# Developing Linux with Buildroot

MA35 SoC Series

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#### Setting up build environment

Install Ubuntu 22.04.4 LTS 64-bit Desktop

Browse <a href="https://releases.ubuntu.com/jammy">https://releases.ubuntu.com/jammy</a> to fetch the latest Ubuntu 22.04, or directly download the ISO image <a href="https://releases.ubuntu.com/jammy/ubuntu-22.04.4-desktop-amd64.iso">https://releases.ubuntu.com/jammy/ubuntu-22.04.4-desktop-amd64.iso</a> (link maybe broken or outdated).

- Update and install the essential APT packages
  - \$ sudo apt update
  - \$ sudo apt install git build-essential libncurses-dev automake



#### Fetching source code

- Fetch Buildroot for MA35 series \$ until git clone https://github.com/OpenNuvoton/MA35D1\_Buildroot.git ma35xx-buildroot; do echo "retry"; done
- Create a workspace in the root directory of Buildroot
   \$ cd \${BR2\_DIR}; mkdir -p workspace
   Note: \${BR2\_DIR} denotes the root directory of Buildroot 'ma35xx-buildroot'.
- Fetch Linux into workspace/linux-5.10 \$ until git clone <a href="https://github.com/OpenNuvoton/MA35D1\_linux-5.10.y.git">https://github.com/OpenNuvoton/MA35D1\_linux-5.10.y.git</a> workspace/linux-5.10; do echo "retry"; done
- Fetch U-Boot into workspace/uboot-2020.07 \$ until git clone https://github.com/OpenNuvoton/MA35D1\_u-boot-v2020.07.git workspace/uboot-2020.07; do echo "retry"; done
- Fetch TF-A into workspace/tfa-2.3 \$ until git clone https://github.com/OpenNuvoton/MA35D1\_arm-trusted-firmware-v2.3.git workspace/tfa-2.3; do echo "retry"; done
- Fetch optee-os into workspace/optee-os-3.9.0 \$until git clone https://github.com/OpenNuvoton/MA35D1\_optee\_os-v3.9.0.git workspace/optee-os-3.9.0; do echo "retry"; done



#### Overriding source directories

- Fetch *local.mk* from link <a href="https://raw.githubusercontent.com/symfund/ma35d1-portal/master/mk/local.mk">https://raw.githubusercontent.com/symfund/ma35d1-portal/master/mk/local.mk</a> into the root directory of Buildroot.
- Modify local.mk as shown below. It is not allowed to use absolute path in local.mk, use relative path instead. It is preferable to use \$(CONFIG\_DIR) to denote the root directory of Buildroot.

```
ARM_TRUSTED_FIRMWARE_OVERRIDE_SRCDIR=workspace/tfa-2.3
UBOOT_OVERRIDE_SRCDIR=$(CONFIG_DIR)/workspace/uboot-2020.07
OPTEE_OS_OVERRIDE_SRCDIR=workspace/optee-os-3.9.0
LINUX_OVERRIDE_SRCDIR=workspace/linux-5.10
```



#### **Configuring Buildroot**

- Before configuring Buildroot, it is required to load a default configuration for target board.
- List all configurations provided by MA35 SoC series
   \$ make list-defconfigs | grep ma35
- Load a specific board configuration
   \$ make numaker\_iot\_ma35d16f80\_defconfig
- Configure Buildroot
   \$ make menuconfig



### Configuring Buildroot (Download Directory)

 Specify where files are downloaded

→ Build options

Download dir

workspace/dl

```
Build options
Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenus ----).
Highlighted letters are hotkeys. Pressing <Y> selects a feature, while <N> excludes a
feature. Press <Esc> <Esc> to exit, <?> for Help, </> for Search. Legend: [*] feature is
selected [ ] feature is excluded
               Nuvoton MPU (NUC9X0) --->
              Commands --->
          (Mhomeconfigs/my company board_defconfig) Location to save buildroot config
          (workspace/dl) Download dir
          ($(BASE DIR)/host) Host dir
               Mirrors and Download locations --->
           (0) Number of jobs to run simultaneously (0 for auto)
           [ ] Enable compiler cache
           [ ] build packages with debugging symbols
           [*] strip target binaries
                 executables that should not be stripped
                directories that should be skipped when stripping
               gcc optimization level (optimize for size) --->
           [ ] Enable google-breakpad support
               libraries (both static and shared) --->
           ($(CONFIG_DIR)/local.mk) location of a package override file
           () global patch directories
               Advanced --->
               *** Security Hardening Options ***
               *** Stack Smashing Protection needs a toolchain w/ SSP ***
               *** RELocation Read Only (RELRO) needs shared libraries ***
               *** Fortify Source needs a glibc toolchain and optimization ***
                             < Exit >
```



## Configuring Buildroot (Configuration Location)

 Specify location to save Buildroot configuration. The configuration file must be in the form of \*\_defconfig and should be saved to configs/\*\_defconfig

#### → Build options

Location to save buildroot config configs/my\_company\_board\_defconfig

```
Build options
Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenus ----).
Highlighted letters are hotkeys. Pressing <Y> selects a feature, while <N> excludes a
feature. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] feature is
selected [ ] feature is excluded
               Nuvoton MPU (NUC9X0) --->
             onfigs/my_company_board_defconfig)    Location to sav<u>e buildroot conf</u>i
           ($(BASE DIR)/host) Host dir
               Mirrors and Download locations --->
           (0) Number of jobs to run simultaneously (0 for auto)
               Enable compiler cache
               build packages with debugging symbols
           [*] strip target binaries
                 executables that should not be stripped
                directories that should be skipped when stripping
               qcc optimization level (optimize for size) --->
           [ ] Enable google-breakpad support
               libraries (both static and shared) --->
           ($(CONFIG DIR)/local.mk) location of a package override file
           () alobal patch directories
               Advanced --->
               *** Security Hardening Options ***
               *** Stack Smashing Protection needs a toolchain w/ SSP ***
               *** RELocation Read Only (RELRO) needs shared libraries ***
               *** Fortify Source needs a glibc toolchain and optimization ***
```



#### Configuring Buildroot (Boot Device)

- MA35D1/MA35D0/MA35
   H0 series use the default
   U-Boot board
   configuration to boot
   from different devices.
  - 1. ma35d1\_sdcard0
  - 2. ma35d1\_sdcard1
  - 3. ma35d1\_spinand
  - 4. ma35d1\_spinor
  - 5. ma35d1\_nand

```
Bootloaders
Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenus ----).
Highlighted letters are hotkeys. Pressing <Y> selects a feature, while <N> excludes a feature.
Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] feature is selected [ ]
feature is excluded
            [*] optee os
                 OP-TEE OS version (MA35D1 tarball) --->
            (master) Custom repository version
            -*- Build core
                 Build TA devkit
                 Build service TAs and libs
            (nuvoton) Target platform (mandatory)
            (MA35D1) Target platform flavor (optional)
                 Additional build variables
            (tee.bin tee-* v2.bin) Binary boot images
            [ ] shim
            [*] U-Boot
                 Build system (Kconfia) --->
                 U-Boot Version (Custom tarball) --->
            ($(call github,OpenNuvoton,MA35D1 u-boot-v2020.07,master)/MA35D1 u-boot-v2020.07-m
                  Beet configuration (Using an in-tree board defconfig file) --->
            (ma35d1 nand) Board defconfig
                 Auto resize sdcard to Max.
                 Additional configuration fragment files
                 U-Boot needs dtc
                 U-Boot needs host Python (no) --->
                 U-Boot needs pylibfdt
                 U-Boot needs pyelftools
                 U-Boot needs OpenSSL
                 U-Boot needs lzop
                   <Select>
                              < Exit >
```



## Configuring Buildroot (Remote Debugging)

 The options of toolchain and other packages must be tailored to meet the conditions for remote debugging with GDB server.

```
Toolchain
Arrow keys navigate the menu.  <Enter> selects submenus ---> (or empty submenus ----).  Highlighted letters are
hotkeys. Pressing <Y> selects a feature, while <N> excludes a feature. Press <Esc><to exit, <?> for Help,
</> for Search. Legend: [*] feature is selected [ ] feature is excluded
                        Toolchain type (Buildroot toolchain) --->
                        *** Toolchain Buildroot Options ***
                    (nuvoton) custom toolchain vendor name
                        C library (glibc) --->
                        *** Kernel Header Options ***
                        Kernel Headers (Same as kernel being built) --->
                        Custom kernel headers series (5.10.x or later) --->
                        *** Glibc Options ***
                    [ ] Install glibc utilities
                        *** Binutils Options ***
                        Binutils Version (binutils 2.35.2) --->
                    () Additional binutils options
                        *** GCC Options ***
                        GCC compiler Version (qcc 9.x) --->
                    () Additional acc options
                    [*] Enable C++ support
                        Enable Fortran support
                        Enable D language support
                        Enable compiler link-time-optimization support
                        Enable compiler OpenMP support
                       1 Enable graphite support
                         *** Host CDR Options ***
                        Build cross qdb for the host
                          TUI support
                          Python support (Python 3)
                         Simulator support
                          GDB debugger Version (gdb 9.2.x) --->
                        *** Toolchain Generic Options ***
                    Copy gconv libraries
                    () Extra toolchain libraries to be copied to target
                    [*] Enable MMU support
                    () Target Optimizations
                    () Target linker options
                    [ ] Register toolchain within Eclipse Buildroot plug-in
```



#### **Building the whole artifact**

- Type make to build the whole artifact
   \$ make
- Depending on boot device, machine type and memory capacity, the artifact is produced at loation output/images as shown in below table.

<b>Boot Device</b>	Artifact
SD0/SD1	pack-core-image-buildroot-ma35d1-som-256m-sdcard.bin
SPI NAND Flash	pack-core-image-buildroot-ma35d1-iot-512m-spinand.bin
SPI Nor Flash	pack-core-image-buildroot-ma35d1-iot-512m-spinor.bin
NAND Flash	pack-core-image-buildroot-ma35d1-som-1g-nand.bin

Use NuWriter to program the artifact to memory of boot device



#### **Building a specific artifact**

- Build the artifact Linux when its source is changed
  - \$ make linux-rebuild && make
- Build the artifact U-Boot when its source is changed
  - \$ make uboot-alter-rebuild

Note: uboot-alter-rebuild is defined in local.mk, do not use uboot-rebuild. If one persists in using uboot-rebuild to rebuild U-Boot, the Buildroot 2021 must be patched with <a href="https://raw.githubusercontent.com/symfund/ma35d1-portal/refs/heads/master/patches/buildroot-2021/0001-package-pkg-generic.mk-a-more-generic-way-to-rebuild.patch and Buildroot 2024 must be patched with <a href="https://raw.githubusercontent.com/symfund/ma35d1-portal/refs/heads/master/patches/buildroot-2024/0001-more-generic-way-to-rebuild-package.patch">https://raw.githubusercontent.com/symfund/ma35d1-portal/refs/heads/master/patches/buildroot-2024/0001-more-generic-way-to-rebuild-package.patch</a>

#### Patch Buildroot 2021/2024

\$ git apply --verbose 0001-more-generic-way-to-rebuild-package.patch (or 0001-package-pkg-generic.mk-a-more-generic-way-to-rebuild.patch)

After patching Buildroot 2021/2024 with package/pkg-generic.mk, then rebuild U-Boot as shown below \$ make uboot-rebuild && make

- Build the artifact Arm Trusted Firmware when its source is changed
  - \$ make arm-trusted-firmware-rebuild && make
- Build the artifact optee OS when its source is changed
  - \$ make optee-os-rebuild && make
- Build the rootfs when in Buildroot a package is selected/unselected or system configuration is changed
  - \$ make rootfs-rebuild



#### **Saving configurations**

- Save Buildroot configuration
   \$ make buildroot-save-config
- Save Linux configuration\$ make linux-save-config
- Save U-Boot configuration
   \$ make uboot-save-config
- Save Busybox configuration
   \$ make busybox-save-config
- Save uClibc configuration
   \$ make uclibc-save-config
- Save all configurations\$ make all-save-config

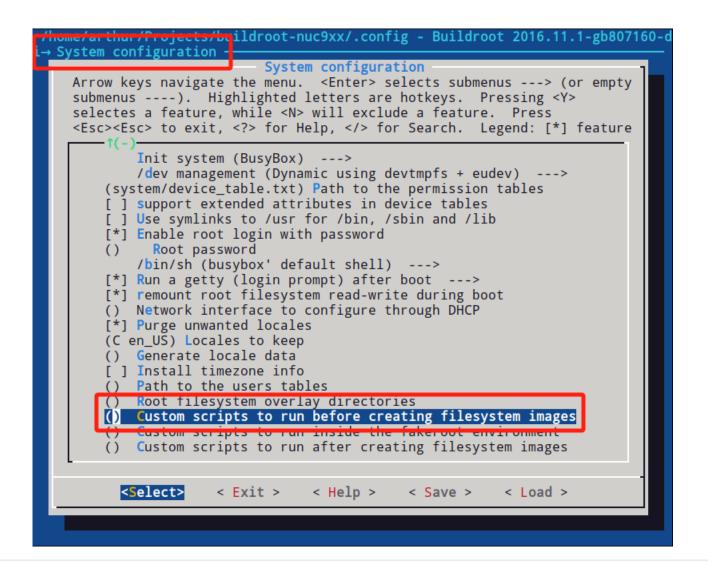
Main	Parts
Buildroot Co	U-Boot Configuration
	Linux Configuraiton
Configur	<b>Busybox Configuration</b>
ration	uClibc Configuration

Configuration	Command (*-save-config)
buildroot	make buildroot-save-config
linux	make linux-save-config
uboot	make uboot-save-config
busybox	make busybox-save-config
uclibc	make uclibc-save-config
all	make all-save-config



#### **Customizing rootfs**

- Buildroot provides two recommended methods root filesystem overlay(s) and post build script(s), which can co-exist, to customize the generated target root filesystem.
  - 1. Root filesystem overlays
  - 2. Post-build scripts





#### Customizing rootfs through Post-Build script

 Post-Build scripts are shell scripts called after Buildroot builds all the selected software, but before the rootfs images are assembled. The following environment variables can be used in post-build scripts.

Variable	Value
BR2_CONFIG	the path to the Buildroot .config file
CONFIG_DIR	the directory containing the .config file, and therefore the top-level Buildroot Makefile to use
TARGET_DIR	the path to the output/target
BINARIES_DIR	The place where all binary files (aka images) are stored

#### Customizing rootfs through Post-Build script

 The below Post-Build script file checks whether OpenSSH Server is enabled in the Buildroot configuration (\${BR2\_CONFIG}). If enabled, it changes the configuration file (/etc/ssh/sshd\_config) of OpenSSH Server on the generated target root filesystem.

#### Post-Build Script (workspace/scripts/post-build.sh)

```
if grep -Eq "^BR2_PACKAGE_OPENSSH=y$" ${BR2_CONFIG}; then sed -i 's/^#PermitRootLogin.*/PermitRootLogin yes/' ${TARGET_DIR}/etc/ssh/sshd_config sed -i 's/^#PasswordAuthentication.*/PasswordAuthentication yes/' ${TARGET_DIR}/etc/ssh/sshd_config sed -i 's/^#PermitEmptyPasswords.*/PermitEmptyPasswords yes/' ${TARGET_DIR}/etc/ssh/sshd_config fi
```



#### Generating standalone SDK toolchain

• For third-party developers, a standalone SDK toolchain is must be have on hand. By distributing standalone SDK tool to independent software vendors, OEM manufacturers need not to disclose proprietary source code to the public.

Resort to the local Makefile *local.mk*, SDK toolchain can be generated without user intervention by the extensions of build instruction.



#### Generating standalone SDK toolchain

 Before generating the standalone SDK toolchain, Buildroot must be correctly configured. That means toolchain options are tailored to meet the development requirements, some mandatory packages are selected in mind.

Refer to the slide *Configuring Buildroot (Remote Debugging)* for configuring toolchain to meet development requirements.



#### Generating standalone SDK toolchain

- Begin building SDK toolchain, the action make clean is optional, if want to save the build time.
  - \$ make clean; make sdk-tool
- When complete generating SDK tool, the SDK tool is located at output/images/aarch64-nuvoton-linux-gnu\_sdk-buildroot\_installer
- To install the SDK tool on local computer in which the SDK tool is built or another computer, launch the SDK tool installer show below.
  - \$ sudo output/images/aarch64-nuvoton-linux-gnu\_sdk-buildroot\_installer
- By default, the SDK tool is installed in /opt/aarch64-nuvoton-linux-gnu\_sdk-buildroot
- Before using the SDK tool, open a terminal window and set up the build environment for the new terminal.
  - \$ source /opt/aarch64-nuvoton-linux-gnu\_sdk-buildroot/environment-setup



#### Remote debugging with the GNU GDB debugger

 MA35D1/MA35D0/MA35H0 series support remote debugging with the GNU GDB debugger using Eclipse and Qt Creator.





#### Remote debugging with GDB using Eclipse

• Refer to developer guide (PDF) Remote Debugging with the GNU GDB Debugger using Eclipse.

> The Eclipse Installer 2023-12 R now includes a JRE for macOS, Windows and Linux. Try the Eclipse Installer 2023-12 R The easiest way to install and update your Eclipse Development Environment. Find out more **₹** 874.864 Installer Downloads **₹** 772,712 Package Downloads and Updates Download macOS x86 64 | AArch64 Windows x86 64 Linux x86 64 | AArch64



#### Remote debugging with GDB using Qt Creator

 Refer to developer guide (PDF) Remote Debugging with the GNU GDB Debugger using Qt Creator.



#### Building an external (out-of-tree) kernel module

- To build an out-of-tree (external) module, a prebuild kernel with the configuration and header files must exist. Also the kernel must have been configured to enable loadable module support (CONFIG\_MODULES). That means the Linux artifact is built by typing "make linux-rebuild" in Buildroot.
- Assuming that the module name is "mod\_xyz', create a Kbuild file as show below

```
# filename: Kbuild
obj-m := mod_xyz.o
mod_xyz-y := main.o
ccflags-y := -I$(src)
```



#### Building an external (out-of-tree) kernel module

Create a makefile as shown below

```
# filename: Makefile
ifneq ($(KERNELRELEASE),)
include Kbuild
else
KERNELDIR ?= /lib/modules/`uname -r`/build
default:
  $(MAKE) -C $(KERNELDIR) M=$$PWD
clean:
  $(MAKE) -C $(KERNELDIR) M=$$PWD clean
endif
```

#### Building an external (out-of-tree) kernel module

- Structure of kernel module source \$(src)
  - \_ Kbuild
  - \_ Makefile
  - \_ main.c
- Open a new terminal window, change to the directory of driver source in command line and set up build environment for the terminal.
  - \$ source \${BR2\_DIR}/output/host/environment-setup NOTE: \${BR2\_DIR} denotes the root directory of Buildroot.
- Build the kernel module \$ make
- Clean build \$ make clean

```
/* filename: main.c */
#include ux/init.h>
#include linux/module.h>
#include linux/printk.h>
#include ux/kernel.h>
#include linux/utsname.h>
static int init mod xyz init(void)
  printk(KERN_INFO "Loading mod_xyz ...");
  pr alert("%s version %s: %s\n", utsname()->sysname, utsname()->release, utsname()->version);
  return 0;
static void __exit mod_xyz_exit(void)
  pr_alert("exit mod_xyz driver\n");
module init(mod xyz init);
module_exit(mod_xyz_exit);
MODULE LICENSE("GPL");
MODULE DESCRIPTION("Linux module mod-xyz");
MODULE AUTHOR("2024@nuvoton");
```



Joy of innovation

NUVOTON

谢谢 謝謝 Děkuji Bedankt Thank you Kiitos Merci Danke Grazie ありがとう 감사합니다 Dziękujemy Obrigado Спасибо Gracias Teşekkür ederim Cảm ơn