

Tutorial 4: Compilers, linkers and performance

Informatik elective: GPU Computing

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NVIDIA GPU architectures

Arch →	Tesla	Fermi	Kepler	Maxwell	Pascal	Volta	Turing	Ampere	Ada Lovelace	Hopper	Blackwell
Compute capability →	1.0	2.0	3.0	5.x	6.x	7.0	7.5	8.0	8.9	9.0	Blackwell
GPUs →					P100	V100		A100		H100	

New architectures → new features, more performance.

Summit
supercomputer
(ORNL, USA)

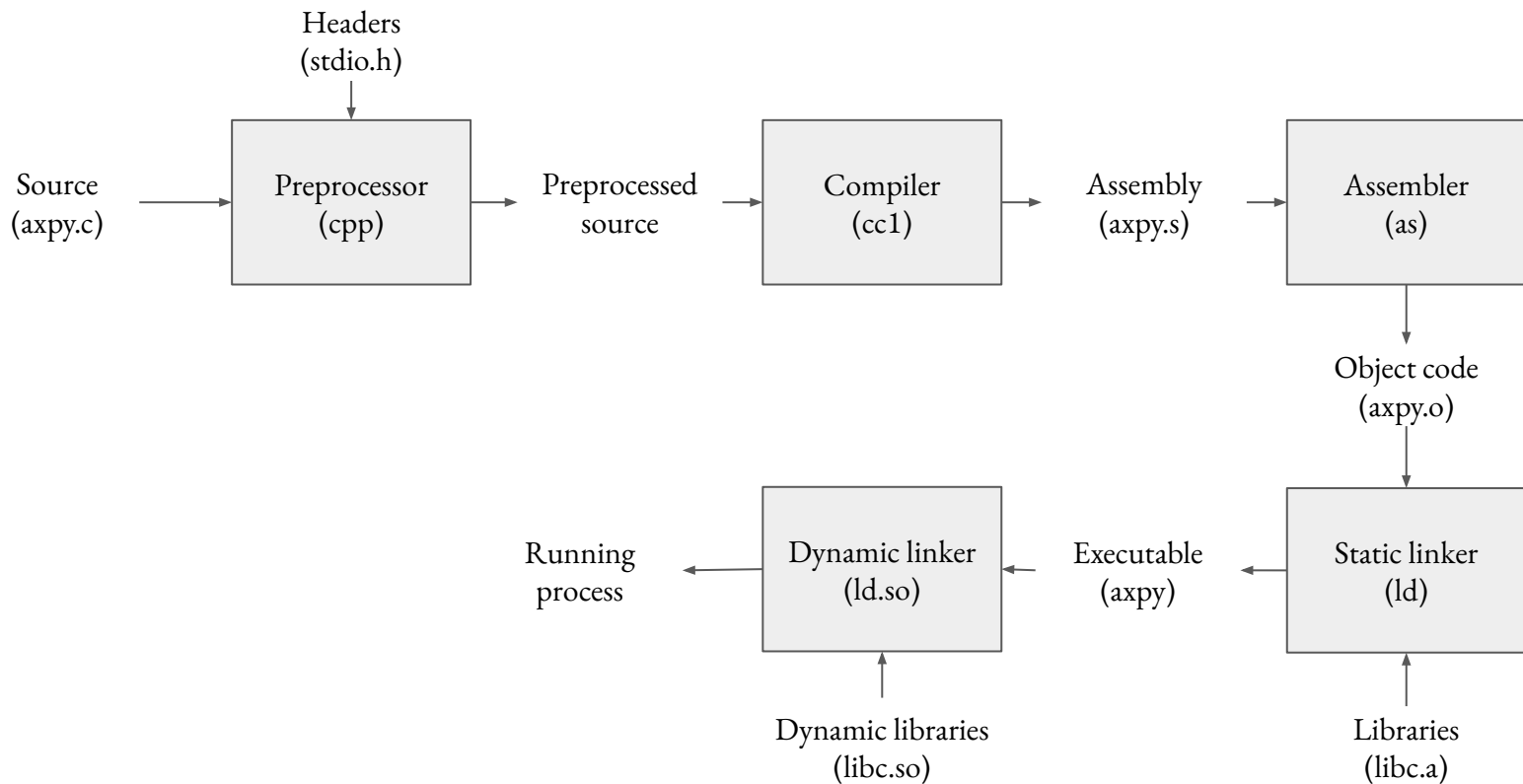
JUPITER
(Jülich, DE)

NVIDIA GPU architectures

Feature support (unlisted features are supported for all compute capabilities)	Compute capability (version)									
	1.0, 1.1	1.2, 1.3	2.x	3.0	3.2	3.5, 3.7, 5.x, 6.x, 7.0, 7.2	7.5	8.x	9.0	
Warp vote functions (<code>__all()</code> , <code>__any()</code>)	No	Yes								
Warp vote functions (<code>__ballot()</code>)	No		Yes							
Memory fence functions (<code>__threadfence_system()</code>)										
Synchronization functions (<code>__syncthreads_count()</code> , <code>__syncthreads_and()</code> , <code>__syncthreads_or()</code>)										
Surface functions										
3D grid of thread blocks										
Warp shuffle functions	No			Yes						
Unified memory programming	No			Yes						
Funnel shift	No			Yes						
Dynamic parallelism	No				Yes					
Uniform Datapath ^[57]	No							Yes		
Hardware-accelerated async-copy	No							Yes		
Hardware-accelerated <i>split arrive/wait barrier</i>										
Warp-level support for reduction ops										
L2 cache residency management										
DPX instructions for accelerated dynamic programming	No							Yes		
Distributed shared memory										
Thread block cluster										
Tensor memory accelerator (TMA) unit										
Feature support (unlisted features are supported for all compute capabilities)	1.0,1.1	1.2,1.3	2.x	3.0	3.2	3.5, 3.7, 5.x, 6.x, 7.0, 7.2	7.5	8.x	9.0	
	Compute capability (version)									

[Wikimedia: wikipedia.org/wiki/CUDA]

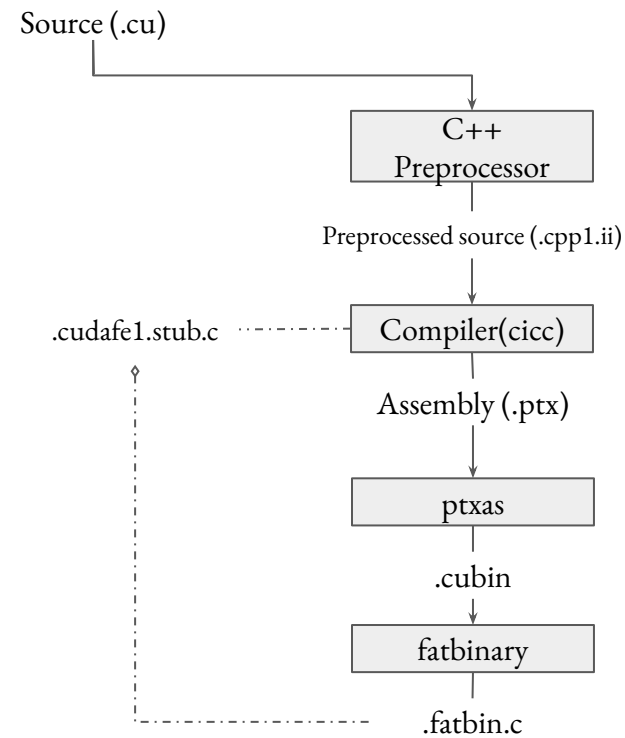
C build process




NVIDIA CUDA compilation process

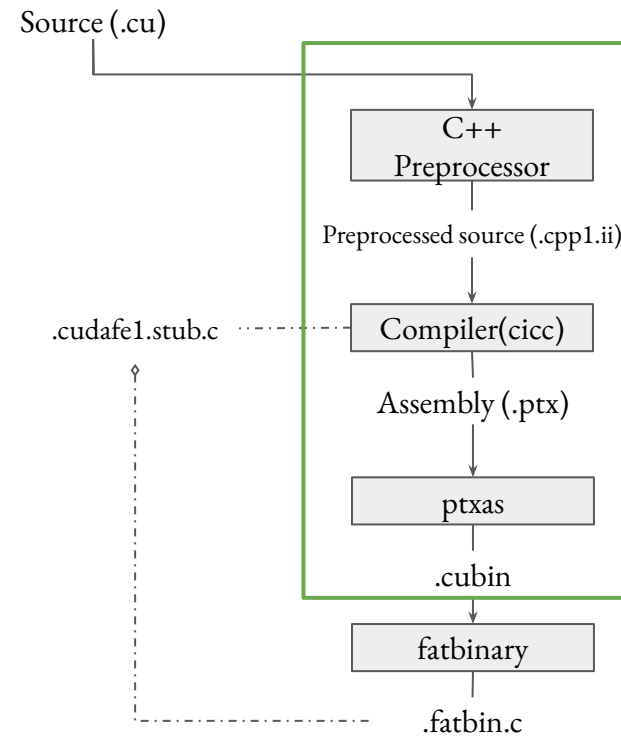
- NVIDIA CUDA compiler driver: `nvcc`
 - Performs the necessary steps to build a CUDA executable/library.
 - Includes compilation of both host code and device code.
- See <https://docs.nvidia.com/cuda/cuda-compiler-driver-nvcc/index.html> for documentation and more details.

CUDA build process




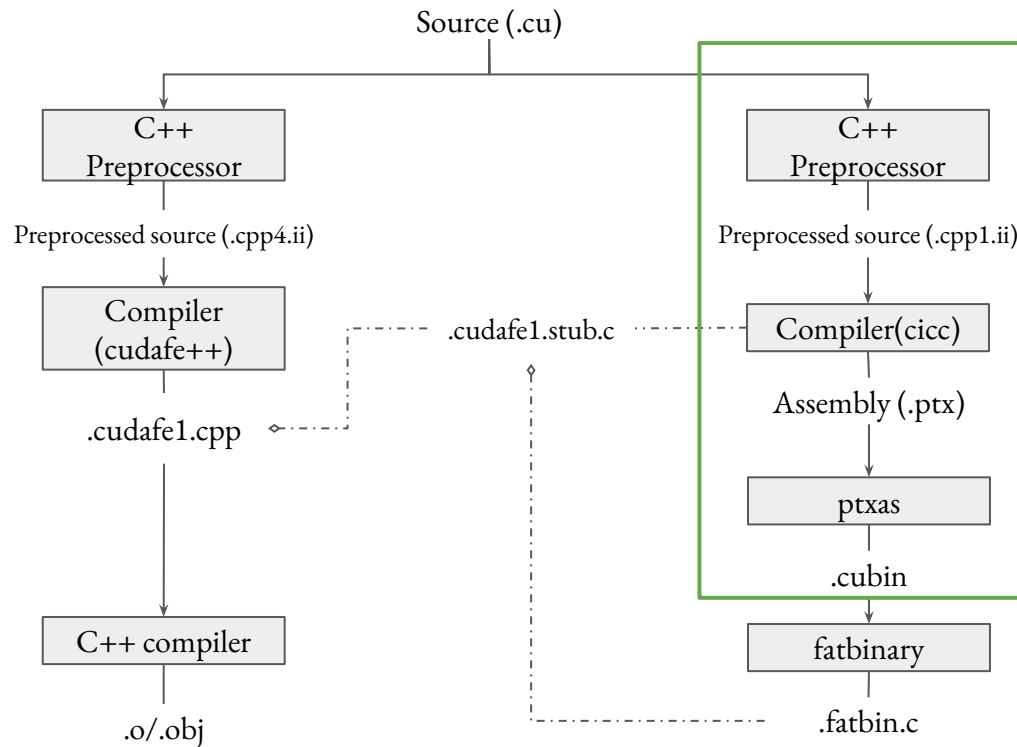
CUDA build process

- Repeat  for each architecture





CUDA build process

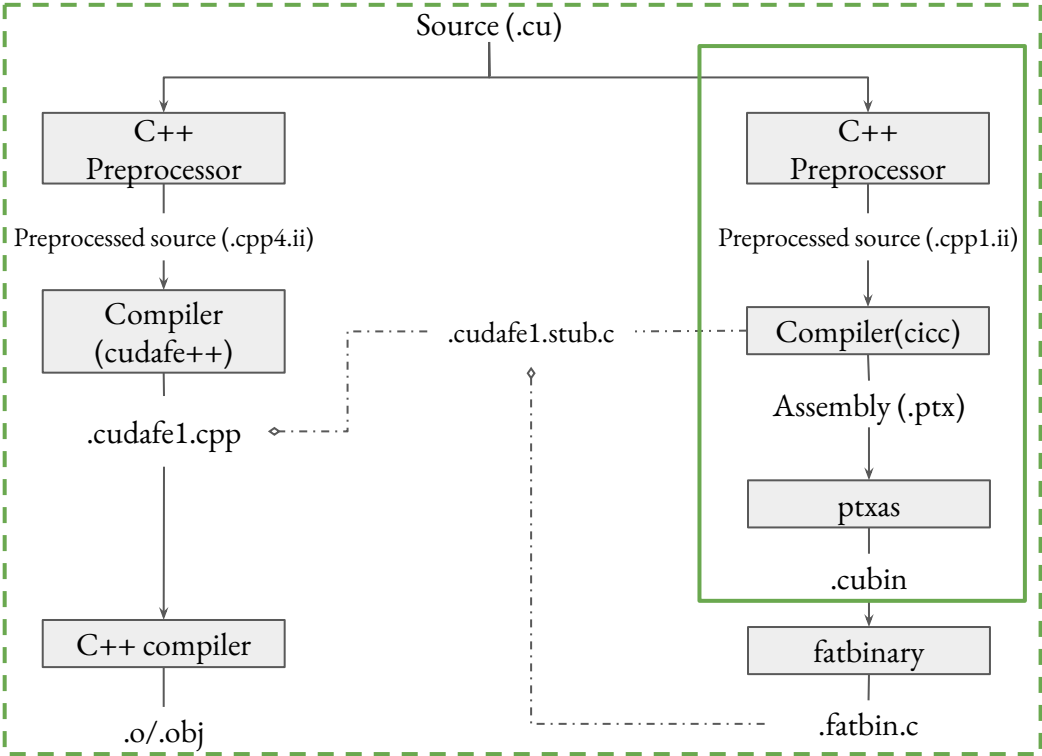
- Repeat  for each architecture





CUDA build process

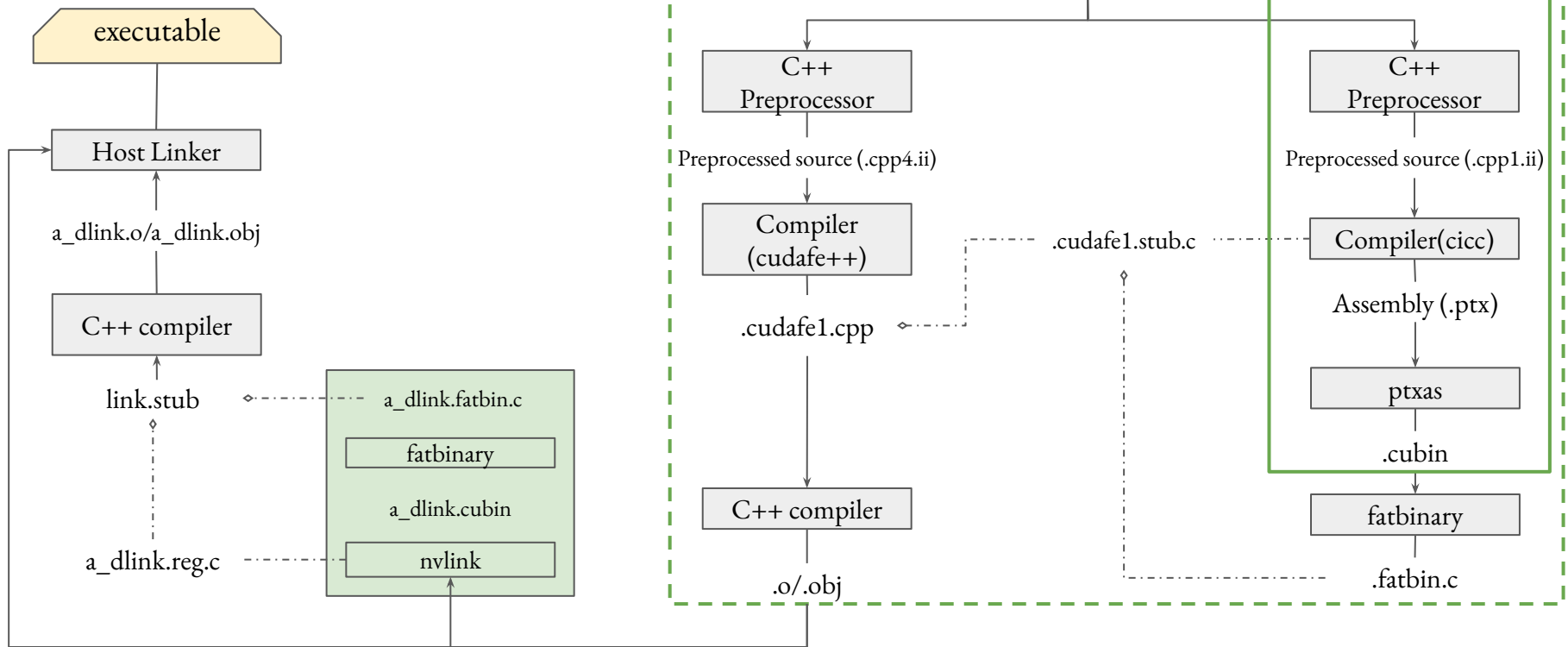


- Repeat  for each architecture
- Repeat  for each .cu file



CUDA build process

- Repeat  for each architecture
- Repeat  for each .cu file



Helpful tools (Linux)

- Dump assembly from object file:

```
objdump -d file.o
```

```
# See documentation: man objdump
```

- Look at available symbols in the object file

```
nm file.o
```

```
# See documentation: man nm
```

- Look at linked libraries (dependencies on other shared objects)

```
ldd executable
```

```
# See documentation: man ldd
```

Measuring performance (best practices)

- Compilation flags are appropriate: For example with all the required optimization flags and no debug flags.
- Eliminate noise by repeating measurement a few times and averaging the overall time.
- Ensure operation is complete (synchronize explicitly if necessary).
- Ensure clock used is steady and cannot be arbitrarily updated (system_clock v/s steady_clock).
- Ensure operation is actually being performed (not skipped due to predication, or due to some clause).
- Try to eliminate common sources of interference: other users, some unrelated I/O, system effects.

Highly recommended read: <https://blogs.fau.de/hager/archives/category/fooling-the-masses>