, C. Moon, H. Kim, **Y. Sung**, and W. Chung, “Tracking human legs for an indoor mobile robot with a single laser range finder,” *International Conference on Engineering and Applied Sciences (ICEAS 2015)*, 2015.
- [C1] **Y. Sung**, and W. Chung, “Human tracking of a mobile robot with an onboard LRF(Laser Range Finder) using human walking motion analysis,” *International Conference on Ubiquitous Robots and Ambient Intelligence (URAI 2011)*, 2011.

Refereed Workshop Publications

- [W2] **Y. Sung**, S. Buebel, and P. Tokekar, “Detecting and mapping hazardous plumes with aerial and surface robots,” *IEEE International Conference on Robotics and Automation (ICRA 2018) Workshop on Robot Teammates Operating in Dynamic, Unstructured Environment*, 2018.
- [W1] **Y. Sung**, AK Budhiraja, RK Williams, and P. Tokekar, “Distributed simultaneous action and target assignment for multi-robot multi-target tracking,” *IEEE International Conference on Robotics and Automation (ICRA 2017) Workshop on Multi-robot Perception-driven Control and Planning*, 2017.

Book Chapters

- [B1] C. Knabe, R. Griffin, J. Burton, G. Cantor-Cooke, L. Dantanarayana, G. Day, O. Ebeling-Koning, E. Hahn, M. Hopkins, J. Neal, J. Newton, C. Nogales, V. Orekhov, J. Peterson, M. Rouleau, J. Seminatore, **Y. Sung**, J. Webb, N. Wittenstein, J. Ziglar, A. Leonessa, B. Lattimer, and T. Furukawa, “Team VALOR’s ESCHER: A Novel Electromechanical Biped for the DARPA Robotics Challenge,” *The DARPA Robotics Challenge Finals: Humanoid Robots To The Rescue*. Springer, Cham., pp. 583-629, 2018.

Posters

- [P1] **Y. Sung**, and W. Chung, “Implementation of JPDAFs to track humans for a mobile robot with a laser range finder,” *IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN 2013)*, 2013.

Patents

- Y. Sung**, and W. Chung, “Leg tracking method based on SJPDF method,” KR (No. 10-1573620)

Honors

Awards

Conference Travel Awards: ICRA 2017, ICRA 2018
 DARPA Robotics Challenge (DRC) Finalist, 2015

Graduate Fellowship

Research Assistant Scholarships, Virginia Tech, Blacksburg, USA, Fall 2014–Present
 The Welfare Section Scholarship, Korea University, Seoul, Korea, Fall 2012, Spring 2012
 The Second Stage of BK21 Scholarship, Korea University, Seoul, Korea, Spring 2011
 Research Assistant Scholarships, Korea University, Seoul, Korea, Fall 2011

Undergraduate Fellowship

Best Honors Scholarships, Korea University, Seoul, Korea, Spring 2010
Honors Scholarships, Korea University, Seoul, Korea, Fall 2010, Spring 2009, Fall
2008
National Science Scholarship, Korea University, Seoul, Korea, Fall 2009

References Available Upon Request (Last updated: Jan 4, 2019)