SYED WAJIH RIZVI

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EDUCATION

University of Waterloo | Mechanical Engineering & Computer Science | Overall GPA: 3.4

Summary: Software engineer with over 5 years of experience building scalable applications and performing automation testing.

SKILLS

Languages: Python, Javascript, Typescript, C#, HTML/CSS

Frameworks/Libraries: ASP.NET, Express, React, React-Native,
Tailwind, Nativewind, ThreeJS, GSAP

Databases: MySQL, T-SQL, MongoDB
Others: AWS, Git, Linux, Docker

RECENT EXPERIENCE

Ford Motor Company | Software Engineer

September 2023 - Present

- Developed over 900 automation test cases which covered EV architecture and settings for Ford's next generation vehicles
- Maintained a branch coverage of over 90% and a code coverage of over 95% on all product code
- Provided 100% rainy day coverage across all testing requirements ensuring each edge case was tested
- Reduced code duplication to under 2% across multiple components with nearly 100K total lines
- Tools: Python, Git, Jenkins, Linux, Powershell

Ford Motor Company | Software Engineer Intern

September 2022 - January 2023

- Optimized functional tests to reduce runtime by 28% for Jenkin's Nodes
- Developed CLI tools via **Python** to improve the analysis of log files by **44%**
- Improved testing speed by nearly 80% through delivery of Android based automation tests using Appium
- Tools: Python, Git, Appium, Selenium, Jenkins

Solace | Software Engineer Intern

September 2021 - January 2022

- Improved functional test speed by nearly 20% by converting API from XML based to JSON based which reduced payload size and optimized response parsing
- Tools: Python, Java, SVN

ADP Canada | Robotics Process Automation Consultant

April 2019 - September 2019

- Identified bottlenecks and automation opportunities in several Standard Operating Procedures that could reduce ADP'S cost of operations by nearly \$500,000
- Tools: Python, Excel, Blue Prim, Visio

RELEVANT PROJECTS

Rockstar Games Community Hub

- Built a full-stack application that supported **hundreds of users** to serve as a community hub for Rockstar Games players to share content, organize multiplayer sessions, and engage through likes, comments, and notifications
- Utilized Controllers, Dependency Injections and Routing to handle session tracking, mission history, and user participation
- Built **50+ API** endpoints using **ASP.NET** to manage posts, sessions, and user interactions
- Utilized secure authentication (OAuth, JWT) and request validation to protect user data
- Designed and optimized a MySQL database with several different schemas that handled thousands of records efficiently
- Tools: C#, ASP.NET Core, WebAPI, Shell, MySQL, React, Typescript

Gamecom | syed-rizvi-gamecom.netlify.app/ | github.com/syedwajihrizvi/GameCom

- Developed a full stack web application providing information on millions of video games
- Built RESTful API endpoints with Express.js, achieving 70% faster responses through CRUD operations
- Reduced network usage by over 90% by utilizing React Query to implement infinite queries and cache API responses
- Tools: React, Typescript, Express, MongoDB, Framer-Motion, Git, AWS

CScape | cscape.netlify.app/ | github.com/syedwajihrizvi/CScape

- Built a full stack web application that provides information on millions of cities worldwide
- Integrated Google Places API to fetch real time data on destinations, including restaurants, hotels, and amusement parks
- Leveraged the Weather API to display live weather data and 7-day forecasts for any city
- Used Google's Distance Matrix API for an optimized Traveling Salesman algorithm to plan efficient trips for users
- Tools: React, Typescript, Express, MongoDB, GSAP, Git

iPhone 16 Showcase | syed-rizvi-iphone-16.netlify.app/ | github.com/syedwajihrizvi/iPhone16

- Developed a launch site for the iPhone 16 which had beautiful carousels and interactive 3D models
- Implemented responsive components that rendered optimized images based on screen width
- Tools: React, Typescript, ThreeJS, GSAP, Git

Autonomous Omnidirectional Robot

- Engineered an omni-directional robot which utilized Lidar to navigate any path autonomously
- Tools: Raspberry Pi, Python, Linux. AutoCAD, Microsoft Excel