

1 K-means algorithm

Let $n \geq 1$ and X_1, \dots, X_n in \mathbb{R}^d . The K -means algorithm aims at minimizing over all partitions $G = (G_1, \dots, G_K)$ of $\{1, \dots, p\}$ the criterion

$$\mathcal{L}(G) = \sum_{k=1}^K \sum_{i \in G_k} \|X_i - \bar{X}_{G_k}\|^2 \quad \text{with} \quad \bar{X}_{G_k} = \frac{1}{|G_k|} \sum_{a \in G_k} X_a.$$

1. Prove that

$$\mathcal{L}(G) = \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} \langle X_a, X_a - X_b \rangle = \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} \|X_a - X_b\|^2.$$

By definition,

$$\begin{aligned} \mathcal{L}(G) &= \sum_{k=1}^K \sum_{a \in G_k} \|X_a - \bar{X}_{G_k}\|^2 \\ &= \sum_{k=1}^K \sum_{a \in G_k} \langle X_a - \frac{1}{|G_k|} \sum_{b \in G_k} X_b, X_a - \frac{1}{|G_k|} \sum_{c \in G_k} X_c \rangle \\ &= \sum_{k=1}^K \frac{1}{|G_k|^2} \sum_{a,b,c \in G_k} \langle X_a - X_b, X_a - X_c \rangle \\ &= \sum_{k=1}^K \frac{1}{|G_k|^2} \sum_{a,b,c \in G_k} \langle X_a - X_b, X_a \rangle - \sum_{k=1}^K \frac{1}{|G_k|^2} \sum_{a,b,c \in G_k} \langle X_a - X_b, X_c \rangle, \end{aligned}$$

where

$$\sum_{a,b,c \in G_k} \langle X_a - X_b, X_c \rangle = |G_k| \sum_{a,c \in G_k} \langle X_a, X_c \rangle - |G_k| \sum_{b,c \in G_k} \langle X_b, X_c \rangle = 0.$$

Thus,

$$\mathcal{L}(G) = \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} \langle X_a, X_a - X_b \rangle.$$

For the second equality, note that

$$\begin{aligned} \mathcal{L}(G) &= \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} \langle X_a - X_b, X_a - X_b \rangle + \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} \langle X_b, X_a - X_b \rangle \\ &= \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} \|X_a - X_b\|^2 - \mathcal{L}(G), \end{aligned}$$

which concludes the proof.

2. Assume now that the observations are independent. Write $\mathbb{E}[X_a] = \mu_a \in \mathbb{R}^d$ so that $X_a = \mu_a + \varepsilon_a$ with $\varepsilon_1, \dots, \varepsilon_n$ centered and independent. Define $v_a = \text{trace}(\mathbb{V}[X_a])$. Prove that

$$\mathbb{E}[\mathcal{L}(G)] = \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} (\|\mu_a - \mu_b\|^2 + v_a + v_b) \mathbf{1}_{a \neq b}.$$

What is the value of $\mathbb{E}[\mathcal{L}(G)]$ when all the within-group variables have the same mean?

The expectation of $\mathcal{L}(G)$ is given by

$$\mathbb{E}[\mathcal{L}(G)] = \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} \mathbb{E}[\|X_a - X_b\|^2].$$

Let $a, b \in G_k, a \neq b$,

$$\begin{aligned} \mathbb{E}[\|X_a - X_b\|^2] &= \mathbb{E}[\|\mu_a - \mu_b + \varepsilon_a - \varepsilon_b\|^2] \\ &= \mathbb{E}[\|\mu_a - \mu_b\|^2] + \mathbb{E}[\|\varepsilon_a - \varepsilon_b\|^2] + 2\mathbb{E}[\langle \mu_a - \mu_b, \varepsilon_a - \varepsilon_b \rangle] \\ &= \|\mu_a - \mu_b\|^2 + \mathbb{E}[\|\varepsilon_a\|^2] + \mathbb{E}[\|\varepsilon_b\|^2] + 2\mathbb{E}[\langle \varepsilon_a, \varepsilon_b \rangle], \end{aligned}$$

since ε_a and ε_b are independent and centred. Finally, since for all $a \in G_k, \mathbb{E}[\|\varepsilon_a\|^2] = v_a$,

$$\mathbb{E}[\mathcal{L}(G)] = \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} (\|\mu_a - \mu_b\|^2 + v_a + v_b) \mathbf{1}_{a \neq b}.$$

If all the within-group variables have the same mean, for all k , there exists μ_k such that, for all $a \in G_k, \mu_a = \mu_k$. Therefore,

$$\begin{aligned} \mathbb{E}[\mathcal{L}(G)] &= \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} (v_a + v_b) \mathbf{1}_{a \neq b} \\ &= \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} (v_a + v_b) \mathbf{1}_{a \neq b}, \end{aligned}$$

where

$$\begin{aligned} \frac{1}{|G_k|} \sum_{a,b \in G_k} (v_a + v_b) \mathbf{1}_{a \neq b} &= \frac{1}{|G_k|} \left(\sum_{a,b \in G_k} (v_a + v_b) - \sum_{a,b \in G_k} (v_a + v_b) \mathbf{1}_{a=b} \right) \\ &= \frac{1}{|G_k|} \left(2|G_k| \sum_{a \in G_k} v_a - 2 \sum_{a \in G_k} v_a \right) \\ &= \frac{2(|G_k| - 1)}{|G_k|} \sum_{a \in G_k} v_a. \end{aligned}$$

Consequently, if, for all $a \in G_k, \mu_a = \mu_k$, we have

$$\mathbb{E}[\mathcal{L}(G)] = \sum_{k=1}^K \frac{|G_k| - 1}{|G_k|} \sum_{a \in G_k} v_a.$$

3. We assume now that there exists a partition $G^* = (G_1^*, \dots, G_K^*)$ such that there exist $m_1, \dots, m_K \in \mathbb{R}^d$ and $\gamma_1, \dots, \gamma_K > 0$ satisfying $\mu_a = m_k$ and $v_a = \gamma_k$ for all $a \in G_k^*$ and $k = 1, \dots, K$. Compute $\mathbb{E}[\mathcal{L}(G^*)]$.

By definition of G^* ,

$$\begin{aligned}\mathbb{E}[\mathcal{L}(G^*)] &= \sum_{k=1}^K \frac{|G_k^*| - 1}{|G_k^*|} \sum_{a \in G_k^*} v_a \\ &= \sum_{k=1}^K \frac{|G_k^*| - 1}{|G_k^*|} |G_k^*| \gamma_k \\ &= \sum_{k=1}^K (|G_k^*| - 1) \gamma_k.\end{aligned}$$

4. In the special case where there exists $\gamma > 0$ such that $v_i = \gamma$ for all $i \in \{1, \dots, n\}$, which partition $G = (G_1, \dots, G_K)$ minimizes $\mathbb{E}[\mathcal{L}(G)]$?

Assume that $v_a = \gamma$ for all a . Then, for any partition G ,

$$\begin{aligned}\mathbb{E}[\mathcal{L}(G)] &= \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} (\|\mu_a - \mu_b\|^2) + \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} (v_a + v_b) \mathbb{1}_{a \neq b} \\ &= \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} (\|\mu_a - \mu_b\|^2) + \sum_{k=1}^K \frac{|G_k| - 1}{|G_k|} \sum_{a \in G_k} \gamma \\ &= \frac{1}{2} \sum_{k=1}^K \frac{1}{|G_k|} \sum_{a,b \in G_k} (\|\mu_a - \mu_b\|^2) + \gamma(n - K) \\ &\geq \gamma(n - K).\end{aligned}$$

In particular, for G^* we have $\mathbb{E}[\mathcal{L}(G^*)] = \gamma(n - K)$. Therefore, the minimum of $\mathbb{E}[\mathcal{L}(G)]$ is reached at $G = G^*$. To prove that this minimum is unique when all μ_k are different, choose G such that $\mathbb{E}[\mathcal{L}(G)] = \mathbb{E}[\mathcal{L}(G^*)]$. Then, for all k , and for all $a, b \in G_k$, $\mu_a = \mu_b$ which implies that $G = G^*$.

2 EM algorithm (bonus)

In the case where we are interested in estimating unknown parameters $\theta \in \mathbb{R}^m$ characterizing a model with missing data, the Expectation Maximization (EM) algorithm (Dempster et al. 1977) can be used when the joint distribution of the missing data X and the observed data Y is explicit. For all $\theta \in \mathbb{R}^m$, let p_θ be the probability density function of (X, Y) when the model is parameterized by θ with respect to a given reference measure μ . The EM algorithm aims at computing iteratively an approximation of the maximum likelihood estimator which maximizes the observed data loglikelihood:

$$\ell(\theta; Y) = \log p_\theta(Y) = \log \int f_\theta(x, Y) \mu(dx).$$

As this quantity cannot be computed explicitly in general cases, the EM algorithm finds the maximum likelihood estimator by iteratively maximizing the expected complete data loglikelihood. Start with an initial value $\theta^{(0)}$ and let $\theta^{(t)}$ be the estimate at the t -th iteration for $t \geq 0$, then the next iteration of EM is decomposed into two steps.

1. **E step.** Compute the expectation of the complete data loglikelihood, with respect to the conditional distribution of the missing data given the observed data parameterized by $\theta^{(t)}$:

$$Q(\theta, \theta^{(t)}) = \mathbb{E}_{\theta^{(t)}} [\log p_\theta(X, Y) | Y].$$

2. **M step.** Determine $\theta^{(t+1)}$ by maximizing the function Q :

$$\theta^{(t+1)} \in \operatorname{argmax}_{\theta} Q(\theta, \theta^{(t)}).$$

1. Prove the following crucial property motivates the EM algorithm. For all $\theta, \theta^{(t)}$,

$$\ell(Y; \theta) - \ell(Y; \theta^{(t)}) \geq Q(\theta, \theta^{(t)}) - Q(\theta^{(t)}, \theta^{(t)}).$$

This may be proved by noting that

$$\ell(Y; \theta) = \log \left(\frac{p_{\theta}(X, Y)}{p_{\theta}(X|Y)} \right).$$

Considering the conditional expectation of both terms given Y when the parameter value is $\theta^{(t)}$ yields

$$\ell(Y; \theta) = Q(\theta, \theta^{(t)}) - \mathbb{E}_{\theta^{(t)}}[\log p_{\theta}(X|Y)|Y].$$

Then,

$$\ell(Y; \theta) - \ell(Y; \theta^{(t)}) = Q(\theta, \theta^{(t)}) - Q(\theta^{(t)}, \theta^{(t)}) + H(\theta, \theta^{(t)}) - H(\theta^{(t)}, \theta^{(t)}),$$

where

$$H(\theta, \theta^{(t)}) = -\mathbb{E}_{\theta^{(t)}}[\log p_{\theta}(X|Y)|Y].$$

The proof is completed by noting that

$$H(\theta, \theta^{(t)}) - H(\theta^{(t)}, \theta^{(t)}) \geq 0,$$

as this difference is a Kullback-Leibler divergence.

In the following, $X = (X_1, \dots, X_n)$ and $Y = (Y_1, \dots, Y_n)$ where $\{(X_i, Y_i)\}_{1 \leq i \leq n}$ are i.i.d. in $\{-1, 1\} \times \mathbb{R}^d$. For $k \in \{-1, 1\}$, write $\pi_k = \mathbb{P}(X_1 = k)$. Assume that, conditionally on the event $\{X_1 = k\}$, Y_1 has a Gaussian distribution with mean $\mu_k \in \mathbb{R}^d$ and covariance matrix $\Sigma \in \mathbb{R}^{d \times d}$. In this case, the parameter $\theta = (\pi_1, \mu_1, \mu_{-1}, \Sigma)$ belongs to the set $\Theta = [0, 1] \times \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^{d \times d}$.

1. Write the complete data loglikelihood.

The complete data loglikelihood is given by

$$\begin{aligned} \log p_{\theta}(X, Y) &= -\frac{nd}{2} \log(2\pi) + \sum_{i=1}^n \sum_{k \in \{-1, 1\}} \mathbb{1}_{X_i=k} \left(\log \pi_k - \frac{\log \det \Sigma}{2} - \frac{1}{2} (Y_i - \mu_k)^{\top} \Sigma^{-1} (Y_i - \mu_k) \right), \\ &= -\frac{nd}{2} \log(2\pi) - \frac{n}{2} \log \det \Sigma + \left(\sum_{i=1}^n \mathbb{1}_{X_i=1} \right) \log \pi_1 + \left(\sum_{i=1}^n \mathbb{1}_{X_i=-1} \right) \log(1 - \pi_1) \\ &\quad - \frac{1}{2} \sum_{i=1}^n \mathbb{1}_{X_i=1} (Y_i - \mu_1)^{\top} \Sigma^{-1} (Y_i - \mu_1) - \frac{1}{2} \sum_{i=1}^n \mathbb{1}_{X_i=-1} (Y_i - \mu_{-1})^{\top} \Sigma^{-1} (Y_i - \mu_{-1}). \end{aligned}$$

2. Let $\theta^{(t)}$ be the current parameter estimate. Compute $\theta \mapsto Q(\theta, \theta^{(t)})$.

Write $\omega_t^i = \mathbb{P}_{\theta^{(t)}}(X_i = 1|Y_i)$. The intermediate quantity of the EM algorithm is given by

$$\begin{aligned} Q(\theta, \theta^{(t)}) &= -\frac{nd}{2} \log(2\pi) - \frac{n}{2} \log \det \Sigma + \left(\sum_{i=1}^n \omega_t^i \right) \log \pi_1 + \sum_{i=1}^n (1 - \omega_t^i) \log(1 - \pi_1) \\ &\quad - \frac{1}{2} \sum_{i=1}^n \omega_t^i (Y_i - \mu_1)^{\top} \Sigma^{-1} (Y_i - \mu_1) - \frac{1}{2} \sum_{i=1}^n (1 - \omega_t^i) (Y_i - \mu_{-1})^{\top} \Sigma^{-1} (Y_i - \mu_{-1}). \end{aligned}$$

3. Compute $\theta^{(t+1)}$.

The gradient of $Q(\theta, \theta^{(t)})$ with respect to θ is therefore given by

$$\begin{aligned}\frac{\partial Q(\theta, \theta^{(t)})}{\partial \pi_1} &= \frac{\sum_{i=1}^n \omega_t^i}{\pi_1} - \frac{n - \sum_{i=1}^n \omega_t^i}{1 - \pi_1}, \\ \frac{\partial Q(\theta, \theta^{(t)})}{\partial \mu_1} &= \sum_{i=1}^n \omega_t^i (2\Sigma^{-1}Y_i - 2\Sigma^{-1}\mu_1), \\ \frac{\partial Q(\theta, \theta^{(t)})}{\partial \mu_{-1}} &= \sum_{i=1}^n (1 - \omega_t^i) (2\Sigma^{-1}Y_i - 2\Sigma^{-1}\mu_{-1}), \\ \frac{\partial Q(\theta, \theta^{(t)})}{\partial \Sigma^{-1}} &= \frac{n}{2}\Sigma - \frac{1}{2} \sum_{i=1}^n \omega_t^i (Y_i - \mu_1)(Y_i - \mu_1)^\top - \frac{1}{2} \sum_{i=1}^n (1 - \omega_t^i) (Y_i - \mu_{-1})(Y_i - \mu_{-1})^\top.\end{aligned}$$

Then, $\theta^{(t+1)}$ is defined as the only parameter such that all these equations are set to 0. It is given by

$$\begin{aligned}\hat{\pi}_1^{(t+1)} &= \frac{1}{n} \sum_{i=1}^n \omega_t^i, \\ \hat{\mu}_1^{(t+1)} &= \frac{1}{\sum_{i=1}^n \omega_t^i} \sum_{i=1}^n \omega_t^i Y_i, \\ \hat{\Sigma}^{(t+1)} &= \frac{1}{n} \sum_{i=1}^n \omega_t^i (Y_i - \mu_1)(Y_i - \mu_1)^\top + \frac{1}{n} \sum_{i=1}^n (1 - \omega_t^i) (Y_i - \mu_{-1})(Y_i - \mu_{-1})^\top.\end{aligned}$$