

$$u_L(x,t) = d_L f(x - c_L t)$$

$$F_0 \frac{\partial^2 u}{\partial x^2} - M \frac{\partial^2 u}{\partial t^2} = 0 = F_0 \frac{\partial^2 u}{\partial (x - c_L t)^2} \frac{\partial (x - c_L t)^2}{\partial x^2} - M \frac{\partial^2 u}{\partial (x - c_L t)^2} \frac{\partial (x - c_L t)^2}{\partial t^2}$$

$$F_0 - d_L M c_L^2 = 0$$

$$\Leftrightarrow c_L = \sqrt{\frac{F_0}{d_L M}}$$

c)  $u$  muss stetig (und 2mal diff'bar) sein. ✓

$\frac{\partial u}{\partial x}$  muss stetig (und diff'bar) sein. ✓

d)  $d_L = -c_L^2 M^{-1} E$  ?

$$u_R(x,t) = d_R f(-x - c_R t)$$

$$F_0 \frac{\partial^2 u}{\partial (-x - c_R t)^2} \frac{\partial (-x - c_R t)^2}{\partial x^2} + M d_R \frac{\partial^2 u}{\partial (-x - c_R t)^2} \frac{\partial (-x - c_R t)^2}{\partial t^2}$$

$$F_0 + M d_R c_R^2 = 0 \Leftrightarrow d_R = -F c_R^2 M^{-1}$$

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