

# Yoonchang Sung

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## Research Interests

Robotics algorithms, Embodied AI, Robot manipulation, Task and motion planning, Multi-robot systems

## Employment

<b>Nanyang Technological University</b> <b>College of Computing and Data Science</b> Assistant Professor	Apr 2025 - Present Singapore
<b>The University of Texas at Austin</b> <b>Department of Computer Science</b> Postdoctoral Fellow Host: Peter Stone	Oct 2021 - Mar 2025 Austin, TX, USA
<b>Massachusetts Institute of Technology</b> <b>Computer Science and Artificial Intelligence Laboratory (CSAIL)</b> Postdoctoral Associate Hosts: Leslie Pack Kaelbling and Tomás Lozano-Pérez	Oct 2019 - Sep 2021 Cambridge, MA, USA

## Education

<b>Ph.D. in Electrical and Computer Engineering</b> <b>Virginia Tech</b> Advisor: Pratap Tokekar Thesis: Multi-robot coordination for hazardous environmental monitoring	Sep 2019 Blacksburg, VA, USA
<b>M.S. in Mechanical Engineering</b> <b>Korea University</b> Advisor: Woojin Chung Thesis: Novel tracking method for following human legs using a mobile robot in a cluttered environment	Aug 2013 Seoul, Korea
<b>B.S. in Mechanical Engineering</b> <b>Korea University</b>	Feb 2011 Seoul, Korea

## Honors

Microsoft Future Leader in Robotics and AI, 2025  
IROS Best Cognitive Robotics Paper Award Finalist, 2021  
IROS Best Robocup Paper Award Winner, 2021

Robotics: Science and Systems (RSS) Pioneers, 2019  
DARPA Robotics Challenge (DRC) Finalist, 2015  
Korea University Best Honors Scholarships, Spring 2010  
Korea University Honors Scholarships, Fall 2008, Spring 2009, Fall 2010  
Korea National Science Scholarship (merit-based), Fall 2009

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## Journal Publications

(<sup>+</sup>: corresponding author, <sup>\*</sup>: equal contribution, <sup>#</sup>: student I mentored)

Faraz Heravi<sup>\*</sup>, James Ouyang<sup>\*</sup>, Zifan Xu, Arjun Kumar, **Yoonchang Sung**, Peter Stone. "LLM-enhanced curriculum learning for reinforcement learning in long-horizon manipulation tasks." In Revision.

**Yoonchang Sung**<sup>\*</sup>, Shahaf Shperberg<sup>\*</sup>, Qi Wang<sup>\*</sup>, Yoonwoo Kim, Peter Stone. "Effort allocation for deadline-aware task and motion planning: a metareasoning approach." In Revision.

**Yoonchang Sung**, Zhiang Chen, Jnaneshwar Das, Pratap Tokekar. "A Survey of decision-theoretic approaches for robotic environmental monitoring." *Foundations and Trends in Robotics*, 2023.

**Yoonchang Sung**, Pratap Tokekar. "GM-PHD filter for searching and tracking an unknown number of targets with a mobile sensor with limited FOV." *IEEE Transactions on Automation Science and Engineering (T-ASE)*, 2021.

Zhongshun Zhang, Jonathon M. Smereka, Joseph Lee, Lifeng Zhou, **Yoonchang Sung**, Pratap Tokekar. "Game tree search for minimizing detectability and maximizing visibility." *Autonomous Robots (AURO)*, 2021.

**Yoonchang Sung**, Ashish K. Budhiraja, Ryan K. Williams, Pratap Tokekar. "Distributed assignment with limited communication for multi-robot multitarget tracking." *Autonomous Robots (AURO)*, 2020.

**Yoonchang Sung** is one of 23 co-authors. "Team VALOR's ESCHER: A novel electromechanical biped for the DARPA Robotics Challenge." *Journal of Field Robotics (JFR)*, 2017.

**Yoonchang Sung**, Woojin Chung. "Hierarchical sample-based joint probabilistic data association filter for following human legs using a mobile robot in a cluttered environment." *IEEE Transactions on Human-Machine Systems (T-HMS)*, 2015.

## Conference Publications

Yoonwoo Kim<sup>#</sup>, Raghav Arora<sup>#</sup>, Roberto Martín-Martín, Peter Stone, Ben AbbateMatteo, **Yoonchang Sung**<sup>+</sup>. "Large-language-model-guided state estimation for partially observable task and motion planning." Under Review.

Zichen Wang, Jingjing Wang, Zhijun Meng, Gai Weiqi, Qingfang Xiao, Guodong Zhao, Yufan Xie, **Yoonchang Sung**, Pujie Xin, Peng Pan. "Topological graph partition based UAV hierarchical autonomous target search framework." Under Review.

Caroline Wang<sup>\*</sup>, Arrasy Rahman<sup>\*</sup>, Jiaxun Cui, **Yoonchang Sung**, Peter Stone. "ROTATE: Regret-driven open-ended

training for ad hoc teamwork." Under Review.

**Yoonchang Sung** is one of 86 co-authors. "Evaluating generalization capabilities of LLM-based agents in mixed-motive scenarios using concordia." *Advances in Neural Information Processing Systems (NeurIPS) Datasets and Benchmarks Track*, 2025.

Mingyo Seo\*\*#, Yoonyoung Cho\*, **Yoonchang Sung**, Peter Stone, Yuke Zhu, Beomjoon Kim. "PRESTO: fast motion planning using diffusion models based on key-configuration environment representation." *IEEE International Conference on Robotics and Automation (ICRA)*, 2025.

**Yoonchang Sung**, Rahul Shome, Peter Stone. "Asynchronous task plan refinement for multi-robot task and motion planning." *IEEE International Conference on Robotics and Automation (ICRA)*, 2024.

**Yoonchang Sung**, Peter Stone. "Motion planning (in)feasibility detection using a prior roadmap via path and cut search." *Robotics: Science and Systems (RSS)*, 2023.

**Yoonchang Sung**\*, Zizhao Wang\*, Peter Stone. "Learning to correct mistakes: backjumping in long-horizon task and motion planning." *Conference on Robot Learning (CoRL)*, 2022.

Kaiyu Zheng#, Rohan Chitnis, **Yoonchang Sung**, George Konidaris, Stefanie Tellex. "Towards optimal correlational object search." *IEEE International Conference on Robotics and Automation (ICRA)*, 2022.

**Yoonchang Sung**, Leslie P. Kaelbling and Tomás Lozano-Pérez. "Learning when to quit: meta-reasoning for motion planning." *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2021. **(Finalist for Best Cognitive Robotics Paper Award)**

Kaiyu Zheng#, **Yoonchang Sung**, George Konidaris, Stefanie Tellex. "Multi-resolution POMDP planning for multi-object search in 3D." *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2021. **(Winner of Best Robocup Paper Award)**

Shen Li\*, Daehyung Park\*, **Yoonchang Sung**\*, Julie Shah, Nicholas Roy. "Reactive task and motion planning under temporal logic specifications." *IEEE International Conference on Robotics and Automation (ICRA)*, 2021.

**Yoonchang Sung**, Deeksha Dixit, Pratap Tokekar. "Environmental hotspot identification in limited time with a UAV equipped with a downward-facing camera." *IEEE International Conference on Robotics and Automation (ICRA)*, 2021.

Zhongshun Zhang, Jonathon M. Smereka, Joseph Lee, **Yoonchang Sung**, Lifeng Zhou, Pratap Tokekar. "Tree search techniques for minimizing detectability and maximizing visibility." *IEEE International Conference on Robotics and Automation (ICRA)*, 2019.

**Yoonchang Sung**, Pratap Tokekar. "A competitive algorithm for online multi-robot exploration of a translating plume." *IEEE International Conference on Robotics and Automation (ICRA)*, 2019.

**Yoonchang Sung**, Ashish K. Budhiraja, Ryan K. Williams, Pratap Tokekar. "Distributed simultaneous action and target assignment for multi-robot multitarget tracking." *IEEE International Conference on Robotics and Automation*

(ICRA), 2018.

**Yoonchang Sung**, Pratap Tokekar. "Algorithms for searching and tracking an unknown and varying number of mobile targets using a limited FoV sensor." *IEEE International Conference on Robotics and Automation (ICRA)*, 2017.

**Yoonchang Sung**, Tomonari Furukawa. "Information measure for the optimal control of target searching via the grid-based method." *International Conference on Information Fusion (Fusion)*, 2016.

## Workshop Publications

Caroline Wang\*, Arrasy Rahman\*, Jiaxun Cui, **Yoonchang Sung**, Peter Stone. "ROTATE: Regret-driven open-ended training for ad hoc teamwork." *Reinforcement Learning Conference (RLC) Workshop on Coordination and Cooperation in Multi-Agent Reinforcement Learning*, 2025.

Miguel Iglesias Alcázar, Fernando Fernández Rebollo, **Yoonchang Sung**, Yuqian Jiang. "Formalization, development, and baseline analysis of a task and motion planning domain in RDDL." *International Conference on Automated Planning and Scheduling (ICAPS) Workshop on the International Planning Competition*, 2024.

**Yoonchang Sung**, Spencer Buebel, Pratap Tokekar. "Detecting and mapping hazardous plumes with aerial and surface robots." *IEEE International Conference on Robotics and Automation (ICRA) Workshop on Robot Teammates Operating in Dynamic, Unstructured Environment*, 2018.

**Yoonchang Sung**, Ashish K. Budhiraja, Ryan K. Williams, Pratap Tokekar. "Distributed simultaneous action and target assignment for multi-robot multi-target tracking." *IEEE International Conference on Robotics and Automation (ICRA) Workshop on Multi-robot Perception-driven Control and Planning*, 2017.

## Preprints

**Yoonchang Sung**, Deeksha Dixit, Pratap Tokekar. "Online exploration of an unknown region of interest with a team of aerial robots." arXiv 2018.

## Patents

**Yoonchang Sung**, Woojin Chung. "Leg tracking method based on SJPDAF method." KR (No. 10-1573620).

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## Teaching

Guest Lecturer for Task and Motion Planning, KAIST AI. Seoul, Korea, Dec 2024

Guest Lecturer for Intelligent Robotic Systems, Sogang University. Seoul, Korea, May 2024

Guest Lecturer for Robot Learning and Interaction, KAIST. Daejeon, Korea, Apr 2022

Guest Lecturer for Robot Motion Planning, Virginia Tech. Blacksburg, VA, USA Aug 2018

Teaching Assistant for Computer Aided Mechanical Drawing, Korea University. Seoul, Korea, Spring 2012

Teaching Assistant for Machine Component Design, Korea University. Seoul, Korea, Fall 2011

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## Funding

### Current

Bridging the Deployment Gap with Generative AI. NRF T-CRP

PI: Harold Soh, Co-PIs: Yoonchang Sung, Cheston Tan, S\$4,000,000, Personal Share: S\$750,000, 10/2025-10/2029

Development and Demonstration of an Integrated Automation System for a Precision Strawberry Harvesting and Packaging AI Robot. AcRF Tier 1 Seed Funding Grant

PI: Cha Robotics, Co-PI: Yoonchang Sung, S\$620,000, Personal Share: S\$177,000, 10/2025-10/2027

Meta-reasoning for Robot Motion Planning Problems: Learning to Detect (In)feasibility. AcRF Tier 1 Grant

PI: Yoonchang Sung, S\$100,000, 10/2025-10/2027

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## Student Advising

### Ph.D. Students

Jean-Manuel Cabrillana, NTU Singapore, 2025-Present

Yeseung Kim (Ph.D. advisor: Daehyung Park), KAIST, 2024-2025

Ming Liu (Ph.D. advisor: Peter Stone), UT Austin, 2024-Present

Yoonwoo Kim (Ph.D. advisor: Peter Stone), UT Austin, 2023-Present

Yoonyoung Cho (Ph.D. advisor: Beomjoon Kim), KAIST, 2023-2024

Mingyo Seo (Ph.D. advisors: Luis Sentis and Yuke Zhu), UT Austin, 2022-2024

Zizhao Wang (Ph.D. advisor: Peter Stone), UT Austin, 2022

Yuqian Jiang (Ph.D. advisor: Peter Stone), UT Austin, 2021-2022

Yifeng Zhu (Ph.D. advisors: Peter Stone and Yuke Zhu), UT Austin, 2021-2022

Kaiyu Zheng (Ph.D. advisor: Stefanie Tellex), Brown University, 2019-2021

### M.S./MEng Students

Antareep Singha, NTU Singapore, 2025-Present

Ajith Kemisetty (M.S. advisor: Peter Stone), UT Austin, 2024-Present

Raghav Arora (M.S. advisor: Peter Stone), UT Austin, 2024-Present

Jasmeet Kaur (M.S. advisor: Peter Stone), UT Austin, 2022-2023

Shiloh Curtis (MEng advisor: Leslie Pack Kaelbling), MIT, 2020-2021

Deeksha Dixit (M.S. advisor: Pratap Tokekar), Virginia Tech, 2018-2019

### Undergraduate Students

Juho Kim, Seoul National University, 2025

Qi Wang, UT Austin, 2023-2024

Arjun Kumar, UT Austin, 2024-Present

Aaroh Gokhale, UT Austin, 2024

Jay Shim, UT Austin, 2024-Present

Romir Sharma, UT Austin, 2024-Present

## Mentoring Programs

## Thesis Supervision

### M.S./MEng Students

Ajith Kemissetti. "Stochastic SIPP: a novel approach for motion planning in stochastic dynamic environments." UT Austin, 2024.

Shiloh Curtis. "A hierarchical algorithm for probabilistically complete path planning in multi-floor environments." MIT, 2021.

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## Invited Talks

### Beyond Motion Planning for Static Environments: Addressing Dynamic and Partially Observable Worlds

Workshop on LeaPRiDE: Learning, Planning, and Reasoning in Dynamic Environments at IROS 2025, Oct 2025

### TAMP Approach to Robot Manipulation Problems: Challenges and Opportunities

Pinto Group, New York University, NY, USA, May 2025

### Extending Current Capabilities of Task and Motion Planning

LIS Group, Massachusetts Institute of Technology, MA, USA, Apr 2025

Khoury College of Computer Sciences, Northeastern University, MA, USA, Apr 2025

Department of Computer Science Engineering, Kyung Hee University, Korea, Dec 2024

Kavraki Lab, Rice University, TX, USA, Dec 2024

### Towards Long-Horizon Robot Decision Making

Computer Science and Engineering, UNSW Sydney, Australia, Oct 2024

College of Computing and Data Science, Nanyang Technological University, Singapore, Sep 2024

AIIS, Seoul National University, Korea, Aug 2024

Department of Artificial Intelligence, Yonsei University, Korea, Aug 2024

Department of Electronic Engineering, Sogang University, Korea, Aug 2024

Department of Computer Science and Engineering, POSTECH, Korea, Aug 2024

School of Computing, KAIST, Korea, Aug 2024

Department of Artificial Intelligence, Korea University, Korea, Aug 2024

AIR Group, Binghamton University, NY, USA, Jul 2024

Computer Science Department, University of Texas at Dallas, TX, USA, Apr 2024

Department of Computer Science, NC State University, NC, USA, Feb 2024

### Exploring Long-Horizon Dependency in Task and Motion Planning

IMΛ2 lab, KAIST AI, Korea, Oct 2022

School of Mechanical Engineering, Korea University, Korea, Oct 2022

### Meta-Reasoning for Task and Motion Planning

School of Computing, KAIST, Korea, Apr 2022

SISL Lab, Stanford University, CA, USA, Nov 2021

## **Robust Autonomy in the Wild**

Workshop on Robots in the Wild: Challenges in Deploying Robust Autonomy for Robotic Exploration at RSS  
2020, July 2020  
Brown Robotics, Brown University, RI, USA, Nov 2019  
NAVER LABS, Korea, Jul 2019  
Department of Aerospace Engineering, KAIST, Korea, Jun 2019

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## **Service**

### **Technical Committee**

Junior Co-chair, IEEE Robotics and Automation Society Technical Committee on Multi-Robot Systems, 2025

### **Conference Organizing Committee**

Conference on Robot Learning (CoRL) Publication Chair, 2026

### **Senior Program Committee**

- International Joint Conference on Artificial Intelligence (IJCAI) Conference Editorial Board, 2025

### **Program Committee**

- AAAI Conference on Artificial Intelligence (AAAI) Conference Editorial Board, 2023-2026

### **Associate Editor**

- IEEE International Conference on Robotics and Automation (ICRA) Conference Editorial Board, 2026  
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) Conference Editorial Board, 2021

### **Workshop Co-organizer**

- Robotics: Science and Systems (RSS) Pioneers, Oregon, USA, Jul 2020  
- Full-day workshop, Robotics: Science and Systems (RSS), Freiburg, Germany, Jun 2019  
(Title: Robots in the wild: challenges in deploying robust autonomy for robotic exploration)

### **Reviewer**

- Journals: International Journal of Robotics Research (IJRR), IEEE Transactions on Robotics (T-RO), Autonomous Robots (AURO), IEEE Transactions on Automation Science and Engineering (T-ASE), IEEE Robotics and Automation Letters (RA-L), Artificial Intelligence (AI)  
- Conferences: IEEE International Conference on Robotics and Automation (ICRA), IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Robotics: Science and Systems (RSS), Conference on Robot Learning (CoRL), Workshop on the Algorithmic Foundations of Robotics (WAFR), AAAI Conference on Artificial Intelligence (AAAI), International Joint Conference on Artificial Intelligence (IJCAI), IEEE International Symposium on Multi-Robot & Multi-Agent Systems (MRS), International Conference on Autonomous Agents and Multiagent Systems (AAMAS)

### **Graduate Admission Committee**

- UT Austin CS. Fall 2024 admission  
- MIT CSAIL. Fall 2021 admission

**Misc. Organizer**

- Korean-American Roboticists Association (KARA), 2025

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