

UCL, CASA
2024

Utilising IoT Sensors to Understand the Environmental Performance of NHS Eye Clinics

Yaman Kalaji & Duncan Wilson

Content

- 1. Context**
- 2. Device design**
- 3. Data infrastructure**
- 4. Initial results**
- 5. Challenges**

1

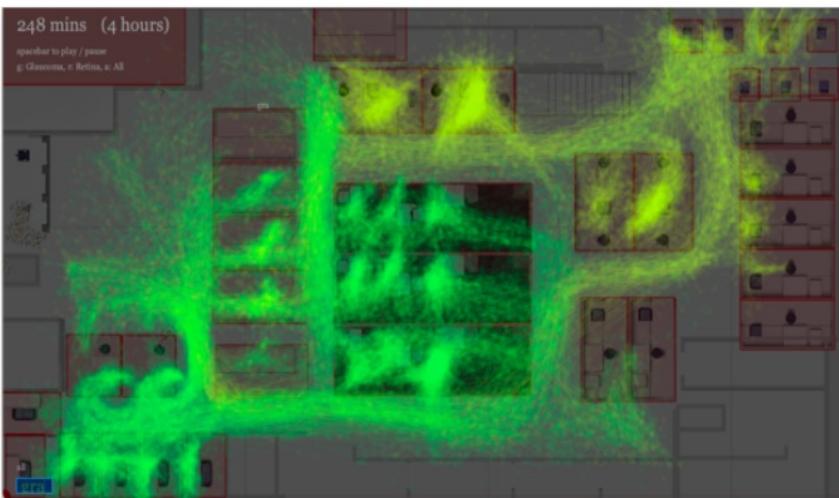
Context



Brent Cross,
London



Phase 1: Tracking patients



- On behalf of The HERCULES Consortium
- Funded by the NIHR Biomedical Research Centre at Moorfields Eye Hospital

(Now) Phase 2: Environmental monitoring



20

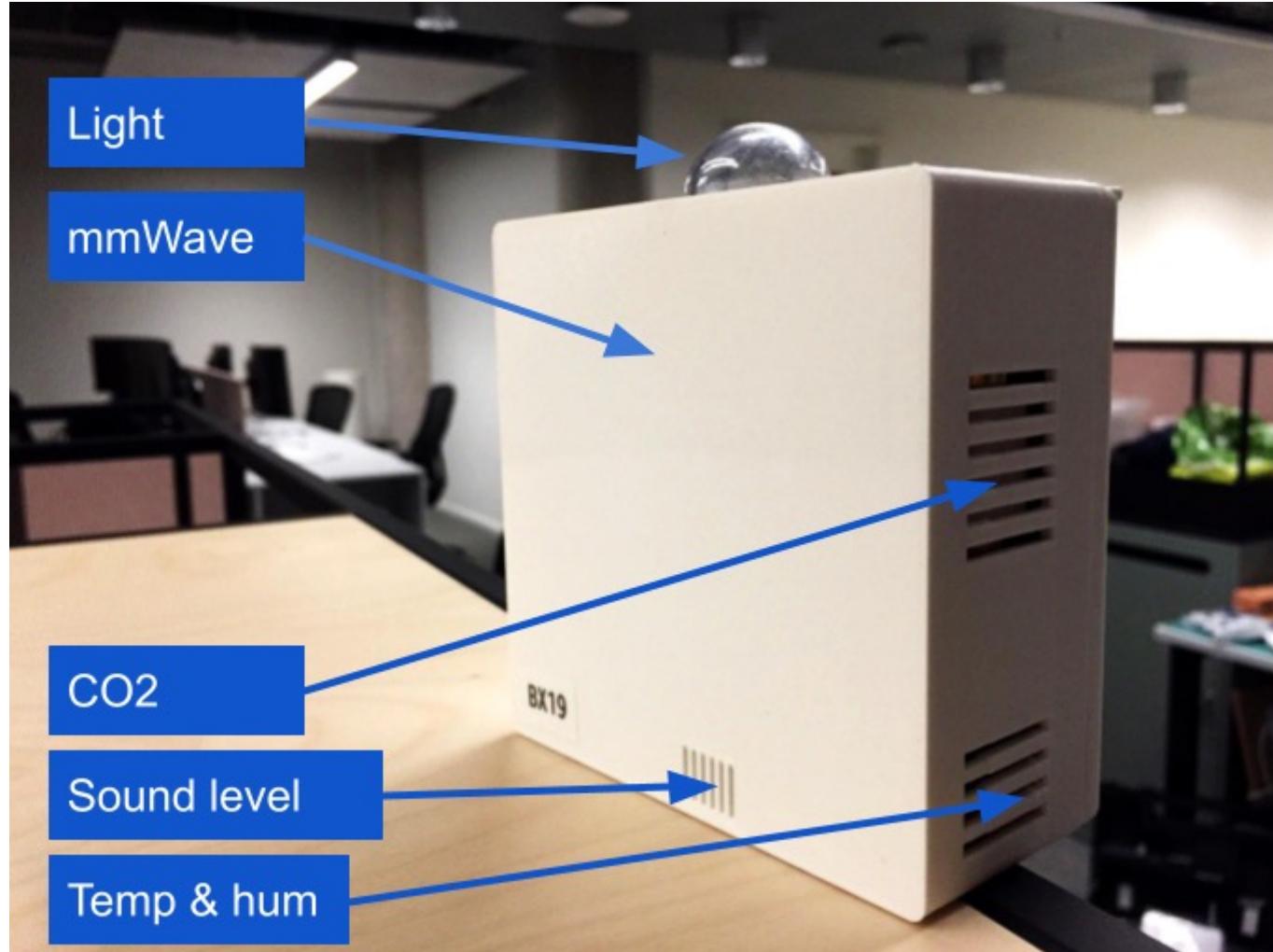
Deployed Sensors

Wi-Fi connected
~50% Ceiling mounted
~50% Wall mounted

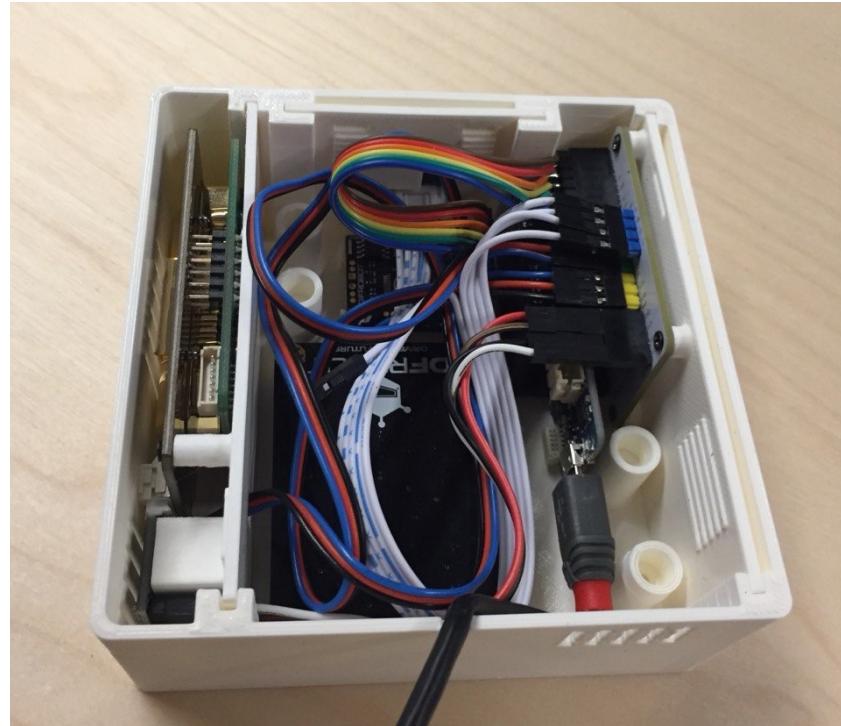
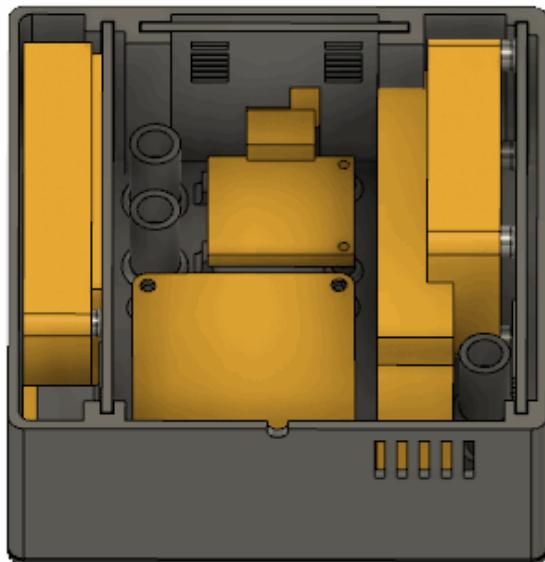


2

Device Design

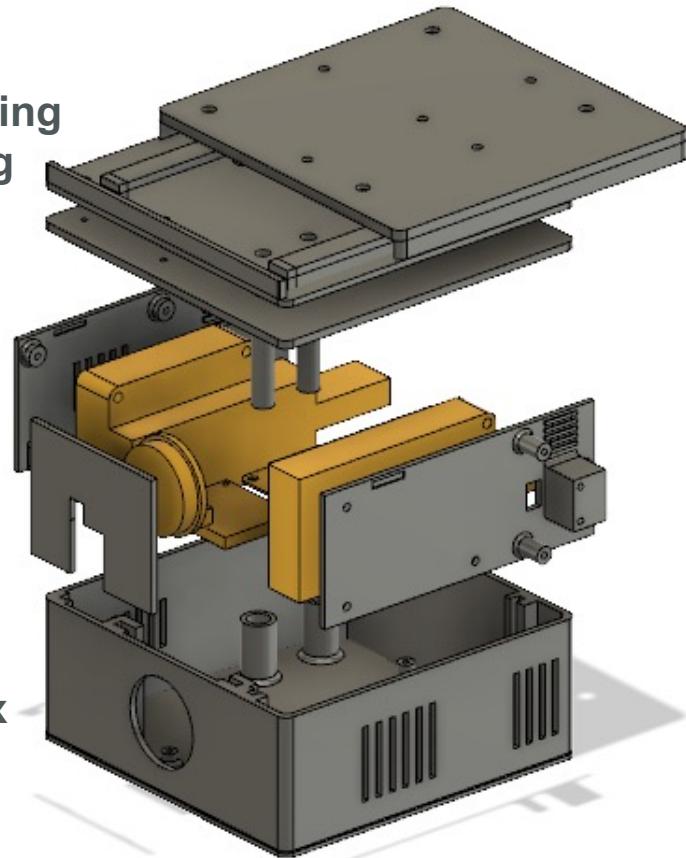


Internal sensor positioning



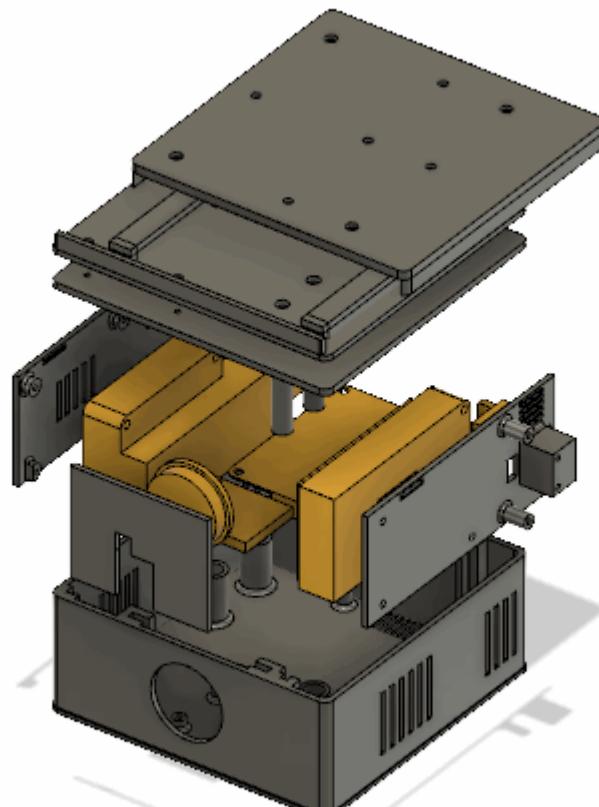
- Based on Arduino MKR Wifi 1010
- Custom PCB

Wall/Ceiling
mounting

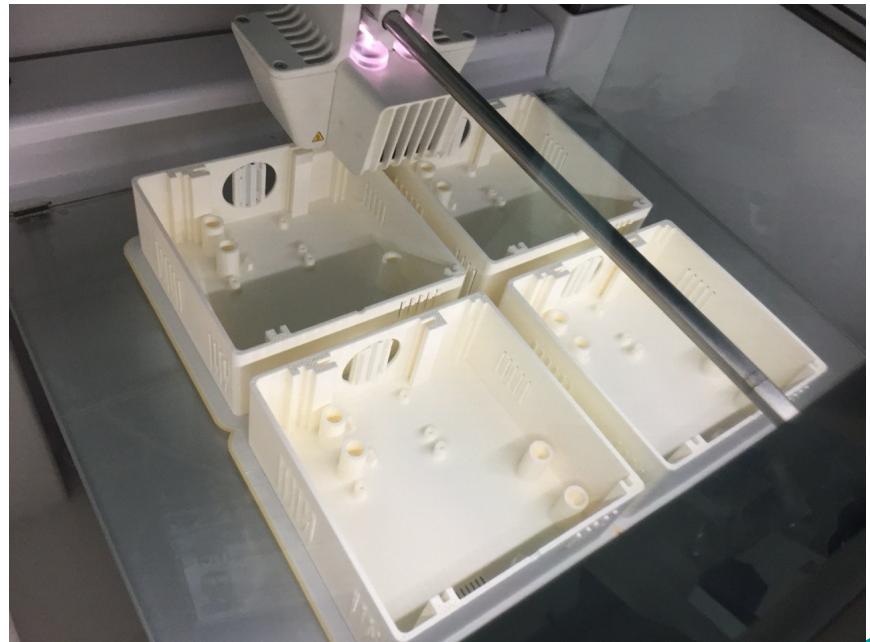


Sensor
holders

Main box



3D Designed Using Fusion360



3D Printed & assembled at UCL East



Ceiling and wall mounting



COACH after assembly and deployment

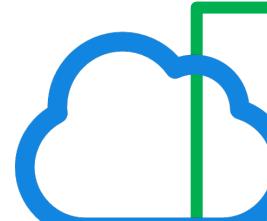
3

Data Infrastructure

Infrastructure



Wi-Fi



Internet

MQTT
Broker



influxdb

MQTT

Self-hosted Infrastructure

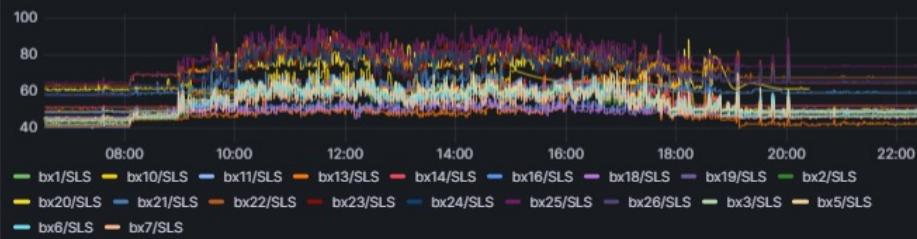


Grafana



bx1	bx2	bx3	bx5	bx6
Now	Now	Now	Now	Now
bx7	bx10	bx11	bx13	bx14
Now	Now	Now	Now	Now
bx16	bx18	bx19	bx20	bx21
Now	Now	Now	249.4 hrs	Now
bx22	bx23	bx24	bx25	bx26
67.1 hrs	190.1 hrs	Now	Now	Now

Sound level dBA



Light Lux



Grafana dashboard



4

Initial results

Usage per minute

bx1

83.1



bx10

215



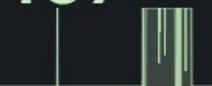
bx11

8.90



bx13

157



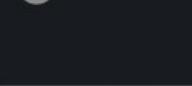
bx14

42



bx16

0



bx18

0.600



bx19

0.800



bx2

15.2



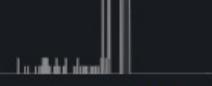
bx20

48.0



bx21

46.0



bx22

342



bx23

277



bx24

134



bx25

344



bx26

11.0



bx3

335



bx5

386



bx6

121

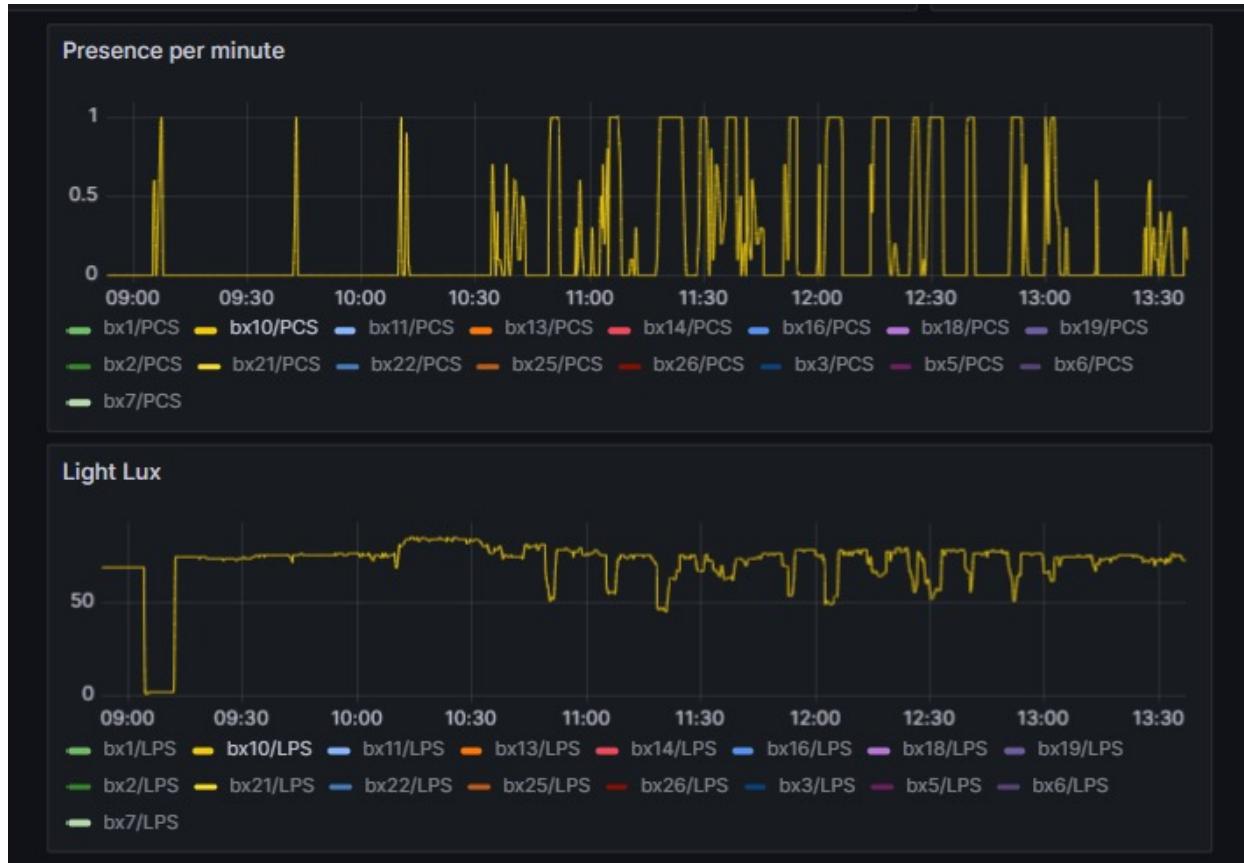


bx7

80.0



Cubicles usage in minutes



Examination time

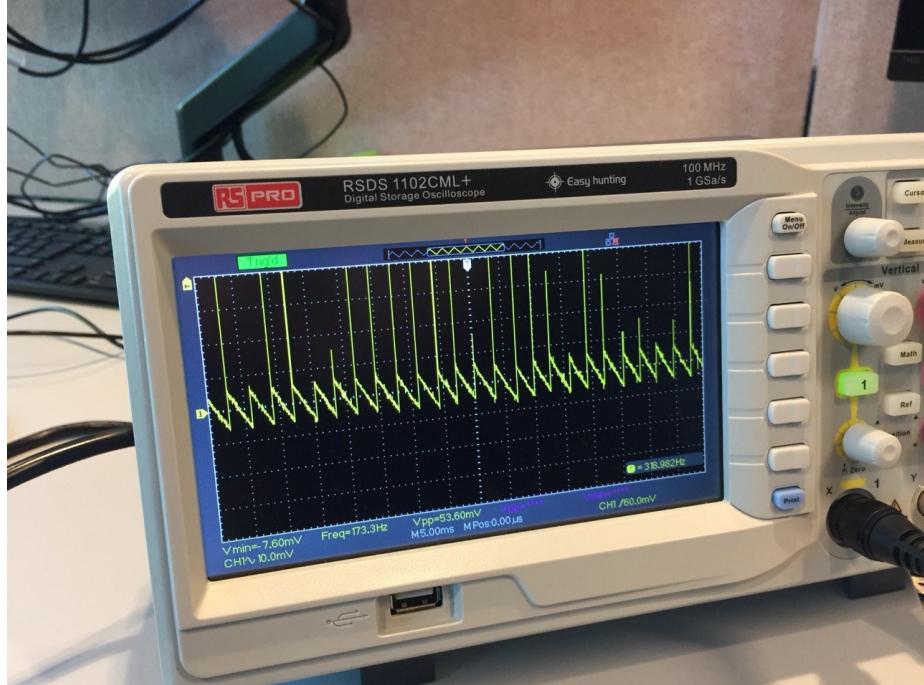
Sound levels



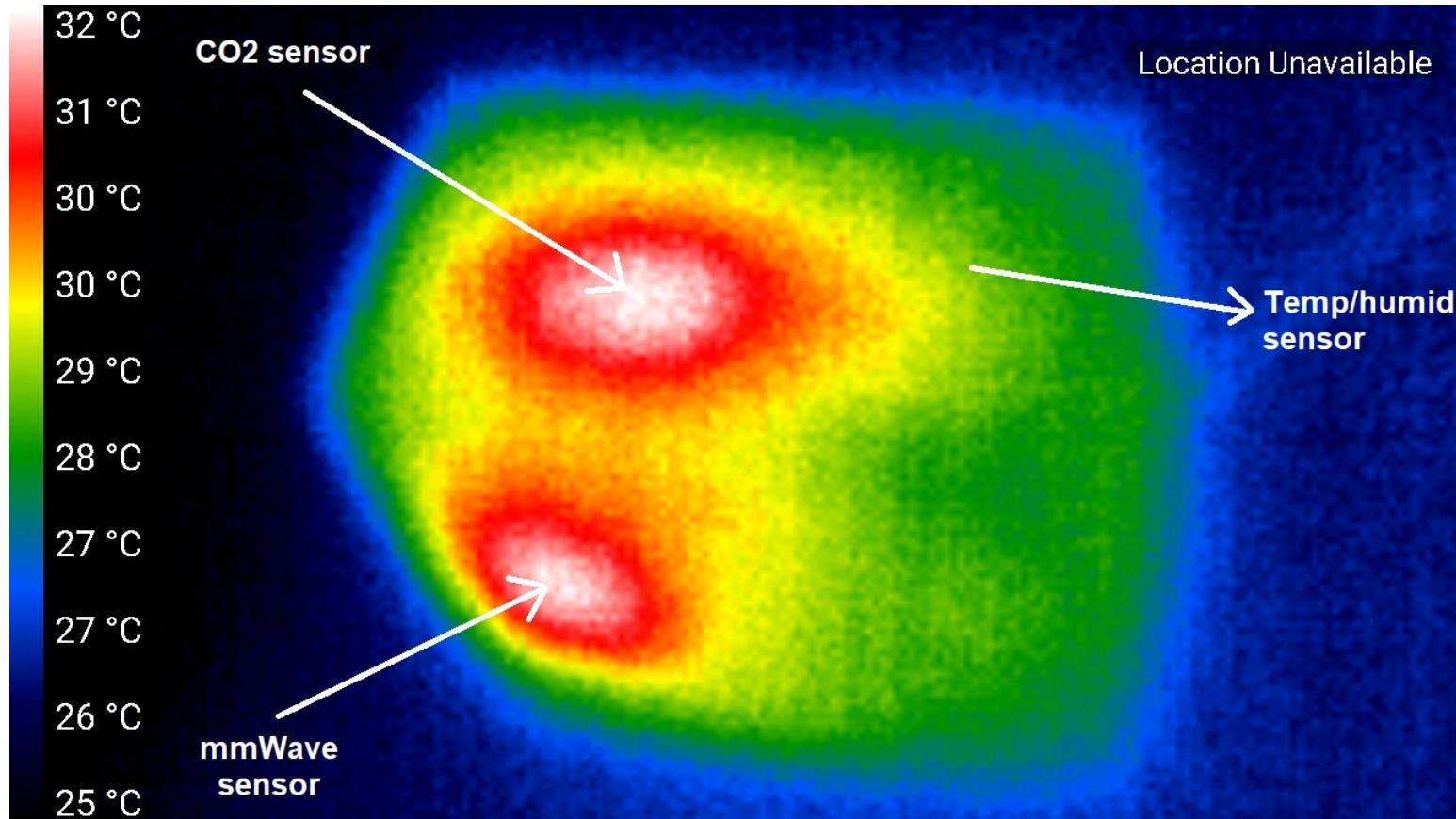
Sound average during workday

5

Challenges



Sensitivity to power quality



Thermal management



CO2 sensors calibration

Thank you for listening

List of used sensors:

- Gravity: Analog Sound Level Meter (SEN0232)
- DFROBOT: Ambient Light Sensor (0-200klx)
- HDC1080 Humidity and Temperature sensor
- DFROBOT: mmWave Radar (SEN0395)
- Gravity: Analog Infrared CO2 Sensor (0~5000 ppm)