

Lecture 7: CUDA Streams and dynamic parallelism

Informatik elective: GPU Computing

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In this session

- Asynchronous programming with CUDA streams
- Dynamic parallelism in CUDA



What is a kernel?

- An C++ extension provided by CUDA to define functions that are executed N times in parallel by N different CUDA threads.
 - Defined with a __global__ specifier.
 - The launch configuration (number of threads and organization) defined by <<< . . . >>> has to be specified.
 - The executing thread is given a unique thread ID, accessible within the kernel call.
 - Cannot be a class member and must have return type Void
 - Call to a __global__ function is asynchronous. The return back to the caller is immediate,
 before the device execution has completed.



Function specifiers in CUDA C++

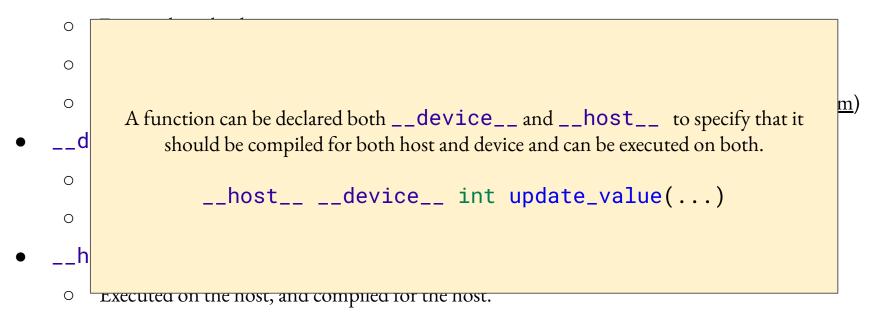
- __global__: Declaration of a function as a kernel.
 - Executed on the device
 - Callable from the host
 - Also callable from the device for CC > 5.0 (Kernels from within kernels: <u>Dynamic parallelism</u>)
- __device__: Declaration of a device function.
 - Executed on the device, and compiled for the device.
 - Callable ONLY from the device.
- __host__: Declaration of a host function.
 - Executed on the host, and compiled for the host.
 - Callable ONLY from the host.





Function specifiers in CUDA C++

• __global__: Declaration of a function as a kernel.



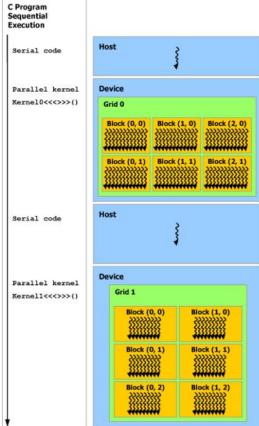
• Callable ONLY from the host.





Kernel execution on device

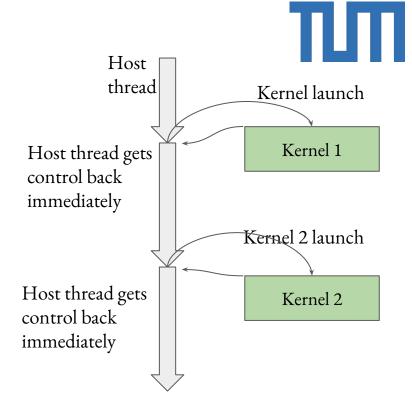
- When running a single-threaded CPU program, two different kernels can be interleaved with host code.
- As the device kernel launches are asynchronous with respect to host, host and device code can run concurrently.
- By default, device kernels launched one after the other will be serialized on the <u>default CUDA</u>
 <u>"stream"</u>





Asynchronous execution

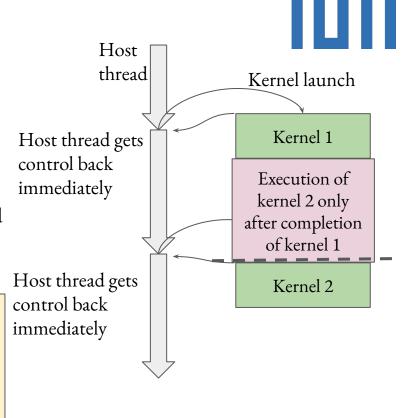
• The kernel launches are always asynchronous with respect to the host.



Asynchronous execution

- The kernel launches are always asynchronous with respect to the host.
- By default two subsequently launched kernels are serialized on the default stream

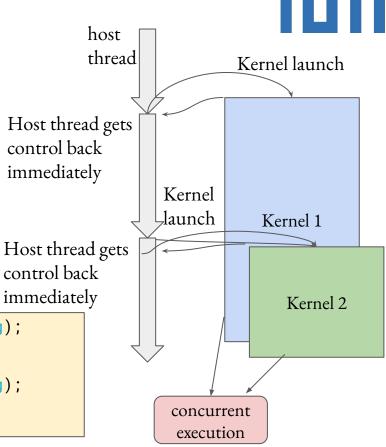
```
kernel<<<grid, block, shmem, stream>>>(...)
// By default, stream is NULL.
kernel<<<grid, block, shmem>>>(...)
```



Asynchronous execution

- This is inefficient if Kernel 1 and Kernel 2 have no data-dependencies.
- CUDA allows you to launch two independent kernels on two different streams, enabling concurrent GPU execution.

```
cudaStreamCreateWithFlags(&stream1, cudaStreamNonblocking);
kernel1<<<..., stream1>>>(...);
cudaStreamCreateWithFlags(&stream2, cudaStreamNonblocking);
kernel2<<<..., stream2>>>(...)
```





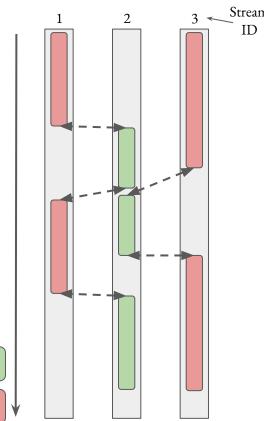
Stream API: basics

- Need to create and destroy required streams.
- On host, you can explicitly synchronize two streams.
- A cudaDeviceSynchronize() synchronizes all streams on device.



Stream behaviour

- You can think of streams as independent "execution pipelines" with some workload in them.
- They <u>may</u> be executed concurrently on the GPU, but are not guaranteed to.
- The runtime makes the scheduling decisions based on the available resources.
- Workloads mapped to one stream always run in sequence.
- Explicit synchronization necessary to exchange data between parallel workload in different streams.



Compute

workload Memory workload



Better control with Events

- As order of execution of workloads between different streams is unspecified, explicitly managing dependencies with synchronizations can be difficult.
- CUDA provides Event API to map specific operations to events called CUDA Events



Managing events on streams

- Just creating an event is not sufficient. You need to map an event to the stream. You can then synchronize and query at the event-level.
- Events are designed to be light-weight, so the overhead of creation, recording and querying should be low.
- Finer time measurement is possible with events \rightarrow using GPU clock \rightarrow independent of OS





Asynchronous memory operations

```
cudaMemcpyAsync(dest, src, byte_count, kind, stream) // __host__ and __device__
dest: destination memory address
src: source memory address
byte_count: Number of bytes to copy
kind: cudaMemcpyHostToDevice/ DeviceToHost etc, specifies direction of copy.
stream: The stream to associate the copy operation with
```

- Similar to kernel launches, you can assign a stream to memory copies.
- Enables overlap of computation and memory operations in different streams.
- Semantics same as before: In single streams, operations are executed in-order; in different streams order of operation is not guaranteed without explicit synchronizations.



Stream-ordered memory allocator

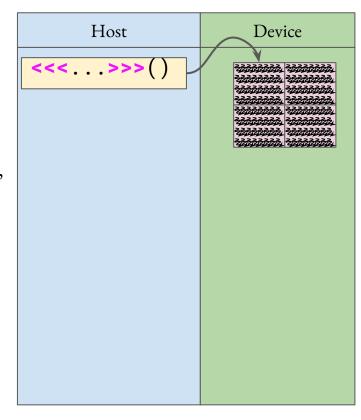
```
cudaMallocAsync(ptr, stream); // Allocates memory with stream ordered semantics
cudaFreeAsync(ptr, stream); // Frees memory with stream ordered semantics
```

- cudaMalloc and cudaFree implicitly synchronize the device, which is necessary due to page management.
- CUDA provides stream-order allocator to allocate and free memory on streams, to remove the necessity for the implicit synchronization.
- The user is responsible for using the memory only in the promised stream order, otherwise the behaviour is undefined.



Dynamic parallelism in CUDA

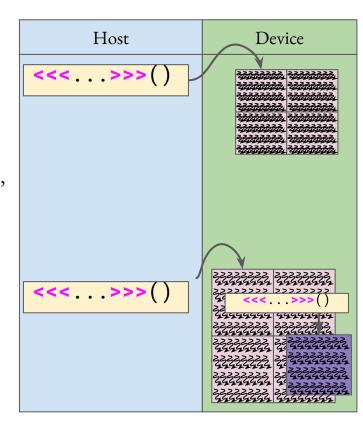
- Till now we looked at how we can launch one kernel from the host with the <<<...>>() syntax.
- Works well for algorithms with a flat, single-level of parallelism
- For implementations with recursion or irregular loop structure, these needed to be modified/control needed to be returned to host etc.





Dynamic parallelism in CUDA

- Till now we looked at how we can launch one kernel from the host with the <<<...>>() syntax.
- Works well for algorithms with a flat, single-level of parallelism
- For implementations with recursion or irregular loop structure, these needed to be modified/control needed to be returned to host etc.
- With dynamic parallelism, you can launch kernels from inside kernels.

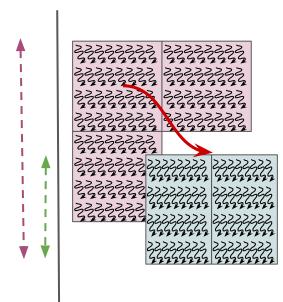






Some terminology

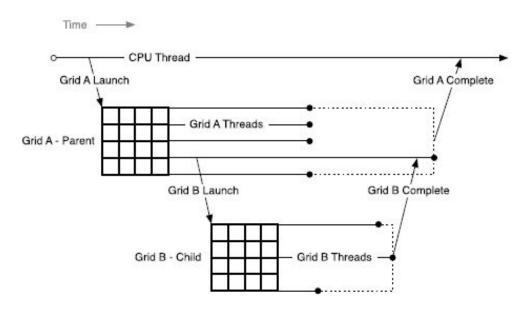
- Grid: A collection of threads which execute a kernel
- Thread block: A group of threads that execute on the same multiprocessor (SM).
- <u>Kernel:</u> An function that executes on the device with the CUDA execution and memory model for <u>every thread in the grid</u>
- <u>Parent:</u> A grid/thread-block/thread that has launched new grid(s) called child grid(s). It does not complete until all its children have also finished.
- <u>Child:</u> A grid/thread-block/thread which has been launched by a parent. It has to complete before its parent is considered to be completed.







Nested launches



Runtime guarantees implicit synchronization between parent and child grid





Launch syntax and behaviour

```
kernel_name<<< grid_size, block_size, sm_bytes, stream >>>([kernel arguments]);
```

- Device-side kernel launch syntax is the same standard host-kernel launch syntax.
- Similar to host-launches, device-kernel launches are also asynchronous wrt the launching thread. That is, <>>>> () call returns immediately, and the launching thread continues to execute.
- Any configuration setup (L1 cache, shared memory etc) will be inherited from the parent grid.





Stream behaviour

```
kernel_name<<< grid_size, block_size, sm_bytes, stream >>>([kernel arguments]);
```

- stream has to be created in the same grid that the kernel is being launched from.
- The NULL stream has different behaviour → It does not insert an implicit dependency.
- Named streams (not NULL) have to be created with ... CreateWithFlags() with the cudaStreamNonBlocking flag.



Tail launch

- As cudaDeviceSynchronize() is too restrictive for device kernel launches, a specific named stream is available: cudaStreamTailLaunch, providing the same functionality.
 - Each grid has its own tail launch stream, enabling automatic ordering of subsequent kernel launches with proper implicit synchronization.

```
// In this example, C2 will only launch after C1 completes.
__global__ void P( ... ) {
   C1<<< ... , cudaStreamTailLaunch >>>( ... );
   C2<<< ... , cudaStreamTailLaunch >>>( ... );
}
```



Fire and forget

- In many cases, you don't care about the dependencies (example for some independent task).
- CUDA provides a fire-and-forget named stream for this purpose: cudaStreamFireAndForget
- No need to create a new stream per launch.
- No stream-tracking overhead.
- Will implicitly synchronize with a tail launch stream

```
// In this example, C2's launch will not wait for C1's completion
__global__ void P( ... ) {
   C1<<< ... , cudaStreamFireAndForget >>>( ... );
   C2<<< ... , cudaStreamFireAndForget >>>( ... );
}
```



Event support

- For device-kernel launches, events are supported, but restricted.
- cudaStreamWaitEvent() is supported, but event synchronization and timings are not supported.
- Events must be created with the cudaEventDisableTiming flag.



Summary

- CUDA streams and events: Enabling asynchronous computatations
- CUDA dynamic parallelism: Enabling better expression for more complex programs



Next lecture

• No lecture next week due to Dies Academicus

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