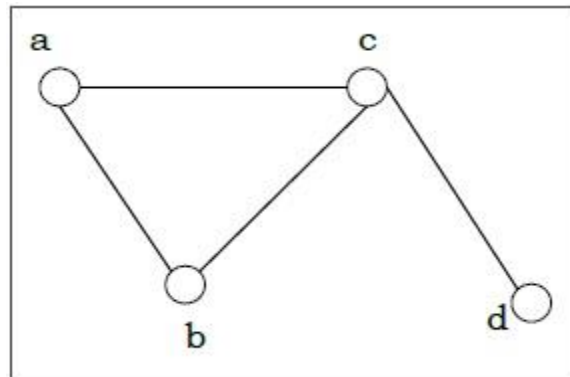


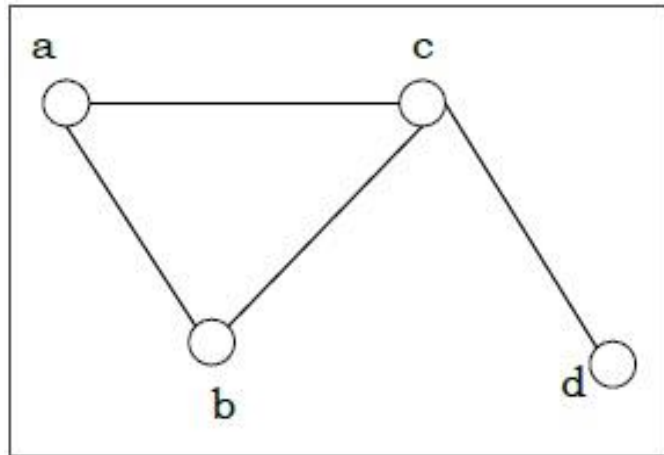
Graph Theory

Definition

- A graph (denoted as $G=(V,E)$) consists of a non-empty set of vertices or nodes V and a set of edges E .
- **Example** – Let us consider, a Graph is $G=(V,E)$ where $V=\{a,b,c,d\}$ and $E=\{\{a,b\},\{a,c\},\{b,c\},\{c,d\}\}$



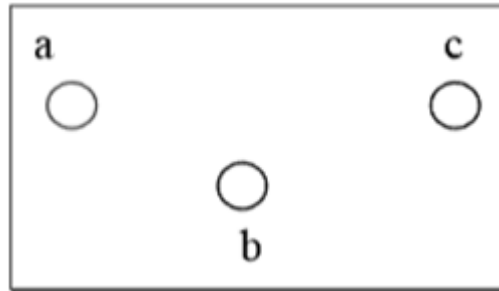
- **Degree of a Vertex** – The degree of a vertex V of a graph G (denoted by $\deg(V)$) is the number of edges incident with the vertex V .
- **Even and Odd Vertex** – If the degree of a vertex is even, the vertex is called an even vertex and if the degree of a vertex is odd, the vertex is called an odd vertex.
- **Degree of a Graph** – The degree of a graph is the largest vertex degree of that graph. For the below graph the degree of the graph is 3.
- **The Handshaking Lemma** – In a graph, the sum of all the degrees of all the vertices is equal to twice the number of edges.



Vertex	Degree	Even / Odd
a	2	even
b	2	even
c	3	odd
d	1	odd

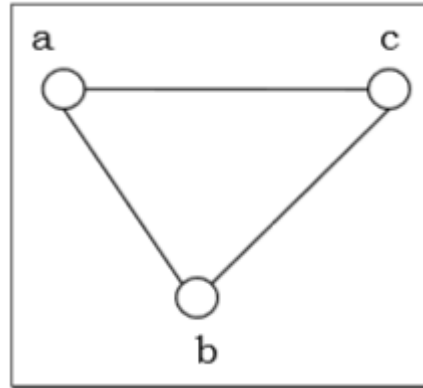
Types of Graphs

- There are different types of graphs, which we will learn in the following section.
- Null Graph
- A null graph has no edges. The null graph of n vertices is denoted by N_n



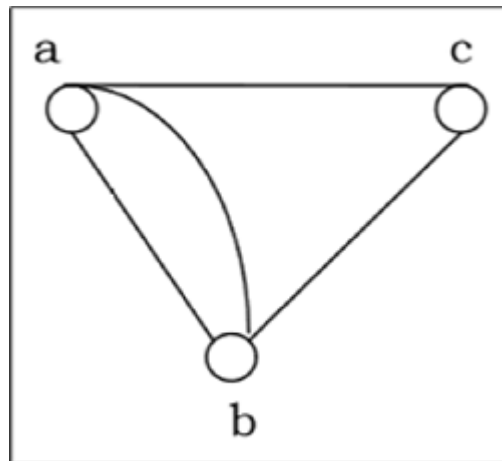
Simple Graph

A graph is called simple graph/strict graph if the graph is undirected and does not contain any loops or multiple edges.



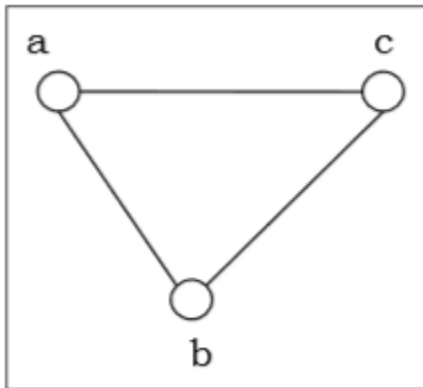
Multi-Graph

If in a graph multiple edges between the same set of vertices are allowed, it is called Multigraph. In other words, it is a graph having at least one loop or multiple edges.

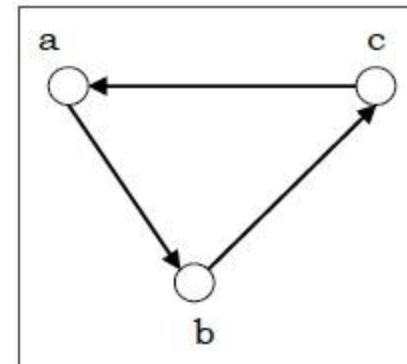


Directed and Undirected Graph

A graph $G=(V,E)$ is called a directed graph if the edge set is made of ordered vertex pair and a graph is called undirected if the edge set is made of unordered vertex pair.



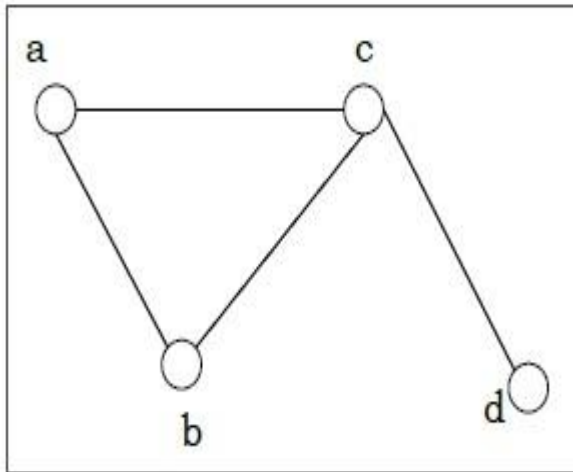
Undirected Graph



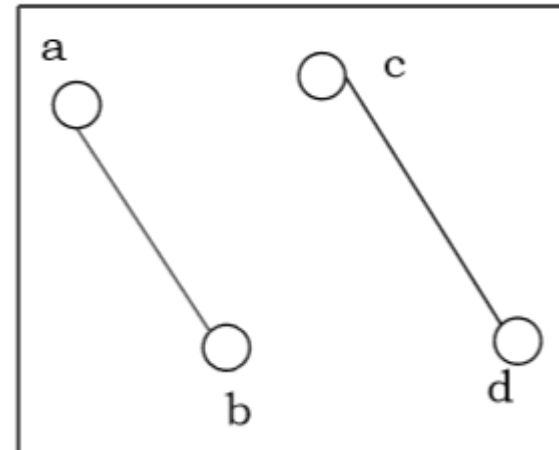
Directed Graph

Connected and Disconnected Graph

A graph is connected if any two vertices of the graph are connected by a path; while a graph is disconnected if at least two vertices of the graph are not connected by a path. If a graph G is disconnected, then every maximal connected subgraph of G is called a connected component of the graph G .



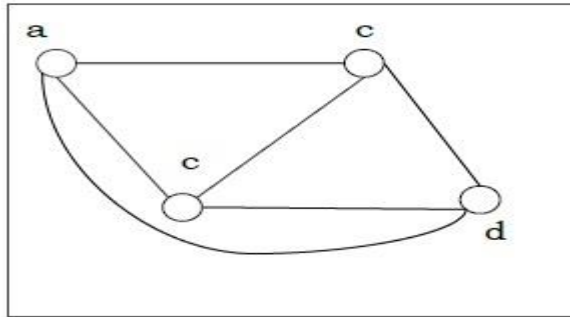
Connected Graph



Disconnected Graph

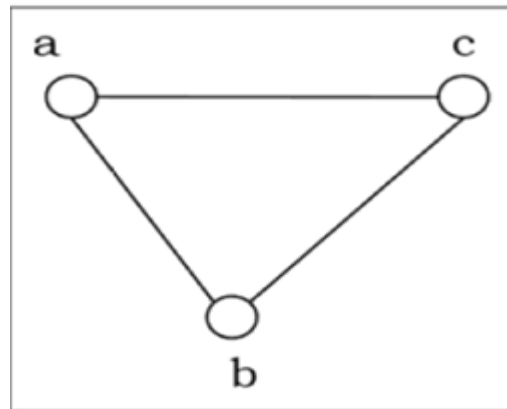
Regular Graph

A graph is regular if all the vertices of the graph have the same degree. In a regular graph G of degree r , the degree of each vertex of G is r .



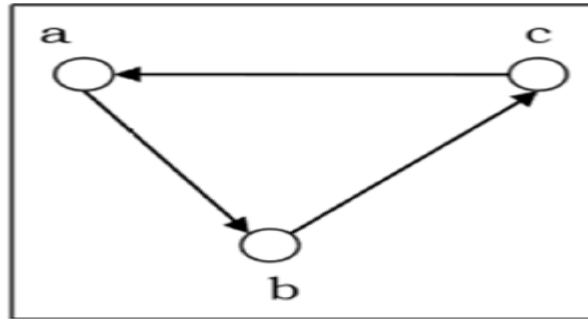
Complete Graph

A graph is called complete graph if every two vertices pair are joined by exactly one edge. The complete graph with n vertices is denoted by K_n



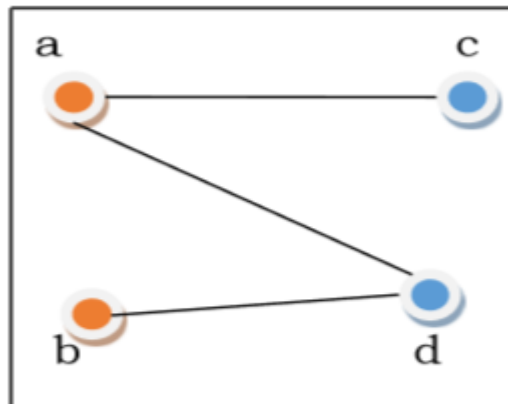
Cycle Graph

If a graph consists of a single cycle, it is called cycle graph. The cycle graph with n vertices is denoted by C_n



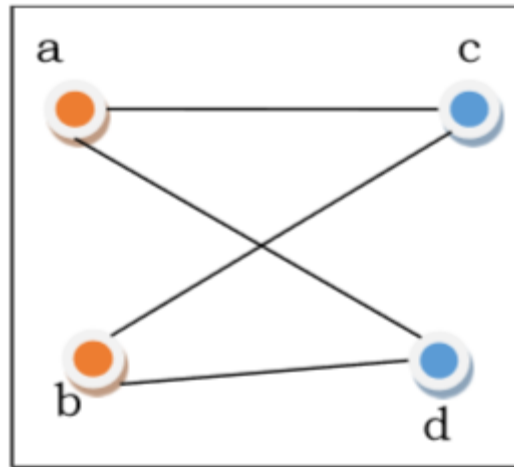
Bipartite Graph

If the vertex-set of a graph G can be split into two disjoint sets, V_1 and V_2 , in such a way that each edge in the graph joins a vertex in V_1 to a vertex in V_2 , and there are no edges in G that connect two vertices in V_1 or two vertices in V_2 , then the graph G is called a bipartite graph.



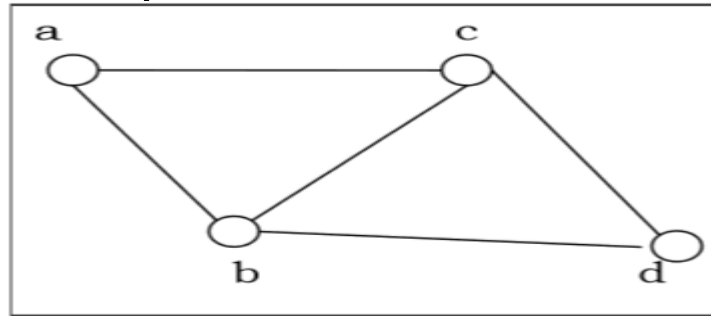
Complete Bipartite Graph

A complete bipartite graph is a bipartite graph in which each vertex in the first set is joined to every single vertex in the second set. The complete bipartite graph is denoted by $K_{x,y}$ where the graph G contains x vertices in the first set and y vertices in the second set.



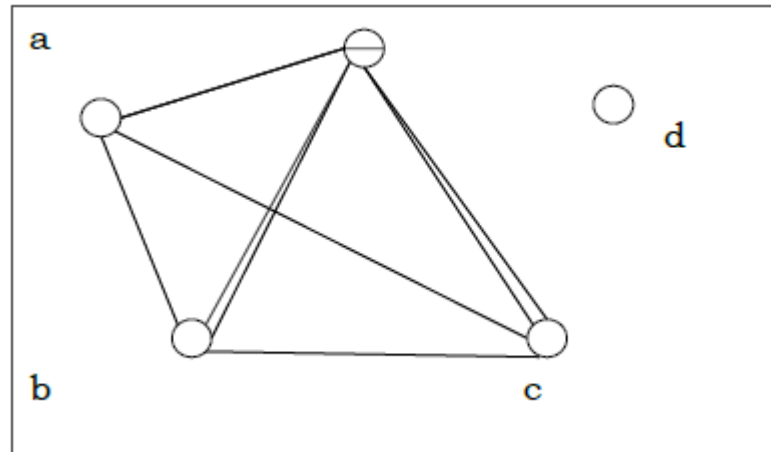
Planar graph

A graph G is called a planar graph if it can be drawn in a plane without any edges crossed. If we draw graph in the plane without edge crossing, it is called embedding the graph in the plane.



Non-planar graph

A graph is non-planar if it cannot be drawn in a plane without graph edges crossing.



Representation of Graphs

There are mainly two ways to represent a graph –

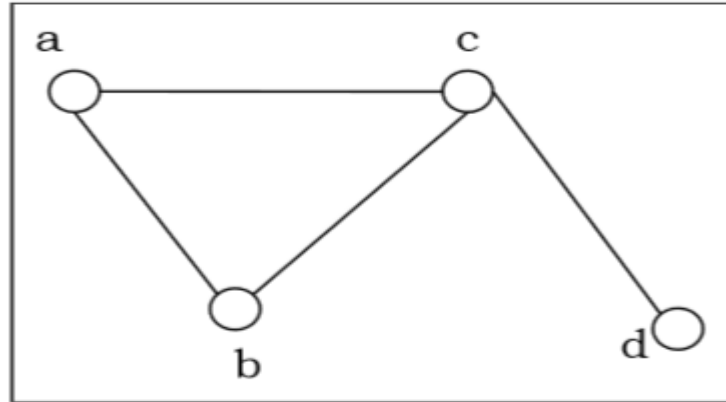
1. Adjacency Matrix
2. Adjacency List

Adjacency Matrix

An Adjacency Matrix $A[V]$ is a 2D array of size $V \times V$ where V is the number of vertices in a undirected graph. If there is an edge between V_x to V_y then the value of $A[V_x][V_y]=1$ and $A[V_y][V_x]=1$, otherwise the value will be zero. And for a directed graph, if there is an edge between V_x to V_y , then the value of $A[V_x][V_y]=1$, otherwise the value will be zero.

Adjacency Matrix of an Undirected Graph

Let us consider the following undirected graph and construct the adjacency matrix –

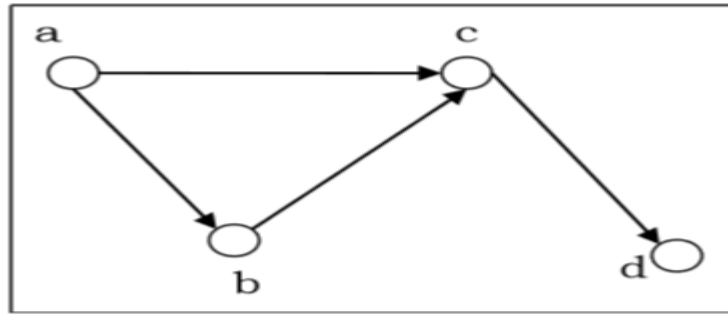


Adjacency matrix of the above undirected graph will be –

	a	b	c	d
a	0	1	1	0
b	1	0	1	0
c	1	1	0	1
d	0	0	1	0

Adjacency Matrix of a Directed Graph

Let us consider the following directed graph and construct its adjacency matrix

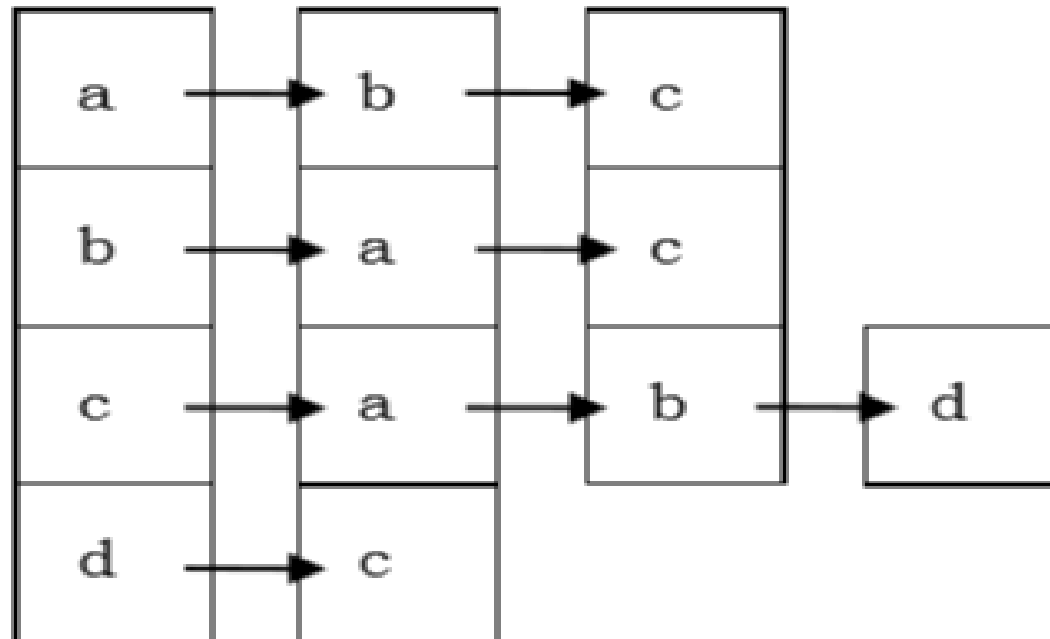


Adjacency matrix of the above directed graph will be –

	a	b	c	d
a	0	1	1	0
b	0	0	1	0
c	0	0	0	1
d	0	0	0	0

Adjacency List

In adjacency list, an array ($A[V]$) of linked lists is used to represent the graph G with V number of vertices. An entry $A[V_x]$ represents the linked list of vertices adjacent to the V_x -th vertex. The adjacency list of the undirected graph is as shown in the figure below –



Questions

1. Consider a graph G with vertices $\{v_1, v_2, v_3, v_4\}$ and edges $(v_1, v_3), (v_1, v_4), (v_2, v_3)$. Which of the following are subgraphs of G ?
 - Graph G_1 with vertex v_1 and edge (v_1, v_3)
 - Graph G_2 with vertices $\{v_1, v_3\}$ and no edges
 - Graph G_3 with vertices $\{v_1, v_2\}$ and edge (v_1, v_2)
2. Consider a graph G with 5 nodes and 7 edges. Can G be bipartite?