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import numpy as np
c1 tot = 0
c rand tot = 0
c min tot = 0
trials = 100000
coins = np.zeros((1000,10))
for k in range(trials):
   for i in range(1000):
       for j in range (10):
           result = np.random.rand(1)
           if (result[0] > 0.5): # heads
               coins[i][j] = 1
           else: # tails
               coins[i][j] = 0
   heads per coin = np.sum(coins, axis = 1)
   c1 tot += float(heads per coin[0]) / 10
   c rand tot += float(heads per coin[np.random.randint(1000)]) / 10
   c min tot += float(heads per coin[np.argmin(heads per coin)]) / 10
v1 = c1 tot / trials
v_rand = c_rand_tot / trials
v min = c min tot / trials
print "v1 " + str(v1) + " v rand " + str(v rand) + " v min " + str(v min)
import numpy as np
import random
import matplotlib.pyplot as plt
runs = 1000
d = 2
def prob5():
   error = 0
   points = 100
   for q in range(runs):
       xs = np.random.uniform(-1,1, (points, d))
       xs = np.c_[np.ones(points), xs]
       target points = np.random.uniform(-1,1, (2, d))
       ys = np.zeros(points)
       for i in range(len(xs)):
           det = (xs[i][1] - target points[0][0]) * (target points[1][1] -
target points[0][0])
           if det > 0:
               # on one side
               ys[i] = 1
           else:
               # on the other side
               ys[i] = -1
       processed = np.linalg.pinv(xs)
       weight = np.dot(processed, ys)
       # use weight to classify points
       newys = np.sign(np.dot(np.transpose(weight), np.transpose(xs)))
       for i in range(len(ys)):
           if (newys[i] != ys[i]):
               error += 1
   print float(error) / (runs * points)
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def prob6():
   error = 0
   points = 1000
   for q in range (runs):
       xs = np.random.uniform(-1,1, (points, d))
       xs = np.c [np.ones(points), xs]
       out sample = np.random.uniform(-1,1, (points, d))
       out sample = np.c [np.ones(points), out sample]
       target points = np.random.uniform(-1,1, (2, d))
       ys = np.zeros(points)
       for i in range(len(xs)):
           det = (xs[i][1] - target points[0][0]) * (target points[1][1] -
target points[0][0])
           if det > 0:
               # on one side
               ys[i] = 1
           else:
               # on the other side
               ys[i] = -1
       processed = np.linalg.pinv(xs)
       weight = np.dot(processed, ys)
       # use weight to classify points
       newys = np.sign(np.dot(np.transpose(weight), np.transpose(xs)))
       outys = np.sign(np.dot(np.transpose(weight), np.transpose(out sample)))
       for i in range(len(ys)):
           if (outys[i] != ys[i]):
               error += 1
   print float(error) / (runs * points)
def prob7():
   error = 0
   points = 10
   total iterations = 0
   for q in range(runs):
       xs = np.random.uniform(-1,1, (points, d))
       xs = np.c [np.ones(points), xs]
       target_points = np.random.uniform(-1,1, (2, d))
       ys = np.zeros(points)
       for i in range(len(xs)):
           det = (xs[i][1] - target points[0][0]) * (target points[1][1] -
target points[0][1]) - (xs[i][2] - target points[0][1]) * (target points[1][0] -
target points[0][0])
           if det > 0:
               # on one side
               ys[i] = 1
           else:
               # on the other side
               ys[i] = -1
       processed = np.linalg.pinv(xs)
       weight = np.dot(processed, ys)
       errors = points
       while (errors != 0):
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total iterations += 1
            i = np.random.randint(points)
            out = np.sign(np.dot(np.transpose(weight), np.transpose(xs)))
            if (np.array equal(out, ys)):
                break
            else.
                weight += xs[i]
            errors -= 1
    print float(total iterations) / runs
import numpy as np
import random
import matplotlib.pyplot as plt
runs = 1000
d = 2
def prob8 9 10():
    error = 0
    points = 1000
    for q in range(runs):
        xs = np.random.uniform(-1,1, (points, d))
        xs = np.c [np.ones(points), xs]
        out sample = np.random.uniform(-1,1, (points, d))
        out sample = np.c [np.ones(points), out sample]
        target points = np.random.uniform(-1,1, (2, d))
        ys = np.zeros(points)
        for i in range(len(xs)):
            det = (xs[i][1] - target points[0][0]) * (target points[1][1] -
target points[0][1]) - (xs[i][2] - target points[0][1]) * (target points[1][0] -
target points[0][0])
            if det > 0:
                # on one side
                ys[i] = 1
            else:
                # on the other side
                ys[i] = -1
        processed = np.linalg.pinv(xs)
        #weight = np.dot(processed, ys)
        weight = np.array([1, xs[0][0], xs[0][1]])
        weight2 = np.array([1, xs[0][0], xs[0][1], xs[0][0] * xs[0][1], xs[0][0] **
2, xs[0][1] ** 2])
        # use weight to classify points
        newys = np.sign(np.dot(np.transpose(weight), np.transpose(xs)))
        outys = np.sign(np.dot(np.transpose(weight), np.transpose(out sample)))
        noises = np.random.choice(range(points), points / 10, replace = False)
        for noise in noises:
            ys[noise] *= -1
        for i in range(len(ys)):
            if (outys[i] != ys[i]):
                error += 1
    print float(error) / (runs * points)
    print weight2
```